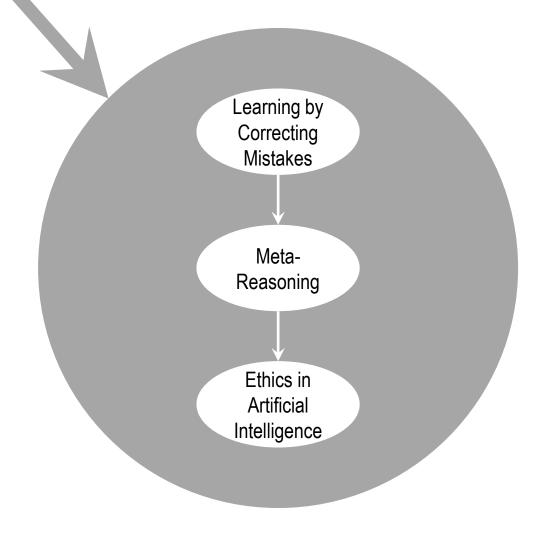
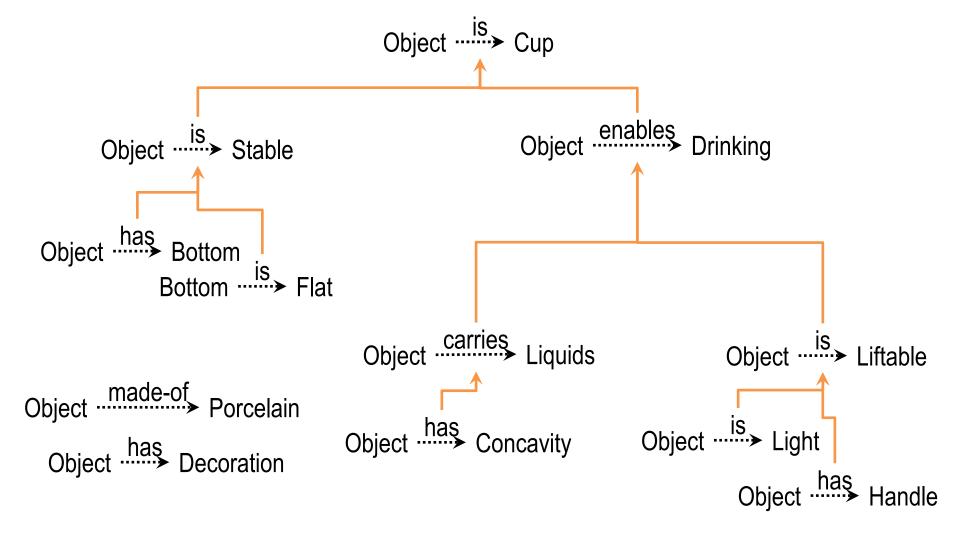


