

These slides are used in the Open Mission Stack Raspberry Pi App Demo project at

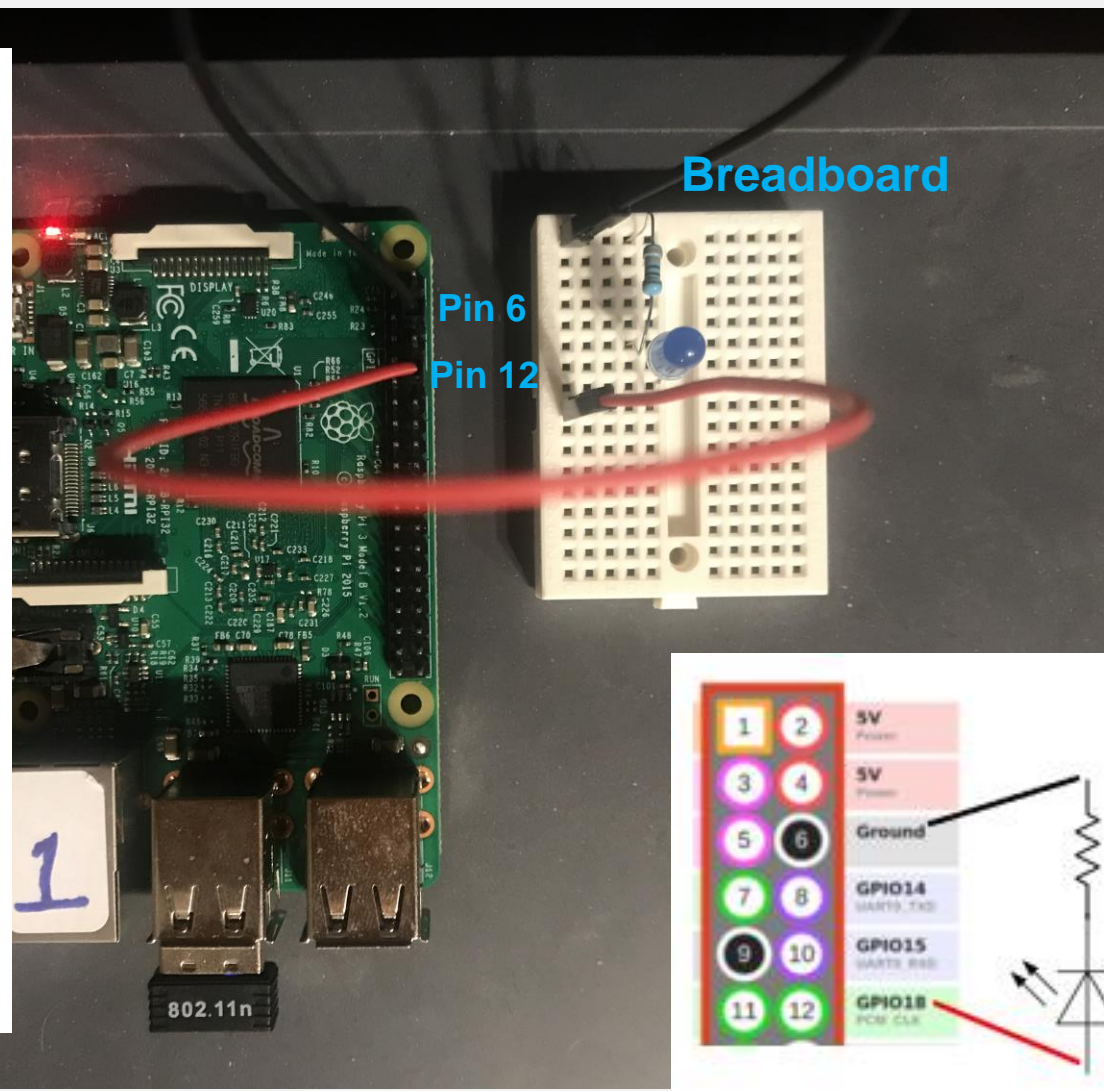
https://openmissionstack.com/projects_read/gpio_demo

They are included in GPIO_DEMO's repo as a reference. See the project website for detailed instructions.

