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# Clara Fernández Labrador

# Current position: PhD Student at University of Zaragoza and

University of Bourgogne

cfernandez@unizar.es (work e-mail) flabclara@gmail.com (personal e-mail) (+34) 606 23 74 35

Contact information:

Current Address: C/ Juan Martín Sauras nº14 50011 Zaragoza, Spain

#### **EDUCATION**

# PhD studies in Computer Vision

Computer Science and Systems Engineering Dept., University of Zaragoza – Spain / University of Bourgogne – France Advisors: Dr. José J. Guerrero Campo and Dr. Cédric Demonceaux

# Visit during Master of Industrial Engineering

Politecnico di Torino Torino – Italy Funded by EU Erasmus Program

# Master of Industrial Engineering

University of Zaragoza – Spain

Thesis title: "3D Room Layout Estimation from a Single 360° Panorama" Advisors: Dr. José J. Guerrero Campo and PhD student Alejandro Pérez Yus

#### Visit during Bachelor of Industrial Engineering

Università degli studi di Trieste Trieste – Italy Funded by EU Erasmus Program

## **Bachelor of Industrial Engineering**

University of Zaragoza – Spain

Thesis title: "Design and Organization for the Machines Control in a Company"

Advisors: Dr. Ángel Fernández Cuello and Dr. Nicolich Marino

#### SCHOLARSHIPS

# Erasmus Scholarship from the EU

Funded by the European Union To perform part of the Master studies abroad At Politecnico di Torino, Italy

#### Erasmus Scholarship from the EU

Funded by the European Union To perform part of the Bachelor studies abroad At Università degli studi di Trieste, Italy

# Oct 2017 - present

# Sep 2016 - Mar 2017

# Sep 2015 - Oct 2017

# Sep 2014 - Jun 2015

Sep 2014 - Juli 2015

# Sep 2011 - Sep 2015

Sep 2016 - Feb 2017

Sep 2014 - Feb 2015

#### WORK EXPERIENCE

## Research Assistant - Ms. Candidate - PhD Candidate

Oct 2017 - present

Robotics, Perception & Real Time Group.

University of Zaragoza, Spain

Research Project: "DPI2015-65962-R: Egocentric Computer Vision for Environment Interaction of Visually Impaired People, EVEIVI"

Research in Computer Vision and Robotics: Complex scene analysis with non-conventional cameras for robotics and people assistance. Geometry and deep learning combination.

#### Research Assistant - Ms. Candidate

Mar 2017 - Oct 2017

Robotics, Perception & Real Time Group.

University of Zaragoza, Spain

Research Initiation Scholarship

Research Project: "DPI2014-61792-EXP: Sistemas de visión no convencionales para percepción en prótesis de visión simulada"

Research in Computer Vision and Robotics: 3D layout recovery of indoor scenes from single 360 degrees panoramas. Geometry and deep learning combination.

## Undergraduate Intern - Bs. Candidate

Mar 2015 - Jul 2015

Colombin GM & Figlio Spa

Trieste, Italy

Project management. Bottlenecks and personal protective equipment (PPE) managing.

# Undergraduate Intern - Bs. Candidate

May 2014 - Aug 2014

Techopackaging

Zaragoza, Spain

3D CAD design and injection simulations in prosthetics with biocompatible plastics.

#### LANGUAGES

English - First Certificate (B2). Currently preparing Cambridge Advanced (C1)

Italian - CILS Livello TRE (C1)

French - Lower Intermediate

Spanish - Mother tongue

#### **PUBLICATIONS**

[1] "Layouts from Panoramic Images with Geometry and Deep Learning"

Clara Fernandez-Labrador, Alejandro Perez-Yus, Gonzalo Lopez-Nicolas and Jose J. Guerrero

Under review at RA-L and IROS 2018

## SUPERVISED BACHELLOR/MASTER THESIS PROJECTS

"Omnidirectional Vision for Scene Understanding".
 Juan Carlos Medina. Co-supervised with Dr. José J. Guerrero Campo.
 Bs. Industrial Eng. University of Zaragoza. 2018

# PARTICIPATION IN RESEARCH PROJECTS

- Egocentric Computer Vision for Environment Interaction of Visually Impaired People (EVEIVI), DPI2015-65962-R. Financed by MINECO and UE/FEDER. P.I.(principal investigator): José J. Guerrero
- Sistemas de visión no convencionales para percepción en prótesis de visión simulada, DPI2014-61792-EXP. Financed by MINECO and UE/FEDER. P.I.(principal investigator): Gonzalo López Nicolás