

- $$\underset{\tilde{x} \in \mathbf{R}^2}{\text{minimize}} \quad \max_k f_k(\tilde{x})$$

where  $f_k(\tilde{x}) = \frac{1}{2}(\tilde{x} - y_k)^T P_k (\tilde{x} - y_k) + r_k$  with

$$P_1 = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}, P_2 = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}, P_3 = \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix}, y_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, y_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}, y_3 = \begin{bmatrix} -1 \\ -2 \end{bmatrix}, r_1 = 0, r_2 = 1, r_3 = -1$$

- Since the objective function above is not differentiable, the Newton's method cannot be applied directly.
- This problem can be transformed into an equivalent problem:

$$\begin{aligned} & \underset{\tilde{x} \in \mathbf{R}^2, w \in \mathbf{R}}{\text{minimize}} && w \\ & \text{subject to} && f_1(\tilde{x}) - w \leq 0 \\ & && f_2(\tilde{x}) - w \leq 0 \\ & && f_3(\tilde{x}) - w \leq 0 \end{aligned}$$

- To solve this problem, we will apply the barrier method.

- Let  $x = \begin{bmatrix} \tilde{x} \\ w \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ . Then we use the log barrier  $\varphi(x)$  to rewrite the problem.

$$\begin{aligned} &\rightarrow \begin{aligned} &\text{minimize}_{x \in \mathbf{R}^3} && t f_0(x) + \varphi(x) \end{aligned} \\ &\text{where } f_0(x) = w = x_3 \text{ and } \varphi(x) = -\sum_{i=1}^3 \log(-f_i(x) + w) \end{aligned}$$

- Initial point  $x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 10 \end{bmatrix}$  and  $t = 1$ .

- Newton step  $\Delta x_{nt} = -(\nabla^2 f(x))^{-1} \nabla f(x) \rightarrow \Delta x_{nt}^{(l)}$
- Newton decrement  $\lambda(x) = (-\nabla f(x)^T \Delta x_{nt})^{1/2} \rightarrow \lambda^{(l)}(x)$
- Backtracking line search along search direction using  $\beta = 0.7$  starting from  $s = 1$  until  $x^{(l)} + s\Delta x_{nt}^{(l)} \in \mathbf{dom} f$  (Note:  $t^+ := \beta t$ )
- Continue the backtracking line search until  $f(x + s\Delta x_{nt}^{(l)}) \leq \alpha s \lambda(x^{(l)})^2$ , where  $\alpha = 0.1$
- Update  $x^{(l+1)} = x^{(l)} + s\Delta x_{nt}^{(l)}$
- If  $\lambda(x)^2 / 2 < \epsilon_{inner}$ , then break the Newton iteration.
- Updating  $t^+ := \mu t$ . If  $\frac{m}{t} < \epsilon_{outer}$ , then break the loop.