

COMP - 285

Analysis of Algorithms

# **Welcome to COMP 285**

## **Lecture 15: Graph DFS + Topological Sort**

Lecturer: Chris Lucas (cflucas@ncat.edu)



**Midterm Grades  
Released!**

**Midpoint Grades  
Submitted!**

**HW4 grades by EoW!**

# **HW5 due in 1 week!**

**10/25 @ 11:59PM ET**

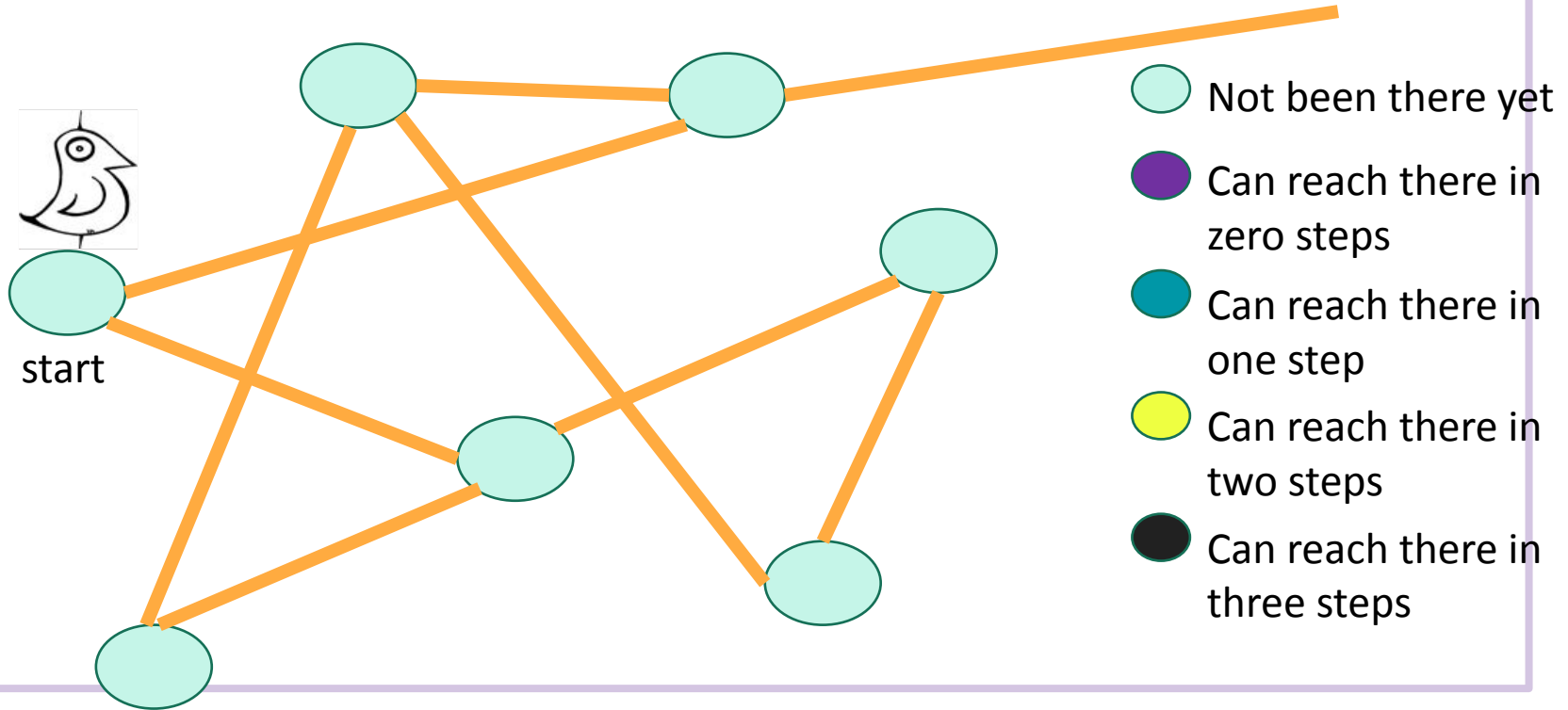
# Quiz!

[www.comp285-fall22.ml](http://www.comp285-fall22.ml)



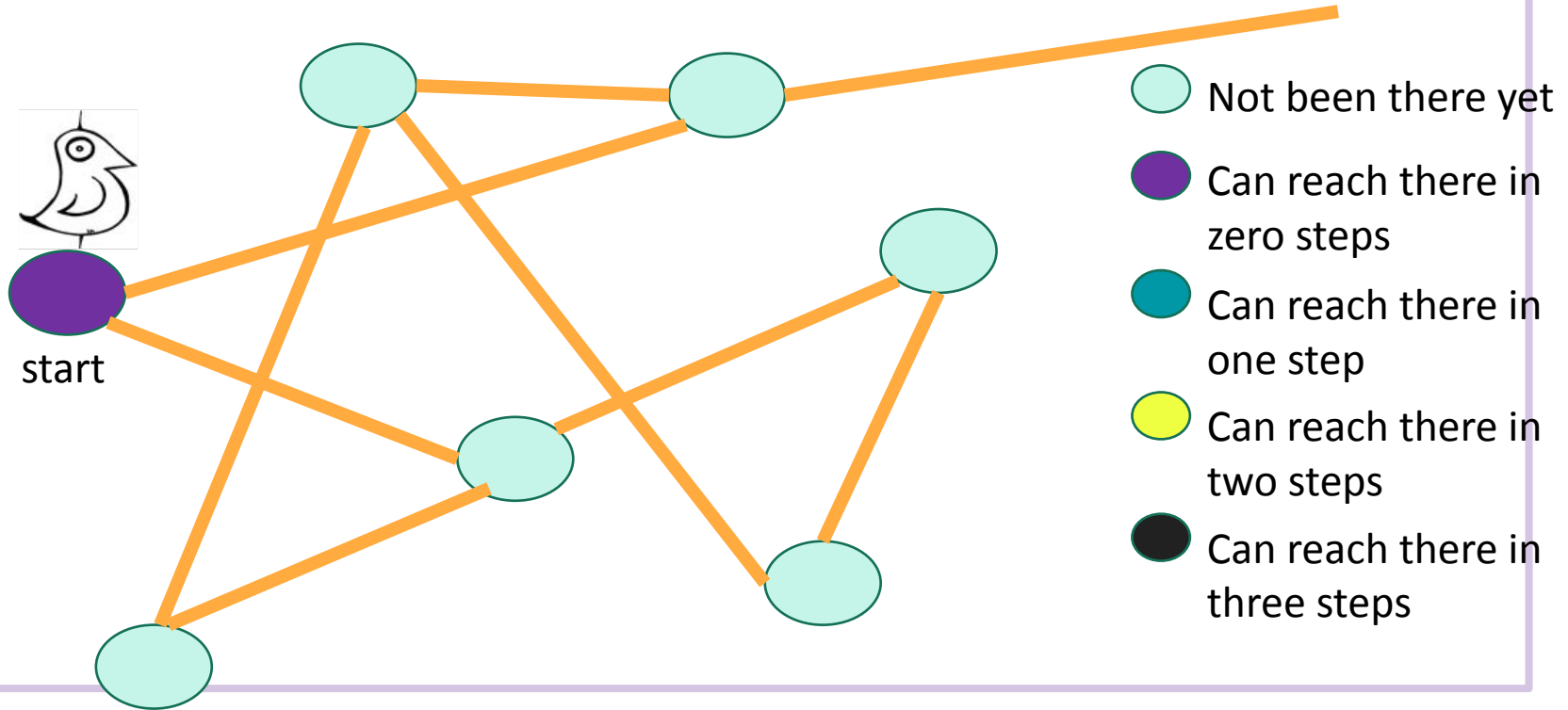
**Recall where we  
ended last lecture...**

