CSCI 470: Heaps (continued), Partition Procedure

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Overview

1. A quick update

2. Heaps

3. Heapsort

4. Partition

A quick update

Course Material on GitHub

- Corrected a couple of mistakes from lecture notes 03: https://github.com/vijayko/csci-470 (a temporary arrangement)
- Please let me know if there are any errors in the lecture notes to be corrected.
- You can always clone the repo with all updated/corrected notes.
- · Homework 01 has been posted and it's due on Mon Sep 18.
- Exam 1 will be pushed at least by one lecture session.
- If you are new to the class, please fill out this form: https://tinyurl.com/csci-470-form

Heaps

Heaps

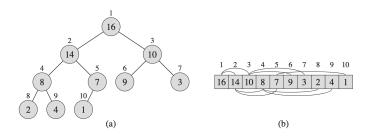


Figure 6.1 A max-heap viewed as (a) a binary tree and (b) an array. The number within the circle at each node in the tree is the value stored at that node. The number above a node is the corresponding index in the array. Above and below the array are lines showing parent-child relationships; parents are always to the left of their children. The tree has height three; the node at index 4 (with value 8) has height one.

Implementation of the heap

```
PARENT(i)
   return |i/2|
LEFT(i)
   return 2i
RIGHT(i)
   return 2i + 1
Can we verify these using Figure 6.1?
```

Definition of height in a binary heap

- We define the *height* of a node in a heap to be the number of edges on the longest simple downward path from the node to a leaf, and we define the height of the heap to be the height of its root.
- · What's going to be the height of node 4 in Figure 6.1?

Maintaining heap property

```
Max-Heapify(A, i)
 1 l = LEFT(i)
 2 r = RIGHT(i)
 3 if l < A.heapsize and A[l] > A[i]
          largest = l
    else largest = i
    if r \leq A.heapsize and A[r] > A[largest]
          largest = r
    if largest \neq i
 8
 9
          exchange A[i] with A[largest]
10
          MAX-HEAPIFY(A, largest)
```

Assumptions while calling Max-Heapify

When it is called, Max-Heapify assumes that the binary trees rooted at Left(i) and Right(i) are max-heaps, but that A[i] might be smaller than its children, thus, violating the max-heap property.

Max-Heapify: Illustration

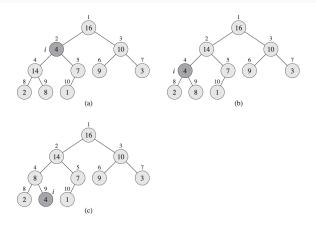


Figure 6.2 The action of MAX-HEAPIFY(A.2), where A. heap-size = 10. (a) The initial configuration, with A[2] at node i = 2 violating the max-heap property since it is not larger than both children. The max-heap property is restored for node 2 in (b) by exchanging A[2] with A[4], which destroys the max-heap property for node 4. The recursive call MAX-HEAPIFY(A, 4) now has i = 4. After swapping A[4] with A[9], as shown in (e), node 4 is fixed up, and the recursive call MAX-HEAPIFY(A, 9) yields no further change to the data structure.

Classwork

Show that, with the array representation for storing an n-element heap, the leaves are the nodes indexed by $\lfloor n/2 \rfloor + 1$, $\lfloor n/2 \rfloor + 2$, ..., n.

Building a heap

```
BUILD-MAX-HEAP(A)
```

- 1 A.heapsize = A.length
- 2 **for** i = [A.length/2] **downto** 1
- 3 Max-Heapify(A, i)

Illustration

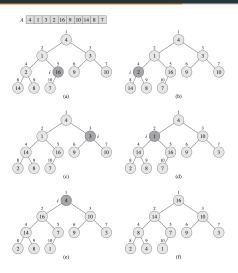


Figure 6.3 The operation of BUILD-MAX-HEAP; showing the data structure before the call to MAX-HEAP(s) in line 3 of BUILD-MAX-HEAP(s) a) A 10-element input array A and the binary tree it represents. The figure shows that the loop index r feefers to node 5 before the call MAX-HEAP(s)(A), (b) The data structure that results. The loop index i for the next iteration refers to node 4. (b)-(s) Subsequent iterations of the fer loop in BUILD-MAX-HEAP(D blace whenever MAX-HEAP(FV) is called on a node, the two subtrees of than took are both max-heaps.