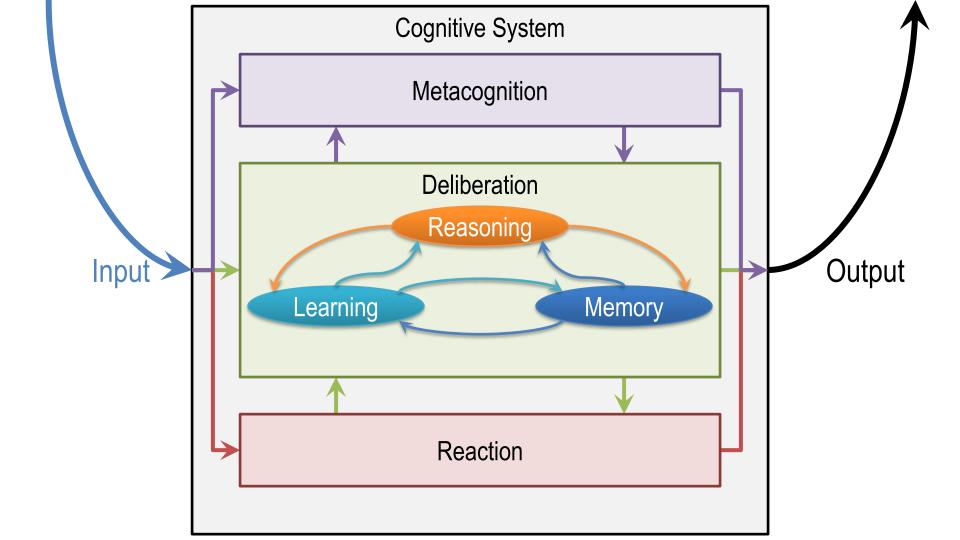
Metacognition

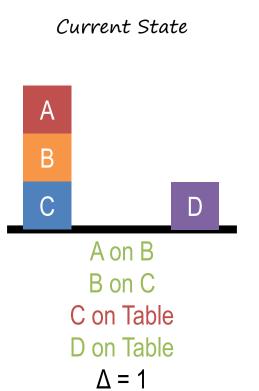


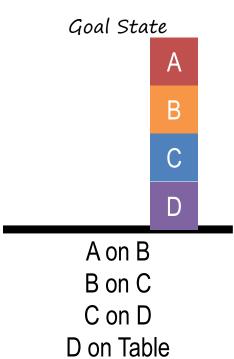
Lesson Preview

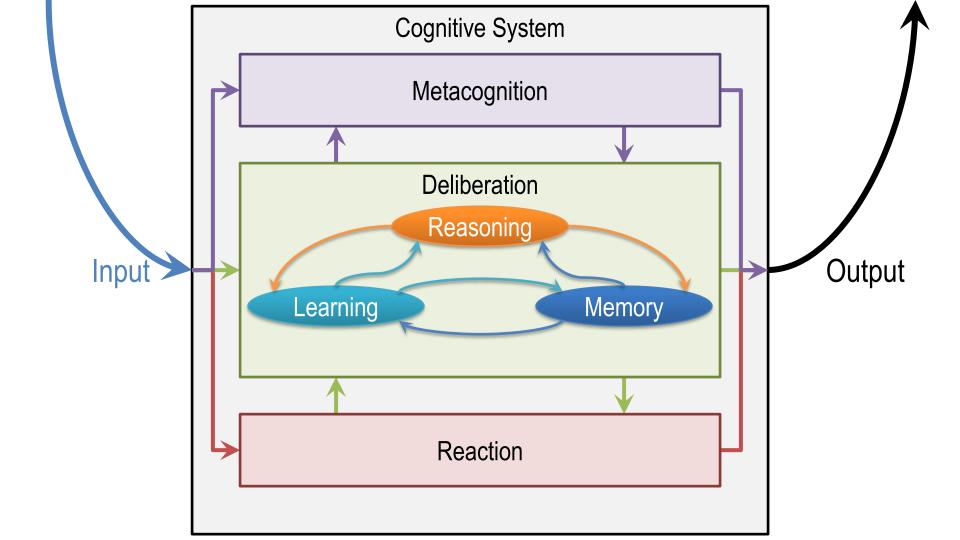
- Mistakes in knowledge, reasoning, and learning
- Gaps in knowledge and reasoning
- Strategy selection and integration
- Meta-meta-reasoning?
- Goal-based autonomy