## Breadth-First Search: Exploring the world with a bird's-eye view

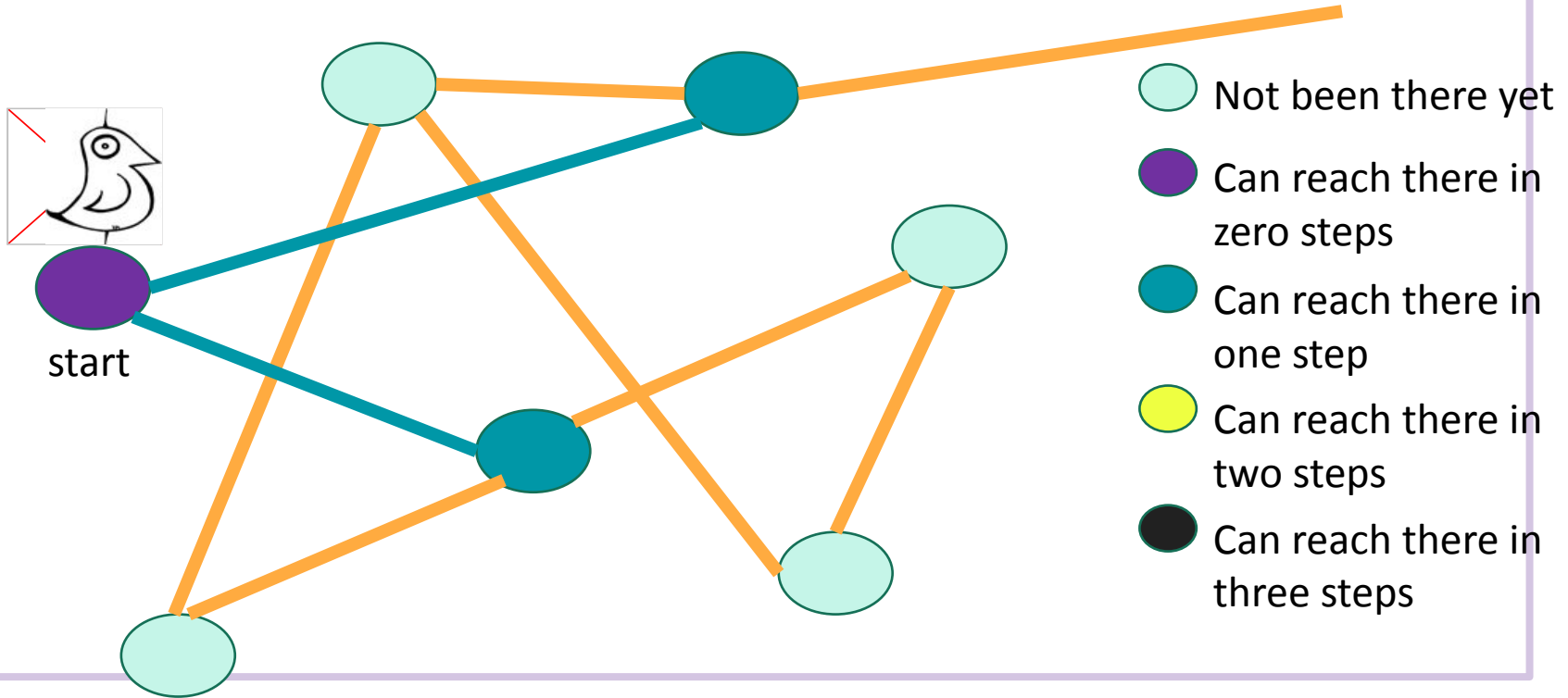




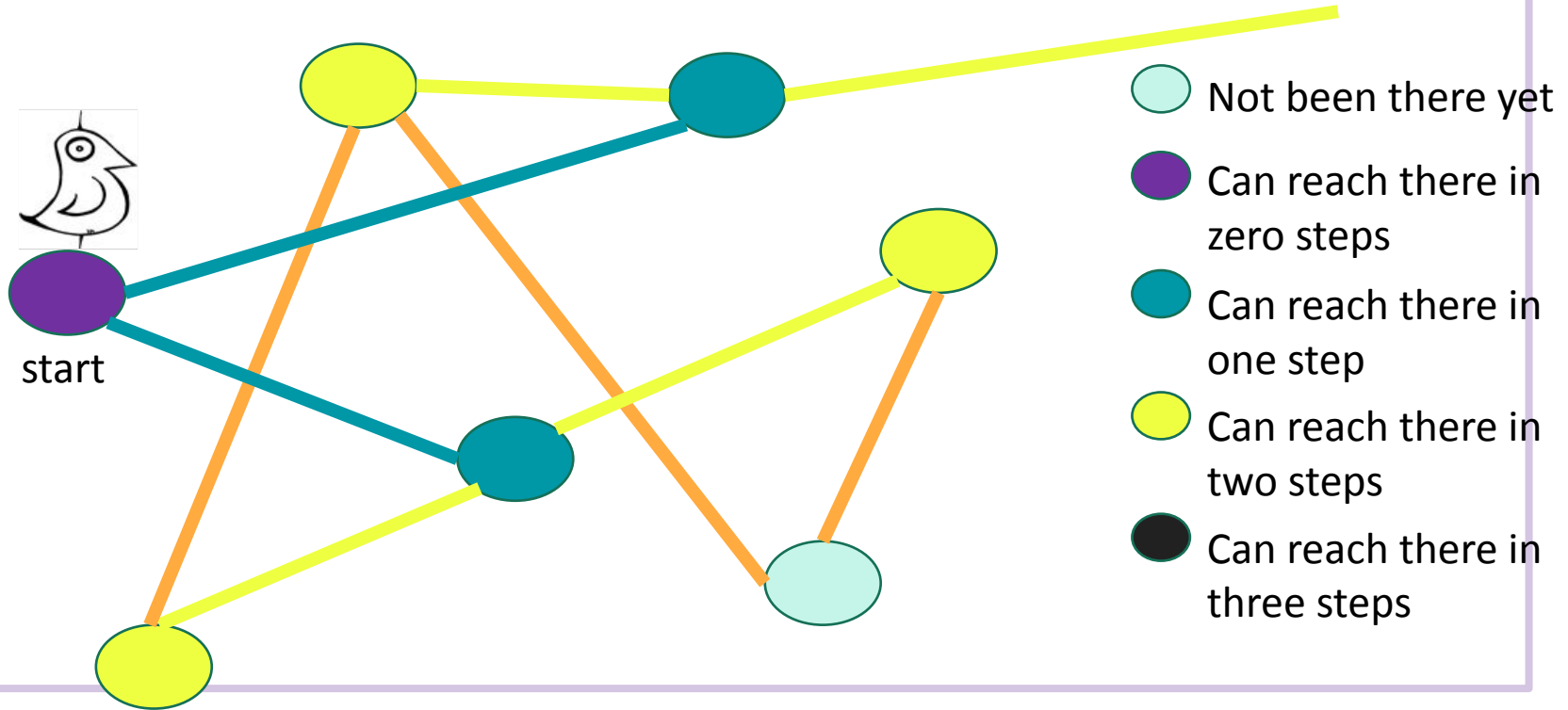
## Breadth-First Search: Exploring the world with a bird's-eye view



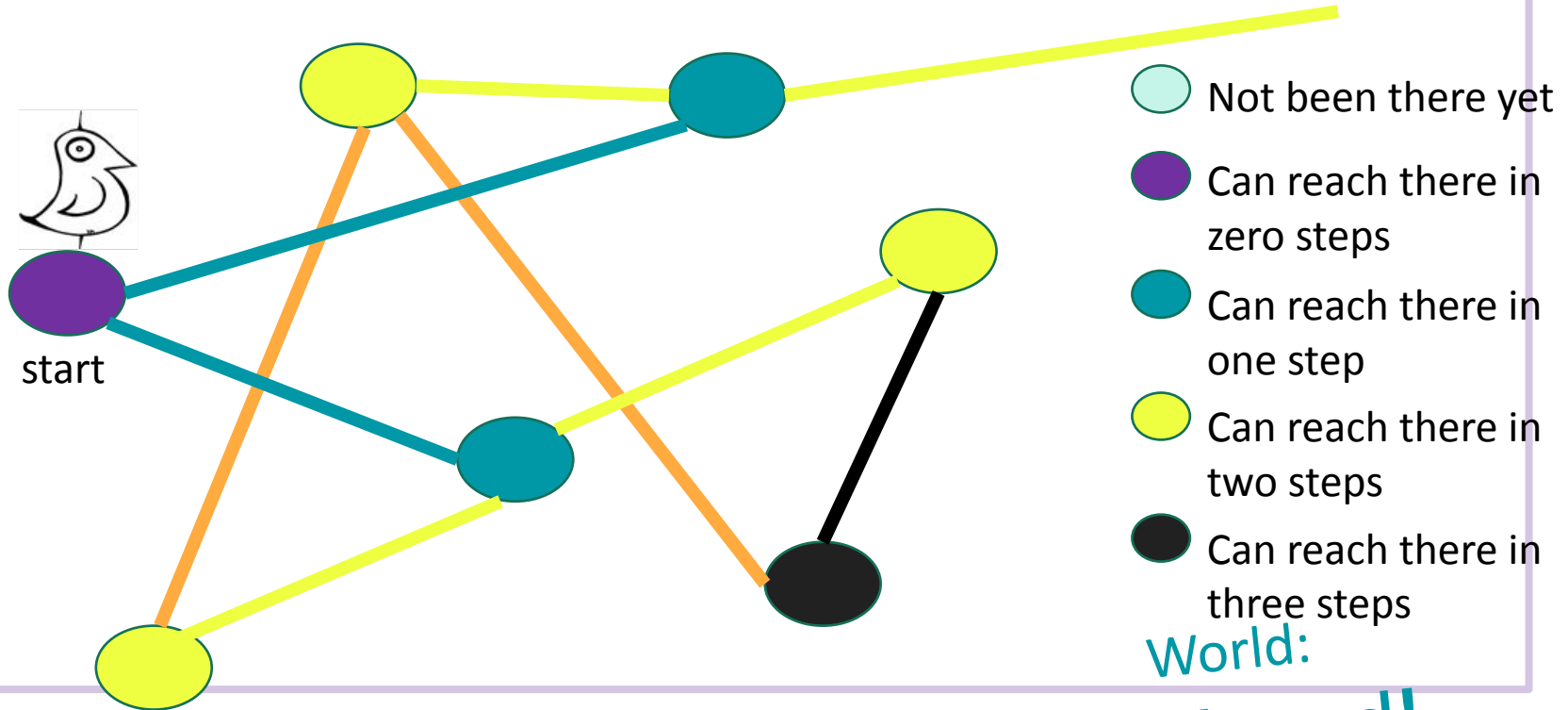
## Breadth-First Search: Exploring the world with a bird's-eye view



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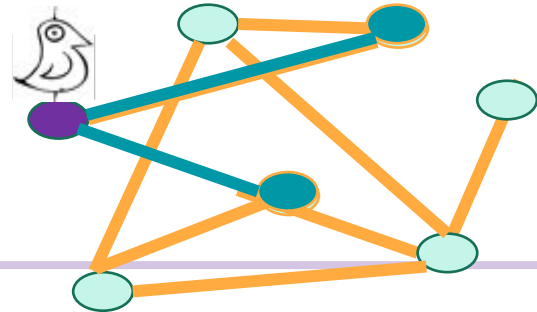
## Breadth-First Search Pseudocode

algorithm bfs

Input: undirected graph  $G = (V, E)$ ,  $s$  and  $d$

Output: true/false if path from  $s$  to  $d$

```
frontier = Queue of integers
visited = {} // empty hash set
frontier.add(s)
visited.insert(s)
while not frontier.empty()
    currNode = frontier.remove()
    if currNode == d
        return true
    for each neighbor of currNode
        if neighbor not in visited
            visited.insert(neighbor)
            frontier.add(neighbor)
return false
```



## Breadth-First Search Pseudocode

algorithm bfs

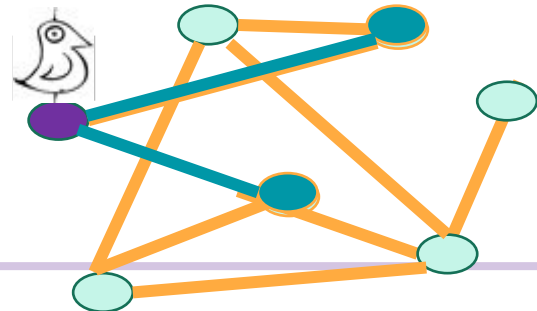
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            frontier.add(neighbor)
return false
```

**Runtime:**  $O(V + E)$

Why? What does this signify?



## Breadth-First Search Pseudocode

algorithm bfs

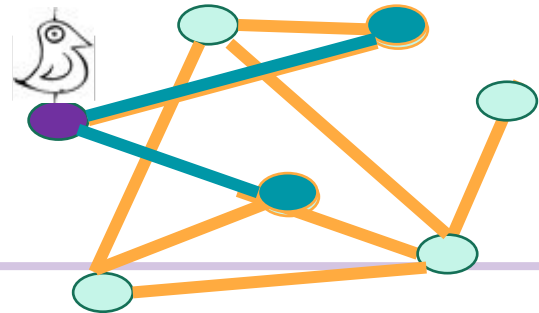
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            visited.insert(neighbor)
            frontier.add(neighbor)
return false
```

**Runtime:**  $O(V + E)$

Traversing every edge and vertex!