Correctness of building a heap

To show why Build-Max-Heap works correctly, we use the following loop invariant:

At the start of each iteration of the **for** loop of lines 2-3, each node i+1, i+2, ..., n is the root of a max-heap.

Referencing previous figure

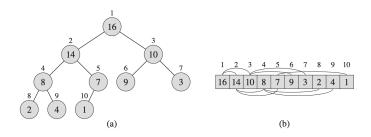


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Correctness

Initialization: Prior to the first iteration of the loop, $i = \lfloor n/2 \rfloor$. Each node $\lfloor n/2 \rfloor + 1$, $\lfloor n/2 \rfloor + 2$, ..., n is a leaf and is thus the root of a trivial max-heap.

Correctness continued

Maintenance: To see that each iteration maintains the loop invariant, observe that the children of node i are numbered higher than i. By the loop invariant, therefore, they are both roots of max-heaps. This is precisely the condition required for the MAX-HEAPIFY(A, i) to make node i a max-heap root. Moreover, the MAX-HEAPIFY call preserves the property that nodes i+1, i+2, ..., n are all roots of max-heaps. Decrementing i in the **for** loop update reestablishes the loop invariant for the next iteration.

Correctness continued

Termination: At termination i = 0. By the loop invariant, each node 1, 2, ..., n is the root of a max-heap. In particular, node 1 is.

Runtime

Simpler upper bound: We can compute a simpler upper bound on the running time of Build-Max-Heap as follows. Each call to Max-Heapify costs $O(\lg n)$ time and Build-Max-Heap makes O(n) such calls. Thus, the running time is $O(n \lg n)$. Although this is a correct upper bound, it's not a tight bound for this problem.

Runtime: A tight upper bound

- An n-element heap has a height of $\lfloor \lg n \rfloor$.
- An n-element heap has at most $\lceil n/2^{h+1} \rceil$ nodes for any height h. (Exercise 6.3-3 from CLRS)

$$T(n) = \sum_{h=0}^{\lfloor \lg n \rfloor} \lceil n/2^{h+1} \rceil O(h)$$

$$= O\left(n \sum_{h=0}^{\lfloor \lg n \rfloor} \frac{h}{2^h}\right)$$

$$\leq O\left(n \sum_{h=0}^{\infty} \frac{h}{2^h}\right)$$

$$= O(2n)$$

$$= O(n)$$

Please refer Lecture Note 5 & 6 for this derivation.

Heapsort

Heapsort

```
HEAPSORT(A)
```

- 1 BUILD-MAX-HEAP(A)
- 2 **for** i = A.length **downto** 2
- 3 exchange A[1] with A[i]
- 4 A.heapsize = A.heapsize -1
- 5 Max-Heapify(A, 1)

Runtime

Here line 1 takes O(n), the loop runs n times out of which the body of the for loop runs n-1. MAX-HEAPIFY(A, 1) in line 5 takes $O(\lg n)$, because the height of the heap is $O(\lg n)$. Putting it together, the runtime of heapsort is $O(n \lg n)$.

Heapsort: Illustration

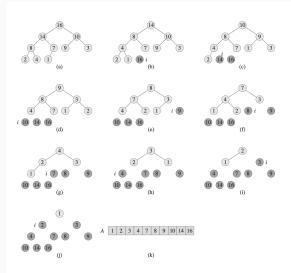


Figure 6.4 The operation of HEAPSORT. (a) The max-heap data structure just after BUILD-MAX-HEAP has built it in line 1. (b)-(j) The max-heap just after each call of MAX-HEAPIFY in line 5, showing the value of i at that time. Only lightly shaded nodes remain in the heap. (k) The resulting sorted array A.

Partition

Quick-Sort

Before we discuss quick sort, we will go over Partition procedure, used in this algorithm.

Partition Procedure

```
PARTITION(A, p, r)

1 x = A[r]

2 i = p - 1

3 for j = p to r - 1

4 if A[j] \le x

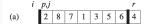
5 i = i + 1

6 exchange A[i] with A[j]

7 exchange A[i + 1] with A[r]

8 return i + 1
```

Partition Illustration



(c)
$$\begin{bmatrix} p, i & j & r \\ 2 & 8 & 7 & 1 & 3 & 5 & 6 & 4 \end{bmatrix}$$

(d)
$$\begin{bmatrix} p,t & j & r \\ 2 & 8 & 7 & 1 & 3 & 5 & 6 & 4 \end{bmatrix}$$