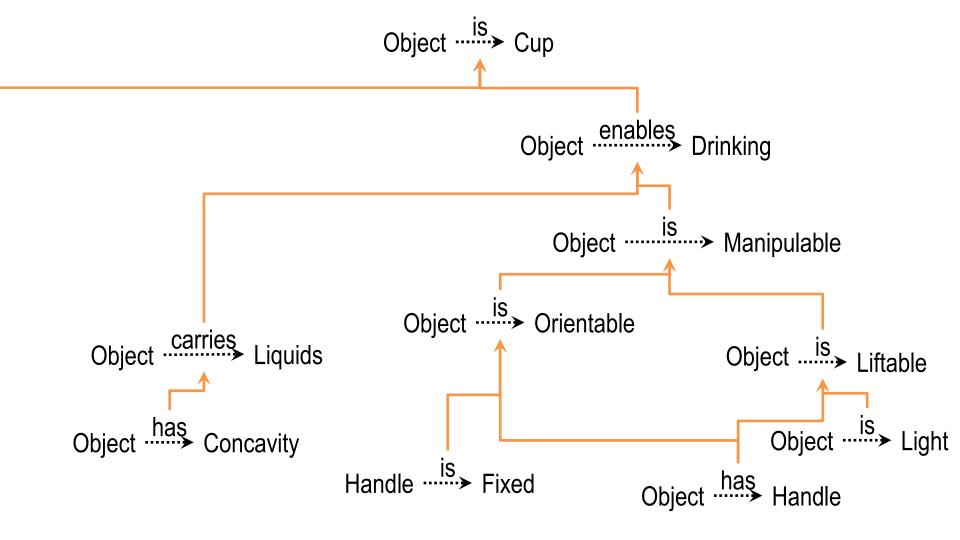


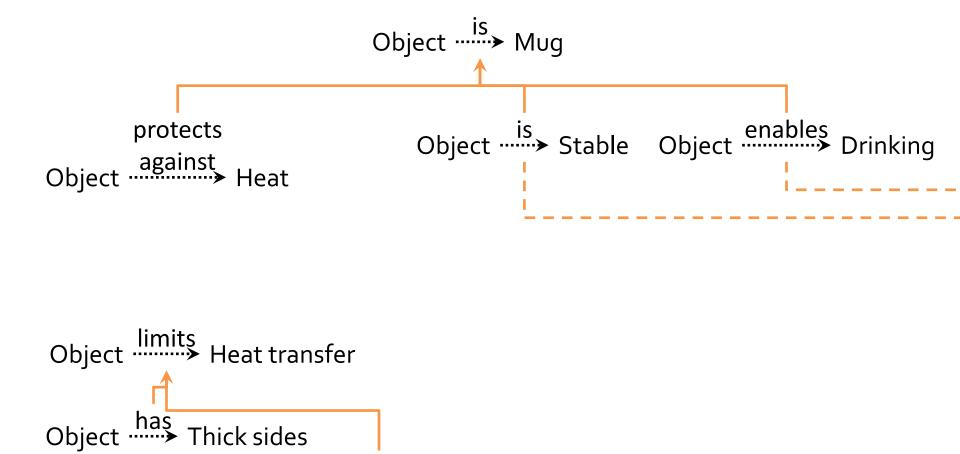




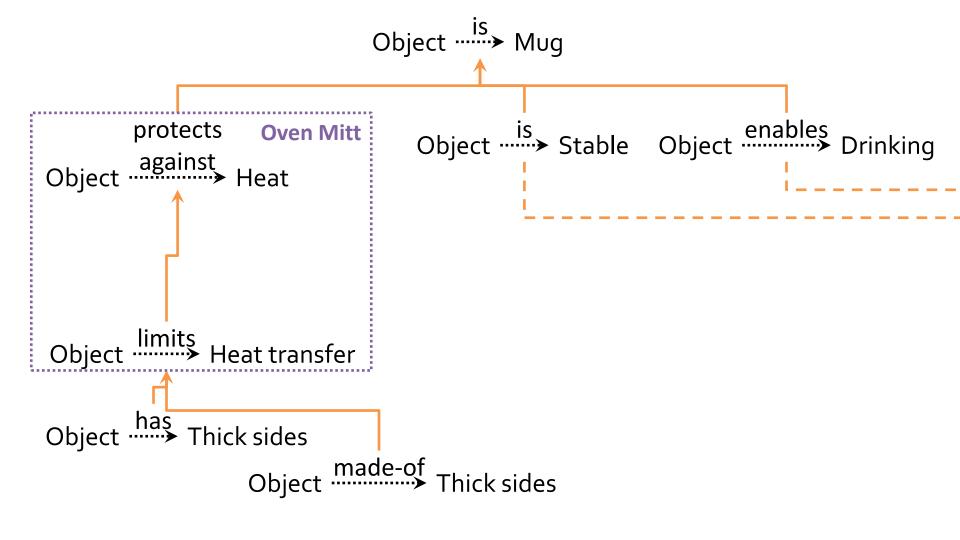


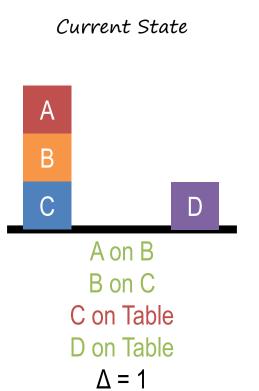


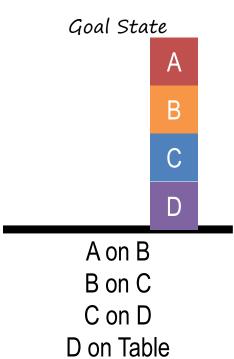


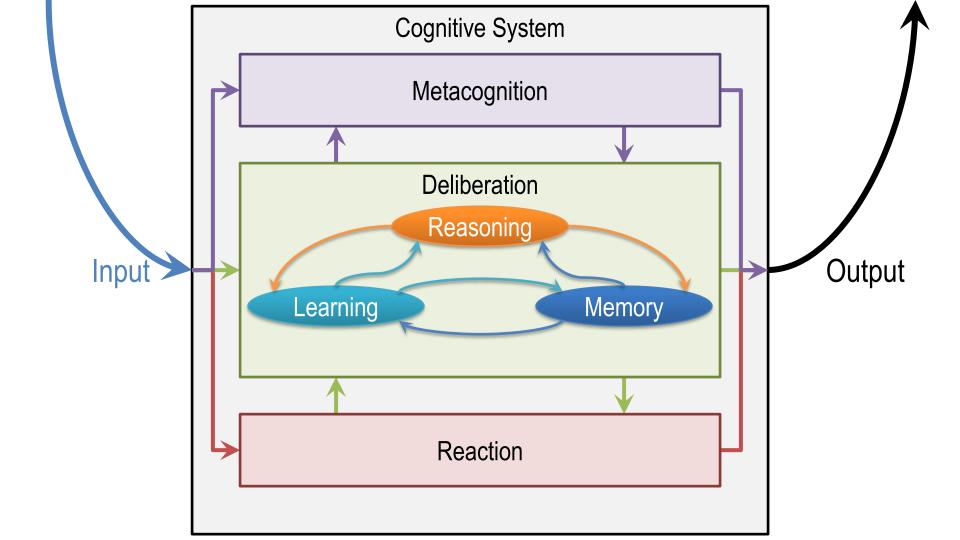


