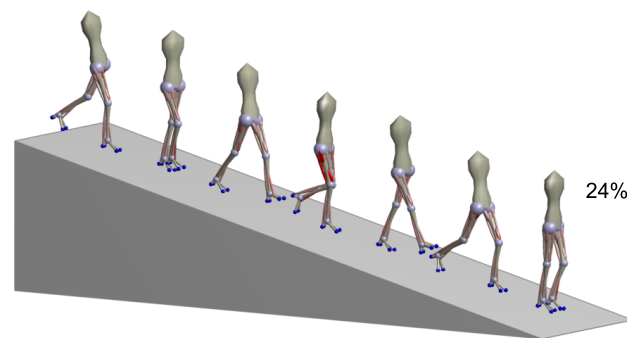
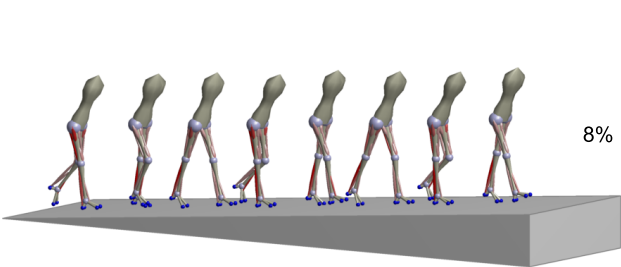
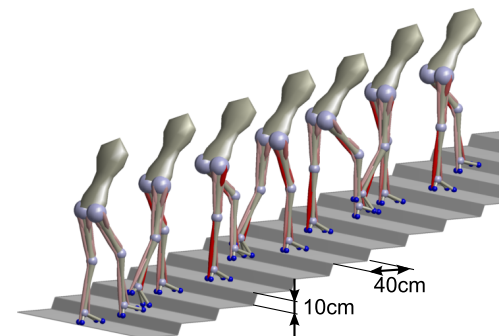


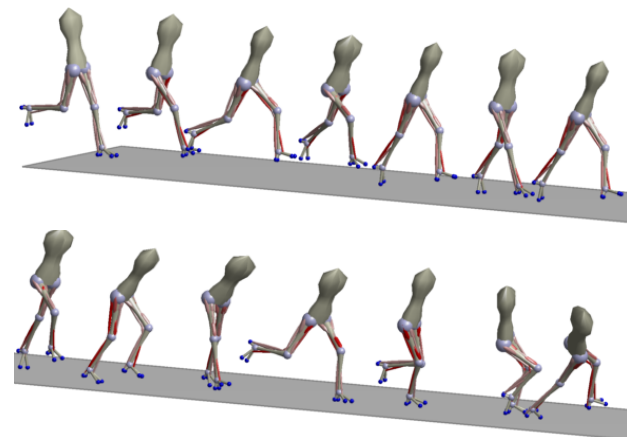
slope ascend and descend



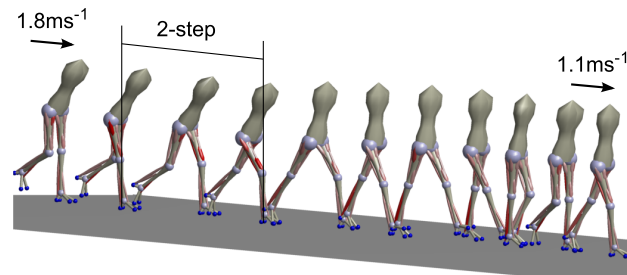
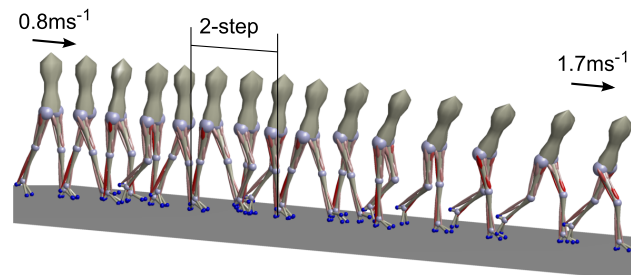
stair ascend



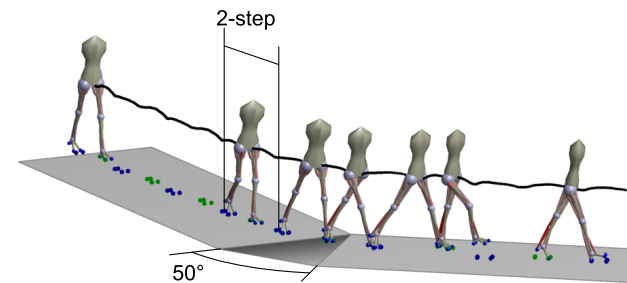
running



speed increase and decrease



turning



obstacle avoidance

