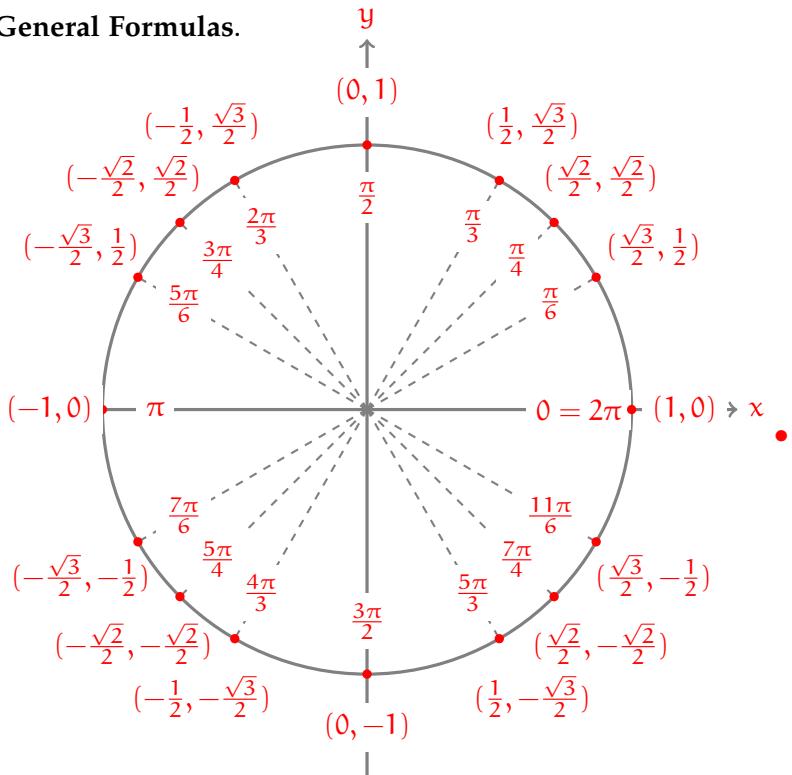


General Formulas.



- $\arctan(t) = \int \frac{1}{1+t^2} dt$

- $\arcsin(t) = \int \frac{1}{\sqrt{1-t^2}} dt$

- $\ln|t| = \int \frac{1}{t} dt$

- power reduction formulas:

- $\cos^2 \theta = \frac{1 + \cos 2\theta}{2}$ and $\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$

- double-angle formulas:

- $\sin 2t = 2 \sin t \cos t$ and $\cos 2t = \cos^2 t - \sin^2 t$

A1 Formulas.

- products and lengths and angles:
 - $\mathbf{v} \cdot \mathbf{w} = \|\mathbf{v}\| \|\mathbf{w}\| \cos \theta$
 - $\|\mathbf{v} \times \mathbf{w}\| = \|\mathbf{v}\| \|\mathbf{w}\| \sin \theta$ [parallelogram area]
- projection and scalar component:
 - $\text{proj}_{\mathbf{v}}(\mathbf{w}) = \left(\frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{v} \cdot \mathbf{v}} \right) \mathbf{v}$
 - $\text{comp}_{\mathbf{v}}(\mathbf{w}) = \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\|}$
- scalar triple product = ± parallelepiped volume:
 - $\mathbf{v} \cdot (\mathbf{w} \times \mathbf{r}) = \mathbf{r} \cdot (\mathbf{v} \times \mathbf{w}) = \mathbf{w} \cdot (\mathbf{r} \times \mathbf{v})$

A2 Formulas.

- distance from point B to plane P with normal \mathbf{n} :
 - $\frac{|\mathbf{AB} \cdot \mathbf{n}|}{\|\mathbf{n}\|}$ where A is on P
- distance from point B to line ℓ with direction vector \mathbf{v} :
 - $\frac{\|\mathbf{AB} \times \mathbf{v}\|}{\|\mathbf{v}\|}$ where A is on ℓ

A3 Formulas.

- standard form surfaces:
 - paraboloid: $\hat{z} = \hat{x}^2 + \hat{y}^2$
 - saddle: $\hat{z} = \hat{x}^2 - \hat{y}^2$
 - 1-sheeted hyperboloid: $\hat{x}^2 + \hat{y}^2 - \hat{z}^2 = 1$
 - 2-sheeted hyperboloid: $-\hat{x}^2 - \hat{y}^2 + \hat{z}^2 = 1$
 - ellipsoid: $\hat{x}^2 + \hat{y}^2 + \hat{z}^2 = 1$
 - double-cone: $\hat{z}^2 = \hat{x}^2 + \hat{y}^2$

A4 Formulas.

