17. Train System

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2009

- To present the development of a a train system controller
- It is a piece of software helping a train agent to control trains
- The goal is to have trains safely circulating in a certain network

- Studying a very complex data structure: the track network.

- Studying a very complex object: a train on a track network.

- Reliability is absolutely fundamental in this project

- Showing once again the modelling of a closed system (software + environment)

- Showing once again a systematic methodology

- Explaining the problem and constructing the requirement document

- Defining the refinement strategy

- Constructing the formal model (and doing the proofs)

- Conclusion

- A real study is done presently on the same subject for RATP
- Size of initial "bad" document: 90 pages
- Time length of the study: 6 months (one engineer)
- Re-writing of the requirement document: 2.5 months
- Development of the formal model and its proofs: 2.5 months
- Writing a final "system study" document, plus an animation: 1 month

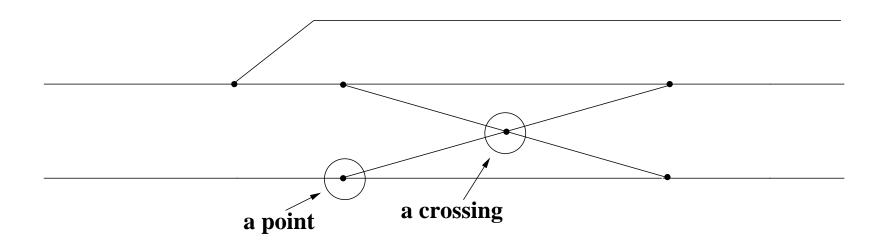
- Re-writing of the requirement document:
 - Understanding the problem: 2 weeks
 - Getting more explanation and information: 3 weeks
 - Writing the explanatory text: 4 weeks
 - Writing the reference text (the precise requirements): 2 weeks
- The client (RATP) is required to sign the new requirement document
- Development of the formal model:
 - Refinement strategy and allocation of requirements: 2 weeks
 - Construction and proof of the formal model: 2 months

ENV	Environment
FUN	Functional
SAF	Safety

MVT	Movement
TRN	Train
FLR	Failure

The goal of the train system is to safely control trains moving on a track network

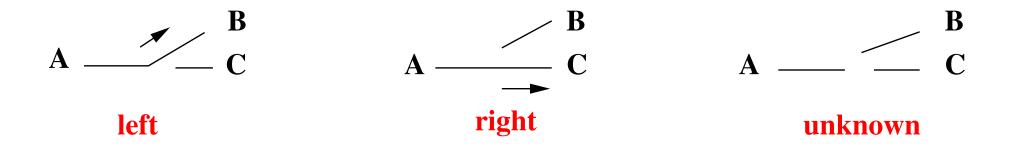
- Here is a (simplified) track network controlled by a train agent



- Two kinds of special components: points and crossings

A track network may contain some special components: points and crossings

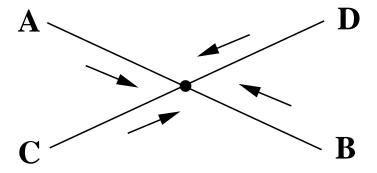
- A point might be in three different positions: left, right, and unknown



- For simplification, the unknown position is not considered

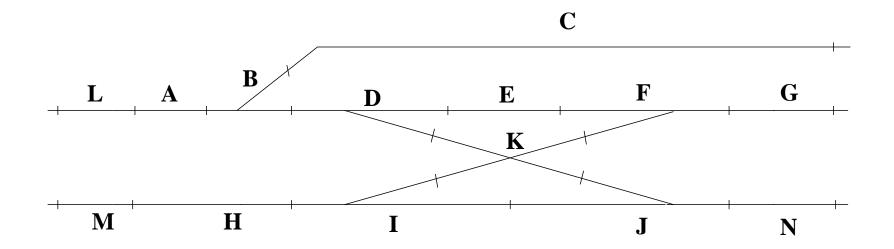
A point may have two positions: left or right ENV-2

- Unlike a point, a crossing has no state



A track network is made of a number of named fixed blocks

ENV-3

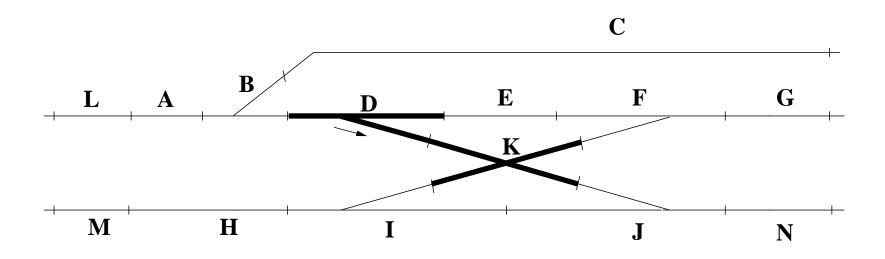


A special component (points or crossings) is always attached to a given block. A block contains at most one special component

- Each block is equipped with a track circuit

- It is used to detect the presence of a train on the concerned block

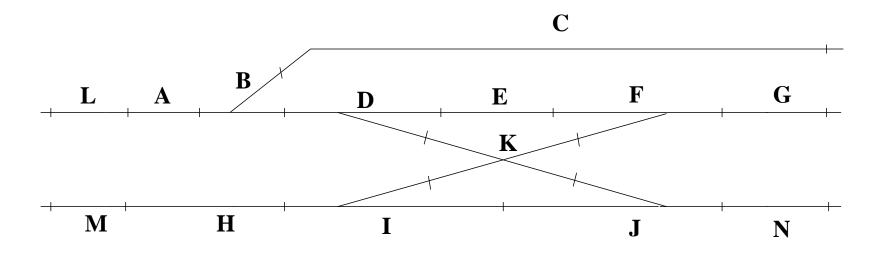
A block may be occupied or unoccupied by a train



