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momer: Exposing the Python library momepy in R

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Executive Summary

Signatories

Community members of:

- [Rbanism](#)
- [r-spatial](#)
- [geocompr](#)
- [SDSL](#)
- ???

Project team

Claudiu Forgaci is assistant professor of urban design and analytics engaged in urban morphology research. Claudiu is experienced in R package development (see [rcrisp](#), [rcoins](#), and [visor](#)), he is a member of the Spatial Data Science across Languages (SDSL) community. He is also one of the initiators of the [Rbanism community](#) promoting reproducibility, automation and scalability in urbanism research using R. Claudiu will lead the development of **momer** and will **maintain** it after completion.

John Doe is a research software engineer at the TU Delft Digital Competence Center ... **Jane Doe** is a research software engineer at the TU Delft Digital Competence Center ... John and Jane

will carry out the software engineering work planned in this project with a shared 0.4FTE for the planned duration of the project.

Contributors

The creator of `momepy` ??? and members of the SDSL community ???, ??? and ??? provided input at the proposal stage.

Consulted

ISC member **Name Surname**, also member of the SDSL community, provided feedback on the proposal.

The Problem

Urban morphometrics is an growing sub-field of urban morphology that enables scalable quantitative analysis of urban form. The field of urban morphometrics is inherently programmatic and has been heavily driven and promoted by the Python library `momepy` (Fleischmann 2019). While `momepy` has played an important role in making the quantitative analysis of urban form accessible to many, it is limited to users of the Python programming language.

Moreover, a large part of urban morphology research is conducted with GUI-based tools and qualitative interpretation, which limits the kind of analytical questions that can be asked. Automated, reproducible and scalable urban morphology research can only be truly achieved in a programmatic way. Considering that those three objectives are central to the mission of the Rbanism community which the applicant has co-initiated and which has been growing steadily, `momer` is an opportunity to further promote those standards and enable quantitative research alongside `momepy`.

Currently, a number of R packages provide some functionality for morphometric analysis, but they do not meet the level of comprehensiveness of `momepy`. Most prominent examples are the `foot` package (WorldPop Research Group, University of Southampton 2021), which focuses on processing building footprints, and the `vectormetrics` package (Matuszek et al. 2024), which provides tools for landscape and shape metrics. While the former is limited to building footprint analysis the latter is only meant to analyse polygon data and is not specifically designed for the analysis of urban form elements.

`momer` will expose the R community (existing and new R users) to a comprehensive and up-to-date set of tools and methods for urban morphometrics assembled in `momepy` from a large portion of urban morphometrics literature.

The proposal

Overview

The project aims to develop `momer`, an R package that wraps the Python library `momepy` using the `reticulate` package and sets up a synchronised documentation system.

`momer` will enable R users to perform urban morphometric analyses without needing to switch to Python, thereby broadening the reach of `momepy` and increasing the adoption of morphometric methodologies.

The development of **momer** is timely as **momepy** is approaching a major release (v1.0.0) which will stabilise its API, making it easier to maintain the R wrapper in the long term.

The project will be structured around four main milestones over a ???-month period, from initial setup and basic wrappers to final review and release.

Detail

Minimum Viable Product

The minimum viable product is a package that wraps all core functions of **momepy** and mirrors its documentation (without synchronising).

Architecture

momer will wrap **momepy** functions with **reticulate** and will be organised into the same nine modules, namely: “Managing morphological elements”, “Measuring dimension”, “Measuring shape”, “Measuring spatial distribution”, “Measuring intensity”, “Measuring diversity”, “Measuring connectivity”, “Measuring streetscape”, and “Data preprocessing”.

momer will also be set up with a script on CI to automate the generation of documentation

Assumptions

One of the main assumptions is that, according to creator and maintainer of **momepy** ???, with the upcoming major release, the **momepy** API will be kept stable, which will allow **momer** to be feasibly maintained.

We also assume that there is a feasible way of mirroring the latest version of the documentation with every **momepy** release automatically.

External dependencies

The project primarily depends on the wrapped Python library **momepy** and the R package **reticulate** used for wrapping. The user

Project plan

Start-up phase

To enable collaboration and contributions, we will set up the project on GitHub. The repository will include guidelines for contributors, a code of conduct, and a **README.md** file with an overview of the project.

A project team will be set up to track tasks and milestones, and issues will be used for feature requests and bug reports. Reporting will be done quarterly, with updates shared on the R Consortium blog and social media platforms to keep the community informed of progress.