- tangent plane to $z = f(x, y)$ at $(a, b, f(a, b))$ is:
 - $z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$

A5 Formulas.

- $D_{\mathbf{u}}f(P) = \nabla f(P) \cdot \mathbf{u}$ where \mathbf{u} is a unit direction
 - max'ed in direction $\nabla f(P)$, with value $\|\nabla f(P)\|$
 - min'ed in direction $-\nabla f(P)$, with value $-\|\nabla f(P)\|$
 - equals 0 in directions \perp to $\nabla f(P)$
- tangent plane to level set $F(x, y, z) = C$ at P is:
 - $\nabla F(P) \cdot (x - p) = 0$

B1 Formulas.

- If P is a critical point of $f(x, y)$ and:
 - $D = f_{xx}(P)f_{yy}(P) - (f_{xy}(P))^2$
 - $T = f_{xx}(P) + f_{yy}(P)$
- then:
 - $D < 0 \Rightarrow$ saddle
 - $D > 0$ and $T > 0 \Rightarrow$ local minimizer
 - $D > 0$ and $T < 0 \Rightarrow$ local maximizer

B2 Formulas.

- An extremizer P of f subject to $g = C$ satisfies:
 - $\nabla f(P) = \lambda \nabla g(P)$ or $\nabla g(P) = 0$

B5 Formulas.

- polar and cylindrical
 - $r^2 = x^2 + y^2$ and $\tan \theta = \frac{y}{x}$
 - $x = r \cos \theta$ and $y = r \sin \theta$
 - $dA = r dr d\theta$ and $dV = r dz dr d\theta$

C1 Formulas.

- spherical
 - $\rho^2 = x^2 + y^2 + z^2$ and $\tan \phi = \frac{r}{z}$
 - $r = \rho \sin \phi$ and $z = \rho \cos \phi$
 - $x = \rho \sin \phi \cos \theta$ and $y = \rho \sin \phi \sin \theta$
 - $dV = \rho^2 \sin \phi \ dr d\phi d\theta$

C2 Formulas.

- arclength $= \int_C f \ ds = \int_a^b \|r'(t)\| dt$
- scalar line integral:
 - $\int_C f \ ds$ where $ds = \|r'(t)\| dt$
- vector line integral:
 - $\int_C \mathbf{F} \cdot d\mathbf{r}$ where $d\mathbf{r} = r'(t) dt$
 - or $\int_C P dx + Q dy + R dz$ where:
 - $\langle dx, dy, dz \rangle = \langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \rangle dt$

C3 Formulas.

- fundamental theorem of line integrals:
 - if $\mathbf{F} = \nabla f$, and given path $\mathbf{r}(t)$ with $a \leq t \leq b$:
 - $\int_r \mathbf{F} \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$
- conservative vector fields are irrotational ($\text{curl } \mathbf{F} = 0$)
- [irrotational + simply-connected domain] \Rightarrow conservative
- conservative vec. fields have path-independent line integrals
- $\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$
 - for 2D vector fields $\mathbf{F} = \langle P, Q \rangle$, have: $\text{curl } \mathbf{F} = (Q_x - P_y)k$

C5 Formulas.

- Green's Theorem:
 - $C = \partial D$, oriented so D on left, then:

$$\oint_C P \ dx + Q \ dy = \iint_D Q_x - P_y \ dA$$
- Stokes's Theorem:
 - $C = \partial S$, oriented by righthand rule for normals:

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$$

C4 Formulas.

- $dS = \|\mathbf{R}_u \times \mathbf{R}_v\| \ du \ dv$
- $dS = \pm (\mathbf{R}_u \times \mathbf{R}_v) \ du \ dv$
 - choice \pm depends on orientation

- graph $z = f(x, y)$ has:

- $dS = \sqrt{f_x^2 + f_y^2 + 1} \ dx \ dy$
- $dS = \langle -f_x, -f_y, 1 \rangle \ dx \ dy$ (upwards)

- graph $z = f(r)$ has:

- $dS = r \sqrt{[f'(r)]^2 + 1} \ dr \ d\theta$
- $dS = \langle -f'(r)r \cos \theta, -f'(r)r \sin \theta, r \rangle \ dr \ d\theta$ (upwards, if $r > 0$)

- sphere $\rho = R$ has:

- $dS = R^2 \sin \phi \ d\phi \ d\theta$
- $dS = R^2 \sin \phi \langle \cos \theta \sin \phi, \sin \theta \sin \phi, \cos \phi \rangle \ d\phi \ d\theta$ (outwards)
 - $= (R \sin \phi) \langle x, y, z \rangle \ d\phi \ d\theta$ (outwards)