


Ref. «Stochastic Differential Equations An Introduction with Application» by Øksendal, «Nonlinear Expectation. Nonlinear Evaluations and Risk Measures» by Shige Peng and «Backward Stochastic Differential Equation in Finance» by N. El Karoui, S. Peng, M.C. Quenez. «Backward Stochastic Differential Equations» by Jianfeng Zhang

1. Martingale representation thm.

$(\Omega, \mathcal{F}, \mathbb{P})$: a probability space. $(B_t)_{t \geq 0}$ a standard d -dim B.M.

$\mathcal{F}_t = \sigma\{B_s : 0 \leq s \leq t\}$ where N is the collection of \mathbb{P} null sets in Ω .

$L^2(\Omega, \mathcal{F}_T, \mathbb{P}) := \{r.v. X \in \mathcal{F}_T \text{ and } \int_0^T |X_s|^2 d\mathbb{P} < +\infty\}$

$L^2(0, T; \Omega, \mathcal{F}_t, \mathbb{P}) := \{\text{an } \mathcal{F}_t\text{-adapted process } \phi_t(w) \text{ s.t. } \mathbb{E}\left[\int_0^T |\phi_t(s)|^2 ds\right] < +\infty\}$

Recall that we have prove if $V \in L^2(0, T)$, the Ito integral.

$$X_t = X_0 + \int_0^t V(s, w) dB_s \quad t \geq 0$$

is always a martingale wr.t. \mathcal{F}_t , now we'll give the converse result:

Any \mathcal{F}_t -adapted martingale in $L^2(\Omega, \mathcal{F}_T, \mathbb{P})$ can be representation as an Ito integral.

Lemma 1. Fix $T > 0$, the set of r.v.s

$$\left\{ \phi(B_{t_1}, \dots, B_{t_n}) : t_i \in [0, T], \phi \in C^{\infty}(\mathbb{R}^n) \right\}$$

(thus cylindrical function) is dense in $L^2(\Omega, \mathcal{F}_T, \mathbb{P})$.

Lemma 2. The linear span of r.v.s of the type

$$\exp\left\{\int_0^T h(t) dB_t - \frac{1}{2} \int_0^T h^2(t) dt\right\}, h \in L^2(0, T) \quad (\text{deterministic})$$

is dense in $L^2(\Omega, \mathcal{F}_T, \mathbb{P})$. simple function

Thm 3. Let $F \in L^2(\Omega, \mathcal{F}_T, \mathbb{P})$. Then there exists a unique stochastic process $f(t, w) \in L^2(0, T)$ s.t.

$$F(w) = \mathbb{E}[F] + \int_0^T f(t, w) dB_t.$$

Rmk: $f(t, w)$ can be express in terms of the Malliavin derivation of F .

Thm 4. Suppose M_t is an \mathcal{F}_t -adapted martingale and $M_t \in L^2(\Omega, \mathbb{P}) \forall t \geq 0$. there exist a unique stochastic process $g(s, w) \in L^2(0, t)$ s.t.

$$M_t(w) = \mathbb{E}[M_t] + \int_0^t g(s, w) dB_s \quad a.s. \quad \forall t \geq 0$$

2. Existence, uniqueness of BSDEs

Consider the BSDE

$$\begin{cases} -dY_t = f(t, Y_t, Z_t) dt - Z_t^* dW_t \\ Y_T = \bar{Y}, \quad \mathcal{F}_T \end{cases}$$

or equivalently

$$Y_t = \bar{Y} + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z_s^* dW_s$$

where: $\cdot W_t$ is an n -dim B.M.

- The terminal value is an \mathcal{F}_T -measurable r.v $\bar{Y}: \Omega \rightarrow \mathbb{R}^d$
 - The generator $f: \Omega \times \mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R}^{n \times d} \rightarrow \mathbb{R}^d$ and $P \otimes \mathcal{B}^d \otimes \mathcal{B}^{n \times d}$ -measurable.
- We need to find a pair of \mathcal{F}_t -adapted process $(Y_t, Z_t) \in L^2(0, T; \mathbb{R}^n \times \mathbb{R}^{n \times d})$ satisfying BSDE (x)

Qn: Why Z_t is needed as a part of solution?

