IAR C/C++ Compiler

Reference Guide

for Atmel® Corporation's AVR Microcontroller Family





COPYRIGHT NOTICE

Copyright © 1996-2011 IAR Systems AB.

No part of this document may be reproduced without the prior written consent of IAR Systems AB. The software described in this document is furnished under a license and may only be used or copied in accordance with the terms of such a license.

DISCLAIMER

The information in this document is subject to change without notice and does not represent a commitment on any part of IAR Systems. While the information contained herein is assumed to be accurate, IAR Systems assumes no responsibility for any errors or omissions.

In no event shall IAR Systems, its employees, its contractors, or the authors of this document be liable for special, direct, indirect, or consequential damage, losses, costs, charges, claims, demands, claim for lost profits, fees, or expenses of any nature or kind.

TRADEMARKS

IAR Systems, IAR Embedded Workbench, C-SPY, visualSTATE, From Idea To Target, IAR KickStart Kit, IAR PowerPac, IAR YellowSuite, IAR Advanced Development Kit, IAR, and the IAR Systems logotype are trademarks or registered trademarks owned by IAR Systems AB. J-Link is a trademark licensed to IAR Systems AB.

Microsoft and Windows are registered trademarks of Microsoft Corporation.

Atmel is a registered trademark of Atmel® Corporation. AVR is a trademark of Atmel® Corporation.

Adobe and Acrobat Reader are registered trademarks of Adobe Systems Incorporated.

All other product names are trademarks or registered trademarks of their respective owners.

EDITION NOTICE

Sixth edition: June 2011 Part number: CAVR-6

This guide applies to version 6.x of IAR Embedded Workbench® for AVR.

Internal reference: M10, csrct2010.1, V_100308, IMAE.

Brief contents

| Tables |
|--|
| Preface 17 |
| Part I. Using the compiler25 |
| Getting started |
| Data storage |
| Functions47 |
| Placing code and data53 |
| The DLIB runtime environment71 |
| The CLIB runtime environment109 |
| Assembler language interface |
| Using C |
| Using C++ |
| Efficient coding for embedded applications 159 |
| Part 2. Reference information179 |
| External interface details181 |
| Compiler options187 |
| Data representation |
| Extended keywords |
| Pragma directives |
| Intrinsic functions |
| The preprocessor |

| Library functions | 301 |
|---|-----|
| Segment reference | 317 |
| Implementation-defined behavior | 333 |
| Implementation-defined behavior for C89 | 349 |
| Index | 363 |

Contents

| Tables | | 15 |
|-------------|------------------------------------|------|
| Preface | | 17 |
| Who | should read this guide | . 17 |
| How | to use this guide | . 17 |
| Wha | t this guide contains | . 18 |
| Othe | er documentation | . 19 |
| | User and reference guides | . 19 |
| | The online help system | . 20 |
| | Further reading | . 20 |
| | Web sites | . 21 |
| Docu | ument conventions | . 21 |
| | Typographic conventions | . 22 |
| | Naming conventions | . 22 |
| Getting sta | arted | 27 |
| IAR | language overview | . 27 |
| Supp | orted AVR devices | . 28 |
| Build | ling applications—an overview | . 28 |
| | Compiling | . 28 |
| | Linking | . 29 |
| Basic | project configuration | . 29 |
| | Processor configuration | . 30 |
| | Memory model | .31 |
| | Size of double floating-point type | . 32 |
| | Optimization for speed and size | . 32 |
| | Runtime environment | .32 |
| Spec | ial support for embedded systems | . 34 |
| | Extended keywords | . 34 |
| | Pragma directives | . 34 |

| | Predefined symbols | 35 |
|----------|---|----|
| | Special function types | 35 |
| | Accessing low-level features | 35 |
| Data s | torage | 37 |
| ı | ntroduction | 37 |
| | Different ways to store data | 37 |
| ı | Memory models | 38 |
| | Specifying a memory model | 38 |
| ı | Memory types | 39 |
| | Using data memory attributes | |
| | Pointers and memory types | 41 |
| | Structures and memory types | 42 |
| | More examples | 42 |
| • | C++ and memory types | 43 |
| | Auto variables—on the stack | 44 |
| | The stack | 44 |
| | Dynamic memory on the heap | 45 |
| Function | ons | 47 |
| F | Function-related extensions | 47 |
| F | Function storage | 47 |
| | Using function memory attributes | 47 |
| F | Primitives for interrupts, concurrency, and OS-relate | :d |
| F | programming | 48 |
| | Interrupt functions | 48 |
| | Monitor functions | 49 |
| | C++ and special function types | 51 |
| Placing | g code and data | 53 |
| 9 | Segments and memory | 53 |
| | What is a segment? | 53 |
| F | Placing segments in memory | 54 |
| | Customizing the linker configuration file | 54 |

| Data segments | 57 |
|---|----------------|
| Static memory segments | 57 |
| The stack | 61 |
| The return address stack | 63 |
| The heap | 64 |
| Located data | 65 |
| User-defined segments | 65 |
| Code segments | 65 |
| Interrupt and reset vectors | 66 |
| Functions | 66 |
| Compiler-generated segments | 66 |
| C++ dynamic initialization | 66 |
| Verifying the linked result of code and da | ta placement67 |
| Segment too long errors and range errors | 67 |
| Linker map file | 67 |
| Managing multiple address spaces | 68 |
| The DLIB runtime environment | 71 |
| Introduction to the runtime environmen | t 71 |
| Runtime environment functionality | 71 |
| Setting up the runtime environment | 72 |
| Using a prebuilt library | 73 |
| Choosing a library | 74 |
| Customizing a prebuilt library without rebuil | ding75 |
| Choosing formatters for printf and scanf | 75 |
| Choosing a printf formatter | 76 |
| Choosing a scanf formatter | 77 |
| Application debug support | 78 |
| Including C-SPY debugging support | 78 |
| The debug library functionality | 79 |
| The C-SPY Terminal I/O window | 79 |
| Low-level functions in the debug library | 80 |
| The C-SPV Terminal I/O window | 80 |

| Overriding library modules | 81 |
|---|-----|
| Building and using a customized library | 82 |
| Setting up a library project | 83 |
| Modifying the library functionality | 83 |
| Using a customized library | 83 |
| System startup and termination | 84 |
| System startup | 84 |
| System termination | 86 |
| Customizing system initialization | 87 |
| _low_level_init | 87 |
| Modifying the file cstartup.s90 | 88 |
| Library configurations | 88 |
| Choosing a runtime configuration | 88 |
| Standard streams for input and output | 89 |
| Implementing low-level character input and output | 89 |
| Configuration symbols for printf and scanf | 91 |
| Customizing formatting capabilities | 92 |
| File input and output | 92 |
| Locale | 93 |
| Locale support in prebuilt libraries | 93 |
| Customizing the locale support | 94 |
| Changing locales at runtime | 95 |
| Environment interaction | 95 |
| The getenv function | 96 |
| The system function | 96 |
| Signal and raise | 96 |
| Time | 97 |
| Strtod | 97 |
| Pow | 97 |
| Assert | 98 |
| Heaps | 98 |
| Managing a multithreaded environment | 98 |
| Multithread support in the DLIB library | 99 |
| Enabling multithread support | 100 |

| | Changes in the linker configuration file | 103 |
|----------|--|-----|
| Che | ecking module consistency | 103 |
| | Runtime model attributes | 104 |
| | Using runtime model attributes | 104 |
| | Predefined runtime attributes | 105 |
| | User-defined runtime model attributes | 107 |
| The CLIE | runtime environment | 109 |
| Usi | ng a prebuilt library | 110 |
| | Choosing a library | 110 |
| Inp | ut and output | 111 |
| | Character-based I/O | 111 |
| | Formatters used by printf and sprintf | 112 |
| | Formatters used by scanf and sscanf | 113 |
| Sys | tem startup and termination | 113 |
| | System startup | 114 |
| | System termination | 114 |
| Ove | erriding default library modules | 114 |
| Cus | stomizing system initialization | 114 |
| C-S | PY runtime interface | 115 |
| | The debugger Terminal I/O window | 115 |
| | Termination | 115 |
| Che | ecking module consistency | 115 |
| Assemble | er language interface | 117 |
| Mix | ing C and assembler | 117 |
| | Intrinsic functions | 117 |
| | Mixing C and assembler modules | 118 |
| | Inline assembler | 119 |
| Cal | ling assembler routines from C | 120 |
| | Creating skeleton code | |
| | Compiling the code | 121 |
| Cal | ling assembler routines from C++ | 122 |
| Cal | ling convention | 123 |
| | Choosing a calling convention | 124 |

| | Function declarations | 125 |
|-----------|---|-----|
| | Using C linkage in C++ source code | 125 |
| | Preserved versus scratch registers | 126 |
| | Function entrance | 127 |
| | Function exit | 130 |
| | Restrictions for special function types | 130 |
| | Examples | 131 |
| | Function directives | 132 |
| Call f | rame information | 133 |
| | CFI directives | 133 |
| | Creating assembler source with CFI support | 133 |
| Using C | | 135 |
| | guage overview | |
| | nsions overview | |
| | Enabling language extensions | |
| IAR (| C language extensions | |
| | Extensions for embedded systems programming | |
| | Relaxations to Standard C | 140 |
| Using C++ | | 143 |
| Over | view | 143 |
| | Embedded C++ | 143 |
| | Extended Embedded C++ | 144 |
| Enab | ling support for C++ | 144 |
| EC++ | feature descriptions | 145 |
| | Using IAR attributes with Classes | 145 |
| | Function types | 148 |
| | New and Delete operators | 149 |
| | Using static class objects in interrupts | 150 |
| | Using New handlers | 150 |
| | Templates | 151 |
| | Debug support in C-SPY | 151 |
| EEC+ | ++ feature description | 151 |
| | Templates | 151 |

| | Variants of cast operators | . 154 |
|--------------|---|-------|
| | Mutable | . 155 |
| | Namespace | . 155 |
| | The STD namespace | . 155 |
| | Pointer to member functions | . 155 |
| C++ I | anguage extensions | . 156 |
| Efficient co | ding for embedded applications | 159 |
| Selec | ting data types | . 159 |
| | Locating strings in ROM, RAM or flash | . 160 |
| | Using efficient data types | . 160 |
| | Floating-point types | . 161 |
| | Memory model and memory attributes for data | . 162 |
| | For details about the memory types, see <i>Memory types</i> , page 39 | . 162 |
| | Using the best pointer type | . 162 |
| | Anonymous structs and unions | . 162 |
| Cont | rolling data and function placement in memory | . 164 |
| | Data placement at an absolute location | . 165 |
| | Data and function placement in segments | . 166 |
| Cont | rolling compiler optimizations | . 168 |
| | Scope for performed optimizations | . 168 |
| | Multi-file compilation units | . 168 |
| | Optimization levels | . 169 |
| | Speed versus size | . 170 |
| | Fine-tuning enabled transformations | . 170 |
| Facili | tating good code generation | . 172 |
| | Writing optimization-friendly source code | . 173 |
| | Saving stack space and RAM memory | . 173 |
| | Function prototypes | . 173 |
| | Integer types and bit negation | . 174 |
| | Protecting simultaneously accessed variables | . 175 |
| | Accessing special function registers | . 176 |
| | Non initialized variables | 176 |

| Part 2. Reference information | on 179 |
|----------------------------------|---------------|
| External interface details | |
| Invocation syntax | 181 |
| | 181 |
| Passing options | 181 |
| Environment variables | 182 |
| Include file search procedure | |
| Compiler output | |
| Diagnostics | 185 |
| Message format | |
| Severity levels | |
| Setting the severity level | |
| Internal error | 186 |
| Compiler options | 187 |
| Options syntax | 187 |
| Types of options | |
| Rules for specifying parameters | |
| Summary of compiler options | 190 |
| Descriptions of compiler options | |
| Data representation | 231 |
| Alignment | 231 |
| Alignment on the AVR microcontro | oller231 |
| Byte order | 232 |
| Basic data types | 232 |
| Integer types | 232 |
| Floating-point types | 235 |
| Pointer types | 237 |
| Function pointers | 237 |
| Data pointers | 237 |
| Casting | 238 |
| Structure types | 240 |
| Alignment | 240 |

| General layout | 240 |
|--|-----------|
| Type qualifiers | 240 |
| Declaring objects volatile | 240 |
| Declaring objects volatile and const | 242 |
| Declaring objects const | 242 |
| Data types in C++ | 243 |
| Extended keywords | 245 |
| General syntax rules for extended keywords | 245 |
| Type attributes | 245 |
| Object attributes | 248 |
| Summary of extended keywords | 249 |
| Descriptions of extended keywords | 250 |
| Pragma directives | 265 |
| Summary of pragma directives | 265 |
| Descriptions of pragma directives | 266 |
| Intrinsic functions | 283 |
| Summary of intrinsic functions | 283 |
| Descriptions of intrinsic functions | |
| The preprocessor | 293 |
| Overview of the preprocessor | 293 |
| Descriptions of predefined preprocessor symbols | |
| Descriptions of miscellaneous preprocessor exten | sions 299 |
| Library functions | 301 |
| Library overview | 301 |
| Header files | 301 |
| Library object files | 302 |
| Alternative more accurate library functions | 302 |
| Reentrancy | 302 |
| The longjmp function | 303 |
| IAR DLIB Library | 303 |
| C harder files | 303 |

| C++ header files | 304 |
|---|-----|
| Library functions as intrinsic functions | 307 |
| Added C functionality | 307 |
| Symbols used internally by the library | 309 |
| IAR CLIB Library | 309 |
| Library definitions summary | 310 |
| AVR-specific library functions | 310 |
| Specifying read and write formatters | 311 |
| Segment reference | 317 |
| Summary of segments | 317 |
| Descriptions of segments | 318 |
| Implementation-defined behavior | 333 |
| Descriptions of implementation-defined behavior | 333 |
| Implementation-defined behavior for C89 | 349 |
| Descriptions of implementation-defined behavior | 349 |
| Index | 363 |

Tables

| 1. Typographic conventions used in this guide | 22 |
|--|-------|
| 2: Naming conventions used in this guide | 22 |
| 3: Summary of processor configuration | 31 |
| 4: Memory model characteristics | 39 |
| 5: Memory types and their corresponding memory attributes | 40 |
| 6: Function memory attributes | 47 |
| 7: XLINK segment memory types | 54 |
| 8: Memory layout of a target system (example) | 55 |
| 9: Memory types with corresponding segment groups | 58 |
| 10: Segment name suffixes | 58 |
| 11: Prebuilt libraries | 74 |
| 12: Customizable items | 75 |
| 13: Formatters for printf | 76 |
| 14: Formatters for scanf | 77 |
| 15: Levels of debugging support in runtime libraries | 78 |
| 16: Functions with special meanings when linked with debug library | 80 |
| 17: Library configurations | 88 |
| 18: Descriptions of printf configuration symbols | 91 |
| 19: Descriptions of scanf configuration symbols | 92 |
| 20: Low-level I/O files | 93 |
| 21: Heaps and memory types | 98 |
| 22: Library objects using TLS | 99 |
| 23: Macros for implementing TLS allocation | . 102 |
| 24: Example of runtime model attributes | . 104 |
| 25: Predefined runtime model attributes | . 105 |
| 26: Runtime libraries | . 110 |
| 27: Registers used for passing parameters | . 128 |
| 28: Passing parameters in registers | . 129 |
| 29: Registers used for returning values | . 130 |
| 30: Language extensions | . 137 |
| 31: Compiler optimization levels | . 169 |

| 32: | Compiler environment variables | 182 |
|-----|--|-----|
| 33: | Error return codes | 184 |
| 34: | Compiler options summary | 190 |
| 35: | Accessing variables with aggregate initializers | 208 |
| 36: | Integer types | 232 |
| 37: | Floating-point types | 235 |
| 38: | Function pointers | 237 |
| 39: | Data pointers | 237 |
| 40: | size_t typedef | 239 |
| 41: | ptrdiff_t typedef | 239 |
| 42: | Type of volatile accesses treated in a special way | 242 |
| 43: | Extended keywords summary | 249 |
| 44: | Pragma directives summary | 265 |
| 45: | Intrinsic functions summary | 283 |
| 46: | Predefined symbols | 294 |
| 47: | Traditional Standard C header files—DLIB | 304 |
| 48: | Embedded C++ header files | 305 |
| 49: | Standard template library header files | 305 |
| 50: | New Standard C header files—DLIB | 306 |
| 51: | IAR CLIB Library header files | 310 |
| 52: | Segment summary | 317 |
| 53: | Message returned by strerror()—IAR DLIB library | 348 |
| 54: | Message returned by strerror()—IAR DLIB library | 359 |
| 55: | Message returned by strerror()—IAR CLIB library | 362 |

Preface

Welcome to the IAR C/C++ Compiler Reference Guide for AVR. The purpose of this guide is to provide you with detailed reference information that can help you to use the compiler to best suit your application requirements. This guide also gives you suggestions on coding techniques so that you can develop applications with maximum efficiency.

Who should read this guide

Read this guide if you plan to develop an application using the C or C++ language for the AVR microcontroller and need detailed reference information on how to use the compiler. You should have working knowledge of:

- The architecture and instruction set of the AVR microcontroller. Refer to the documentation from Atmel® Corporation for information about the AVR microcontroller
- The C or C++ programming language
- Application development for embedded systems
- The operating system of your host computer.

How to use this guide

When you start using the IAR C/C++ Compiler for AVR, you should read *Part 1. Using the compiler* in this guide.

When you are familiar with the compiler and have already configured your project, you can focus more on *Part 2. Reference information*.

If you are new to using the IAR Systems build tools, we recommend that you first study the *IAR Embedded Workbench*® *IDE Project Management and Building Guide*. This guide contains a product overview, tutorials that can help you get started, conceptual and user information about the IDE and the IAR C-SPY® Debugger, and corresponding reference information.

What this guide contains

Below is a brief outline and summary of the chapters in this guide.

Part I. Using the compiler

- Getting started gives the information you need to get started using the compiler for
 efficiently developing your application.
- Data storage describes how to store data in memory, focusing on the different memory models and memory type attributes.
- Functions gives a brief overview of function-related extensions—mechanisms for controlling functions—and describes some of these mechanisms in more detail.
- Placing code and data describes the concept of segments, introduces the linker command file, and describes how code and data are placed in memory.
- The DLIB runtime environment describes the DLIB runtime environment in which
 an application executes. It covers how you can modify it by setting options,
 overriding default library modules, or building your own library. The chapter also
 describes system initialization introducing the file cstartup, how to use modules
 for locale, and file I/O.
- The CLIB runtime environment gives an overview of the CLIB runtime libraries and how to customize them. The chapter also describes system initialization and introduces the file cstartup.
- Assembler language interface contains information required when parts of an
 application are written in assembler language. This includes the calling convention.
- Using C gives an overview of the two supported variants of the C language and an overview of the compiler extensions, such as extensions to Standard C.
- *Using C*++ gives an overview of the two levels of C++ support: The industry-standard EC++ and IAR Extended EC++.
- Efficient coding for embedded applications gives hints about how to write code that compiles to efficient code for an embedded application.

Part 2. Reference information

- External interface details provides reference information about how the compiler interacts with its environment—the invocation syntax, methods for passing options to the compiler, environment variables, the include file search procedure, and the different types of compiler output. The chapter also describes how the compiler's diagnostic system works.
- Compiler options explains how to set options, gives a summary of the options, and contains detailed reference information for each compiler option.

- Data representation describes the available data types, pointers, and structure types.
 This chapter also gives information about type and object attributes.
- Extended keywords gives reference information about each of the AVR-specific keywords that are extensions to the standard C/C++ language.
- Pragma directives gives reference information about the pragma directives.
- Intrinsic functions gives reference information about functions to use for accessing AVR-specific low-level features.
- *The preprocessor* gives a brief overview of the preprocessor, including reference information about the different preprocessor directives, symbols, and other related information.
- Library functions gives an introduction to the C or C++ library functions, and summarizes the header files.
- Segment reference gives reference information about the compiler's use of segments.
- Implementation-defined behavior describes how the compiler handles the implementation-defined areas of the C language standard.

Other documentation

User documentation is available as hypertext PDFs and as a context-sensitive online help system in HTML format. You can access the documentation from the Information Center or from the **Help** menu in the IAR Embedded Workbench IDE. The online help system is also available via the F1 key.

USER AND REFERENCE GUIDES

The complete set of IAR Systems development tools is described in a series of guides. For information about:

- System requirements and information about how to install and register the IAR Systems products, refer to the booklet *Quick Reference* (available in the product box) and the *Installation and Licensing Guide*.
- Getting started using IAR Embedded Workbench and the tools it provides, see the guide Getting Started with IAR Embedded Workbench®.
- Using the IDE for project management and building, see the IAR Embedded Workbench® IDE Project Management and Building Guide
- Using the IAR C-SPY® Debugger, see the C-SPY® Debugging Guide for AVR
- Using the IAR XLINK Linker, the IAR XAR Library Builder, and the IAR XLIB Librarian, see the IAR Linker and Library Tools Reference Guide.

- Programming for the IAR Assembler for AVR, see the IAR Assembler Reference Guide for AVR.
- Using the IAR DLIB Library, see the *DLIB Library Reference information*, available in the online help system.
- Using the IAR CLIB Library, see the *IAR C Library Functions Reference Guide*, available in the online help system.
- Porting application code and projects created with a previous version of the IAR Embedded Workbench for AVR, see the IAR Embedded Workbench® Migration Guide for AVR®.
- Developing safety-critical applications using the MISRA C guidelines, see the IAR Embedded Workbench® MISRA C:2004 Reference Guide or the IAR Embedded Workbench® MISRA C:1998 Reference Guide.

Note: Additional documentation might be available depending on your product installation.

THE ONLINE HELP SYSTEM

The context-sensitive online help contains:

- Comprehensive information about debugging using the IAR C-SPY® Debugger
- Reference information about the menus, windows, and dialog boxes in the IDE
- Compiler reference information
- Keyword reference information for the DLIB library functions. To obtain reference
 information for a function, select the function name in the editor window and press
 F1. Note that if you select a function name in the editor window and press F1 while
 using the CLIB library, you will get reference information for the DLIB library.

FURTHER READING

These books might be of interest to you when using the IAR Systems development tools:

- Barr, Michael, and Andy Oram, ed. *Programming Embedded Systems in C and C++*. O'Reilly & Associates.
- Harbison, Samuel P. and Guy L. Steele (contributor). C: A Reference Manual. Prentice Hall.
- Josuttis, Nicolai M. *The C++ Standard Library: A Tutorial and Reference*. Addison-Wesley.
- Kernighan, Brian W. and Dennis M. Ritchie. The C Programming Language. Prentice Hall.
- Labrosse, Jean J. Embedded Systems Building Blocks: Complete and Ready-To-Use Modules in C. R&D Books.

- Lippman, Stanley B. and Josée Lajoie. C++ Primer. Addison-Wesley.
- Mann, Bernhard. C für Mikrocontroller. Franzis-Verlag. [Written in German.]
- Meyers, Scott. *Effective C++: 50 Specific Ways to Improve Your Programs and Designs.* Addison-Wesley.
- Meyers, Scott. *More Effective C++*. Addison-Wesley.
- Meyers, Scott. Effective STL. Addison-Wesley.
- Stroustrup, Bjarne. *The C++ Programming Language*. Addison-Wesley.
- Stroustrup, Bjarne. *Programming Principles and Practice Using C++*. Addison-Wesley.
- Sutter, Herb. Exceptional C++: 47 Engineering Puzzles, Programming Problems, and Solutions. Addison-Wesley.

WEB SITES

Recommended web sites:

- The Atmel® Corporation web site, www.atmel.com, contains information and news about the AVR microcontroller.
- The IAR Systems web site, www.iar.com, holds application notes and other product information.
- The web site of the C standardization working group, www.open-std.org/jtc1/sc22/wg14.
- The web site of the C++ Standards Committee, www.open-std.org/jtc1/sc22/wg21.
- Finally, the Embedded C++ Technical Committee web site,
 www.caravan.net/ec2plus, contains information about the Embedded C++ standard.

Document conventions

When, in this text, we refer to the programming language C, the text also applies to C++, unless otherwise stated.

When referring to a directory in your product installation, for example avr\doc, the full path to the location is assumed, for example c:\Program Files\IAR Systems\Embedded Workbench 6.n\avr\doc.

TYPOGRAPHIC CONVENTIONS

This guide uses the following typographic conventions:

| Style | Used for | |
|-----------|--|--|
| computer | Source code examples and file paths. Text on the command line. Binary, hexadecimal, and octal numbers. | |
| parameter | A placeholder for an actual value used as a parameter, for example filename.h where filename represents the name of the file. | |
| [option] | An optional part of a command. | |
| [a b c] | An optional part of a command with alternatives. | |
| {a b c} | A mandatory part of a command with alternatives. | |
| bold | Names of menus, menu commands, buttons, and dialog boxes that appear on the screen. | |
| italic | A cross-reference within this guide or to another guide.Emphasis. | |
| | An ellipsis indicates that the previous item can be repeated an arbitrary number of times. | |
| X | Identifies instructions specific to the IAR Embedded Workbench® IDE interface. | |
| | Identifies instructions specific to the command line interface. | |
| | Identifies helpful tips and programming hints. | |
| <u>•</u> | Identifies warnings. | |

Table 1: Typographic conventions used in this guide

NAMING CONVENTIONS

The following naming conventions are used for the products and tools from IAR Systems® referred to in this guide:

| Brand name | Generic term |
|-------------------------------------|-------------------------|
| IAR Embedded Workbench® for AVR | IAR Embedded Workbench® |
| IAR Embedded Workbench® IDE for AVR | the IDE |
| IAR C-SPY® Debugger for AVR | C-SPY, the debugger |
| IAR C-SPY® Simulator | the simulator |
| IAR C/C++ Compiler™ for AVR | the compiler |

Table 2: Naming conventions used in this guide

| Brand name | Generic term |
|--------------------------|---------------------|
| IAR Assembler™ for AVR | the assembler |
| IAR XLINK Linker™ | XLINK, the linker |
| IAR XAR Library Builder™ | the library builder |
| IAR XLIB Librarian™ | the librarian |
| IAR DLIB Library™ | the DLIB library |
| IAR CLIB Library™ | the CLIB library |

Table 2: Naming conventions used in this guide (Continued)

Document conventions

Part I. Using the compiler

This part of the IAR C/C++ Compiler Reference Guide for AVR includes these chapters:

- Getting started
- Data storage
- Functions
- Placing code and data
- The DLIB runtime environment
- The CLIB runtime environment
- Assembler language interface
- Using C
- Using C++
- Efficient coding for embedded applications.



Getting started

This chapter gives the information you need to get started using the compiler for efficiently developing your application.

First you will get an overview of the supported programming languages, followed by a description of the steps involved for compiling and linking an application.

Next, the compiler is introduced. You will get an overview of the basic settings needed for a project setup, including an overview of the techniques that enable applications to take full advantage of the AVR microcontroller. In the following chapters, these techniques are studied in more detail.

IAR language overview

There are two high-level programming languages you can use with the IAR C/C++ Compiler for AVR:

- C, the most widely used high-level programming language in the embedded systems industry. You can build freestanding applications that follow these standards:
 - Standard C—also known as C99. Hereafter, this standard is referred to as *Standard C* in this guide.
 - C89—also known as C94, C90, C89, and ANSI C. This standard is required when MISRA C is enabled.
- C++, a modern object-oriented programming language with a full-featured library well suited for modular programming. Any of these standards can be used:
 - Embedded C++ (EC++)—a subset of the C++ programming standard, which is intended for embedded systems programming. It is defined by an industry consortium, the Embedded C++ Technical committee. See the chapter *Using* C++.
 - IAR Extended Embedded C++ (EEC++)—EC++ with additional features such as full template support, multiple inheritance, namespace support, the new cast operators, as well as the Standard Template Library (STL).

Each of the supported languages can be used in *strict* or *relaxed* mode, or relaxed with IAR extensions enabled. The strict mode adheres to the standard, whereas the relaxed mode allows some common deviations from the standard.

For more information about C, see the chapter Using C.

For more information about Embedded C++ and Extended Embedded C++, see the chapter Using C++.

For information about how the compiler handles the implementation-defined areas of the languages, see the chapter *Implementation-defined behavior*.

It is also possible to implement parts of the application, or the whole application, in assembler language. See the *IAR Assembler Reference Guide for AVR*.

Supported AVR devices

The IAR C/C++ Compiler for AVR supports all devices based on the standard Atmel® Corporation AVR microcontroller.

An up-to-date list of supported AVR devices is available on the IAR Systems web site.

Building applications—an overview

A typical application is built from several source files and libraries. The source files can be written in C, C++, or assembler language, and can be compiled into object files by the compiler or the assembler.

A library is a collection of object files that are added at link time only if they are needed. A typical example of a library is the compiler library containing the runtime environment and the C/C++ standard library. Libraries can also be built using the IAR XAR Library Builder, the IAR XLIB Librarian, or be provided by external suppliers.

The IAR XLINK Linker is used for building the final application. XLINK normally uses a linker configuration file, which describes the available resources of the target system.





Below, the process for building an application on the command line is described. For information about how to build an application using the IDE, see the *IAR Embedded Workbench*® *IDE Project Management and Building Guide*.

COMPILING

In the command line interface, the following line compiles the source file myfile.c into the object file myfile.r90 using the default settings:

iccavr myfile.c

You must also specify some critical options, see *Basic project configuration*, page 29.

LINKING

The IAR XLINK Linker is used for building the final application. Normally, XLINK requires the following information as input:

- One or more object files and possibly certain libraries
- The standard library containing the runtime environment and the standard language functions
- A program start label
- A linker configuration file that describes the placement of code and data into the memory of the target system
- Information about the output format.

On the command line, the following line can be used for starting XLINK:

```
xlink myfile.r90 myfile2.r90 -s __program_start -f lnkm128s.xcl
cl3s-ec_mul.r90 -o aout.a90 -r -FIntel-extended
```

In this example, myfile.r90 and myfile2.r90 are object files, lnkm128s.xcl is the linker configuration file, and cl3s-ec_mul.r90 is the runtime library. The option -s specifies the label where the application starts. The option -o specifies the name of the output file, and the option -r is used for specifying the output format UBROF, which can be used for debugging in C-SPY®.

The IAR XLINK Linker produces output according to your specifications. Choose the output format that suits your purpose. You might want to load the output to a debugger—which means that you need output with debug information. Alternatively, you might want to load the output to a flash loader or a PROM programmer—in which case you need output without debug information, such as Intel hex or Motorola S-records. The option -F can be used for specifying the output format. (The default output format is Motorola.)

Basic project configuration

This section gives an overview of the basic settings for the project setup that are needed to make the compiler and linker generate the best code for the AVR device you are using. You can specify the options either from the command line interface or in the IDE.

You need to make settings for:

- Processor configuration
- Memory model
- Size of double floating-point type
- Optimization settings

• Runtime environment.

In addition to these settings, many other options and settings can fine-tune the result even further. For information about how to set options and for a list of all available options, see the chapters *Compiler options* and the *IAR Embedded Workbench® IDE Project Management and Building Guide*, respectively.

PROCESSOR CONFIGURATION

To make the compiler generate optimum code, you should configure it for the AVR microcontroller you are using.

The --cpu option versus the -v option

There are two processor options that can be used for configuring the processor support:

```
--cpu=device and -vn
```

Your application may only use one processor option at a time, and the same processor option must be used by all user and library modules to maintain consistency.

Both options set up default behavior—implicit assumptions—but note that the --cpu option is more precise because it contains more information about the intended target than the more generic -v option. The --cpu option knows, for example, how much flash memory is available in the given target.

The --cpu=device option implicitly sets up all internal compiler settings needed to generate code for the processor variant you are using. These options are implicitly controlled when you use the --cpu option: --eecr_address, --eeprom_size, --enhanced_core, --spmcr_address, -v and --64k_flash.

Because these options are automatically set when you use the --cpu option, you cannot set them explicitly. For information about implicit assumptions when using the -v option, see *Summary of processor configuration for -v*, page 31. For more information about the generated code, see -v, page 226.



Use the --cpu or -v option to specify the AVR device; see the chapter *Compiler options* for syntax information.



See the IAR Embedded Workbench® IDE Project Management and Building Guide for information about setting project options in the IDE.