## Breadth-First Search Pseudocode

algorithm bfs

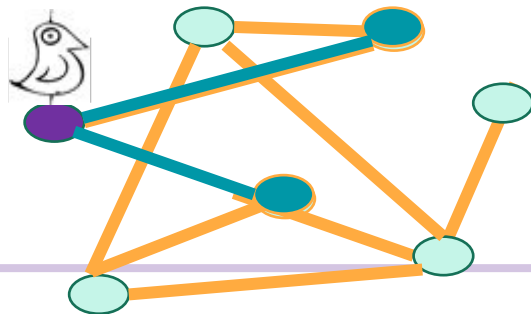
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        if neighbor not in visited
            visited.insert(neighbor)
            frontier.add(neighbor)
return false
```

**Runtime:**  $O(V + E)$

**Space Complexity:** ???





## Breadth-First Search Pseudocode

algorithm bfs

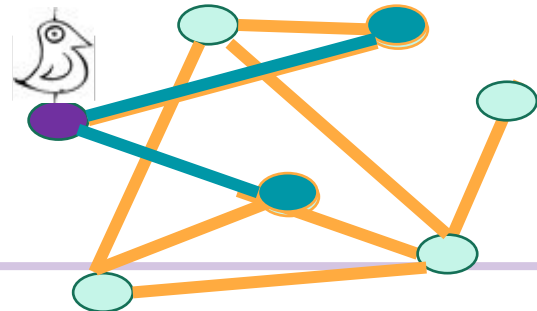
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            frontier.add(neighbor)
return false
```

**Runtime:**  $O(V + E)$

**Space Complexity:**  $O(V)$



## Summary of Breadth-First Search

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- BFS can be written such that starting from a node  $v$ :
  - You find a path to every other vertex in  $G$  (if one exists)
  - You find a path to a specific destination node  $w$
  - (Depends on your use case)
- BFS is guaranteed to find the shortest path between nodes
- BFS running time is  $O(V + E)$ : traversing every node and every edge
- Note that BFS also works on directed graphs.

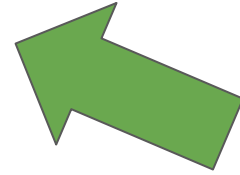
## Big Questions!

- What about Depth-first search (DFS)?
- What's a DAG?
- What about topological sorting (TopoSort)?



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- What about Depth-first search (DFS)?
- What's a DAG?
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# Analogy

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**BFS**



## Analogy

---

**BFS**



**DFS**



## Breadth/Depth-First Search Pseudocode

algorithm BFS

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        return true
    for each neighbor of currNode
        if neighbor not in visited
            visited.insert(neighbor)
            frontier.add(neighbor)
return false
```

algorithm DFS

Input: undirected graph  $G = (V, E)$ ,  $s$  and  $d$

Output: true/false if path from  $s$  to  $d$

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frontier = Stack of integers
visited = {} // empty hash set
frontier.add(s)
visited.insert(s)
while not frontier.empty()
    currNode = frontier.remove()
    if currNode == d
        return true
    for each neighbor of currNode
        if neighbor not in visited
            visited.insert(neighbor)
            frontier.add(neighbor)
return false
```

# One More DFS Implementation...

## algorithm DFS

Input: undirected graph  $G = (V, E)$ , int  $s$  and int  $t$

Output: whether or not there's a path from  $s$  to  $t$

```
visited = new boolean array of size |V|  
return dfsHelper(G, s, t, visited)
```

## algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

```
visited[s] = true  
if s == t  
    return true  
for each neighbor of s, starting from smallest labeled neighbor  
    if !visited[neighbor] and dfsHelper(G, neighbor, t, visited)  
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return false
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## One More DFS Implementation...

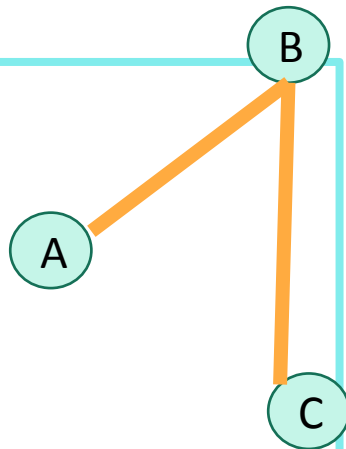
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DFS(A, C) ?



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if  $s == t$ 
```

```
    return true
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for each neighbor of  $s$ , starting from smallest labeled neighbor
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    if !visited[neighbor] and dfsHelper( $G$ , neighbor,  $t$ , visited)
```

```
        return true
```

```
return false
```

**DFS(A, C) ?**

A	B	C
F	F	F

visited



dfsHelper( $G$ , A, C,

F	F	F
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# One More DFS Implementation...

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Input: undirected graph  $G = (V, E)$ , int  $s$  and int  $t$

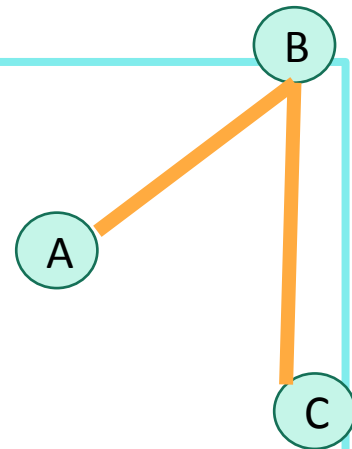
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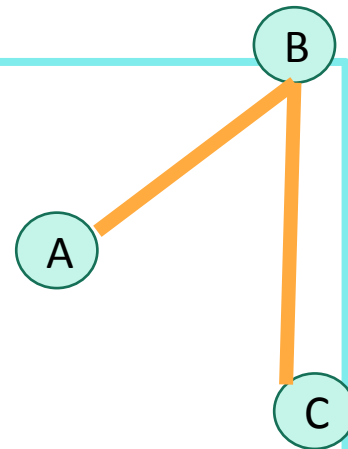
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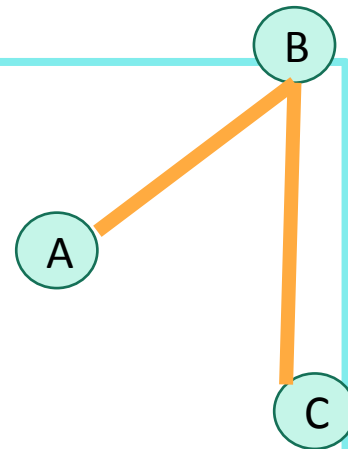
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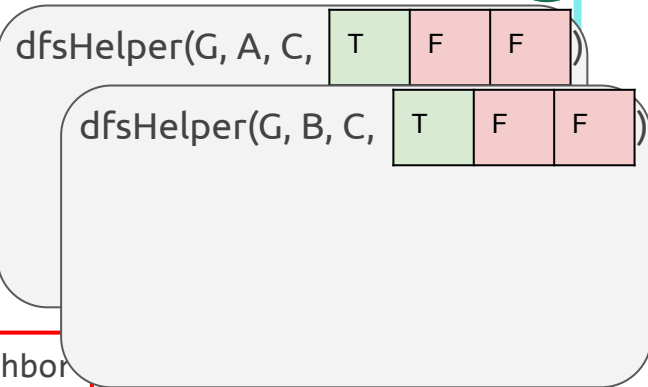
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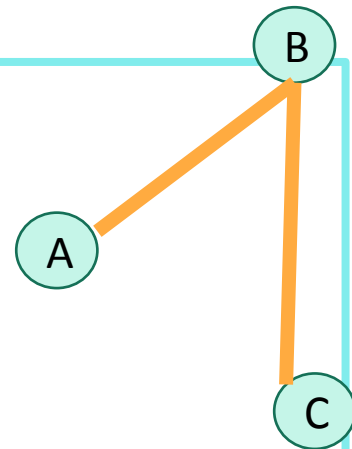
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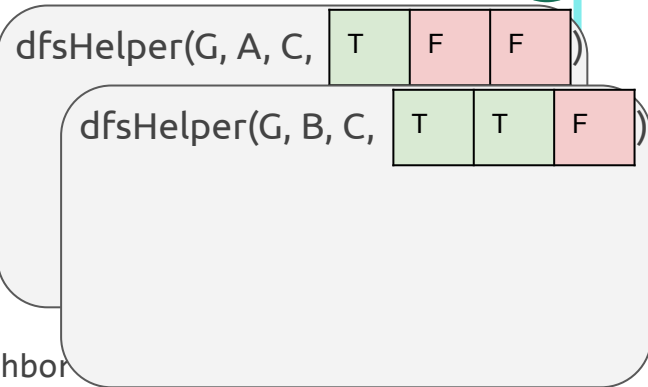
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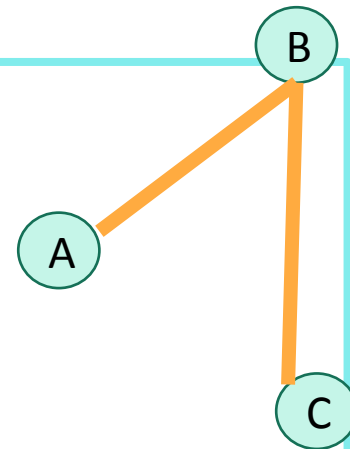
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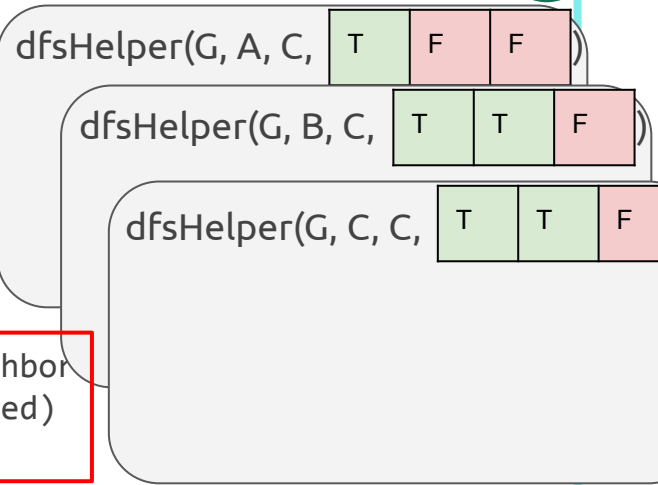
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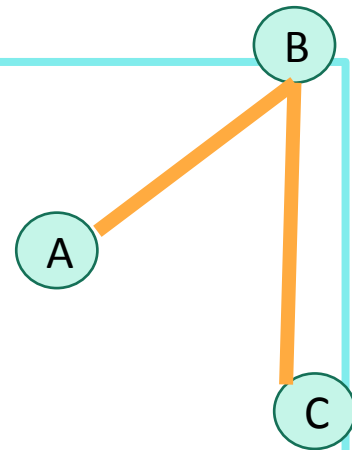
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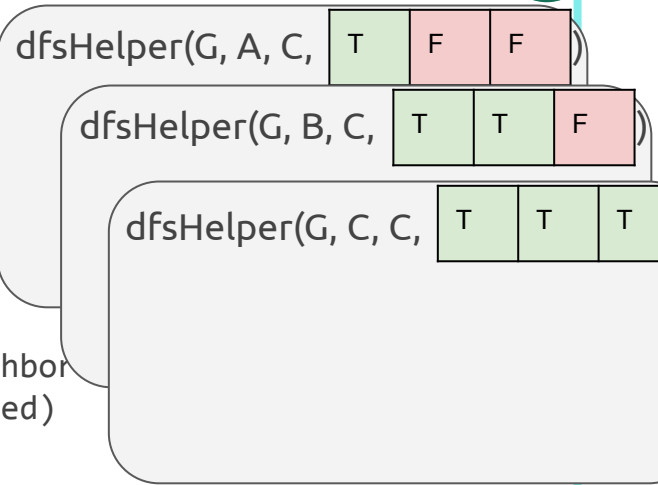
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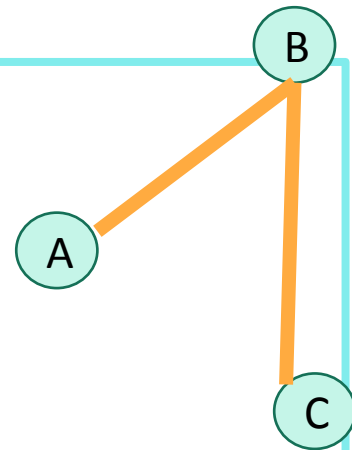
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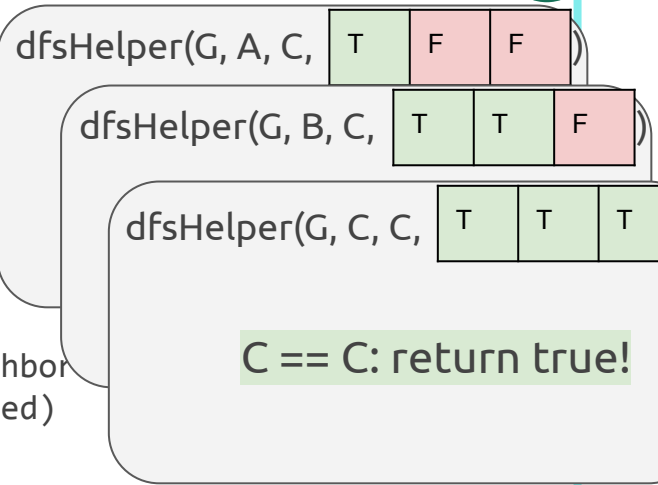
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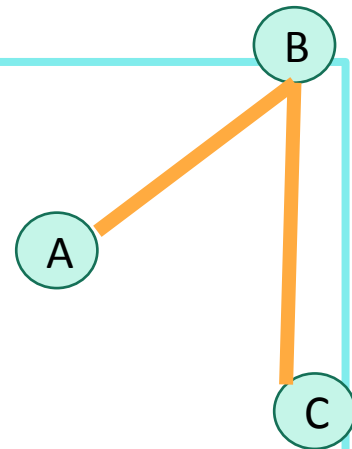
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A	B	C
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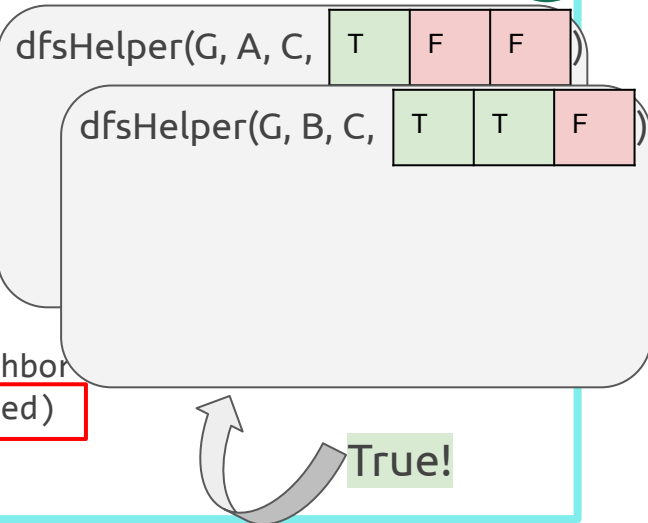