If we consider $\begin{cases} dY_t = f'(t, Y_t) dt \text{ where } f' \text{ is a deterministic function} \\ Y_T = \bar{Y} \end{cases}$

Y_t is a map of \bar{Y}_t which is \mathcal{F}_T -measurable not \mathcal{F}_0 .

Hence we need Z_t as a part of solution to fit measurability.

Lemma 5: For a fixed $\bar{Y} \in L^2(\Omega, \mathcal{F}_T; \mathbb{R}^d)$ and $g(\cdot)$ satisfying

$$\mathbb{E}[\int_0^T g(s) ds]^2 < \infty$$

there exist a unique pair of process $(Y_t, Z_t) \in L^2(0, T; \mathbb{R}^n \times \mathbb{R}^n)$ st.

$$Y_t = \bar{Y} + \int_t^T g(s) ds - \int_t^T Z_s dB_s$$

In particular we have the following prior estimate.

$$\|Y\|^2 + \mathbb{E}[\int_0^T (\frac{\beta}{2} |Y_s|^2 + |Z_s|^2) e^{\beta s} ds] \leq \|\bar{Y}\|^2 + \frac{2}{\beta} \mathbb{E}[\int_0^T g(s)^2 e^{\beta s} ds], \quad \forall \beta \in \mathbb{R}.$$

Proof: Uniqueness is a simple corollary of prior estimate.

Existence: define $M_t = \mathbb{E}[\bar{Y} + \int_t^T g(s) ds | \mathcal{F}_t]$, ($\mathbb{E}[M_t | \mathcal{F}_s] = M_s$)

M_t is a square integrable \mathcal{F}_t -martingale.. by martingale representation thm.

$\exists! Z_t \in L^2(0, T)$ st. $M_t = M_0 + \int_0^t Z_s dB_s$

thus $M_t = M_0 - \int_t^T Z_s dB_s = \bar{Y} + \int_0^T g(s) ds - \int_t^T Z_s dB_s$

let $y_t := M_t - \int_0^t g(s) ds$, $y_t = \bar{Y} + \int_t^T g(s) ds - \int_t^T Z_s dB_s$.

With some prior estimates, we assume

① For each $(y, z) \in \mathbb{R}^m \times \mathbb{R}^{m \times d}$, $g(\cdot, y, z) \in \mathcal{F}_t$ and
 $\int_0^T |g(\cdot, 0, 0)| ds \in L^2(\Omega, \mathcal{F}_T, P)$

② For each $y, y' \in \mathbb{R}^m$ and $z, z' \in \mathbb{R}^{m \times d}$
 $|g(t, y, z) - g(t, y', z')| \leq C(|y - y'| + |z - z'|)$

Thm 6. For any terminal condition $\hat{z} \in L^1(\mathcal{F}_T)$. BSDE has a unique solution $(Y, Z) \in L^2(0, T; \mathbb{R}^m \times \mathbb{R}^{m \times d})$.

Proof: Prior estimate + fixed points thm or Picard iteration.

$$Y_t^{k+1} = \hat{z} + \int_t^T f(s, Y_s^k, Z_s^k) ds - \int_t^T (Z_s^{k+1})^* dB_s$$

Rmk: Since Y_t is \mathcal{F}_t -adapted, and \mathcal{F}_0 is a trivial σ -field.
 Y_0 is a constant!

3. Formulation of Linear BSDE

We next consider the linear BSDE with suitable condition, and provide a representation formula for its solution. ($d=m=1$ for simplicity)

$$Y_t = \hat{z} + \int_t^T [\alpha_s Y_s + z_s \beta_s + f_s] ds - \int_t^T z_s dB_s$$

we define $T_t := \exp\{\int_0^t \beta_s dB_s + \int_0^t [\alpha_s - \frac{1}{2}(\beta_s)^2] ds\}$

thus $dT_t = \beta_t T_t dB_t + \alpha_t T_t dt$ (adjoint process)

