

Lecture 3

Data Link Layer

(Computer Communication Networks)

CS 35201
Spring 2020

Acronyms

Data Link Layer
Design Issues

How can reliability be
provided?

Framing

Error Detection

Error Correction

Clock-Based Framing:
SONET

Reliable Transmission

Automatic Repeat
Request (ARQ)

What Could Go Wrong

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The contents of this lecture have been composed from various resources including those listed at the reference section.

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§3.0.0 Glossaries

ARQ	Automatic Repeat Request 41
HDLC	High-Level Data Link Control 13
IP	Internet Protocol 7
LAP	Link Access Procedure 14
LAPB	Link Access Procedure - Balanced 14
LAPD	Link Access Procedure for the D channel 14
LLC	Logical Link Control 14
PPP	Point-to-Point Protocol 12
TCP	Transport Control Protocol 7, 8
TO	Time Out 54
UDP	User Data Protocol 7

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§3.1.0 Data Link Layer Design Issues

1 Network layer services

2 Framing

3 Error control

4 Flow control

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Possible Services Offered

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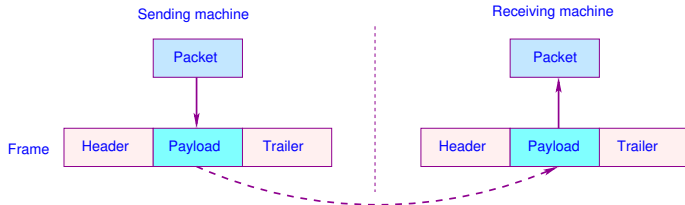
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What Could Go Wrong

§3.1.1 Packets vs. Frames



■ Packets

- ▶ Layer 3 data units
- ▶ Mostly variable size $\Rightarrow 20 \leq \text{IP} \leq 65,535 \text{ bytes} = 64\text{k bytes}$
- ▶ Carry routing information

■ Frames

- ▶ Layer 2 data units
- ▶ Fix size \Rightarrow Ethernet 1500 bytes, WiFi 2346 bytes
- ▶ No or minimal routing information \Rightarrow forwarding

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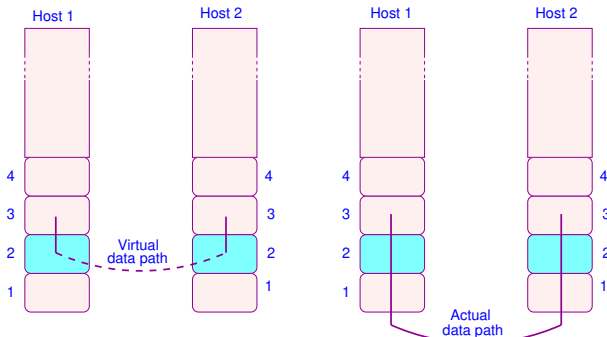
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§3.1.2 Virtual vs. Actual Connections



- Layer 3 doesn't know how layer 2 delivers its packet
- Layers 2 & 4 are designed to provide reliable connections
 - ▶ Connection-oriented
 - ▶ Acknowledgements
 - ▶ Request-Reply
- Layer 3 is designed to provide **best effort** delivery
 - ▶ Connection-less-oriented
 - ▶ Unreliable

How?

How?

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§3.1.3 Possible Services Offered

	Services		Examples
Connection–Oriented	Reliable	Message stream	Sequence of pages
		Byte stream	Remote login
	Unreliable	Datagram /Pulse	Digitized voice
Connection–less–Oriented	Reliable	Acked datagram	Sequence of pages
		Request–Reply	Registered mail
	Unreliable	Datagram	Database query

- 1 Unacknowledged connectionless service
 - ▶ User Data Protocol (UDP)
- 2 Acknowledged connectionless service
 - ▶ Ethernet frames, Internet Protocol (IP)
- 3 Acknowledged connection-oriented service
 - ▶ Transport Control Protocol (TCP)

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§3.2.0 How can reliability be provided?

- 1 Acknowledgment,
- 2 Partial acknowledgment (cumulative acknowledgment) \Rightarrow TCP
- 3 Automatic-repeat and request (ARQ)
- 4 Byte-stream
- 5 Message sequencing

\Rightarrow *Reliability is a relative term*

What is the Problem?

When two devices exchange data:

- Data is transmitted one bit at a time (typically)
- Transmitting and receiving data rates must be the same
- The transmitter/receiver must recognize the start/end of each bit
 - ▶ To make sure sampling can be done correctly
 - ▶ Also, a drift in time results errors

Two Approaches: Framing Methods

- 1 Asynchronous data transmission
- 2 Synchronous data transmission

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§3.2.1 Transmission Methods

1 Asynchronous data transmission

- ▶ Timing problem is avoided by not sending long streams of bits
- ▶ Data is transmitted one character at a time
 - Byte (character-oriented) protocols
- ▶ Synchronization bits are required
 - Bits are synchronized, data is not
- ▶ Good for low-rate channels



2 Synchronous data transmission

- ▶ Bit-oriented protocols
- ▶ Transmitter and receiver clocks must be synchronized
 - Using separate timing circuit \Rightarrow out-of-band signaling
 - Manchester coding
- ▶ There is a minimum frame length



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§3.3.0 Framing

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What is a Frame?

- A basic transmission unit
- Typically implemented by network adaptor
- Adaptor fetches/deposits frames out/in to memory
- The receiver must determine first and last bit of the frame

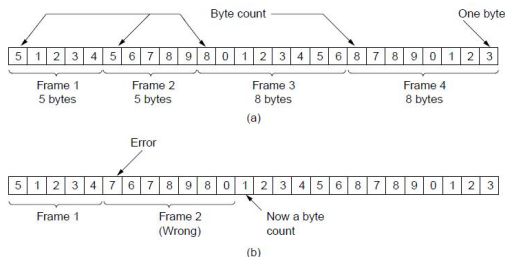
Basic Framing Techniques

- 1 Byte count
- 2 Flag bytes with byte stuffing
- 3 Flag bits with bit stuffing
- 4 Physical layer coding violations
- 5 Clock-based Framing ⇒ SONET

§3.3.1 Framing Methods I

1 Byte Count Framing ⇒ Byte-Oriented Protocols

- ▶ Each frame starts with a **byte** that contains the frame size (in bytes)
- ▶ What would happen when an error occurs in a byte count?
 - Synchronization is lost
 - Correct start/end of the frames will be lost
 - Even if the **checksum** detects such an error, it cannot correct it
- ▶ A byte stream. (a) Without errors. (b) With one error



- ▶ Example: Digital Data Communication Message Protocol (DDCMP)

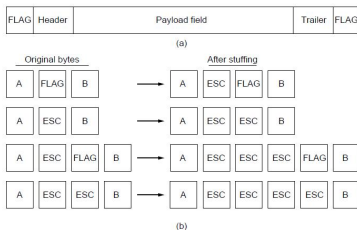


§3.3.1 Framing Methods II

2 Framing With Flags

- ▶ A frame delimited by flag bytes
- ▶ What would happen if the FLAG appears in the text?
 - Use an escape character
 - Four examples of byte sequences before and after byte stuffing.