Summary of processor configuration for -v

This table summarizes the memory characteristics for each -v option:

| Generic processor | Available | Function mem- | Max addressable | Max module and/or |
|-------------------|---------------|---------------|------------------|-------------------|
| option | memory models | ory attribute | data | program size |
| -v0 (default) | Tiny | nearfunc | \leq 256 bytes | ≤8 Kbytes |
| -v1 | Tiny, Small | nearfunc | \leq 64 Kbytes | ≤8 Kbytes |
| -v2 | Tiny | nearfunc | \leq 256 bytes | ≤ I28 Kbytes |
| -v3 | Tiny, Small | nearfunc | \leq 64 Kbytes | ≤ I28 Kbytes |
| -v4 | Small, Large | nearfunc | ≤ 16 Mbytes | ≤ I28 Kbytes |
| -v5 | Tiny, Small | farfunc* | \leq 64 Kbytes | ≤ 8 Mbytes |
| -v6 | Small, Large | farfunc* | ≤ 16 Mbytes | ≤8 Mbytes |

Table 3: Summary of processor configuration

Note:

- *) When using the -v5 or the -v6 option, it is possible, for individual functions, to override the __farfunc attribute and instead use the __nearfunc attribute
- Pointers with function memory attributes have restrictions in implicit and explicit casts between pointers and between pointers and integer types. For details about the restrictions, see *Casting*, page 238.
- -v2: There are currently no devices that match this processor option, which has been added to support future devices
- All implicit assumptions for a given -v option are also true for corresponding --cpu options.

It is important to be aware of the fact that the -v option does not reflect the amount of used data, but the maximum amount of addressable data. This means that, for example, if you are using a microcontroller with 16 Mbytes addressable data, but you are not using more than 256 bytes or 64 Kbytes of data, you must still use either the -v4 or the -v6 option for 16 Mbytes data.

MEMORY MODEL

One of the characteristics of the AVR microcontroller is a trade-off in how memory is accessed, ranging from cheap access limited to small memory areas, up to, up to more expensive access methods that can access any location in memory.

In the compiler, you can set a default memory access method by selecting a memory model. There are three memory models available—Tiny, Small, and Large. Your choice of processor option determines which memory models are available.

For more details about memory models, see *Memory models*, page 38.

SIZE OF DOUBLE FLOATING-POINT TYPE

Floating-point values are represented by 32- and 64-bit numbers in standard IEEE 754 format. If you use the compiler option --64bit_doubles, you can make the compiler use 64-bit doubles. The data type float is always represented using 32 bits.

OPTIMIZATION FOR SPEED AND SIZE

The compiler is a state-of-the-art compiler with an optimizer that performs, among other things, dead-code elimination, constant propagation, inlining, common sub-expression elimination, and precision reduction. It also performs loop optimizations, such as induction variable elimination.

You can decide between several optimization levels and for the highest level you can choose between different optimization goals—*size*, *speed*, or *balanced*. Most optimizations will make the application both smaller and faster. However, when this is not the case, the compiler uses the selected optimization goal to decide how to perform the optimization.

The optimization level and goal can be specified for the entire application, for individual files, and for individual functions. In addition, some individual optimizations, such as function inlining, can be disabled.

For information about compiler optimizations and for more information about efficient coding techniques, see the chapter *Efficient coding for embedded applications*.

RUNTIME ENVIRONMENT

To create the required runtime environment you should choose a runtime library and set library options. You might also need to override certain library modules with your own customized versions.

Two different sets of runtime libraries are provided:

- The IAR DLIB Library, which supports Standard C and C++. This library also supports floating-point numbers in IEEE 754 format and it can be configured to include different levels of support for locale, file descriptors, multibyte characters, etc.
- The IAR CLIB Library is a light-weight library, which is not fully compliant with Standard C. Neither does it fully support floating-point numbers in IEEE 754 format or does it support Embedded C++. (This library is used by default).

The runtime library contains the functions defined by the C and the C++ standards, and include files that define the library interface (the system header files).

The runtime library you choose can be one of the prebuilt libraries, or a library that you customized and built yourself. The IDE provides a library project template for both libraries, that you can use for building your own library version. This gives you full control of the runtime environment. If your project only contains assembler source code, you do not need to choose a runtime library.

For more information about the runtime environments, see the chapters *The DLIB* runtime environment and *The CLIB* runtime environment, respectively.



Setting up for the runtime environment in the IDE

To choose a library, choose **Project>Options**, and click the **Library Configuration** tab in the **General Options** category. Choose the appropriate library from the **Library** drop-down menu.

Note that for the DLIB library there are different configurations—Normal and Full—which include different levels of support for locale, file descriptors, multibyte characters, et cetera. See *Library configurations*, page 88, for more information.

Based on which library configuration you choose and your other project settings, the correct library file is used automatically. For the device-specific include files, a correct include path is set up.



Setting up for the runtime environment from the command line

On the compiler command line, specify whether you want the system header files for DLIB or CLIB by using the --dlib option or the --clib option. If you use the DLIB library, you can use the --dlib_config option instead if you also want to explicitly define which library configuration to be used.

On the linker command line, you must specify which runtime library object file to be used. The linker command line can for example look like this:

```
dlavr-3s-ec_mul-64-f.r90
```

A library configuration file that matches the library object file is automatically used. To explicitly specify a library configuration, use the --dlib_config option.

In addition to these options you might need to specify application-specific compiler and linker options, for example the include path to the application-specific header files, for example:

-I application\inc

For information about the prebuilt library object files for the IAR DLIB Library, see *Using a prebuilt library*, page 73. Make sure to use the object file that matches your other project options.

For information about the prebuilt object files for the IAR CLIB Library, see *Using a prebuilt library*, page 110. Make sure to use the object file that matches your other project options.

Setting library and runtime environment options

You can set certain options to reduce the library and runtime environment size:

- The formatters used by the functions printf, scanf, and their variants, see *Choosing formatters for printf and scanf*, page 75 (DLIB) and *Input and output*, page 111 (CLIB).
- The size of the stack and the heap, see *The stack*, page 61, and *The heap*, page 64, respectively.

Special support for embedded systems

This section briefly describes the extensions provided by the compiler to support specific features of the AVR microcontroller.

EXTENDED KEYWORDS

The compiler provides a set of keywords that can be used for configuring how the code is generated. For example, there are keywords for controlling the memory type for individual variables as well as for declaring special function types.



By default, language extensions are enabled in the IDE.

The command line option -e makes the extended keywords available, and reserves them so that they cannot be used as variable names. See, -e, page 203 for additional information.

For more information about the extended keywords, see the chapter Extended keywords.

PRAGMA DIRECTIVES

The pragma directives control the behavior of the compiler, for example how it allocates memory, whether it allows extended keywords, and whether it issues warning messages.

The pragma directives are always enabled in the compiler. They are consistent with standard C, and are very useful when you want to make sure that the source code is portable.

For more information about the pragma directives, see the chapter *Pragma directives*.

PREDEFINED SYMBOLS

With the predefined preprocessor symbols, you can inspect your compile-time environment, for example time of compilation, processor variant, and memory model in use.

For more information about the predefined symbols, see the chapter *The preprocessor*.

SPECIAL FUNCTION TYPES

The special hardware features of the AVR microcontroller are supported by the compiler's special function types: interrupt and monitor. You can write a complete application without having to write any of these functions in assembler language.

For more information, see *Primitives for interrupts, concurrency, and OS-related programming*, page 48.

ACCESSING LOW-LEVEL FEATURES

For hardware-related parts of your application, accessing low-level features is essential. The compiler supports several ways of doing this: intrinsic functions, mixing C and assembler modules, and inline assembler. For information about the different methods, see *Mixing C and assembler*, page 117.

Special support for embedded systems

Data storage

This chapter gives a brief introduction to the memory layout of the AVR microcontroller and the fundamental ways data can be stored in memory: on the stack, in static (global) memory, or in heap memory. For efficient memory usage, the compiler provides a set of memory models and memory attributes, allowing you to fine-tune the access methods, resulting in smaller code size. The concepts of memory models and memory types are described in relation to pointers, structures, Embedded C++ class objects, and non-initialized memory. Finally, detailed information about data storage on the stack and the heap is provided.

Introduction

The AVR microcontroller is based on the Harvard architecture—thus code and data have separate memory spaces and require different access mechanisms. Code and different types of data are located in memory spaces as follows:

- The internal flash space, which is used for code, __flash declared objects, and initializers
- The data space, which can consist of external ROM, used for constants, and RAM areas used for the stack, for registers, and for variables
- The EEPROM space, which is used for variables.

DIFFERENT WAYS TO STORE DATA

In a typical application, data can be stored in memory in three different ways:

- Auto variables
 - All variables that are local to a function, except those declared static, are stored on the stack. These variables can be used as long as the function executes. When the function returns to its caller, the memory space is no longer valid.
- Global variables, module-static variables, and local variables declared static In this case, the memory is allocated once and for all. The word static in this context means that the amount of memory allocated for this kind of variables does not change while the application is running. For more information, see *Memory models*, page 38 and *Memory types*, page 39.

• Dynamically allocated data.

An application can allocate data on the *heap*, where the data remains valid until it is explicitly released back to the system by the application. This type of memory is useful when the number of objects is not known until the application executes. Note that there are potential risks connected with using dynamically allocated data in systems with a limited amount of memory, or systems that are expected to run for a long time. For more information, see *Dynamic memory on the heap*, page 45.

Memory models

Technically, the memory model specifies the default memory type attribute and the default data pointer attribute. This means that the memory model controls the following:

- The default placement of static and global variables, and constant literals
- Dynamically allocated data, for example data allocated with malloc, or, in C++, the operator new
- The default pointer type
- The placement of the runtime stack. For details about stack placement, see CSTACK, page 319.

For information about how to specify a memory type for individual objects, see *Using data memory attributes*, page 39.

SPECIFYING A MEMORY MODEL

Four memory models are implemented: Tiny, Small, Large, and Huge. These models are controlled by the --memory_model option. Each model has a default memory type and a default pointer size. The code size will also be reduced somewhat if the Tiny or Small memory model is used.

If you do not specify a memory model option, the compiler will use the Tiny memory model for all processor options, except for -v4 and -v6, where the Small memory model will be used. For information about processor options, see *Summary of processor configuration for -v*, page 31.

Your project can only use one memory model at a time, and the same model must be used by all user modules and all library modules. However, you can override the default memory type for individual data objects and pointers by explicitly specifying a memory attribute, see *Using data memory attributes*, page 39.

This table summarizes the different memory models:

| Memory model | Default memory attribute | Default data pointer | Max. stack range | Placement of data |
|-----------------|--------------------------|-------------------------|------------------|-------------------------|
| Tiny | tiny | tiny | ≤ 256 bytes | -v0, -v1, -v2, -v3, -v5 |
| Small | near | near | ≤ 64 Kbytes | -v1, -v3, -v4, -v5, -v6 |
| Large | far | far | ≤ 16 Mbytes | -v4, -v6 |
| Huge | huge | huge | ≤ 16 Mbytes | -v4, -v6 |

Table 4: Memory model characteristics



See the *IAR Embedded Workbench*® *IDE Project Management and Building Guide* for information about setting options in the IDE.



Use the --memory_model option to specify the memory model for your project; see --memory model, -m, page 211.

Memory types

This section describes the concept of *memory types* used for accessing data by the compiler. It also discusses pointers in the presence of multiple memory types. For each memory type, the capabilities and limitations are discussed.

The compiler uses different memory types to access data that is placed in different areas of the memory. There are different methods for reaching memory areas, and they have different costs when it comes to code space, execution speed, and register usage. The access methods range from generic but expensive methods that can access the full memory space, to cheap methods that can access limited memory areas. Each memory type corresponds to one memory access method. If you map different memories—or part of memories—to memory types, the compiler can generate code that can access data efficiently.

For example, the memory accessible using the near memory access method is called memory of near type, or simply near memory.

By selecting a *memory model*, you have selected a default memory type that your application will use. However, it is possible to specify—for individual variables or pointers—different memory types. This makes it possible to create an application that can contain a large amount of data, and at the same time make sure that variables that are used often are placed in memory that can be efficiently accessed.

USING DATA MEMORY ATTRIBUTES

The compiler provides a set of *extended keywords*, which can be used as *data memory attributes*. These keywords let you override the default memory type for individual data

objects, which means that you can place data objects in other memory areas than the default memory. This also means that you can fine-tune the access method for each individual data object, which results in smaller code size.

This table summarizes the available memory attributes:

| Memory | Pointer | Memory | | Max object |
|-----------|--------------------|---------------------|---|-----------------------|
| attribute | size | Address range space | | size |
| tiny | I byte | Data | 0x0-0xFF | 128 bytes |
| near | 2 bytes | Data | 0x0-0xFFFF | 32 Kbytes |
| far | 3 bytes | Data | $0 \times 0 - 0 \times FFFFFFFFFFFFFFFFFFFFFFFFFFFF$ | 32 Kbytes |
| huge | 3 bytes | Data | 0x0-0xFFFFFF | 8 Mbytes |
| tinyflash | I byte | Code | 0x0-0xFF | 128 bytes |
| flash | 2 bytes | Code | 0x0-0xFFFF | 32 Kbytes |
| farflash | 3 bytes | Code | $0 \times 0 - 0 \times FFFFFFFFFFFFFFFFFFFFFFFFFFFF$ | 32 Kbytes |
| hugeflash | 3 bytes | Code | 0x0-0xFFFFFF | 8 Mbytes |
| eeprom | I bytes | EEPROM | 0x0-0xFF | 128 bytes |
| eeprom | 2 bytes | EEPROM | 0x0-0xFFFF | 32 Kbytes |
| io | N/A | I/O space | 0x0-0x3F | 4 bytes |
| io | N/A | Data | 0x60-0xFF | 4 bytes |
| ext_io | N/A | Data | 0x100-0xFFFF | 4 bytes |
| generic | 2 bytes 3 bytes | Data or Code | The most significant bit (MSB) determines whether this pointer points to code space (I) or data space (0). The small generic pointer is generated for the processor options $-\mathrm{v}0$ and $-\mathrm{v}1$. | 32 Kbytes 8 Mbytes |
| regvar | N/A | Data | 0x4-0x0F | 4 bytes |

Table 5: Memory types and their corresponding memory attributes

The keywords are only available if language extensions are enabled in the compiler.



In the IDE, language extensions are enabled by default.



Use the -e compiler option to enable language extensions. See -e, page 203 for additional information.

For more information about each keyword, see *Descriptions of extended keywords*, page 250.

Syntax

The keywords follow the same syntax as the type qualifiers const and volatile. The memory attributes are *type attributes* and therefore they must be specified both when variables are defined and in the declaration, see *General syntax rules for extended keywords*, page 245.

The following declarations place the variables i and j in EEPROM memory. The variables k and l will also be placed in EEPROM memory. The position of the keyword does not have any effect in this case:

```
__eeprom int i, j;
int __eeprom k, 1;
```

Note that the keyword affects both identifiers. If no memory type is specified, the default memory type is used.

The #pragma type_attribute directive can also be used for specifying the memory attributes. The advantage of using pragma directives for specifying keywords is that it offers you a method to make sure that the source code is portable. Refer to the chapter *Pragma directives* for details about how to use the extended keywords together with pragma directives.

Type definitions

Storage can also be specified using type definitions. These two declarations are equivalent:

```
/* Defines via a typedef */
typedef char __far Byte;
typedef Byte *BytePtr;
Byte aByte;
BytePtr aBytePointer;

/* Defines directly */
__far char aByte;
char __far *aBytePointer;
```

POINTERS AND MEMORY TYPES

Pointers are used for referring to the location of data. In general, a pointer has a type. For example, a pointer that has the type int * points to an integer.

In the compiler, a pointer also points to some type of memory. The memory type is specified using a keyword before the asterisk. For example, a pointer that points to an integer stored in far memory is declared by:

```
int __far * MyPtr;
```

Note that the location of the pointer variable MyPtr is not affected by the keyword. In the following example, however, the pointer variable MyPtr2 is placed in tiny memory. Like MyPtr, MyPtr2 points to a character in far memory.

```
char __far * __tiny MyPtr2;
```

Whenever possible, pointers should be declared without memory attributes. For example, the functions in the standard library are all declared without explicit memory types.

Differences between pointer types

A pointer must contain information needed to specify a memory location of a certain memory type. This means that the pointer sizes are different for different memory types.

In the compiler, it is illegal to convert pointers between different types without explicit casts. For more information, see *Casting*, page 238.

For more information about pointers, see *Pointer types*, page 237.

STRUCTURES AND MEMORY TYPES

For structures, the entire object is placed in the same memory type. It is not possible to place individual structure members in different memory types.

In the example below, the variable gamma is a structure placed in eeprom memory.

```
struct MyStruct
{
   int mAlpha;
   int mBeta;
};

__eeprom struct MyStruct gamma;

This declaration is incorrect:

struct MyStruct
{
   int mAlpha;
   __eeprom int mBeta; /* Incorrect declaration */
};
```

MORE EXAMPLES

The following is a series of examples with descriptions. First, some integer variables are defined and then pointer variables are introduced. Finally, a function accepting a pointer to an integer in flash memory is declared. The function returns a pointer to an integer in

eeprom memory. It makes no difference whether the memory attribute is placed before or after the data type.

| int MyA; | A variable defined in default memory. |
|---|---|
| <pre>intfar MyB;</pre> | A variable in far memory. |
| eeprom int MyC; | A variable in eeprom memory. |
| int * MyD; | A pointer stored in default memory. The pointer points to an integer in default memory. |
| intfar * MyE; | A pointer stored in default memory. The pointer points to an integer in far memory. |
| <pre>intfar *eeprom MyF;</pre> | A pointer stored in eeprom memory pointing to an integer stored in far memory. |
| <pre>inteeprom * MyFunction(intfar *);</pre> | A declaration of a function that takes a parameter which is a pointer to an integer stored in far memory. The function returns a pointer to an integer stored in eeprom memory. |

C++ and memory types

Instances of C++ classes are placed into a memory (just like all other objects) either implicitly, or explicitly using memory type attributes or other IAR language extensions. Non-static member variables, like structure fields, are part of the larger object and cannot be placed individually into specified memories.

In non-static member functions, the non-static member variables of a C++ object can be referenced via the this pointer, explicitly or implicitly. The this pointer is of the default data pointer type unless class memory is used, see *Using IAR attributes with Classes*, page 145.

Static member variables can be placed individually into a data memory in the same way as free variables.

All member functions except for constructors and destructors can be placed individually into a code memory in the same way as free functions.

For more information about C++ classes, see *Using IAR attributes with Classes*, page 145.

Auto variables—on the stack

Variables that are defined inside a function—and not declared static—are named *auto variables* by the C standard. A few of these variables are placed in processor registers; the rest are placed on the stack. From a semantic point of view, this is equivalent. The main differences are that accessing registers is faster, and that less memory is required compared to when variables are located on the stack.

Auto variables can only live as long as the function executes; when the function returns, the memory allocated on the stack is released.

THE STACK

The stack can contain:

- Local variables and parameters not stored in registers
- Temporary results of expressions
- The return value of a function (unless it is passed in registers)
- · Processor state during interrupts
- Processor registers that should be restored before the function returns (callee-save registers).

The stack is a fixed block of memory, divided into two parts. The first part contains allocated memory used by the function that called the current function, and the function that called it, etc. The second part contains free memory that can be allocated. The borderline between the two areas is called the *top of stack* and is represented by the stack pointer, which is a dedicated processor register. Memory is allocated on the stack by moving the stack pointer.

A function should never refer to the memory in the area of the stack that contains free memory. The reason is that if an interrupt occurs, the called interrupt function can allocate, modify, and—of course—deallocate memory on the stack.

Advantages

The main advantage of the stack is that functions in different parts of the program can use the same memory space to store their data. Unlike a heap, a stack will never become fragmented or suffer from memory leaks.

It is possible for a function to call itself either directly or indirectly—a *recursive function*—and each invocation can store its own data on the stack.

Potential problems

The way the stack works makes it impossible to store data that is supposed to live after the function returns. The following function demonstrates a common programming mistake. It returns a pointer to the variable x, a variable that ceases to exist when the function returns.

```
int *MyFunction()
{
  int x;
  /* Do something here. */
  return &x; /* Incorrect */
}
```

Another problem is the risk of running out of stack. This will happen when one function calls another, which in turn calls a third, etc., and the sum of the stack usage of each function is larger than the size of the stack. The risk is higher if large data objects are stored on the stack, or when recursive functions are used.

Dynamic memory on the heap

Memory for objects allocated on the heap will live until the objects are explicitly released. This type of memory storage is very useful for applications where the amount of data is not known until runtime.

In C, memory is allocated using the standard library function malloc, or one of the related functions calloc and realloc. The memory is released again using free.

In C++, a special keyword, new, allocates memory and runs constructors. Memory allocated with new must be released using the keyword delete.

The compiler supports heaps in both tiny, near, far, and huge memory. For more information about this, see *The heap*, page 64.

Potential problems

Applications that are using heap-allocated objects must be designed very carefully, because it is easy to end up in a situation where it is not possible to allocate objects on the heap.

The heap can become exhausted if your application uses too much memory. It can also become full if memory that no longer is in use was not released.

For each allocated memory block, a few bytes of data for administrative purposes is required. For applications that allocate a large number of small blocks, this administrative overhead can be substantial.

There is also the matter of *fragmentation*; this means a heap where small sections of free memory is separated by memory used by allocated objects. It is not possible to allocate a new object if no piece of free memory is large enough for the object, even though the sum of the sizes of the free memory exceeds the size of the object.

45

Dynamic memory on the heap

Unfortunately, fragmentation tends to increase as memory is allocated and released. For this reason, applications that are designed to run for a long time should try to avoid using memory allocated on the heap.

Functions

This chapter contains information about functions. It gives a brief overview of function-related extensions—mechanisms for controlling functions—and describes some of these mechanisms in more detail.

Function-related extensions

In addition to supporting Standard C, the compiler provides several extensions for writing functions in C. Using these, you can:

- Control the storage of functions in memory
- Use primitives for interrupts, concurrency, and OS-related programming
- Facilitate function optimization
- Access hardware features.

The compiler uses compiler options, extended keywords, pragma directives, and intrinsic functions to support this.

For more information about optimizations, see *Efficient coding for embedded applications*, page 159. For information about the available intrinsic functions for accessing hardware operations, see the chapter *Intrinsic functions*.

Function storage

USING FUNCTION MEMORY ATTRIBUTES

It is possible to override the default placement for individual functions. Use the appropriate *function memory attribute* to specify this. These attributes are available:

| Memory attribute | Address range | Pointer size | Used in processor option |
|------------------|------------------------|--------------|--------------------------|
| nearfunc | 0-0x1FFFE (128 Kbytes) | 16 bits | -v0, -v1, -v2, -v3, -v4 |
| farfunc | 0-0x7FFFFE (8 Mbytes) | 24 bits | -v5, -v6 |

Table 6: Function memory attributes

When using the -v5 or the -v6 option, it is possible, for individual functions, to override the $__$ farfunc attribute and instead use the $__$ nearfunc attribute. The default

memory can be overridden by explicitly specifying a memory attribute in the function declaration or by using the #pragma type_attribute directive:

```
#pragma type_attribute=__nearfunc
void MyFunc(int i)
{
   ...
}
```

It is possible to call a __nearfunc function from a __farfunc function and vice versa. Only the size of the function pointer is affected.

It is possible to place functions into named segments using either the @ operator or the #pragma location directive. For more information, see *Controlling data and function placement in memory*, page 164.

Pointers with function memory attributes have restrictions in implicit and explicit casts between pointers and between pointers and integer types. For information about the restrictions, see *Casting*, page 238.

For syntax information and for more information about each attribute, see the chapter *Extended keywords*.

Primitives for interrupts, concurrency, and OS-related programming

The IAR C/C++ Compiler for AVR provides the following primitives related to writing interrupt functions, concurrent functions, and OS-related functions:

- The extended keywords __interrupt, __nested, __task, and __monitor
- The pragma directive #pragma vector
- The intrinsic functions __enable_interrupt and __disable_interrupt.

INTERRUPT FUNCTIONS

In embedded systems, using interrupts is a method for handling external events immediately; for example, detecting that a button was pressed.

Interrupt service routines

In general, when an interrupt occurs in the code, the microcontroller immediately stops executing the code it runs, and starts executing an interrupt routine instead. It is important that the environment of the interrupted function is restored after the interrupt is handled (this includes the values of processor registers and the processor status register). This makes it possible to continue the execution of the original code after the code that handled the interrupt was executed.

The AVR microcontroller supports many interrupt sources. For each interrupt source, an interrupt routine can be written. Each interrupt routine is associated with a vector number, which is specified in the AVR microcontroller documentation from the chip manufacturer. If you want to handle several different interrupts using the same interrupt routine, you can specify several interrupt vectors.

Interrupt vectors and the interrupt vector table

For the AVR microcontroller, the interrupt vector table always starts at the address 0×0 and is placed in the INTVEC segment. The interrupt vector is the offset into the interrupt vector table. The interrupt vector table contains pointers to interrupt routines, including the reset routine. The AT90S80515 device has 13 interrupt vectors and one reset vector. For this reason, you should specify 14 interrupt vectors, each of two bytes.

If a vector is specified in the definition of an interrupt function, the processor interrupt vector table is populated. It is also possible to define an interrupt function without a vector. This is useful if an application is capable of populating or changing the interrupt vector table at runtime.

The header file iodevice.h, where device corresponds to the selected device, contains predefined names for the existing interrupt vectors.

Defining an interrupt function—an example

To define an interrupt function, the __interrupt keyword and the #pragma vector directive can be used. For example:

```
#pragma vector = 0x14
__interrupt void MyInterruptRoutine(void)
{
    /* Do something */
}
```

Note: An interrupt function must have the return type void, and it cannot specify any parameters.

MONITOR FUNCTIONS

A monitor function causes interrupts to be disabled during execution of the function. At function entry, the status register is saved and interrupts are disabled. At function exit, the original status register is restored, and thereby the interrupt status that existed before the function call is also restored.

To define a monitor function, you can use the __monitor keyword. For more information, see *monitor*, page 257.



Avoid using the __monitor keyword on large functions, since the interrupt will otherwise be turned off for too long.

Example of implementing a semaphore in C

In the following example, a binary semaphore—that is, a mutex—is implemented using one static variable and two monitor functions. A monitor function works like a critical region, that is no interrupt can occur and the process itself cannot be swapped out. A semaphore can be locked by one process, and is used for preventing processes from simultaneously using resources that can only be used by one process at a time, for example a USART. The __monitor keyword assures that the lock operation is atomic; in other words it cannot be interrupted.

```
/* This is the lock-variable. When non-zero, someone owns it. */
static volatile unsigned int sTheLock = 0;
/* Function to test whether the lock is open, and if so take it.
 * Returns 1 on success and 0 on failure.
 monitor int TryGetLock(void)
 if (sTheLock == 0)
    /* Success, nobody has the lock. */
    sTheLock = 1;
   return 1;
 }
 else
    /* Failure, someone else has the lock. */
   return 0;
 }
/* Function to unlock the lock.
 * It is only callable by one that has the lock.
__monitor void ReleaseLock(void)
 sTheLock = 0;
/* Function to take the lock. It will wait until it gets it. */
```

```
void GetLock(void)
{
  while (!TryGetLock())
  {
     /* Normally, a sleep instruction is used here. */
  }
}

/* An example of using the semaphore. */

void MyProgram(void)
  {
    GetLock();
    /* Do something here. */
    ReleaseLock();
}
```

C++ AND SPECIAL FUNCTION TYPES

C++ member functions can be declared using special function types. However, this restriction applies: Interrupt member functions must be static. When a non-static member function is called, it must be applied to an object. When an interrupt occurs and the interrupt function is called, there is no object available to apply the member function to.

Primitives for interrupts, concurrency, and OS-related programming

Placing code and data

This chapter describes how the linker handles memory and introduces the concept of segments. It also describes how they correspond to the memory and function types, and how they interact with the runtime environment. The methods for placing segments in memory, which means customizing a linker configuration file, are described.

The intended readers of this chapter are the system designers that are responsible for mapping the segments of the application to appropriate memory areas of the hardware system.

Segments and memory

In an embedded system, there might be many different types of physical memory. Also, it is often critical *where* parts of your code and data are located in the physical memory. For this reason it is important that the development tools meet these requirements.

WHAT IS A SEGMENT?

A *segment* is a container for pieces of data or code that should be mapped to a location in physical memory. Each segment consists of one or more *segment parts*. Normally, each function or variable with static storage duration is placed in a separate segment part. A segment part is the smallest linkable unit, which allows the linker to include only those segment parts that are referred to. A segment can be placed either in RAM or in ROM. Segments that are placed in RAM generally do not have any content, they only occupy space.

The compiler has several predefined segments for different purposes. Each segment is identified by a name that typically describes the contents of the segment, and has a *segment memory type* that denotes the type of content. In addition to the predefined segments, you can also define your own segments.

At compile time, the compiler assigns code and data to the various segments. The IAR XLINK Linker is responsible for placing the segments in the physical memory range, in accordance with the rules specified in the linker configuration file. Ready-made linker configuration files are provided, but, if necessary, they can be modified according to the requirements of your target system and application. It is important to remember that, from the linker's point of view, all segments are equal; they are simply named parts of memory.

Segment memory type

Each segment always has an associated segment memory type. In some cases, an individual segment has the same name as the segment memory type it belongs to, for example CODE. Make sure not to confuse the segment name with the segment memory type in those cases.

By default, the compiler uses these XLINK segment memory types:

| Segment memory type | Description |
|---------------------|---------------------------|
| CODE | For executable code |
| DATA | For data placed in RAM |
| XDATA | For data placed in EEPROM |

Table 7: XLINK segment memory types

XLINK supports several other segment memory types than the ones described above. However, they exist to support other types of microcontrollers.

For more information about individual segments, see the chapter Segment reference.

Placing segments in memory

The placement of segments in memory is performed by the IAR XLINK Linker. It uses a linker configuration file that contains command line options which specify the locations where the segments can be placed, thereby assuring that your application fits on the target chip. To use the same source code with different derivatives, just rebuild the code with the appropriate linker configuration file.

In particular, the linker configuration file specifies:

- The placement of segments in memory
- The maximum stack size
- The maximum heap size.

This section describes the the most common linker commands and how to customize the linker configuration file to suit the memory layout of your target system. For showing the methods, fictitious examples are used.

CUSTOMIZING THE LINKER CONFIGURATION FILE

The config directory contains ready-made linker configuration files (filename extension xc1). The files contain the information required by the linker, and are ready to be used. The only change you will normally have to make to the supplied linker configuration file is to customize it so it fits the target system memory map. If, for

example, your application uses additional external RAM, you must add details about the external RAM memory area.

As an example, we can assume that the target system has this memory layout:

| Range | Туре |
|---------------|--------------|
| 0x100-0xFFF | RAM |
| 0x0-0x1FFFF | Flash |
| 0x0-0xFFF | EEPROM |
| 0x1000-0xFFFF | External RAM |

Table 8: Memory layout of a target system (example)

The flash memory can be used for storing CODE segment memory types. The RAM memory can contain segments of DATA type. The main purpose of customizing the linker configuration file is to verify that your application code and data do not cross the memory range boundaries, which would lead to application failure.

Remember not to change the original file. We recommend that you make a copy in the working directory, and modify the copy instead.

The contents of the linker configuration file

Among other things, the linker configuration file contains three different types of XLINK command line options:

- The CPU used:
 - -ca90

This specifies your target microcontroller.

- Definitions of constants used in the file. These are defined using the XLINK option
 -D.
- The placement directives (the largest part of the linker configuration file). Segments can be placed using the ¬Z and ¬P options. The former will place the segment parts in the order they are found, while the latter will try to rearrange them to make better use of the memory. The ¬P option is useful when the memory where the segment should be placed is not continuous.

In the linker configuration file, all numbers are specified in hexadecimal format. However, neither the prefix $0 \times$ nor the suffix h is used.

Note: The supplied linker configuration file includes comments explaining the contents.

See the IAR Linker and Library Tools Reference Guide for more information.

Using the -Z command for sequential placement

Use the -Z command when you must keep a segment in one consecutive chunk, when you must preserve the order of segment parts in a segment, or, more unlikely, when you must put segments in a specific order.

