

# Math 269B, 2012 Winter, Homework 3 (Solutions)

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## 1 Theory

1. (Strikwerda 5.1.2.) Show that the modified leapfrog scheme (5.1.6) is stable for  $\epsilon$  satisfying

$$0 < \epsilon \leq 1 \quad \text{if} \quad 0 < a^2 \lambda^2 \leq \frac{1}{2}$$

and

$$0 < \epsilon \leq 4a^2 \lambda^2 (1 - a^2 \lambda^2) \quad \text{if} \quad \frac{1}{2} \leq a^2 \lambda^2 < 1.$$

Note that these limits are not sharp. It is possible to choose  $\epsilon$  larger than these limits and still have the scheme be stable.

### Solution

Continuing from the text, we find the amplification factors to be

$$g_{\pm}(\theta) = -ia\lambda \sin \theta \pm \sqrt{1 - a^2 \lambda^2 \sin^2 \theta - \epsilon \sin^4 \frac{1}{2} \theta}.$$

If the expression under the  $\sqrt{\cdot}$  is nonnegative, then

$$|g_{\pm}(\theta)|^2 = 1 - \epsilon \sin^4 \frac{1}{2} \theta \leq 1,$$

hence the scheme is stable. We thus wish to satisfy

$$0 \leq 1 - a^2 \lambda^2 \sin^2 \theta - \epsilon \sin^4 \frac{1}{2} \theta =: \alpha(\theta).$$

We compute that

$$\alpha'(\theta) = -\frac{1}{2} \sin \theta ((4a^2 \lambda^2 - \epsilon) \cos \theta + \epsilon),$$

and hence the extrema of  $\alpha$  occur when  $\sin \theta = 0$  or  $\cos \theta = \epsilon / (\epsilon - 4a^2 \lambda^2)$ . Values of  $\theta$  satisfying  $\sin \theta = 0$  give  $\alpha = 1$  or  $\alpha = 1 - \epsilon$ , requiring that  $\epsilon \leq 1$ . Values of  $\theta$  satisfying  $\cos \theta = \epsilon / (\epsilon - 4a^2 \lambda^2)$  exist if and only if  $|\epsilon / (\epsilon - 4a^2 \lambda^2)| \leq 1$ , which is equivalent to  $\epsilon \leq 2a^2 \lambda^2$ . For such  $\theta$ , we get  $\alpha = 1 - 4a^4 \lambda^4 / (4a^2 \lambda^2 - \epsilon)$ , and for this to be nonnegative, we must have  $\epsilon \leq 4a^2 \lambda^2 (1 - a^2 \lambda^2)$ . In particular, we must have  $|a\lambda| < 1$ .

So far, we have deduced that, at a minimum,  $0 < \epsilon \leq 1$ . Furthermore, if  $\epsilon \leq 2a^2 \lambda^2$ , then we must additionally satisfy  $\epsilon \leq 4a^2 \lambda^2 (1 - a^2 \lambda^2)$ . Now, in the instance that  $2a^2 \lambda^2 \leq 4a^2 \lambda^2 (1 - a^2 \lambda^2)$ , we would automatically satisfy the second condition, and this latter inequality is equivalent to  $a^2 \lambda^2 \leq \frac{1}{2}$ . It follows that

- If  $0 < a^2 \lambda^2 \leq \frac{1}{2}$ , it is sufficient to take  $0 < \epsilon \leq 1$ .

– If  $\frac{1}{2} \leq a^2 \lambda^2 < 1$ , it is sufficient to take  $0 < \epsilon \leq 4a^2 \lambda^2 (1 - a^2 \lambda^2)$ .

2. Derive the stability condition for the backward-time forward-space scheme

$$\frac{1}{k} (v_m^{n+1} - v_m^n) + \frac{a}{h} (v_{m+1}^{n+1} - v_m^{n+1}) = 0$$

used to approximate solutions to  $u_t + au_x = 0$  with, say,  $x \in [0, 1]$  and periodic boundary conditions. Give an example of an initial condition  $v_m^0$  and an explicit expression for  $v_m^n$  that demonstrate unstable behavior for a particular  $\lambda$  (your choice) which fails to satisfy the stability condition. Does the growth in your example agree with your theoretical amplification factor?

### Solution

Our difference operator is

$$P_{k,h} v_m^n = \frac{1}{k} (v_m^{n+1} - v_m^n) + \frac{a}{h} (v_{m+1}^{n+1} - v_m^{n+1})$$

which has symbol

$$\begin{aligned} p_{k,h}(s, \xi) &= P_{k,h} (e^{skn+imh\xi}) / e^{skn+imh\xi} \\ &= \frac{1}{k} (e^{sk} - 1) + \frac{a}{h} e^{sk} (e^{ih\xi} - 1). \end{aligned}$$

We determine stability by finding the roots of the symbol as a function of  $g := e^{sk}$ , yielding

$$g = \frac{1}{1 + a\lambda (e^{i\theta} - 1)}$$

where  $\lambda := k/h$  and  $\theta := h\xi$ . We find that

$$|g|^{-2} = 1 + 2a\lambda (a\lambda - 1) (1 - \cos \theta),$$

hence the scheme is stable ( $|g| \leq 1$ ) if and only if  $a \leq 0$  or  $a\lambda \geq 1$ .