Configure and connect a breadboard to the Pi as shown below

- Note physical pin 12 is logical GPIO pin 18 which is the identifier used by the FSW

Pin#	NAME	NAME	Pin#
01	3.3v DC Power	DC Power 5v	02
03	GPIO02 (SDA1 , I2C)	DC Power 5v	04
05	GPIO03 (SCL1 , I2C)	Ground	06
07	GPIO04 (GPIO_GCLK)	(TXD0) GPIO14	08
09	Ground	(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)	(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)	Ground	14
15	GPIO22 (GPIO_GEN3)	(GPIO_GEN4) GPIO23	16
17	3.3v DC Power	(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)	Ground	20
21	GPIO09 (SPI_MISO)	(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)	(SPI_CE0_N) GPIO08	24
25	Ground	(SPI_CE1_N) GPIO07	26
27	ID_SD (I2C ID EEPROM)	(I2C ID EEPROM) ID_SC	28
29	GPIO05	Ground	30
31	GPIO06	GPIO12	32
33	GPIO13	Ground	34
35	GPIO19	GPIO16	36
37	GPIO26	GPIO20	38
39	Ground	GPIO21	40



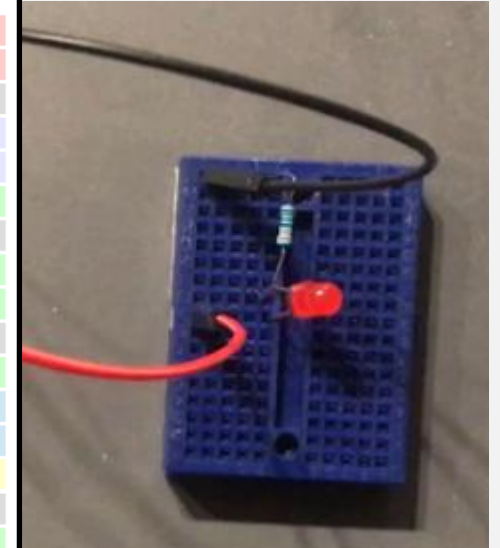
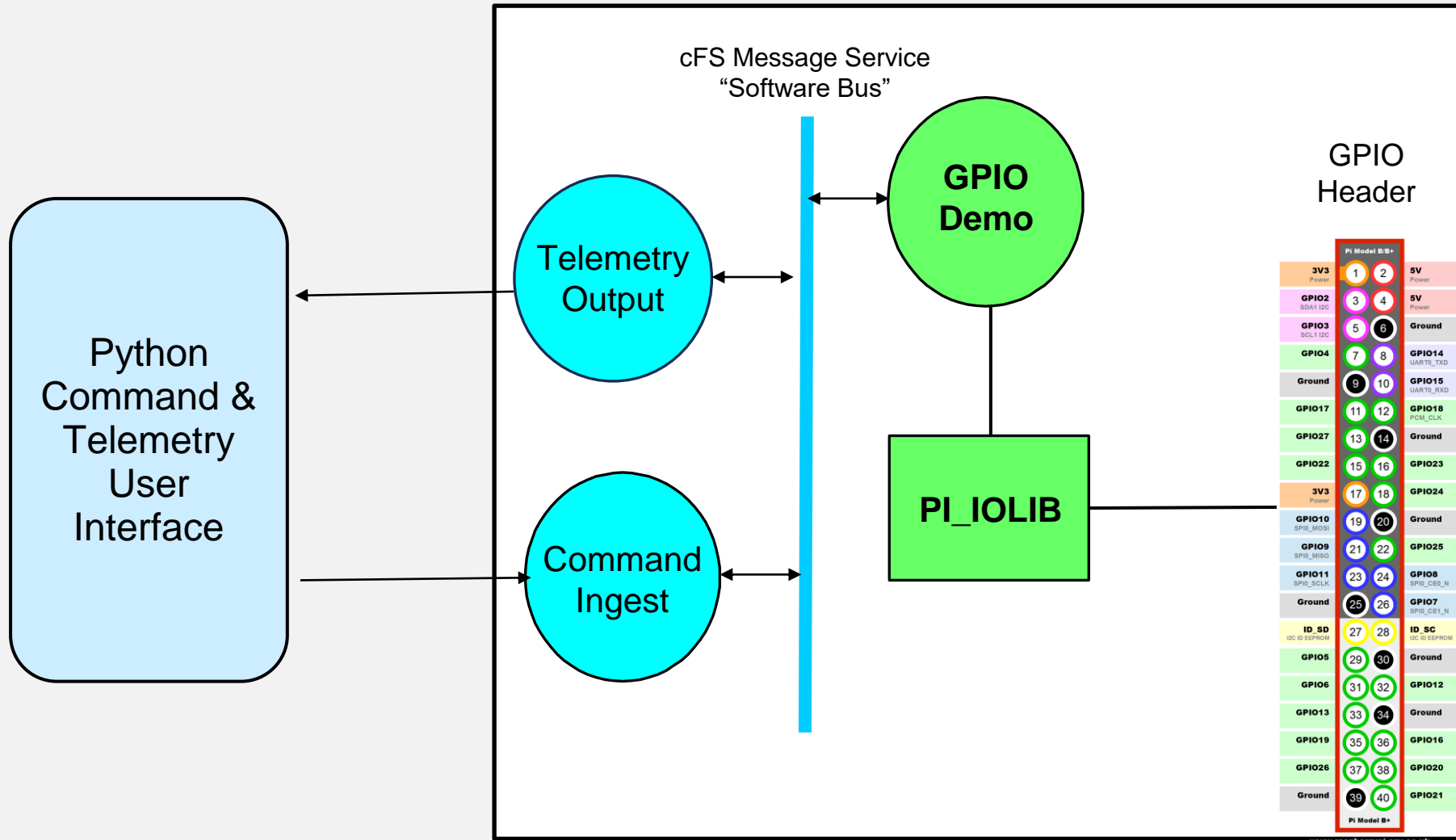
220 Ohm Resistor
(red, red, brown)