A network has a fixed number of routes. Each route is characterized by a sequence of adjacent blocks

ENV-6

- The controller will allow trains to use some routes

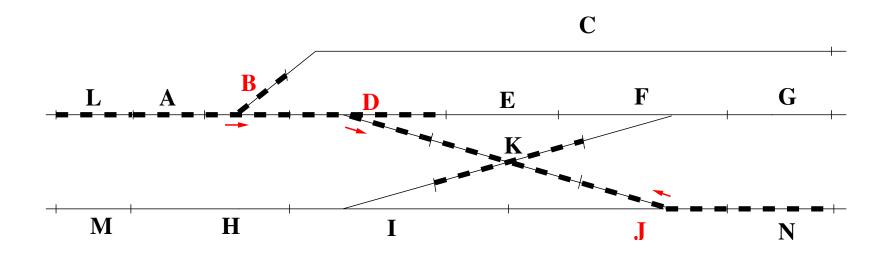


R1	$m{L}$ $m{A}$ $m{B}$ $m{C}$	R6	$C\ B\ A\ L$
R2	$m{L}$ $m{A}$ $m{B}$ $m{D}$ $m{E}$ $m{F}$ $m{G}$	R7	$G \ F \ E \ D \ B \ A \ L$
R3	$oldsymbol{L}$ $oldsymbol{A}$ $oldsymbol{B}$ $oldsymbol{D}$ $oldsymbol{K}$ $oldsymbol{J}$ $oldsymbol{N}$	R8	$m{N}$ $m{J}$ $m{K}$ $m{D}$ $m{B}$ $m{A}$ $m{L}$
R4	M H I K F G	R9	$G \ F \ K \ I \ H \ M$
R5	M H I J N	R10	N J I H M

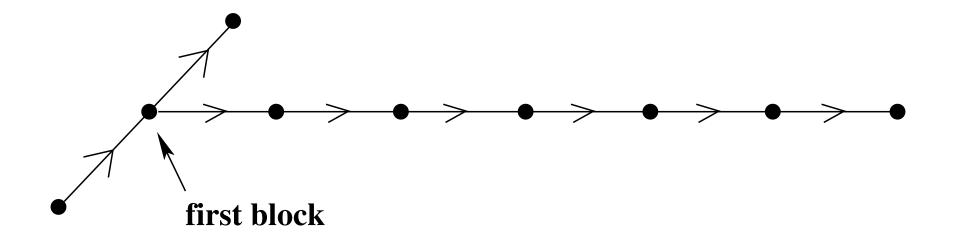
A route is also characterized by the positions of the points which are situated in blocks composing it

ENV-7

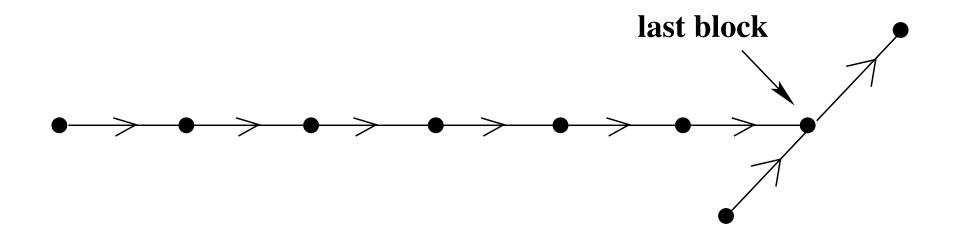
- Route R3: L A B D K J N



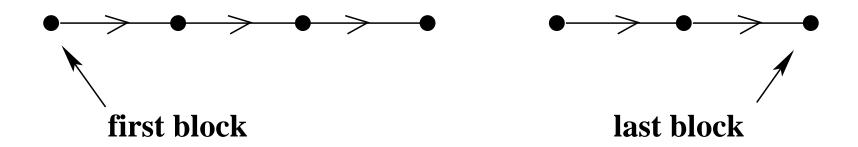
- the point in block **B** is positioned to the right,
- the point in block **D** is positioned to the right,
- the point in block **J** is positioned to the right.



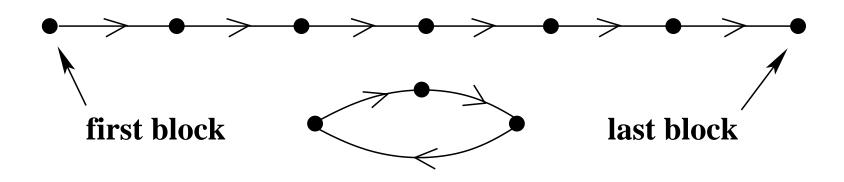
The first block of a route cannot be part of another route unless it is also the first or last block of that route



The last block of a route cannot be part of another route unless it is also the first or last block of that route



