

# Connor Geshan

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<b>Education</b>	<b>Master of Science in Mechanical Engineering</b> <b>GPA: 4.0/4.0</b> Carnegie Mellon University, Pittsburgh, PA <b>Current Courses:</b> Computer Vision, Bio-Inspired Robot Design & Experimentation, Humanoid Robotics & Cognition, Designing & Deploying AI/ML Systems, Adv. Engineering Computation, Space Robotics	December 2023
	<b>Bachelor of Science in Mechanical Engineering</b> <b>Concentration in Mechatronics</b> <b>Minors: Computer Science &amp; Mathematics</b> Western New England University, Springfield, MA <b>Courses:</b> Design Mechatronics Systems, Software Design, Abstract Algebra	May 2022
<b>Work Experience</b>	<b>Research and Development Intern</b> Callaway Golf, Carlsbad, CA <ul style="list-style-type: none"><li>Utilize Python to enhance the usability and efficiency of Graphical User Interfaces (GUI)</li><li>Supported patent initiative for putting alignment aid</li><li>Generated data manipulation Excel Sheets using Visual Basic to study the effect golf ball properties have on performance</li></ul> <b>Product Engineering Intern</b> Callaway Golf, Chicopee, MA <ul style="list-style-type: none"><li>Set up a golf ball packing factor to estimate the quantity of balls per container within 10% accuracy to decrease manual counting for packers</li><li>Created a test system to track inventory using RFID which eliminated the need for a physical count.</li></ul> <b>Teacher's Assistant-WNEU</b> <b>3D Printing Lab Technician-WNEU</b> <ul style="list-style-type: none"><li>Printed parts to support first-year projects</li></ul>	June 2021 – August 2021  October 2020 – April 2021  August 2019 – May, 2022 October 2019 – May 2021
<b>Projects</b>	<b>PRISM Ranger - CMU</b> <ul style="list-style-type: none"><li>Perception Deputy of Surface Mobility Team</li></ul> <b>Synchronizing Multimodal Behaviors - CMU</b> <ul style="list-style-type: none"><li>Simulated synchronized multimodal behaviors using metahuman and Unreal Engine 5</li></ul> <b>Rabbit &amp; Snitch Robot Competition - WNEU</b> <ul style="list-style-type: none"><li>Developed one remote-controlled seeker robot and one autonomous avoidance robot</li><li>Won First Place Overall</li></ul> <b>Emerging Engineers Expo - WNEU</b> <ul style="list-style-type: none"><li>Created a mobile robot equipped with an arm to assist persons with disabilities</li></ul>	September 2022 – December 2022 September 2022 – December 2022 August 2018 – December 2019 January 2019 – May 2019
<b>Skills</b>	<b>Programming:</b> Python, C++, Git, CMake, Java, Arduino, Visual Basic <b>Engineering Software:</b> SolidWorks, NX, MATLAB, LabVIEW <b>Additive Manufacturing:</b> 3D Printing, CURA	
<b>Activities</b>	<b>NCAA Athlete – Men's Ice Hockey – Western New England</b>	2018-2022
<b>Summary</b>	Mechanical Engineering graduate student with successful work and leadership experiences. Recognized for strong dedication. Effective leader with group experience and team success. Motivated to apply all education and skills in an Engineering position.	