

Here is the theoretical part of Diffusion Model.

1 Langevin SDE

The Langevin SDE has the following form:

$$X_{t+s} = X_t + \nabla \log p_t(x_t)s + \sqrt{2s}\xi \quad (1)$$

where $X_t \in \mathcal{R}^d$, $p_t(x_t) = p(X_t = x_t)$, $\xi \sim N(0, I)$, I is identical matrix of $m \times m$. Our goal is to sample from specific $p(x, t)$.

Theorem 1 *The density of Langevin Diffusion Model converges to $p(x)$ over time. In other words, if $X_t \sim p(x)$, then $X_{t+s} \sim p(x)$ for $\forall s > 0$.*

Proof 1 Let $\mu_t(f) = E[f(X_t)]$. Consider $\mu_{t+\tau}(f) = E[f(X_{t+\tau})]$, as $\tau \rightarrow 0$. Then

$$\begin{aligned} \mu_{t+\tau} &= E \left[f \left(X_t + \nabla \log p_t(x_t) \cdot \tau + \sqrt{2\tau}\xi \right) \right] \\ &= E \left[f(x_t) + \nabla^\top f(x_t) \left(\tau \nabla \log p_t(x_t) + \sqrt{2\tau}\xi \right) \right. \\ &\quad \left. + \frac{1}{2} \left(\nabla^\top \log p_t(x_t) \tau + \sqrt{2\tau}\xi \right) \nabla^2 f(x_t) \nabla \log p_t(x_t) \tau + \sqrt{2\tau}\xi \right] \\ &= E[f(x_t)] + E \left[\tau \nabla^\top f(x_t) \nabla \log p_t(x_t) \right] \\ &\quad + \frac{\tau^2}{2} E \left[\nabla^\top \log p(x_t) \cdot \nabla^2 f(x_t) \cdot \nabla \log p(x_t) \right] + E \left[\tau \xi^\top \nabla^2 f(x_t) \xi \right] \end{aligned} \quad (2)$$

The second term:

$$\begin{aligned} &\tau E \left[\nabla^\top f \nabla \log p_t \right] \\ &= \tau \int \nabla f \cdot \nabla \log p_t p_t dx = \tau \int \nabla f \cdot \nabla p_t dx \\ &= -\tau \int \text{tr}(\nabla^2 f) \cdot p_t dx = -\tau E \left[\text{tr}(\nabla^2 f) \right] \\ &= -\tau E \left[\xi^\top \nabla^2 f \xi \right] \end{aligned} \quad (3)$$

Then

$$\mu_{t+\tau} = E \left[\frac{1}{2} \nabla^\top \log p_t \nabla^2 f \nabla \log p_t \right] \cdot \tau^2 = O(\tau^2) \quad (4)$$

Hence we have $\frac{d}{dt}(\mu_t) = 0$, i.e. $E[\mu_t] = E[\mu_{t+s}]$ for $\forall s > 0$.

Remark 1 We define the density of normal distribution $N(x; \mu, \Sigma)$, and its log-density, gradient of density and score as follows:

$$\begin{cases} N(x; \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} e^{-\frac{1}{2}(x-\mu)^\top \Sigma^{-1}(x-\mu)} \\ \log N(x; \mu, \Sigma) = -\frac{1}{2}(x-\mu)^\top \Sigma^{-1}(x-\mu) - \log \left(\sqrt{(2\pi)^d |\Sigma|} \right) \\ \nabla_x N(x; \mu, \Sigma) = N(x; \mu, \Sigma) \Sigma^{-1}(x-\mu) \\ \nabla_x \log N(x; \mu, \Sigma) = -\Sigma^{-1}(x-\mu). \end{cases} \quad (5)$$

Actually, Langevin SDE is not necessary be as above i.e. the diffusion term is not necessary to be $\sqrt{2}$. The reason is to guarantee the stationary distribution of $p_t(x)$. i.e. the term $\frac{\partial p(x,t)}{\partial t} = 0$ in FPK equation. If the diffusion term is $g(t)$, then by FPK equation, we have

$$\nabla_x \cdot (fp - \frac{1}{2}g^2(t)\nabla p) = 0$$

then $f(x, t) = \frac{1}{2}g^2(t) \frac{\nabla_x p(x,t)}{p(x,t)} = \frac{1}{2}g^2(t) \nabla_x \log p(x, t)$.