If, for example,  $a\lambda = \frac{1}{4}$ , then

$$|g|^{-2} = 1 - \frac{3}{8} (1 - \cos \theta) = \frac{5}{8} + \frac{3}{8} \cos \theta.$$

Choosing, for example,  $\theta = \pi$  ought to give an amplification factor of exactly  $g = 2$  of the pure mode  $v_m = e^{i\theta m} = (-1)^m$ . Indeed, one can quickly verify that  $v_m^n = 2^n (-1)^m$  satisfies the difference equation:

$$\begin{aligned} kP_{k,h} v_m^n &= v_m^{n+1} - v_m^n + a\lambda (v_{m+1}^{n+1} - v_m^{n+1}) \\ &= 2^{n+1} (-1)^m - 2^n (-1)^m + \frac{1}{4} (2^{n+1} (-1)^{m+1} - 2^{n+1} (-1)^m) \\ &= 2^n (-1)^m \left( 2 - 1 + \frac{1}{4} (-2 - 2) \right) \\ &= 0. \end{aligned}$$

One final remark: Notice that if  $a\lambda = \frac{1}{2}$ ,  $|g|$  is *unbounded* near  $\theta = \pi$ . This corresponds to a null space in the resulting system of equations for  $v^{n+1}$  induced by the difference operator, and this null space is spanned precisely by the mode corresponding to  $\theta = \pi$ ,  $v_m = (-1)^m$ .

3. Prove that numerical solutions to the Lax-Friedrichs scheme

$$\frac{1}{k} \left( v_m^{n+1} - \frac{1}{2} (v_{m+1}^n + v_{m-1}^n) \right) + \frac{a}{2h} (v_{m+1}^n - v_{m-1}^n) = 0$$

converge to solutions to the corresponding modified equation

$$u_t + au_x = \frac{h^2}{2k} \left( 1 - \left( \frac{ak}{h} \right)^2 \right) u_{xx}$$

to second order accuracy in  $L^\infty$ . I.e., show that  $|v_m^n - u_{k,h}(t_n, x_m)| \rightarrow 0$  as  $h, k \rightarrow 0$  (according to the stability criterion), where the subscripts on  $u_{k,h}$  only indicate that the solution to the modified equation is parameterized by  $k, h$ .

**Solution**

The difference operator for the Lax-Friedrichs scheme is

$$P_{k,h} v_m^n = \frac{1}{k} \left( v_m^{n+1} - \frac{1}{2} (v_{m+1}^n + v_{m-1}^n) \right) + \frac{a}{2h} (v_{m+1}^n - v_{m-1}^n)$$

which has symbol

$$\begin{aligned} p_{k,h}(s, \xi) &= P_{k,h}(e^{skn+imh\xi}) / e^{skn+imh\xi} \\ &= \frac{1}{k} (e^{sk} - \cos h\xi) + i \frac{a}{h} \sin h\xi \\ &= \frac{1}{k} \left( 1 + sk + \frac{1}{2} s^2 k^2 - 1 + \frac{1}{2} h^2 \xi^2 \right) + i \frac{a}{h} (h\xi) + O(k^2 + h^2 + h^4 k^{-1}) \\ &= s + ia\xi + \frac{k}{2} s^2 + \frac{h^2}{2k} \xi^2 + O(k^2 + h^2 + h^4 k^{-1}). \end{aligned}$$

4. (Strikwerda 4.1.2.) Show that the (2, 2) leapfrog scheme for  $u_t + au_{xxx} = f$  (see (2.2.15)) given by

$$\frac{v_m^{n+1} - v_m^{n-1}}{2k} + a\delta^2 \delta_0 v_m^n = f_m^n,$$

with  $\nu = k/h^3$  constant, is stable if and only if

$$|a\nu| < \frac{2}{3^{3/2}}.$$

**Solution**

5. (Strikwerda 3.2.1.) Show that the (forward-backward) MacCormack scheme

$$\begin{aligned} \tilde{v}_m^{n+1} &= v_m^n - a\lambda (v_{m+1}^n - v_m^n) + k f_m^n, \\ v_m^{n+1} &= \frac{1}{2} (v_m^n + \tilde{v}_m^{n+1} - a\lambda (\tilde{v}_m^{n+1} - \tilde{v}_{m-1}^{n+1}) + k f_m^{n+1}) \end{aligned}$$

is a second-order accurate scheme for the one-way wave equation (1.1.1). Show that for  $f = 0$  it is identical to the Lax-Wendroff scheme (3.1.1).

**Solution**

## 2 Programming

1. For the one-way wave equation  $u_t + au_x = 0$ , investigate how close the numerical solution to a finite difference scheme is to the solution to the corresponding modified equation. To be concrete, suppose a convenient initial condition for which you can solve the modified equation explicitly with periodic boundary conditions. Take  $a = 1$ ,  $k/h = 0.5$ , and final time  $T = 0.5$ . Compare the following finite difference schemes: upwinding, Lax-Friedrichs, and Lax-Wendroff. Also, include a derivation of the respective corresponding modified equations.