How?



- ▶ Example: Point-to-Point Protocol (PPP)



- ▶ Example: BISYNC(binary sync. comm.) (IBM)



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§3.3.1 Framing Methods III

3 Bit-oriented protocols

- ▶ High-Level Data Link Control (HDLC) (OSI)
 - Synchronous Data Link Control (SDLC) - IBM



- ▶ Delineate frame with a special bit-sequence: 01111110

Bit Stuffing Protocol

- Sender: any time five consecutive 1s have been transmitted from the body of the message, insert a 0.
- Receiver: should five consecutive 1s arrive, look at next bit(s):
 - ▶ if next bit is a 0: remove it ⇒ un-stuff it
 - ▶ if next bits are 10: end-of-frame marker
 - ▶ if next bits are 11: error

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§3.3.1 Framing Methods IV

Example 3.1 (Bit Stuffing)

```

(a) 0 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 1 0
(b) 0 1 1 0 1 1 1 1 1 0 1 1 1 1 1 0 1 1 1 1 1 0 1 0 0 1 0
      ^         ^         ^
      |         |         |
      Stuffed bits
(c) 0 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 1 0
  
```

(a) The original data. (b) The data as they appear on the line
 (c) The data stored in the receiver's memory after de-stuffing

Other Bit-Oriented Protocols

- Link Access Procedure (LAP) ⇒ CCITT
- Link Access Procedure - Balanced (LAPB) ⇒ ITU-T (for X.25)
- Link Access Procedure for the D channel (LAPD) ⇒ ITU-T (for ISDN)
- Hewlett Packard Data Link Control (HDLC: HP)
- Advanced Data Communications Control Procedures (ADCCP) - ANSI
- Logical Link Control (LLC) ⇒ IEEE 802.2

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§3.4.0 Error Detection

- Reliability requires error detection and possibly correction
 - ▶ We cannot correct all the time
 - ▶ Too many bit errors may not be correctable
- Many techniques
 - ▶ From dictionary search to in-line (real-time) detection and possibly correction
 - ▶ Not all good equally for different noise (error) rate
- In general we extra bits to the data bits for the purpose of:
 - ▶ Detecting errors
 - ▶ Correcting errors if possible
- We start with simple techniques, and we cover more robust techniques
 - ▶ Used by NASA for various missions

Major Error Detection Techniques

- 1 Parity
- 2 Checksum
- 3 Cyclic Redundancy Checks.

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§3.4.1 Parity Bit

■ Detecting a single bit error \Rightarrow parity bit

- ▶ Memory read/write (R/W) \Rightarrow 8 data bits + 1 parity bit

0	1	2	3	4	5	6	7
1	0	1	1	0	1	1	
1	0	1	1	0	1	1	0
1	0	1	1	0	1	1	1

odd parity, odd number of 1's

even parity, even number of 1's

- ▶ Even number of bit errors goes undetected \Downarrow

- Keeps the parity bit unchanged

■ In general, we decode m bits to $n = m + r$ bits \Rightarrow **codewords**

- ▶ r bits overhead \Rightarrow next

■ Odd/even parity is weak \Rightarrow 50% of errors cannot be detected

Why?

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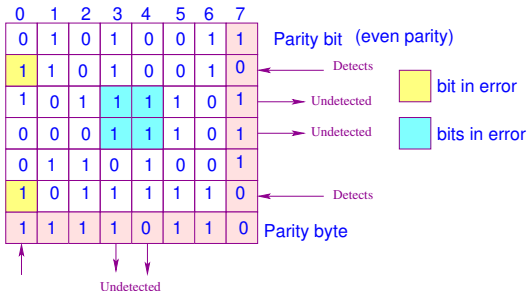
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What Could Go Wrong

§3.4.2 Two-Dimensional Parity Check

- Multiple bytes are sent in matrix form \Rightarrow blocks
- Each bit of data is checked by two parity bits
 - Row and column
- What happens if the parity itself received in error?
- 2D parity detects better but still misses a lot of errors undetected



Homework 3.1

Show that (by example) 2D parity catches 1, 2, and 3-bit errors, and most 4-bit errors

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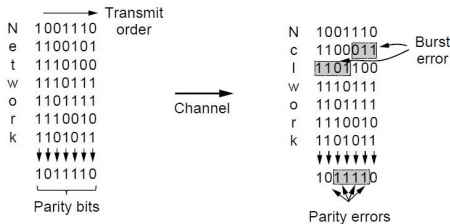
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What Could Go Wrong

§3.4.3 Interleaving Parity Bits

- Errors often occur in bursts as a result of:
 - ▶ Transit-time noise \Rightarrow unpredictable
 - ▶ Random statistical fluctuations of the electric current \Rightarrow shot noise \Rightarrow unpredictable
 - ▶ \vdots
- Interleaving parity bit with data bits allows spread the bits
 - ▶ Better detection, and also help correction
- Data is horizontal, parity is vertical \Rightarrow scrambles the bits



- Used in fiber optics \Rightarrow minimal computations

§3.4.4 Checksum

- Simple, but weak
- The sum of bytes computed as parity bits \Rightarrow 1's complement

Data	Checksum	Data	Checksum
0001	1	0011	3
0010	2	0000	0
0011	3	0001	1
0001	1	0011	3
Total	7	Total	7

- Does not detect all common errors
 \Rightarrow weak error detection (used in IP)
- Used in networks where speed is more important than errors
 - Other layers take care of error correction/detection

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§3.4.5 Cyclic Redundancy Check (CRC) I

- Given a m -bit message, generate an $m + r$ -bit frame such that $m + r$ bit frame evenly divisible by some predefined number



- How does it work?