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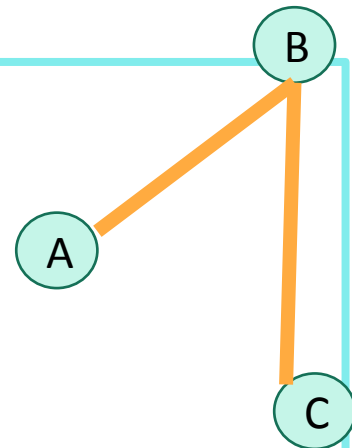
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```
        return true
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```
return false
```

dfsHelper(G, A, C,

T	F	F
---	---	---



True!

## One More DFS Implementation...

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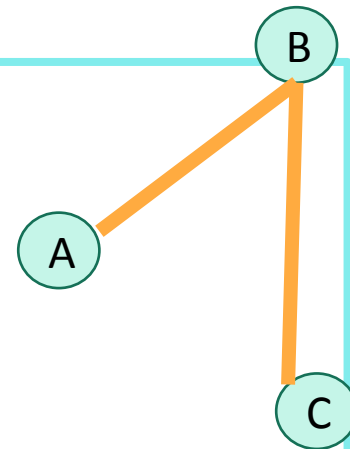
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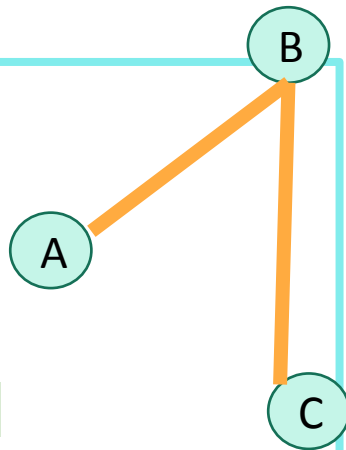
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Output: whether or not there's a path from  $s$  to  $t$

```
visited = new boolean array of size |V|  
return dfsHelper(G, s, t, visited)
```

**DFS(A, C) is True!**



### algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

```
visited[s] = true  
if s == t  
    return true  
for each neighbor of s, starting from smallest labeled neighbor  
    if !visited[neighbor] and dfsHelper(G, neighbor, t, visited)  
        return true  
return false
```

# Kahoot!

[www.kahoot.it](http://www.kahoot.it), Code: XXX YYY

Enter your @aggies.ncat email



# One More DFS Implementation...

## algorithm DFS

Input: undirected graph  $G = (V, E)$ , int  $s$  and int  $t$

Output: whether or not there's a path from  $s$  to  $t$

```
visited = new boolean array of size |V|  
return dfsHelper(G, s, t, visited)
```

**Time Complexity?**  $O(V + E)$

**Space Complexity?**  $O(V)$

## algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

```
visited[s] = true  
if s == t  
    return true  
for each neighbor of s, starting from smallest labeled neighbor  
    if !visited[neighbor] and dfsHelper(G, neighbor, t, visited)  
        return true  
return false
```

# Depth-First Search Pseudocode

## algorithm DFS

Input: undirected graph  $G$ , int  $s$  and int  $t$

Output: whether or not there's a path from  $s$  to  $t$

visited = new boolean array of size  $|V|$

return dfsHelper( $G$ ,  $s$ ,  $t$ , visited)

## algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

visited[ $s$ ] = true

if  $s == t$

    return true

for each neighbor of  $s$ , starting from smallest labeled neighbor

    if !visited[neighbor] and dfsHelper( $G$ , neighbor,  $t$ , visited)

        return true

return false

## algorithm DFS

Input: undirected graph  $G = (V, E)$ ,  $s$  and  $d$

Output: true/false if path from  $s$  to  $d$

frontier = Stack of integers

visited = {} // empty hash set

frontier.add( $s$ )

visited.insert( $s$ )

while not frontier.empty()

    currNode = frontier.remove()

    if currNode ==  $d$

        return true

    for each neighbor of currNode

        if neighbor not in visited

            visited.insert(neighbor)

            frontier.add(neighbor)

return false

# Depth-First Search Pseudocode

## algorithm DFS

Input: undirected graph  $G$ , int  $s$  and int  $t$

Output: whether or not there's a path from  $s$  to  $t$

visited = new boolean array of size  $|V|$

return dfsHelper( $G$ ,  $s$ ,  $t$ , visited)

## algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

visited[ $s$ ] = true

if  $s == t$

return true

for each neighbor of  $s$ , starting from smallest labeled neighbor

if !visited[neighbor] and dfsHelper( $G$ , neighbor,  $t$ , visited)

return true

return false **Time Complexity?**  $O(V + E)$

**Space Complexity?**  $O(V)$

## algorithm DFS

Input: undirected graph  $G = (V, E)$ ,  $s$  and  $d$

Output: true/false if path from  $s$  to  $d$

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while not frontier.empty()

currNode = frontier.remove()

if currNode ==  $d$

return true

for each neighbor of currNode

if neighbor not in visited

visited.insert(neighbor)

frontier.add(neighbor)

return false

**Time Complexity?** ???

**Space Complexity?** ???

# Kahoot!

[www.kahoot.it](http://www.kahoot.it), Code: XXX YYY

Enter your @aggies.ncat email

# Depth-First Search Pseudocode

## algorithm DFS

Input: undirected graph  $G$ , int  $s$  and int  $t$

Output: whether or not there's a path from  $s$  to  $t$

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visited = new boolean array of size  $|V|$   
return dfsHelper( $G$ ,  $s$ ,  $t$ , visited)
```

## algorithm DFSHelper

Input: undirected graph  $G = (V, E)$ ,  $s$ ,  $t$ , and visited

Output: whether or not there's a path from  $s$  to  $t$

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visited[s] = true  
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for each neighbor of  $s$ , starting from smallest  
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    if !visited[neighbor] and dfsHelper( $G$ ,  
neighbor,  $t$ , visited)  
        return true  
return false
```

**Time Complexity?**  $O(V + E)$   
**Space Complexity?**  $O(V)$

## algorithm DFS

Input: undirected graph  $G = (V, E)$ ,  $s$  and  $d$

Output: true/false if path from  $s$  to  $d$