A route connects its first block to its last one in a continuous manner

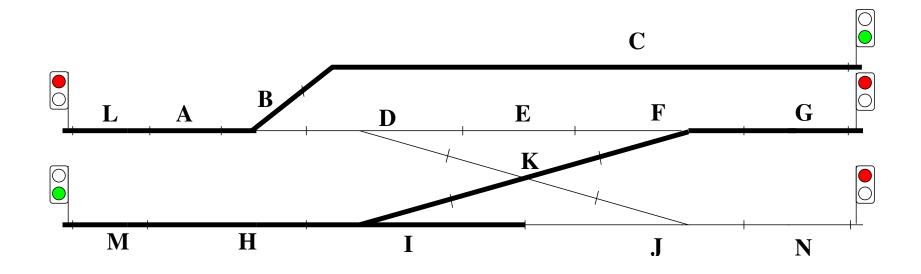


A route contains no cycles

Each route is protected by a signal situated just before its first block

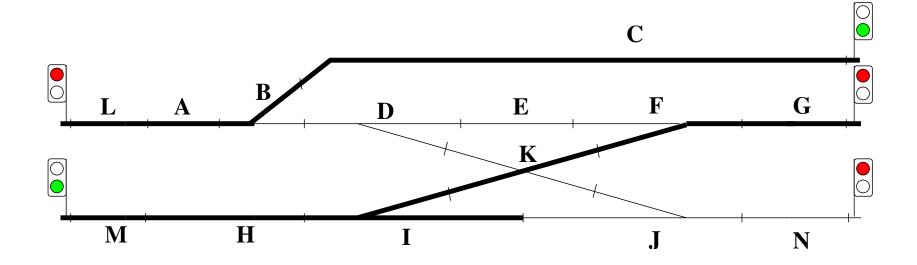
ENV-12

A signal can be red or green. Trains are supposed to stop at red signals



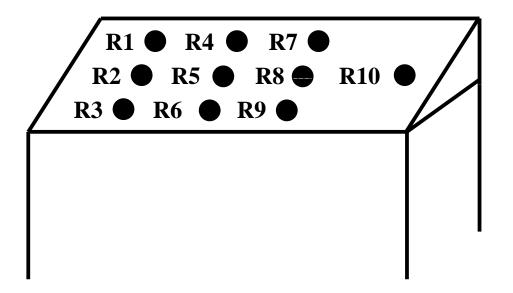
Routes having the same first block share the same signal

ENV-14



A green signal turns back to red automatically as soon as the first block is made occupied

- The train agent is provided with a panel with route commands.



A route can be reserved for a train. The software is in charge of controlling the reservation process

- The reservation process of a route r is made of three phases:

1. the individual reservation of the blocks of r,

2. the positioning of the relevant points of r,

3. the turning to green of the signal protecting route r.

A block can be reserved or free

FUN-3

An occupied block is always reserved

FUN-4

Reserving a route consists in reserving the individual blocks it is made of. Once this is done, the route is said to be reserved

Once it is reserved, a route has to be formed by properly positioning its points

FUN-6

A formed route is always a reserved route

Once it is formed, a route is made available for the incoming train by turning its signal to green

- Main risks:

- Two trains traversing the network hit each other.

- A point changing position under a train.

- The point of a route changing position in front of a train.

- In all cases, A TRAIN MAY DERAIL

A block can be reserved for at most one route

SAF-1

The signal of a route can only be green when all blocks of that route are reserved for it and are unoccupied, and when all points of this route are properly positioned

SAF-2

A point can only be re-positioned if it belongs to a block which is in a reserved but not yet formed route

SAF-3

No blocks of a reserved, but not yet formed, route are occupied

SAF-4

Once a block of a formed route is made unoccupied, it is also freed

MVT-1

A route remains formed as long as there are some reserved blocks in it

MVT-2

A formed route can be made free (not formed and not reserved any more) when no blocks are reserved for it any more

MVT-3

- A freed block cannot be made occupied again by the same train without freeing the concerned route

A train cannot split while in the network

TRN-1

A train cannot move backwards in the network

TRN-2

A train cannot enter in the middle of a route. It has to do so through its first block.

TRN-3

A train cannot leave a route without first occupying then freeing all its blocks

TRN-4

Trains are equipped with the Automatic Train Protection system (ATP), which guarantees that they cannot enter a route guarded by a red signal

FLR-1

Trains are equipped with special bindings, which guarantee that they cannot be mechanically broken.

FLR-2

The ATP and a slight delay observed by the track circuit guarantee that a train moving backward cannot occupy again a block which has been physically freed.

FLR-3

The risk of a faulty detection of a block occupancy is not treated

FLR-4

The case where a short train derails and leaves its block is not treated.

FLR-5

- We have 39 requirements: far more in a real train system!

ENV	Environment	15
FUN	Functional	8
SAF	Safety	4

MVT	Movement	3
TRN	Train	4
FLR	Failure	5

- Logical block and route concepts are formalized.

- Physical blocks are introduced and connected to the logical ones.

- A notion of readiness for a route.

- Introduction of the physical signals.

- Introduction of the abstract points.

- More refinements are needed in order to finalize details.

carrier sets: B, R

constants: rtbl, nxt

- Set of blocks: B

- Set of routes: $oldsymbol{R}$

- Variable *rtbl* denotes the routes of a block

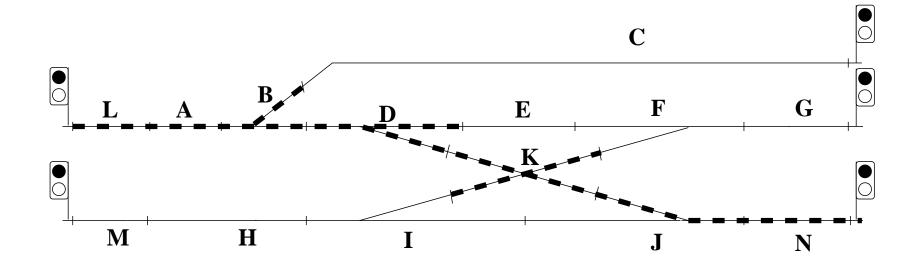
- Variables nxt denotes the succession of blocks in each route

 $axm0_1: rtbl \in B \iff R$

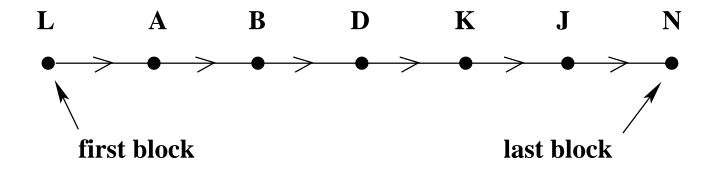
axm0_2: $nxt \in R \rightarrow (B \rightarrowtail B)$

