

# Numbers and Points

## Overview

Julian Pfeifle

Dept. Matemàtica Aplicada II  
Universitat Politècnica de Catalunya



Computational Geometry 2011/12

# Computational Geometry is about ... Computing

... and *computing* means: Algorithms work on numbers.

## What is a number?

|                          |   |  |
|--------------------------|---|--|
| $\mathbb{N}, \mathbb{Z}$ | int, long int, long long int<br>or work with arbitrary precision (slower)                                       | $-9.2 \cdot 10^{18} \dots 9.2 \cdot 10^{18}$<br>gmp <code>lib.org</code> |
| $\mathbb{Q}$             | $\{(n, d) : n \in \mathbb{Z}, d \in \mathbb{N}_{>0}\} / \sim$ ,<br>where $(n, d) \sim (n', d')$ iff $nd' = n'd$ | gmp <code>lib.org</code>   |
| $\mathbb{R}$             | algebraic numbers ok ( $\sqrt{2}$ , $\sqrt[4]{3}$ ),<br>transcendental ones not ( $\pi$ , $e$ )                 | cgal <code>.org</code> , mpfr <code>.org</code>                          |
| $\mathbb{C}, \mathbb{H}$ | pairs or quadruples of reals  | <code>#include &lt;complex&gt;</code>                                    |

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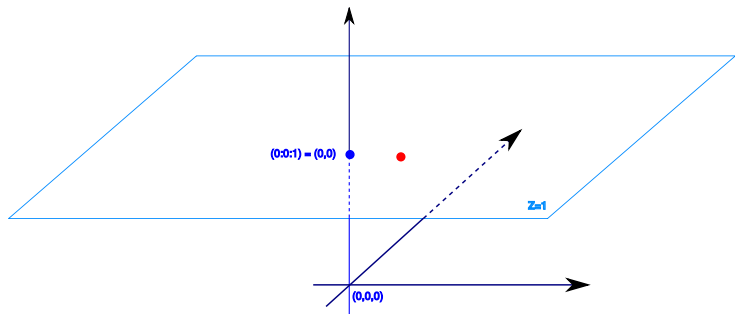
|                          |   |   |
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## How much space does a number occupy on your hard disk?

Roughly  $\log_2 n$  bits.

$(5 \cdot 10^{12})$  digits of  $\pi$  occupy 8.32 TB as .txt, 3.8 TB compressed)

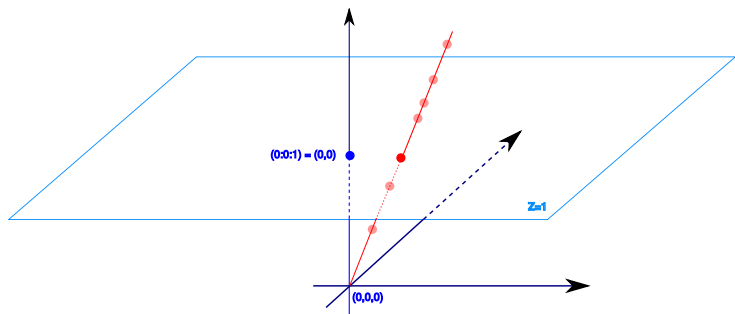
# Computational Geometry is about ... Geometry



## Homogeneous coordinates for points in the plane

- Embed  $\mathbb{R}^2$  at height 1 into  $\mathbb{R}^3$ :  $(x, y) \mapsto (x : y : 1)$

