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momer: Exposing the Python library momepy in R

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Executive Summary

Urban morphometrics is an emerging field that leverages computational techniques and large open datasets to analyse and understand the physical form of cities at unprecedented scale. The Python open-source library **momepy** (Fleischmann 2019) has been instrumental in advancing this field as it has enabled researchers to carry out complex morphometric analyses and workflow with relative ease. Arguably, the potential of **momepy** reaches way beyond Python, and its adoption in the broader scientific community and practice could be significantly enhanced by integrating it with R.

momer is an R package meant to bridge this gap by providing a seamless interface to **momepy** functionalities within the R environment. This integration will empower R users to use the capabilities of **momepy** for urban morphometric analyses without needing to switch between programming languages. Support from the Urbanism community, the r-spatial community, and the Spatial Data Science across Languages community confirms the domain-specific relevance for R users and the potential cross-language impact of this project.

momer will be implemented as a wrapper around **momepy** using the **reticulate** package. The package will mirror **momepy**'s modules and core functionalities. The package will also include comprehensive documentation and vignettes to guide users through typical workflows. Our ambition is to set up a workflow triggered by every **momepy** release that automatically updates the documentation of **momer** to reflect any changes in **momepy**. This will ensure that **momer** remains up-to-date with the latest features and improvements in **momepy**. We expect this to be feasible considering

the upcoming release of `momepy` v1.0.0, which is expected to have a stable API and documentation structure.

Signatories

Members of:

- the [Rbanism community](#), namely ,
- the [r-spatial community](#), namely ,
- the [geocompr community](#), namely ,
- the ISUF community namely , and
- the [SDSL community](#) namely

have read this proposal and confirm the relevance of this project and its expected impact on the R ecosystem.

Project team

Claudiu Forgaci is assistant professor of urban design and analytics engaged in urban morphology research, experienced in R package development (see [rcrisp](#), [rcoins](#), and [visor](#)). He is also a member of the Spatial Data Science across Languages (SDSL) community with special interest in cross-language projects. He is also one of the initiators of the [Rbanism community](#) promoting reproducibility, automation and scalability in urbanism research using R. Claudiu will lead the development of `momer` and he will maintain it after completion.

John Doe is a research software engineer at the TU Delft Digital Competence Center ... **Jane Doe** is a research software engineer at the TU Delft Digital Competence Center ... John and Jane will carry out the software engineering work planned in this project with a shared 0.4FTE for the planned duration of the project.

Contributors

The creator of `momepy` ??? and members of the SDSL community ???, ??? and ??? provided input at the proposal stage.

Consulted

ISC member ???, also member of the SDSL community, provided feedback on the proposal.

The Problem

Urban morphometrics is a growing sub-field of urban morphology that enables scalable quantitative analysis of urban form. The field of urban morphometrics is inherently programmatic and has been heavily driven and promoted by the Python library `momepy` (Fleischmann 2019). While `momepy` has played an important role in making the quantitative analysis of urban form accessible to many, it is limited to users of the Python programming language.

Moreover, a large part of urban morphology research is conducted with GUI-based tools and qualitative interpretation, which limits the kind of analytical questions that researchers and practitioners can ask. Automated, reproducible and scalable urban morphology research can only be

effectively achieved in a programmatic way. Considering that those three objectives are central to the mission of the Rbanism community which the applicant has co-initiated and which has been growing steadily, **momer** is an opportunity to further promote those standards and enable quantitative research alongside **momepy**.

Currently, a number of R packages provide some functionality for morphometric analysis, but they do not meet the level of comprehensiveness of **momepy**. Most prominent examples are the **foot** package (WorldPop Research Group, University of Southampton 2021), which focuses on processing building footprints, and the **vectormetrics** package (Matuszek et al. 2024), which provides tools for landscape and shape metrics. The former is limited to building footprint analysis, while the latter is only meant to analyse polygon data and is not specifically designed for the analysis of urban form elements.

Note

Are there any other packages which should be mentioned here?

The proposal

Overview

The project aims to develop **momer**, an R package that wraps the Python library **momepy** using the **reticulate** package and a mirrored documentation.

momer will enable R users to perform urban morphometric analyses without needing to switch to Python, thereby broadening the reach of **momepy** and increasing the adoption of morphometric methodologies.

The development of **momer** is timely as **momepy** is approaching a major release (v1.0.0) which will stabilise its API, making it easier to maintain the R wrapper in the long term.

The project will be structured around four main milestones over a 12-month period, from initial setup and basic wrappers to final review and release.

Detail

Minimum Viable Product

The minimum viable product is an R package that (1) wraps all core functions of **momepy**, (2) mirrors its documentation, and (3) includes a detailed documentation for maintainers on how to update the wrappers and documentation with future **momepy** releases.

Architecture

momer will wrap exported **momepy** functions with **reticulate** and will be organised into the same nine modules, namely: **elements**, **dimension**, **shape**, **distribution**, **intensity**, **diversity**, **connectivity**, **streetscape**, and **preprocessing**.

We also aim to set up a workflow to automate the generation of **roxygen2** documentation to be used for the generation of a **pkgdown** website.

