



Design variables

xs, ys: in-plane (xy-plane)
location of control support rod
hs: height of central support rod

O: = angle from XY-plane to support rod i

l: = length of ith support rod

$$\begin{aligned} & \ell_{i} = \| \times_{i} - \times_{s} \|^{2} = \left[ (\times_{i} - \times_{s})^{2} + (Y_{i} - Y_{s})^{2} + (\xi_{i} - \xi_{s})^{2} \right]^{1/2} \\ & \ell_{i} \sin \theta_{i} = \mathcal{Z}_{i} - \left( -h_{cG} + h_{s} \right) \\ & \theta_{i} = \arcsin \left[ \frac{\mathcal{Z}_{i} - \left( -h_{cG} + h_{s} \right)}{\mathcal{I}_{i}} \right] \end{aligned}$$