

Corrected version
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Qualifying Exam, Winter 2002

NUMERICAL ANALYSIS

DO NOT FORGET TO WRITE YOUR SID NO. ON YOUR EXAM.

ALL PROBLEMS HAVE EQUAL VALUE. There are 7 problems.

MA: Do any 5 problems.

Ph.D.: Do 5 problems and only 3 of them from 1, 2, 3, and 4.

[1] Consider the equation

$$f(x) = x^2 - 2x + 1 \quad (1)$$

and let x^* be a solution of $f(x^*) = 0$.

- (a) Give the iteration that results when Newton's method is employed to find the roots of (1).
- (b) Let $e_n = x_n - x^*$ be the error at the n th step of this iteration. Derive a recurrence relation for the error that relates e_n to e_{n-1} .
- (c) What is the rate of convergence of the iteration in (a)? Justify your answer.

[2] Consider the centered difference approximation to $f'(x)$

$$f'(x) \approx \frac{f(x + \Delta x) - f(x - \Delta x)}{2\Delta x}$$

- (a) Derive an expression for the leading term of the truncation error of this approximation.
- (b) Suppose that $f(x + \Delta x)$ and $f(x - \Delta x)$ have an evaluation error of size ε for all Δx , e.g.

$$f_c(x + \Delta x) = f(x + \Delta x) + \varepsilon_1$$

$$f_c(x - \Delta x) = f(x - \Delta x) + \varepsilon_2$$

where $f_c(x + \Delta x)$ and $f_c(x - \Delta x)$ are the "computed" values of f at $x + \Delta x$ and $x - \Delta x$ respectively with $|\varepsilon_1| < \varepsilon$ and $|\varepsilon_2| < \varepsilon$.

How does the error in the approximation of $f'(x)$ behave when the computed values are used and $\Delta x \rightarrow 0$?

- (c) How should Δx be chosen in relation to ε so that the error in the approximation of $f'(x)$ is minimized when computed values are used?

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[3] Consider the following factorization of a tri-diagonal matrix A :

$$A = \begin{pmatrix} a_1 & c_1 & & & \\ b_2 & a_2 & c_2 & & \\ & * & * & * & \\ & & * & * & c_{n-1} \\ & & & b_n & a_n \end{pmatrix} = \begin{pmatrix} 1 & & & & \\ d_2 & 1 & & & \\ & * & * & & \\ & & * & * & \\ & & & d_n & 1 \end{pmatrix} \begin{pmatrix} e_1 & c_1 & & & \\ e_2 & c_2 & & & \\ & * & * & & \\ & & * & * & c_{n-1} \\ & & & e_n & \end{pmatrix}$$

- (a) Derive the recurrence relations that determine the values of the d_k 's and e_k 's in terms of the values of the a_k 's, b_k 's and c_k 's.
- (b) Give a condition on the matrix A which ensures your recurrence relations won't break down.
- (c) Give the formulas that allow you to compute the solution of $A \vec{x} = \vec{b}$ in $O(n)$ operations.

[4] Consider the second order Runge-Kutta method

$$\begin{aligned} y^* &= y^n + \Delta t F(y^n) \\ y^{n+1} &= y^n + \frac{\Delta t}{2} F(y^n) + \frac{\Delta t}{2} F(y^*) \end{aligned}$$

for approximating solutions to the initial value problem

$$\frac{dy}{dt} = F(y), \quad y(t_0) = y_0.$$

Derive an error bound of the form

$$|e_n| \leq C_1 |e_0| + C_2 (\Delta t)^2, \quad n = 1, 2, \dots, N$$

where $e_n = y^n - y(t_n)$, C_1 and C_2 are constants, and $\Delta t = \frac{(T - t_0)}{N}$. Please state your assumptions concerning F .

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[5] For the equation

$$u_{tt} + u_t = u_{xx} + u_x$$

to be solved for $t > 0$ $0 < x < 1$ with periodic boundary conditions

$$u(0, t) = u(1, t), \quad u_x(0, t) = u_x(1, t)$$

and initial data

$$u(x, 0) = \varphi(x)$$

$$u_t(x, 0) = \psi(x)$$

(a) Restate this problem as an equivalent system of first order equations.

(b) Give a convergent second order accurate finite difference approximation to this first order system. Justify your answers.

[6] Consider constructing a numerical method to solve $u_t = u_{xx}$ for $t > 0$, $0 \leq x \leq 1$, with periodic boundary conditions:

$$u(0, t) \equiv u(1, t)$$

and smooth initial data

$$u(x, 0) = \varphi(x)$$

Would you rather use the approximation (A) or (B):

$$\frac{u_i^{n+1} - u_i^{n-1}}{2\Delta t} = \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

$$\frac{u_i^{n+1} - u_i^{n-1}}{2\Delta t} = \frac{u_{i+1}^n - (u_i^{n+1} + u_i^{n-1}) + u_{i-1}^n}{(\Delta x)^2}$$

Describe the stability and convergence properties of both methods.

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[7] Consider the Neumann problem

$$-(u_{xx} + u_{yy}) = f(x, y) \quad -1 \leq x \leq 1 \quad -1 \leq y \leq 1$$

with

$$\frac{\partial u}{\partial \vec{n}} = g$$

(\vec{n} is the outwards unit normal) and the condition

$$\int_{|x|<1, |y|<1} u(x, y) dx dy = 0$$

(a) Why do we need condition (C)?

Now replace (A) by

$$u - (u_{xx} + u_{yy}) = f$$

and keep condition (B).

(b) Do we still need condition C? Why or why not?

(c) Set up a finite element method that converges for the problem (A'), (B)
Justify your answers.