LED

- Connect shorter leg Cathode (-) to resistor
- Connect longer leg Anode (+) to GPIO pin 12

Connect LED to RPI GPIO header

cFS Target



 = Project Apps and Library

cFS Target

cFS Message Service
"Software Bus"

Telemetry
Output

Command
Ingest

GPIO
Demo

PI_IOLIB

GPIO
Header

3V3	1	2	SV
GPIO2	3	4	SV
GPIO3	5	6	Ground
GPIO4	7	8	GPIO14
Ground	9	10	GPIO15
GPIO17	11	12	GPIO18
GPIO27	13	14	Ground
GPIO22	15	16	GPIO23
3V3	17	18	GPIO24
GPIO19	19	20	Ground
GPIO9	21	22	GPIO25
GPIO11	23	24	GPIO8
Ground	25	26	GPIO7
ID_SD	27	28	ID_SC
GPIO5	29	30	Ground
GPIO6	31	32	GPIO12
GPIO13	33	34	Ground
GPIO19	35	36	GPIO16
GPIO26	37	38	GPIO20
Ground	39	40	GPIO21



Download App

Select one or more apps to download then follow the steps in 'Add App'. See 'A

- ☐ BERRY_IMU Core Flight System app that interfaces to the Ozzmaker Berry
- ☐ GPIO_DEMO Example app controlling a GPIO pin that can be used as a start
- ☐ MQTT_GW Provide a gateway between the core Flight System (cFS) Softw
- ☐ MQTT_LIB The Eclipse Paho Embedded C MQTT Library ported to the core
- ☐ PI_IOLIB cFS library providing an interface to Raspberry Pi peripherals
- ☐ PL_MGR Example payload management app.
- ☐ PL_SIM Payload simulator app that provides a ground interface to the
- ☐ PL_SIM_LIB Payload simulator library that simulates a fictitious detector th
- ☐ SC_SIM Simulate a simple spacecraft operational interface that expose
- ☐ TBL_SAT Raspberry Pi app used in the Table Sat kit.