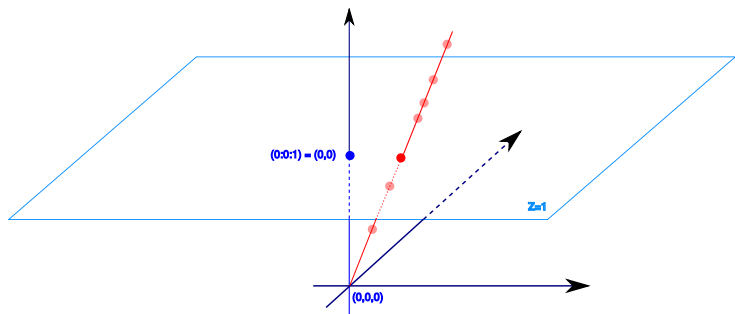
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- ▶ **Embed**  $\mathbb{R}^2$  at height 1 into  $\mathbb{R}^3$ :  $(x, y) \mapsto (x : y : 1)$
- ▶ **Identify** points on a ray through the origin:  
 $(x : y : 1) \sim (\lambda x : \lambda y : \lambda)$ , for any  $\lambda > 0$

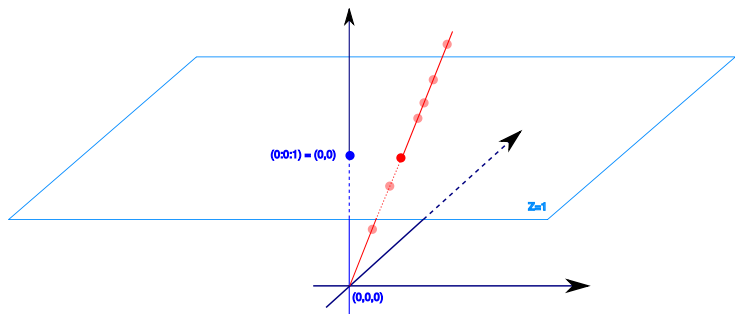
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- ▶ **Subtlety**:  $\lambda > 0$  makes **oriented projective geometry** (we use this)

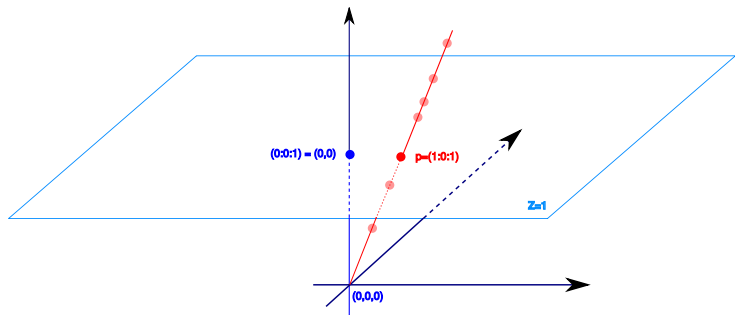
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- ▶ **Identify** points on a ray through the origin:  
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- ▶ **Subtlety**:  $\lambda \neq 0$  makes **projective geometry**

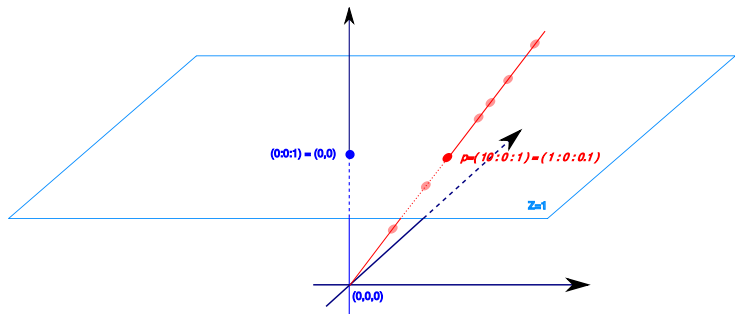
# Computational Geometry is about ... Geometry



What happens if the last coordinate is zero?