- Let $M(x)$ be the message 1101011111

$$M(x) = x^9 + x^8 + x^6 + x^4 + x^3 + x^2 + x + 1$$

- Choose $G(x)$ with degree r

$$G(x) = x^4 + x + 1 = 10011 = 19$$

- Append r zero bits to end of the frame $\Rightarrow x^r M(x)$

$$x^r M(x) = x^{13} + x^{12} + x^{10} + x^8 + x^7 + x^6 + x^5 + x^4 = 1101011111\ 0000$$

- Let $E(x)$ be the remainder of $x^r M(x) / G(x)$

$$E(x) = x = 10$$

- Transmit $T(x) = x^r M(x) - E(x)$

$$T(x) = x^{13} + x^{12} + x^{10} + x^8 + x^7 + x^6 + x^5 + x^4 + x = 1101011111\ 0010$$

- Recipient divides $T(x)$ by $G(x)$; with remainder $E(x)$

if $E(x) = 0 \Rightarrow$ no error

if $E(x) \neq 0 \Rightarrow$ error

Why?

Why?



Just detection, no correction

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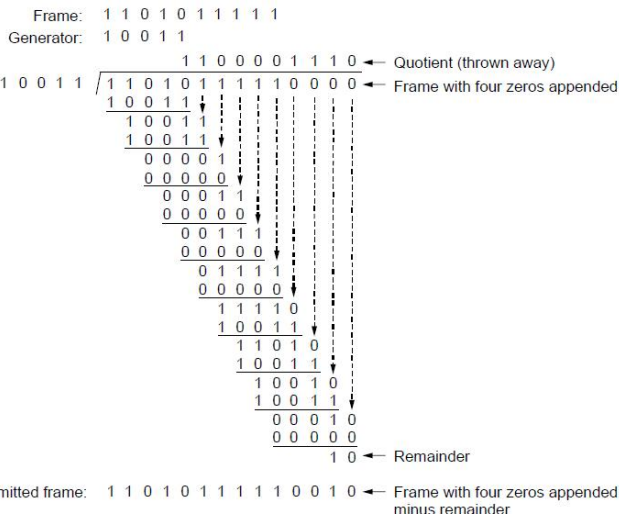
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§3.4.5 Cyclic Redundancy Check (CRC) II



⇒ All done in Binary, Hardware, with Shift Registers + Adder

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§3.4.5 Cyclic Redundancy Check (CRC) III

■ CRC codes can detect the following

- ▶ All error bursts of length $m - r$ or less
- ▶ All errors with an odd number of errors if generator $G(x)$ has an even number of nonzero coefficient

■ Common CRC polynomials

CRC	Generator $g(x)$
CRC-8	$x^8 + x^2 + x^1 + 1$
CRC-10	$x^{10} + x^9 + x^5 + x^4 + x^1 + 1$
CRC-12	$x^{12} + x^{11} + x^3 + x^2 + 1$
CRC-16	$x^{16} + x^{15} + x^2 + 1$
CRC-CCITT	$x^{16} + x^{12} + x^5 + 1$
CRC-32	$x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$

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§3.5.0 Error Correction

Major Techniques

- 1 Hamming codes
- 2 Binary convolutional codes
- 3 Reed-Solomon codes
- 4 Low-Density Parity Check codes

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§3.5.1 Hamming Code I

Definition 3.1 (Hamming Distance)

Given two codewords x and y ,

$$d(x, y) = \text{number of places that } x \text{ and } y \text{ differ} = \# \text{ of 1's in } x \oplus y$$

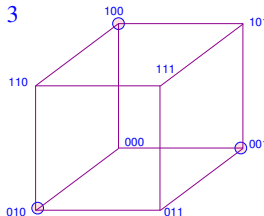
Example 3.2

$$d(100, 101) = 1 \quad d(100, 111) = 2 \quad d(100, 011) = 3$$

$$d(101, 010) = 101 \oplus 010 = 111 \equiv 3$$

$d \Rightarrow$ distance in number of hops

$d \Rightarrow$ shows how far codewords are apart



■ We like codewords that are far apart \Rightarrow how many can we have?

■ The higher the distance, the better we can detect errors

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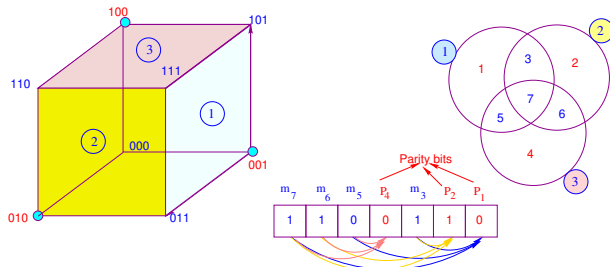
§3.5.1 Hamming Code II

Theorem 3.1 (Minimum Distance)

To detect ℓ -bit errors, $d_{min} \geq \ell + 1$.

Example 3.3 (Hamming Code, H(7,4) $n = 7$, $r = 3$, $m = 4$)

■ 7-bit codeword, 3-bit error control



■ Counting # of 1's in each circle (dimension)

- ▶ $P_1 = m_3 \oplus m_5 \oplus m_7 = 2 \bmod 2 = 0 \Rightarrow$ positions with 1st bit = 1
- ▶ $P_2 = m_3 \oplus m_6 \oplus m_7 = 3 \bmod 2 = 1 \Rightarrow$ positions with 2nd bit = 1
- ▶ $P_4 = m_5 \oplus m_6 \oplus m_7 = 2 \bmod 2 = 0 \Rightarrow$ positions with 3rd bit = 1

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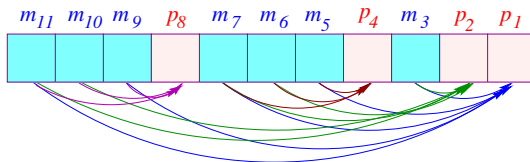
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§3.5.1 Hamming Code III