```
frontier = Stack of integers  
visited = {} // empty hash set  
frontier.add( $s$ )  
visited.insert( $s$ )  
while not frontier.empty()  
    currNode = frontier.remove()  
    if  $currNode == d$   
        return true  
    for each neighbor of currNode  
        if neighbor not in visited  
            visited.insert(neighbor)  
            frontier.add(neighbor)  
return false
```

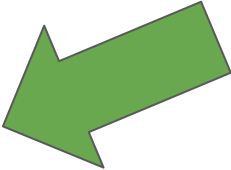
**Time Complexity?**  $O(V+E)$   
**Space Complexity?**  $O(V)$

# Application: Flood Fill

- Microsoft Paint Bucket Tool
- Note that images can be represented as a grid of pixels
- To fill every connected pixel that is the same color as the “seed”, we can use a BFS or DFS
- We look up, down, left, and right, and explore the next node only if it is the same color as the seed



## Big Questions!

- What about Depth-first search (DFS)?
- What's a DAG? 
- What about topological sorting (TopoSort)?



## Directed Acyclic Graphs (DAGs)

---

When we have a graph that is both directed and has no loops (acyclic), we call it a Directed Acyclic Graph (a.k.a DAG).

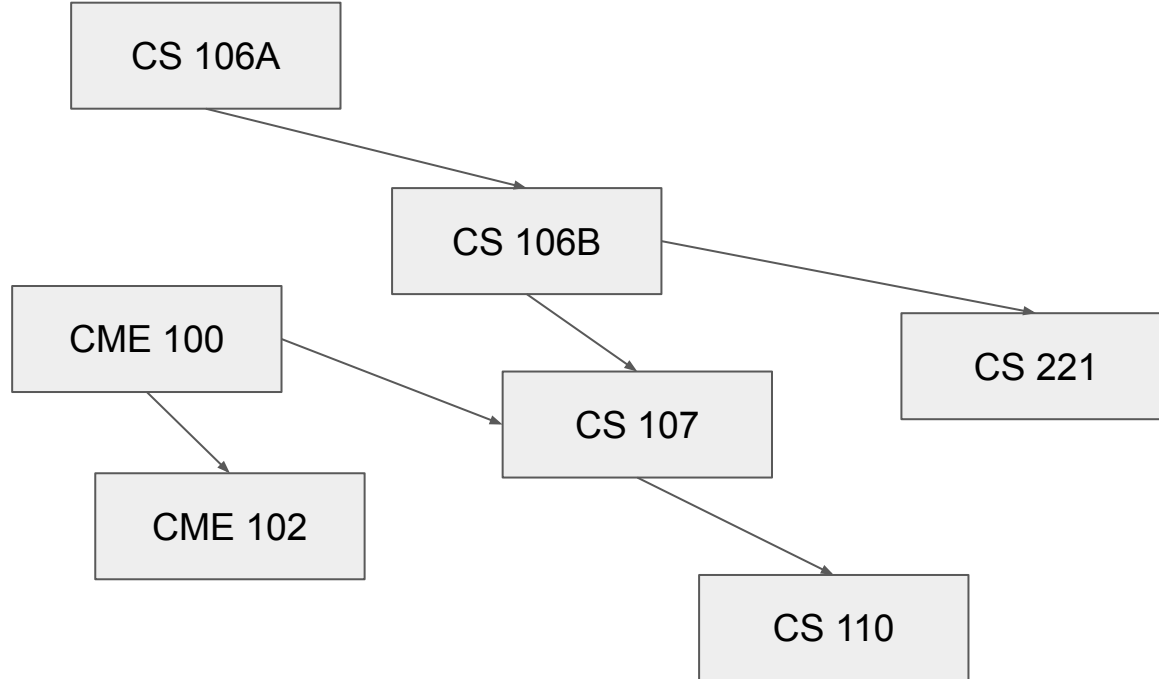
They're useful for representing real-world dependencies.

Directed graphs (not just DAGs) have nodes that are:

- Sources: no inbound edges (i.e. no arrows pointing to it)
- Sinks: no outbound edges (i.e. no arrows pointing away from it)



# Course Prerequisites



# Kahoot!

[www.kahoot.it](http://www.kahoot.it), Code: XXX YYYY

Enter your @aggies.ncat email

## Polls

Is this a DAG?

Yes

Which Nodes are source nodes?

3, 5

Which Nodes are sink nodes?

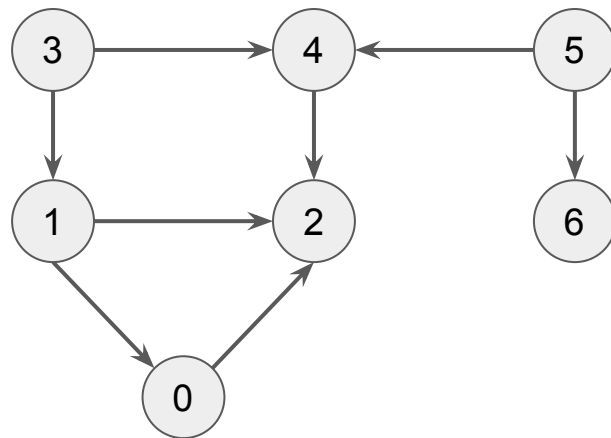
2, 6

If we ran DFS starting at 4 and followed only the outbound edges, what would we print out?

