Cevahir Koprulu

cevahir.koprulu@utexas.edu · 1-512-902-3307 · Website · Github · LinkedIn

EDUCATION

University of Texas at Austin

M.S. 2023, PhD 2026

Electrical and Computer Engineering

Research Focus: Reinforcement Learning and Multi-task Learning.

Bilkent University (Ankara/Turkey)

Bachelor of Science in Electrical and Electronics Engineering

June 2021 GPA: 3.73/4

GPA: 3.93/4

Honours/Awards:

Bilkent University Comprehensive Scholarship (Fall 2016-Spring 2021)

Scholarship of Turkish Prime Ministry (Fall 2016-Spring 2021)

Bilkent University EEE Department High Honours (8 Consecutive Semesters: Fall 2016-Spring 2020)

University Entrance Exam, Ranked 24th among 2 million students (June 2016)

FIRST Robotics Competition 2015: Recycle Rush, Rookie All-Star Award (Spring 2015)

WORK EXPERIENCE

Eatron Technologies

Istanbul, Turkey

June 2020 - June 2021

Python, Pytorch, ROS

• Worked on **graph convolutional** and **self-attention**-based architectures to extract spatio-temporal features of a traffic scene for trajectory prediction in a Level-2+ ADAS powered autonomous vehicle.

ROKETSAN (in collaboration with Bilkent University)

Ankara, Turkey

Industrial Design Project (all the work is under NDA)

Engineering Intern (all the work is under NDA)

Python, C++, Pytorch, ROS

Sept 2019 - June 2020

Developed a mobile robot that completes tasks given by a human leader, combining YOLOV3 for object
detection and artificial potential field method for path planning in a mapped area with unknown
obstacles.

RESEARCH WORK

Risk-Aware Curriculum Generation for Heavy-tailed Task Distributions	UAI, 2023
Cevahir Koprulu, Thiago D. Simão, Nils Jansen, Ufuk Topcu	
Reward-Machine-Guided, Self-Paced Reinforcement Learning (Full Paper)	UAI, 2023
Cevahir Koprulu, Ufuk Topcu	
Reward-Machine-Guided, Self-Paced Reinforcement Learning (Extended Abstract)	AAMAS, 2023
Cevahir Koprulu, Ufuk Topcu	
Joint Learning of Reward Machines and Policies in Environments with Partially Known	ArXiV, 2023
Semantics	AIAiV, 2020
Christos Verginis, Cevahir Koprulu , Sandeep Chinchali, Ufuk Topcu	
Act to Reason: A Dynamic Game Theoretical Driving Model for Highway Merging Applications	CCTA, 2021
Cevahir Koprulu, Yildiray Yildiz	

TECHNICAL SKILLS

- Programming languages: (Competent) Python, MATLAB, (Knowledgeable) C++, Java
- Software: Pytorch, TensorFlow, ROS, Linux

Relevant Coursework

- UT Austin: Causality and Reinforcement Learning, Statistical Machine Learning, Learning-based Optimal Control, Game-Theoretic Modeling of Multi-Agent Systems, Program Synthesis, Cyber-Physical Systems, Reinforcement Learning, Convex Optimization, Probability and Statistics, and Complex Networks in the Real World.
- Bilkent University: Statistical Learning and Data Analytics (Grad), Robust Feedback Theory (Grad), Introduction to Financial Mathematics (Grad), Neural Networks, Deep Learning, Image Analysis and Pattern Recognition, and Game Theory.

Systems Laboratory

Undergraduate Researcher

Ankara, Turkey Sept 2019 - July 2021

• Developed **human driver models** from real-traffic data that can change its reasoning level dynamically by combining **level-k game theory** and **reinforcement learning**. Published the corresponding work at CCTA 2021.

IEEE Robotics and Automation Society at Bilkent University

Chairman

Ankara, Turkey May 2017 - June 2018

- Organized "Mühendis Kafası" in cooperation with Technology Development Foundation of Turkey: Series of sessions on Computer Vision and Deep Learning.
- Gave lectures on robotics, control techniques, and related micro-controller programming: EE-101: Introduction to Robotics with Arduino.

SHORT PROJECTS

Automatic Image-Captioning via InceptionV3 - EEE-443 Neural Networks

Fall 2019

 An auto image-captioning project based on Inception V3 to extract feature vectors processed with GLoVe word representations via merge and inject structures to carry out an image captioning task using LSTMs and GRUs.

Knockurity: Knocking Based Door Security System in C++ - EEE-212 Microprocessors

Spring 2018

• A security system operates by recognizing knocking patterns and registering users by their secret knocks. The system provides user access by Bluetooth-based wireless control for various functions.

The Thing: Wireless Controller in VHDL - EEE 102 Digital Design

Fall 2017

• A Bluetooth-based wireless controller that utilizes an inertial measurement unit via transferring orientation data from an Arduino to an FPGA to enable the user to control the mouse on a PC Screen.

LANGUAGE SKILLS

• Turkish: Native proficiency

• English: TOEFL 110/120 (Fall 2020)

• French: DELF B1 (Spring 2015)

RECREATIONAL INTERESTS

I enjoy bouldering, sports climbing, cycling, watching soccer (football:)), and reading/watching podcasts on psychology.