The following illustrates how to use the -z command to place the segment MYSEGMENTA followed by the segment MYSEGMENTB in CODE memory (that is, flash memory) in the memory range 0x1000-0xCFFF.

```
-Z (CODE) MYSEGMENTA, MYSEGMENTB=1000-CFFF
```

To place two segments of different types consecutively in the same memory area, do not specify a range for the second segment. In the following example, the MYSEGMENTA segment is first located in memory. Then, the rest of the memory range could be used by MYCODE.

```
-Z(CODE)MYSEGMENTA=1000-CFFF
```

 $-\mathbb{Z}$ (CODE) MYCODE

Two memory ranges can overlap. This allows segments with different placement requirements to share parts of the memory space; for example:

```
-Z(CODE)MYSMALLSEGMENT=1000-20FF
-Z(CODE)MYLARGESEGMENT=1000-CFFF
```



Even though it is not strictly required, make sure to always specify the end of each memory range. If you do this, the IAR XLINK Linker will alert you if your segments do not fit in the available memory.

Using the -P command for packed placement

The -P command differs from -Z in that it does not necessarily place the segments (or segment parts) sequentially. With -P it is possible to put segment parts into holes left by earlier placements.

The following example illustrates how the XLINK -P option can be used for making efficient use of the memory area. This command will place the data segment MYDATA in DATA memory (that is, in RAM) in a fictitious memory range:

```
-P(DATA)MYDATA=0-FFF,1000-1FFF
```

If your application has an additional RAM area in the memory range 0xF000-0xF7FF, you can simply add that to the original definition:

```
-P(DATA)MYDATA=0-FFF,1000-1FFF,F000-F7FF
```

The linker can then place some parts of the MYDATA segment in the first range, and some parts in the second range. If you had used the -z command instead, the linker would have to place all segment parts in the same range.

Note: Copy initialization segments—*BASENAME_I* and *BASENAME_ID*—must be placed using -z.

Data segments

This section contains descriptions of the segments used for storing the different types of data: static, stack, heap, and located.

To get a clear understanding about how the data segments work, you must be familiar with the different memory types and the different data models available in the compiler. For information about these details, see the chapter *Data storage*.

STATIC MEMORY SEGMENTS

Static memory is memory that contains variables that are global or declared static, see the chapter *Data storage*. Variables declared static can be divided into these categories:

- Variables that are initialized to a non-zero value
- Variables that are initialized to zero
- Variables that are located by use of the @ operator or the #pragma location directive
- Variables that are declared as const and therefore can be stored in ROM
- Variables defined with the __no_init keyword, meaning that they should not be initialized at all.

For the static memory segments it is important to be familiar with:

- The segment naming
- How the memory types correspond to segment groups and the segments that are part
 of the segment groups
- · Restrictions for segments holding initialized data
- The placement and size limitation of the segments of each group of static memory segments.

Segment naming

The names of the segments consist of two parts—the segment group name and a suffix—for instance, NEAR_Z. There is a segment group for each memory type, where each segment in the group holds different categories of declared data. The names of the segment groups are derived from the memory type and the corresponding keyword, for

example NEAR and __near. The following table summarizes the memory types and the corresponding segment groups:

| Memory type | Segment group | Memory range |
|-------------|---------------|---|
| tiny | TINY | 0x0-0xFF |
| near | NEAR | 0x0-0xFFFF |
| far | FAR | $0 \times 0 - 0 \times FFFFFF$ |
| huge | HUGE | $0 \times 0 - 0 \times FFFFFF$ |
| EEPROM | EEPROM | 0x0-0xFF or $0x0-0xFFFF$, depending on your device |

Table 9: Memory types with corresponding segment groups

Some of the declared data is placed in non-volatile memory, for example flash memory, and some of the data is placed in RAM. For this reason, it is also important to know the XLINK segment memory type of each segment. For more information about segment memory types, see *Segment memory type*, page 54.

This table summarizes the different suffixes, which XLINK segment memory type they are, and which category of declared data they denote:

| Categories of declared data | Suffix | Segment memory type |
|-----------------------------|--------|---------------------|
| Non-initialized data | N | DATA |
| Zero-initialized data | Z | DATA |
| Non-zero initialized data | I | DATA |
| Initializers for the above | ID | CODE |
| Constants | С | DATA |
| Persistent data | P | DATA |
| Data placed in flash memory | F | CODE |

Table 10: Segment name suffixes

For information about all supported segments, see Summary of segments, page 317.

Examples

These examples demonstrate how declared data is assigned to specific segments:

```
__near int j;
__near int i = 0;
```

The near variables that are to be initialized to zero when the system starts are placed in the segment NEAR_Z.

```
__no_init __near int j; The near non-initialized variables are placed in the segment NEAR_N.

__near int j = 4; The near non-zero initialized variables are placed in the segment NEAR_I in RAM, and the corresponding initializer data in the segment NEAR_ID in CODE.
```

Initialized data

When an application is started, the system startup code initializes static and global variables in these steps:

- I It clears the memory of the variables that should be initialized to zero.
- 2 It initializes the non-zero variables by copying a block of CODE to the location of the variables in RAM. This means that the data in the CODE segment with the suffix ID is copied to the corresponding I segment.

This works when both segments are placed in continuous memory. However, if one of the segments is divided into smaller pieces, it is important that:

- The other segment is divided in exactly the same way
- It is legal to read and write the memory that represents the gaps in the sequence.

For example, if the segments are assigned these ranges, the copy will fail:

```
NEAR_I 0x1000-0x10FF and 0x1200-0x12FF
NEAR_ID 0x4000-0x41FF
```

However, in the following example, the linker will place the content of the segments in identical order, which means that the copy will work appropriately:

```
NEAR_I 0x1000-0x10FF and 0x1200-0x12FF
NEAR_ID 0x4000-0x40FF and 0x4200-0x42FF
```

Note that the gap between the ranges will also be copied. Note also that the NEAR_ID segment holding the initializers is always located in flash memory and that these initializers are only used once, that is before reaching the main function.

3 Finally, global C++ objects are constructed, if any.

Initialization of local aggregates at function invocation

Initialized aggregate auto variables—struct, union, and array variables local to a function—have the initial values in blocks of memory. As an auto variable is allocated either in registers or on the stack, the initialization has to take place every time the function is called. Assume the following example:

```
void f()
{
  struct block b = { 3, 4, 2, 3, 6634, 234 };
  ...
}
```

The initializers are copied to the b variable allocated on the stack each time the function is entered.

The initializers can either come from the code memory space (flash) or from the data memory space (optional external ROM). By default, the initializers are located in segments with the suffix _c and these segments are copied from external ROM to the stack.

If you use either the -y option or the --initializers_in_flash option, the aggregate initializers are located in segments with the suffix _F, which are copied from flash memory to the stack. The advantage of storing these initializers in flash is that valuable data space is not wasted. The disadvantage is that copying from flash is slower.

Initialization of constant objects

There are different ways of initializing constant objects.

By default, constant objects are placed in segments with the suffix _C, which are located in the optional external ROM that resides in the data memory space. The reason for this is that it must be possible for a default pointer—a pointer without explicit memory attributes—to point to the object, and a default pointer can only point to the data memory space.

However, if you do not have any external ROM in the data memory space, and for single chip applications you most likely do not have it, the constant objects have to be placed in RAM and initialized as any other non-constant variables. To achieve this, use the -y option, which means the objects are placed in segments with the suffix _ID.

If you want to place an object in flash memory, you can use any of the memory attributes __tinyflash, __flash, __farflash, or __hugeflash. The object becomes a flash object, which means you cannot take the address of it and store it in a default pointer. However, it is possible to store the address in either a __flash pointer or a __generic pointer, though neither of these are default pointers. Note that if you attempt to take the address of a constant __flash object and use it as a default pointer object, the compiler will issue an error. If you make an explicit cast of the object to a default pointer object,

the error message disappears, instead there will be problems at runtime as the cast cannot copy the object from the flash memory to the data memory.

To access strings located in flash memory, you must use alternative library routines that expect flash strings. A few such alternative functions are provided—they are declared in the pgmspace.h header file. They are flash alternatives for some common C library functions with an extension _P. For your own code, you can always use the __flash keyword when passing the strings between functions. For reference information about the alternative functions, see *AVR-specific library functions*, page 310.

Data segments for static memory in the default linker configuration file

As described in the section, static data can be placed in many different segments depending on the application requirements and your target system. In the linker configuration file the segment definitions can look like this:

```
/* First, the segments to be placed in ROM are defined. */
-Z(CODE)TINY_F=0-FF
-Z(CODE)NEAR_F=0-1FF
-Z(CODE)TINY_ID,NEAR_ID=0-1FFF

/* Then, the RAM data segments are defined. */
-Z(DATA)TINY_I,TINY_Z,TINY_N=60-FF
-Z(DATA)NEAR_I,NEAR_Z=60-25F

/* Then, the segments to be placed in external EPROM are defined.
*/
-Z(DATA)NEAR_C=EXT_EPROM_BASE:+_EXT_EPROM_SIZE
```

* The _EXT_EPROM_BASE and _EXT_EPROM_SIZE symbols are defined in the linker command file template, where they have the value 0. If you want to use those symbols, you must provide values that suit the hardware. This method can also be used for placing other types of objects in the external memory space. */

THE STACK

The stack is used by functions to store variables and other information that is used locally by functions, see the chapter *Data storage*. It is a continuous block of memory pointed to by the processor stack pointer register Y.

The data segment used for holding the stack is called CSTACK. The system startup code initializes the stack pointer to the end of the stack segment.

If external SRAM is available it is possible to place the stack there. However, the external memory is slower than the internal stack so moving it to external memory will decrease the performance.

Allocating a memory area for the stack is done differently using the command line interface as compared to when using the IDE.



Stack size allocation in the IDE

Choose Project>Options. In the General Options category, click the Stack/Heap tab.

Add the required stack size in the Stack size text box.



Stack size allocation from the command line

The size of the CSTACK segment is defined in the linker configuration file.

The default linker file sets up a constant representing the size of the stack, at the beginning of the linker file:

-D_CSTACK_SIZE=size

Note: This line can be prefixed with the comment character //. To make the directive take effect, remove the comment character.

Specify an appropriate size for your application. Note that the size is written hexadecimally without the 0x notation.





Placement of stack segment

Further down in the linker file, the actual stack segment is defined in the memory area available for the stack:

-Z(DATA)CSTACK+ CSTACK SIZE=60-25F

Note: This range does not specify the size of the stack; it specifies the range of the available memory.



Stack size considerations

The compiler uses the internal data stack, CSTACK, for a variety of user program operations, and the required stack size depends heavily on the details of these operations. If the given stack size is too large, RAM is wasted. If the given stack size is too small, two things can happen, depending on where in memory you located your stack. Both alternatives are likely to result in application failure. Either program variables will be overwritten, leading to undefined behavior, or the stack will fall outside of the memory area, leading to an abnormal termination of your application.

THE RETURN ADDRESS STACK

The return address stack is used for storing the return address when a CALL, RCALL, ICALL, or EICALL instruction is executed. Each call will use two or three bytes of return address stack. An interrupt will also place a return address on this stack.

The data segment used for holding the return address stack is called RSTACK.

To determine the size of the return address stack, see *Stack size considerations*, page 62. Notice however that if the cross-call optimization has been used (-z9 without --no_cross_call), the value can be off by as much as a factor of six depending on how many times the cross-call optimizer has been run (--cross_call_passes). Each cross-call pass adds one level of calls, for example, two cross-call passes might result in a tripled stack usage.

If external SRAM is available, it is possible to place the stack there. However, the external memory is slower than the internal memory so moving the stacks to external memory will normally decrease the system performance; see *--enable_external_bus*, page 204.

Allocating a memory area for the stack is done differently using the command line interface compared to when using the IDE.



RSTACK size allocation in the IDE

Choose Project>Options. In the General Options category, click the Stack/Heap tab.

Add the required stack size in the **Return address stack size** text box.



RSTACK size allocation from the command line

The size of the RSTACK segment is defined in the linker configuration file.

The default linker file sets up a constant representing the size of the stack, at the beginning of the linker file:

-D_RSTACK_SIZE=size

Specify an appropriate size for your application. Note that the size is written hexadecimally without the 0x notation.





Placement of RSTACK segment

Further down in the linker file, the actual stack segment is defined in the memory area available for the stack:

-Z(DATA)RSTACK+_RSTACK_SIZE=60-25F

Note: This range does not specify the size of the stack; it specifies the range of the available memory.

THE HEAP

The heap contains dynamic data allocated by the C function malloc (or one of its relatives) or the C++ operator new.

If your application uses dynamic memory allocation, you should be familiar with:

- The linker segment used for the heap, which differs between the DLIB and the CLIB runtime environment
- The steps involved for allocating the heap size, which differs depending on which build interface you are using
- The steps involved for placing the heap segments in memory.

Heap segments in DLIB

To access a heap in a specific memory, use the appropriate memory attribute as a prefix to the standard functions malloc, free, calloc, and realloc, for example:

```
__near_malloc
```

If you use any of the standard functions without a prefix, the function will be mapped to the default memory type near.

Each heap will reside in a segment with the name _HEAP prefixed by a memory attribute, for example NEAR_HEAP.

For information about available heaps, see *Heaps*, page 98.

Heap segments in the CLIB runtime environment

The memory allocated to the heap is placed in the segment HEAP, which is only included in the application if dynamic memory allocation is actually used.



Heap size allocation in the IDE

Choose Project>Options. In the General Options category, click the Stack/Heap tab.

Add the required heap size in the **Heap size** text box.



Heap size allocation from the command line

The size of the heap segment is defined in the linker configuration file.

The default linker file sets up a constant, representing the size of the heap, at the beginning of the linker file:

- -D_TINY_HEAP_SIZE=size
- -D_NEAR_HEAP_SIZE=size
- -D_FAR_HEAP_SIZE=size
- $\verb|-D_HUGE_HEAP_SIZE| = size$

```
-D_HEAP_SIZE=size /* For CLIB */
```

These lines can be prefixed with the comment character // because the IDE controls the heap size allocation. To make the directive take effect, remove the comment character.

Specify the appropriate size for your application.



Placement of heap segment

The actual heap segment is allocated in the memory area available for the heap:

```
-Z(DATA)HEAP+_TINY_HEAP_SIZE=60-25F
```

Note: This range does not specify the size of the heap; it specifies the range of the available memory.

Use the same method for all used heaps.



Heap size and standard I/O

If you have excluded FILE descriptors from the DLIB runtime environment, like in the normal configuration, there are no input and output buffers at all. Otherwise, like in the full configuration, be aware that the size of the input and output buffers is set to 512 bytes in the stdio library header file. If the heap is too small, I/O will not be buffered, which is considerably slower than when I/O is buffered. If you execute the application using the simulator driver of C-SPY, you are not likely to notice the speed penalty, but it is quite noticeable when the application runs on an AVR microcontroller. If you use the standard I/O library, you should set the heap size to a value which accommodates the needs of the standard I/O buffer.

LOCATED DATA

A variable that is explicitly placed at an address, for example by using the #pragma location directive or the @ operator, is placed in the SEGMENT_AN segment. The individual segment part of the segment knows its location in the memory space, and it should not be specified in the linker configuration file.

USER-DEFINED SEGMENTS

If you create your own segments using the #pragma location directive or the @ operator, these segments must also be defined in the linker configuration file using the -Z or -P segment control directives.

Code segments

This section contains descriptions of the segments used for storing code, and the interrupt vector table. For information about all segments, see *Summary of segments*, page 317.

INTERRUPT AND RESET VECTORS

The interrupt vector table contains pointers to interrupt routines, including the reset routine. The table is placed in the segment INTVEC. The AT90S80515 device has 13 interrupt vectors and one reset vector. For this reason, you should specify 14 interrupt vectors, each of two bytes.

The linker directive would then look like this:

-Z(CODE)INTVEC=0-1B /* 14 interrupt vectors; 2 bytes each */

FUNCTIONS

Functions are placed in the CODE or FARCODE segmnts, depending on which -v processor option you are using. The -v option implicitly determines the default function memory attributes __nearfunc or __farfunc, which in turn determines the used segments for the functions. For information about which attribute is used by default for each -v option, see *Summary of processor configuration for -v*, page 31.

In the linker configuration file, it can look like this:

-Z(CODE)CODE=0-1FFF

Compiler-generated segments

The compiler uses a set of internally generated segments, which are used for storing information that is vital to the operation of the program.

- The SWITCH segment which contains data statements used in the switch library routines. These tables are encoded in such a way as to use as little space as possible.
- The INITTAB segment contains the segment initialization description blocks that
 are used by the __segment_init function which is called by CSTARTUP. This table
 consists of a number of SegmentInitBlock_Type objects. This type is declared in
 the segment_init.h file which is located in the avr\src\lib directory.

In the linker configuration file, it can look like this:

-Z (CODE) SWITCH, INITTAB=0-1FFF

C++ dynamic initialization

In C++, all global objects are created before the main function is called. The creation of objects can involve the execution of a constructor.

The DIFUNCT segment contains a vector of addresses that point to initialization code. All entries in the vector are called when the system is initialized.

For example:

-Z(CODE)DIFUNCT=0000-1FFFF

For additional information, see *DIFUNCT*, page 320.

Verifying the linked result of code and data placement

The linker has several features that help you to manage code and data placement, for example, messages at link time and the linker map file.

SEGMENT TOO LONG ERRORS AND RANGE ERRORS

All code or data that is placed in relocatable segments will have its absolute addresses resolved at link time. Note that it is not known until link time whether all segments will fit in the reserved memory ranges. If the contents of a segment do not fit in the address range defined in the linker configuration file, XLINK will issue a *segment too long* error.

Some instructions do not work unless a certain condition holds after linking, for example that a branch must be within a certain distance or that an address must be even. XLINK verifies that the conditions hold when the files are linked. If a condition is not satisfied, XLINK generates a *range error* or warning and prints a description of the error.

For more information about these types of errors, see the *IAR Linker and Library Tools Reference Guide*.

LINKER MAP FILE

XLINK can produce an extensive cross-reference listing, which can optionally contain the following information:

- A segment map which lists all segments in dump order
- A module map which lists all segments, local symbols, and entries (public symbols) for every module in the program. All symbols not included in the output can also be listed
- A module summary which lists the contribution (in bytes) from each module
- A symbol list which contains every entry (global symbol) in every module.





Use the option **Generate linker listing** in the IDE, or the option -x on the command line, and one of their suboptions to generate a linker listing.

Normally, XLINK will not generate an output file if any errors, such as range errors, occur during the linking process. Use the option **Range checks disabled** in the IDE, or the option $\neg R$ on the command line, to generate an output file even if a range error was encountered

For more information about the listing options and the linker listing, see the *IAR Linker* and *Library Tools Reference Guide*, and the *IAR Embedded Workbench*® *IDE Project Management and Building Guide*.

MANAGING MULTIPLE ADDRESS SPACES

Output formats that do not support more than one memory space—like MOTOROLA and INTEL-HEX—might require up to one output file per memory space. This causes no problems if you are only producing output to one memory space (flash), but if you also are placing objects in EEPROM or an external ROM in DATA memory space, the output format cannot represent this, and the linker issues this error message:

Error[e133]: The output format Format cannot handle multiple address spaces. Use format variants (-y -0) to specify which address space is wanted.

To limit the output to flash memory, make a copy of the linker configuration file for the device and memory model you are using, and put it in your project directory. Use this copy in your project and add this line at the end of the file:

```
-y(CODE)
```

To produce output for the other memory space(s), you must generate one output file per memory space (because the output format you chose does not support more than one memory space). Use the XLINK option -0 for this purpose.

For each additional output file, you must specify format, XLINK segment type, and file name. For example:

```
-Omotorola, (DATA) = external_rom.a90 -Omotorola, (XDATA) = eeprom.a90
```

Note: As a general rule, an output file is only necessary if you use non-volatile memory. In other words, output from the data space is only necessary if the data space contains external ROM.

The IAR Postlink utility

You can also use the IAR Postlink utility, delivered with the compiler. This application takes as input an object file (of the XLINK simple format) and extracts one or more of its XLINK segment types into one file (which can be in either Intel extended hex

format or Motorola S-record format). For example, it can put all code segments into one file, and all EEPROM segments into another.

See the postlink.htm document for more information about IAR Postlink.

Verifying the linked result of code and data placement

The DLIB runtime environment

This chapter describes the runtime environment in which an application executes. In particular, the chapter covers the DLIB runtime library and how you can optimize it for your application.

DLIB can be used with both the C and the C++ languages. CLIB, on the other hand, can only be used with the C language. For more information, see the chapter *The CLIB runtime environment*.

Introduction to the runtime environment

The runtime environment is the environment in which your application executes. The runtime environment depends on the target hardware, the software environment, and the application code.

RUNTIME ENVIRONMENT FUNCTIONALITY

The *runtime environment* supports Standard C and C++, including the standard template library. The runtime environment consists of the *runtime library*, which contains the functions defined by the C and the C++ standards, and include files that define the library interface (the system header files).

The runtime library is delivered both as prebuilt libraries and (depending on your product package) as source files, and you can find them in the product subdirectories avr\lib and avr\src\lib, respectively.

The runtime environment also consists of a part with specific support for the target system, which includes:

- Support for hardware features:
 - Direct access to low-level processor operations by means of *intrinsic* functions, such as functions for interrupt mask handling
 - Peripheral unit registers and interrupt definitions in include files
 - Special compiler support for accessing strings in flash memory, see AVR-specific library functions, page 310.
- Runtime environment support, that is, startup and exit code and low-level interface to some library functions.

- A floating-point environment (fenv) that contains floating-point arithmetics support, see fenv.h, page 307.
- Special compiler support, for instance functions for switch handling or integer arithmetics.

For more information about the library, see the chapter *Library functions*.

SETTING UP THE RUNTIME ENVIRONMENT

The IAR DLIB runtime environment can be used as is together with the debugger. However, to run the application on hardware, you must adapt the runtime environment. Also, to configure the most code-efficient runtime environment, you must determine your application and hardware requirements. The more functionality you need, the larger your code will become.

This is an overview of the steps involved in configuring the most efficient runtime environment for your target hardware:

- Choose which library to use—the DLIB or the CLIB library

 Use the compiler option --clib or --dlib, respectively. For more information about the libraries, see *Library overview*, page 301.
- Choose which runtime library object file to use
 The IDE will automatically choose a runtime library based on your project settings.
 If you build from the command line, you must specify the object file explicitly. See
 Using a prebuilt library, page 73.
- Choose which predefined runtime library configuration to use—Normal, or Full You can configure the level of support for certain library functionality, for example, locale, file descriptors, and multibyte characters. If you do not specify anything, a default library configuration file that matches the library object file is automatically used. To specify a library configuration explicitly, use the --dlib_config compiler option. See *Library configurations*, page 88.
- Optimize the size of the runtime library
 - You can specify the formatters used by the functions printf, scanf, and their variants, see *Choosing formatters for printf and scanf*, page 75. You can also specify the size and placement of the stacks and the heaps, see *The stack*, page 61, and *The heap*, page 64, respectively.
- Include debug support for runtime and I/O debugging
 The library offers C-SPY debug support and if you want to debug your application, you must choose to use it, see Application debug support, page 78
- Adapt the library functionality
 Some library functions must be customized to suit your target hardware, for example low-level functions for character-based I/O, environment functions, signal functions,

and time functions. This can be done without rebuilding the entire library, see *Overriding library modules*, page 81.

• Customize system initialization

It is likely that you need to customize the source code for system initialization, for example, your application might need to initialize memory-mapped special function registers, or omit the default initialization of data segments. You do this by customizing the routine <code>__low_level_init</code>, which is executed before the data segments are initialized. See *System startup and termination*, page 84 and *Customizing system initialization*, page 87.

• Configure your own library configuration files

In addition to the prebuilt library configurations, you can make your own library configuration, but that requires that you *rebuild* the library. This gives you full control of the runtime environment. See *Building and using a customized library*, page 82.

• Manage a multithreaded environment

In a multithreaded environment, you must adapt the runtime library to treat all library objects according to whether they are global or local to a thread. See *Managing a multithreaded environment*, page 98.

• Check module consistency

You can use runtime model attributes to ensure that modules are built using compatible settings, see *Checking module consistency*, page 103.

Using a prebuilt library

The prebuilt runtime libraries are configured for different combinations of these features:

- Type of library
- Processor option (-v)
- Memory model option (--memory_model)
- AVR enhanced core option (--enhanced_core)
- Small flash memory option (--64k_flash)
- 64-bit doubles option (--64bit_doubles)
- Library configuration—Normal, or Full.

CHOOSING A LIBRARY



The IDE will include the correct library object file and library configuration file based on the options you select. See the *IAR Embedded Workbench*® *IDE Project Management and Building Guide* for more information.



If you build your application from the command line, make the following settings:

- Specify which library object file to use on the XLINK command line, for instance: dlavr-3s-ec mul-64-f.r90
- If you do not specify a library configuration, the default will be used. However, you
 can specify the library configuration explicitly for the compiler:

```
--dlib_config C:\...\dlavr-3s-ec_mul-64-f.h
```

Note: All modules in the library have a name that starts with the character ? (question mark).

You can find the library object files and the library configuration files in the subdirectory avr\lib\dlib.

These are some examples of how to decode a library name:

| | Generic | Memory | | Small | 64-bit | Library |
|--------------------------|---------------------|--------|------|-------|--------|---------------|
| Library | processor option | model | Cara | | | configuration |
| dlavr-3s-ec_mul-sf-n.r90 | -v3 | Small | Х | Χ | | Normal |
| dlavr-3s-ec_mul-64-f.r90 | -v3 | Small | Χ | | Χ | Full |

Table 11: Prebuilt libraries

Library filename syntax

The names of the libraries are constructed in this way:

```
\label{library} $$\{1ibrary\} $$\{target\} - \{cpu\} - \{memModel\} - \{core\} - \{smallFlash\} - \{64BitDoubles\} - \{1ib\_config\} .r90$
```

where

| {library} | is dl for the IAR DLIB runtime environment |
|------------|--|
| {target} | is avr |
| {memModel} | is either t, s, 1, or h for Tiny, Small, Large, or Huge memory model, respectively |

| {core} | is ec_mul or ec_nomul when enhanced core is used depending on whether the MUL instruction is available or not, or xmega if the device is from the xmega family. If neither the enhanced core nor the xmega core is used, this value is not specified. |
|----------------|---|
| {smallFlash} | is sf when the small flash memory is available. When small flash memory is not available, this value is not specified |
| {64bitDoubles} | is 64 when 64-bit doubles are used. When 32-bit doubles are used, this value is not specified. |
| {lib_config} | is one of n or f for normal and full, respectively. |

Note: The library configuration file has the same base name as the library.

CUSTOMIZING A PREBUILT LIBRARY WITHOUT REBUILDING

The prebuilt libraries delivered with the compiler can be used as is. However, you can customize parts of a library without rebuilding it.

These items can be customized:

| Items that can be customized | Described in |
|-------------------------------------|---|
| Formatters for printf and scanf | Choosing formatters for printf and scanf, page 75 |
| Startup and termination code | System startup and termination, page 84 |
| Low-level input and output | Standard streams for input and output, page 89 |
| File input and output | File input and output, page 92 |
| Low-level environment functions | Environment interaction, page 95 |
| Low-level signal functions | Signal and raise, page 96 |
| Low-level time functions | Time, page 97 |
| Size of heaps, stacks, and segments | Placing code and data, page 53 |

Table 12: Customizable items

For information about how to override library modules, see *Overriding library modules*, page 81.

Choosing formatters for printf and scanf

To override the default formatter for all the printf- and scanf-related functions, except for wprintf and wscanf variants, you simply set the appropriate library options. This section describes the different options available.

Note: If you rebuild the library, you can optimize these functions even further, see *Configuration symbols for printf and scanf*, page 91.

CHOOSING A PRINTF FORMATTER

The printf function uses a formatter called _Printf. The full version is quite large, and provides facilities not required in many embedded applications. To reduce the memory consumption, three smaller, alternative versions are also provided in the Standard C/EC++ library.

This table summarizes the capabilities of the different formatters:

| Formatting capabilities | Tiny | Small/ SmallNoMb | Large/ LargeNoMb | Full/ FullNoMb |
|--|------|---------------------|---------------------|-------------------|
| Basic specifiers c, d, i, o, p, s, u, X, x, and % | Yes | Yes | Yes | Yes |
| Multibyte support | No | Yes/No | Yes/No | Yes/No |
| Floating-point specifiers a, and A | No | No | No | Yes |
| Floating-point specifiers e, E, f, F, g, and ${\tt G}$ | No | No | Yes | Yes |
| Conversion specifier n | No | No | Yes | Yes |
| Format flag +, -, #, 0, and space | No | Yes | Yes | Yes |
| Length modifiers h, 1, L, s, t, and ${\tt Z}$ | No | Yes | Yes | Yes |
| Field width and precision, including * | No | Yes | Yes | Yes |
| long long support | No | No | Yes | Yes |

Table 13: Formatters for printf

For information about how to fine-tune the formatting capabilities even further, see *Configuration symbols for printf and scanf*, page 91.



Specifying the print formatter in the IDE

To explicitly specify a formatter, choose **Project>Options** and select the **General Options** category. Select the appropriate option on the **Library options** page.



Specifying the printf formatter from the command line

To explicitly specify a formatter, add one of these lines in the linker configuration file you are using:

- -e_PrintfFull=_Printf
- -e PrintfFullNoMb= Printf
- -e_PrintfLarge=_Printf
- -e PrintfLargeNoMb= Printf

_e_PrintfSmall=_Printf

-e PrintfSmallNoMb= Printf

-e_PrintfTiny=_Printf

CHOOSING A SCANF FORMATTER

In a similar way to the printf function, scanf uses a common formatter, called _Scanf. The full version is quite large, and provides facilities that are not required in many embedded applications. To reduce the memory consumption, two smaller, alternative versions are also provided in the Standard C/C++ library.

This table summarizes the capabilities of the different formatters:

| Formatting capabilities | Small/ | Large/ | Full/ |
|--|-----------|------------------|----------|
| Torriacting capabilities | SmallNoMB | LargeNoMb | FullNoMb |
| Basic specifiers c, d, i, o, p, s, u, X, x, and % | Yes | Yes | Yes |
| Multibyte support | Yes/No | Yes/No | Yes/No |
| Floating-point specifiers a, and A | No | No | Yes |
| Floating-point specifiers e, E, f, F, g, and ${\tt G}$ | No | No | Yes |
| Conversion specifier n | No | No | Yes |
| Scan set [and] | No | Yes | Yes |
| Assignment suppressing * | No | Yes | Yes |
| long long support | No | No | Yes |

Table 14: Formatters for scanf

For information about how to fine-tune the formatting capabilities even further, see *Configuration symbols for printf and scanf*, page 91.



Specifying the scanf formatter in the IDE

To explicitly specify a formatter, choose **Project>Options** and select the **General Options** category. Select the appropriate option on the **Library options** page.



Specifying the scanf formatter from the command line

To explicitly specify a formatter, add one of these lines in the linker configuration file you are using:

- -e_ScanfFull=_Scanf
- -e_ScanfFullNoMb=_Scanf
- -e_ScanfLarge=_Scanf
- -e_ScanfLargeNoMb=_Scanf

_e_ScanfSmall=_Scanf _e_ScanfSmallNoMb=_Scanf

Application debug support

In addition to the tools that generate debug information, there is a debug version of the DLIB low-level interface (typically, I/O handling and basic runtime support). If your application uses this interface, you can either use the debug version of the interface or you must implement the functionality of the parts that your application uses.

INCLUDING C-SPY DEBUGGING SUPPORT

You can make the library provide different levels of debugging support—basic, runtime, and I/O debugging.

This table describes the different levels of debugging support:

| Debugging support | Linker option in the IDE | Linker command line option | Description |
|-----------------------|-----------------------------------|----------------------------------|---|
| Basic debugging | Debug information for C-SPY | -Fubrof | Debug support for C-SPY without any runtime support |
| Runtime debugging* | With runtime control modules | -r | The same as -Fubrof, but also includes debugger support for handling program abort, exit, and assertions. |
| I/O debugging* | With I/O emulation modules | -rt | The same as $-r$, but also includes debugger support for I/O handling, which means that $stdin$ and $stdout$ are redirected to the C-SPY Terminal I/O window, and that it is possible to access files on the host computer during debugging. |

Table 15: Levels of debugging support in runtime libraries

^{*} If you build your application project with this level of debug support, certain functions in the library are replaced by functions that communicate with the IAR C-SPY Debugger. For more information, see *The debug library functionality*, page 79.



