**Reproducibility plan for <paper title>**

Reproducibility levels: as per <https://cgranell.github.io/rrp/assessment.html>

*0 –undocumented; 1 – documented (i.e. recreatable); 2 – available; 3 – available & open (long term, with DOI)*

Data

|  |  |  |
| --- | --- | --- |
| Dataset  (add more rows as needed) | Current reproducibility level and  reasoning why | Planned measures for improvement and  target reproducibility level |
| *E.g., OpenStreetMap Nederland from Geofabrik as base data* | *2 because it is publicly available with a clear license and URL* | *None planned, because 2 is considered sufficient* |
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Methods

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| --- | --- | --- |
| Method  (add more rows as needed) | Current reproducibility level and  reasoning why | Planned measures for improvement and  target reproducibility level |
| *E.g., K-means clustering for earthquake epicenters* | *0 because parameters (e.g. K) and software environment not yet defined* | *Publish Python code for analysis on Github, target level 2 (no DOI, but open source, publicly available)* |
|  |  |  |
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Results

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| --- | --- | --- |
| Results  (add more rows as needed) | Current reproducibility level and  reasoning why | Planned measures for improvement and  target reproducibility level |
| *E.g., choropleth maps showing priority areas for intervention* | *0 because nothing is yet defined* | *Publish interactive web map including underlying data set, target level 2 (no DOI, but users can investigate outcomes fully, publicly available)* |
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| Computational environment | Yes/no | Planned measures for improvement |
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