General Algorithm of Hamming Code

- 1 Write the bit positions in binary; 001, 010, 011, etc.
- 2 Parity bits are power of 2 positions; 1, 2, 4, 8, etc.
- 3 All other bits are data bits
- 4 Each data bit is included in a unique set of parity bits
 - ① Parity bit 1 covers bits positions with 1st bit = 1, (1, 3, 5, 7, 9, ...)
 - ② Parity bit 2 covers bits positions with 2nd bit = 1, (2, 3, 6, 7, 10 ...)
 - ③ Parity bit 4 covers bits positions with 3rd bit = 1, (4-7, 12-15, 20-23, ...)
 - ④ Parity bit 8 covers bits positions with 4th bit = 1, (8-15, 24-31, 40-47, ...)
 - ⑤ In general each parity bit covers all bits where the bitwise AND of the parity position and the bit position is non-zero
- 5 Set a parity bit to 0 if the total number of 1's in the positions it checks is even
 - otherwise, 0



§3.5.1 Hamming Code IV

Example 3.4 (Hamming Code, H(7,4) $n = 7$, $r = 3$, $m = 4$)

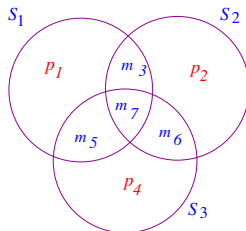
■ Let the codeword be $m_7 m_6 m_5 p_4 m_3 p_2 p_1$

■ Parity check equations:

$$S_1 = p_1 \oplus m_3 \oplus m_5 \oplus m_7 = 0$$

$$S_2 = m_3 \oplus p_2 \oplus m_6 \oplus m_7 = 0$$

$$S_3 = p_4 \oplus m_5 \oplus m_6 \oplus m_7 = 0$$



➡ *even parity in each circle*

➡ *S_1, S_2, S_3 is called the syndrome*

■ There is an even number of 1's in each circle \Rightarrow even parity

■ Note:

► If $A \oplus B = C$, then $A = B \oplus C$

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§3.5.1 Hamming Code V

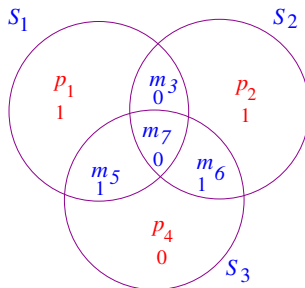
Example 3.5 (Hamming Code: Encoding)

■ Let the message digits be $m_7 m_6 m_5 m_3 = 0 1 1 0$

$$p_1 = m_3 \oplus m_5 \oplus m_7 = 1$$

$$p_2 = m_3 \oplus m_6 \oplus m_7 = 1$$

$$p_4 = m_5 \oplus m_6 \oplus m_7 = 0$$



■ The codeword = $m_7 m_6 m_5 p_4 m_3 p_2 p_1 = 0 1 1 0 0 1 1$

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Hamming Code

Convolutional Coding

Reed Solomon (RS) Codes

Clock-Based Framing: SONET

Reliable Transmission

Automatic Repeat Request (ARQ)

What Could Go Wrong

§3.5.1 Hamming Code VI

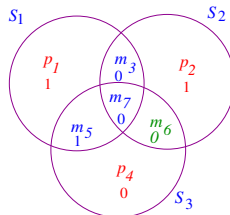
Example 3.6 (Hamming Code: Decoding)

■ Transmitted message:

$m_7 m_6 m_5 p_4 m_3 p_2 p_1 = 0 \ 1 \ 1 \ 0 \ 0 \ 1 \ 1$

■ Received message with one bit error:

$m_7 m_6 m_5 p_4 m_3 p_2 p_1 = 0 \ \hat{0} \ 1 \ 0 \ 0 \ 1 \ 1$



■ By counting # of 1's in each circle, we find

- ▶ There is no error in circle 1 $\Rightarrow S_1 = p_1 \oplus m_3 \oplus m_5 \oplus m_7 = 0$
- ▶ There is an error in circle 2 $\Rightarrow S_2 = m_3 \oplus p_2 \oplus m_6 \oplus m_7 = 1$
- ▶ There is an error in circle 3 $\Rightarrow S_3 = p_4 \oplus m_5 \oplus m_6 \oplus m_7 = 1$
- ▶ Therefore, the error is in the intersection of circle S_2 and S_3
 - $S_3 S_2 S_1 = 110 \Rightarrow m_6 = 1$ must be reverted to 1

■ Note: If the bit error affects

- ▶ two circles \Rightarrow data bit
- ▶ one circles \Rightarrow parity bit

§3.5.1 Hamming Code VII

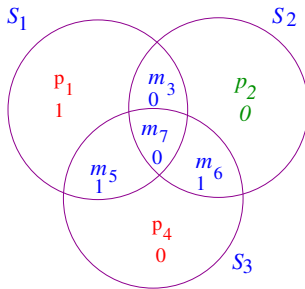
Example 3.7 (Hamming Code: Decoding)

- This time a **parity bit** is in error
- Transmitted message:
 $m_7 m_6 m_5 p_4 m_3 p_2 p_1 = 0\ 1\ 1\ 0\ 0\ 1\ 1$
- Received message with one bit error:

$$m_7 m_6 m_5 p_4 m_3 p_2 p_1 = 0\ 1\ 1\ 0\ 0\ \hat{0}\ 1$$

- By counting 1's in each circle we find

- ▶ There is no error in circle 1 $\Rightarrow S_1 = p_1 \oplus m_3 \oplus m_5 \oplus m_7 = 0$
- ▶ There is an error in circle 2 $\Rightarrow S_2 = m_3 \oplus \hat{p}_2 \oplus m_6 \oplus m_7 = 1$
- ▶ There is no error in circle 3 $\Rightarrow S_3 = p_1 \oplus m_3 \oplus m_5 \oplus m_7 = 0$
- ▶ Therefore, the error is S_2
 - $S_3 S_2 S_1 = 010 \Rightarrow$ second bit \hat{p}_2 must be reverted



§3.5.1 Hamming Code VIII

■ Similarly, $H(11, 7)$, $n = 11$, $r = 4$, $m = 7$

- ▶ $p_1 = m_3 \oplus m_5 \oplus m_7 \oplus m_9 \oplus m_{11}$
- ▶ $p_2 = m_3 \oplus m_6 \oplus m_7 \oplus m_{10} \oplus m_{11}$
- ▶ $p_4 = m_5 \oplus m_6 \oplus m_7$
- ▶ $p_8 = m_9 \oplus m_{10} \oplus m_{11}$

⇒ 1st bit = 1

⇒ 2nd bit = 1

⇒ 3rd bit = 1

⇒ 4th bit = 1

■ In general

- ▶ Block length: $2^r - 1$
- ▶ Message length: $2^r - r - 1$
- ▶ Distance: 3
- ▶ Notation: $H(m, m - r)$
- ▶ Rate (efficiency): $1 - \frac{1}{2^r - 1}$

