

1 Math

Bayes rule: $P(A|B) = \frac{P(A,B)}{P(B)} = \frac{P(B|A)P(A)}{P(B)}$

Chain rule: $\frac{P(A_n, \dots, A_1)}{P(A_n|A_{n-1}, \dots, A_1) \cdot P(A_{n-1}, \dots, A_1)}$

Joint: $P\left(\bigcap_{k=1}^n A_k\right)$

$\prod_{k=1}^n P\left(A_k \middle| \bigcap_{j=1}^{k-1} A_j\right)$

Posterior: unobserved θ , observed x :
 $p(\theta|x) = \frac{p(x|\theta)p(\theta)}{p(x)}$

Prior: prior belief in dist. of θ : $p(\theta)$
Likelihood: prob of observed given parameters: $p(x|\theta)$

MAP: $h_{MAP} = \operatorname{argmax}_{h \in H} P(h|D) = \operatorname{argmax}_{h \in H} P(D|h)P(h)$

Lagrange: $L(\mathbf{x}, \lambda) = f(\mathbf{x}) + \lambda g(\mathbf{x})$ Set constraint $g(\mathbf{x})$ to zero and add multiplier.

$$\mathbf{xy}^T = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} [x_1 \dots x_n] = \begin{bmatrix} x_1 y_1 & \dots & x_1 y_n \\ \vdots & \ddots & \vdots \\ x_m y_1 & \dots & x_m y_n \end{bmatrix}$$

Matrix-vector product: $\mathbf{Ax} = \begin{bmatrix} a_1^T \mathbf{x} \\ \vdots \\ a_m^T \mathbf{x} \end{bmatrix}$

Matrix mult': $(\mathbf{AB})_{ij} = \sum_{k=1}^m A_{ik} B_{kj}$

$$\mathbf{AB} = \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \dots & a_1^T b_p \\ \vdots & \vdots & \ddots & \vdots \\ a_m^T b_1 & a_m^T b_2 & \dots & a_m^T b_p \end{bmatrix}$$

$$(n \times p)(p \times m) = n \times p$$

2 todo

- Marginals
- Eigendecomposition
- $\sin(x)' = \cos x$
- $\cos(x)' = -\sin x$
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- $(AB)^T = B^T A$
- $\log_b(x^y) = y \log_b(x)$
- Uniform distribution: $P_{\theta_1, \theta_2}(x) = \frac{1}{\theta_2 - \theta_1}$
- $AA^{-1} = A^{-1}A = I$ for square matrices.
- $F'(x) = f'(g(x))g'(x)$
- $(f \cdot g)' = f' \cdot g + f \cdot g'$
- Log properties

- Convexity
- $\|\mathbf{x}\|_d = \sum_i x_i^d$
- Polynomial multiplication
- Matrix transpose and inverse properties
- Gradient vs partial derivative
- $\sigma(x)' = \sigma(x)(1 - \sigma(x))$
- $E\left[\left(y - \hat{f}(x)\right)^2\right] = E\left[\hat{f}(x) - f(x)\right]^2 + E\left[\hat{f}(x)^2\right] - E\left[\hat{f}(x)\right]^2 + \epsilon^2$

3 Regression

3.1 L2 regularization

Weights do not reach zero. Faster.

$$J_w = \frac{1}{2}(\Phi \mathbf{w} - \mathbf{y})^T (\Phi \mathbf{w} - \mathbf{y}) + \frac{\lambda}{2} \mathbf{w}^T \mathbf{w}$$

$$\mathbf{w} = (\Phi^T \Phi + \lambda \mathbf{I})^{-1} \Phi^T \mathbf{y}$$

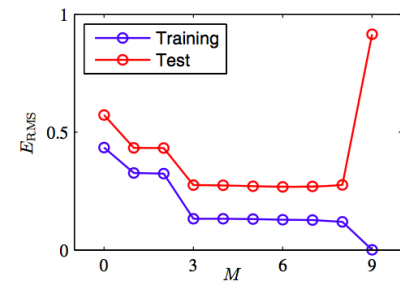
3.2 L1 regularization

Some weights set to zero. More expensive.

3.3 Gradient Descent

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla \log L(\mathbf{w}) \quad \mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla \log J(\mathbf{w})$$

3.4 Bayesian regularization



4 Kernels

$k(\mathbf{x}, \mathbf{z}) = \phi(\mathbf{x}) \cdot \phi(\mathbf{z})$ **Mercer theorem:** $K(\mathbf{x}, \mathbf{z})$ is kernel iff Gram matrix \mathbf{K} symmetric and positive semidefinite: $\mathbf{K}_{ij} = \mathbf{K}_{ji}$ and $\mathbf{z}^T \mathbf{K} \mathbf{z} \geq 0$ $\mathbf{K} = \Phi \Phi^T$ where $\mathbf{K}_{nm} = \phi(\mathbf{x}_n)^T \phi(\mathbf{x}_m) = k(\mathbf{x}_n, \mathbf{x}_m)$ Gram matrix size of input.

- Kernel properties
- Proving kernels

5 SVM

Minimize absolute error. More robust to outliers. Max margin is convex optimization.

$$h_{\mathbf{w}}(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^m \alpha_i y_i (\mathbf{x}_i \mathbf{x}) + \mathbf{w}_0\right)$$

$\alpha_i > 0$ only for support vectors. Soft error SVM: $0 < \zeta \leq 1$ if inside margin. $\zeta > 1$ if misclassified. Total errors: $C \sum_i \zeta_i$. Large C higher variance.