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```

1  package org.firstinspires.ftc.robotcon
2
3  import com.qualcomm.robotcore.eventloc
4  import com.qualcomm.robotcore.eventloc
5  import com.qualcomm.robotcore.hardware
6  import com.qualcomm.robotcore.hardware
7  import com.qualcomm.robotcore.hardware
8
9  @Autonomous(name = "revAutoBlue", grou
10 public class foundationBlue extends Li
11     //Naming motors and servos
12     private DcMotor frontLeft;
13     private DcMotor frontRight;
14     private DcMotor backLeft;
15     private DcMotor backRight;
16     private Servo foundationOne;
17     private Servo foundationTwo;
18     private Servo capStone;
19
20     private void forward(double power,
21         //Set wheels power to the valu
22         frontLeft.setPower(power);
23         frontRight.setPower(power);
24         backLeft.setPower(power);
25         backRight.setPower(power);
26         sleep(runtime); //Wait for run
27         //Set wheels power to 0
28         frontLeft.setPower(0);
29         frontRight.setPower(0);
30         backLeft.setPower(0);
31         backRight.setPower(0);
32
33     }
34
35     private void sideways(double power
36         //Set wheels power to the valu
37         frontLeft.setPower(power);

```