The Magic

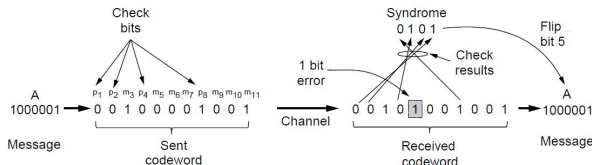
Any two different code words differ in at least 3 places in $H(11, 7)$

1100011	1101000	1110100	1111111	1000101	1001110	1010010	1011001
0100110	0101101	0110001	0111010	0000000	0001011	0010111	0011100

- Why these specific bits? ⇒ maximize code distance
- The knowledge of Hamming distance is used to:
 - ▶ Determine the capacity of a code ⇒ how many bits for data and parity
 - ▶ Detect and correct errors

§3.5.1 Hamming Code IX

Example 3.8 (Hamming Code, H(11,7) $n = 11$, $r = 4$, $m = 7$)



■ m_5 is the only bit that can cause the error

- ▶ $S_1 = p_1 \oplus m_3 \oplus m_5 \oplus m_7 \oplus m_9 \oplus m_{11} = 1$
- ▶ $S_2 = p_2 \oplus m_3 \oplus m_6 \oplus m_7 \oplus m_{10} \oplus m_{11} = 0$
- ▶ $S_3 = p_4 \oplus m_5 \oplus m_6 \oplus m_7 = 1$
- ▶ $S_4 = p_8 \oplus m_9 \oplus m_{10} \oplus m_{11} = 0$

■ $S_8 S_4 S_2 S_1 = 0101 \Rightarrow$ 5th bit, m_5 must be reverted

Why?

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§3.5.1 Hamming Code X

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What Could Go Wrong

Theorem 3.2

The number of errors that can be corrected is

$$\frac{d_{\min} - 1}{2}$$

■ (4,7) Hamming Code **detects** all 1-bit and 2-bit errors

Why?

■ (4,7) Hamming Code **corrects** all 1-bit errors

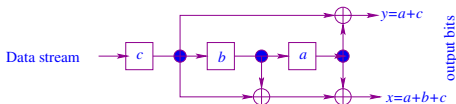
Why?

§3.5.2 Convolutional Coding I

- Generates redundant bits continuously
- More powerful than block codes
 - ▶ NASA Voyager 1977 and 802.11
 - ▶ Provides good performance at low cost

k bits \longrightarrow (n, k, L) \longrightarrow n bits, L lines

- (2,1,3) convolutional code



- Encodes information stream rather than information blocks
- Certain information bits affect the encoding on next information bits
- Easily implemented using shift register
 - ▶ Input processes k bits at a time
 - ▶ Output produces n bits for every k input bits
 - ▶ k and n are very small
 - ▶ L (constraint) factor is the number of shifts over which an input bit can influence the encoder output
 - ▶ In general, the code rate $r = k/n$, $1/2$ in this example

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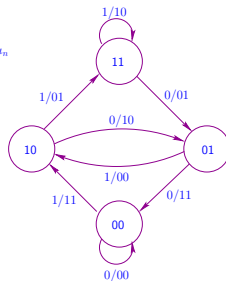
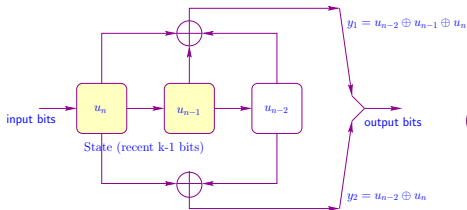
Reliable Transmission

Automatic Repeat
Request (ARQ)

What Could Go Wrong

§3.5.2 Convolutional Coding II

■ Encoding



Input	Initial State	Final State	Output Codeword
0	00	00	00
1	00	10	11
0	01	00	11
1	01	10	00
0	10	01	10
1	10	11	01
0	11	01	01
1	11	11	10

■ Decoding

- Uses maximum likelihood for decoding (Tree of Trellis)
- Viterbi algorithm is the most common

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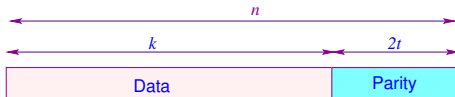
What Could Go Wrong



§3.5.3 Reed Solomon (RS) Codes I

- Block-based error **correcting** codes with a wide range of applications

- ▶ Storage devices (including tape, Compact Disk, DVD, blur-ray, DSL, WiMax, RAID, bar-codes, etc)
- ▶ Wireless or mobile communications
 - Cellular telephones, microwave links, etc.
- ▶ Satellite communications
- ▶ Digital television, CD, DVD, RF, barcodes
- ▶ High-speed modems such as ADSL, xDSL, etc.



- A popular Reed-Solomon code is RS(255,223) with 255 code word bytes, of which 223 bytes are data and 32 bytes are parity

- ▶ $n = 2^s - 1 = 255 \Rightarrow s = 8$
- ▶ $k = 223$
- ▶ $2t = 32, t = 16$

- The decoder can correct any **16 symbol** errors in the code word

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What Could Go Wrong

§3.5.3 Reed Solomon (RS) Codes II

- Errors in up to 16 bytes anywhere in the codeword can be automatically corrected \Rightarrow very strong

How Does it Work? (Details optional)

- RS codeword is generated using a **special** polynomial (generator)

$$g(x) = (x - a^i)(x - a^{i+1})(x - a^{i+2}) \cdots (x - a^{i+2t}) \quad (1)$$

- The codeword $c(x)$ is constructed using $g(x)$ and the information block $i(x) \Rightarrow$ shift the bits to the left

$$c(x) = g(x) \cdot i(x) \quad (2)$$

- The $2t$ parity symbols in a systematic Reed-Solomon codeword are given by

$$p(x) = i(x) \cdot x^{n-k} \mod g(x) \quad (3)$$

§3.5.3 Reed Solomon (RS) Codes III

- The received codeword $r(x)$ is the original (transmitted) codeword $c(x)$ plus errors

$$r(x) = q(x) \cdot g(x) + e(x) \quad q(x)g(x) = c(x) \quad (4)$$

- Finding the position of involves solving simultaneous equations with t unknowns
 - Several fast algorithms are available

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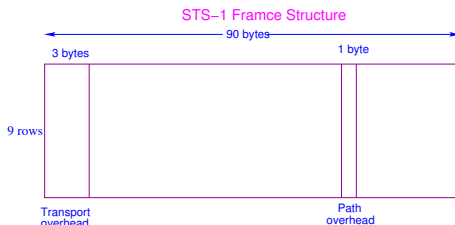
Reliable Transmission

Automatic Repeat
Request (ARQ)

What Could Go Wrong

§3.6.0 Clock-Based Framing: SONET I

- SONET: Synchronous Optical Network
- ITU standard for transmission over fiber
- STS-1 (51.84 Mbps)
- Byte-interleaved multiplexing
- Each frame is $125\mu\text{s}$ long.



