Math 269B, 2012 Winter, Final

Professor Joseph Teran Jeffrey Lee Hellrung, Jr.

March 14, 2012

1 Theory

1. Suppose $u: [0, \infty) \times \mathbb{R} \to \mathbb{R}$ satisfies the inviscid Burger's equation,

$$0 = u_t + \frac{1}{2} (u^2)_x = u_t + uu_x, \quad u(0, x) = u_0(x).$$
 (1)

Use the method of characteristics to show that u must then satisfy the implicit relation

$$u(t,x) = u_0 (x - tu(t,x)).$$
 (2)

[Hint: Begin by defining $\tilde{u}(t,X) := u(t,\varphi(t,X))$ for some to-be-determined change of variables $\varphi : [0,\infty) \times \{X\} \to \{x\}$, and choose φ such that $\tilde{u}_t \equiv 0$.]

- 2. Suppose u_0' in (1) is bounded below, i.e., $u_0' \ge c$ for some constant c. Determine the maximal T such that a solution to (2) is guaranteed to exist for $t \in [0,T)$ (possibly with $T = \infty$). [Hint: Determine when one can guarantee that the function $u \mapsto u u_0(x tu)$ has a root.)
- 3. Solve (1) for $u_0(x) = ax + b$, where a, b are constants. [Hint: Use (2).]
- 4. Denote the solution to (1) by $u = F[u_0]$. Express $F[x \mapsto au_0(x) + b]$ in terms of $F[u_0]$. In other words, given u satisfying (1) for some u_0 , determine the solution v (in terms of the aforementioned u) to

$$v_t + vv_x = 0$$
, $v(0, x) = v_0(x) := au_0(x) + b$.

5. Suppose u_0 is given as

$$u_0(x) := \begin{cases} u_0^L(x) := a_L x + b_L, & x < 0 \\ u_0^R(x) := a_R x + b_R, & x > 0 \end{cases}.$$

Determine the path $t \mapsto (t, x_S(t))$ of the (physically correct) shock in the solution u to (1) eminating from (t, x) = (0, 0). You may use the fact that

$$\frac{1}{2} \int \frac{b_L + b_R + (a_L b_R + a_R b_L) t}{\left(\left(1 + a_L t \right) \left(1 + a_R t \right) \right)^{3/2}} dt = \frac{\left(a_L b_R - a_R b_L \right) t + \left(b_R - b_L \right)}{\left(a_R - a_L \right) \sqrt{\left(1 + a_L t \right) \left(1 + a_R t \right)}} \quad \left[a_L \neq a_R \right].$$

[Hint: Recall that the shock speed $x'_S(t) = \frac{1}{2} (u^L + u^R) (t, x_S(t))$, thus allowing you to set up an ordinary differential equation for x_S .] Consider and explain the physical significance of the special cases $a_L = a_R$ and $b_L = b_R$.

6. Solve the weak form of (1) (i.e., give the entropy solution with rarefaction, and with any shocks propagating at the physically correct speed) on the *periodic* domain [0,4] with the "pulse" initial condition

$$u_0(x) := \begin{cases} 0, & 0 \le x < 1 \\ 2, & 1 < x < 2 \\ 0, & 2 < x \le 4 \end{cases}$$
 (3)

Identify key points in time t when the character of the solution changes. (It will be natural to express the solution u(t,x) piecewise with respect to x and t.) Confirm that $\int u(t,x)dx$ is conserved (i.e., $\int u(t,x)dx = \text{constant for all } t$), and determine $\lim_{t\to\infty} u(t,x)$.

7. (Strikwerda 6.3.9.) Consider a scheme for (6.1.1), $u_t = bu_{xx}$, of the form

$$v_m^{n+1} = \left(1 - 2\alpha_1 - 2\alpha_2\right)v_m^n + \alpha_1\left(v_{m+1}^n + v_{m-1}^n\right) + \alpha_2\left(v_{m+2}^n + v_{m-2}^n\right).$$

Show that when μ is constant, as k and h tend to zero, the scheme is inconsistent unless

$$\alpha_1 + 4\alpha_2 = b\mu$$
.

Show that the scheme is fourth-order accurate in x is $\alpha_2 = -\alpha_1/16$.

2 Programming

- 1. Implement the following numerical schemes to solve (1) on the periodic domain [0, 4]:
 - Godunov's method. At time level n, solve the Riemann problem assuming a piecewise constant initial condition v^n , then resample to determine v^{n+1} .
 - (Backward) Semi-Lagrangian. At time level n+1 and grid vertex m, trace the characteristic $t \mapsto x_m + v_m^n (t t_{n+1})$ backward to time level n and linearly interpolate v^n to determine v_m^{n+1} .
 - (Forward) Semi-Lagrangian. Trace the characteristics $t \mapsto x_m + v_m^n (t t_n)$ forward to time level n+1 and linearly interpolate the nearest characteristics at a given grid vertex m to determine v_m^{n+1} .
 - (Conservative) Lax-Friedrichs. Discretize the conservative form of (inviscid) Burger's equation:

$$\frac{1}{k} \left(v_m^{n+1} - \frac{1}{2} \left(v_{m+1}^n - v_{m-1}^n \right) \right) + \frac{1}{2} \cdot \frac{1}{2h} \left(\left(v_{m+1}^n \right)^2 - \left(v_{m-1}^n \right)^2 \right) = 0$$

- (Advective) Lax-Friedrichs. Discretize the advective form of (inviscid) Burger's equation:

$$\frac{1}{k} \left(v_m^{n+1} - \frac{1}{2} \left(v_{m+1}^n - v_{m-1}^n \right) \right) + v_m^n \frac{1}{2h} \left(v_{m+1}^n - v_{m-1}^n \right) = 0$$

Use the initial condition (3). For those schemes that appear to converge to the exact solution (derived previously), compute a numerical convergence rate. For those schemes that don't appear to converge to the exact solution, explain the discrepancy (e.g., incorrect rarefaction, non-physical shock speed, unstable). Which scheme do you think performs best for the given initial condition?

2. Use your implementation of the Thomas algorithm from Homework 4 to solve *periodic* tridiagonal systems:

$$a_i w_{i-1} + b_i w_i + c_i w_{i+1}, \quad i = 1, \dots, m,$$

with $w_0 = w_m$ and $w_{m+1} = w_1$. The following algorithm is described in Strikwerda. First, solve the following (non-periodic) tridiagonal systems:

$$\begin{split} a_i x_{i-1} + b_i x_i + c_i x_{i+1} &= d_i, \quad x_0 = 0 \text{ and } x_{m+1} = 0; \\ a_i y_{i-1} + b_i y_i + c_i y_{i+1} &= 0, \quad y_0 = 1 \text{ and } y_{m+1} = 0; \\ a_i z_{i-1} + b_i z_i + c_i z_{i+1} &= 0, \quad z_0 = 0 \text{ and } z_{m+1} = 1; \end{split}$$

for i = 1, ..., m. Then w_i is given by

$$w_i = x_i + ry_i + sz_i$$

where

$$r := \frac{1}{D} (x_m (1 - z_1) + x_1 z_m),$$

$$s := \frac{1}{D} (x_m y_1 + x_1 (1 - y_m)),$$

$$D := (1 - y_m) (1 - z_1) - y_1 z_m.$$