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Non-blocking Virtual Delay timer for the Arduino

Details

ELast Updated: 11 February 2018

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Introduction

The standard Arduino delay() function blocks the Arduino, that is not always allowed. The standard delay has limitations too; it is not possible to use multiple delays at the same time. So I decided to developed a VirtualDelay library which has many advantages:

Advantages of the VirtualDelay library

- The delay is virtual, during the delay, the code execution is continued
- We can use multiple delays sequentially in a loop.
- We can use multiple delays simultaneously and independent of each other.
- The delay time can set in micro-seconds or milli-seconds.
- No hardware timers are used
- · The library is timer-rollover safe



VirtualDelay library download

You can download the library from GitHub (https://github.com/avandalen/VirtualDelay).

Questions

Please post any questions at the Arduino forum (http://forum.arduino.cc/index.php?topic=428666.0).

Notes

- The VirtualDelay must always run inside a loop which is executed continuously.
- In contrast with the standard delay function, we need a start() and an elapsed() function.
- The delay time value can be between 0 and 2147483647 (2³¹⁻¹).

Simple blinking LED sketch with the VirtualDelay library

```
1
     #include <Arduino.h>
 2
     #include "avdweb_VirtualDelay.h"
 3
 4
     const byte ledPin = 13;
 5
     bool b;
     VirtualDelay singleDelay; // default = millis
 6
 7
8
     void setup()
9
     { pinMode(ledPin, OUTPUT);
10
11
12
     void loop()
13
     { singleDelay.start(400); // calls while running are ignored
       if(singleDelay.elapsed()) digitalWrite(ledPin, b=!b); // blink the onbo
14
15
     }
```

Micro seconds VirtualDelay example

```
1
     #include "avdweb VirtualDelay.h"
 2
 3
     VirtualDelay delay us(micros);
 4
 5
     void setup()
6
     { Serial.begin(9600);
 7
8
9
     void loop()
10
     { DO ONCE ( delay us.start(1000000)) // 1s
       if(delay us.elapsed()) Serial.print(micros());
11
12
```

Standard Arduino blocking delay

Here a standard blinking LED sketch. Open the serial port and you can see that printing goes very slowly.

```
1
     #include <Arduino.h>
 2
     #include <Streaming.h>
 3
 4
     const byte ledPin = 13;
 5
     int i;
6
 7
     void setup()
     { pinMode(ledPin, OUTPUT);
8
9
       Serial.begin(9600);
     }
10
11
12
     void loop()
     { digitalWrite(ledPin, 1); // this comes after the 700ms delay
13
14
       delay(100);
       digitalWrite(ledPin, 0); // this comes after the 100ms delay
15
16
       delay(700);
       Serial << " " << i++; // since the cpu is being blocked, printing goes
17
18
     }
```

Deadlock

With a sequence of VirtualDelays, each delay will wait on the foregoing by which the sequence can't start. This is a so-called deadlock. To break the deadlock, one of the delays has to start one-time. To do so, I have built a macro DO_ONCE. This is carried out only once in a loop, see the following example:

Using 3 VirtualDelays in sequence

Note: You can use the virtual delay to generate continuously timing signals like the example below. But this is not the most appropriate way. You better use a timer and link it to an interrupt service routine.

We need three separate VirtualDelay instances: delay1, delay2 and delay3. The line with the macro DO ONCE ensures that the sequence is started. You may use any instance e.g. delay2.start(0).

```
1
     #include <Arduino.h>
 2
     #include <Streaming.h>
 3
     #include "avdweb_VirtualDelay.h"
 4
 5
     VirtualDelay delay1, delay2, delay3;
 6
7
     void setup()
8
     { Serial.begin(9600);
       Serial << "\ntestSequence";</pre>
9
10
     }
11
12
     void loop()
     { if(delay1.elapsed()) // this sequence has a deadlock
13
       { Serial << "\ndelay1 200ms " << millis();</pre>
14
15
         delay2.start(100);
16
17
       if(delay2.elapsed())
18
       { Serial << "\ndelay2 100ms " << millis();</pre>
19
         delay3.start(400);
20
       if(delay3.elapsed())
21
       { Serial << "\ndelay3 400ms " << millis();
22
23
         delay1.start(200);
24
25
       DO ONCE(delay1.start(200)); // breaks the deadlock, you can start with
26
     }
```

Here is the serial output:

```
1 delay1 200ms 200
2 delay2 100ms 300
3 delay3 400ms 700
4 delay1 200ms 900
5 delay2 100ms 1000
6 delay3 400ms 1400
7 delay1 200ms 1600
```