Download

Cancel

GPIO_DEMO App

Commands

- Set LED On Time
- Set LED Off Time

Telemetry

```
HkTlm.Payload.ValidCmdCnt    : 0
HkTlm.Payload.InvalidCmdCnt : 0
HkTlm.Payload.CtrlIsMapped  : FALSE
HkTlm.Payload.CtrlOutPin    : 18
HkTlm.Payload.CtrlLedOn     : FALSE
HkTlm.Payload.CtrlSpare     : 0
HkTlm.Payload.CtrlOnTime    : 3000
HkTlm.Payload.CtrlOffTime   : 6000
```

Library and Application Summary

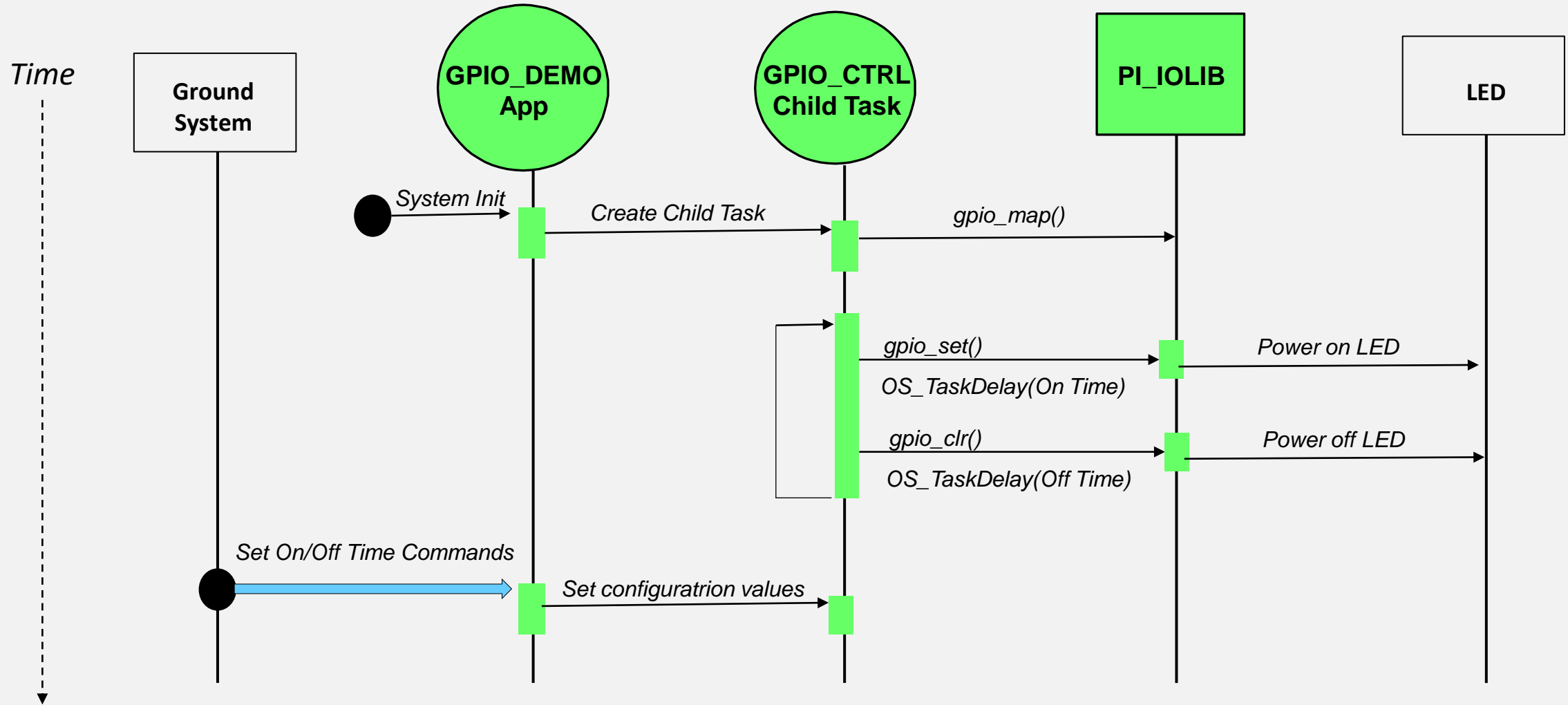
PI_IOLIB

- This library adapts the “minimalistic peripheral access” (MIPEA) library for the Raspberry Pi, <https://github.com/jasLogic/mipea> so it can serve as a cFS library.
- It provides an interface to the Raspberry Pi’s memory mapped General Purpose I/O registers
- The config.h configuration file allows you to select your Broadcom processor chip

GPIO_DEMO

- The main app manages the ground command and telemetry interface
- A child task controls turning on and off the LED
- Ground commands can be sent to set the LED on and off time durations