2 Linear SDE

Then we consider linear SDE having the form:

$$dX_t = (a(t)X_t + b(t))dt + g(t)dW_t \quad (6)$$

By Euler Maruyama method, it can be approximated By

$$\begin{aligned} X_{t+s} &= X_t + (a(t)X_t + b(t))s + g(t)\sqrt{s}\xi \\ &= (1 + a(t)s)X_t + b(t)s + g(t)\sqrt{s}\xi \end{aligned} \quad (7)$$

where $\xi \sim N(0, 1)$. Usually we need to consider the expectation, variance and distribution of x . But the stochastic value of x is dependent of x_0 . Then first we consider

$$\begin{aligned} E[X_{t+s}|X_0] - E[X_t|X_0] &\approx (a(t)E[X_t|X_0] + b(t)s + g(t)\sqrt{s}E[\xi]) \\ &= (a(t)E[X_t|X_0] + b(t))s. \end{aligned} \quad (8)$$

Note $e(t) = E[X_t|X_0]$, then

$$e'(t) = \lim_{s \rightarrow 0} \frac{E[X_{t+s}|X_0] - E[X_t|X_0]}{s} = a(t) \cdot e(t) + b(t). \quad e(0) = X_0. \quad (9)$$

which is an ODE system, having solution

$$e(t) = \left(X_0 + \int_0^t e^{-\int_0^s a(r)dr} b(s)ds \right) \cdot e^{\int_0^t a(s)ds} \quad (10)$$

Therefore

$$\begin{aligned} E[X_t] &= E[E[X_t|X_0]] = E[e(t)] \\ &= \left(E[X_0] + \int_0^t e^{-\int_0^s a(r)dr} b(s)ds \right) e^{\int_0^t a(s)ds} \end{aligned} \quad (11)$$

Similarly, Note $\text{Var}(X_0|X_0) = v(t)$: then $\text{Var}(X_{t+s}|X_0) = (1 + sa(t))^2 \text{Var}(X_t|X_0) + sg^2(t)$. Then

$$\begin{aligned} V'(t) &= \lim_{s \rightarrow 0} \frac{\text{Var}(X_{t+s}|X_0) - \text{Var}(X_t|X_0)}{s} \\ &= [(a^2(t)s + 2a(t))v(t) + g^2(t)]|_{s \rightarrow 0} \\ &= 2a(t)V(t) + g^2(t), \quad V(0) = 0 \end{aligned} \quad (12)$$

Solution is:

$$v(t) = \left(\int_0^t e^{-\int_0^s 2a(r)dr} g^2(s)ds \right) \quad (13)$$

By law of total variance

$$\begin{aligned} \text{Var}(X_t) &= E[X_t^2] - E^2[X_t] = E[E[X_t^2|X_0]] - E^2[X_t] \\ &= E[\text{Var}(X_t|X_0) + E^2[X_t|X_0]] - E^2[X_t] \\ &= E[\text{Var}(X_t|X_0)] + E[E^2[X_t|X_0]] - E^2[E[X_t|X_0]] \\ &= E[\text{Var}(X_t|X_0)] + \text{Var}(E[X_t|X_0]) \end{aligned} \quad (14)$$

then

$$\begin{aligned} \text{Var} &= E[V(t)] + \text{Var}(e(t)) \\ &= \left(\int_0^t e^{-\int_0^s 2a(r)dr} g^2(s)ds \right) e^{\int_0^t 2a(s)ds} + e^{\int_0^t 2a(s)ds} \cdot \text{Var}(X_0). \end{aligned} \quad (15)$$

We have the following theorem which is crucial for diffusion models.

Theorem 2 If $X_{t+s} = (1 + a(t)s)X_t + b(t)s + g(t)\sqrt{s}\xi$
then $X_t|X_0 \sim N(E[X_t|X_0], \text{Var}(X_t|X_0))$, where $(E[X_t|X_0] = e(t), \text{Var}(X_t|X_0) = V(t))$.