Using multiple delays at the same time

In this example, we use 6 VirtualDelays at the same time, this is not possible with the standard Arduino delay function. It is also showed how we can use the macro DO_ONCE multiple times in a loop.

```
1
     #include <Arduino.h>
 2
     #include <Streaming.h>
 3
     #include "avdweb VirtualDelay.h"
 4
 5
     void setup()
     { Serial.begin(9600);
 6
 7
8
9
     void loop()
10
     { static VirtualDelay delay1, delay2, delay3, delay4, delay5, delay6;
11
       DO ONCE
       ( Serial << "\nDO ONCE 1";</pre>
12
13
         delay1.start(200); // start sequence delay1 delay2 delay3
         delay4.start(550); // start one-shot delay4
14
15
         delay5.start(1250); // start one-shot delay5
16
                                                                       " << millis()</pre>
       if(delay4.elapsed()) Serial << "\nONE-SHOT 550ms</pre>
17
                                                                       " << millis()</pre>
       if(delay5.elapsed()) Serial << "\nONE-SHOT 1250ms</pre>
18
19
20
       if(millis()>2250) DO ONCE(Serial << "\nDO ONCE 2 2250ms</pre>
                                                                            " << mi]
21
22
       delay6.start(750);
23
       if(delay6.elapsed()) Serial << "\n Repeat delay6 750ms</pre>
                                                                       " << millis()</pre>
24
25
       if(delay1.elapsed()) // sequence with deadlock
26
       { Serial << "\nsequence delay1 200ms " << millis();</pre>
27
         delay2.start(100);
28
29
       if(delay2.elapsed())
30
       { Serial << "\nsequence delay2 100ms
                                                  " << millis();
31
         delay3.start(400);
32
       if(delay3.elapsed())
33
       { Serial << "\nsequence delay3 400ms
                                                  " << millis();
34
35
         delay1.start(200);
36
       }
37
     }
```

Here is the serial output:

```
1
     DO ONCE 1
 2
     sequence delay1 200ms
                               200
 3
     sequence delay2 100ms
                               300
 4
     ONE-SHOT 550ms
                               550
 5
     sequence delay3 400ms
                               700
       Repeat delay6 750ms
                               750
6
7
     sequence delay1 200ms
                               900
8
     sequence delay2 100ms
                               1000
     ONE-SHOT 1250ms
9
                               1250
10
     sequence delay3 400ms
                               1400
11
       Repeat delay6 750ms
                               1500
12
     sequence delay1 200ms
                               1600
13
     sequence delay2 100ms
                               1700
14
     sequence delay3 400ms
                               2100
15
       Repeat delay6 750ms
                               2250
16
     DO_ONCE 2 2250ms
                               2251
17
                               2300
     sequence delay1 200ms
18
     sequence delay2 100ms
                               2400
19
     sequence delay3 400ms
                               2800
```

To create a one-shot, start() may only be called once during the loop, to do so, the macro DO_ONCE is used.

```
1
     #include <Arduino.h>
 2
     #include <Streaming.h>
 3
     #include "avdweb_VirtualDelay.h"
 4
 5
     VirtualDelay delay1;
 6
 7
     void setup()
8
     { Serial.begin(9600);
9
       Serial << "\ntestOneShot 2s\n";</pre>
10
11
12
     void loop()
     { DO_ONCE(delay1.start(2000)) // do only one time in the loop
13
       if(delay1.elapsed()) Serial << millis() << "ms";</pre>
14
15
```

The library has to be timer-rollover proof

The 32 bit millis() and micros() timers counts from 0, 1, 2 to 4294967295 (2^32-1) and than rollover to 0 again. The millis() timer is going to roll over after roughly 49.7 days, the micros() rolls over every 71.6 minutes. We have to take care about this rollover, because it may happen that we start the virtual-delay just before the rollover time. After the rollover the timestamps will be messed up.

The time compare part in the VirtualDelay library is tricky, it compares 2 timestamps like this:

```
if(millis() >= timeOut)
```

However, this won't work, we have to use:

```
if((millis()-timeOut)>=0)
```

Believe it or not, in this situation, both lines are not identical! You can read all about this in the detailed <u>story from Edgar Bonet (https://arduino.stackexchange.com/questions/12587/how-can-i-handle-the-millis-rollover/12588#12588</u>).

History

The VirtualDelay library looks quite simple, but the development has cost me a lot of time.

The first library from 10-1-2016 didn't use a start function. The library seemed to work well but after a year it turned out that there were situations in which it failed. The reason was that I had used a simple LED test, which caused that a serious shortcoming was not discovered.

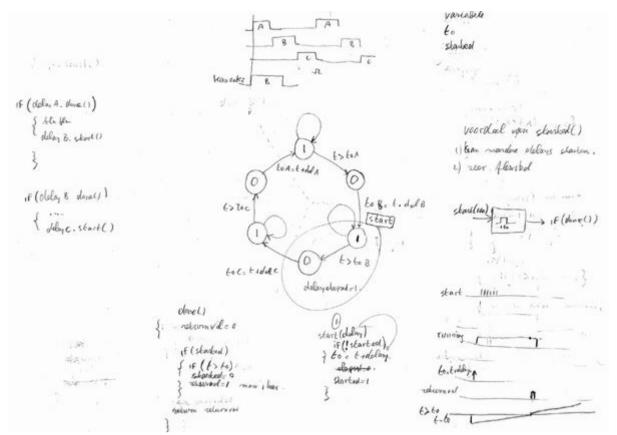
I had to make new library from scratch. This new library seemed to work well, also with a sequence of two delays.

Later tests showed that there were problems with three and more delays sequentially. This again required a completely different approach. But now it turned out that there were problems with using multiple delays simultaneously and again a complete new library had to be made.

Finally, I came to the conclusion that to solve all problems, it was necessary to use a start function and a macro DO_ONCE.

Future expansions

Extra functions may be implemented like restart, pause, resume, stop, reset. Who wants to expand the library on github?



VirtualDelay-development (/Article files/Arduino/Virtual-delay/VirtualDelay-development.jpg)

Simple microseconds VirtualDelay

Do you have any comments? Please let me know (http://www.avdweb.nl/contact.html).



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