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```

1  package org.firstinspires.ftc.robotcon
2
3  import com.qualcomm.robotcore.eventloc
4  import com.qualcomm.robotcore.eventloc
5  import com.qualcomm.robotcore.hardware
6  import com.qualcomm.robotcore.hardware
7  import com.qualcomm.robotcore.hardware
8
9  @Autonomous(name = "shortRed") //Lined
10 public class shortLeft extends LinearO
11     private DcMotor frontLeft;
12     private DcMotor frontRight;
13     private DcMotor backLeft;
14     private DcMotor backRight;
15     private Servo foundationOne;
16     private Servo foundationTwo;
17     private Servo capStone;
18
19     private void forward(double power,
20         frontLeft.setPower(power);
21         frontRight.setPower(power);
22         backLeft.setPower(power);
23         backRight.setPower(power);
24         sleep(runtime);
25         frontLeft.setPower(0);
26         frontRight.setPower(0);
27         backLeft.setPower(0);
28         backRight.setPower(0);
29
30     }
31
32     private void sideways(double power
33         frontLeft.setPower(power);
34         frontRight.setPower(-power);
35         backLeft.setPower(power);
36         backRight.setPower(-power);
37         sleep(runtime);

```