We aim to release **momer** under the permissive Apache 2.0 license which is compatible with the BSD-3-Clause license of **momepy**. **momer** will only wrap **momepy**, i.e., call it at runtime, which means that no BSD-licensed code is redistributed and so mentioning the license in the documentation should suffice.

Technical delivery

The project will be structured by the following milestones:

1. Initial set-up and basic wrappers (Month 1-2):

- Set up the GitHub repository with necessary documentation and contribution guidelines.
 - Implement basic wrappers for core **momepy** functions using **reticulate**.
 - Assess risks related to wrapping and devise a mitigation strategy.
 - Specify data type translation from Python **sf**-compatible objects.
 - Initial testing to ensure functionality.
2. Comprehensive wrappers and testing (Month 3-6):
 - Expand wrappers to cover all major functionalities of **momepy**.
 - Develop a suite of unit tests to ensure reliability and correctness.
 - Begin drafting detailed documentation for each function.
 3. Documentation and vignettes (Month 7-10):
 - Set up automatic synchronisation of **momepy** documentation with **momer** on CI
 - Finalize comprehensive documentation, including examples and use cases.
 - Create vignettes demonstrating typical workflows and applications of **momer**.
 - Conduct user testing and gather feedback for improvements.
 4. Final review and release (Month 11-12):
 - Address any issues or feedback from user testing.
 - Perform a final review of the code base and documentation.
 - Prepare for the official release of **momer** on CRAN and GitHub.
 - Publicize the release through blog posts, social media, and relevant forums.
 - Disseminate in the developer community (e.g., SDSL, ISUF, Rbanism) to attract contributions.

Other aspects

The project will be open-source, hosted on GitHub, and licensed under the Apache 2.0 license. This will enable broad use and contributions from the community.

Updates on progress and milestones achieved will be shared on the R Consortium blog and on the Rbanism community's blog on a quarterly basis. Updates will also be shared on the social media platforms Mastodon (Fosstodon), LinkedIn and Bluesky. To promote the wide adoption of **momer**, we will announce its release at the User! conference and other similar events where the R spatial community is present. We also aim to introduce the package in the International Seminar of Urban Form (ISUF) where most of the research community conducting urban morphology analysis is present.

Budget & funding plan

The requested budget will be used for labor costs divided by period, as follows:

1. Initial set-up and basic wrappers (Month 1-2): €8,000
2. Comprehensive wrappers and testing (Month 3-6): €16,000
3. Documentation and vignettes (Month 7-10): €16,000
4. Final review and release (Month 11-12): €8,000

Total: €40,000

Success

Definition of done

A successful project will deliver a functional and well-documented **momer** package. The package will provide R users with access to the functionalities of the Python library **momepy**, enabling them to perform urban morphometric analyses within R.

Measuring success

Success can be measured against the following indicators:

- Timely completion of all project milestones;
- Positive feedback from user testing and community engagement;
- Adoption of the **momer** package by the R community, as seen in the number of downloads, citations, and contributions;
- Successful integration and functionality of all wrapped **momepy** features;
- Successful synchronisation of the documentation between **momepy** and **momer** triggered at every new **momepy** release;
- Synchronised, comprehensive and clear documentation, including vignettes and examples, aligned with CRAN policies;
- Active post-release maintenance and updates, reflecting ongoing community needs and developments in the field of urban morphometrics.

Future work

momer is expression of the sustained interest of the Spatial Data Science across Languages (SDSL) community in cross-language projects. It is part of the **momex** initiative aiming to build a cross-language infrastructure for morphometrics. In the long term, we aim to gradually develop low-level infrastructure with bindings to multiple languages, including R. Carried out in an incremental way and targeting the most challenging use cases, such an infrastructure will lead to higher performance

Fleischmann, Martin. 2019. “Momepy: Urban Morphology Measuring Toolkit.” *Journal of Open Source Software* 4 (43): 1807. <https://doi.org/10.21105/joss.01807>.

Matuszek, Tomasz, Jakub Nowosad, Marco Sciaiini, Maximillian H. K. Hesselbarth, and Yunyao Ma. 2024. *Vectormetrics: Landscape Metrics for Categorical Map Patterns in Vector Data*.

WorldPop Research Group, University of Southampton. 2021. *Foot: An r Package for Processing Building Footprint Morphometrics*. <https://github.com/wpgrp/foot>.