```java
package org.firstinspires.ftc.robotcon

import com.qualcomm.robotcore.eventloo
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import com.qualcomm.robotcore.hardware
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@Autonomous(name = "shortBlue") //Line
public class shortRight extends Linear
    private DcMotor frontLeft;
    private DcMotor frontRight;
    private DcMotor backLeft;
    private DcMotor backRight;
    private Servo foundationOne;
    private Servo foundationTwo;
    private Servo capStone;

    private void forward(double power,
        frontLeft.setPower(power);
        frontRight.setPower(power);
        backLeft.setPower(power);
        backRight.setPower(power);
        sleep(runtime);
        frontLeft.setPower(0);
        frontRight.setPower(0);
        backLeft.setPower(0);
        backRight.setPower(0);
    }

    private void sideways(double power
        frontLeft.setPower(power);
        frontRight.setPower(-power);
        backLeft.setPower(power);
        backRight.setPower(-power);
        sleep(runtime);
        frontLeft.setPower(0);
```