- Each frame is $125\mu\text{s}$ long $\Rightarrow 8000/\text{s}$
- Frame length = $90 \times 9 \times 8 = 6,400$ bits long

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What Could Go Wrong

§3.7.0 Reliable Transmission

- Delivers frames
 - ▶ Without errors and
 - ▶ In proper order to the network layer
- How to recover from 'from corrupt frames (errors)?
 - 1 Error Correction \Rightarrow also called Forward Error Correction (FEC)
 - 2 Acknowledgments and Timeouts \Rightarrow also called Automatic Repeat Request (ARQ)
- How to keep the proper order of delivery?
 - ▶ The sender should not flood the receiver,
 - ▶ But maximizes the throughput
- The sender is throttled until the receiver grants permission

How?

How?

Note: Refer to the book for the codes



Flow Control \Rightarrow ARQ

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Clock-Based Framing:
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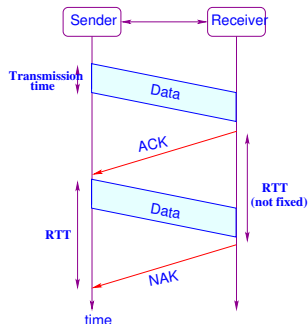
Automatic Repeat
Request (ARQ)

What Could Go Wrong

§3.8.0 Automatic Repeat Request (ARQ)

■ Performed with the combination of:

- 1 Error detection
- 2 Acknowledgment
- 3 Retransmission after timeout
- 4 Negative acknowledgment



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Clock-Based Framing: SONET

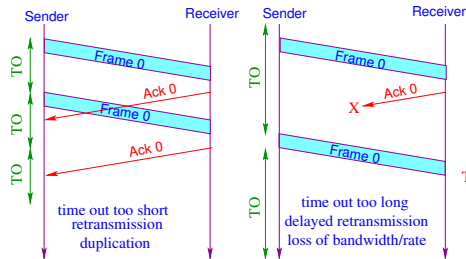
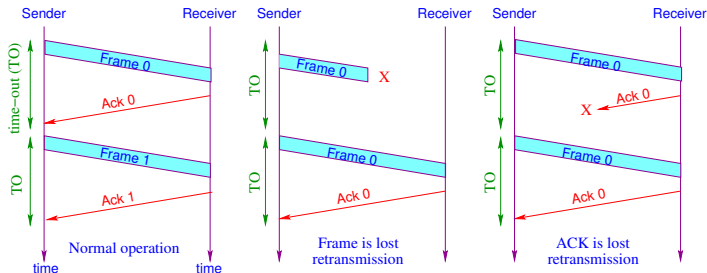
Reliable Transmission

Automatic Repeat Request (ARQ)

What Could Go Wrong

§3.9.0 What Could Go Wrong

Data Link Layer



Flow is controlled partly
by the length of time out

How to accurately
set the time out?

$TO > \text{Access delay} + \text{Transmission delay} +$
 $\text{Propagation delay} + \text{queuing delay}$
(non-deterministic)

TO is vulnerable, How?

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Go-Back-N Protocol

Selective-Reject Protocol

Sequence Number Space

§3.9.1 Frames in Error

■ Possible errors

▶ Damaged frames

- Frames received with error
- Frames lost
- Last frame lost

▶ Damaged ACK

- One ACK lost, next one makes it
- All ACKs lost

▶ Damaged NACK

■ How to handle frames in errors?

1 Stop-and-Wait Protocol

2 Go-Back-N Protocol

3 Selective Reject Protocol

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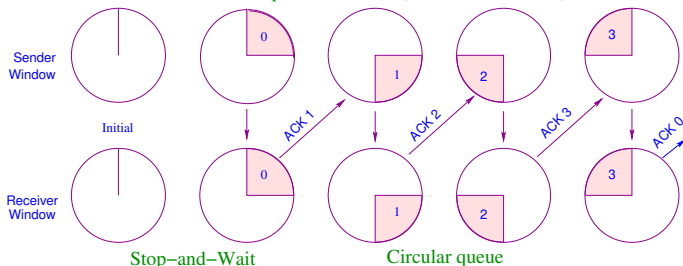
Sequence Number Space

§3.9.2 Stop-and-Wait Protocol I

■ The sender/receiver each has two windows:

- ▶ Sending window
- ▶ Receiving window

2-bit Window = 4 sequence numbers (0, 1, 2, 3, 0, 1, 2, ...)



■ It is a duplex mechanism

- ▶ One can send/receive at the same time
 - Piggybacking

■ Save sequence numbers \Rightarrow reuse once it is released

How?

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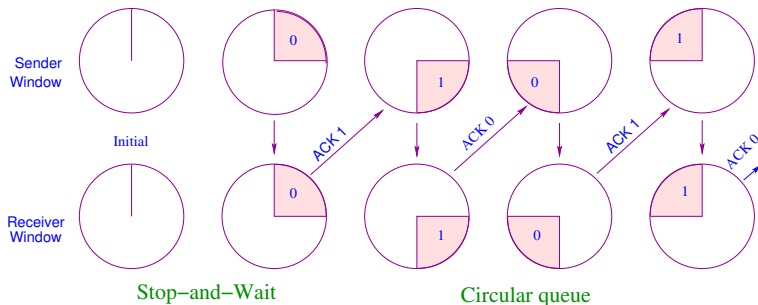
Go-Back-N Protocol

Selective-Repeat Protocol

Sequence Number Space

§3.9.2 Stop-and-Wait Protocol II

1-bit Window = 2 sequence numbers (0, 1, 0, 1, ...)



■ We always ACK the frame to be received

- Receiver knows which frame has been received
- Receiver knows which frame the source is waiting for

Why?