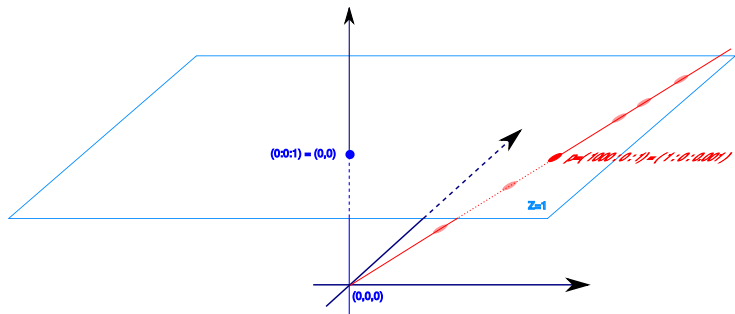


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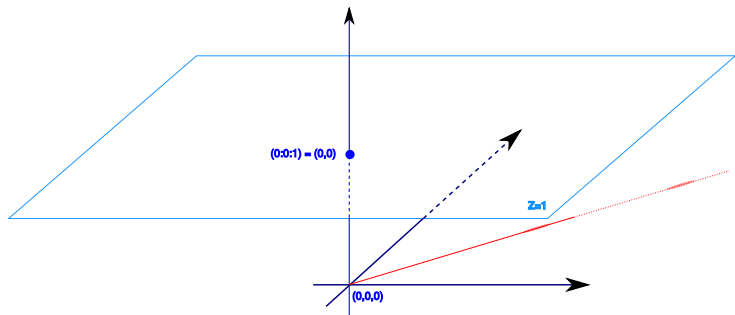
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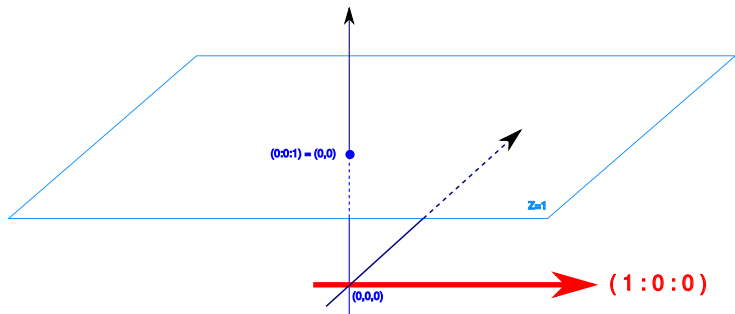
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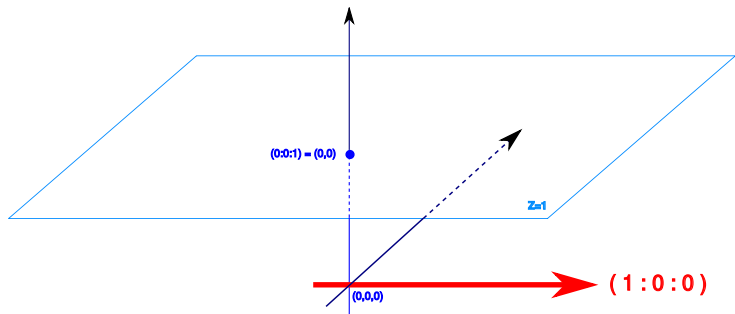
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These vectors correspond to **points at infinity**.

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These vectors correspond to **points at infinity**.  
The only meaningless vector is  $(0, 0, 0)$ .

# Operating with homogeneous coordinates

Homogeneous coordinates for **points**:

$$(x, y) \longleftrightarrow (x : y : 1)$$

Homogeneous coordinates for **lines**:

$$ax + by + c = 0 \longleftrightarrow (a : b : c)$$

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## Incidence relationships

When does  $p = (x : y : 1)$  lie on  $\ell = (a : b : c)$ ?