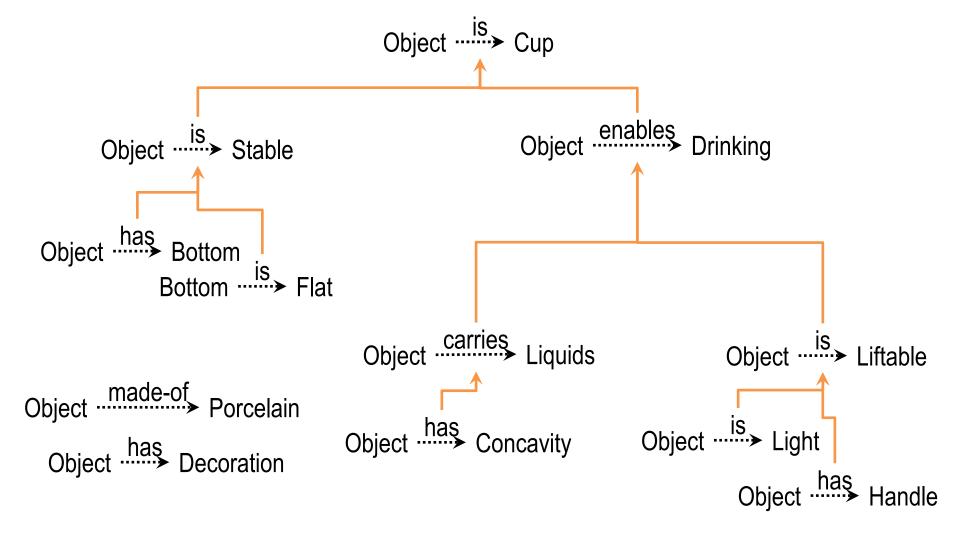
Object made-of Thick sides

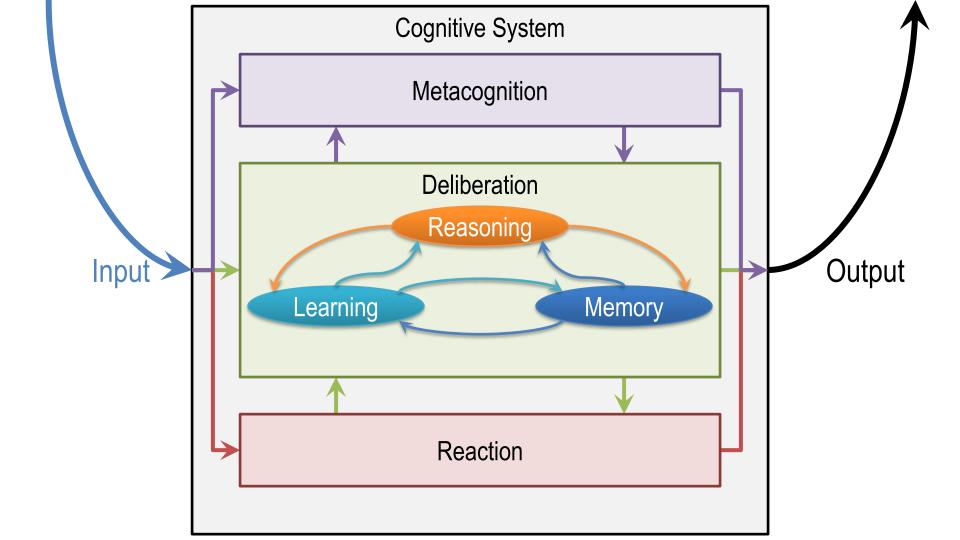


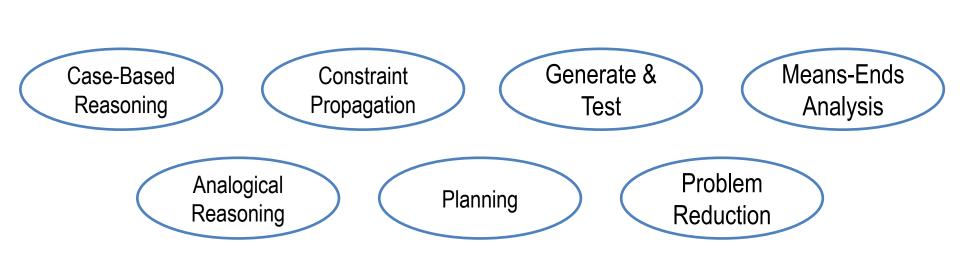


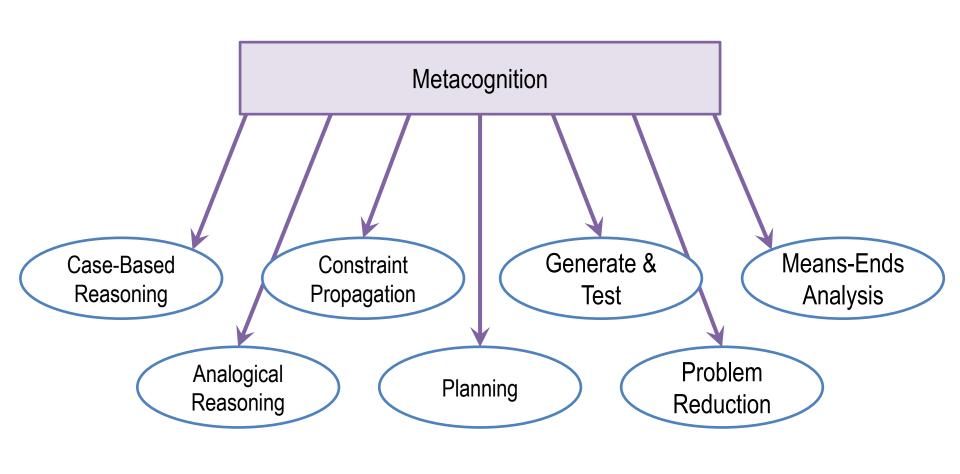


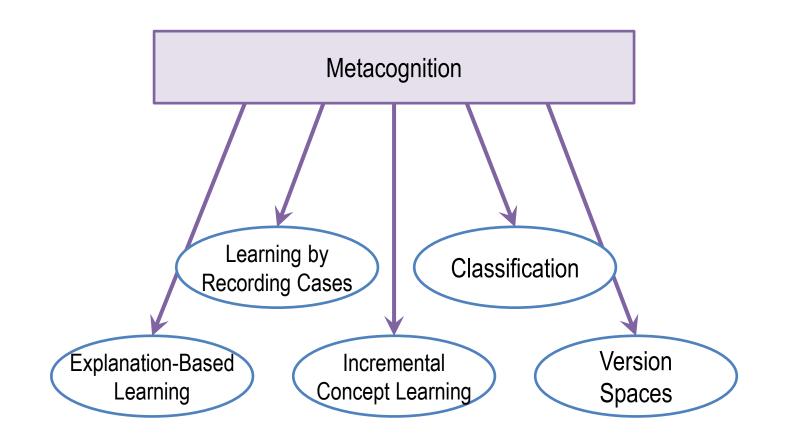


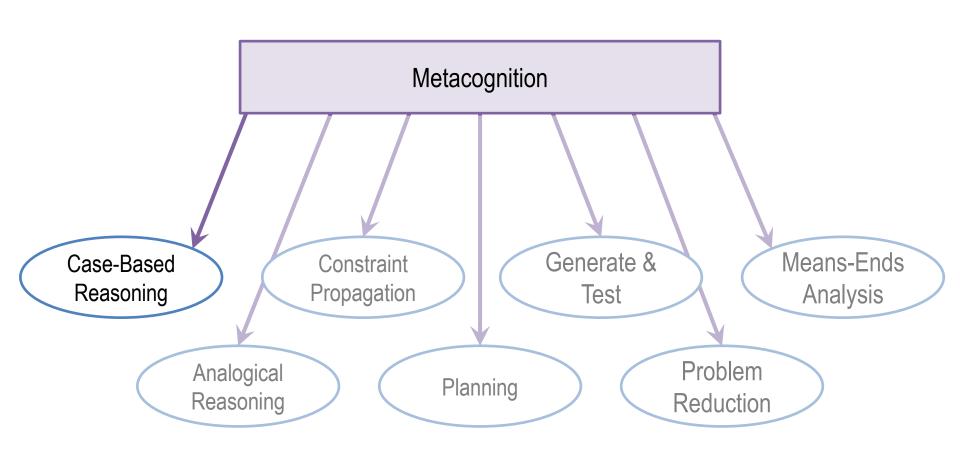