4, 2

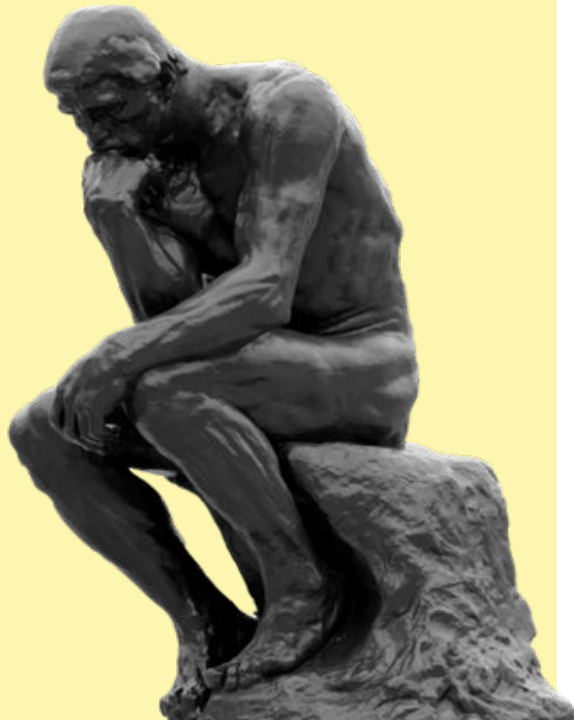
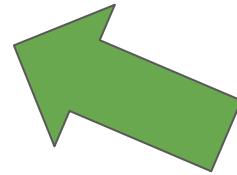
If we ran DFS starting at 3 and only followed the outbound edges, what would we print out? (Ties broken numerically, smallest node value first)

3, 1, 0, 2, 4



## Big Questions!

- What about Depth-first search (DFS)?
- What's a DAG?
- What about topological sorting (TopoSort)?



# Topological Sort

---

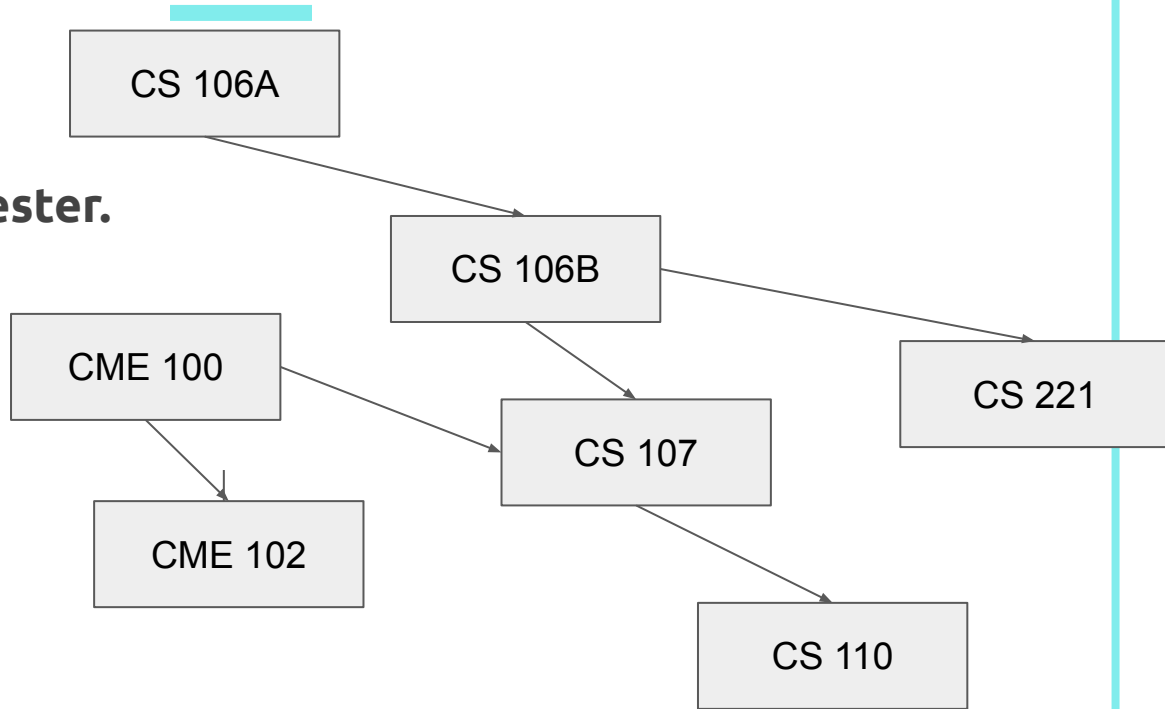
- "A topological sort of a DAG  $G = (V, E)$  is a linear ordering of all its vertices such that if  $G$  contains an edge  $(u, v)$  then  $u$  appears before  $v$  in the ordering. (If the graph contains a cycle, then no linear ordering is possible.)"
  - Fancy way of saying "give me one valid ordering of a DAG's nodes."
  - If  $U \rightarrow V$  in graph, means node  $U$  must occur before node  $V$  in order
  - Only possible to calculate this for DAGs
- A valid topological sort will have all "pre-req" nodes appear before the nodes that depend on those pre-reqs.
- "Sort" is misleading. Don't confuse this with the sorts we saw before. Topological "ordering" is another name that may be less confusing.

# Topological Sort Example #1

**What's one valid course ordering?**

**Assume 1 course per semester.**

CME 100  
CME 102  
CS 106A  
CS 106B  
CS 107  
CS 221  
CS 110

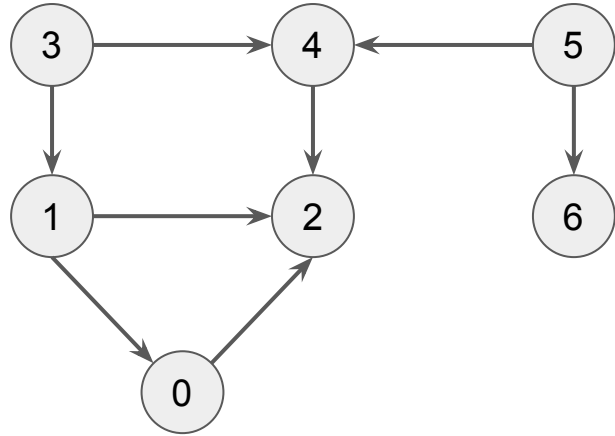


## Topological Sort Example #2

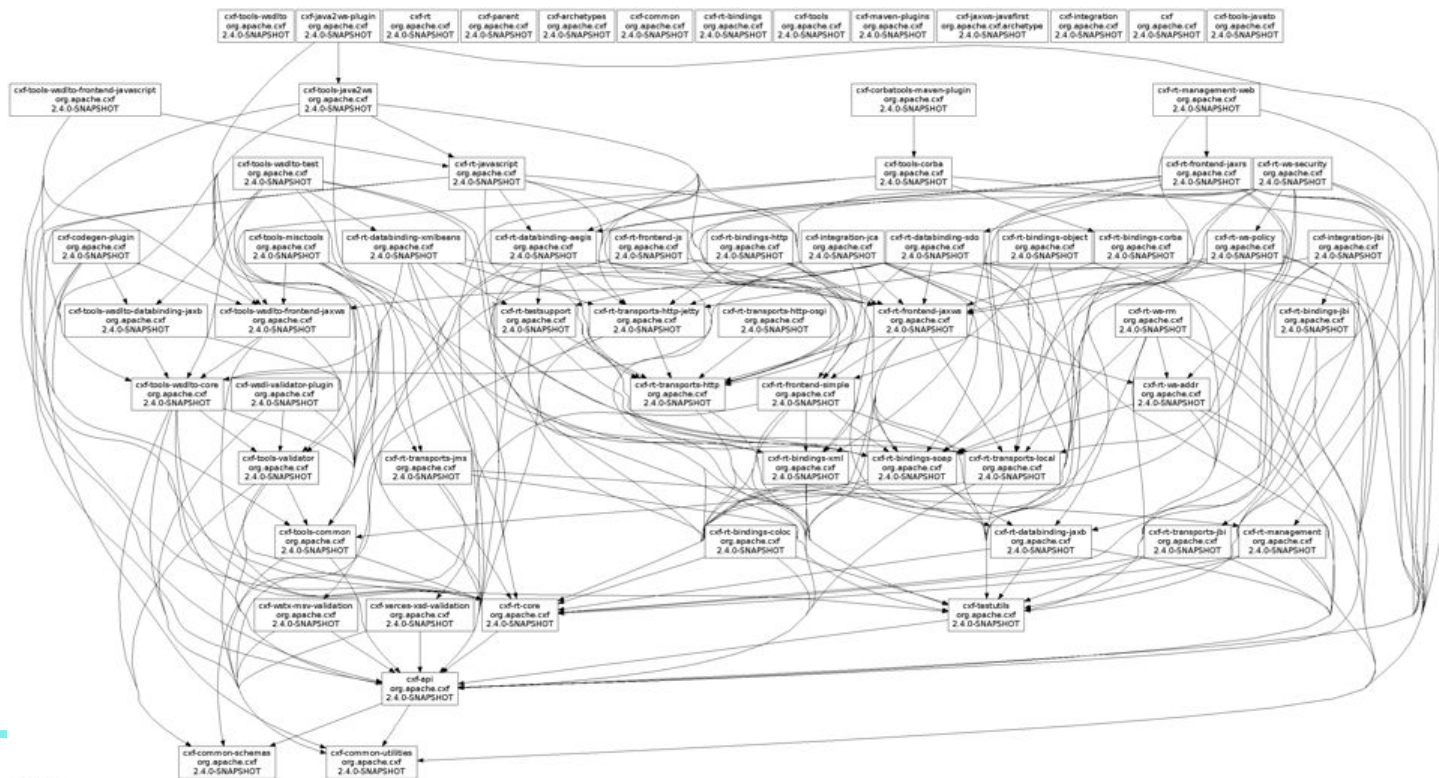
---

**What's one valid ordering?**

5, 4, 6, 3, 1, 0, 2



# Can't always eyeball it...





# Topological Sort Algorithm

---

- Note that some valid orderings laid out each “child” until we reached a sink.