In the IDE, choose **Project>Options>Linker**. On the **Output** page, select the appropriate **Format** option.

On the command line, use any of the linker options -r or -rt.

THE DEBUG LIBRARY FUNCTIONALITY

The debug library is used for communication between the application being debugged and the debugger itself. The debugger provides runtime services to the application via the low-level DLIB interface; services that allow capabilities like file and terminal I/O to be performed on the host computer.

These capabilities can be valuable during the early development of an application, for example in an application that uses file I/O before any flash file system I/O drivers are implemented. Or, if you need to debug constructions in your application that use stdin and stdout without the actual hardware device for input and output being available. Another debugging purpose can be to produce debug printouts.

The mechanism used for implementing this feature works as follows:

The debugger will detect the presence of the function __DebugBreak, which will be part of the application if you linked it with the XLINK option for C-SPY debugging support. In this case, the debugger will automatically set a breakpoint at the __DebugBreak function. When the application calls, for example, open; the __DebugBreak function is called, which will cause the application to break and perform the necessary services. The execution will then resume.

THE C-SPY TERMINAL I/O WINDOW

To make the Terminal I/O window available, the application must be linked with support for I/O debugging. This means that when the functions __read or __write are called to perform I/O operations on the streams stdin, stdout, or stderr, data will be sent to or read from the C-SPY Terminal I/O window.

Note: The Terminal I/O window is not opened automatically just because __read or __write is called; you must open it manually.

For more information about the Terminal I/O window, see the *C-SPY® Debugging Guide for AVR*.

Speeding up terminal output

On some systems, terminal output might be slow because the host computer and the target hardware must communicate for each character.

For this reason, a replacement for the __write function called __write_buffered is included in the DLIB library. This module buffers the output and sends it to the debugger one line at a time, speeding up the output. Note that this function uses about 80 bytes of RAM memory.

To use this feature you can either choose **Project>Options>Linker>Output** and select the option **Buffered terminal output** in the IDE, or add this to the linker command line:

```
-e__write_buffered=__write
```

LOW-LEVEL FUNCTIONS IN THE DEBUG LIBRARY

The debug library contains implementations of the following low-level functions:

| Function in DLIB low-level interface | Response by C-SPY |
|--------------------------------------|---|
| abort | Notifies that the application has called abort * |
| clock | Returns the clock on the host computer |
| close | Closes the associated host file on the host computer |
| exit | C-SPY notifies that the end of the application was reached st |
| lseek | Seeks in the associated host file on the host computer |
| open | Opens a file on the host computer |
| read | stdin, stdout, and stderr will be directed to the Terminal I/O window; all other files will read the associated host file |
| remove | Writes a message to the Debug Log window and returns -1 |
| rename | Writes a message to the Debug Log window and returns -1 |
| _ReportAssert | Handles failed asserts * |
| system | Writes a message to the Debug Log window and returns -1 |
| time | Returns the time on the host computer |
| write | stdin, stdout, and stderr will be directed to the Terminal I/O window, all other files will write to the associated host file |

Table 16: Functions with special meanings when linked with debug library

Note: For your final release build, you must implement the functionality of the functions used by your application.

THE C-SPY TERMINAL I/O WINDOW

To make the Terminal I/O window available, the application must be linked with support for I/O debugging. This means that when the functions __read or __write are called to perform I/O operations on the streams stdin, stdout, or stderr, data will be sent to or read from the C-SPY Terminal I/O window.

Note: The Terminal I/O window is not opened automatically just because __read or __write is called; you must open it manually.

^{*} The linker option With I/O emulation modules is not required for these functions.

See the C-SPY® Debugging Guide for AVR for more information about the Terminal I/O window.

Speeding up terminal output

On some systems, terminal output might be slow because the host computer and the target hardware must communicate for each character.

For this reason, a replacement for the __write function called __write_buffered is included in the DLIB library. This module buffers the output and sends it to the debugger one line at a time, speeding up the output. Note that this function uses about 80 bytes of RAM memory.

To use this feature you can either choose **Project>Options>Linker>Output** and select the option **Buffered terminal output** in the IDE, or add this to the linker command line:

-e__write_buffered=__write

Overriding library modules

The library contains modules which you probably need to override with your own customized modules, for example functions for character-based I/O and system startup code. This can be done without rebuilding the entire library. This section describes the procedure for including your version of the module in the application project build process. The library files that you can override with your own versions are located in the avr\src\lib directory.

Note: If you override a default I/O library module with your own module, C-SPY support for the module is turned off. For example, if you replace the module __write with your own version, the C-SPY Terminal I/O window will not be supported.



Overriding library modules using the IDE

This procedure is applicable to any source file in the library, which means that <code>library_module.c</code> in this example can be *any* module in the library.

- Copy the appropriate library_module.c file to your project directory.
- **2** Make the required additions to the file (or create your own routine, using the default file as a model), and make sure that it has the same *module name* as the original module. The easiest way to achieve this is to save the new file under the same name as the original file.
- **3** Add the customized file to your project.
- **4** Rebuild your project.

>_

Overriding library modules from the command line

This procedure is applicable to any source file in the library, which means that <code>library_module.c</code> in this example can be *any* module in the library.

- Copy the appropriate library_module.c to your project directory.
- **2** Make the required additions to the file (or create your own routine, using the default file as a model), and make sure that it has the same *module name* as the original module. The easiest way to achieve this is to save the new file under the same name as the original file.
- **3** Compile the modified file using the same options as for the rest of the project:

```
iccavr library_module.c
```

This creates a replacement object module file named library_module.r90.

Note: The memory model, include paths, and the library configuration file must be the same for *library_module* as for the rest of your code.

4 Add *library_module*.r90 to the XLINK command line, either directly or by using an extended linker command file, for example:

```
xlink library_module.r90 dlavr-3s-ec_mul-64-n.r90
```

Make sure that <code>library_module.r90</code> is placed before the library on the command line. This ensures that your module is used instead of the one in the library.

Run XLINK to rebuild your application.

This will use your version of <code>library_module.r90</code>, instead of the one in the library. For information about the XLINK options, see the <code>IAR Linker</code> and <code>Library Tools Reference Guide</code>.

Building and using a customized library

Building a customized library is a complex process. Therefore, consider carefully whether it is really necessary. You must build your own library when:

- There is no prebuilt library for the required combination of compiler options or hardware support
- You want to define your own library configuration with support for locale, file descriptors, multibyte characters, et cetera.

In those cases, you must:

- Set up a library project
- Make the required library modifications

- Build your customized library
- Finally, make sure your application project will use the customized library.

Note: To build IAR Embedded Workbench projects from the command line, use the IAR Command Line Build Utility (iarbuild.exe). There is also a batch file (build_libs.bat) provided for building the library from the command line.

For information about the build process and the IAR Command Line Build Utility, see the *IAR Embedded Workbench*® *IDE Project Management and Building Guide*.

SETTING UP A LIBRARY PROJECT

The IDE provides a library project template which can be used for customizing the runtime environment configuration. This library template uses the Full library configuration, see Table 17, *Library configurations*, page 88.



In the IDE, modify the generic options in the created library project to suit your application, see *Basic project configuration*, page 29.

Note: There is one important restriction on setting options. If you set an option on file level (file level override), no options on higher levels that operate on files will affect that file

MODIFYING THE LIBRARY FUNCTIONALITY

You must modify the library configuration file and build your own library if you want to modify support for, for example, locale, file descriptors, and multibyte characters. This will include or exclude certain parts of the runtime environment.

The library functionality is determined by a set of *configuration symbols*. The default values of these symbols are defined in the file <code>DLib_Defaults.h</code>. This read-only file describes the configuration possibilities. Your library also has its own library configuration file <code>dlavrCustom.h</code>, which sets up that specific library with the required library configuration. For more information, see Table 12, *Customizable items*, page 75.

The library configuration file is used for tailoring a build of the runtime library, and for tailoring the system header files.

Modifying the library configuration file

In your library project, open the file dlavrCustom.h and customize it by setting the values of the configuration symbols according to the application requirements.

When you are finished, build your library project with the appropriate project options.

USING A CUSTOMIZED LIBRARY

After you build your library, you must make sure to use it in your application project.



In the IDE you must do these steps:

Choose **Project>Options** and click the **Library Configuration** tab in the **General Options** category.

- 2 Choose Custom DLIB from the Library drop-down menu.
- 3 In the Library file text box, locate your library file.
- 4 In the Configuration file text box, locate your library configuration file.

System startup and termination

This section describes the runtime environment actions performed during startup and termination of your application.

The code for handling startup and termination is located in the source files cstartup.s90, _exit.s90, and low_level_init.c located in the avr\src\lib directory.

For information about how to customize the system startup code, see *Customizing* system initialization, page 87.

SYSTEM STARTUP

During system startup, an initialization sequence is executed before the main function is entered. This sequence performs initializations required for the target hardware and the C/C++ environment.

For the hardware initialization, it looks like this:

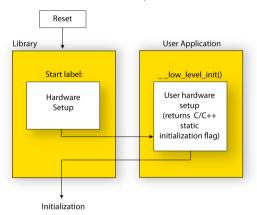


Figure 1: Target hardware initialization phase

- When the CPU is reset it will jump to the program entry label __program_start in the system startup code.
- The external data and address buses are enabled if needed.
- The stack pointer is initialized to the end of the CSTACK or RSTACK segment, respectively.
- The function __low_level_init is called if you defined it, giving the application
 a chance to perform early initializations.

For the C/C++ initialization, it looks like this:

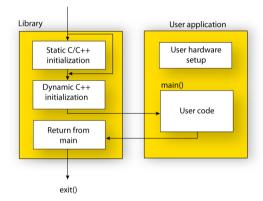


Figure 2: C/C++ initialization phase

- Static and global variables are initialized except for __no_init, __tinyflash, __flash, __farflash, __hugeflash, and __eeprom declared variables. That is, zero-initialized variables are cleared and the values of other initialized variables are copied from ROM to RAM memory. This step is skipped if __low_level_init returns zero. For more information, see *Initialized data*, page 59
- Static C++ objects are constructed
- The main function is called, which starts the application.

SYSTEM TERMINATION

This illustration shows the different ways an embedded application can terminate in a controlled way:

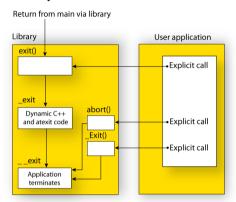


Figure 3: System termination phase

An application can terminate normally in two different ways:

- Return from the main function
- Call the exit function.

Because the C standard states that the two methods should be equivalent, the system startup code calls the exit function if main returns. The parameter passed to the exit function is the return value of main.

The default exit function is written in C. It calls a small assembler function _exit that will perform these operations:

- Call functions registered to be executed when the application ends. This includes C++ destructors for static and global variables, and functions registered with the standard function atexit
- · Close all open files
- Call __exit
- When __exit is reached, stop the system.

An application can also exit by calling the abort or the _Exit function. The abort function just calls __exit to halt the system, and does not perform any type of cleanup. The _Exit function is equivalent to the abort function, except for the fact that _Exit takes an argument for passing exit status information.

If you want your application to do anything extra at exit, for example resetting the system, you can write your own implementation of the __exit(int) function.

C-SPY interface to system termination

If your project is linked with the XLINK options **With runtime control modules** or **With I/O emulation modules**, the normal __exit and abort functions are replaced with special ones. C-SPY will then recognize when those functions are called and can take appropriate actions to simulate program termination. For more information, see *Application debug support*, page 78.

Customizing system initialization

It is likely that you need to customize the code for system initialization. For example, your application might need to initialize memory-mapped special function registers (SFRs), or omit the default initialization of data segments performed by cstartup.

You can do this by providing a customized version of the routine __low_level_init, which is called from cstartup before the data segments are initialized. Modifying the file cstartup.s90 directly should be avoided.

The code for handling system startup is located in the source files cstartup.s90 and low_level_init.c, located in the avr\src\lib directory.

Note: Normally, you do not need to customize either of the files cstartup.s90 or _exit.s90.



If you intend to rebuild the library, the source files are available in the template library project, see *Building and using a customized library*, page 82.

Note: Regardless of whether you modify the routine __low_level_init or the file cstartup.s90, you do not have to rebuild the library.

LOW LEVEL INIT

You can customize the routine __low_level_init, which is called from the system startup code before the data segments are initialized.

The value returned by __low_level_init determines whether or not data segments should be initialized by the system startup code. If the function returns 0, the data segments will not be initialized.

Note: The file intrinsics.h must be included by low_level_init.c to assure correct behavior of the __low_level_init routine.

MODIFYING THE FILE CSTARTUP.S90

As noted earlier, you should not modify the file cstartup.s90 if a customized version of __low_level_init is enough for your needs. However, if you do need to modify the file cstartup.s90, we recommend that you follow the general procedure for creating a modified copy of the file and adding it to your project, see *Overriding library modules*, page 81.

Note that you must make sure that the linker uses the start label used in your version of cstartup.s90. For information about how to change the start label used by the linker, read about the -s option in the *IAR Linker and Library Tools Reference Guide*.

Library configurations

It is possible to configure the level of support for, for example, locale, file descriptors, multibyte characters.

The runtime library configuration is defined in the *library configuration file*. It contains information about what functionality is part of the runtime environment. The configuration file is used for tailoring a build of a runtime library, and tailoring the system header files used when compiling your application. The less functionality you need in the runtime environment, the smaller it becomes.

The library functionality is determined by a set of *configuration symbols*. The default values of these symbols are defined in the file <code>DLib_Defaults.h</code>. This read-only file describes the configuration possibilities.

These predefined library configurations are available:

| Library configuration | Description | |
|-----------------------|---|--|
| Normal DLIB (default) | No locale interface, C locale, no file descriptor support, no multibyte | |
| | characters in printf and scanf, and no hexadecimal floating-point numbers in strtod. | |
| Full DLIB | Full locale interface, C locale, file descriptor support, multibyte characters in printf and scanf, and hexadecimal floating-point numbers in strtod. | |

Table 17: Library configurations

CHOOSING A RUNTIME CONFIGURATION

To choose a runtime configuration, use one of these methods:

Default prebuilt configuration—if you do not specify a library configuration
explicitly you will get the default configuration. A configuration file that matches
the runtime library object file will automatically be used.

- Prebuilt configuration of your choice—to specify a runtime configuration explicitly, use the --dlib_config compiler option. See --dlib config, page 202.
- Your own configuration—you can define your own configurations, which means
 that you must modify the configuration file. Note that the library configuration file
 describes how a library was built and thus cannot be changed unless you rebuild the
 library. For more information, see *Building and using a customized library*, page 82.

The prebuilt libraries are based on the default configurations, see Table 17, *Library configurations*.

Standard streams for input and output

Standard communication channels (streams) are defined in stdio.h. If any of these streams are used by your application, for example by the functions printf and scanf, you must customize the low-level functionality to suit your hardware.

There are primitive I/O functions, which are the fundamental functions through which C and C++ performs all character-based I/O. For any character-based I/O to be available, you must provide definitions for these functions using whatever facilities the hardware environment provides.

IMPLEMENTING LOW-LEVEL CHARACTER INPUT AND OUTPUT

To implement low-level functionality of the stdin and stdout streams, you must write the functions __read and __write, respectively. You can find template source code for these functions in the avr\src\lib directory.

If you intend to rebuild the library, the source files are available in the template library project, see *Building and using a customized library*, page 82. Note that customizing the low-level routines for input and output does not require you to rebuild the library.

Note: If you write your own variants of __read or __write, special considerations for the C-SPY runtime interface are needed, see *Application debug support*, page 78.

Example of using __write

The code in this example uses memory-mapped I/O to write to an LCD display, whose port is assumed to be located at address 0x8:

```
size_t bufSize)

size_t nChars = 0;

/* Check for the command to flush all handles */
if (handle == -1)
{
   return 0;
}

/* Check for stdout and stderr
   (only necessary if FILE descriptors are enabled.) */
if (handle != 1 && handle != 2)
{
   return -1;
}

for (/* Empty */; bufSize > 0; --bufSize)
{
   lcdIO = *buf;
   ++buf;
   ++nChars;
}

return nChars;
```

Note: When DLIB calls __write, DLIB assumes the following interface: a call to __write where buf has the value NULL is a command to flush the stream. When the handle is -1, all streams should be flushed.

Example of using __read

The code in this example uses memory-mapped I/O to read from a keyboard, whose port is assumed to be located at 0x8:

```
if (handle != 0)
{
   return -1;
}

for (/*Empty*/; bufSize > 0; --bufSize)
{
   unsigned char c = kbIO;
   if (c == 0)
      break;

   *buf++ = c;
   ++nChars;
}

return nChars;
```

For information about the @ operator, see *Controlling data and function placement in memory*, page 164.

Configuration symbols for printf and scanf

When you set up your application project, you typically need to consider what printf and scanf formatting capabilities your application requires, see *Choosing formatters* for printf and scanf, page 75.

If the provided formatters do not meet your requirements, you can customize the full formatters. However, that means you must rebuild the runtime library.

The default behavior of the printf and scanf formatters are defined by configuration symbols in the file DLib_Defaults.h.

These configuration symbols determine what capabilities the function printf should have:

| Printf configuration symbols | Includes support for |
|------------------------------|------------------------------------|
| _DLIB_PRINTF_MULTIBYTE | Multibyte characters |
| _DLIB_PRINTF_LONG_LONG | Long long (11 qualifier) |
| _DLIB_PRINTF_SPECIFIER_FLOAT | Floating-point numbers |
| _DLIB_PRINTF_SPECIFIER_A | Hexadecimal floating-point numbers |
| _DLIB_PRINTF_SPECIFIER_N | Output count (%n) |
| _DLIB_PRINTF_QUALIFIERS | Qualifiers h, 1, L, v, t, and z |

Table 18: Descriptions of printf configuration symbols

| Printf configuration symbols | Includes support for |
|----------------------------------|---------------------------------|
| _DLIB_PRINTF_FLAGS | Flags -, +, #, and 0 |
| _DLIB_PRINTF_WIDTH_AND_PRECISION | Width and precision |
| _DLIB_PRINTF_CHAR_BY_CHAR | Output char by char or buffered |

Table 18: Descriptions of printf configuration symbols (Continued)

When you build a library, these configurations determine what capabilities the function scanf should have:

| Scanf configuration symbols | Includes support for |
|------------------------------------|---|
| _DLIB_SCANF_MULTIBYTE | Multibyte characters |
| _DLIB_SCANF_LONG_LONG | Long long (11 qualifier) |
| _DLIB_SCANF_SPECIFIER_FLOAT | Floating-point numbers |
| _DLIB_SCANF_SPECIFIER_N | Output count (%n) |
| _DLIB_SCANF_QUALIFIERS | Qualifiers h, j, 1, t, z, and ${\tt L}$ |
| _DLIB_SCANF_SCANSET | Scanset ([*]) |
| _DLIB_SCANF_WIDTH | Width |
| _DLIB_SCANF_ASSIGNMENT_SUPPRESSING | Assignment suppressing ([*]) |

Table 19: Descriptions of scanf configuration symbols

CUSTOMIZING FORMATTING CAPABILITIES

To customize the formatting capabilities, you must;

- I Set up a library project, see *Building and using a customized library*, page 82.
- **2** Define the configuration symbols according to your application requirements.

File input and output

The library contains a large number of powerful functions for file I/O operations. If you use any of these functions, you must customize them to suit your hardware. To simplify adaptation to specific hardware, all I/O functions call a small set of primitive functions, each designed to accomplish one particular task; for example, __open opens a file, and __write outputs characters.

Note that file I/O capability in the library is only supported by libraries with full library configuration, see *Library configurations*, page 88. In other words, file I/O is supported when the configuration symbol __DLIB_FILE_DESCRIPTOR is enabled. If not enabled, functions taking a FILE * argument cannot be used.

Template code for these I/O files are included in the product:

| I/O function | File | Description |
|--------------|----------|-----------------------------------|
| close | close.c | Closes a file. |
| lseek | lseek.c | Sets the file position indicator. |
| open | open.c | Opens a file. |
| read | read.c | Reads a character buffer. |
| write | write.c | Writes a character buffer. |
| remove | remove.c | Removes a file. |
| rename | rename.c | Renames a file. |

Table 20: Low-level I/O files

The primitive functions identify I/O streams, such as an open file, with a file descriptor that is a unique integer. The I/O streams normally associated with stdin, stdout, and stderr have the file descriptors 0, 1, and 2, respectively.

Note: If you link your library with I/O debugging support, C-SPY variants of the low-level I/O functions are linked for interaction with C-SPY. For more information, see *Application debug support*, page 78.

Locale

Locale is a part of the C language that allows language- and country-specific settings for several areas, such as currency symbols, date and time, and multibyte character encoding.

Depending on what runtime library you are using you get different level of locale support. However, the more locale support, the larger your code will get. It is therefore necessary to consider what level of support your application needs.

The DLIB library can be used in two main modes:

- With locale interface, which makes it possible to switch between different locales during runtime
- Without locale interface, where one selected locale is hardwired into the application.

LOCALE SUPPORT IN PREBUILT LIBRARIES

The level of locale support in the prebuilt libraries depends on the library configuration.

• All prebuilt libraries support the C locale only

- All libraries with full library configuration have support for the locale interface. For
 prebuilt libraries with locale interface, it is by default only supported to switch
 multibyte character encoding at runtime.
- Libraries with *normal library configuration* do not have support for the locale interface.

If your application requires a different locale support, you must rebuild the library.

CUSTOMIZING THE LOCALE SUPPORT

If you decide to rebuild the library, you can choose between these locales:

- The Standard C locale
- The POSIX locale
- A wide range of European locales.

Locale configuration symbols

The configuration symbol _DLIB_FULL_LOCALE_SUPPORT, which is defined in the library configuration file, determines whether a library has support for a locale interface or not. The locale configuration symbols _LOCALE_USE_LANG_REGION and _ENCODING_USE _ENCODING define all the supported locales and encodings:

See DLib_Defaults.h for a list of supported locale and encoding settings.

If you want to customize the locale support, you simply define the locale configuration symbols required by your application. For more information, see *Building and using a customized library*, page 82.

Note: If you use multibyte characters in your C or assembler source code, make sure that you select the correct locale symbol (the local host locale).

Building a library without support for locale interface

The locale interface is not included if the configuration symbol __DLIB_FULL_LOCALE_SUPPORT is set to 0 (zero). This means that a hardwired locale is used—by default the Standard C locale—but you can choose one of the supported locale configuration symbols. The setlocale function is not available and can therefore not be used for changing locales at runtime.

Building a library with support for locale interface

Support for the locale interface is obtained if the configuration symbol __DLIB_FULL_LOCALE_SUPPORT is set to 1. By default, the Standard C locale is used, but you can define as many configuration symbols as required. Because the setlocale function will be available in your application, it will be possible to switch locales at runtime.

CHANGING LOCALES AT RUNTIME

The standard library function setlocale is used for selecting the appropriate portion of the application's locale when the application is running.

The setlocale function takes two arguments. The first one is a locale category that is constructed after the pattern LC_CATEGORY. The second argument is a string that describes the locale. It can either be a string previously returned by setlocale, or it can be a string constructed after the pattern:

```
lang_REGION
or
lang REGION.encoding
```

The *lang* part specifies the language code, and the *REGION* part specifies a region qualifier, and *encoding* specifies the multibyte character encoding that should be used.

The <code>lang_REGION</code> part matches the <code>_LOCALE_USE_LANG_REGION</code> preprocessor symbols that can be specified in the library configuration file.

Example

This example sets the locale configuration symbols to Swedish to be used in Finland and UTF8 multibyte character encoding:

```
setlocale (LC_ALL, "sv_FI.Utf8");
```

Environment interaction

According to the C standard, your application can interact with the environment using the functions getenv and system.

Note: The putenv function is not required by the standard, and the library does not provide an implementation of it.

THE GETENV FUNCTION

The getenv function searches the string, pointed to by the global variable __environ, for the key that was passed as argument. If the key is found, the value of it is returned, otherwise 0 (zero) is returned. By default, the string is empty.

To create or edit keys in the string, you must create a sequence of null terminated strings where each string has the format:

```
key=value\0
```

End the string with an extra null character (if you use a C string, this is added automatically). Assign the created sequence of strings to the __environ variable.

For example:

```
const char MyEnv[] = "Key=Value\0Key2=Value2\0";
environ = MyEnv;
```

If you need a more sophisticated environment variable handling, you should implement your own getenv, and possibly putenv function. This does not require that you rebuild the library. You can find source templates in the files getenv.c and environ.c in the avr\src\lib directory. For information about overriding default library modules, see *Overriding library modules*, page 81.

THE SYSTEM FUNCTION

If you need to use the system function, you must implement it yourself. The system function available in the library simply returns -1.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 82.

Note: If you link your application with support for I/O debugging, the functions getenv and system are replaced by C-SPY variants. For more information, see *Application debug support*, page 78.

Signal and raise

Default implementations of the functions signal and raise are available. If these functions do not provide the functionality that you need, you can implement your own versions.

This does not require that you rebuild the library. You can find source templates in the files signal.c and raise.c in the avr\src\lib directory. For information about overriding default library modules, see *Overriding library modules*, page 81.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 82.

Time

To make the __time32, __time64, and date functions work, you must implement the functions clock, __time32, __time64, and __getzone. Whether you use __time32 or __time64 depends on which interface you use for time_t, see *time.h*, page 418.

To implement these functions does not require that you rebuild the library. You can find source templates in the files clock.c, time.c, time64.c, and getzone.c in the avr\src\lib directory. For information about overriding default library modules, see *Overriding library modules*, page 81.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 82.

The default implementation of __getzone specifies UTC (Coordinated Universal Time) as the time zone.

Note: If you link your application with support for I/O debugging, the functions clock and time are replaced by C-SPY variants that return the host clock and time respectively. For more information, see *Application debug support*, page 78.

Strtod

The function strtod does not accept hexadecimal floating-point strings in libraries with the normal library configuration. To make strtod accept hexadecimal floating-point strings, you must:

- I Enable the configuration symbol _DLIB_STRTOD_HEX_FLOAT in the library configuration file.
- **2** Rebuild the library, see *Building and using a customized library*, page 82.

Pow

The DLIB runtime library contains an alternative power function with extended precision, powxp. The lower-precision pow function is used by default. To use the powxp function instead, link your application with the linker option -epowxp=pow.

Assert

If you linked your application with support for runtime debugging, C-SPY will be notified about failed asserts. If this is not the behavior you require, you must add the source file xreportassert.c to your application project. Alternatively, you can rebuild the library. The __ReportAssert function generates the assert notification. You can find template code in the avr\src\lib directory. For more information, see Building and using a customized library, page 82. To turn off assertions, you must define the symbol NDEBUG.



In the IDE, this symbol NDEBUG is by default defined in a Release project and *not* defined in a Debug project. If you build from the command line, you must explicitly define the symbol according to your needs. See *NDEBUG*, page 299.

Heaps

The runtime environment supports heaps in these memory types:

| Memory type | Segment name | Memory attribute | Used by default in memory model |
|-------------|--------------|------------------|---------------------------------|
| Tiny | TINY_HEAP | tiny | Tiny |
| Near | NEAR_HEAP | near | Near |
| Far | FAR_HEAP | far | Far |
| Huge | HUGE_HEAP | huge | Huge |

Table 21: Heaps and memory types

See *The heap*, page 64 for information about how to set the size for each heap. To use a specific heap, the prefix in the table is the memory attribute to use in front of malloc, free, calloc, and realloc, for example __near_malloc. The default functions will use one of the specific heap variants, depending on project settings such as memory model. For information about how to use a specific heap in C++, see *New and Delete operators*, page 149.

Managing a multithreaded environment

In a multithreaded environment, the standard library must treat all library objects according to whether they are global or local to a thread. If an object is a true global object, any updates of its state must be guarded by a locking mechanism to make sure that only one thread can update it at any given time. If an object is local to a thread, the static variables containing the object state must reside in a variable area local to that thread. This area is commonly named *thread-local storage* (TLS).

There are three possible scenarios, and you need to consider which one that applies to you:

- If you are using an RTOS that supports the multithreading provided by the DLIB library, the RTOS and the DLIB library will handle multithreading which means you do not need to adapt the DLIB library.
- If you are using an RTOS that does not support or only partly supports the multithreading provided by the DLIB library, you probably need to adapt both the RTOS and the DLIB library.
- If you are not using an RTOS, you must adapt the DLIB library to get support for multithreading.

MULTITHREAD SUPPORT IN THE DLIB LIBRARY

The DLIB library uses two kinds of locks—system locks and file stream locks. The file stream locks are used as guards when the state of a file stream is updated, and are only needed in the Full library configuration. The following library objects are guarded with system locks:

- The heap, in other words when malloc, new, free, delete, realloc, or calloc is used
- The file system (only available in the Full library configuration), but not the file streams themselves. The file system is updated when a stream is opened or closed, in other words when fopen, fclose, fdopen, fflush, or freopen is used.
- The signal system, in other words when signal is used.
- The temporary file system, in other words when tmpnam is used.
- Initialization of static function objects.

These library objects use TLS:

| Library objects using TLS | When these functions are used | |
|---------------------------|--|--|
| Error functions | errno, strerror | |
| Locale functions | localeconv, setlocale | |
| Time functions | asctime, localtime, gmtime, mktime | |
| Multibyte functions | mbrlen, mbrtowc, mbsrtowc, mbtowc, wcrtomb, wcsrtomb, wctomb | |
| Rand functions | rand, srand | |
| Miscellaneous functions | atexit, strtok | |

Table 22: Library objects using TLS

ENABLING MULTITHREAD SUPPORT

To enable multithread support in the library, you must:

- Add #define _DLIB_THREAD_SUPPORT in DLib_product.h and rebuild your library
- Implement code for the library's system locks interface
- If file streams are used, implement code for the library's file stream locks interface
 or redirect the interface to the system locks interface (using the linker option -e)
- Implement source code that handles thread creation, thread destruction, and TLS access methods for the library
- Modify the linker configuration file accordingly
- If any of the C++ variants are used, use the compiler option --guard_calls.
 Otherwise, function static variables with dynamic initializers might be initialized simultaneously by several threads.

You can find the required declaration of functions and definitions of macros in the DLib Threads. h file, which is included by yvals. h.

System locks interface

This interface must be fully implemented for system locks to work:

The lock and unlock implementation must survive nested calls.

File streams locks interface

This interface is only needed for the Full library configuration. If file streams are used, they can either be fully implemented or they can be redirected to the system locks interface. This interface must be implemented for file streams locks to work:

The lock and unlock implementation must survive nested calls.

DLIB lock usage

The number of locks that the DLIB library assumes exist are:

- _FOPEN_MAX—the maximum number of file stream locks. These locks are only
 used in the Full library configuration, in other words only if both the macro symbols
 _DLIB_FILE_DESCRIPTOR and _FILE_OP_LOCKS are true.
- MAX LOCK—the maximum number of system locks.

Note that even if the application uses fewer locks, the DLIB library will initialize and destroy all of the locks above.

For information about the initialization and destruction code, see xsyslock.c.

TLS handling

The DLIB library supports TLS memory areas for two types of threads: the *main thread* (the main function including the system startup and exit code) and *secondary threads*.

The main thread's TLS memory area:

- Is automatically created and initialized by your application's startup sequence
- Is automatically destructed by the application's destruct sequence
- Is located in the segment __DLIB_PERTHREAD
- Exists also for non-threaded applications.

Each secondary thread's TLS memory area:

- Must be manually created and initialized
- Must be manually destructed
- Is located in a manually allocated memory area.

If you need the runtime library to support secondary threads, you must override the function:

```
void *__iar_dlib_perthread_access(void *symbp);
```

The parameter is the address to the TLS variable to be accessed—in the main thread's TLS area—and it should return the address to the symbol in the current TLS area.