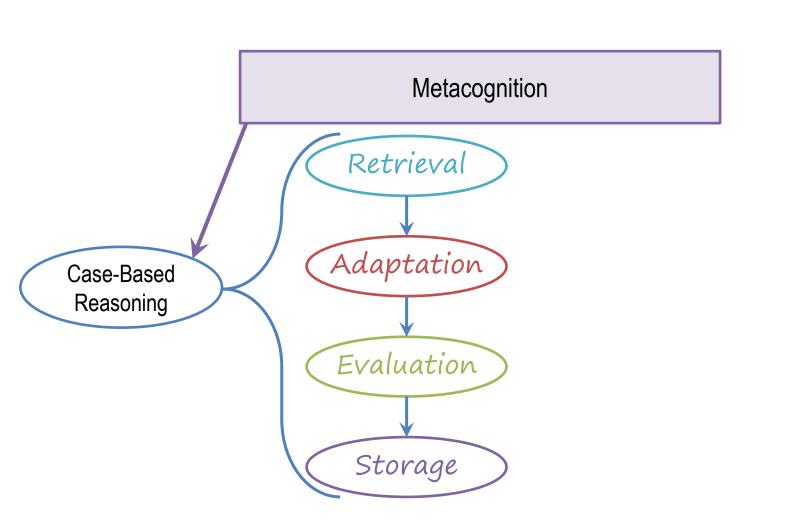


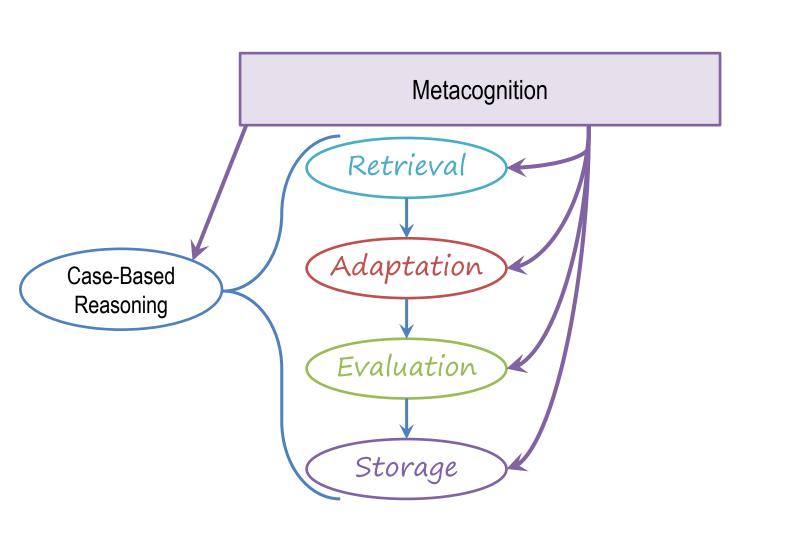


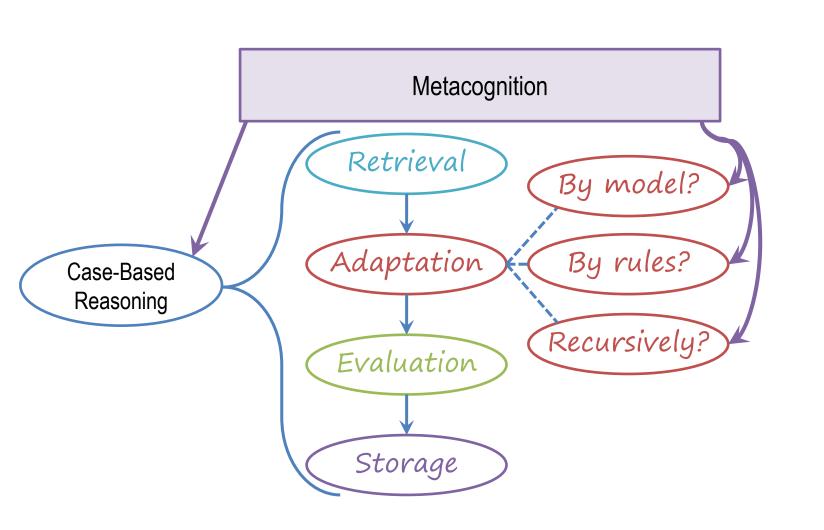


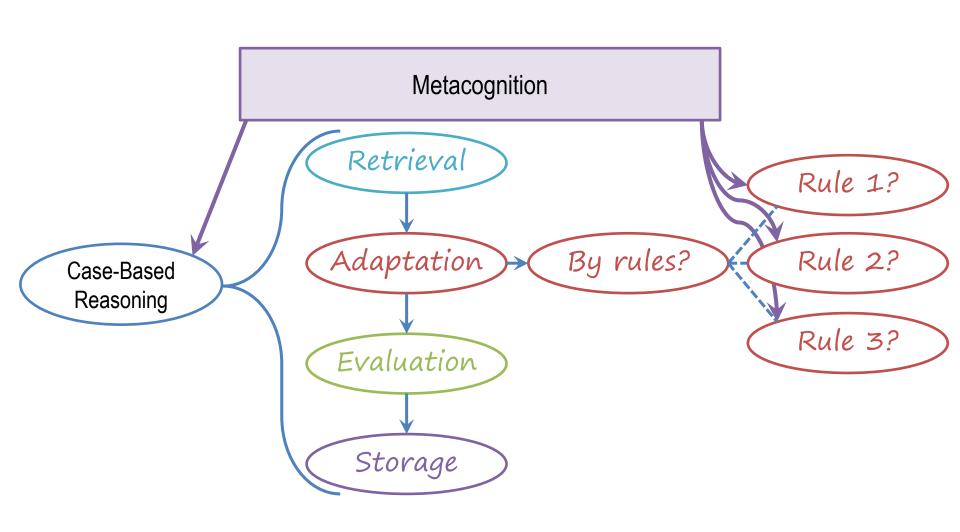
Metacognition

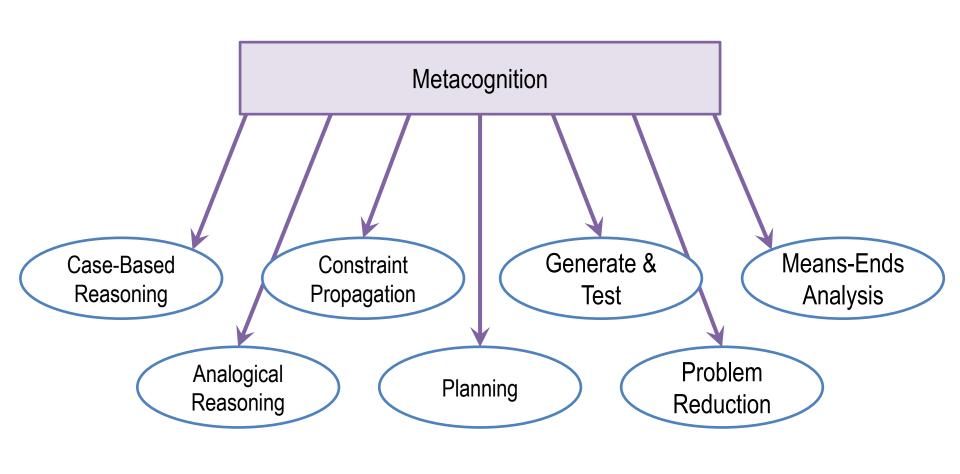
Case-Based Reasoning