Assumptions

One of the main assumptions is that with the upcoming major release, the `momepy` API will remain stable, which will allow `momer` to be feasibly maintained. We also assume that there is a feasible way of mirroring the latest version of the documentation with every `momepy` release automatically.

External dependencies

The project primarily depends on the wrapped Python library `momepy` and the R package `reticulate` used for wrapping. The user needs to have Python installed with `momepy` and its dependencies.

Project plan

Start-up phase

To enable collaboration and contributions, we will set up the project on GitHub. The repository will include guidelines for contributors, a code of conduct, and a `README.md` file with an overview of the project.

A project team will be set up to track tasks and milestones, and issues will be used for feature requests and bug reports. Reporting will be done quarterly, with updates shared on the R Consortium blog and social media platforms to keep the community informed of progress.

We aim to release `momer` under the permissive Apache 2.0 license which is compatible with the BSD-3-Clause license of `momepy`. `momer` will only wrap `momepy`, i.e., call it at runtime, which means that no BSD-licensed code is redistributed and so mentioning the license in the documentation should suffice.

Technical delivery

The project will be structured by the following milestones:

1. Initial set-up and basic wrappers (Month 1-2):
 - Set up the GitHub repository with necessary documentation and contribution guidelines.
 - Implement basic wrappers for core `momepy` functions using `reticulate`.
 - Devise a mitigation strategy for risks related to wrapping.
 - Specify data type translation from Python to `sf` objects.
 - Initial testing to ensure functionality.
2. Comprehensive wrappers and testing (Month 3-6):
 - Expand wrappers to cover all major functionalities of `momepy`.
 - Develop a suite of unit tests to ensure reliability and correctness.
 - Begin drafting detailed documentation for each function.
3. Documentation and vignettes (Month 7-10):
 - Set up automatic synchronisation of `momepy` documentation with `momer` on CI
 - Finalize comprehensive documentation, including examples and use cases.
 - Create vignettes demonstrating typical workflows and applications of `momer`.
 - Conduct user testing and gather feedback for improvements.
4. Final review and release (Month 11-12):

- Address any issues or feedback from user testing.
- Perform a final review of the code base and documentation.
- Prepare for the official release of **momer** on CRAN and GitHub.
- Publicize the release through blog posts, social media, and relevant forums.
- Disseminate in the developer community (e.g., SDSL, ISUF, Rbanism) to attract contributions.

Other aspects

The project will be open-source, hosted on GitHub, and licensed under the Apache 2.0 license. This will enable broad use and contributions from the community.

Updates on progress and milestones achieved will be shared on the R Consortium blog and on the Rbanism community’s blog on a quarterly basis. Updates will also be shared on the social media platforms Mastodon (Fosstodon), LinkedIn and Bluesky. To promote the wide adoption of **momer**, we will announce its release at the UseR! conference and other similar events where the R spatial community is present. We also aim to introduce the package in the International Seminar of Urban Form (ISUF) where most of the research community conducting urban morphology analysis is present.

Budget & funding plan

The requested budget will be used for labor costs divided by period, as follows:

1. Initial set-up and basic wrappers (Month 1-2): €8,000
2. Comprehensive wrappers and testing (Month 3-6): €16,000
3. Documentation and vignettes (Month 7-10): €16,000
4. Final review and release (Month 11-12): €8,000

Total: €40,000

Success

Definition of done

A successful project will deliver a functional and well-documented **momer** package. The package will provide R users with access to the functionalities of the Python library **momepy**, enabling them to perform urban morphometric analyses within R.

Measuring success

Success can be measured against the following indicators:

- Timely completion of all project milestones;
- Positive feedback from user testing and community engagement;
- Adoption of the **momer** package by the R community, as seen in the number of downloads, citations, and contributions;
- Successful integration and functionality of all wrapped **momepy** features;
- Successful synchronisation of the documentation between **momepy** and **momer** triggered at every new **momepy** release;

- Synchronised, comprehensive and clear documentation, including vignettes and examples, aligned with CRAN policies;
- Active post-release maintenance and updates, reflecting ongoing community needs and developments in the field of urban morphometrics.

Future work

`momer` is expression of the sustained interest of the Spatial Data Science across Languages (SDSL) community in cross-language projects. It is part of the `momex` initiative aiming to build a cross-language infrastructure for morphometrics. In the long term, we aim to gradually develop low-level infrastructure enabling bindings to multiple languages, including R. Carried out in an incremental way and targeting the most challenging use cases, such an infrastructure will lead to improved performance and maximised community exposure. The `momer` project is instrumental to that end as it will grow a critical mass of users beyond Python and will help identify pressing high-level cross-language challenges.

Fleischmann, Martin. 2019. “Momepy: Urban Morphology Measuring Toolkit.” *Journal of Open Source Software* 4 (43): 1807. <https://doi.org/10.21105/joss.01807>.

Matuszek, Tomasz, Jakub Nowosad, Marco Sciaini, Maximillian H. K. Hesselbarth, and Yunyao Ma. 2024. *Vectormetrics: Landscape Metrics for Categorical Map Patterns in Vector Data*.

WorldPop Research Group, University of Southampton. 2021. *Foot: An r Package for Processing Building Footprint Morphometrics*. <https://github.com/wpgp/foot>.