Two interfaces can be used for creating and destroying secondary threads. You can use the following interface that allocates a memory area on the heap and initializes it. At deallocation, it destroys the objects in the area and then frees the memory.

```
void *__iar_dlib_perthread_allocate(void);
void __iar_dlib_perthread_deallocate(void *);
```

Alternatively, if the application handles the TLS allocation, you can use this interface for initializing and destroying the objects in the memory area:

```
void __iar_dlib_perthread_initialize(void *);
void __iar_dlib_perthread_destroy(void *);
```

These macros can be helpful when you implement an interface for creating and destroying secondary threads:

| Macro | Description |
|------------------------------|---|
| IAR_DLIB_PERTHREAD_SIZE | Returns the size needed for the TLS memory |
| | area. |
| IAR_DLIB_PERTHREAD_INIT_SIZE | Returns the initializer size for the TLS memory area. You should initialize the rest of the TLS |
| | memory area, up to |
| | IAR_DLIB_PERTHREAD_SIZE to zero. |
| IAR_DLIB_PERTHREAD_SYMBOL_ | Returns the offset to the symbol in the TLS |
| OFFSET(symbolptr) | memory area. |

Table 23: Macros for implementing TLS allocation

Note that the size needed for TLS variables depends on which DLIB resources your application uses.

This is an example of how you can handle threads:

```
#include <yvals.h>
/* A thread's TLS pointer */
void _DLIB_TLS_MEMORY *TLSp;

/* Are we in a secondary thread? */
int InSecondaryThread = 0;

/* Allocate a thread-local TLS memory
    area and store a pointer to it in TLSp. */
void AllocateTLS()
{
    TLSp = __iar_dlib_perthread_allocate();
}

/* Deallocate the thread-local TLS memory area. */
void DeallocateTLS()
{
    __iar_dlib_perthread_deallocate(TLSp);
}
```

```
/* Access an object in the
   thread-local TLS memory area. */
void _DLIB_TLS_MEMORY *__iar_dlib_perthread_access(
   void _DLIB_TLS_MEMORY *symbp)
{
   char _DLIB_TLS_MEMORY *p = 0;
   if (InSecondaryThread)
      p = (char _DLIB_TLS_MEMORY *) TLSp;
   else
      p = (char _DLIB_TLS_MEMORY *)
      __segment_begin("__DLIB_PERTHREAD");

   p += __IAR_DLIB_PERTHREAD_SYMBOL_OFFSET(symbp);
   return (void _DLIB_TLS_MEMORY *) p;
}
```

The TLSp variable is unique for each thread, and must be exchanged by the RTOS or manually whenever a thread switch occurs.

CHANGES IN THE LINKER CONFIGURATION FILE

If threads are used, the main thread's TLS memory area must be initialized by naive copying because the initializers are used for each secondary thread's TLS memory area as well. Insert the following statement in your linker configuration file:

```
-Q__DLIB_PERTHREAD=__DLIB_PERTHREAD_init
```

Both the __DLIB_PERTHREAD segment and the __DLIB_PERTHREAD_init segment must be placed in default memory for RAM and ROM, respectively.

Finally, the startup code must copy __DLIB_PERTHREAD_init to DLIB PERTHREAD.

Checking module consistency

This section introduces the concept of runtime model attributes, a mechanism used by the IAR compiler, assembler, and linker to ensure that modules are built using compatible settings.

When developing an application, it is important to ensure that incompatible modules are not used together. For example, in the compiler, it is possible to specify the size of the double floating-point type. If you write a routine that only works for 64-bit doubles, it is possible to check that the routine is not used in an application built using 32-bit doubles.

The tools provided by IAR Systems use a set of predefined runtime model attributes. You can use these predefined attributes or define your own to perform any type of consistency check.

RUNTIME MODEL ATTRIBUTES

A runtime attribute is a pair constituted of a named key and its corresponding value. Two modules can only be linked together if they have the same value for each key that they both define.

There is one exception: if the value of an attribute is *, then that attribute matches any value. The reason for this is that you can specify this in a module to show that you have considered a consistency property, and this ensures that the module does not rely on that property.

Example

In this table, the object files could (but do not have to) define the two runtime attributes color and taste:

| Object file | Color | Taste |
|-------------|-------|-------------|
| file1 | blue | not defined |
| file2 | red | not defined |
| file3 | red | * |
| file4 | red | spicy |
| file5 | red | lean |

Table 24: Example of runtime model attributes

In this case, file1 cannot be linked with any of the other files, since the runtime attribute color does not match. Also, file4 and file5 cannot be linked together, because the taste runtime attribute does not match.

On the other hand, file2 and file3 can be linked with each other, and with either file4 or file5, but not with both.

USING RUNTIME MODEL ATTRIBUTES

To ensure module consistency with other object files, use the #pragma rtmodel directive to specify runtime model attributes in your C/C++ source code. For example:

```
#pragma rtmodel="__rt_version", "1"
```

For detailed syntax information, see *rtmodel*, page 278.

You can also use the rtmodel assembler directive to specify runtime model attributes in your assembler source code. For example:

For syntax information, see the IAR Assembler Reference Guide for AVR.

Note: The predefined runtime attributes all start with two underscores. Any attribute names you specify yourself should not contain two initial underscores in the name, to eliminate any risk that they will conflict with future IAR runtime attribute names.

At link time, the IAR XLINK Linker checks module consistency by ensuring that modules with conflicting runtime attributes will not be used together. If conflicts are detected, an error is issued.

PREDEFINED RUNTIME ATTRIBUTES

The table below shows the predefined runtime model attributes that are available for the compiler. These can be included in assembler code or in mixed C/C++ and assembler code.

| Runtime model attribute | Value | Description |
|-------------------------|---------------------|--|
| rt_version | n | This runtime key is always present in all modules generated by the compiler. If a major change in the runtime characteristics occurs, the value of this key changes. |
| cpu | 0-6 | Corresponds to the $-v$ option used. For more information, see -v, page 226. |
| cpu_name | device | Corresponds to the processor device name, for example AT90S2343 or ATmega8515. Note that for the FpSLic device, the value is AT94Kxx. |
| double_size | 32 or 64 | The size, in bits, of the double floating-point type. The default size is 32. Use the compiler option64bit_doubles to override the default. |
| 64bit_doubles | Enabled or disabled | Corresponds to the compiler option64bit_doubles. |

Table 25: Predefined runtime model attributes

| Runtime model attribute | Value | Description |
|-------------------------|---------------------|---|
| enhanced_core | Enabled | Available if the compiler option |
| | | enhanced_core or cpu for a |
| | | target processor with enhanced core is used. |
| memory_model | 1-4 | Corresponds to the used memory model, where the value can be $1, 2, 3$, or 4 for Tiny, Small, Large, or Huge, respectively. |
| no_rampd | Enabled or disabled | Defined for targets with >64 Kbytes of data memory. Disabled if the target processor has a RAMPD register, otherwise enabled. |

Table 25: Predefined runtime model attributes (Continued)

The easiest way to find the proper settings of the RTMODEL directive is to compile a C or C++ module to generate an assembler file, and then examine the file.

If you are using assembler routines in the C or C++ code, see the chapter *Assembler directives* in the *IAR Assembler Reference Guide for AVR*.

Examples

For an example of using the runtime model attribute __rt_version for checking the module consistency as regards the used calling convention, see *Hints for using the default calling convention*, page 124.

The following assembler source code provides a function, myCounter, that counts the number of times it has been called by increasing the register R16. The routine assumes that the application does not use R16 for anything else, that is, the register is locked for usage. To ensure this, a runtime module attribute, __reg_r16, is defined with a value counter. This definition will ensure that this specific module can only be linked with either other modules containing the same definition, or with modules that do not set this attribute. Note that the compiler sets this attribute to free, unless the register is locked.

| | rtmodel | "reg_r16", "counter" |
|------------|---------|------------------------|
| | module | myCounter |
| | public | myCounter |
| | rseg | CODE: CODE: NOROOT (1) |
| myCounter: | subi | r16, -1 |
| | ret | |
| | end | |
| | | |

If this module is used in an application that contains modules where the register R16 is not locked, the linker issues an error:

Error[e117]: Incompatible runtime models. Module myCounter
specifies that '__reg_r16' must be 'counter', but module part1
has the value 'free'

USER-DEFINED RUNTIME MODEL ATTRIBUTES

In cases where the predefined runtime model attributes are not sufficient, you can use the RTMODEL assembler directive to define your own attributes. For each property, select a key and a set of values that describe the states of the property that are incompatible. Note that key names that start with two underscores are reserved by the compiler.

For example, if you have a UART that can run in two modes, you can specify a runtime model attribute, for example wart. For each mode, specify a value, for example model and model. Declare this in each module that assumes that the UART is in a particular mode. This is how it could look like in one of the modules:

```
#pragma rtmodel="uart", "model"
```

Checking module consistency

The CLIB runtime environment

This chapter describes the runtime environment in which an application executes. In particular, it covers the CLIB runtime library and how you can optimize it for your application.

The standard library uses a small set of low-level input and output routines for character-based I/O. This chapter describes how the low-level routines can be replaced by your own version. The chapter also describes how you can choose printf and scanf formatters.

The chapter then describes system initialization and termination. It presents how an application can control what happens before the start function main is called, and the method for how you can customize the initialization. Finally, the C-SPY® runtime interface is covered.

Note that the legacy CLIB runtime environment is provided for backward compatibility and should not be used for new application projects.

For information about migrating from CLIB to DLIB, see the IAR Embedded Workbench® Migration Guide for AVR®.

Using a prebuilt library

The prebuilt runtime libraries are configured for different combinations of these features:

- Type of library
- Processor option (-v)
- Memory model option (--memory_model)
- AVR enhanced core option (--enhanced_core)
- Small flash memory option (--64k_flash)
- 64-bit doubles option (--64bit_doubles).

CHOOSING A LIBRARY



The IDE includes the correct runtime library based on the options you select. See the *IAR Embedded Workbench® IDE Project Management and Building Guide* for more information.



Specify which runtime library object file to use on the XLINK command line, for instance:

c10t.r90

The CLIB runtime environment includes the C standard library. The linker will include only those routines that are required—directly or indirectly—by your application. For more information about the runtime libraries, see the chapter *Library functions*.

These are some examples of how to decode a library name:

| Library file | Generic processor option | Memory model | Core | Small flash | 64-bit doubles |
|--------------------|--------------------------------|-----------------|------|-------------|-------------------|
| c10t.r90 | -v0 | Tiny | | | |
| cl1s-64.r90 | -v1 | Small | | | Χ |
| c161-ec_mul-64.r90 | -v6 | Large | X | | Χ |

Table 26: Runtime libraries

Library filename syntax

The runtime library names are constructed in this way:

 $\label{type} $$\{cpu\}\{memModel\}-\{core\}-\{smallFlash\}-\{64BitDoubles\}.r90$$ where$

• {type} is c1 for the IAR CLIB Library

- {cpu} is a value from 0 to 6, matching the -v option
- {memModel} is one of t, s, 1, or h for the Tiny, Small, Large, or Huge memory model, respectively
- {smallflash} is sf when the small flash memory is available. When small flash memory is not available, this value is not specified
- {64BitDoubles} is 64 when 64-bit doubles are used. When 32-bit doubles are used, this value is not specified.

Input and output

You can customize:

- The functions related to character-based I/O
- The formatters used by printf/sprintf and scanf/sscanf.

CHARACTER-BASED I/O

The functions putchar and getchar are the fundamental C functions for character-based I/O. For any character-based I/O to be available, you must provide definitions for these two functions, using whatever facilities the hardware environment provides.

The creation of new I/O routines is based on these files:

- putchar.c, which serves as the low-level part of functions such as printf
- getchar.c, which serves as the low-level part of functions such as scanf.

The code example below shows how memory-mapped I/O could be used to write to a memory-mapped I/O device:

```
__no_init volatile unsigned char devIO @ 8;
int putchar(int outChar)
{
   devIO = outChar;
   return outChar;
}
```

The exact address is a design decision. For example, it can depend on the selected processor variant.

For information about how to include your own modified version of putchar and getchar in your project build process, see *Overriding library modules*, page 81.

FORMATTERS USED BY PRINTF AND SPRINTF

The printf and sprintf functions use a common formatter, called _formatted_write. The full version of _formatted_write is very large, and provides facilities not required in many embedded applications. To reduce the memory consumption, two smaller, alternative versions are also provided in the Standard C library.

medium write

The _medium_write formatter has the same functions as _formatted_write, except that floating-point numbers are not supported. Any attempt to use a %f, %g, %G, %e, or %E specifier will produce a runtime error:

```
FLOATS? wrong formatter installed!
_medium_write is considerably smaller than _formatted_write.
```

_small_write

The _small_write formatter works in the same way as _medium_write, except that it supports only the %%, %d, %o, %c, %s, and %x specifiers for integer objects, and does not support field width or precision arguments. The size of _small_write is 10-15% that of _formatted_write.



Specifying the printf formatter in the IDE

- Choose Project>Options and select the General Options category. Click the Library options tab.
- 2 Select the appropriate Printf formatter option, which can be either Small, Medium, or Large.

>_

Specifying the printf formatter from the command line

To use the _small_write or _medium_write formatter, add the corresponding line in the linker configuration file:

```
-e_small_write=_formatted_write
or
-e_medium_write=_formatted_write
```

To use the full version, remove the line.

Customizing printf

For many embedded applications, sprintf is not required, and even printf with _small_write provides more facilities than are justified, considering the amount of memory it consumes. Alternatively, a custom output routine might be required to support particular formatting needs or non-standard output devices.

For such applications, a much reduced version of the printf function (without sprintf) is supplied in source form in the file intwri.c. This file can be modified to meet your requirements, and the compiled module inserted into the library in place of the original file; see Overriding library modules, page 81.

FORMATTERS USED BY SCANF AND SSCANF

Similar to the printf and sprintf functions, scanf and sscanf use a common formatter, called _formatted_read. The full version of _formatted_read is very large, and provides facilities that are not required in many embedded applications. To reduce the memory consumption, an alternative smaller version is also provided.

_medium_read

The _medium_read formatter has the same functions as the full version, except that floating-point numbers are not supported. _medium_read is considerably smaller than the full version.



Specifying the scanf formatter in the IDE

- I Choose Project>Options and select the General Options category. Click the Library options tab.
- 2 Select the appropriate Scanf formatter option, which can be either Medium or Large.



Specifying the read formatter from the command line

To use the _medium_read formatter, add this line in the linker configuration file:

-e_medium_read=_formatted_read

To use the full version, remove the line.

System startup and termination

This section describes the actions the runtime environment performs during startup and termination of applications.

The code for handling startup and termination is located in the source files estartup. _exit.s90, and low_level_init.c located in the avr\src\lib directory.

113

SYSTEM STARTUP

When an application is initialized, a number of steps are performed:

- The custom function __low_level_init is called, giving the application a chance to perform early initializations
- The external data and address buses are enabled if needed
- The stack pointers are initialized to the end of CSTACK and RSTACK, respectively
- Static variables are initialized except for __no_init and __eeprom declared variables; this includes clearing zero-initialized memory and copying the ROM image of the RAM memory of the remaining initialized variables
- The main function is called, which starts the application.

Note that the system startup code contains code for more steps than described here. The other steps are applicable to the DLIB runtime environment.

SYSTEM TERMINATION

An application can terminate normally in two different ways:

- Return from the main function
- Call the exit function.

Because the C standard states that the two methods should be equivalent, the cstartup code calls the exit function if main returns. The parameter passed to the exit function is the return value of main. The default exit function is written in assembler.

When the application is built in debug mode, C-SPY stops when it reaches the special code label ?C_EXIT.

An application can also exit by calling the abort function. The default function just calls __exit to halt the system, without performing any type of cleanup.

Overriding default library modules

The IAR CLIB Library contains modules which you probably need to override with your own customized modules, for example for character-based I/O, without rebuilding the entire library. For information about how to override default library modules, see *Overriding library modules*, page 81, in the chapter *The DLIB runtime environment*.

Customizing system initialization

For information about how to customize system initialization, see *Customizing system initialization*, page 87.

C-SPY runtime interface

The low-level debugger interface is used for communication between the application being debugged and the debugger itself. The interface is simple: C-SPY will place breakpoints on certain assembler labels in the application. When code located at the special labels is about to be executed, C-SPY will be notified and can perform an action.

THE DEBUGGER TERMINAL I/O WINDOW

When code at the labels <code>?C_PUTCHAR</code> and <code>?C_GETCHAR</code> is executed, data will be sent to or read from the debugger window.

For the ?C_PUTCHAR routine, one character is taken from the output stream and written. If everything goes well, the character itself is returned, otherwise -1 is returned.

When the label <code>?C_GETCHAR</code> is reached, C-SPY returns the next character in the input field. If no input is given, C-SPY waits until the user types some input and presses the Return key.

To make the Terminal I/O window available, the application must be linked with the XLINK option **With I/O emulation modules** selected. See the *IAR Embedded Workbench*® *IDE Project Management and Building Guide*.

TERMINATION

The debugger stops executing when it reaches the special label ?C_EXIT.

Checking module consistency

For information about how to check module consistency, see *Checking module consistency*, page 103.

Checking module consistency

Assembler language interface

When you develop an application for an embedded system, there might be situations where you will find it necessary to write parts of the code in assembler, for example when using mechanisms in the AVR microcontroller that require precise timing and special instruction sequences.

This chapter describes the available methods for this and some C alternatives, with their advantages and disadvantages. It also describes how to write functions in assembler language that work together with an application written in C or C++.

Finally, the chapter covers how you can implement support for call frame information in your assembler routines for use in the C-SPY® Call Stack window.

Mixing C and assembler

The IAR C/C++ Compiler for AVR provides several ways to access low-level resources:

- Modules written entirely in assembler
- Intrinsic functions (the C alternative)
- Inline assembler.

It might be tempting to use simple inline assembler. However, you should carefully choose which method to use.

INTRINSIC FUNCTIONS

The compiler provides a few predefined functions that allow direct access to low-level processor operations without having to use the assembler language. These functions are known as intrinsic functions. They can be very useful in, for example, time-critical routines.

An intrinsic function looks like a normal function call, but it is really a built-in function that the compiler recognizes. The intrinsic functions compile into inline code, either as a single instruction, or as a short sequence of instructions.

117

The advantage of an intrinsic function compared to using inline assembler is that the compiler has all necessary information to interface the sequence properly with register allocation and variables. The compiler also knows how to optimize functions with such sequences; something the compiler is unable to do with inline assembler sequences. The result is that you get the desired sequence properly integrated in your code, and that the compiler can optimize the result.

For more information about the available intrinsic functions, see the chapter *Intrinsic functions*.

MIXING C AND ASSEMBLER MODULES

It is possible to write parts of your application in assembler and mix them with your C or C++ modules. This gives several benefits compared to using inline assembler:

- The function call mechanism is well-defined
- The code will be easy to read
- The optimizer can work with the C or C++ functions.

This causes some overhead in the form of a function call and return instruction sequences, and the compiler will regard some registers as scratch registers. However, the compiler will also assume that all scratch registers are destroyed when calling a function written in assembler. In many cases, the overhead of the extra instructions is compensated by the work of the optimizer.

An important advantage is that you will have a well-defined interface between what the compiler produces and what you write in assembler. When using inline assembler, you will not have any guarantees that your inline assembler lines do not interfere with the compiler generated code.

When an application is written partly in assembler language and partly in C or C++, you are faced with several questions:

- How should the assembler code be written so that it can be called from C?
- Where does the assembler code find its parameters, and how is the return value passed back to the caller?
- How should assembler code call functions written in C?
- How are global C variables accessed from code written in assembler language?
- Why does not the debugger display the call stack when assembler code is being debugged?

The first issue is discussed in the section *Calling assembler routines from C*, page 120. The following two are covered in the section *Calling convention*, page 123.

The answer to the final question is that the call stack can be displayed when you run assembler code in the debugger. However, the debugger requires information about the

call frame, which must be supplied as annotations in the assembler source file. For more information, see *Call frame information*, page 133.

The recommended method for mixing C or C++ and assembler modules is described in *Calling assembler routines from C*, page 120, and *Calling assembler routines from C*++, page 122, respectively.

INLINE ASSEMBLER

It is possible to insert assembler code directly into a C or C++ function. The asm and __asm keywords both insert the supplied assembler statement in-line. The following example demonstrates the use of the asm keyword. This example also shows the risks of using inline assembler.

```
bool flag;

void Func()
{
   while (!flag)
   {
     asm("IN R0, PIND \n"
          "STS flag, R0");
   }
}
```

In this example, the assignment to the global variable flag is not noticed by the compiler, which means the surrounding code cannot be expected to rely on the inline assembler statement.

The inline assembler instruction will simply be inserted at the given location in the program flow. The consequences or side-effects the insertion might have on the surrounding code are not taken into consideration. If, for example, registers or memory locations are altered, they might have to be restored within the sequence of inline assembler instructions for the rest of the code to work properly.

Inline assembler sequences have no well-defined interface with the surrounding code generated from your C or C++ code. This makes the inline assembler code fragile, and will possibly also become a maintenance problem if you upgrade the compiler in the future. There are also several limitations to using inline assembler:

- The compiler's various optimizations will disregard any effects of the inline sequences, which will not be optimized at all
- In general, assembler directives will cause errors or have no meaning. Data definition directives will however work as expected
- Auto variables cannot be accessed.

Inline assembler is therefore often best avoided. If no suitable intrinsic function is available, we recommend that you use modules written in assembler language instead of inline assembler, because the function call to an assembler routine normally causes less performance reduction.

Calling assembler routines from C

An assembler routine that will be called from C must:

- Conform to the calling convention
- Have a PUBLIC entry-point label
- Be declared as external before any call, to allow type checking and optional promotion of parameters, as in these examples:

```
extern int foo(void);
or
extern int foo(int i, int j);
```

One way of fulfilling these requirements is to create skeleton code in C, compile it, and study the assembler list file.

CREATING SKELETON CODE

The recommended way to create an assembler language routine with the correct interface is to start with an assembler language source file created by the C compiler. Note that you must create skeleton code for each function prototype.

The following example shows how to create skeleton code to which you can easily add the functional body of the routine. The skeleton source code only needs to declare the

variables required and perform simple accesses to them. In this example, the assembler routine takes an int and a char, and then returns an int:

```
extern int gInt;
extern char gChar;

int Func(int arg1, char arg2)
{
   int locInt = arg1;
   gInt = arg1;
   gChar = arg2;
   return locInt;
}

int main()
{
   int locInt = gInt;
   gInt = Func(locInt, gChar);
   return 0;
}
```

Note: In this example we use a low optimization level when compiling the code to show local and global variable access. If a higher level of optimization is used, the required references to local variables could be removed during the optimization. The actual function declaration is not changed by the optimization level.

COMPILING THE CODE



In the IDE, specify list options on file level. Select the file in the workspace window. Then choose **Project>Options**. In the **C/C++ Compiler** category, select **Override inherited settings**. On the **List** page, deselect **Output list file**, and instead select the **Output assembler file** option and its suboption **Include source**. Also, be sure to specify a low level of optimization.



Use these options to compile the skeleton code:

```
iccavr skeleton.c -lA .
```

The <code>-lA</code> option creates an assembler language output file including C or C++ source lines as assembler comments. The . (period) specifies that the assembler file should be named in the same way as the C or C++ module (skeleton), but with the filename extension <code>s90</code>. Also remember to specify the memory model you are using, a low level of optimization, and <code>-e</code> for enabling language extensions.

The result is the assembler source output file skeleton.s90.

Note: The -1A option creates a list file containing call frame information (CFI) directives, which can be useful if you intend to study these directives and how they are



used. If you only want to study the calling convention, you can exclude the CFI directives from the list file. In the IDE, choose **Project>Options>C/C++ Compiler>List** and deselect the suboption **Include call frame information**. On the command line, use the option -1B instead of -1A. Note that CFI information must be included in the source code to make the C-SPY Call Stack window work.

The output file

The output file contains the following important information:

- The calling convention
- The return values
- The global variables
- The function parameters
- How to create space on the stack (auto variables)
- Call frame information (CFI).

The CFI directives describe the call frame information needed by the Call Stack window in the debugger. For more information, see *Call frame information*, page 133.

Calling assembler routines from C++

The C calling convention does not apply to C++ functions. Most importantly, a function name is not sufficient to identify a C++ function. The scope and the type of the function are also required to guarantee type-safe linkage, and to resolve overloading.

Another difference is that non-static member functions get an extra, hidden argument, the this pointer.

However, when using C linkage, the calling convention conforms to the C calling convention. An assembler routine can therefore be called from C++ when declared in this manner:

```
extern "C"
{
   int MyRoutine(int);
}
```

In C++, data structures that only use C features are known as PODs ("plain old data structures"), they use the same memory layout as in C. However, we do not recommend that you access non-PODs from assembler routines.

The following example shows how to achieve the equivalent to a non-static member function, which means that the implicit this pointer must be made explicit. It is also possible to "wrap" the call to the assembler routine in a member function. Use an inline member function to remove the overhead of the extra call—this assumes that function inlining is enabled:

```
class MyClass;
extern "C"
{
  void DoIt(MyClass *ptr, int arg);
}
class MyClass
{
public:
  inline void DoIt(int arg)
  {
    ::DoIt(this, arg);
  }
};
```

Note: Support for C++ names from assembler code is extremely limited. This means that:

- Assembler list files resulting from compiling C++ files cannot, in general, be passed through the assembler.
- It is not possible to refer to or define C++ functions that do not have C linkage in assembler.

Calling convention

A calling convention is the way a function in a program calls another function. The compiler handles this automatically, but, if a function is written in assembler language, you must know where and how its parameters can be found, how to return to the program location from where it was called, and how to return the resulting value.

It is also important to know which registers an assembler-level routine must preserve. If the program preserves too many registers, the program might be ineffective. If it preserves too few registers, the result would be an incorrect program.

The compiler provides two calling conventions—one old, which is used in version 1.x of the compiler, and one new which is default. This section describes the calling conventions used by the compiler. These items are examined:

• Choosing a calling convention

- Function declarations
- C and C++ linkage
- Preserved versus scratch registers
- Function entrance
- Function exit
- Return address handling.

At the end of the section, some examples are shown to describe the calling convention in practice.

CHOOSING A CALLING CONVENTION

You can choose between two calling conventions:

- The old calling convention offers a simple assembler interface. It is compatible with
 the calling convention used in version 1.x of the compiler. Even though this
 convention is not used by default, it is recommended for use when mixing C and
 assembler code
- The new calling convention is default. It is more efficient than the old calling convention, but also more complex to understand and subject to change in later versions of the compiler.



To choose another calling convention than the default, use the --version1_calls command line option. You can also declare individual functions to use the old calling convention by using the __version1 function attribute, for example:

```
extern
__version_1 void doit(int arg);
```

For details about the --version1_calls option and the __version1 attribute, see --version1 calls, page 227 and version 1, page 263, respectively.



In the IDE, choose **Use ICCA90 1.x calling convention** on the **Project>C/C++ Compiler>Code** page.



Hints for using the default calling convention

The default calling convention is very complex, and therefore not recommended for use when calling assembler routines. However, if you intend to use it for your assembler routines, you should create a list file and see how the compiler assigns the different parameters to the available registers. For an example, see *Creating skeleton code*, page 120.

If you intend to use the default calling convention, you should *also* specify a value to the runtime model attribute __rt_version using the RTMODEL assembler directive:

```
RTMODEL "__rt_version", "value"
```

The parameter *value* should have the same value as the one used internally by the compiler. For information about what value to use, see the generated list file. If the calling convention changes in future compiler versions, the runtime model value used internally by the compiler will also change. Using this method gives a module consistency check, because the linker produces errors for mismatches between the values.

For more information about checking module consistency, see *Checking module consistency*, page 103.

FUNCTION DECLARATIONS

In C, a function must be declared in order for the compiler to know how to call it. A declaration could look as follows:

```
int MyFunction(int first, char * second);
```

This means that the function takes two parameters: an integer and a pointer to a character. The function returns a value, an integer.

In the general case, this is the only knowledge that the compiler has about a function. Therefore, it must be able to deduce the calling convention from this information.

USING C LINKAGE IN C++ SOURCE CODE

In C++, a function can have either C or C++ linkage. To call assembler routines from C++, it is easiest if you make the C++ function have C linkage.

This is an example of a declaration of a function with C linkage:

```
extern "C"
{
  int F(int);
}
```

It is often practical to share header files between C and C++. This is an example of a declaration that declares a function with C linkage in both C and C++:

```
#ifdef __cplusplus
extern "C"
{
#endif
int F(int);
```

```
#ifdef __cplusplus
}
#endif
```

PRESERVED VERSUS SCRATCH REGISTERS

The general AVR CPU registers are divided into three separate sets, which are described in this section.

Scratch registers

Any function is permitted to destroy the contents of a scratch register. If a function needs the register value after a call to another function, it must store it during the call, for example on the stack.

For both calling conventions, these 14 registers can be used as scratch registers by a function:

```
R0-R3, R16-R23, and R30-R31
```

Preserved registers

Preserved registers, on the other hand, are preserved across function calls. The called function can use the register for other purposes, but must save the value before using the register and restore it at the exit of the function.

For both calling conventions, these registers are preserved registers:

```
R4-R15 and R24-R27
```

Note that the registers R4-R15 can be locked from the command line and used for global register variables; see *--lock_regs*, page 210 and *__regvar*, page 260.

Special registers

For some registers, you must consider certain prerequisites:

- The stack pointer—register Y—must at all times point to the last element on the stack. In the eventuality of an interrupt, everything below the point the stack pointer points to, will be destroyed.
- If using the -v4 or -v6 processor option, the RAMPY register is part of the data stack pointer.
- If using a processor option which uses any of the registers EIND, RAMPX, or RAMPZ, these registers are treated as scratch registers.

FUNCTION ENTRANCE

During a function call, the calling function:

- passes the parameters, either in registers or on the stack
- pushes any other parameters on the data stack (CSTACK)

Control is then passed to the called function with the return address being automatically pushed on the return address stack (RSTACK).

The called function:

- stores any local registers required by the function on the data stack
- allocates space for its auto variables and temporary values
- proceeds to run the function itself.

Register parameters versus stack parameters

Parameters can be passed to a function using one of two basic methods: in registers or on the stack. It is much more efficient to use registers than to take a detour via memory, so the calling convention is designed to use registers as much as possible. Only a limited number of registers can be used for passing parameters; when no more registers are available, the remaining parameters are passed on the stack.

Hidden parameters

In addition to the parameters visible in a function declaration and definition, there can be hidden parameters:

- A function returning structures or unions larger than 4 bytes gets an extra hidden parameter, which is a default pointer—depending on the used memory model—pointing to the location where the result should be stored. This pointer must be returned to the callee.
- For non-static C++ member functions, the this pointer is passed as the first parameter (but placed after the return structure pointer, if there is one). Note that static member functions do not have a this pointer.

Register parameters

For both calling conventions, the registers available for passing parameters are:

R16-R23

Parameters are allocated to registers using a first-fit algorithm, using parameter alignment requirements according to this table:

| Parameters | Alignment | Passed in registers |
|---------------|-----------|--|
| 8-bit values | 1 | R16, R17, R18, R19, R20, R21, R22, R23 |
| 16-bit values | 2 | R17:R16, R19:R18, R21:R20, R23:R22 |
| 24-bit values | 4 | R18:R17:R16, R22:R21:R20 |
| 32-bit values | 4 | R19:R18:R17:R16, R23:R22:R21:R20 |
| 64-bit values | 8 | R23:R22:R21:R20:R19:R18:R17:R16 |

Table 27: Registers used for passing parameters

Register assignment using the default calling convention

In the default calling convention, as many parameters as possible are passed in registers. The remaining parameters are passed on the stack. The compiler may change the order of the parameters in order to achieve the most efficient register usage.

The algorithm for assigning parameters to registers is quite complex in the default calling convention. For details, you should create a list file and see how the compiler assigns the different parameters to the available registers, see *Creating skeleton code*, page 120.

Below follows some examples of combinations of register assignment.

A function with the following signature (not C++):

```
void Func(char __far * a, int b, char c, int d)
```

would have a allocated to R18:R17:R16, b to R21:R20 (alignment requirement prevents R20:R19), c to R19 (first fit), and d to R23:R22 (first fit).

Another example:

```
void bar(char a, int b, long c, char d)
```

This would result in a being allocated to R16 (first fit), b to R19:R18 (alignment), c to R23:R22:R21:R20 (first fit), and d to R17 (first fit).

A third example:

```
void baz(char a, char __far * b, int c, int d)
```

This would give, a being allocated to R16, b to R22:R21:R20, c to R19:R18, and d to the stack.

Register assignment using the old calling convention

In the old calling convention, the two left-most parameters are passed in registers if they are scalar and up to 32 bits in size.

