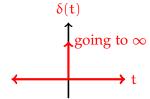
## A. Dirac Delta Function.

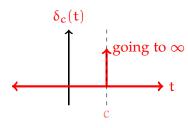
Intuitively the **dirac delta function** is defind by:

$$\delta(t) = \begin{cases} \infty & \text{if } t = 0 \\ 0 & \text{if } t \neq 0 \end{cases}$$



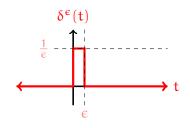
and so its shift right by c is:

$$\delta_{c}(t) = \delta(t-c) = \begin{cases} \\ \end{cases}$$



More precisely  $\delta(t)$  is defined to be the limit as  $\varepsilon \to 0$  of the functions:

$$\delta^{\varepsilon}(t) = \begin{cases} 0 & \text{if } t < 0 \\ \frac{1}{\varepsilon} & \text{if } 0 \leqslant t < \varepsilon \\ 0 & \text{if } t \geqslant \varepsilon \end{cases}$$



**Key Integral Properties.** If **c** is nonnegative:

Total area:  $\int_0^\infty \delta(t-c)\ dt =$ 

Sifting property:  $\int_0^\infty \delta(t-c)f(t)\ dt =$ 

Laplace transform:  $\mathcal{L}(\delta_c)(s) =$ 

$$\mathcal{L}(\delta)(s) =$$

$$\mathcal{L}(\delta_{\mathbf{c}}\mathbf{f})(\mathbf{s}) =$$

The Laplace transform of  $\delta_c$  would be:

$$\int_0^\infty e^{-st} \delta_c(t) dt$$

## **Example 1.** Solve the following initial value problem:

$$y^{\prime\prime}-12y^{\prime}+40y=\delta(t-\frac{\pi}{6})\sin t$$
 with  $y(0)=y^{\prime}(0)=0$ 

Recall the Laplace transform rules:

$$\mathcal{L}(y')(s) = sY - y(0)$$

$$\mathcal{L}(y'')(s) = s^2Y - sy(0) - y'(0)$$

Recall the formula from the last page:

$$\mathcal{L}(\delta_c f)(s) = e^{-c\,s} f(c)$$

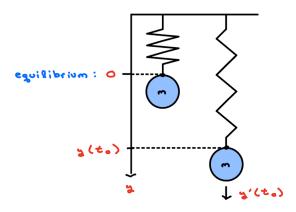
Recall the inverse translation formula:

$$\mathcal{L}^{-1}\lbrace e^{-cs}F(s)\rbrace(t) = H_c(t)f(t-c)$$

Recall the inverse Laplace formula:

$$\mathcal{L}^{-1}\left\{\frac{1}{(s-\alpha)^2+b^2}\right\}(t) = \frac{e^{\alpha t}\sin bt}{b}$$

## B. **Unit Impulse Response.** Consider a mass m hanging from a spring:



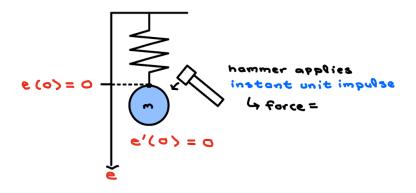
In the absence of an external force the differential equation governing motion is:

$$my'' + \mu y' + ky = 0$$

If there is an external force f(t) then the appropriate differential equation is:

$$my'' + \mu y' + ky =$$

In particular consider the response e(t) to an **instant unit impulse**:



 $\mu$  is the damping constant and k is the spring constant.

**Impulse** is (force)  $\cdot$  (change in time). If the impulse equals 1, but the change in time is 0, then the force must be  $\infty$ .

Given a system with constant coefficients:

ay'' + by' + cy = f(t) with any initial values

the unit impulse response is the solution e(t) to initial value problem:

The Laplace transform of this system is:

and its solution is called the transfer function E.

E =

There is a technicality here: we will see that e'(0) is not actually defined in practice, because the sudden impulse leads to a corner, a failure of differentiability. Therefore the correct condition to impose here is  $e'(0^-) = 0$ , indicating that there is no response before the impulse hits, i.e. just to the left of time t=0.

In discussion section, you will learn that, in the s-domain, the transfer function converts the forcing term f(t) to a state-free solution of the system. A state-free system is one in which the initial values are all 0.

**Example 2.** Let  $\omega_0$  be a constant and consider the system:

$$y'' + \omega_0^2 y = \cos t$$
 with  $y(0) = 1$  and  $y'(0) = -1$ 

Find the transfer function and unit impulse response.

Recall the formula:

$$\mathcal{L}^{-1}\left\{\frac{1}{s^2+b^2}\right\}(t) = \frac{\sin bt}{b}$$

Note that we need to multiply by the Heaviside function H(t) here because there is no response until the impulse hits at t=0. This leads to a strange issue: the condition e'(0)=0 is not technically defined because e(t) will not be differentiable at 0: it will have a corner due to truncation by the Heaviside. So really, the correct initial value to impose here is that  $e'(0^-)=0$ , i.e. the derivative coming from the left is zero, as was indicated in an earlier margin note. This is what the impulse reponse will genuinely satisfy.