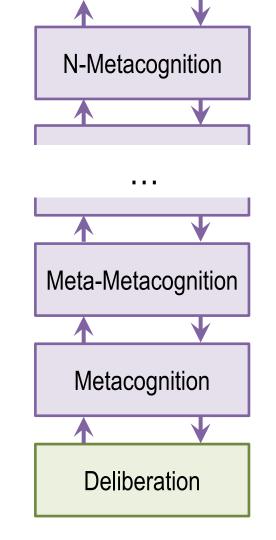








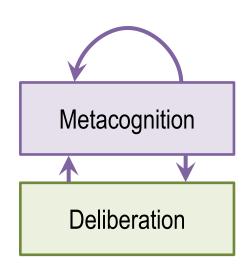




Is this a good way to think about levels of metacognition?

- o Yes, because it is possible to think about every successive level.
- o No, because there is a maximum level of metacognition possible.
 - No, because each level of metacognition is conceptually identical, so they are better represented as self-referential.

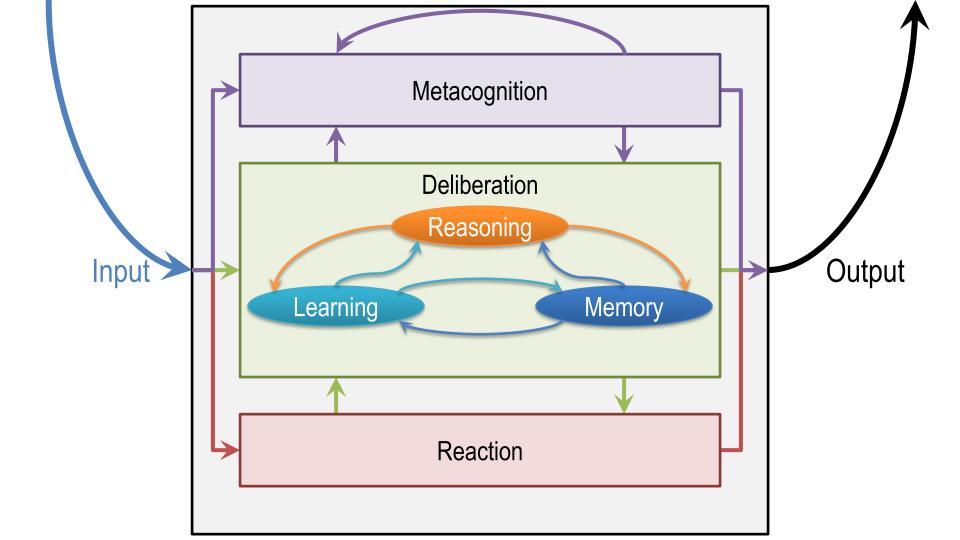
o No, because there is no need to distinguish between metacognition and deliberation.