This table shows some of the possible combinations:

| Parameters* | Parameter I | Parameter 2 |
|-------------|--------------------|--------------------|
| f(b1,b2,) | R16 | R20 |
| f(b1,w2,) | R16 | R20, R21 |
| f(w1,11,) | R16, R17 | R20, R21, R22, R23 |
| f(11,b2,) | R16, R17, R18, R19 | R20 |
| f(11,12,) | R16, R17, R18, R19 | R20, R21, R22, R23 |

Table 28: Passing parameters in registers

Stack parameters and layout

A function call creates a stack frame as follows:

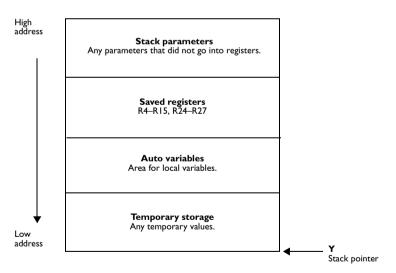


Figure 4: Stack image after the function call

Note that only registers that are used will be saved.

^{*} Where b denotes an 8-bit data type, w denotes a 16-bit data type, and 1 denotes a 32-bit data type. If the first and/or second parameter is a 3-byte pointer, it will be passed in R16-R19 or R20-R22 respectively.

FUNCTION EXIT

A function can return a value to the function or program that called it, or it can have the return type void.

The return value of a function, if any, can be scalar (such as integers and pointers), floating-point, or a structure.

Registers used for returning values

For the old calling convention, the registers available for returning values are R16-R19. The default calling convention can use the registers R16-R23 for returning values.

| Return values | Passed in registers |
|---------------|---------------------------------|
| 8-bit values | R16 |
| 16-bit values | R17:R16 |
| 24-bit values | R18:R17:R16 |
| 32-bit values | R19:R18:R17:R16 |
| 64-bit values | R23:R22:R21:R20:R19:R18:R17:R16 |

Table 29: Registers used for returning values

Note that the size of a returned pointer depends on the memory model in use; appropriate registers are used accordingly.

Stack layout at function exit

Normally, it is the responsibility of the called function to clean the stack. The only exception is for ellipse functions—functions with a variable argument list such as printf—for which it is the responsibility of the caller to clean the stack.

Return address handling

A function written in assembler language should, when finished, return to the caller. At a function call, the return address is automatically stored on the RSTACK (not the CSTACK).

Typically, a function returns by using the RET instruction.

RESTRICTIONS FOR SPECIAL FUNCTION TYPES

Interrupt functions

Interrupt functions differ from ordinary C functions in that:

• If used, flags and scratch registers are saved

- Calls to interrupt functions are made via interrupt vectors; direct calls are not allowed
- No arguments can be passed to an interrupt function
- Interrupt functions return by using the RETI function.

For more information about interrupt functions, see *Interrupt functions*, page 48.

Monitor functions

A monitor function causes interrupts to be disabled during execution of the function. At function entry, the status register SREG is saved and global interrupts are disabled. At function exit, the global interrupt enable bit (I) is restored in the SREG register, and thereby the interrupt status existing before the function call is also restored.

For more information about monitor functions, see *Monitor functions*, page 49.

EXAMPLES

The following section shows a series of declaration examples and the corresponding calling conventions. The complexity of the examples increases toward the end.

Example I

Assume this function declaration:

```
int add1(int);
```

This function takes one parameter in the register R17:R16, and the return value is passed back to its caller in the register R17:R16.

This assembler routine is compatible with the declaration; it will return a value that is one number higher than the value of its parameter:

```
subi R16,FF
sbci R17,FF
```

Example 2

This example shows how structures are passed on the stack. Assume these declarations:

```
struct MyStruct
{
  long long mA;
  long long mB;
};
int MyFunction(struct MyStruct x, int y);
```

The calling function must reserve 16 bytes on the top of the stack and copy the contents of the struct to that location. The integer parameter y is passed in the register R17:R16. The return value is passed back to its caller in the register R17:R16.

Example 3

The function below will return a structure of type struct MyStruct.

```
struct MyStruct
{
  long long mA;
  long long mB;
};
int MyFunction(struct MyStruct x, int y);
```

It is the responsibility of the calling function to allocate a memory location for the return value and pass a pointer to it as a hidden first parameter. The pointer to the location where the return value should be stored is passed in the first suitable register/register pair, which is R16, R17:R16, and R18:R17:R16 for the Tiny, Small, Large, and Huge memory model, respectively. The parameter x is passed in R19:R18, R19:R18, and R21:R20 for the Tiny, Small, Large, and Huge memory model, respectively.

Assume that the function instead was declared to return a pointer to the structure:

```
struct MyStruct *MyFunction(int x);
```

In this case, the return value is a scalar, so there is no hidden parameter. The parameter x is passed in R17:R16, and the return value is returned in R16, R17:R16, and R18:R17:R16 for the Tiny, Small, and Large memory model, respectively.

FUNCTION DIRECTIVES

Note: This type of directive is primarily intended to support static overlay, a feature which is useful in some smaller microcontrollers. The IAR C/C++ Compiler for AVR does not use static overlay, because it has no use for it.

The function directives FUNCTION, ARGFRAME, LOCFRAME, and FUNCALL are generated by the compiler to pass information about functions and function calls to the IAR XLINK Linker. These directives can be seen if you use the compiler option **Assembler file** (-1A) to create an assembler list file.

For more information about the function directives, see the *IAR Assembler Reference Guide for AVR*.

Call frame information

When you debug an application using C-SPY, you can view the *call stack*, that is, the chain of functions that called the current function. To make this possible, the compiler supplies debug information that describes the layout of the call frame, in particular information about where the return address is stored.

If you want the call stack to be available when debugging a routine written in assembler language, you must supply equivalent debug information in your assembler source using the assembler directive CFI. This directive is described in detail in the *IAR Assembler Reference Guide for AVR*.

CFI DIRECTIVES

The CFI directives provide C-SPY with information about the state of the calling function(s). Most important of this is the return address, and the value of the stack pointer at the entry of the function or assembler routine. Given this information, C-SPY can reconstruct the state for the calling function, and thereby unwind the stack.

A full description about the calling convention might require extensive call frame information. In many cases, a more limited approach will suffice.

When describing the call frame information, the following three components must be present:

- A names block describing the available resources to be tracked
- A *common block* corresponding to the calling convention
- A data block describing the changes that are performed on the call frame. This
 typically includes information about when the stack pointer is changed, and when
 permanent registers are stored or restored on the stack.

For AVR, the defined resources depend on which processor option you are using. You can find the resources in the list file section CFI Names.

CREATING ASSEMBLER SOURCE WITH CFI SUPPORT

The recommended way to create an assembler language routine that handles call frame information correctly is to start with an assembler language source file created by the compiler.

I Start with suitable C source code, for example:

```
int F(int);
int cfiExample(int i)
{
   return i + F(i);
}
```

2 Compile the C source code, and make sure to create a list file that contains call frame information—the CFI directives.



On the command line, use the option -1A.



In the IDE, choose **Project>Options>**C/C++ Compiler>List and make sure the suboption **Include call frame information** is selected.

Using C

This chapter gives an overview of the compiler's support for the C language. The chapter also gives a brief overview of the IAR C language extensions.

C language overview

The IAR C/C++ Compiler for AVR supports the ISO/IEC 9899:1999 standard (including up to technical corrigendum No.3), also known as C99. In this guide, this standard is referred to as *Standard C* and is the default standard used in the compiler. This standard is stricter than C89.

In addition, the compiler also supports the ISO 9899:1990 standard (including all technical corrigenda and addenda), also known as C94, C90, C89, and ANSI C. In this guide, this standard is referred to as *C89*. Use the --c89 compiler option to enable this standard.

The C99 standard is derived from C89, but adds features like these:

- The inline keyword advises the compiler that the function declared immediately
 after the directive should be inlined
- Declarations and statements can be mixed within the same scope
- A declaration in the initialization expression of a for loop
- The bool data type
- The long long data type
- The complex floating-point type
- C++ style comments
- · Compound literals
- Incomplete arrays at the end of structs
- · Hexadecimal floating-point constants
- Designated initializers in structures and arrays
- The preprocessor operator _Pragma()
- Variadic macros, which are the preprocessor macro equivalents of printf style functions
- VLA (variable length arrays) must be explicitly enabled with the compiler option
 -vla
- Inline assembler using the asm or the __asm keyword.

Note: Even though it is a C99 feature, the IAR C/C++ Compiler for AVR does not support UCNs (universal character names).

Inline assembler

Inline assembler can be used for inserting assembler instructions in the generated function.

The asm extended keyword and its alias __asm both insert assembler instructions. However, when you compile C source code, the asm keyword is not available when the option --strict is used. The __asm keyword is always available.

Note: Not all assembler directives or operators can be inserted using these keywords.

The syntax is:

```
asm ("string");
```

The string can be a valid assembler instruction or a data definition assembler directive, but not a comment. You can write several consecutive inline assembler instructions, for example:

where \n (new line) separates each new assembler instruction. Note that you can define and use local labels in inline assembler instructions.

For more information about inline assembler, see *Mixing C and assembler*, page 117.

Extensions overview

The compiler offers the features of Standard C and a wide set of extensions, ranging from features specifically tailored for efficient programming in the embedded industry to the relaxation of some minor standards issues.

This is an overview of the available extensions:

• IAR C language extensions

For information about available language extensions, see *IAR C language extensions*, page 138. For more information about the extended keywords, see the chapter *Extended keywords*. For information about C++, the two levels of support for the language, and C++ language extensions; see the chapter *Using C*++.

Pragma directives

The #pragma directive is defined by Standard C and is a mechanism for using vendor-specific extensions in a controlled way to make sure that the source code is still portable.

The compiler provides a set of predefined pragma directives, which can be used for controlling the behavior of the compiler, for example how it allocates memory, whether it allows extended keywords, and whether it outputs warning messages. Most pragma directives are preprocessed, which means that macros are substituted in a pragma directive. The pragma directives are always enabled in the compiler. For several of them there is also a corresponding C/C++ language extension. For information about available pragma directives, see the chapter *Pragma directives*.

Preprocessor extensions

The preprocessor of the compiler adheres to Standard C. The compiler also makes several preprocessor-related extensions available to you. For more information, see the chapter *The preprocessor*.

Intrinsic functions

The intrinsic functions provide direct access to low-level processor operations and can be very useful in, for example, time-critical routines. The intrinsic functions compile into inline code, either as a single instruction or as a short sequence of instructions. For more information about using intrinsic functions, see *Mixing C and assembler*, page 117. For information about available functions, see the chapter *Intrinsic functions*.

• Library functions

The IAR DLIB Library provides the C and C++ library definitions that apply to embedded systems. For more information, see *IAR DLIB Library*, page 303. For information about AVR-specific library functions, see *AVR-specific library functions*, page 310.

Note: Any use of these extensions, except for the pragma directives, makes your source code inconsistent with Standard C.

ENABLING LANGUAGE EXTENSIONS

You can choose different levels of language conformance by means of project options:

| Command line | IDE* | Description |
|--------------|------------------------------|--|
| strict | Strict | All IAR C language extensions are disabled; errors are issued for anything that is not part of Standard C. |
| None | Standard | All extensions to Standard C are enabled, but no extensions for embedded systems programming. For information about extensions, see IAR C language extensions, page 138. |
| -e | Standard with IAR extensions | All IAR C language extensions are enabled. |

Table 30: Language extensions

IAR C language extensions

The compiler provides a wide set of C language extensions. To help you to find the extensions required by your application, they are grouped like this in this section:

- Extensions for embedded systems programming—extensions specifically tailored for efficient embedded programming for the specific microcontroller you are using, typically to meet memory restrictions
- Relaxations to Standard C—that is, the relaxation of some minor Standard C issues
 and also some useful but minor syntax extensions, see Relaxations to Standard C,
 page 140.

EXTENSIONS FOR EMBEDDED SYSTEMS PROGRAMMING

The following language extensions are available both in the C and the C++ programming languages and they are well suited for embedded systems programming:

- Memory attributes, type attributes, and object attributes
 For information about the related concepts, the general syntax rules, and for reference information, see the chapter Extended keywords.
- Placement at an absolute address or in a named segment
 The @ operator or the directive #pragma location can be used for placing global and static variables at absolute addresses, or placing a variable or function in a named segment. For more information about using these features, see Controlling data and function placement in memory, page 164, and location, page 274.
- Alignment control

Each data type has its own alignment; for more information, see *Alignment*, page 231. If you want to change the alignment, the #pragma pack and #pragma data_alignment directives are available. If you want to check the alignment of an object, use the __ALIGNOF__() operator.

The __ALIGNOF__ operator is used for accessing the alignment of an object. It takes one of two forms:

- __ALIGNOF___ (type)
- __ALIGNOF__ (expression)

In the second form, the expression is not evaluated.

^{*} In the IDE, choose Project>Options> C/C++ Compiler>Language>Language conformance and select the appropriate option. Note that language extensions are enabled by default.

• Anonymous structs and unions

C++ includes a feature called anonymous unions. The compiler allows a similar feature for both structs and unions in the C programming language. For more information, see *Anonymous structs and unions*, page 162.

· Bitfields and non-standard types

In Standard C, a bitfield must be of the type int or unsigned int. Using IAR C language extensions, any integer type or enumeration can be used. The advantage is that the struct will sometimes be smaller. For more information, see *Bitfields*, page 233.

• static_assert()

The construction static_assert(const-expression, "message"); can be used in C/C++. The construction will be evaluated at compile time and if const-expression is false, a message will be issued including the message string.

Parameters in variadic macros

Variadic macros are the preprocessor macro equivalents of printf style functions. The preprocessor accepts variadic macros with no arguments, which means if no parameter matches the . . . parameter, the comma is then deleted in the ", ##__VA_ARGS__" macro definition. According to Standard C, the . . . parameter must be matched with at least one argument.

Dedicated segment operators

The compiler supports getting the start address, end address, and size for a segment with these built-in segment operators:

```
__segment_begin Returns the address of the first byte of the named segment.

__segment_end Returns the address of the first byte after the named segment.

__segment_size Returns the size of the named segment in bytes.
```

Note:

The operators can be used on named segments defined in the linker file.

These operators behave syntactically as if declared like:

```
void * __segment_begin(char const * segment)
void * __segment_end(char const * segment)
size_t * __segment_size(char const * segment)
```

When you use the @ operator or the #pragma location directive to place a data object or a function in a user-defined segment in the linker configuration file, the segment

operators can be used for getting the start and end address of the memory range where the segments were placed.

The named <code>segment</code> must be a string literal and it must have been declared earlier with the <code>#pragma</code> segment directive. If the segment was declared with a memory attribute <code>memattr</code>, the type of the <code>__segment_begin</code> operator is a pointer to <code>memattr</code> void. Otherwise, the type is a default pointer to <code>void</code>. Note that you must enable language extensions to use these operators.

Example

```
In this example, the type of the __segment_begin operator is void __huge *.
#pragma segment="MYSEGMENT" __huge
...
segment_start_address = __segment_begin("MYSEGMENT");
See also segment, page 279, and location, page 274.
```

RELAXATIONS TO STANDARD C

This section lists and briefly describes the relaxation of some Standard C issues and also some useful but minor syntax extensions:

• Arrays of incomplete types

An array can have an incomplete struct, union, or enum type as its element type. The types must be completed before the array is used (if it is), or by the end of the compilation unit (if it is not).

- Forward declaration of enum types
 - The extensions allow you to first declare the name of an enum and later resolve it by specifying the brace-enclosed list.
- Accepting missing semicolon at the end of a struct or union specifier
 A warning—instead of an error—is issued if the semicolon at the end of a struct or union specifier is missing.
- Null and void
 - In operations on pointers, a pointer to void is always implicitly converted to another type if necessary, and a null pointer constant is always implicitly converted to a null pointer of the right type if necessary. In Standard C, some operators allow this kind of behavior, while others do not allow it.
- Casting pointers to integers in static initializers
 - In an initializer, a pointer constant value can be cast to an integral type if the integral type is large enough to contain it. For more information about casting pointers, see *Casting*, page 238.

• Taking the address of a register variable

In Standard C, it is illegal to take the address of a variable specified as a register variable. The compiler allows this, but a warning is issued.

• long float means double

The type long float is accepted as a synonym for double.

• Repeated typedef declarations

Redeclarations of typedef that occur in the same scope are allowed, but a warning is issued.

Mixing pointer types

Assignment and pointer difference is allowed between pointers to types that are interchangeable but not identical; for example, unsigned char * and char *. This includes pointers to integral types of the same size. A warning is issued.

Assignment of a string constant to a pointer to any kind of character is allowed, and no warning is issued.

• Non-top level const

Assignment of pointers is allowed in cases where the destination type has added type qualifiers that are not at the top level (for example, int ** to int const **). Comparing and taking the difference of such pointers is also allowed.

• Non-1value arrays

A non-lvalue array expression is converted to a pointer to the first element of the array when it is used.

• Comments at the end of preprocessor directives

This extension, which makes it legal to place text after preprocessor directives, is enabled unless the strict Standard C mode is used. The purpose of this language extension is to support compilation of legacy code; we do *not* recommend that you write new code in this fashion.

An extra comma at the end of enum lists

Placing an extra comma is allowed at the end of an enum list. In strict Standard C mode, a warning is issued.

• A label preceding a }

In Standard C, a label must be followed by at least one statement. Therefore, it is illegal to place the label at the end of a block. The compiler allows this, but issues a warning.

Note that this also applies to the labels of switch statements.

• Empty declarations

An empty declaration (a semicolon by itself) is allowed, but a remark is issued (provided that remarks are enabled).

• Single-value initialization

Standard C requires that all initializer expressions of static arrays, structs, and unions are enclosed in braces.

Single-value initializers are allowed to appear without braces, but a warning is issued. The compiler accepts this expression:

```
struct str
{
   int a;
} x = 10;
```

• Declarations in other scopes

External and static declarations in other scopes are visible. In the following example, the variable y can be used at the end of the function, even though it should only be visible in the body of the if statement. A warning is issued.

```
int test(int x)
{
   if (x)
   {
      extern int y;
      y = 1;
   }
   return y;
}
```

• Expanding function names into strings with the function as context

Use any of the symbols __func__ or __FUNCTION__ inside a function body to make the symbol expand into a string that contains the name of the current function. Use the symbol __PRETTY_FUNCTION__ to also include the parameter types and return type. The result might, for example, look like this if you use the __PRETTY_FUNCTION__ symbol:

```
"void func(char)"
```

These symbols are useful for assertions and other trace utilities and they require that language extensions are enabled, see -e, page 203.

• Static functions in function and block scopes

Static functions may be declared in function and block scopes. Their declarations are moved to the file scope.

• Numbers scanned according to the syntax for numbers

Numbers are scanned according to the syntax for numbers rather than the pp-number syntax. Thus, 0x123e+1 is scanned as three tokens instead of one valid token. (If the --strict option is used, the pp-number syntax is used instead.)

Using C++

IAR Systems supports the C++ language. You can choose between the industry-standard Embedded C++ and Extended Embedded C++. This chapter describes what you need to consider when using the C++ language.

Overview

Embedded C++ is a proper subset of the C++ programming language which is intended for embedded systems programming. It was defined by an industry consortium, the Embedded C++ Technical Committee. Performance and portability are particularly important in embedded systems development, which was considered when defining the language. EC++ offers the same object-oriented benefits as C++, but without some features that can increase code size and execution time in ways that are hard to predict.

EMBEDDED C++

The following C++ features are supported:

- Classes, which are user-defined types that incorporate both data structure and behavior; the essential feature of inheritance allows data structure and behavior to be shared among classes
- Polymorphism, which means that an operation can behave differently on different classes, is provided by virtual functions
- Overloading of operators and function names, which allows several operators or functions with the same name, provided that their argument lists are sufficiently different
- Type-safe memory management using the operators new and delete
- Inline functions, which are indicated as particularly suitable for inline expansion.

C++ features that are excluded are those that introduce overhead in execution time or code size that are beyond the control of the programmer. Also excluded are features added very late before Standard C++ was defined. Embedded C++ thus offers a subset of C++ which is efficient and fully supported by existing development tools.

Embedded C++ lacks these features of C++:

- Templates
- Multiple and virtual inheritance
- Exception handling
- Runtime type information

- New cast syntax (the operators dynamic_cast, static_cast, reinterpret_cast, and const_cast)
- Namespaces
- The mutable attribute.

The exclusion of these language features makes the runtime library significantly more efficient. The Embedded C++ library furthermore differs from the full C++ library in that:

- The standard template library (STL) is excluded
- Streams, strings, and complex numbers are supported without the use of templates
- Library features which relate to exception handling and runtime type information (the headers except, stdexcept, and typeinfo) are excluded.

Note: The library is not in the std namespace, because Embedded C++ does not support namespaces.

EXTENDED EMBEDDED C++

IAR Systems' Extended EC++ is a slightly larger subset of C++ which adds these features to the standard EC++:

- Full template support
- Multiple and virtual inheritance
- Namespace support
- The mutable attribute
- The cast operators static_cast, const_cast, and reinterpret_cast.

All these added features conform to the C++ standard.

To support Extended EC++, this product includes a version of the standard template library (STL), in other words, the C++ standard chapters utilities, containers, iterators, algorithms, and some numerics. This STL is tailored for use with the Extended EC++ language, which means no exceptions, no multiple inheritance, and no support for runtime type information (rtti). Moreover, the library is not in the std namespace.

Note: A module compiled with Extended EC++ enabled is fully link-compatible with a module compiled without Extended EC++ enabled.

Enabling support for C++



In the compiler, the default language is C.

To compile files written in Embedded C++, you must use the --ec++ compiler option. See --ec++, page 203.

To take advantage of *Extended* Embedded C++ features in your source code, you must use the --eec++ compiler option. See --eec++, page 203.

For EC++ and EEC++, you must also use the IAR DLIB runtime library.



To enable EC++ or EEC++ in the IDE, choose **Project>Options>C/C++ Compiler>Language** and select the appropriate standard.

EC++ feature descriptions

When you write C++ source code for the IAR C/C++ Compiler for AVR, you must be aware of some benefits and some possible quirks when mixing C++ features—such as classes, and class members—with IAR language extensions, such as IAR-specific attributes.

USING IAR ATTRIBUTES WITH CLASSES

Static data members of C++ classes are treated the same way global variables are, and can have any applicable IAR type, memory, and object attribute.

Member functions are in general treated the same way free functions are, and can have any applicable IAR type, memory, and object attributes. Virtual member functions can only have attributes that are compatible with default function pointers, and constructors and destructors cannot have any such attributes.

The location operator @ and the #pragma location directive can be used on static data members and with all member functions.

Example

```
class MyClass
{
public:
    // Locate a static variable in __near memory at address 60
    static __near __no_init int mI @ 60;

    // Locate a static function in __nearfunc memory
    static __nearfunc void F();

    // Locate a function in __nearfunc memory
    __nearfunc void G();

    // Locate a virtual function in __nearfunc memory
    virtual __nearfunc void H();
```

```
// Locate a virtual function into SPECIAL
virtual void M() const volatile @ "SPECIAL";
};
```

The this pointer

The this pointer used for referring to a class object or calling a member function of a class object will by default have the data memory attribute for the default data pointer type. This means that such a class object can only be defined to reside in memory from which pointers can be implicitly converted to a default data pointer. This restriction might also apply to objects residing on a stack, for example temporary objects and auto objects.

Class memory

To compensate for this limitation, a class can be associated with a *class memory type*. The class memory type changes:

- the this pointer type in all member functions, constructors, and destructors into a pointer to class memory
- the default memory for static storage duration variables—that is, not auto variables—of the class type, into the specified class memory
- the pointer type used for pointing to objects of the class type, into a pointer to class memory.

Example

```
class __far C
public:
              // Has a this pointer of type C __far *
  void MyF();
  void MyF() const; // Has a this pointer of type
                   // C far const *
                   // Has a this pointer pointing into far
  C();
                   // memory
  C(C const &); // Takes a parameter of type C __far
                   // const & (also true of generated copy
                    // constructor)
  int mI;
};
C Ca;
                   // Resides in far memory instead of the
                   // default memory
                   // Resides in near memory, the 'this'
C __near Cb;
                   // pointer still points into far memory
void MyH()
                   // Resides on the stack
  C cd;
}
C *Cp1;
                    // Creates a pointer to far memory
C __near *Cp2; // Creates a pointer to near memory
```

Note: To place the C class in huge memory is not allowed, unless using the huge memory model, because a huge pointer cannot be implicitly converted into a __far pointer.

Whenever a class type associated with a class memory type, like C, must be declared, the class memory type must be mentioned as well:

```
class __far C;
```

Also note that class types associated with different class memories are not compatible types.

```
A built-in operator returns the class memory type associated with a class, __memory_of(class). For instance, __memory_of(C) returns __far.
```

When inheriting, the rule is that it must be possible to convert implicitly a pointer to a subclass into a pointer to its base class. This means that a subclass can have a *more* restrictive class memory than its base class, but not a *less* restrictive class memory.

```
class __far D : public C
```

```
{ // OK, same class memory
public:
  void MyG();
  int mJ;
};
class __near E : public C
{ // OK, near memory is inside far
public:
  void MyG() // Has a this pointer pointing into near memory
    MyF(); // Gets a this pointer into far memory
  }
  int mJ;
};
class F : public C
\{\ //\ {\tt OK},\ {\tt will}\ {\tt be}\ {\tt associated}\ {\tt with}\ {\tt same}\ {\tt class}\ {\tt memory}\ {\tt as}\ {\tt C}
public:
  void MyG();
  int mJ;
};
```

Note that the following is not allowed, unless using the huge memory model, because huge is not inside far memory:

```
class __huge G:public C
{
};
```

A new expression on the class will allocate memory in the heap associated with the class memory. A delete expression will naturally deallocate the memory back to the same heap. To override the default new and delete operator for a class, declare

```
void *operator new(size_t);
void operator delete(void *);
```

as member functions, just like in ordinary C++.

For more information about memory types, see *Memory types*, page 39.

FUNCTION TYPES

A function type with extern "C" linkage is compatible with a function that has C++ linkage.

Example

NEW AND DELETE OPERATORS

There are operators for new and delete for each memory that can have a heap, that is, tiny, near, far, and huge memory.

```
// Assumes that there is a heap in both __near and __far memory
void __near *operator new __near(__near_size_t);
void __far *operator new __far (__far_size_t);
void operator delete(void __near *);
void operator delete(void __far *);

// And correspondingly for array new and delete operators
void __near *operator new[] __near(__near_size_t);
void __far *operator new[] __far (__far_size_t);
void operator delete[](void __near *);
void operator delete[](void __far *);
```

Use this syntax if you want to override both global and class-specific operator new and operator delete for any data memory.

Note that there is a special syntax to name the operator new functions for each memory, while the naming for the operator delete functions relies on normal overloading.

New and delete expressions

A new expression calls the operator new function for the memory of the type given. If a class, struct, or union type with a class memory is used, the class memory will determine the operator new function called. For example,

```
void MyF()
  // Calls operator new __huge(__huge_size_t)
  int __huge *p = new __huge int;
  // Calls operator new __near(__near_size_t)
  int near *g = new int near;
  // Calls operator new[] __near(__near_size_t)
  int near *r = new near int[10];
  // Calls operator new __huge(__huge_size_t)
  class huge S
  };
  S *s = new S;
  // Calls operator delete(void __huge *)
  delete p;
  // Calls operator delete(void __near *)
  delete s:
  int __huge *t = new __far int;
  delete t; // Error: Causes a corrupt heap
}
```

Note that the pointer used in a delete expression must have the correct type, that is, the same type as that returned by the new expression. If you use a pointer to the wrong memory, the result might be a corrupt heap.

USING STATIC CLASS OBJECTS IN INTERRUPTS

If interrupt functions use static class objects that need to be constructed (using constructors) or destroyed (using destructors), your application will not work properly if the interrupt occurs before the objects are constructed, or after the objects are destroyed.

To avoid this, make sure that these interrupts are not enabled until the static objects have been constructed, and are disabled when returning from main or calling exit. For information about system startup, see *System startup and termination*, page 84.

Function local static class objects are constructed the first time execution passes through their declaration, and are destroyed when returning from main or when calling exit.

USING NEW HANDLERS

To handle memory exhaustion, you can use the set_new_handler function.

If you do not call <code>set_new_handler</code>, or call it with a NULL new handler, and operator new fails to allocate enough memory, it will call abort. The nothrow variant of the new operator will instead return NULL.

If you call <code>set_new_handler</code> with a non-NULL new handler, the provided new handler will be called by <code>operator</code> new if <code>operator</code> new fails to allocate memory. The new handler must then make more memory available and return, or abort execution in some manner. The <code>nothrow</code> variant of <code>operator</code> new will never return NULL in the presence of a new handler.

TEMPLATES

Extended EC++ supports templates according to the C++ standard, but not the export keyword. The implementation uses a two-phase lookup which means that the keyword typename must be inserted wherever needed. Furthermore, at each use of a template, the definitions of all possible templates must be visible. This means that the definitions of all templates must be in include files or in the actual source file.

DEBUG SUPPORT IN C-SPY

C-SPY® has built-in display support for the STL containers. The logical structure of containers is presented in the watch views in a comprehensive way that is easy to understand and follow. For more information about displaying STL containers in the C-SPY debugger, see the *C-SPY® Debugging Guide for AVR*.

EEC++ feature description

This section describes features that distinguish Extended EC++ from EC++.

TEMPLATES

Templates and data memory attributes

For data memory attributes to work as expected in templates, two elements of the standard C++ template handling were changed—class template partial specialization matching and function template parameter deduction.

In Extended Embedded C++, the class template partial specialization matching algorithm works like this:

When a pointer or reference type is matched against a pointer or reference to a template parameter type, the template parameter type will be the type pointed to, stripped of any data memory attributes, if the resulting pointer or reference type is the same.

Example

```
// We assume that __far is the memory type of the default
// pointer.
template<typename> class Z {};
template<typename T> class Z<T *> {};

Z<int __near *> Zn; // T = int __near
Z<int __far *> Zf; // T = int
Z<int *> Zd; // T = int
Z<int __huge *> Zh; // T = int __huge
```

In Extended Embedded C++, the function template parameter deduction algorithm works like this:

When function template matching is performed and an argument is used for the deduction; if that argument is a pointer to a memory that can be implicitly converted to a default pointer, do the parameter deduction as if it was a default pointer.

When an argument is matched against a reference, do the deduction as if the argument and the parameter were both pointers.

Example

For templates that are matched using this modified algorithm, it is impossible to get automatic generation of special code for pointers to "small" memory types. For "large" and "other" memory types (memory that cannot be pointed to by a default pointer) it is possible. To make it possible to write templates that are fully memory-aware—in the rare cases where this is useful—use the #pragma basic_template_matching directive in front of the template function declaration. That template function will then match without the modifications described above.

Example

```
// We assume that __far is the memory type of the default
// pointer.
#pragma basic_template_matching
template<typename T> void fun(T *);

void MyF()
{
  fun((int __near *) 0); // T = int __near
}
```

Non-type template parameters

It is allowed to have a reference to a memory type as a template parameter, even if pointers to that memory type are not allowed.

Example

```
extern int __near X;

template<__near int &y>
void Func()
{
   y = 17;
}

void Bar()
{
   Foo<X>();
}
```

The standard template library

The STL (standard template library) delivered with the product is tailored for Extended EC++, see *Extended Embedded C*++, page 144.

The containers in the STL, like vector and map, are memory attribute aware. This means that a container can be declared to reside in a specific memory type which has the following consequences:

- The container itself will reside in the chosen memory
- Allocations of elements in the container will use a heap for the chosen memory
- All references inside it use pointers to the chosen memory.

Example

```
#include <vector>
```

Note that this is illegal:

```
vector<int __near> __huge Z;
```

Note also that map<key, T>, multimap<key, T>, hash_map<key, T>, and hash_multimap<key, T> all use the memory of T. This means that the value_type of these collections will be pair<key, const T> mem where mem is the memory type of T. Supplying a key with a memory type is not useful.