Next, we will see how the above formula can be applied to diffusion models. There are three frameworks to build SDEs for diffusion models, VP, VE and sub-VP.

Definition 1 Noise function $\beta(t)$. s.t. $\beta(0) = 0; \beta'(t) \geq 0; \beta(t) \rightarrow \infty$ as $t \rightarrow \infty$

2.1 Variance Preserving (VP) SDE

So if we have diffusion model like:

$$\begin{aligned} X_{t_{i+1}} &= \sqrt{1 - (\beta(t_{i+1}) - \beta(t_i))}X_{t_i} + \sqrt{(\beta(t_{i+1}) - \beta(t_i))}\xi \\ &= \sqrt{1 - \Delta\beta(t_i)}X_{t_i} + \sqrt{\Delta\beta(t_i)}\xi \end{aligned} \quad (16)$$

Then the conditional distribution is given by:

$$q(X_{t_{i+1}}|X_{t_i}) = N(x_{t_{i+1}}; \sqrt{1 - \Delta\beta(t_i)}X_{t_i}, \Delta\beta(t_i)) \quad (17)$$

Then we need to estimate θ drift term f and diffusion term g :

$$\begin{aligned} f(x, t) &= \lim_{h \rightarrow 0} \frac{E[X_{t+h} - X_t | X_t = x]}{h} \\ &= \lim_{h \rightarrow 0} \frac{x\sqrt{1 - \Delta\beta(t)} - x}{h} = -\frac{x}{2}\beta'(t). \\ g(t) &= \sqrt{\lim_{h \rightarrow 0} \frac{N[X_{t+h}|X_t = x]}{h}} = \sqrt{\lim_{h \rightarrow 0} \frac{\beta(t+h) - \beta(t)}{h}} = \sqrt{\beta'(t)} \end{aligned} \quad (18)$$

Then the model can be written as $dx = -\frac{x}{2}\beta'(t)dt + \sqrt{\beta'(t)}dW_t$

Then by Theorem 2 we have

$$\begin{cases} E[X_t|X_0] = X_0 e^{\int_0^t -\frac{1}{2}\beta'(s)ds} = X_0 e^{-\frac{1}{2}\beta(t)} \\ E[X_t] = E[X_0] e^{-\frac{1}{2}\beta(t)} \\ V(X_t|X_0) = \int_0^t e^{\int_0^s \beta'(r)dr} \beta'(s)ds \cdot e^{-\beta(t)} = 1 - e^{-\beta(t)} \\ V(X_t) = 1 - e^{-\beta(t)} + V(X_0) e^{-\beta(t)} = 1 + (V(X_0) - 1) e^{-\beta(t)}. \end{cases} \quad (19)$$

So as $t \rightarrow \infty, \beta(t) \rightarrow \infty$, then $E \rightarrow 0, V \rightarrow 1$, i.e. $X_t|X_0 \sim N(E[X_t|X_0], \text{Var}[X_t|X_0]) \rightarrow N(0, 1)$ as $t \rightarrow \infty$.

2.2 Variance-Exploding SDE

Here is the model: $X_{t+h} = X_t + \sqrt{\Delta\beta(t)}\xi$

Similarly we can compute the $f(x, t) \equiv 0$ and $g(t) = \sqrt{\beta'(t)}$. Hence

$$\begin{cases} E[X_0|X_0] = X_0 \\ E[X_t] = E[X_0] \\ V(X_t|X_0) = \int_0^t e^{\int_0^s \beta'(r)dr} \beta'(s)ds = \beta(t) \\ V(X_t) = V[X_0] + \beta(t) \end{cases} \quad (20)$$

So the expectation value is constant and the variance is increasing monotonical.

If we rescale X_t as $Y_t = \frac{X_t}{\sqrt{\beta(t)}}$, then $Y_t \rightarrow N(0, 1), t \rightarrow \infty$.

