

## Set 2

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### Hoeffding Inequality

1) B. 0.01

See the Hoeffding code. For 100,000 repetitions, the average value of  $v_{min}$  was about 0.0376.

2) D.  $c_1$  and  $c_{rand}$

See the Hoeffding code. For 100,000 repetitions, the average value of  $c_1$  and  $c_{rand}$  were about 0.5. This satisfies the single-bin Hoeffding Inequality because it

### Error and Noise

3) E.  $\lambda\mu + (1 - \lambda)(1 - \mu)$

Function  $h$  approximates  $f$  with error  $\mu$ . But there is a  $1 - \lambda$  chance that  $f$  is wrong. We can determine the probability that  $h$  incorrectly approximates  $y$  with a decision tree.

4)

$$\begin{aligned}P(h(x) \neq y) &= \lambda\mu + (1 - \lambda)(1 - \mu) \\&= \lambda\mu + (1 - \lambda - \mu + \lambda\mu) \\&= 2\lambda\mu - \lambda - \mu + 1 \\&= \mu(2\lambda - 1) - \lambda + 1 \\2\lambda - 1 &= 0 \\2\lambda &= 1 \\\lambda &= \frac{1}{2}\end{aligned}$$

Thus, when  $\lambda = \frac{1}{2}$ ,  $\mu$  is irrelevant to the output of  $P(h(x) \neq y)$ .

## Linear Regression

5) C. 0.01

See the linear regression code. For 10,000 repetitions, the average in-sample error was 0.039185.

6) C. 0.01

See the linear regression code. For 10,000 repetitions, the average out-sample error was 0.0484795.

7) A. 1

See the linear regression code. For 1,000 repetitions, the average numbers of modified PLA iterations required is 5.334

## Nonlinear Transformation

8) D. 0.5

See the non-linear transformation code. For 1,000 repetitions, the average in-sample error for the non-transformed data was 0.51429.

9) A.  $\text{sign}(-1 - 0.05 * x_1 + 0.08 * x_2 + 0.13 * x_1 * x_2 + 1.5 * x_1 ** 2 + 1.5 * x_2 ** 2)$

See the non-linear transformation code. For 1000 test data points, the functions a - e had accuracy rates of 0.952, 0.693, 0.677, 0.614, and 0.547, respectively. Thus, [a] most resembles the hypothesis found.

10) A. 0

See the non-linear transformation code. For 1,000 repetitions, the average out-sample error for the transformed data was 0.033848.