Example

Note that two containers that only differ by the data memory attribute they use cannot be assigned to each other. Instead, the templated assign member method must be used.

```
#include <vector>
vector<int __near> X;
vector<int __huge> Y;

void MyF()
{
    // The templated assign member method will work
    X.assign(Y.begin(), Y.end());
    Y.assign(X.begin(), X.end());
}
```

VARIANTS OF CAST OPERATORS

In Extended EC++ these additional variants of C++ cast operators can be used:

```
const_cast<to>(from)
static_cast<to>(from)
reinterpret_cast<to>(from)
```

MUTABLE

The mutable attribute is supported in Extended EC++. A mutable symbol can be changed even though the whole class object is const.

NAMESPACE

The namespace feature is only supported in *Extended* EC++. This means that you can use namespaces to partition your code. Note, however, that the library itself is not placed in the std namespace.

THE STD NAMESPACE

The std namespace is not used in either standard EC++ or in Extended EC++. If you have code that refers to symbols in the std namespace, simply define std as nothing; for example:

```
#define std
```

You must make sure that identifiers in your application do not interfere with identifiers in the runtime library.

POINTER TO MEMBER FUNCTIONS

A pointer to a member function can only contain a default function pointer, or a function pointer that can implicitly be casted to a default function pointer. To use a pointer to a member function, make sure that all functions that should be pointed to reside in the default memory or a memory contained in the default memory.

Example

```
class X
{
public:
    __nearfunc void F();
};

void (__nearfunc X::*PMF)(void) = &X::F;
```

C++ language extensions

When you use the compiler in any C++ mode and enable IAR language extensions, the following C++ language extensions are available in the compiler:

• In a friend declaration of a class, the class keyword can be omitted, for example:

• Constants of a scalar type can be defined within classes, for example:

According to the standard, initialized static data members should be used instead.

• In the declaration of a class member, a qualified name can be used, for example:

```
struct A
{
  int A::F(); // Possible when using IAR language extensions
  int G(); // According to the standard
}:
```

• It is permitted to use an implicit type conversion between a pointer to a function with C linkage (extern "C") and a pointer to a function with C++ linkage (extern "C++"), for example:

According to the standard, the pointer must be explicitly converted.

• If the second or third operands in a construction that contains the ? operator are string literals or wide string literals (which in C++ are constants), the operands can be implicitly converted to char * or wchar_t *, for example:

- Default arguments can be specified for function parameters not only in the top-level function declaration, which is according to the standard, but also in typedef declarations, in pointer-to-function function declarations, and in pointer-to-member function declarations.
- In a function that contains a non-static local variable and a class that contains a non-evaluated expression (for example a sizeof expression), the expression can reference the non-static local variable. However, a warning is issued.
- An anonymous union can be introduced into a containing class by a typedef name.
 It is not necessary to first declare the union. For example:

```
typedef union
{
  int i,j;
} U; // U identifies a reusable anonymous union.

class A
{
public:
  U; // OK -- references to A::i and A::j are allowed.
};
```

In addition, this extension also permits *anonymous classes* and *anonymous structs*, as long as they have no C++ features (for example, no static data members or member functions, and no non-public members) and have no nested types other than other anonymous classes, structs, or unions. For example:

```
struct A
{
   struct
   {
     int i,j;
   }; // OK -- references to A::i and A::j are allowed.
};
```

• The friend class syntax allows nonclass types as well as class types expressed through a typedef without an elaborated type name. For example:

Note: If you use any of these constructions without first enabling language extensions, errors are issued.

Efficient coding for embedded applications

For embedded systems, the size of the generated code and data is very important, because using smaller external memory or on-chip memory can significantly decrease the cost and power consumption of a system.

The topics discussed are:

- Selecting data types
- Controlling data and function placement in memory
- Controlling compiler optimizations
- Facilitating good code generation.

As a part of this, the chapter also demonstrates some of the more common mistakes and how to avoid them, and gives a catalog of good coding techniques.

Selecting data types

For efficient treatment of data, you should consider the data types used and the most efficient placement of the variables. This section provides useful information for efficient treatment of data:

- Locating strings in ROM, RAM or flash
- Using efficient data types
- Floating-point types
- Memory model and memory attributes for data
- Using the best pointer type
- Anonymous structs and unions.

LOCATING STRINGS IN ROM, RAM OR FLASH

With the IAR C/C++ Compiler for AVR there are three possible locations for storing strings:

- In external ROM in the data memory space
- In internal RAM in the data memory space
- In flash in the code memory space.

To read more about this, see *Initialized data*, page 59.

Locating strings in flash

This can be done on individual strings or for the whole application/file using the option --string_literals_in_flash. Examples on how to locate individual strings into flash:

```
__flash char str1[] = "abcdef";
__flash char str2[] = "ghi";
__flash char __flash * pVar[] = { str1, str2 };
```

String literals cannot be put in flash automatically, but you can use a local static variable instead:

```
#include <pgmspace.h>
void f (int i)
{
   static __flash char sl[] = "%d cookies\n";
   printf_P(sl, i);
}
```

This does not result in more code compared to allowing string literals in flash.

To use flash strings, you must use alternative library routines that expect flash strings. A few such alternative functions are provided—they are declared in the pgmspace.h header file. They are flash alternatives for some common C library functions with an extension _P. For your own code, you can always use the __flash keyword when passing the strings between functions.

For reference information about the alternative functions, see *AVR-specific library functions*, page 310.

USING EFFICIENT DATA TYPES

The data types you use should be considered carefully, because this can have a large impact on code size and code speed.

• Use small and unsigned data types, (unsigned char and unsigned short) unless your application really requires signed values.

- Try to avoid 64-bit data types, such as double and long long.
- Bitfields with sizes other than 1 bit should be avoided because they will result in inefficient code compared to bit operations.
- When using arrays, it is more efficient if the type of the index expression matches
 the index type of the memory of the array. For __near, the index type is int.
- Using floating-point types on a microprocessor without a math co-processor is very inefficient, both in terms of code size and execution speed.
- Declaring a pointer parameter to point to const data tells the calling function that the data pointed to will not change, which opens for better optimizations.

For information about representation of supported data types, pointers, and structures types, see the chapter *Data representation*.

FLOATING-POINT TYPES

Using floating-point types on a microprocessor without a math coprocessor is very inefficient, both in terms of code size and execution speed. Thus, you should consider replacing code that uses floating-point operations with code that uses integers, because these are more efficient.

The compiler supports two floating-point formats—32 and 64 bits. The 32-bit floating-point type float is more efficient in terms of code size and execution speed. However, the 64-bit format double supports higher precision and larger numbers.

In the compiler, the floating-point type float always uses the 32-bit format. The format used by the double floating-point type depends on the setting of the --64bit_doubles compiler option (Use 64-bit doubles).

By default, a *floating-point constant* in the source code is treated as being of the type double. This can cause innocent-looking expressions to be evaluated in double precision. In the example below a is converted from a float to a double, the double constant 1.0 is added and the result is converted back to a float:

```
double Test(float a)
{
    return a + 1.0;
}
```

To treat a floating-point constant as a float rather than as a double, add the suffix f to it, for example:

```
double Test(float a)
{
    return a + 1.0f;
}
```

For more information about floating-point types, see *Floating-point types*, page 235.

MEMORY MODEL AND MEMORY ATTRIBUTES FOR DATA

For many applications it is sufficient to use the memory model feature to specify the default memory for the data objects. However, for individual objects it might be necessary to specify other memory attributes in certain cases, for example:

- An application where some global variables are accessed from a large number of locations. In this case they can be declared to be placed in memory with a smaller pointer type
- An application where all data, with the exception of one large chunk of data, fits into the region of one of the smaller memory types
- Data that must be placed at a specific memory location.

The IAR C/C++ Compiler for AVR provides memory attributes for placing data objects in the different memory spaces, and for the DATA and CODE space (flash) there are different memory attributes for placing data objects in different memory types, see *Using data memory attributes*, page 39.

Efficient usage of memory type attributes can significantly reduce the application size.

For details about the memory types, see *Memory types*, page 39.

USING THE BEST POINTER TYPE

The generic pointers, pointers declared __generic, can point to all memory spaces, which makes them simple and also tempting to use. However, they carry a cost in that special code is needed before each pointer access to check which memory a pointer points to and taking the appropriate actions. Use the smallest pointer type you can, and avoid any generic pointers unless necessary. For details about available pointer types, see *Pointer types*, page 237.

ANONYMOUS STRUCTS AND UNIONS

When a structure or union is declared without a name, it becomes anonymous. The effect is that its members will only be seen in the surrounding scope.

Anonymous structures are part of the C++ language; however, they are not part of the C standard. In the IAR C/C++ Compiler for AVR they can be used in C if language extensions are enabled.



In the IDE, language extensions are enabled by default.



Use the -e compiler option to enable language extensions. See -e, page 203, for additional information.

Example

In this example, the members in the anonymous union can be accessed, in function F, without explicitly specifying the union name:

```
struct S
{
   char mTag;
   union
   {
      long mL;
      float mF;
   };
} St;

void F(void)
{
   St.mL = 5;
}
```

The member names must be unique in the surrounding scope. Having an anonymous struct or union at file scope, as a global, external, or static variable is also allowed. This could for instance be used for declaring I/O registers, as in this example:

```
__no_init volatile
union
{
   unsigned char IOPORT;
   struct
   {
      unsigned char way: 1;
      unsigned char out: 1;
   };
} @ 8;

/* The variables are used here. */
void Test(void)
{
   IOPORT = 0;
   way = 1;
   out = 1;
}
```

This declares an I/O register byte IOPORT at address 8. The I/O register has 2 bits declared, Way and Out. Note that both the inner structure and the outer union are anonymous.

Anonymous structures and unions are implemented in terms of objects named after the first field, with a prefix _A_ to place the name in the implementation part of the namespace. In this example, the anonymous union will be implemented through an object named _A_IOPORT.

Controlling data and function placement in memory

The compiler provides different mechanisms for controlling placement of functions and data objects in memory. To use memory efficiently, you should be familiar with these mechanisms to know which one is best suited for different situations. You can use:

Memory models

Use the different compiler options for memory models to take advantage of the different addressing modes available for the microcontroller and thereby also place data objects in different parts of memory. For more information about memory models, see *Memory models*, page 38, and *Function storage*, page 47, respectively.

Memory attributes

Use memory attributes to override the default addressing mode and placement of individual functions and data objects. For more information about memory attributes for data and functions, see *Using data memory attributes*, page 39, and *Using function memory attributes*, page 47, respectively.

The @ operator and the #pragma location directive for absolute placement
 Use the @ operator or the #pragma location directive to place individual global and
 static variables at absolute addresses. The variables must be declared either
 __no_init or const.

This is useful for individual data objects that must be located at a fixed address to conform to external requirements, for example to populate interrupt vectors or other hardware tables. Note that it is not possible to use this notation for absolute placement of individual functions.

• The @ operator and the #pragma location directive for segment placement

Use the @ operator or the #pragma location directive to place groups of functions
or global and static variables in named segments, without having explicit control of
each object. The variables must be declared either __no_init or const. The
segments can, for example, be placed in specific areas of memory, or initialized or
copied in controlled ways using the segment begin and end operators. This is also
useful if you want an interface between separately linked units, for example an
application project and a boot loader project. Use named segments when absolute
control over the placement of individual variables is not needed, or not useful.

• The --segment option

Use the --segment option to place functions and/or data objects in named segments, which is useful, for example, if you want to direct them to different fast or slow memories. In contrast to using the @ operator or the #pragma location directive, there are no restrictions on what types of variables that can be placed in named segments when using the --segment option. For more information about the --segment option, see --segment, page 222.

At compile time, data and functions are placed in different segments, see *Data segments*, page 57, and *Code segments*, page 65, respectively. At link time, one of the most important functions of the linker is to assign load addresses to the various segments used by the application. All segments, except for the segments holding absolute located data, are automatically allocated to memory according to the specifications of memory ranges in the linker configuration file, see *Placing segments in memory*, page 54.

DATA PLACEMENT AT AN ABSOLUTE LOCATION

The @ operator, alternatively the #pragma location directive, can be used for placing global and static variables at absolute addresses. The variables must be declared using one of these combinations of keywords:

- __no_init
- __no_init and const (without initializers).
- const (with initializers).

To place a variable at an absolute address, the argument to the @ operator and the #pragma location directive should be a literal number, representing the actual address.

Note: All declarations of variables placed at an absolute address are *tentative definitions*. Tentatively defined variables are only kept in the output from the compiler if they are needed in the module being compiled. Such variables will be defined in all modules in which they are used, which will work as long as they are defined in the same way. The recommendation is to place all such declarations in header files that are included in all modules that use the variables.

Examples

In this example, a __no_init declared variable is placed at an absolute address. This is useful for interfacing between multiple processes, applications, etc:

```
__no_init volatile char alpha @ 0xFF2000;/* OK */
```

The next example contains two const declared objects. The first one is not initialized, and the second one is initialized to a specific value. Both objects are placed in ROM. This is useful for configuration parameters, which are accessible from an external

interface. Note that in the second case, the compiler is not obliged to actually read from the variable, because the value is known.

In the first case, the value is not initialized by the compiler; the value must be set by other means. The typical use is for configurations where the values are loaded to ROM separately, or for special function registers that are read-only.

These examples show incorrect usage:

C++ considerations

In C++, module scoped const variables are static (module local), whereas in C they are global. This means that each module that declares a certain const variable will contain a separate variable with this name. If you link an application with several such modules all containing (via a header file), for instance, the declaration:

```
volatile const __no_init int x @ 0x100; /* Bad in C++ */
```

the linker will report that more than one variable is located at address 0x100.

To avoid this problem and make the process the same in C and C++, you should declare these variables extern, for example:

```
/* The extern keyword makes x public. */
extern volatile const __no_init int x @ 0x100;
```

Note: C++ static member variables can be placed at an absolute address just like any other static variable.

DATA AND FUNCTION PLACEMENT IN SEGMENTS

The following methods can be used for placing data or functions in named segments other than default:

- The @ operator, alternatively the #pragma location directive, can be used for
 placing individual variables or individual functions in named segments. The named
 segment can either be a predefined segment, or a user-defined segment. The
 variables must be declared either __no_init or const. If declared const, they
 can have initializers.
- The --segment option can be used for placing variables and functions, which are parts of the whole compilation unit, in named segments.

C++ static member variables can be placed in named segments just like any other static variable.

If you use your own segments, in addition to the predefined segments, the segments must also be defined in the linker configuration file using the -z or the -P segment control directives.

Note: Take care when explicitly placing a variable or function in a predefined segment other than the one used by default. This is useful in some situations, but incorrect placement can result in anything from error messages during compilation and linking to a malfunctioning application. Carefully consider the circumstances; there might be strict requirements on the declaration and use of the function or variable.

The location of the segments can be controlled from the linker configuration file.

For more information about segments, see the chapter Segment reference.

Examples of placing variables in named segments

In the following examples, a data object is placed in a user-defined segment.

```
__no_init int alpha @ "MY_NOINIT"; /* OK */

#pragma location="MY_CONSTANTS"

const int beta; /* OK */

const int gamma @ "MY_CONSTANTS" = 3;/* OK */
```

As usual, you can use memory attributes to direct the variable to a non-default memory (and then also place the segment accordingly in the linker configuration file):

```
__huge __no_init int alpha @ "MY_HUGE_NOINIT";/* Placed in huge*/
```

This example shows incorrect usage:

Examples of placing functions in named segments

```
void f(void) @ "MY_FUNCTIONS";

void g(void) @ "MY_FUNCTIONS"
{
}

#pragma location="MY_FUNCTIONS"
void h(void);
```

Specify a memory attribute to direct the function to a specific memory, and then modify the segment placement in the linker configuration file accordingly:

```
__farfunc void f(void) @ "MY_FARFUNC_FUNCTIONS";
```

Controlling compiler optimizations

The compiler performs many transformations on your application to generate the best possible code. Examples of such transformations are storing values in registers instead of memory, removing superfluous code, reordering computations in a more efficient order, and replacing arithmetic operations by cheaper operations.

The linker should also be considered an integral part of the compilation system, because some optimizations are performed by the linker. For instance, all unused functions and variables are removed and not included in the final output.

SCOPE FOR PERFORMED OPTIMIZATIONS

You can decide whether optimizations should be performed on your whole application or on individual files. By default, the same types of optimizations are used for an entire project, but you should consider using different optimization settings for individual files. For example, put code that must execute very quickly into a separate file and compile it for minimal execution time, and the rest of the code for minimal code size. This will give a small program, which is still fast enough where it matters.

You can also exclude individual functions from the performed optimizations. The #pragma optimize directive allows you to either lower the optimization level, or specify another type of optimization to be performed. See *optimize*, page 275, for information about the pragma directive.

MULTI-FILE COMPILATION UNITS

In addition to applying different optimizations to different source files or even functions, you can also decide what a compilation unit consists of—one or several source code files.

By default, a compilation unit consists of one source file, but you can also use multi-file compilation to make several source files in a compilation unit. The advantage is that interprocedural optimizations such as inlining, cross call, and cross jump have more source code to work on. Ideally, the whole application should be compiled as one compilation unit. However, for large applications this is not practical because of resource restrictions on the host computer. For more information, see --mfc, page 212.

If the whole application is compiled as one compilation unit, it is very useful to make the compiler also discard unused public functions and variables before the interprocedural optimizations are performed. Doing this limits the scope of the optimizations to functions and variables that are actually used. For more information, see --discard unused publics, page 201.

OPTIMIZATION LEVELS

The compiler supports different levels of optimizations. This table lists optimizations that are typically performed on each level:

| Optimization level | Description |
|-----------------------------|---|
| None (Best debug support) | Variables live through their entire scope |
| Low | Same as above but variables only live for as long as they are needed, not necessarily through their entire scope Dead code elimination Redundant label elimination Redundant branch elimination |
| Medium | Same as above, and: Live-dead analysis and optimization Code hoisting Register content analysis and optimization Common subexpression elimination Static clustering |
| High (Maximum optimization) | Same as above, and: Peephole optimization Cross jumping Cross call (when optimizing for size) Loop unrolling Function inlining Code motion Type-based alias analysis |

Table 31: Compiler optimization levels

Note: Some of the performed optimizations can be individually enabled or disabled. For more information about these, see *Fine-tuning enabled transformations*, page 170.

A high level of optimization might result in increased compile time, and will most likely also make debugging more difficult, because it is less clear how the generated code relates to the source code. For example, at the low, medium, and high optimization levels, variables do not live through their entire scope, which means processor registers used for storing variables can be reused immediately after they were last used. Due to this, the C-SPY Watch window might not be able to display the value of the variable throughout its scope. At any time, if you experience difficulties when debugging your code, try lowering the optimization level.

SPEED VERSUS SIZE

At the high optimization level, the compiler balances between size and speed optimizations. However, it is possible to fine-tune the optimizations explicitly for either size or speed. They only differ in what thresholds that are used; speed will trade size for speed, whereas size will trade speed for size. Note that one optimization sometimes enables other optimizations to be performed, and an application might in some cases become smaller even when optimizing for speed rather than size.

FINE-TUNING ENABLED TRANSFORMATIONS

At each optimization level you can disable some of the transformations individually. To disable a transformation, use either the appropriate option, for instance the command line option --no_inline, alternatively its equivalent in the IDE **Function inlining**, or the #pragma optimize directive. These transformations can be disabled individually:

- Common subexpression elimination
- Loop unrolling
- Function inlining
- Code motion
- Type-based alias analysis
- Static clustering
- · Cross call.

Common subexpression elimination

Redundant re-evaluation of common subexpressions is by default eliminated at optimization levels Medium and High. This optimization normally reduces both code size and execution time. However, the resulting code might be difficult to debug.

Note: This option has no effect at optimization levels None and Low.

For more information about the command line option, see --no cse, page 213.

Function inlining

Function inlining means that a simple function, whose definition is known at compile time, is integrated into the body of its caller to eliminate the overhead of the call. This optimization, which is performed at optimization level High, normally reduces execution time, but the resulting code might be difficult to debug.

The compiler heuristically decides which functions to inline. Different heuristics are used when optimizing for speed, size, or when balancing between size and speed. Normally, code size does not increase when optimizing for size. To control the heuristics

for individual functions, use the #pragma inline directive or the Standard C inline keyword.

If you do not want to disable inlining for a whole module, use #pragma inline=never on an individual function instead.

Note: This option has no effect at optimization levels None, Low, and Medium.

For more information about the command line option, see *--no_inline*, page 214. For information about the pragma directive, see *inline*, page 272.

Code motion

Evaluation of loop-invariant expressions and common subexpressions are moved to avoid redundant re-evaluation. This optimization, which is performed at optimization level High, normally reduces code size and execution time. The resulting code might however be difficult to debug.

Note: This option has no effect at optimization levels None, and Low.

For more information about the command line option, see --no code motion, page 213.

Type-based alias analysis

When two or more pointers reference the same memory location, these pointers are said to be *aliases* for each other. The existence of aliases makes optimization more difficult because it is not necessarily known at compile time whether a particular value is being changed.

Type-based alias analysis optimization assumes that all accesses to an object are performed using its declared type or as a char type. This assumption lets the compiler detect whether pointers can reference the same memory location or not.

Type-based alias analysis is performed at optimization level High. For application code conforming to standard C or C++ application code, this optimization can reduce code size and execution time. However, non-standard C or C++ code might result in the compiler producing code that leads to unexpected behavior. Therefore, it is possible to turn this optimization off.

Note: This option has no effect at optimization levels None, Low, and Medium.

For more information about the command line option, see --no tbaa, page 215.

Example

```
short F(short *p1, long *p2)
{
    *p2 = 0;
    *p1 = 1;
```

```
return *p2;
}
```

With type-based alias analysis, it is assumed that a write access to the short pointed to by p1 cannot affect the long value that p2 points to. Thus, it is known at compile time that this function returns 0. However, in non-standard-conforming C or C++ code these pointers could overlap each other by being part of the same union. If you use explicit casts, you can also force pointers of different pointer types to point to the same memory location.

Static clustering

When static clustering is enabled, static and global variables that are defined within the same module are arranged so that variables that are accessed in the same function are stored close to each other. This makes it possible for the compiler to use the same base pointer for several accesses.

Note: This option has no effect at optimization levels None and Low.

For more information about the command line option, see --no clustering, page 212.

Cross call

Common code sequences are extracted to local subroutines. This optimization, which is performed at optimization level High size, can reduce code size, sometimes dramatically, on behalf of execution time and stack size. The resulting code might however be difficult to debug. This optimization cannot be disabled using the #pragma optimize directive.

Note: This option has no effect at optimization levels None, Low, and Medium, unless the option --do_cross_call is used.

For more information about related command line options, see --no_cross_call, page 213, --do cross call, page 202, and --cross call passes, page 196.

Facilitating good code generation

This section contains hints on how to help the compiler generate good code, for example:

- Using efficient addressing modes
- Helping the compiler optimize
- Generating more useful error message.

WRITING OPTIMIZATION-FRIENDLY SOURCE CODE

The following is a list of programming techniques that will, when followed, enable the compiler to better optimize the application.

- Local variables—auto variables and parameters—are preferred over static or global variables. The reason is that the optimizer must assume, for example, that called functions can modify non-local variables. When the life spans for local variables end, the previously occupied memory can then be reused. Globally declared variables will occupy data memory during the whole program execution.
- Avoid taking the address of local variables using the & operator. This is inefficient
 for two main reasons. First, the variable must be placed in memory, and thus cannot
 be placed in a processor register. This results in larger and slower code. Second, the
 optimizer can no longer assume that the local variable is unaffected over function
 calls.
- Module-local variables—variables that are declared static—are preferred over global variables (non-static). Also avoid taking the address of frequently accessed static variables.
- The compiler is capable of inlining functions, see Function inlining, page 170. To maximize the effect of the inlining transformation, it is good practice to place the definitions of small functions called from more than one module in the header file rather than in the implementation file. Alternatively, you can use multi-file compilation. For more information, see Multi-file compilation units, page 168.
- Avoid using inline assembler. Instead, try writing the code in C or C++, use intrinsic functions, or write a separate module in assembler language. For more information, see Mixing C and assembler, page 117.

SAVING STACK SPACE AND RAM MEMORY

The following is a list of programming techniques that will, when followed, save memory and stack space:

- If stack space is limited, avoid long call chains and recursive functions.
- Avoid using large non-scalar types, such as structures, as parameters or return type.
 To save stack space, you should instead pass them as pointers or, in C++, as references.

FUNCTION PROTOTYPES

It is possible to declare and define functions using one of two different styles:

- Prototyped
- Kernighan & Ritchie C (K&R C)

Both styles are included in the C standard; however, it is recommended to use the prototyped style, since it makes it easier for the compiler to find problems in the code. Using the prototyped style will also make it possible to generate more efficient code, since type promotion (implicit casting) is not needed. The K&R style is only supported for compatibility reasons.

To make the compiler verify that all functions have proper prototypes, use the compiler option **Require prototypes** (--require_prototypes).

Prototyped style

In prototyped function declarations, the type for each parameter must be specified.

```
int Test(char, int); /* Declaration */
int Test(char ch, int i) /* Definition */
{
   return i + ch;
}
```

Kernighan & Ritchie style

In K&R style—pre-Standard C—it is not possible to declare a function prototyped. Instead, an empty parameter list is used in the function declaration. Also, the definition looks different.

For example:

INTEGER TYPES AND BIT NEGATION

In some situations, the rules for integer types and their conversion lead to possibly confusing behavior. Things to look out for are assignments or conditionals (test expressions) involving types with different size, and logical operations, especially bit negation. Here, *types* also includes types of constants.

In some cases there might be warnings (for example, for constant conditional or pointless comparison), in others just a different result than what is expected. Under certain circumstances the compiler might warn only at higher optimizations, for example, if the compiler relies on optimizations to identify some instances of constant

conditionals. In this example an 8-bit character, a 16-bit integer, and two's complement is assumed:

```
void F1(unsigned char c1)
{
   if (c1 == ~0x80)
   ;
}
```

Here, the test is always false. On the right hand side, 0x80 is 0x0080, and $\sim0x0080$ becomes 0xFF7F. On the left hand side, c1 is an 8-bit unsigned character, so it cannot be larger than 255. It also cannot be negative, which means that the integral promoted value can never have the topmost 8 bits set.

PROTECTING SIMULTANEOUSLY ACCESSED VARIABLES

Variables that are accessed asynchronously, for example by interrupt routines or by code executing in separate threads, must be properly marked and have adequate protection. The only exception to this is a variable that is always *read-only*.

To mark a variable properly, use the volatile keyword. This informs the compiler, among other things, that the variable can be changed from other threads. The compiler will then avoid optimizing on the variable (for example, keeping track of the variable in registers), will not delay writes to it, and be careful accessing the variable only the number of times given in the source code.

For sequences of accesses to variables that you do not want to be interrupted, use the __monitor keyword. This must be done for both write *and* read sequences, otherwise you might end up reading a partially updated variable. Accessing a small-sized volatile variable can be an atomic operation, but you should not rely on it unless you continuously study the compiler output. It is safer to use the __monitor keyword to ensure that the sequence is an atomic operation. For more information, see __monitor, page 257.

For more information about the volatile type qualifier and the rules for accessing volatile objects, see *Declaring objects volatile*, page 240.



Protecting the eeprom write mechanism

A typical example of when it can be necessary to use the __monitor keyword is when protecting the eeprom write mechanism, which can be used from two threads (for example, main code and interrupts). Servicing an interrupt during an EEPROM write sequence can in many cases corrupt the written data.

ACCESSING SPECIAL FUNCTION REGISTERS

Specific header files for several AVR devices are included in the IAR product installation. The header files are named iodevice.h and define the processor-specific special function registers (SFRs).

To enable bit definitions in IAR Embedded Workbench, select the option General Options>System>Enable bit definitions in I/O include files.

Note: Each header file contains one section used by the compiler, and one section used by the assembler.

SFRs with bitfields are declared in the header file. This example is from iom128.h:

By including the appropriate include file in your code, it is possible to access either the whole register or any individual bit (or bitfields) from C code as follows:

```
/* whole register access */
PORTE = 0x12;
/* Bitfield accesses */
PORTE_Bit0 = 1;
```

You can also use the header files as templates when you create new header files for other AVR devices. For information about the @ operator, see *Located data*, page 65.

NON-INITIALIZED VARIABLES

Normally, the runtime environment will initialize all global and static variables when the application is started.

The compiler supports the declaration of variables that will not be initialized, using the __no_init type modifier. They can be specified either as a keyword or using the #pragma object_attribute directive. The compiler places such variables in a

separate segment, according to the specified memory keyword. See the chapter *Placing code and data* for more information.

For __no_init, the const keyword implies that an object is read-only, rather than that the object is stored in read-only memory. It is not possible to give a __no_init object an initial value.

Variables declared using the __no_init keyword could, for example, be large input buffers or mapped to special RAM that keeps its content even when the application is turned off.

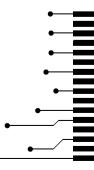
For information about the __no_init keyword, see page 259. Note that to use this keyword, language extensions must be enabled; see -e, page 203. For information about the #pragma object_attribute, see page 275.

Facilitating good code generation

Part 2. Reference information

This part of the IAR C/C++ Compiler Reference Guide for AVR contains these chapters:

- External interface details
- Compiler options
- Data representation
- Extended keywords
- Pragma directives
- Intrinsic functions
- The preprocessor
- Library functions
- Segment reference
- Implementation-defined behavior.





External interface details

This chapter provides reference information about how the compiler interacts with its environment. The chapter briefly lists and describes the invocation syntax, methods for passing options to the tools, environment variables, the include file search procedure, and finally the different types of compiler output.

Invocation syntax

You can use the compiler either from the IDE or from the command line. See the *IAR Embedded Workbench*® *IDE Project Management and Building Guide* for information about using the compiler from the IDE.

COMPILER INVOCATION SYNTAX

The invocation syntax for the compiler is:

```
iccavr [options] [sourcefile] [options]
```

For example, when compiling the source file prog.c, use this command to generate an object file with debug information:

```
iccavr prog.c --debug
```

The source file can be a C or C++ file, typically with the filename extension c or cpp, respectively. If no filename extension is specified, the file to be compiled must have the extension c.

Generally, the order of options on the command line, both relative to each other and to the source filename, is *not* significant. There is, however, one exception: when you use the $-\mathbb{I}$ option, the directories are searched in the same order as they are specified on the command line.

If you run the compiler from the command line without any arguments, the compiler version number and all available options including brief descriptions are directed to stdout and displayed on the screen.

PASSING OPTIONS

There are three different ways of passing options to the compiler:

Directly from the command line
 Specify the options on the command line after the iccavr command, either before or after the source filename; see *Invocation syntax*, page 181.

Via environment variables

The compiler automatically appends the value of the environment variables to every command line; see *Environment variables*, page 182.

• Via a text file, using the -f option; see -f, page 206.

For general guidelines for the option syntax, an options summary, and a detailed description of each option, see the *Compiler options* chapter.

ENVIRONMENT VARIABLES

These environment variables can be used with the compiler:

Environment variable Description

| C_INCLUDE | Specifies directories to search for include files; for example: | | |
|-----------|---|--|--|
| | <pre>C_INCLUDE=c:\program files\iar systems\embedded</pre> | | |
| | <pre>workbench 6.n\avr\inc;c:\headers</pre> | | |
| QCCAVR | Specifies command line options; for example: ${\tt QCCAVR=-lA}$ ${\tt asm.lst}$ | | |

Table 32: Compiler environment variables

Include file search procedure

This is a detailed description of the compiler's #include file search procedure:

- If the name of the #include file is an absolute path specified in angle brackets or double quotes, that file is opened.
- If the compiler encounters the name of an #include file in angle brackets, such as:

```
#include <stdio.h>
```

it searches these directories for the file to include:

- 1 The directories specified with the -I option, in the order that they were specified, see -I, page 208.
- 2 The directories specified using the C_INCLUDE environment variable, if any; see *Environment variables*, page 182.
- 3 The automatically set up library system include directories. See --clib, page 195, --dlib, page 201, and --dlib_config, page 202.
- If the compiler encounters the name of an #include file in double quotes, for example:

```
#include "vars.h"
```

it searches the directory of the source file in which the #include statement occurs, and then performs the same sequence as for angle-bracketed filenames.