2.3 Sub-VP SPE

Here, we set the drift and diffusion term as

$$\begin{aligned} f(x, t) &= -\frac{1}{2}\beta'(t) \\ g(t) &= \sqrt{\beta'(t)(1 - e^{-2\beta(t)})} \end{aligned} \quad (21)$$

As the same, we can compute that.

$$\begin{cases} E[X_t|X_0] = X_0 e^{-\frac{1}{2}\beta(t)} \\ E[X_t] = E[X_0] e^{-\frac{1}{2}\beta(t)} \\ V(X_t|X_0) = (1 - e^{-\beta(t)})^2 \\ V(X_t) = (1 - e^{-\beta(t)})^2 + V(X_0) e^{-\beta(t)}. \end{cases} \quad (22)$$

We can find out that the variance is always smaller than VP SDE.

Remark 2 To sum up, finally we hope that X_t converges to a normal distribution by choosing different drift and diffusion functions. For generative model, the goal is to sample from a Data distribution p_{data} . We have known that if we set the initial distribution $p_0(x_0) = p(X_0 = x_0) \sim p_{data}$, then after $t = T$, the distribution of X_t is tend to be $N(0, 1)$ under certain conditions.

So the idea is backward: if we sample from $X_T \sim N(0, 1)$, and then run SDE backwards, could we get the initial distribution?

3 Reverse SDE

Assume we have forward SDE: from $X_0 \sim p_0, X_T \sim p_T$,

$$dX_t = f(X_t, t)dt + g(t)dW_t \quad (23)$$

Then we define the reverse SDE as: from $X_T \sim p_T$,

$$d\bar{X}_t = \bar{f}(\bar{X}_t, t)dt + \bar{g}(t)d\bar{W}_t \quad (24)$$

where \bar{W}_t is Brownian Motion runs backward in time, i.e. $\bar{W}_{t-s} - \bar{W}_t$ is independent of \bar{W}_t . We can approximate by EM:

$$\bar{X}_{t-s} - \bar{X}_t = -s\bar{f}(\bar{X}_t, t) + \sqrt{s}\bar{g}(t)\xi \quad (25)$$

So the problem is: If given f, g , are there \bar{f}, \bar{g} s.t. the reverse time diffusion process \bar{X}_t has the same distribution as the forward process X_t ? Yes!

Theorem 3 The reverse SDE with \bar{f}, \bar{g} having the following form has the same distribution as the forward SDE 23:

$$\begin{cases} \bar{f}(x, t) = f(x, t) - g^2(x, t) \frac{\partial}{\partial x} \log p_t(x) \\ \bar{g} = g(t) \end{cases} \quad (26)$$

i.e.

$$d\bar{X}_t = [f(\bar{X}_t, t) - g^2(t) \log p_t(x_t)] dt + g(t)d\bar{W}_t \quad (27)$$

Proof 2 The proof is skipped.

This theorem allows us to learn how to generate samples from p_{data} .

Algorithm 1 :

Step1. Select $f(x, t)$ and $g(t)$ with affine drift coefficients s.t. $X_T \sim N(0, 1)$

Step2. Train a network $s_\theta(x, t) = \frac{\partial}{\partial x} \log p_t(x)$ where $p_t(x) = p(X_t = x)$ is the forward distribution.

Step3. Sample X_T from $N(0, 1)$, then run reverse SDE from T to 0 :

$$\bar{X}_{t-s} = \bar{X}_t + s [g^2(t)s_\theta(\bar{X}_t, t) - f(\bar{X}_t, t)] + \sqrt{s}g(t)\xi \quad (28)$$

4 Loss function

Normally we can define the loss function as follows:

$$\begin{aligned} L_\theta &= \frac{1}{T} \int_0^T \lambda(t) E_{x_0 \sim p_{data}} \left[E_{x_t \sim p_{t|0}(x_t|x_0)} [\|s_\theta(x_t, t) - \nabla_{x_t} \log p_t(x_t)\|^2] \right] dt \\ &= E_{t \sim U(0, T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[E_{x_t \sim p_{t|0}(x_t|x_0)} [\|s_\theta(x_t, t) - \nabla_{x_t} \log p_t(x_t)\|^2] \right] \right] \end{aligned} \quad (29)$$