- Notice the injection

- Route **R3**: L A B D K J N



- Here is nxt(R3):



constants: ···

 $fst, \\ lst$

axm0_3: $fst \in R \rightarrow B$

axm0_4: $lst \in R \rightarrow B$

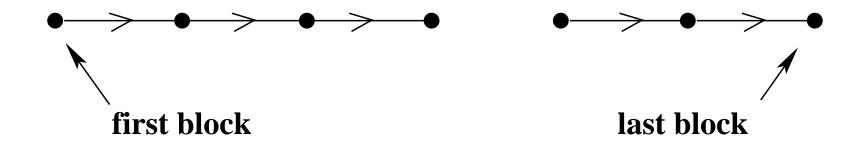
- The first and last block of a route are in that route (axm0_5, axm0_6)
- They are distinct (axm0₋7)

axm0_5: $fst^{-1} \subseteq rtbl$

 $axm0_6: lst^{-1} \subseteq rtbl$

 $axm0_{-}7: \forall r \cdot (r \in R \Rightarrow fst(r) \neq lst(r))$

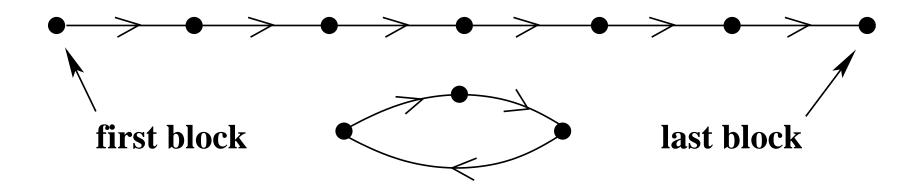
- To be avoided!



axm0_8:
$$\forall r \cdot \begin{pmatrix} r \in R \\ \Rightarrow \\ nxt(r) \in s \setminus \{lst(r)\} \not o s \setminus \{fst(r)\} \end{pmatrix}$$

where s is $rtbl^{-1}[\{r\}]$ (the blocks of route r)

To be avoided!



$$\mathsf{axm0_9} \colon \ \forall r \cdot \left(\begin{array}{c} r \in R \ \Rightarrow \ \forall \, S \cdot \begin{pmatrix} S \subseteq B \\ S \subseteq nxt(r)[S] \\ \Rightarrow \\ S = \varnothing \end{array} \right) \right)$$

- The first block of a route r cannot be the block of another route s unless if first or last of s

$$\textbf{axm0_10:} \quad \forall \, r,s \cdot \begin{pmatrix} r \in R \\ s \in R \\ r \neq s \\ \Rightarrow \\ fst(r) \notin rtbl^{-1}[\{s\}] \setminus \{fst(s),lst(s)\} \end{pmatrix}$$

- The last block of a route r cannot be the block of another route s unless if first or last of s

axm0_11:
$$orall r,s \cdot egin{pmatrix} r \in R \ s \in R \ r
eq s \end{pmatrix} \ \Rightarrow \ lst(r)
otin rtbl^{-1}[\{s\}] \setminus \{fst(s),lst(s)\} \end{pmatrix}$$

variables: resrt,

 $resbl, \\ rsrtbl, \\ OCC$

inv0_1: $resrt \subseteq R$

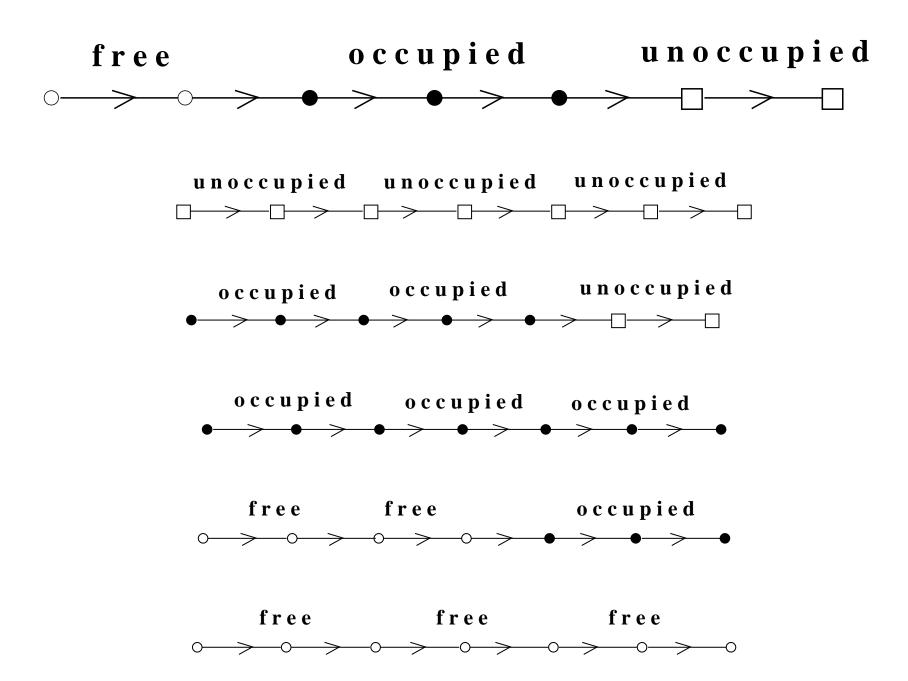
inv0_2: $resbl \subseteq B$

inv0_3: $rsrtbl \in resbl \rightarrow resrt$

inv0_4: $rsrtbl \subseteq rtbl$

inv0_5: $OCC \subseteq resbl$

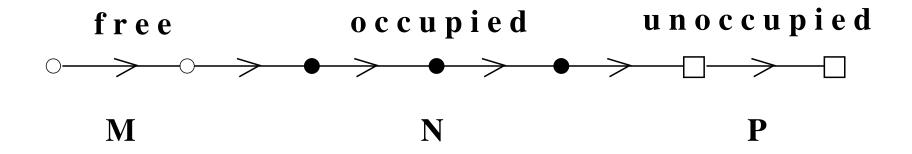
- Set of reserved routes: resrt, a controller variable
- Set of reserved blocks: resbl, a controller variable
- Reserved route of reserved block: rsrtbl, a controller variable
- Set of occupied block: OCC, an environment variable (UPPER case)