- We can actually perform a DFS, starting at source nodes and reverse the DFS finishing times to get a valid topological sort.

## Topological Sort Algorithm

---

- Note that some valid orderings laid out each “child” until we reached a sink.
- We can actually perform a DFS, starting at source nodes and reverse the DFS finishing times to get a valid topological sort.



**How do we know which  $v$  in  $G(V, E)$  are source nodes?**

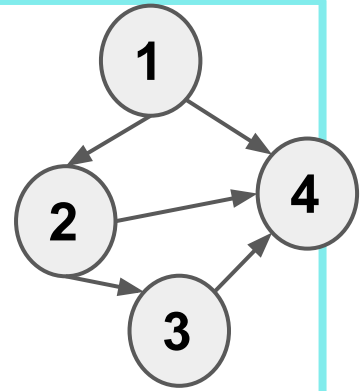
# Graph Representation Examples

	destination			
start	0	1	0	1
	0	1	1	1
	0	0	0	1
	0	0	0	0

*Adjacency Matrix*

1: [2, 4]  
2: [4, 2, 3]  
3: [4]  
4: []

*Adjacency List*



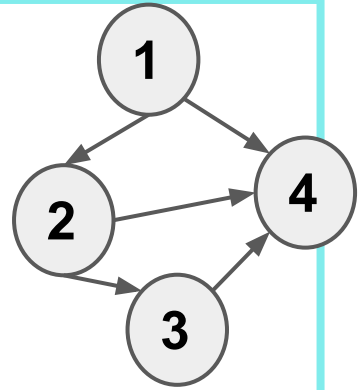
**How do we know which  $v$  in  $G(V, E)$  are source nodes?**

# Graph Representation Examples

	destination			
start	0	1	0	1
	0	1	1	1
	0	0	0	1
	0	0	0	0

*Adjacency Matrix*

- **Sources:** ???
- **Sinks:** ???



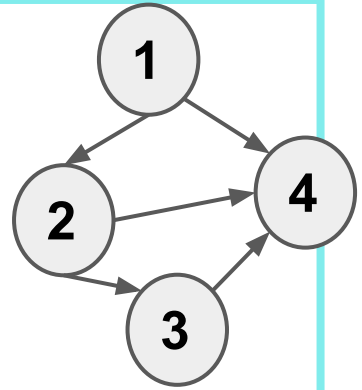
**How do we know which  $v$  in  $G(V, E)$  are source/sink nodes?**

# Graph Representation Examples

	destination			
start	0	1	0	1
	0	1	1	1
	0	0	0	1
	0	0	0	0

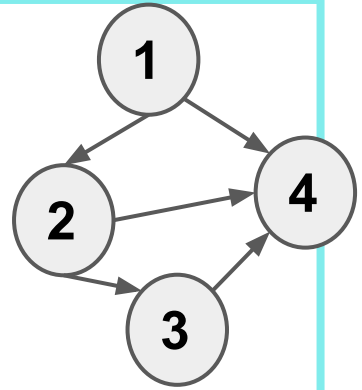
*Adjacency Matrix*

- **Sources:** Columns of all 0s
- **Sinks:** Rows of all 0s



**How do we know which  $v$  in  $G(V, E)$  are source/sink nodes?**

# Graph Representation Examples



- **Sources:** ???

- **Sinks:** ???

1: [2, 4]

2: [4, 2, 3]

3: [4]

4: []

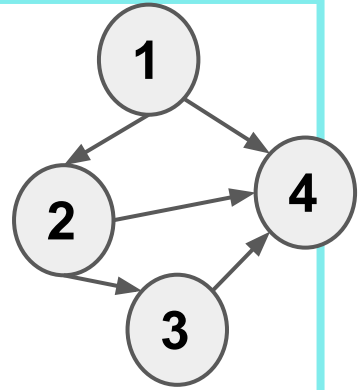
*Adjacency List*

**How do we know which  $v$  in  $G(V, E)$  are source nodes?**

## Graph Representation Examples

- **Sources:** Node that doesn't appear in any list
- **Sinks:** Node that has empty list

1: [2, 4]  
2: [4, 2, 3]  
3: [4]  
4: []



*Adjacency List*