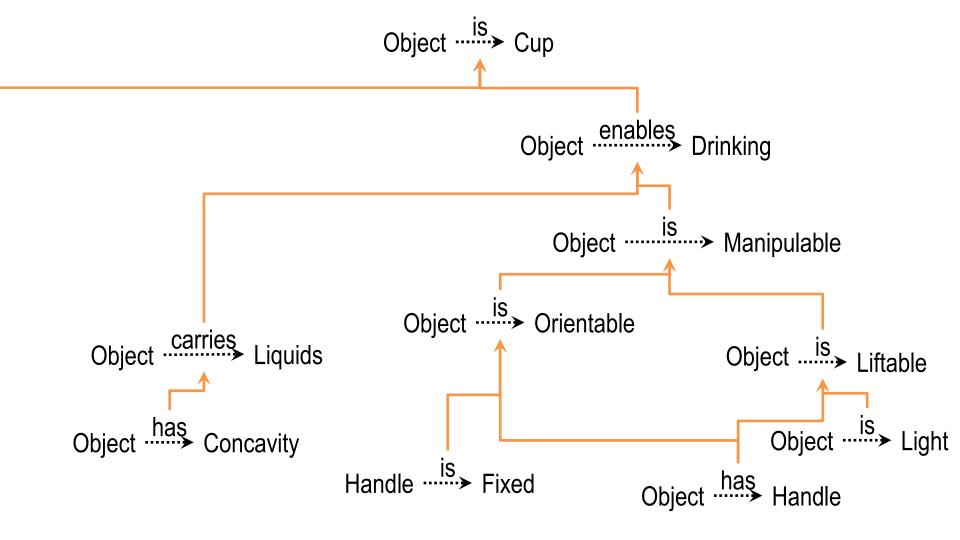


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o No, because there is no need to distinguish between metacognition and deliberation.





```
Goal: Painted (Ladder) Goal: Painted (Ceiling)
On (Robot, Floor) ^
                                  On (Robot, Floor) ^
Dry(Ladder) ∧ Dry(Ceiling)
                                  Dry(Ladder) ∧ Dry(Ceiling)
               paint-ladder
                                                  climb-ladder
On (Robot, Floor) ^
                                  On (Robot, Ladder) ^
¬Dry(Ladder) ∧ Dry(Ceiling)
                                  Dry(Ladder) ∧ Dry(Ceiling)
∧ Painted (Ladder)
                                                  paint-ceiling
 climb-ladder:
                                  On (Robot, Ladder) ^
 Precondition:
                                  Dry(Ladder) ∧ ¬Dry(Ceiling)
     On (Robot, Floor) A
                                  ∧ Painted (Ceiling)
   — Dry (Ladder)
   Postcondition:
     On (Robot, Ladder)
```

```
inning : 5th
portion : bottom
game : 131
weather : windy
runners : 1st, 3rd
outs: 1
batter : Pierzynski
average: .283
bats : left-handed
score: 1-4
goal : pitch
pitch : throw-fast-ball
result : homerun
```

(r8) If two operators selected and one has an episode with **result**homerun

then prefer other operator

"chunking"

Version Spaces





General

Is this a foo?



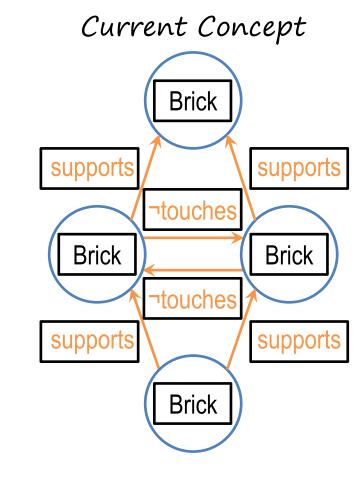
o Yes

o No

This is not a foo.



Modify the concept on the right to specialize based on this example.



<u>Assignment</u>

How would you use meta-reasoning to design an agent that could answer Raven's progressive matrices?

To recap...

Resolving mistakes and gaps

- Strategy selection and integration
- Meta-meta-reasoning?

- Goal-based autonomy