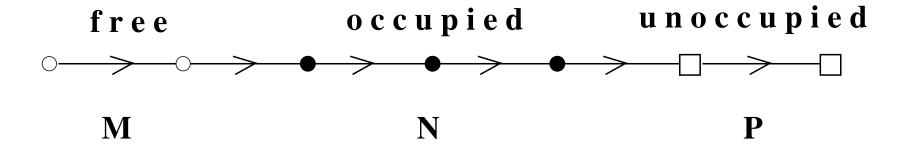


Given a reserved route r:

- Let M be the free blocks of r (those behind the train)
- Let N be the occupied blocks in r (those where the train is)
- Let P be the unoccupied blocks in r (those in front of the train)

$$egin{aligned} M &= rtbl^{-1}[\{r\}] \setminus rsrtbl^{-1}[\{r\}] \ N &= rsrtbl^{-1}[\{r\}] \, \cap \, OCC \ \end{aligned}$$
 $egin{aligned} P &= rsrtbl^{-1}[\{r\}] \setminus OCC \end{aligned}$





- Here are the possible transitions: MMMMNNNPPPP

$$M o M \quad M o N \quad N o N \quad N o P \quad P o P$$

$$M o M \quad M o N \quad N o N \quad N o P \quad P o P$$

$$nxt(r)[M] \subseteq M \cup N$$
 $nxt(r)[N] \subseteq N \cup P$ $nxt(r)[P] \subseteq P$

- Such conditions are equivalent to the following ones

$$nxt(r)[M] \cap P = \varnothing \quad nxt(r)[N \cup P] \subseteq N \cup P \quad nxt(r)[P] \subseteq P$$

inv0_6:
$$\forall r \cdot (r \in R \Rightarrow nxt(r)[rtbl^{-1}[\{r\}] \setminus s] \cap (s \setminus OCC) = \varnothing)$$

inv0_7:
$$\forall r \cdot (r \in R \Rightarrow nxt(r)[s] \subseteq s)$$

inv0_8:
$$\forall r \cdot (r \in R \Rightarrow nxt(r)[s \setminus OCC] \subseteq s \setminus OCC)$$

where s is $rsrtbl^{-1}[\{r\}]$

- Controller events:
 - route_reservation,
 - route_freeing.
- Environment events:
 - FRONT_MOVE_1,
 - FRONT_MOVE_2,
 - BACK_MOVE.

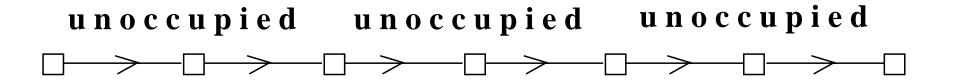
- r is a non-reserved route
- No block of r is reserved

```
\begin{array}{l} \mathsf{route\_reservation} \\ & \mathsf{any} \ r \ \mathsf{where} \\ & r \in R \setminus resrt \\ & rtbl^{-1}[\{r\}] \ \cap \ resbl = \varnothing \\ & \mathsf{then} \\ & resrt := resrt \ \cup \ \{r\} \\ & rsrtbl := rsrtbl \ \cup \ rtbl \rhd \{r\} \\ & resbl := resbl \ \cup \ rtbl^{-1}[\{r\}] \\ & \mathsf{end} \end{array}
```

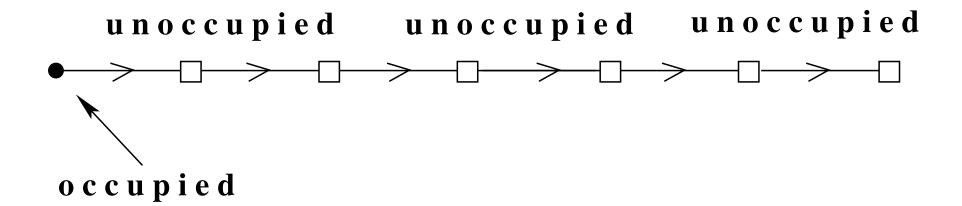
- r is a reserved route
- r has no block reserved for it any more

```
egin{array}{ll} {
m route\_freeing} & {
m any} \ r \ {
m where} \ r \in resrt \ r 
otin {
m resrt:=} resrt ackslash \{r\} \ {
m end} \end{array}
```

- Before:



- After:

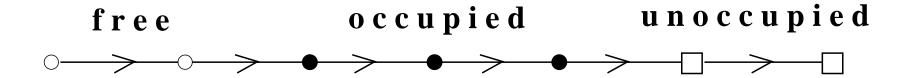


- r is a reserved route
- fst(r) is a reserved and unoccupied block
- The reserved route of fst(r) is indeed r