**How do we know which  $v$  in  $G(V, E)$  are source nodes?**

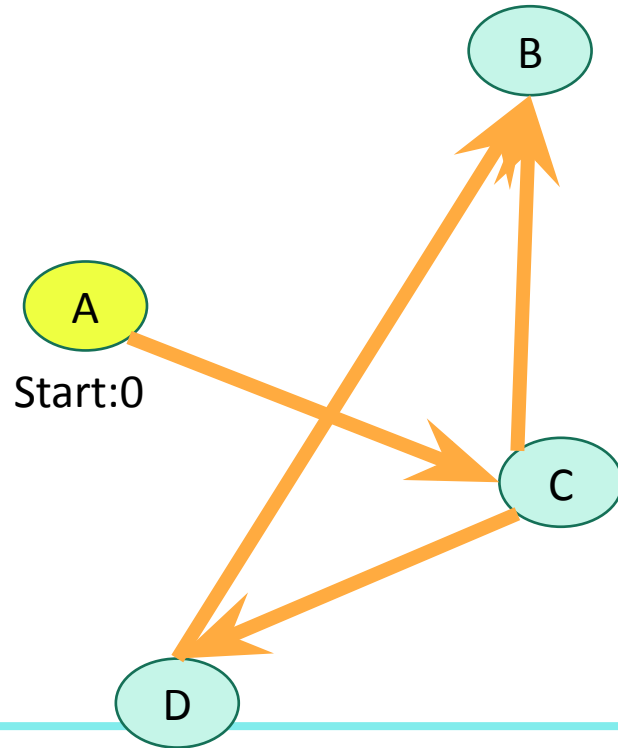
# Topological Sort Algorithm

---

- Note that some valid orderings laid out each “child” until we reached a sink.
- We can actually perform a DFS, starting at source nodes and reverse the DFS finishing times to get a valid topological sort.

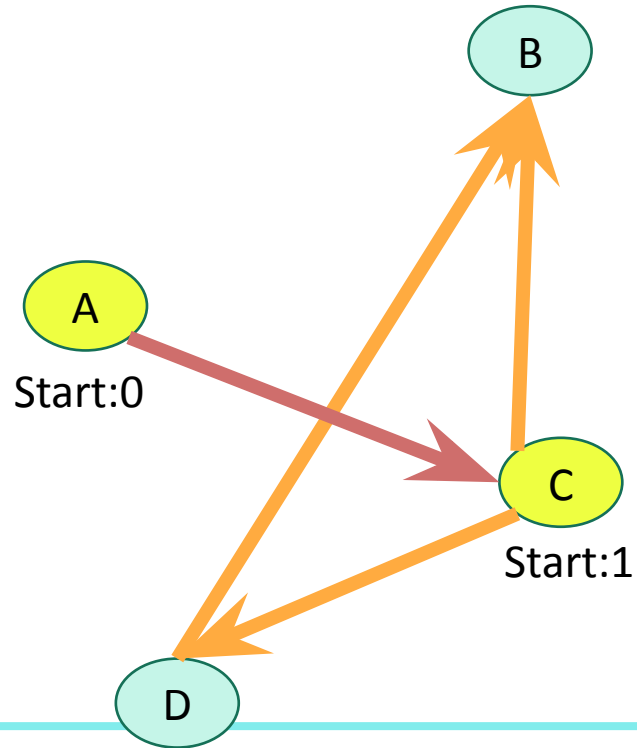


# TopoSort Example



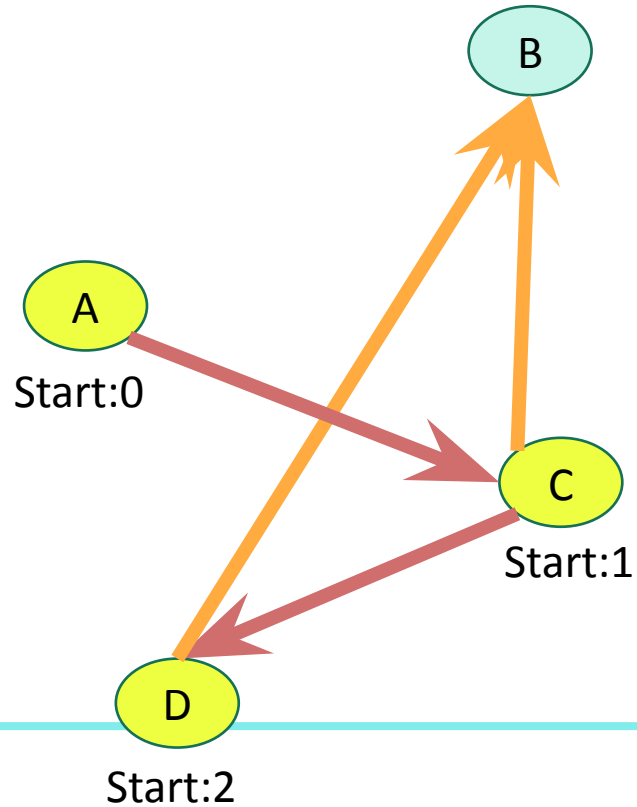
- Unvisited
- In progress
- All done


# TopoSort Example



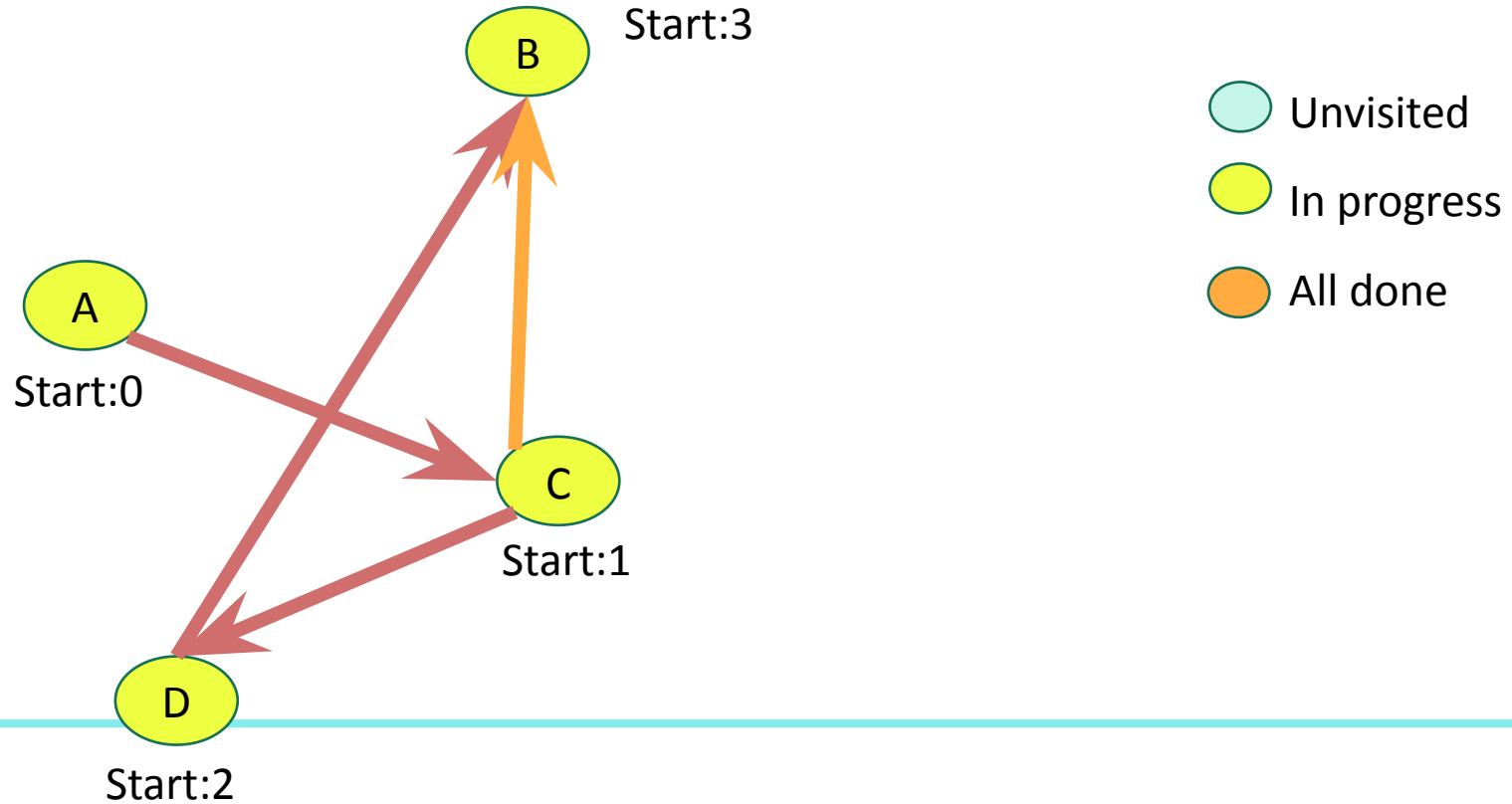
- Unvisited
- In progress
- All done

# TopoSort Example

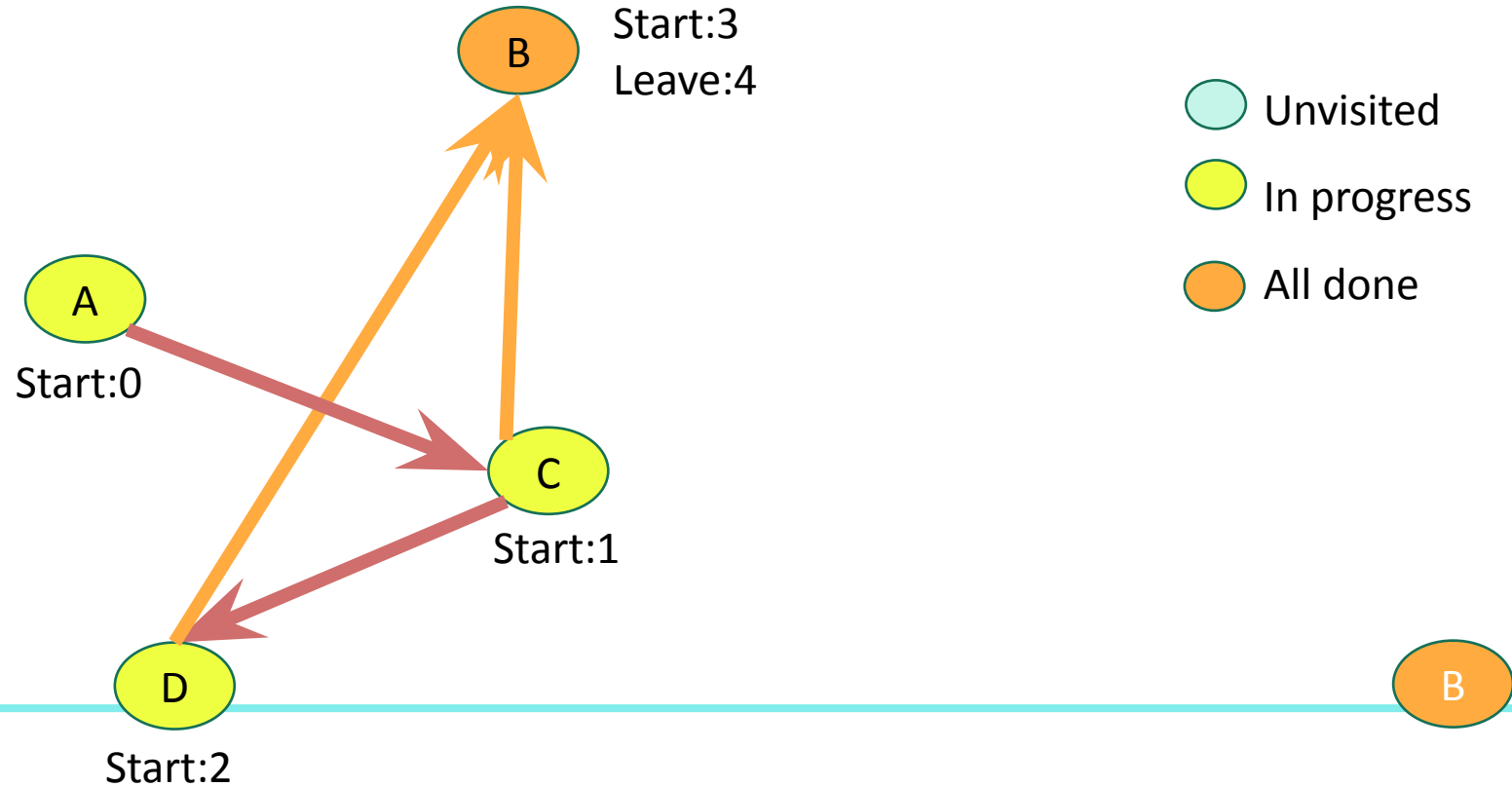


-  Unvisited
-  In progress
-  All done

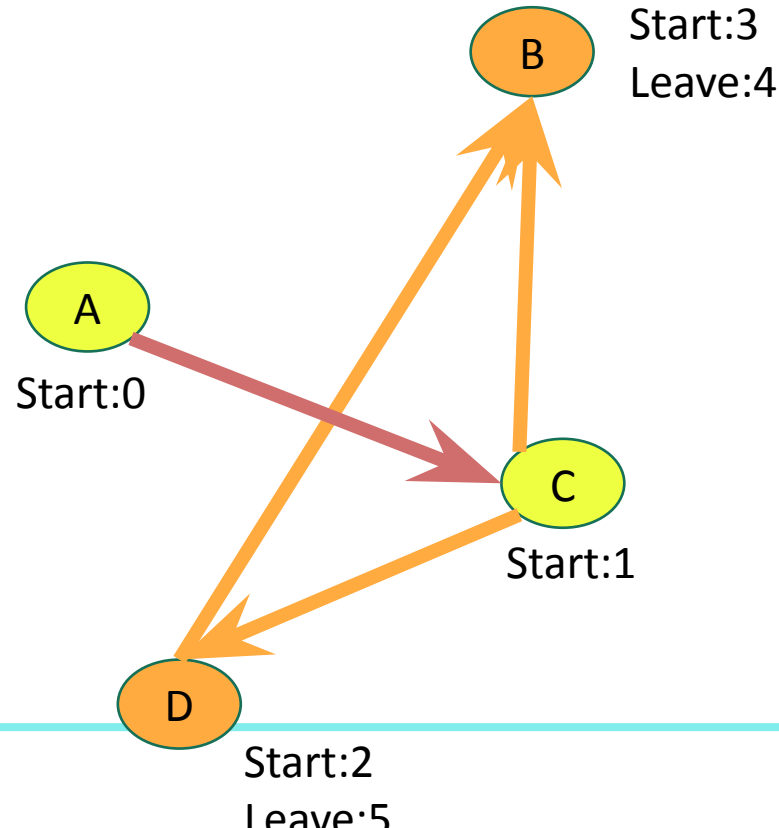
# TopoSort Example



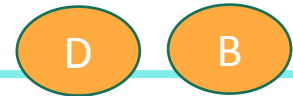
# TopoSort Example



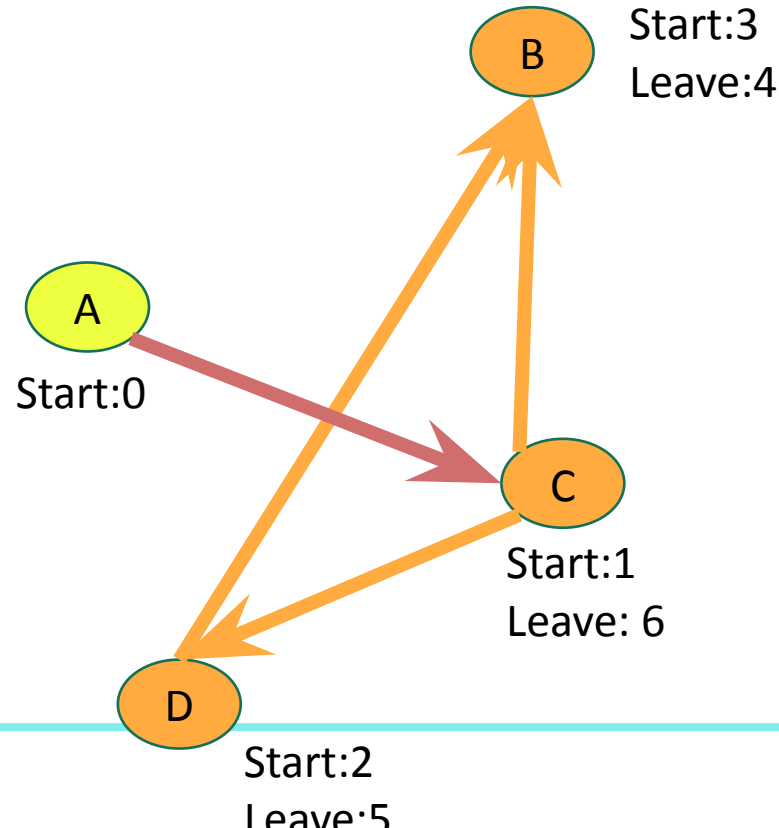
# TopoSort Example



- Unvisited
- In progress
- All done



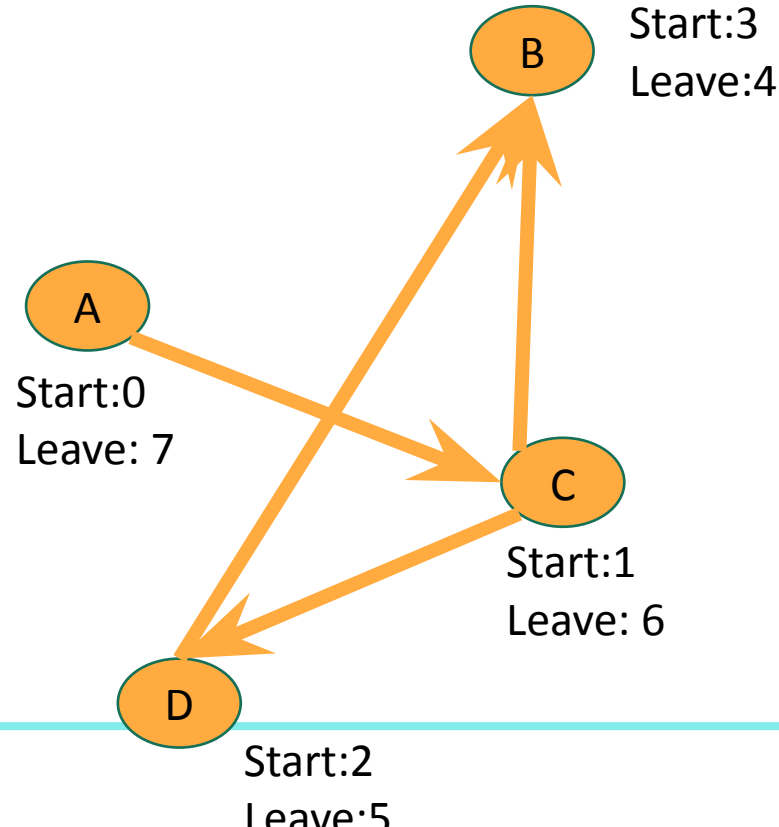
# TopoSort Example



- Unvisited
- In progress
- All done

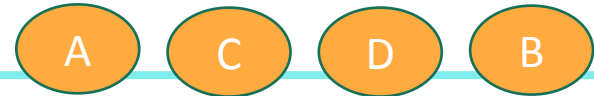


# TopoSort Example



- Unvisited
- In progress
- All done

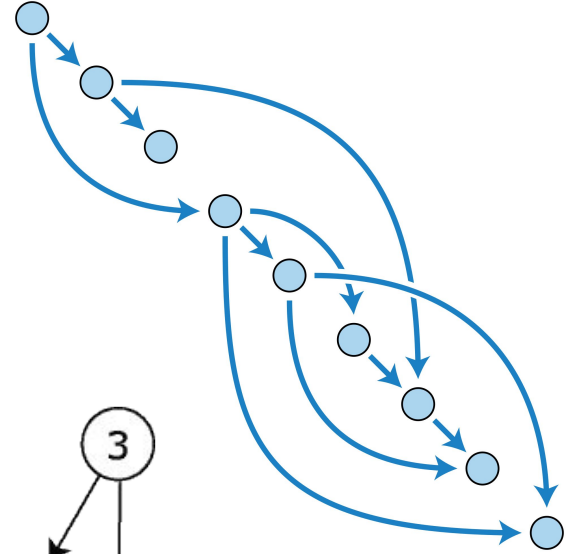
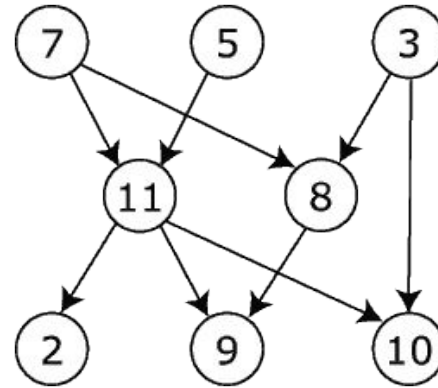
Do them in this order:





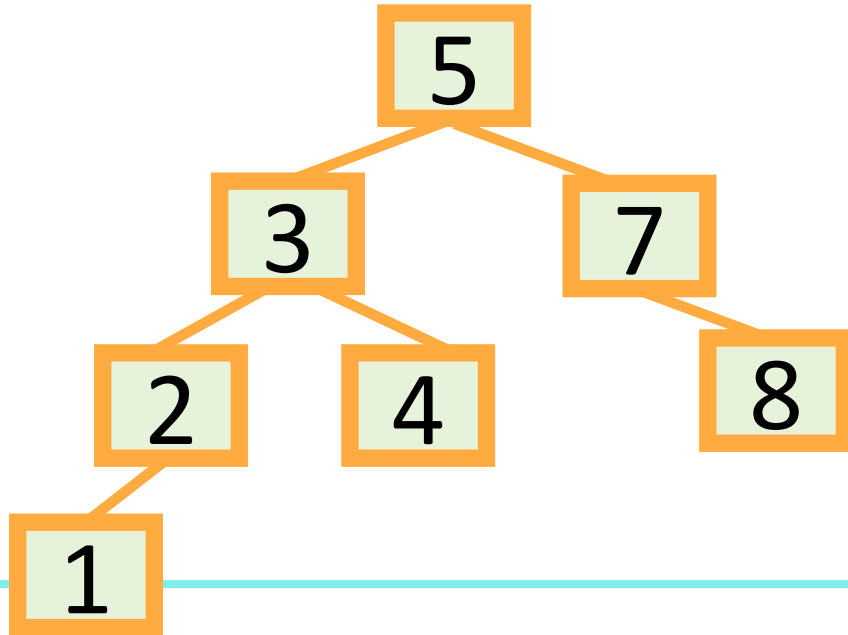
## TopoSort Code

For implementation,  
see [repl.it](https://repl.it)



## Another use of DFS that we've already seen...

- In-order enumeration of binary search trees



Perform DFS and print a node's label when you are done with the left child and before you begin the right child.

COMP - 285

Analysis of Algorithms

# **Welcome to COMP 285**

## **Lecture 15: Graph DFS + Topological Sort**

Lecturer: Chris Lucas (cflucas@ncat.edu)