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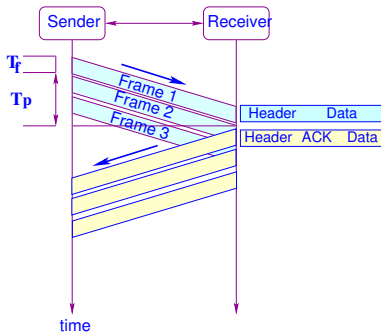
Go-Back-N Protocol

Selective-Repeat Protocol

Sequence Number Space

§3.9.2 Stop-and-Wait Protocol III

Piggybacking



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Sequence Number Space

§3.9.3 How Good Stop-and-Wait Is?

Example 3.9 (Utilization (or Efficiency) Problem)

- Assume 1.5 Mbps link and 45 ms RTT \Rightarrow Pipe = 67.5 Kb (8KB)
- Frame size: 1 KB
- SW uses about 1/8 of the bandwidth
- How do we fix this
 - Send up to 8 frames before having to wait for an ACK

Homework 3.2 (Efficiency vs. Utilization)

Describe **efficiency** and **utilization** in a communication channel.
Under what condition they are equal?

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§3.9.4 Performance of SW Protocol I

- T_f : frame time and T_p : propagation delay

$$\alpha = \frac{T_p}{T_f} = \frac{\frac{\text{Distance}}{\text{Speed of signal}}}{\frac{\text{Frame size}}{\text{Bit rate}}} = \frac{\text{Distance} \times \text{Bit rate}}{\text{Frame size} \times \text{Speed of signal}} \quad (5)$$

$$\text{SW Utilization} = E = \frac{1}{1 + 2\alpha} \quad (6)$$

Homework 3.3 (SW Efficiency)

Prove that the efficiency of Stop-and-Wait protocol in Equation (6).

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§3.9.4 Performance of SW Protocol II

Example 3.10

Long propagation delay

- Satellite link $\Rightarrow T_p = 278$ ms
- Suppose the frame size is 4k bits = 4096 bits
- Suppose data rate is DS0, 56 kbps $\Rightarrow T_f = 4096/56000 = 0.073$ sec.

$$\alpha = \frac{T_p}{T_f} = \frac{0.278}{0.073} = 3.8$$

3.8 frames fits into the pipe on one direction.

$$U = \frac{1}{1 + 2\alpha} = \frac{1}{1 + 7.6} = 0.12 \quad U = 12\%$$

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§3.9.4 Performance of SW Protocol III

Example 3.11

Short propagation delay \Rightarrow Ethernet

■ $T_p = 10 \mu\text{s} = 10^{-5} \text{ sec}$

■ Frame = 4Kb = 4096 bits

■ Data rate = 10 Mbps $\Rightarrow T_f = 4096/10^7 = .0004096 \text{ sec}$

$$\alpha = \frac{T_p}{T_f} = \frac{10^{-5}}{.0004096} = 0.0244$$

$$U = \frac{1}{1 + 2\alpha} = \frac{1}{1 + 0.0488} = 0.95 \quad U = 95\%$$

How to Solve the Efficiency Problem

\Rightarrow *Keep the pipe/channel full to get better efficiency*

\Rightarrow *send more than one frame at a time*

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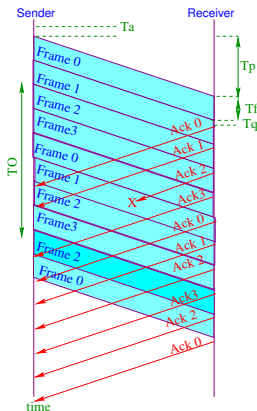
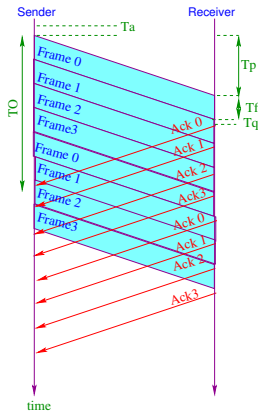
Go-Back-N Protocol

Selective-Reject Protocol

Sequence Number Space

§3.9.5 Sliding Window I

- Allow sender to transmit multiple frames before receiving an acknowledgment
 - keeping the pipe full



- The receiver has two copies of frame 2
- The 2nd incarnation discarded if both both have the same sequence numbers

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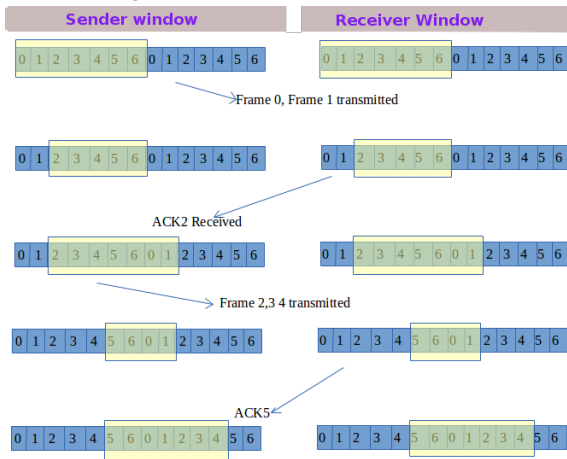
Sliding Window

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§3.9.5 Sliding Window II



wikistack.com

■ Window size = 7

- Potentially can send 7 frames if it does not overwhelm the receive

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§3.9.5 Sliding Window III

- Note that speed of light in:
 - ▶ vacuum is 300×10^6 m/s
 - ▶ fiber is 200×10^6 m/s
- The sender should not send frames at a higher rate than what the receiver can receive
 - ▶ Transmission rate = $\min\{\text{sender rate, receiver rate}\}$
 - ▶ This is called **Flow Control**
- How?
 - ▶ Send only when an ACK arrives
 - ▶ Accurately calculate Time Out (TO)
- What could go wrong with sliding window?
 - ▶ Multiple frames can be lost
- How to handle that?
 - ▶ Use Go-Back-N Protocol or Selective-Reject Protocol
 - ▶ Selective-Reject Protocol performs well with devices with large buffers

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Protocol

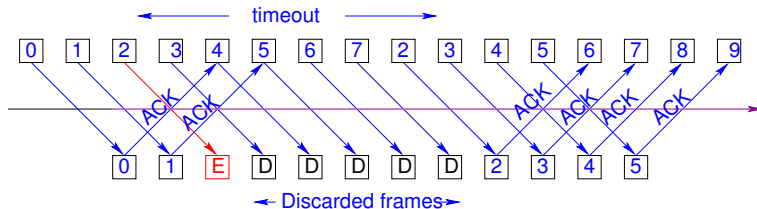
Sliding Window

Go-Back-N Protocol

Selective-Reject Protocol

Sequence Number Space

§3.9.6 Go-Back-N Protocol



See the video Go back N sliding window Protocol

Data Link Layer

Acronyms

Data Link Layer

Design Issues

How can reliability be provided?