**Answer:** When  $ax + by + c = \langle (a, b, c), (x, y, 1) \rangle = 0$ .

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**Answer:** When  $ax + by + c = \langle (a, b, c), (x, y, 1) \rangle = 0$ .  $p \perp \ell$



# Operating with homogeneous coordinates: lines

The line  $\ell$  through points  $p_1$  and  $p_2$

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**Example** (The line  $\ell$  through  $(1, 2) = (1 : 2 : 1)$  and  $(3, -4) = (3 : -4 : 1)$ )

$$\ell = (1, 2, 1) \times (3, -4, 1) = (6 : 2 : -10) \sim (3 : 1 : -5).$$

This is correct, because both points satisfy  $3x + y - 5 = 0$ .

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**Example** (The  $x$ -axis)

$$y = 0 \quad \longleftrightarrow \quad 0 \cdot x + 1 \cdot y + 0 = 0 \quad \longleftrightarrow \quad (0 : 1 : 0)$$

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This is correct, because this point lies on both lines.

**Watch out:** Choose the order of the factors in  $p \times q$  so that the last coordinate is **nonnegative**.



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Where do parallel lines intersect?

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What is the line through two points at infinity?

$(x_1 : y_1 : 0) \times (x_2 : y_2 : 0) = (0 : 0 : x_1 y_2 - x_2 y_1) \sim (0 : 0 : 1)$ ,  
the line at infinity.

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the line at infinity.  
(Unless the points coincide (are proportional); then you get  $(0, 0, 0)$ .)



# Computational Geometry is about ... algorithms & coding

Let's intersect lines and join points, first in **homogeneous coordinates**.

```
void intersect_lines(const vec_t& l1, const vec_t& l2, vec_t& p)
{
    cross_product(l1, l2, p);
}
void join_points(const vec_t& p1, const vec_t& p2, vec_t& l)
{
    cross_product(p1, p2, l);
}
void cross_product(const vec_t& l1, const vec_t& l2, vec_t& p)
{
    p[0] =  l1[1]*l2[2] - l1[2]*l2[1];
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- This code is **correct, efficient, and robust**.

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- This code is **correct**, **efficient**, and **robust**.  
It calculates exactly what it should.

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No extraneous copying (&); reuse of code

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No influence of rounding errors

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}
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- This code is **correct**, **efficient**, and **robust**.  
It handles all cases, even degenerate ones.

# Computational Geometry is about ... algorithms & coding

Now let's intersect lines in **Cartesian coordinates**.

A line is now  $y = kx + d$ , stored as a vector  $(k, d)$ .

```
bool intersect_lines(const vec_t& l1, const vec_t& l2, vec_t& p) {  
    if (l1[0]==l2[0]) {  
        if (l1[1]==l2[1]) {  
            return COINCIDENT_LINES;  
        }  
        return PARALLEL_LINES;  
    }  
    p[0] = (l2[1]-l1[1])/(l1[0]-l2[0]);  
    p[1] = l1[0]*p[0] + l1[1];  
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- This code is **somewhat efficient**, **not robust**, and *not even correct*.

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**Again**, no copying; **BUT**: no reuse of code for `join_points`

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- This code is **somewhat efficient**, **not robust**, and *not even correct*.  
It's unstable numerically (`==`, `/`)—say `if (fabs(l1[0]-l2[0]) < EPS)`



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- This code is **somewhat efficient**, **not robust**, and *not even correct*.  
It doesn't handle parallel lines, but that's Euclidean geometry's fault.

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```

- This code is **somewhat efficient**, **not robust**, and **not even correct**. But it **IS the code's fault** that it doesn't handle vertical lines! Need:

```
class line {  
    bool is_vertical;  
    vec_t k_and_d;  
};
```

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        return PARALLEL_LINES;  
    }  
    p[0] = (l2[1]-l1[1])/(l1[0]-l2[0]);  
    p[1] = l1[0]*p[0] + l1[1];  
}
```

- ▶ This code is **somewhat efficient**, **not robust**, and **not even correct**. But it **IS the code's fault** that it doesn't handle vertical lines! Need:
- ▶ It's much harder to get right, because of **more special cases**.
- ▶ It needs an **extra variable**, the boolean return value.