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- tetrisTele.java

```

1  package org.firstinspires.ftc.robotcon
2  import com.qualcomm.robotcore.eventloc
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4  import com.qualcomm.robotcore.hardware
5  import com.qualcomm.robotcore.hardware
6  import com.qualcomm.robotcore.hardware
7
8  @Autonomous(name = "revAutoRed", group
9  public class foundationRed extends Lin
10     //Naming motors and servos
11     private DcMotor frontLeft;
12     private DcMotor frontRight;
13     private DcMotor backLeft;
14     private DcMotor backRight;
15     private Servo foundationOne;
16     private Servo foundationTwo;
17     private Servo capStone;
18
19     private void forward(double power,
20         //Set wheels power to the valu
21         frontLeft.setPower(power);
22         frontRight.setPower(power);
23         backLeft.setPower(power);
24         backRight.setPower(power);
25         sleep(runtime); //Wait for run
26         //Set wheels power to 0
27         frontLeft.setPower(0);
28         frontRight.setPower(0);
29         backLeft.setPower(0);
30         backRight.setPower(0);
31     }
32
33     private void sideways(double power
34         //Set wheels power to the valu
35         frontLeft.setPower(power);
36         frontRight.setPower(-power);
37         backLeft.setPower(power);

```