$$|\mathbf{A} - \lambda \mathbf{I}| = \begin{vmatrix} 1 & 0 \\ 1 & 3 \end{vmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix}$$
$$= \begin{vmatrix} 1 - \lambda & 0 \\ 1 & 3 - \lambda \end{vmatrix} = (1 - \lambda)(3 - \lambda) = 0$$

implies that there are two roots,  $\lambda_1 = 1$  and  $\lambda_2 = 3$ . The eigenvalues of **A** are 3 and 1. Let

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix}$$

are  $\lambda_1 = 1$  and  $\lambda_2 = 3$ . The eigenvectors associated with these eigenvalues can be determined by solving the following equations:

$$\begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 1 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\mathbf{A}\mathbf{x} = \lambda_1 \mathbf{x}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 3 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\mathbf{A}\mathbf{x} = \lambda_2 \mathbf{x}$$

From the first expression,

$$x_1 = x_1$$
$$x_1 + 3x_2 = x_2$$

or

$$x_1 = -2x_2$$

There are many solutions for  $x_1$  and  $x_2$ .

Setting  $x_2 = 1$  (arbitrarily) gives  $x_1 = -2$ , and hence,

$$\mathbf{x} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

is an eigenvector corresponding to the eigenvalue 1. From the second expression,

$$x_1 = 3x_1$$
$$x_1 + 3x_2 = 3x_2$$

implies that  $x_1 = 0$  and  $x_2 = 1$  (arbitrarily), and hence,

$$\mathbf{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

is an eigenvector corresponding to the eigenvalue 3. It is usual practice to determine an eigenvector so that it has length unity. That is, if  $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$ , we take  $\mathbf{e} = \mathbf{x}/\sqrt{\mathbf{x}'\mathbf{x}}$  as the eigenvector corresponding to  $\lambda$ . For example, the eigenvector for  $\lambda_1 = 1$  is  $\mathbf{e}'_1 = \left[-2/\sqrt{5}, 1/\sqrt{5}\right]$ .