Framing

Error Detection

Error Correction

Clock-Based Framing:
SONET

Reliable Transmission

Automatic Repeat
Request (ARQ)

What Could Go Wrong

Frames in Error

Stop-and-Wait Protocol

How Good Stop-and-Wait
Is?

Performance of SW
Protocol

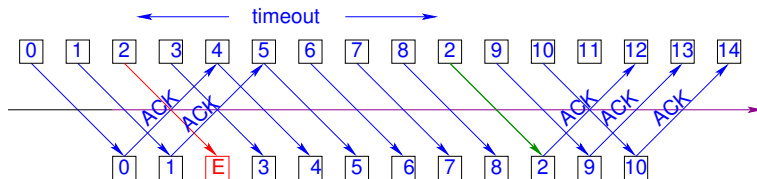
Sliding Window

Go-Back-N Protocol

Selective-Reject Protocol

Sequence Number Space

§3.9.7 Selective-Reject Protocol



See the video [Selective Repeat sliding Window Protocol](#)

Data Link Layer

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Protocol

Sliding Window

Go-Back-N Protocol

Selective-Reject Protocol

Sequence Number Space

§3.9.8 Sequence Number Space

- SeqNum field is finite \Rightarrow wraps around
- SeqNum space $>$ # of outstanding frames
- $SWS \leq \text{MaxSeqNum} - 1$ is not sufficient

How?

Why?

Why?

Example 3.12 (suppose 3-bit SeqNum field (0 . . 7))

- $SWS = RWS = 7$
- Sender transmit frames 0 . . 6
- Arrive successfully, but ACKs lost
- Sender retransmits 0 . . 6
- Receiver expecting 7, 0 . . 5, but receives second **incarnation** of 0 . . 5
- $SWS < (\text{MaxSeqNum} + 1) / 2$ is correct rule
 - ▶ Intuitively, SeqNum “frames” between two halves of sequence number space
- What does it mean? \Rightarrow Don't send more than half of your sequence number

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Sequence Number Space

§3.10.0 References

References

Suggested Exercises From the Text

[Tanenbaum and Wetherall, 2011] Tanenbaum, A. S. and Wetherall, D. J. (2011).
Computer Networks: 5th Edition.
Prentice Hall PTR.

§3.11.0 Suggested Exercises From the Text I

- 2 The following character encoding is used in a data link protocol:
 A: 01000111 B: 11100011 FLAG: 01111110 ESC: 11100000
 Show the bit sequence transmitted (in binary) for the four-character frame A B ESC FLAG when each of the following framing methods is used: (a) Byte count.
 (b) Flag bytes with byte stuffing.
 (c) Starting and ending flag bytes with bit stuffing.
- 2 The following data fragment occurs in the middle of a data stream for which the bytestuffing algorithm described in the text is used: A B ESC C ESC FLAG FLAG D. What is the output after stuffing?
- 4 What is the maximum overhead in byte-stuffing algorithm?
- 6 A bit string, 011110111110111110, needs to be transmitted at the data link layer. What is the string actually transmitted after bit stuffing?
- 8 To provide more reliability than a single parity bit can give, an error-detecting coding scheme uses one parity bit for checking all the odd-numbered bits and a second parity bit for all the even-numbered bits. What is the Hamming distance of this code?
- 9 Sixteen-bit messages are transmitted using a Hamming code. How many check bits are needed to ensure that the receiver can detect and correct single-bit errors? Show the bit pattern transmitted for the message 1101001100110101. Assume that even parity is used in the Hamming code.
- 14 Using the convolutional coder of Fig. 3-7, what is the output sequence when the input sequence is 10101010 (left to right) and the internal state is initially all zero?
- 15 Suppose that a message 1001 1100 1010 0011 is transmitted using Internet Checksum (4-bit word). What is the value of the checksum?
- 16 What is the remainder obtained by dividing $x^7 + x^5 + 1$ by the generator polynomial $x^3 + 1$?

§3.11.0 Suggested Exercises From the Text II

- 18 A 1024-bit message is sent that contains 992 data bits and 32 CRC bits. CRC is computed using the IEEE 802 standardized, 32-degree CRC polynomial. For each of the following, explain whether the errors during message transmission will be detected by the receiver: (a) There was a single-bit error.
(b) There were two isolated bit errors.
(c) There were 18 isolated bit errors.
(d) There were 47 isolated bit errors.
(e) There was a 24-bit long burst error.
(f) There was a 35-bit long burst error.
- 19 In the discussion of ARQ protocol in Section 3.3.3, a scenario was outlined that resulted in the receiver accepting two copies of the same frame due to a loss of acknowledgement frame. Is it possible that a receiver may accept multiple copies of the same frame when none of the frames (message or acknowledgement) are lost?
- 20 A channel has a bit rate of 4 Kbps and a propagation delay of 20 msec. For what range of frame sizes does stop-and-wait give an efficiency of at least 50%?
- 27 The distance from earth to a distant planet is approximately 9×10^{10} m. What is the channel utilization if a stop-and-wait protocol is used for frame transmission on a 64 Mbps point-to-point link? Assume that the frame size is 32 KB and the speed of light is 3×10^8 m/s.
- 28 In the previous problem, suppose a sliding window protocol is used instead. For what send window size will the link utilization be 100%? You may ignore the protocol processing times at the sender and the receiver.
- 32 Frames of 1000 bits are sent over a 1-Mbps channel using a geostationary satellite whose propagation time from the earth is 270 msec. Acknowledgements are always piggybacked onto data frames. The headers are very short. Three-bit sequence numbers are used. What is the maximum achievable channel utilization for (a) Stop-and-wait?
(b) Protocol 5?
(c) Protocol 6?
- 35 A 100-km-long cable runs at the T1 data rate. The propagation speed in the cable is 2/3 the speed of light in vacuum. How many bits fit in the cable?