- JSON initialization table defines the GPIO LED control pin and the default LED on/off time durations

Control Flows

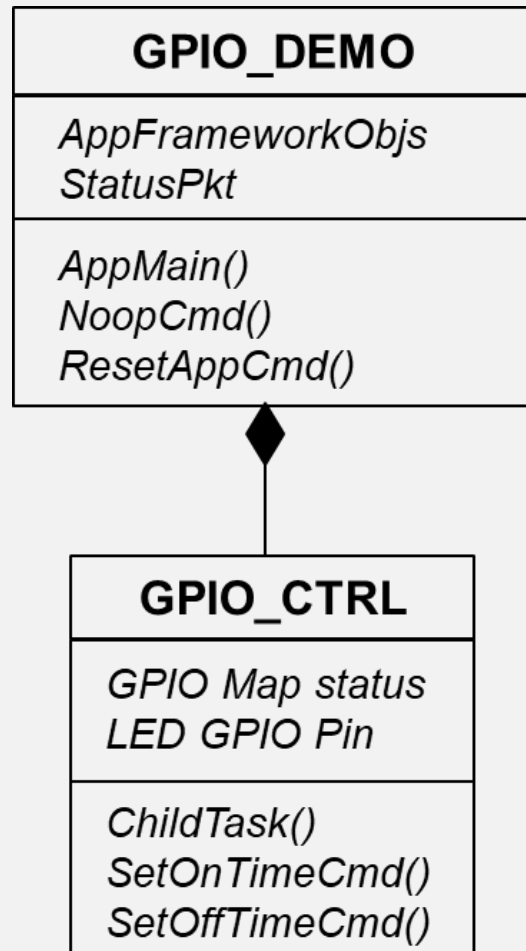


● Start Event

➡ Software Bus Message

→ Library Call

GPIO_DEMO App Object Design



GPIO_DEMO

- Manages app initialization, main runtime loop, and status telemetry
- Dispatches commands to objects

cFS

GPIO_CTRL

- Manages GPIO and LED interface
- Contains child task that turns the LED on and off
- Calls to PI_IOLIB functions should be limited to this object to localize coupling

GPIO Demo Control Flow

App

Initialize App

Start →
Subscribe to Command and
'Send Status' messages
Create child task

Pend on SB message pipe

Send
Status?

Yes

Send status telemetry

No

Cmd?

Yes

Process Command

No

Send error event

Child Task

Initialize Child Task

Read ini table LED pin and
on/off times
Map GPIO

GPIO
Mapped?

No

Exit

Yes

Set LED On
Suspend task for on time duration

Set LED Off
Suspend task for off time duration