apply Itô formula to $T_t Y_t$. we have

$$d(T_t Y_t) = T_t dY_t + Y_t dT_t + d\langle T_t, Y_t \rangle$$

where $dY_t = -(\alpha_t Y_t + z_t \beta_t + f_t) dt + z_t dB_t$

$$d\langle T_t, Y_t \rangle = -T_t f_t^* dt + T_t I[Y_t \beta_t^* + z_t] dB_t$$

denote $\hat{Y}_t = T_t Y_t$; $\hat{z}_t = T_t [Y_t \beta_t^* + z_t]$; $\hat{f}_t = T_t f_t^*$

$$\hat{Y}_t = \hat{z}_t + \int_t^T \hat{f}_s ds - \int_t^T \hat{z}_s dB_s$$

according to Lemma 5.

$$\hat{Y}_t = \mathbb{E}[\hat{z}_t + \int_t^T \hat{f}_s ds | \mathcal{F}_t]$$

$$Y_t = T_t^{-1} \mathbb{E}[\hat{z}_t + \int_t^T \hat{f}_s ds | \mathcal{F}_t]$$

$Z_t = ? \longleftrightarrow$ Martingale Re thm

4. Comparison Theorem

For
and
We suppose

$$Y_t^1 = \tilde{z}^1 + \int_t^T f^1(s, Y_s^1, Z_s^1) ds - \int_t^T (Z_s^1)^* dW_s$$

$$Y_t^2 = \tilde{z}^2 + \int_t^T f^2(s, Y_s^2, Z_s^2) ds - \int_t^T (Z_s^2)^* dW_s$$

$\textcircled{1} \quad \tilde{z}^1 \geq \tilde{z}^2 \quad P \text{ a.s.}$

$\textcircled{2} \quad f^1(t, y, z) \geq f^2(t, y, z) \quad dP \otimes dt \text{ a.a.}$

Then we have a.e. $Y_t^1 \geq Y_t^2 \quad (0 \leq t \leq T)$

Rmk: The comparison for SDE needs some more conditions on f .
(see e.g. GITM 113 Prop 2.18).

5. Application

We consider asset pricing:

riskless asset: $dP_t^0 = P_t^0 r_t dt$ r_t : short rate.

n risky securities: $dP_t^i = P_t^i [b_t^i dt + \sum_{j=1}^n \sigma_t^{ij} dW_t^j]$ b_t^i : appreciation rate

Assume (The market is dynamically complete)

- Γ_t, b_t are predictable bounded and nonnegative.
- σ, σ^{-1} (volatility matrix) are predictable bdd. $\sigma = (\sigma^{ij})$
- \exists bdd θ (risk premium) s.t. $b_t - \Gamma_t I = \sigma_t \theta_t \quad dP \otimes dt \text{ a.s.}$
- Π_t^i : the wealth invested in the i -th stock.

$$\Pi^0 := V - \sum_{i=1}^n \Pi_t^i \quad V_t = V_0 + \int_0^t \sum_{i=1}^n \Pi_t^i \frac{dP_t^i}{P_t^i} \quad \Pi^* = (\Pi^1, \dots, \Pi^n)$$

thus

$$\begin{aligned} dV_t &= \sum_{i=1}^n \Pi_t^i [b_t^i dt + \sum_{j=1}^n \sigma_t^{ij} dW_t^j] + \Pi_t^* \Gamma_t dt \\ &= \Gamma_t V_t dt + \Pi_t^* (b_t - \Gamma_t) dt + \Pi_t^* \sigma_t dW_t \\ &= \Gamma_t V_t dt + \Pi_t^* \sigma_t [dW_t + \theta_t dt] \end{aligned}$$

(V, Π) is a trading strategy.

A fair price of positive contingent claim is to find (X, Π)

s.t.

$$\begin{cases} dX_t = \Gamma_t X_t dt + \Pi_t^* \sigma_t \theta_t dt + \Pi_t^* \sigma_t dW_t \\ X_T = \tilde{z} \in \mathcal{F}_T \text{ and } \tilde{z} \geq 0 \end{cases}$$

where \tilde{z} is the future price, the X_0 is a fair price at $t=0$.