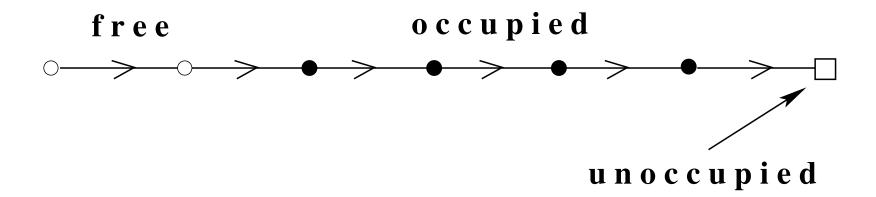
```
egin{aligned} \mathsf{FRONT\_MOVE\_1} \ & \mathbf{any} \ r \ & \mathbf{where} \ & r \in resrt \ & fst(r) \in resbl \setminus OCC \ & rsrtbl(fst(r)) = r \ & \mathsf{then} \ & OCC := OCC \cup \{fst(r)\} \ & \mathsf{end} \ \end{aligned}
```

- The guard depends on some controller variables

- Before:



- After:

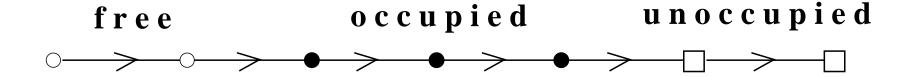


- b is an occupied block
- c is an unoccupied block
- c is next to b in the reserved route of b

```
egin{array}{ll} {\sf FRONT\_MOVE\_2} & {\sf any} \ b,c \ {\sf where} \ & b \in OCC \ & c \in B \setminus OCC \ & b \mapsto c \in nxt(rsrtbl(b)) \ & {\sf then} \ & OCC := OCC \cup \{c\} \ & {\sf end} \ \end{array}
```

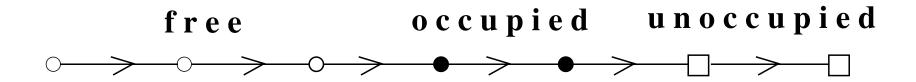
- The guard depends on some controller variables

- Before:



- "free" blocks behind the train can be reserved for another route

- After:



- b is an occupied block
- if any, the block next to b is also occupied
- if any, the block before b is not reserved or reserved for a route not equal to that of b

```
\begin{array}{c} \mathsf{BACK\_MOVE} \\ & \mathsf{any} \ b, n \ \mathsf{where} \\ & b \in \mathit{OCC} \\ & n = \mathit{nxt}(\mathit{rsrtbl}(b)) \\ & b \in \mathit{dom}(n) \ \Rightarrow \ \mathit{n}(b) \in \mathit{OCC} \\ & b \in \mathit{ran}(n) \ \Rightarrow \ \mathit{n}^{-1}(b) \notin \mathit{dom}(\mathit{rsrtbl}) \ \lor \ \mathit{rsrtbl}(\mathit{n}^{-1}(b)) \neq \mathit{rsrtbl}(b) \\ & \mathsf{then} \\ & \mathit{OCC} := \mathit{OCC} \setminus \{b\} \\ & \mathit{rsrtbl} := \{b\} \lessdot \mathit{rsrtbl} \\ & \mathit{resbl} := \mathit{resbl} \setminus \{b\} \\ & \mathsf{end} \end{array}
```

- The guard depends on some controller variables

variables: $\cdots, \\ TRK, \\ frm, \\ LBT$

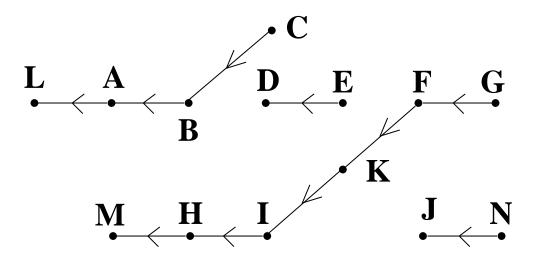
- Variable TRK denotes the physical succession of blocks

- Variable frm denotes the set of formed routes

- Variable LBT denotes the set of last blocks occupied by trains

inv1_1:
$$TRK \in B \rightarrowtail B$$

- Here is an illustration of the variable TRK in a certain situation:



- Route R9 (G F K I H H M) and R6 (C B A L) are visible.
- The crossing in block $oldsymbol{K}$ is "broken"
- The physical track "remembers" the direction followed by trains

- A formed route is a reserved route
- Routes of occupied blocks are formed
- A reserved but not formed route has all its blocks reserved

```
\begin{array}{lll} & \textbf{inv1\_3:} & frm \subseteq resrt \\ & \textbf{inv1\_4:} & rsrtbl[OCC] \subseteq frm \\ \\ & \textbf{inv1\_5:} & \forall r \cdot \begin{pmatrix} r \in resrt \setminus frm \\ \Rightarrow \\ rtbl \rhd \{r\} = rsrtbl \rhd \{r\} \end{pmatrix} \end{array}
```

- Let r be a formed route
- The logical succession of reserved blocks of r

$$rsrtbl^{-1}[\{r\}] \lhd nxt(r)$$

- is identical to the physical succession of reserved blocks of r

$$rsrtbl^{-1}[\{r\}] \lhd TRK$$

$$\mathsf{inv1_6:} \ \ \, \forall r \cdot \left(\begin{matrix} r \in frm \\ \Rightarrow \\ rsrtbl^{-1}[\{r\}] \lhd nxt(r) \ = \ rsrtbl^{-1}[\{r\}] \lhd TRK \end{matrix} \right)$$