It should be clarified that $p_{t|0}(x_t|x_0) = p(X_t = x_t|X_0 = x_0)$. So

$$p_t(x_t) = \int p_{t|0}(x_t|x_0)p_0(x_0)dx_0 = E_{x_0 \sim p_{data}} [p_{t|0}(x_t|x_0)]$$

. Then $p_t(x) = p(X_t = x)$. $p_{t|0}(x|y) = p(X_t = x|x_0 = y)$.

$$\begin{aligned} \nabla \log p_t(x) &= \frac{1}{p_t(x)} \nabla p_t(x). \\ &= \frac{1}{p_t(x)} \nabla \int p_{t|0}(x|y)p_0(y)dy \\ &= \frac{1}{p_t(x)} \int \nabla p_{t|0}(x|y)p_0(y)dy \\ &= \frac{1}{p_t(x)} \int \frac{\nabla p_{t|0}(x|y)}{p_{t|0}(x|y)} p_0(y) \cdot p_{t|0}(x|y)dy \\ &= \int \nabla_x \log (p_{t|0}(x|y)) \cdot p_0(y|y)dy \\ &= E_y [\nabla_x \log (p_{t|0}(x|y))] \end{aligned} \quad (30)$$

Lemma 1 If $y \sim p_{0|t}(y|x), x \sim p_t(x)$, then $y \sim p_0(y)$

Proof 3

$$\begin{aligned} p(x_0 = y|x_t = x) &= \int p(x_0 = y|x_t = x)p(x_t = x)dx = \int p(x_t = x|x_0 = y)p(x_0 = y)dx. \\ &= p(x_0 = y) = p_{data}(y) \end{aligned} \quad (31)$$

Then we can rewrite the loss function as:

$$\begin{aligned} L_\theta &= E_{t \sim U(0, T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[E_{x_t \sim p_{t|0}(x_t|x_0)} \left[\left\| S_\theta(x_t, t) - \frac{\partial}{\partial x_t} \log p_t(x_t) \right\|^2 \right] \right] \right] \\ &\leq E_{t \sim U(0, T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[E_{x_t \sim p_{t|0}(x_t|x_0)} \left[E_{y \sim p_{data}} [\|S_\theta(x_t, t) - \nabla_{x_t} \log p_{t|0}(x|y)\|^2] \right] \right] \right] \\ &= E_{t \sim U(0, T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[E_{x_t \sim p_{t|0}(x_t|x_0)} [\|S_\theta(x_t, t) - \nabla_{x_t} \log (p_{t|0}(x_t|x_0))\|^2] \right] \right] \end{aligned} \quad (32)$$

Since $p_{t|0}(X_t|x_0) = p(X_t = x_t|X_0 = x_0)$ has been discussed:

$$p_{t|0}(x_t|x_0) \sim N(x_t; E[X_t = x_t|X_0 = x_0], \text{Var}(X_t = x_t|X_0 = x_0)).$$

Then by theorem 2

$$\frac{\partial}{\partial x} \log p_{t|0}(x|x_0) = -\frac{x - E_{t|0}[x|x_0]}{\text{Var}_{t|0}(x|x_0)} = -\frac{x - e(t)}{V(t)} \quad (33)$$

So

$$\begin{aligned} L_\theta &= E_{t \sim U(0,T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[E_{\xi \sim N(0,1)} \left[\left\| s_\theta \left(\sqrt{\text{Var}_{t|0}(x_t|x_0)} \xi + E_{t|0}[x_t|x_0], t \right) + \frac{\xi}{\sqrt{\text{Var}_{t|0}(x_t|x_0)}} \right\|^2 \right] \right] \right] \\ &= E_{t \sim U(0,T)} \left[\lambda(t) E_{x_0 \sim p_{data}} \left[\frac{1}{\text{Var}_{t|0}(x_t|x_0)} E_{\xi \sim N(0,1)} \left[\left\| \xi_\theta \left(\sqrt{\text{Var}_{t|0}(x_t|x_0)} \xi + E_{t|0}[x_t|x_0], t \right) - \xi \right\|^2 \right] \right] \right] \end{aligned} \quad (34)$$

where $\xi_\theta = -s_\theta \sqrt{\text{Var}_{t|0}(x_t|x_0)}$ is called denoising network.