- In other words, the points are well positioned

- The last block of a train is occupied

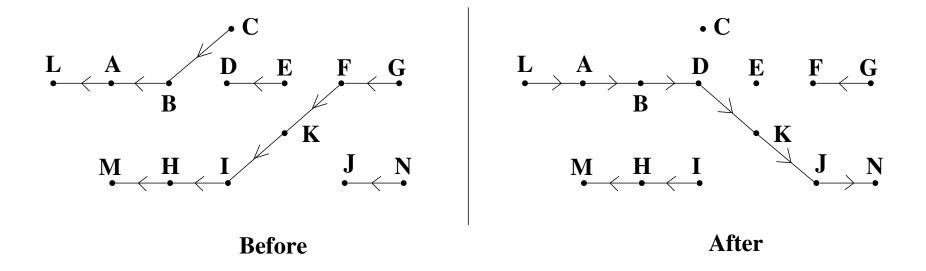
inv1_7:
$$LBT \subseteq OCC$$

If the last block b of a train is preceded by a block then that block is either not reserved or reserved for a route different from that of b

inv1_8:
$$\forall b \cdot \begin{pmatrix} b \in LBT \\ b \in ran(n) \\ \Rightarrow \\ n^{-1}(b) \notin dom(rsrtbl) \ \lor \ rsrtbl(n^{-1}(b)) \neq rsrtbl(b) \end{pmatrix}$$
 where n is $nxt(rsrtbl(b))$

where n is nxt(rsrtbl(b))

- Controller events:
 - point_positioning, (new event)
 - route_formation (new event)
 - route_reservation,
 - route_freeing,
- Environment events:
 - FRONT_MOVE_1,
 - FRONT_MOVE_2,
 - BACK_MOVE_1, (split)
 - BACK_MOVE_1 (split)



- An abstract view of point positioning:

```
\begin{array}{l} \mathsf{point\_positioning} \\ \quad \mathsf{any} \ r \ \mathsf{where} \\ \quad r \in \mathit{resrt} \setminus \mathit{frm} \\ \quad \mathsf{then} \\ \quad \mathit{TRK} := (\mathrm{dom}(\mathit{nxt}(r)) \lhd \mathit{TRK} \rhd \mathrm{ran}(\mathit{nxt}(r))) \ \cup \ \mathit{nxt}(r) \\ \mathsf{end} \end{array}
```

- The physical track of a reserved but not yet formed route is modified

- r is a reserved but not yet formed route
- the logical succession of blocks of r coincides with the physical one

```
route_formation \begin{array}{l} \text{any } r \text{ where} \\ r \in resrt \setminus frm \\ rsrtbl^{-1}[\{r\}] \lhd nxt(r) \ = \ rsrtbl^{-1}[\{r\}] \lhd TRK \\ \text{then} \\ frm := frm \ \cup \ \{r\} \\ \text{end} \end{array}
```

- This corresponds to a response from the physical track
- The controller verifies that the points are well positioned

```
egin{aligned} 	ext{(abstract-)FRONT\_MOVE\_1} & 	ext{any } r 	ext{ where} \ r \in resrt \ fst(r) \in resbl \setminus OCC \ rsrtbl(fst(r)) = r \ 	ext{then} \ OCC := OCC \cup \{fst(r)\} \ 	ext{end} \end{aligned}
```

- The (abstract) train still has access to some controller variables

```
\mathsf{FRONT\_MOVE\_1} any r where r \in frm fst(r) \in resbl \setminus OCC rsrtbl(fst(r)) = r then OCC := OCC \cup \{fst(r)\} LBT := LBT \cup \{fst(r)\} end
```

```
egin{array}{ll} 	ext{(abstract-)FRONT\_MOVE\_2} \ & 	ext{any} \;\; b, c \;\; 	ext{where} \ & b \in \mathit{OCC} \ & c \in \mathit{B} \setminus \mathit{OCC} \ & b \mapsto c \in \mathit{nxt}(\mathit{rsrtbl}(b)) \ & 	ext{then} \ & \mathit{OCC} := \mathit{OCC} \cup \{c\} \ & 	ext{end} \ \end{array}
```

The train now follows the physical track

```
\begin{array}{cccc} \mathsf{FRONT\_MOVE\_2} \\ & \mathsf{any} \ b \ \mathsf{where} \\ & b \in \mathit{OCC} \\ & b \in \mathit{dom}(TRK) \\ & \mathit{TRK}(b) \notin \mathit{OCC} \\ & \mathsf{then} \\ & \mathit{OCC} := \mathit{OCC} \cup \{\mathit{TRK}(b)\} \\ & \mathsf{end} \end{array}
```

```
\begin{array}{l} (\mathsf{abstract}\text{-})\mathsf{BACK}\_\mathsf{MOVE} \\ & \mathbf{any} \ b, n \ \ \mathsf{where} \\ & b \in \mathit{OCC} \\ & n = nxt(rsrtbl(b)) \\ & b \in \mathrm{dom}(n) \Rightarrow n(b) \in \mathit{OCC} \\ & \begin{pmatrix} b \in \mathrm{ran}(n) \land \\ n^{-1}(b) \in \mathrm{dom}(rsrtbl) \\ \Rightarrow \\ rsrtbl(n^{-1}(b)) \neq rsrtbl(b) \end{pmatrix} \\ & \mathsf{then} \\ & \mathit{OCC} := \mathit{OCC} \setminus \{b\} \\ & \mathit{rsrtbl} := \{b\} \lessdot \mathit{rsrtbl} \\ & \mathit{resbl} := \mathit{resbl} \setminus \{b\} \\ & \mathsf{end} \end{array}
```

```
egin{aligned} \mathsf{BACK\_MOVE\_1} \ & \mathsf{any} \ b \ \mathsf{where} \ & b \in LBT \ & b 
otinet \ & \mathsf{dom}(TRK) \ & \mathsf{then} \ & \mathit{OCC} := \mathit{OCC} \setminus \{b\} \ & \mathit{rsrtbl} := \{b\} \ \mathit{\dashv} \, \mathit{rsrtbl} \ & \mathit{resbl} := \mathit{resbl} \setminus \{b\} \ & \mathit{LBT} := \mathit{LBT} \setminus \{b\} \ & \mathsf{end} \ \end{aligned}
```

- The train follows the physical track
- A message is sent and treated by the controller (later split into 2 events)

```
\begin{array}{l} (\mathsf{abstract}\text{-})\mathsf{BACK\_MOVE} \\ & \mathbf{any} \ b, n \ \ \mathsf{where} \\ & b \in \mathit{OCC} \\ & n = nxt(rsrtbl(b)) \\ & b \in \mathrm{dom}(n) \Rightarrow n(b) \in \mathit{OCC} \\ & \begin{pmatrix} b \in \mathrm{ran}(n) \land \\ & n^{-1}(b) \in \mathrm{dom}(rsrtbl) \\ & \Rightarrow \\ & rsrtbl(n^{-1}(b)) \neq rsrtbl(b) \end{pmatrix} \\ & \mathsf{then} \\ & \mathit{OCC} := \mathit{OCC} \setminus \{b\} \\ & rsrtbl := \{b\} \lessdot rsrtbl \\ & resbl := resbl \setminus \{b\} \\ & \mathsf{end} \end{array}
```

```
\mathsf{BACK\_MOVE\_2}
\mathsf{any}\ b\ \mathsf{where}
b\in LBT
b\in \mathsf{dom}(TRK)
TRK(b)\in OCC
\mathsf{then}
OCC:=OCC\setminus\{b\}
rsrtbl:=\{b\} \mathrel{\lhd} rsrtbl
resbl:=resbl\setminus\{b\}
LBT:=(LBT\setminus\{b\})\cup\{TRK(b)\}
end
```

- The train follows the physical track
- A message is sent and treated by the controller (later split into 2 events)

variables: ...,

rdy

inv2_1: $rdy \subseteq frm$

inv2_2: $\forall r egin{pmatrix} r \in rdy \ \Rightarrow \ rtbl \rhd \{r\} \ = \ rsrtbl \rhd \{r\} \end{pmatrix}$

 $\mathsf{inv2_3:} \hspace{0.3cm} orall r \in rdy \ \Rightarrow \ \operatorname{dom}(rtbl \rhd \{r\}) \hspace{0.3cm} \cap \hspace{0.3cm} \mathit{OCC} = \varnothing \hspace{0.3cm}
ight)$

```
\begin{array}{l} \text{route\_formation} \\ & \text{any } r \text{ where} \\ & r \in resrt \setminus frm \\ & rsrtbl^{-1}[\{r\}] \lhd nxt(r) = rsrtbl^{-1}[\{r\}] \lhd TRK \\ & \text{then} \\ & frm := frm \ \cup \ \{r\} \\ & rdy := rdy \ \cup \ \{r\} \\ & \text{end} \end{array}
```

```
egin{array}{ll} 	ext{(abstract-)FRONT\_MOVE\_1} & 	ext{any } r 	ext{ where} \ r \in frm \ fst(r) \in resbl \setminus OCC \ rsrtbl(fst(r)) = r \ 	ext{then} \ OCC := OCC \cup \{fst(r)\} \ LBT := LBT \cup \{fst(r)\} \ 	ext{end} \end{array}
```

This event still uses some controller variables (wait until next refinement!)

```
\mathsf{FRONT}_{\mathsf{MOVE\_1}} any r where r \in rdy rsrtbl(fst(r)) = r then \mathit{OCC} := \mathit{OCC} \cup \{fst(r)\} \mathit{LBT} := \mathit{LBT} \ \cup \ \{fst(r)\} rdy := rdy \setminus \{r\} end
```

- Signals implement the concept of readiness (new carrier set S)

carrier sets: B, R, S

constants:

SIG

 $axm3_1: SIG \in ran(fst) \leftrightarrow S$

variables: ··

GRN

inv3_1: $GRN \subseteq S$

inv3_2: SIG[fst[rdy]] = GRN

```
\begin{array}{l} \text{route\_formation} \\ \quad \textbf{any} \ r \ \text{ where} \\ \quad r \in resrt \setminus frm \\ \quad rsrtbl^{-1}[\{r\}] \lhd nxt(r) = rsrtbl^{-1}[\{r\}] \lhd TRK \\ \text{then} \\ \quad frm := frm \ \cup \ \{r\} \\ \quad GRN := GRN \ \cup \ \{SIG(fst(r))\} \\ \text{end} \end{array}
```

```
\begin{array}{l} (\mathsf{abstract}\text{-})\mathsf{FRONT}\_\mathsf{MOVE}\_\mathsf{1} \\ \quad \mathsf{any} \ \ r \ \ \mathsf{where} \\ \quad r \in rdy \\ \quad rsrtbl(fst(r)) = r \\ \quad \mathsf{then} \\ \quad \mathit{OCC} := \mathit{OCC} \cup \{fst(r)\} \\ \quad \mathit{LBT} := \mathit{LBT} \ \cup \ \{fst(r)\} \\ \quad \mathit{rdy} := rdy \setminus \{r\} \\ \quad \mathsf{end} \end{array}
```

- The train now follows the physical track and obeys the green signal

```
\mathsf{FRONT\_MOVE\_1} any b where b \in \mathsf{dom}(SIG) SIG(b) \in GRN then OCC := OCC \cup \{b\} LBT := LBT \cup \{b\} GRN := GRN \setminus \{SIG(b)\} end
```

- More Refinements are needed in order to:
 - Introduce the physical points
 - Decompose events route_reservation, route_formation, and point_positioning in more atomic events

	Number of proofs	Automatic	Interactive
Initial Model	40	24	16
1st Refinement	46	26	20
2nd Refinement	26	15	11
3rd Refinement	12	9	3
4th Refinement	10	8	2
Total	134	82	52

- Not so many proofs (134), but a large proportion of interactive proofs (39%)
- Some interactive proofs are complex