If there are nested #include files, the compiler starts searching the directory of the file that was last included, iterating upwards for each included file, searching the source file directory last. For example:

```
src.c in directory dir\src
    #include "src.h"
    ...
src.h in directory dir\include
    #include "config.h"
    ...
```

When dir\exe is the current directory, use this command for compilation:

```
iccavr ..\src\src.c -I..\include -I..\debugconfig
```

Then the following directories are searched in the order listed below for the file config.h, which in this example is located in the dir\debugconfig directory:

dir\include Current file is src.h.

dir\src File including current file (src.c).

dir\include As specified with the first -I option.

dir\debugconfig As specified with the second -I option.

Use angle brackets for standard header files, like stdio.h, and double quotes for files that are part of your application.

For information about the syntax for including header files, see *Overview of the preprocessor*, page 293.

Compiler output

The compiler can produce the following output:

A linkable object file

The object files produced by the compiler use a proprietary format called UBROF, which stands for Universal Binary Relocatable Object Format. By default, the object file has the filename extension r90.

Optional list files

Various kinds of list files can be specified using the compiler option -1, see -*l*, page 209. By default, these files will have the filename extension 1st.

• Optional preprocessor output files

A preprocessor output file is produced when you use the --preprocess option; by default, the file will have the filename extension i.

• Diagnostic messages

Diagnostic messages are directed to the standard error stream and displayed on the screen, and printed in an optional list file. For more information about diagnostic messages, see *Diagnostics*, page 185.

Error return codes

These codes provide status information to the operating system which can be tested in a batch file, see *Error return codes*, page 184.

Size information

Information about the generated amount of bytes for functions and data for each memory is directed to the standard output stream and displayed on the screen. Some of the bytes might be reported as *shared*.

Shared objects are functions or data objects that are shared between modules. If any of these occur in more than one module, only one copy is retained. For example, in some cases inline functions are not inlined, which means that they are marked as shared, because only one instance of each function will be included in the final application. This mechanism is sometimes also used for compiler-generated code or data not directly associated with a particular function or variable, and when only one instance is required in the final application.

Error return codes

The compiler returns status information to the operating system that can be tested in a batch file.

These command line error codes are supported:

| Code | Description |
|------|--|
| 0 | Compilation successful, but there might have been warnings. |
| I | Warnings were produced and the optionwarnings_affect_exit_code was used. |
| 2 | Errors occurred. |
| 3 | Fatal errors occurred, making the compiler abort. |
| 4 | Internal errors occurred, making the compiler abort. |

Table 33: Error return codes

Diagnostics

This section describes the format of the diagnostic messages and explains how diagnostic messages are divided into different levels of severity.

MESSAGE FORMAT

All diagnostic messages are issued as complete, self-explanatory messages. A typical diagnostic message from the compiler is produced in the form:

filename, linenumber level[tag]: message

with these elements:

The name of the source file in which the issue was encountered

1 Inenumber The line number at which the compiler detected the issue

1evel The level of seriousness of the issue

A unique tag that identifies the diagnostic message

message An explanation, possibly several lines long

Diagnostic messages are displayed on the screen, as well as printed in the optional list file.

Use the option --diagnostics_tables to list all possible compiler diagnostic messages.

SEVERITY LEVELS

The diagnostic messages are divided into different levels of severity:

Remark

A diagnostic message that is produced when the compiler finds a source code construct that can possibly lead to erroneous behavior in the generated code. Remarks are by default not issued, but can be enabled, see *--remarks*, page 221.

Warning

A diagnostic message that is produced when the compiler finds a potential programming error or omission which is of concern, but which does not prevent completion of the compilation. Warnings can be disabled by use of the command line option --no_warnings, see page 217.

Error

A diagnostic message that is produced when the compiler finds a construct which clearly violates the C or C++ language rules, such that code cannot be produced. An error will produce a non-zero exit code.

Fatal error

A diagnostic message that is produced when the compiler finds a condition that not only prevents code generation, but which makes further processing of the source code pointless. After the message is issued, compilation terminates. A fatal error will produce a non-zero exit code.

SETTING THE SEVERITY LEVEL

The diagnostic messages can be suppressed or the severity level can be changed for all diagnostics messages, except for fatal errors and some of the regular errors.

See *Summary of compiler options*, page 190, for information about the compiler options that are available for setting severity levels.

See the chapter *Pragma directives*, for information about the pragma directives that are available for setting severity levels.

INTERNAL ERROR

An internal error is a diagnostic message that signals that there was a serious and unexpected failure due to a fault in the compiler. It is produced using this form:

```
Internal error: message
```

where *message* is an explanatory message. If internal errors occur, they should be reported to your software distributor or IAR Systems Technical Support. Include enough information to reproduce the problem, typically:

- The product name
- The version number of the compiler, which can be seen in the header of the list files generated by the compiler
- Your license number
- The exact internal error message text
- The source file of the application that generated the internal error
- A list of the options that were used when the internal error occurred.

Compiler options

This chapter describes the syntax of compiler options and the general syntax rules for specifying option parameters, and gives detailed reference information about each option.

Options syntax

Compiler options are parameters you can specify to change the default behavior of the compiler. You can specify options from the command line—which is described in more detail in this section—and from within the IDE.



See the *IAR Embedded Workbench*® *IDE Project Management and Building Guide* for information about the compiler options available in the IDE and how to set them.

TYPES OF OPTIONS

There are two *types of names* for command line options, *short* names and *long* names. Some options have both.

- A short option name consists of one character, and it can have parameters. You specify it with a single dash, for example −e
- A long option name consists of one or several words joined by underscores, and it can have parameters. You specify it with double dashes, for example
 --char_is_signed.

For information about the different methods for passing options, see *Passing options*, page 181.

RULES FOR SPECIFYING PARAMETERS

There are some general syntax rules for specifying option parameters. First, the rules depending on whether the parameter is *optional* or *mandatory*, and whether the option has a short or a long name, are described. Then, the rules for specifying filenames and directories are listed. Finally, the remaining rules are listed.

Rules for optional parameters

For options with a short name and an optional parameter, any parameter should be specified without a preceding space, for example:

-0 or -0h

For options with a long name and an optional parameter, any parameter should be specified with a preceding equal sign (=), for example:

```
--misrac2004=n
```

Rules for mandatory parameters

For options with a short name and a mandatory parameter, the parameter can be specified either with or without a preceding space, for example:

```
-I..\src or -I ..\src\
```

For options with a long name and a mandatory parameter, the parameter can be specified either with a preceding equal sign (=) or with a preceding space, for example:

```
--diagnostics_tables=MyDiagnostics.lst
or
--diagnostics_tables MyDiagnostics.lst
```

Rules for options with both optional and mandatory parameters

For options taking both optional and mandatory parameters, the rules for specifying the parameters are:

- For short options, optional parameters are specified without a preceding space
- For long options, optional parameters are specified with a preceding equal sign (=)
- For short and long options, mandatory parameters are specified with a preceding space.

For example, a short option with an optional parameter followed by a mandatory parameter:

```
-1A MyList.1st
```

For example, a long option with an optional parameter followed by a mandatory parameter:

```
--preprocess=n PreprocOutput.1st
```

Rules for specifying a filename or directory as parameters

These rules apply for options taking a filename or directory as parameters:

• Options that take a filename as a parameter can optionally take a file path. The path can be relative or absolute. For example, to generate a listing to the file List.lst in the directory ..\listings\:

```
iccavr prog.c -1 ..\listings\List.lst
```

• For options that take a filename as the destination for output, the parameter can be specified as a path without a specified filename. The compiler stores the output in that directory, in a file with an extension according to the option. The filename will be the same as the name of the compiled source file, unless a different name was specified with the option -o, in which case that name is used. For example:

```
iccavr prog.c -1 ..\listings\
```

The produced list file will have the default name ..\listings\prog.lst

• The *current directory* is specified with a period (.). For example:

```
iccavr prog.c -1 .
```

- / can be used instead of \ as the directory delimiter.
- By specifying -, input files and output files can be redirected to the standard input and output stream, respectively. For example:

```
iccavr prog.c -1 -
```

Additional rules

These rules also apply:

When an option takes a parameter, the parameter cannot start with a dash (-)
followed by another character. Instead, you can prefix the parameter with two
dashes; this example will create a list file called -r:

```
iccavr prog.c -1 ---r
```

 For options that accept multiple arguments of the same type, the arguments can be provided as a comma-separated list (without a space), for example:

```
--diag_warning=Be0001,Be0002
```

Alternatively, the option can be repeated for each argument, for example:

```
--diag warning=Be0001
```

⁻⁻diag_warning=Be0002

Summary of compiler options

This table summarizes the compiler command line options:

| Command line option | Description | |
|------------------------|---|--|
| 64bit_doubles | Forces the compiler to use 64-bit doubles | |
| 64k_flash | Specifies a maximum of 64 Kbytes flash memory | |
| c89 | Specifies the C89 dialect | |
| char_is_signed | Treats char as signed | |
| char_is_unsigned | Treats char as unsigned | |
| clib | Uses the system include files for the CLIB library | |
| cpu | Specifies a specific device | |
| cross_call_passes | Cross call optimization | |
| -D | Defines preprocessor symbols | |
| debug | Generates debug information | |
| dependencies | Lists file dependencies | |
| diag_error | Treats these as errors | |
| diag_remark | Treats these as remarks | |
| diag_suppress | Suppresses these diagnostics | |
| diag_warning | Treats these as warnings | |
| diagnostics_tables | Lists all diagnostic messages | |
| disable_direct_mode | Disables direct addressing mode | |
| discard_unused_publics | Discards unused public symbols | |
| dlib | Uses the system include files for the DLIB library | |
| dlib_config | Uses the system include files for the DLIB library and determines which configuration of the library to use | |
| do_cross_call | Forces the compiler to run the cross call optimizer. | |
| -e | Enables language extensions | |
| ec++ | Specifies Embedded C++ | |
| eec++ | Specifies Extended Embedded C++ | |
| eecr_address | Defines the EECR address | |
| eeprom_size | Specifies the EEPROM size | |
| enable_external_bus | Adds code to enable external data bus | |

Table 34: Compiler options summary

| Command line option | Description |
|---------------------------------|--|
| enable_multibytes | Enables support for multibyte characters in source files |
| enhanced_core | Enables enhanced instruction set |
| error_limit | Specifies the allowed number of errors before compilation stops |
| -f | Extends the command line |
| force_switch_type | Forces the switch type |
| guard_calls | Enables guards for function static variable initialization |
| header_context | Lists all referred source files and header files |
| -I | Specifies include file path |
| initializers_in_flash | Places aggregate initializers in flash memory |
| -1 | Creates a list file |
| library_module | Creates a library module |
| lock_regs | Locks registers |
| -m | Specifies a memory model |
| macro_positions_in _diagnostics | Obtains positions inside macros in diagnostic messages |
| memory_model | Specifies a memory model |
| mfc | Enables multi-file compilation |
| misrac | Enables error messages specific to MISRA-C:1998. This option is a synonym ofmisrac1998 and is only available for backwards compatibility. |
| misrac1998 | Enables error messages specific to MISRA-C:1998. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide. |
| misrac2004 | Enables error messages specific to MISRA-C:2004. See the IAR Embedded Workbench® MISRA C:2004 Reference Guide. |
| misrac_verbose | Enables verbose logging of MISRA C checking. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide or the IAR Embedded Workbench® MISRA C:2004 Reference Guide. |
| module_name | Sets the object module name |
| no_clustering | Disables static clustering optimizations |

Table 34: Compiler options summary (Continued)

| Command line option | Description |
|----------------------------|--|
| no_code_motion | Disables code motion optimization |
| no_cross_call | Disables cross-call optimization |
| no_cse | Disables common subexpression elimination |
| no_inline | Disables function inlining |
| no_path_in_file_macros | Removes the path from the return value of the symbolsFILE andBASE_FILE |
| no_rampd | Uses RAMPZ instead of RAMPD |
| no_static_destruction | Disables destruction of C++ static variables at program exit |
| no_system_include | Disables the automatic search for system include files |
| no_tbaa | Disables type-based alias analysis |
| no_typedefs_in_diagnostics | Disables the use of typedef names in diagnostics |
| no_ubrof_messages | Minimizes object file size |
| no_unroll | Disables loop unrolling |
| no_warnings | Disables all warnings |
| no_wrap_diagnostics | Disables wrapping of diagnostic messages |
| -O | Sets the optimization level |
| -0 | Sets the object filename. Alias foroutput. |
| omit_types | Excludes type information |
| only_stdout | Uses standard output only |
| output | Sets the object filename |
| predef_macros | Lists the predefined symbols. |
| preinclude | Includes an include file before reading the source file |
| preprocess | Generates preprocessor output |
| public_equ | Defines a global named assembler label |
| -r | Generates debug information. Alias fordebug. |
| relaxed_fp | Relaxes the rules for optimizing floating-point expressions |
| remarks | Enables remarks |
| require_prototypes | Verifies that functions are declared before they are defined |

Table 34: Compiler options summary (Continued)

| Command line option | Description | |
|--|---|--|
| root_variables | Specifies variables asroot | |
| -s | Optimizes for speed. | |
| segment | Changes a segment name | |
| separate_cluster_for_ initialized_variables | Separates initialized and non-initialized variables | |
| silent | Sets silent operation | |
| spmcr_address | Defines the SPMCR address | |
| strict | Checks for strict compliance with Standard C/C++ | |
| string_literals_in_flash | Puts "string" in thenearflash orfarflash segment | |
| system_include_dir | Specifies the path for system include files | |
| use_c++_inline | Uses C++ inline semantics in C99 | |
| -v | Specifies the processor variant | |
| version1_calls | Uses the ICCA90 calling convention | |
| vla | Enables C99 VLA support | |
| warnings_affect_exit_code | Warnings affect exit code | |
| warnings_are_errors | Warnings are treated as errors | |
| -у | Places constants and literals | |
| -z | Optimizes for size | |
| zero_register | Specifies register R15 as the zero register | |

Table 34: Compiler options summary (Continued)

Descriptions of compiler options

The following section gives detailed reference information about each compiler option.



Note that if you use the options page **Extra Options** to specify specific command line options, the IDE does not perform an instant check for consistency problems like conflicting options, duplication of options, or use of irrelevant options.

--64bit doubles

Syntax --64bit_doubles

Description Use this option to force the compiler to use 64-bit doubles instead of 32-bit doubles

which is the default.

See also *Floating-point types*, page 235.

X

To set related options, choose:

Project>Options>General Options>Target

--64k flash

Syntax --64k_flash

Description This option tells the compiler that the intended target processor does not have more than

64 Kbytes program flash memory (small flash), and that the AVR core therefore does

not have the ${\tt RAMPZ}$ register or the ${\tt ELPM}$ instruction.

This option can only be used together with the -v2, -v3, and -v4 processor options.

X

Project>Options>General Options>Target (No RAMPZ register)

--c89

Syntax --c89

Description Use this option to enable the C89 C dialect instead of Standard C.

Note: This option is mandatory when the MISRA C checking is enabled.

See also *C language overview*, page 135.

×

Project>Options>General Options>Language>C dialect>C89

--char_is_signed

Syntax --char_is_signed

Description By default, the compiler interprets the plain char type as unsigned. Use this option to

make the compiler interpret the plain char type as signed instead. This can be useful when you, for example, want to maintain compatibility with another compiler.

Note: The runtime library is compiled without the --char_is_signed option and cannot be used with code that is compiled with this option.

X

Project>Options>C/C++ Compiler>Language>Plain 'char' is

--char_is_unsigned

Syntax --char_is_unsigned

the default interpretation of the plain char type.

X

Project>Options>C/C++ Compiler>Language>Plain 'char' is

--clib

Syntax --clib

Description Use this option to use the system header files for the CLIB library; the compiler will

automatically locate the files and use them when compiling.

Note: The CLIB library is used by default: To use the DLIB library, use the --dlib or

the --dlib_config option instead.

See also --dlib, page 201 and --dlib config, page 202.

X

To set related options, choose:

Project>Options>General Options>Library Configuration

--cpu

Syntax --cpu=processor

Parameters

processor Specifies a specific device

Description The compiler supports different processor variants. Use this option to select a specific

processor variant for which the code will be generated.

Note that to specify the processor, you can use either the --cpu option or the -v option. The --cpu option is, however, more precise because it contains more information about

the intended target than the more generic -v option.

See also -v, page 226, Processor configuration, page 30.

X

To set related options, choose:

Project>Options>General Options>Processor configuration

--cross_call_passes

Syntax --cross_call_passes=N

N

Parameters

The number of times to run the cross call optimizer, which can be 1-5.

Description Use this option to decrease the RSTACK usage by running the cross-call optimizer. The

default is to run it until no more improvements can be made.

Note: Use this option if you have a target processor with a hardware stack or a small

internal return stack segment, RSTACK.

See also --no_cross_call, page 213

X

To set related options, choose:

Project>Options>C/C++ Compiler>Optimizations

-D

Syntax -D symbol[=value]

Parameters

symbol The name of the preprocessor symbol

value The value of the preprocessor symbol

Description

Use this option to define a preprocessor symbol. If no value is specified, 1 is used. This option can be used one or more times on the command line.

The option -D has the same effect as a #define statement at the top of the source file:

-Dsymbol

is equivalent to:

#define symbol 1

To get the equivalence of:

#define FOO

specify the = sign but nothing after, for example:

-DFOO=



Project>Options>C/C++ Compiler>Preprocessor>Defined symbols

--debug, -r

Syntax --debug -r

Description

Use the --debug or -r option to make the compiler include information in the object modules required by the IAR C-SPY® Debugger and other symbolic debuggers.

Note: Including debug information will make the object files larger than otherwise.



Project>Options>C/C++ Compiler>Output>Generate debug information

--dependencies

Parameters

i (default) Lists only the names of files

m Lists in makefile style

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 188.

Description

Use this option to make the compiler list the names of all source and header files opened for input into a file with the default filename extension i.

Example

If --dependencies or --dependencies=i is used, the name of each opened input file, including the full path, if available, is output on a separate line. For example:

```
c:\iar\product\include\stdio.h
d:\myproject\include\file.h
```

If --dependencies=m is used, the output is in makefile style. For each input file, one line containing a makefile dependency rule is produced. Each line consists of the name of the object file, a colon, a space, and the name of an input file. For example:

```
file.r90: c:\iar\product\include\stdio.h
file.r90: d:\myproject\include\file.h
```

An example of using --dependencies with a popular make utility, such as gmake (GNU make):

I Set up the rule for compiling files to be something like:

```
%.r90 : %.c
    $(ICC) $(ICCFLAGS) $< --dependencies=m $*.d</pre>
```

That is, in addition to producing an object file, the command also produces a dependency file in makefile style (in this example, using the extension .d).

2 Include all the dependency files in the makefile using, for example:

```
-include $(sources:.c=.d)
```

Because of the dash (-) it works the first time, when the .d files do not yet exist.



This option is not available in the IDE.

--diag_error

Syntax --diag_error=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe117

Description

Use this option to reclassify certain diagnostic messages as errors. An error indicates a violation of the C or C++ language rules, of such severity that object code will not be generated. The exit code will be non-zero. This option may be used more than once on the command line.



Project>Options>C/C++ Compiler>Diagnostics>Treat these as errors

--diag_remark

Syntax --diag_remark=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe177

Description

Use this option to reclassify certain diagnostic messages as remarks. A remark is the least severe type of diagnostic message and indicates a source code construction that may cause strange behavior in the generated code. This option may be used more than once on the command line.

Note: By default, remarks are not displayed; use the --remarks option to display them.



Project>Options>C/C++ Compiler>Diagnostics>Treat these as remarks

--diag_suppress

Syntax --diag_suppress=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe117

Description

Use this option to suppress certain diagnostic messages. These messages will not be displayed. This option may be used more than once on the command line.



Project>Options>C/C++ Compiler>Diagnostics>Suppress these diagnostics

--diag_warning

Syntax --diag_warning=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe826

Description Use this option to reclassify certain diagnostic messages as warnings. A warning

indicates an error or omission that is of concern, but which will not cause the compiler to stop before compilation is completed. This option may be used more than once on the

command line.



Project>Options>C/C++ Compiler>Diagnostics>Treat these as warnings

--diagnostics_tables

Syntax --diagnostics_tables {filename | directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a*

filename or directory as parameters, page 188.

Description Use this option to list all possible diagnostic messages in a named file. This can be

convenient, for example, if you have used a pragma directive to suppress or change the

severity level of any diagnostic messages, but forgot to document why.

This option cannot be given together with other options.



This option is not available in the IDE.

--disable_direct_mode

Syntax --disable_direct_mode

Description Use this option to prevent the compiler from generating the direct addressing mode

instructions LDS and STS.

X

To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--discard_unused_publics

Syntax --discard_unused_publics

Description Use this option to discard unused public functions and variables when compiling with

the --mfc compiler option.

Note: Do not use this option only on parts of the application, as necessary symbols

might be removed from the generated output.

See also --mfc, page 212 and Multi-file compilation units, page 168.

X

Project>Options>C/C++ Compiler>Discard unused publics

--dlib

Syntax --dlib

Description Use this option to use the system header files for the DLIB library; the compiler will

automatically locate the files and use them when compiling.

Note: The DLIB library is used by default: To use the CLIB library, use the --clib

option instead.

See also --dlib config, page 202, --no system include, page 215, --system include dir, page

225, and --clib, page 195.

X

To set related options, choose:

Project>Options>General Options>Library Configuration

--dlib_config

Syntax --dlib_config filename.h|config

Parameters

filename A DLIB configuration header file. For information about specifying

a filename, see Rules for specifying a filename or directory as

parameters, page 188.

config The default configuration file for the specified configuration will be

used. Choose between:

none, no configuration will be used

normal, the normal library configuration will be used (default)

full, the full library configuration will be used.

Description

Each runtime library has a corresponding library configuration file. Use this option to explicitly specify which library configuration file to use, either by specifying an explicit file or by specifying a library configuration—in which case the default file for that library configuration will be used. Make sure that you specify a configuration that corresponds to the library you are using. If you do not specify this option, the default library configuration file will be used.

All prebuilt runtime libraries are delivered with corresponding configuration files. You can find the library object files and the library configuration files in the directory avr\lib. For examples and information about prebuilt runtime libraries, see *Using a prebuilt library*, page 73.

If you build your own customized runtime library, you should also create a corresponding customized library configuration file, which must be specified to the compiler. For more information, see *Building and using a customized library*, page 82.

Note: This option only applies to the IAR DLIB runtime environment.



To set related options, choose:

Project>Options>General Options>Library Configuration

--do_cross_call

Syntax --do_cross_call

Description Use this option to force the compiler to run the cross call optimizer, regardless of the

optimization level. The cross call optimizer is otherwise only run at high size

optimization.

See also -O, page 217



To set related options, choose:

Project>Options>C/C++ Compiler>Optmization

-е

Syntax -e

Description In the command line version of the compiler, language extensions are disabled by

default. If you use language extensions such as extended keywords and anonymous structs and unions in your source code, you must use this option to enable them.

Note: The -e option and the --strict option cannot be used at the same time.

See also Enabling language extensions, page 137.

X

Project>Options>C/C++ Compiler>Language>Standard with IAR extensions

Note: By default, this option is selected in the IDE.

--ec++

Syntax --ec++

Description In the compiler, the default language is C. If you use Embedded C++, you must use this

option to set the language the compiler uses to Embedded C++.

X

Project>Options>C/C++ Compiler>Language>Embedded C++

--eec++

Syntax --eec++

Description In the compiler, the default language is C. If you take advantage of Extended Embedded

C++ features like namespaces or the standard template library in your source code, you must use this option to set the language the compiler uses to Extended Embedded C++.

See also Extended Embedded C++, page 144.

Project>Options>C/C++ Compiler>Language>Extended Embedded C++

--eecr_address

Syntax --eecr_address address

Parameters

address The value of the EECR address. The default is 0x1C.

Description If you use the -v processor option, the --eecr_address option can be used for

modifying the value of the EECR address.

If you use the --cpu processor option, the --eecr_address option is implicitly set,

which means you should not use these options together.

See also -v, page 226 and --cpu, page 196.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--eeprom_size

Syntax --eeprom_size=N

Parameters

N The size of the EEPROM in bytes, 0-65536.

Description Use this option to enable the __eeprom extended keyword by specifying the size of the

built-in EEPROM.

To use the __eeprom extended keyword, language extensions must be enabled.

See also Function storage, page 47, -e, page 203 and language, page 273.



To set related options, choose:

Project>Options>C/C++ Compiler>Code

--enable_external_bus

Syntax --enable_external_bus

Description Use this option to make the compiler add the special __require statement which

makes XLINK include the code in startup. s90 that enables the external data bus. Use

this option if you intend to place RSTACK in external RAM.

Note: The code in cstartup.s90 that enables the external data bus is preferably placed in low_level_init instead.

See also The return address stack, page 63.



Project>Options>General Options>System

--enable_multibytes

Syntax --enable_multibytes

Description

By default, multibyte characters cannot be used in C or C++ source code. Use this option to make multibyte characters in the source code be interpreted according to the host computer's default setting for multibyte support.

Multibyte characters are allowed in C and C++ style comments, in string literals, and in character constants. They are transferred untouched to the generated code.



Project>Options>C/C++ Compiler>Language>Enable multibyte support

--enhanced_core

Syntax --enhanced_core

Description

Use this option to allow the compiler to generate instructions from the enhanced instruction set that is available in some AVR devices, for example ATmega161.

The enhanced instruction set consists of these instructions:

MUL MOVW MULS MULSU FMUL FMULS FMULSU LPM Rd, Z LPM Rd, Z ELPM Rd, Z ELPM Rd, Z+



Project>Options>General Options>Enhanced core

--error limit

Syntax --error_limit=n

n

Parameters

The number of errors before the compiler stops the compilation.

n must be a positive integer; 0 indicates no limit.

Description Use the --error_limit option to specify the number of errors allowed before the

compiler stops the compilation. By default, 100 errors are allowed.



This option is not available in the IDE.

-f

Syntax -f filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or*

directory as parameters, page 188.

Descriptions Use this option to make the compiler read command line options from the named file,

with the default filename extension xc1.

In the command file, you format the items exactly as if they were on the command line itself, except that you may use multiple lines, because the newline character acts just as

a space or tab character.

Both C and C++ style comments are allowed in the file. Double quotes behave in the

same way as in the Microsoft Windows command line environment.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--force_switch_type

Syntax --force_switch_type={0|1|2}

Parameters

Library call with switch table
 Inline code with switch table

2 Inline compare/jump logic

Description Use this option to set the switch type.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

-f

Syntax -f filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or*

directory as parameters, page 188.

Descriptions Use this option to make the compiler read command line options from the named file,

with the default filename extension xc1.

In the command file, you format the items exactly as if they were on the command line itself, except that you may use multiple lines, because the newline character acts just as

a space or tab character.

Both C and C++ style comments are allowed in the file. Double quotes behave in the

same way as in the Microsoft Windows command line environment.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--guard_calls

Syntax --guard_calls

Description Use this option to enable guards for function static variable initialization. This option

should be used in a threaded C++ environment.

See also *Managing a multithreaded environment*, page 166.

X

To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--header_context

Syntax --header_context

Description Occasionally, to find the cause of a problem it is necessary to know which header file

that was included from which source line. Use this option to list, for each diagnostic

message, not only the source position of the problem, but also the entire include stack at that point.



This option is not available in the IDE.

-I

Syntax -I path

Parameters

path The search path for #include files

Description Use this option to specify the search paths for #include files. This option can be used

more than once on the command line.

See also Include file search procedure, page 182.



Project>Options>C/C++ Compiler>Preprocessor>Additional include directories

--initializers in flash

Syntax --initializers_in_flash

Description

Use this option to place aggregate initializers in flash memory. These initializers are otherwise placed in the external segments _C or in the flash segments _F if the compiler

option -y was also specified.

An aggregate initializer—an array or a struct—is constant data that is copied to the stack dynamically at runtime, in this case every time a function is entered.

The drawback of placing data in flash memory is that it takes more time to copy it; the advantage is that it does not occupy memory in the data space.

Local variables with aggregate initializers are copied from the segments:

| Data | Default | -у | initializers_in_flash |
|-----------------|---------|--------|-----------------------|
| auto aggregates | NEAR_C | NEAR_F | NEAR_F |

Table 35: Accessing variables with aggregate initializers

Example

```
void Func ()
{
  char buf[4] = { '1', 'd', 'g', 't' };
  ...
}
```

See also

-y, page 229 and Initialization of local aggregates at function invocation, page 60.



To set related options, choose:

Project>Options>C/C++ Compiler>Code

-1

Syntax

-1[a|A|b|B|c|C|D][N][H] { filename | directory}

Parameters

| a (default) | Assembler list file |
|-------------|--|
| A | Assembler list file with C or C++ source as comments |
| b | Basic assembler list file. This file has the same contents as a list file produced with $-1a$, except that no extra compiler-generated information (runtime model attributes, call frame information, frame size information) is included * |
| В | Basic assembler list file. This file has the same contents as a list file produced with ${\tt -1A},$ except that no extra compiler generated information (runtime model attributes, call frame information, frame size information) is included * |
| С | C or C++ list file |
| C (default) | C or C++ list file with assembler source as comments |
| D | C or C++ list file with assembler source as comments, but without instruction offsets and hexadecimal byte values |
| N | No diagnostics in file |
| Н | Include source lines from header files in output. Without this option, only source lines from the primary source file are included |
| | |

st This makes the list file less useful as input to the assembler, but more useful for reading by a human.

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 188.

Description

Use this option to generate an assembler or C/C++ listing to a file. Note that this option can be used one or more times on the command line.



To set related options, choose:

Project>Options>C/C++ Compiler>List

--library_module

Syntax --library_module

Description Use

Use this option to make the compiler generate a library module rather than a program module. A program module is always included during linking. A library module will only be included if it is referenced in your program.



Project>Options>C/C++ Compiler>Output>Module type>Library Module

--lock_regs

Syntax --lock_regs N

N

Parameters

The number of registers to lock, 0-12.

Description

Use this option to lock registers that are to be used for global register variables. When you use this option, the registers R15 and downwards will be locked.

To maintain module consistency, make sure to lock the same number of registers in all modules.

Note: Locking more than nine registers might cause linking to fail. Because the pre-built libraries delivered with the product do not lock any registers, a library function might potentially use any of the lockable registers. Any such resource conflict between locked registers and compiler-used registers will be reported at link time.

If you need to lock any registers in your code, the library must therefore be rebuilt with the same set of locked registers.



To set related options, choose:

Project>Options>C/C++ Compiler>Code

--macro_positions_in_diagnostics

Syntax --macro_positions_in_diagnostics

Description Use this option to obtain position references inside macros in diagnostic messages. This

is useful for detecting incorrect source code constructs in macros.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--memory_model, -m

 $\label{eq:syntax} --\texttt{memory}_\texttt{model} = \{\texttt{tiny} | \texttt{t} | \texttt{small} | \texttt{s} | \texttt{large} | \texttt{l} | \texttt{huge} | \texttt{h} \}$

-m{tiny|t|small|s|large|1<huge|h}

Parameters

tiny, t Specifies the Tiny memory model

small, s

Specifies the Small memory model

large, 1

Specifies the Large memory model

huge, h

Specifies the Huge memory model

Description Use this option to specify the memory model, for which the code is to be generated.

By default, the compiler generates code for the Tiny memory model for all processor

options except -v4 and -v6 where the Small memory model is the default.

Use the -m or the --memory_model option if you want to generate code for a different

memory model.

Example To generate code for the Large memory model, give the command:

iccavr filename -ml

or:

iccavr filename --memory_model=large

See also *Memory models*, page 38

X

To set related options, choose:

Project>Options>General Options>Memory model

--mfc

Syntax --mfc

Description Use this option to enable *multi-file compilation*. This means that the compiler compiles

one or several source files specified on the command line as one unit, which enhances

interprocedural optimizations.

Note: The compiler will generate one object file per input source code file, where the first object file contains all relevant data and the other ones are empty. If you want only the first file to be produced, use the -o compiler option and specify a certain output file.

Example iccavr myfile1.c myfile2.c myfile3.c --mfc

See also --discard unused publics, page 201, --output, -o, page 218, and Multi-file compilation

units, page 168.



Project>Options>C/C++ Compiler>Multi-file compilation

--module name

Syntax --module_name=name

Parameters

name An explicit object module name

Description Normally, the internal name of the object module is the name of the source file, without

a directory name or extension. Use this option to specify an object module name

explicitly.

This option is useful when several modules have the same filename, because the resulting duplicate module name would normally cause a linker error; for example,

when the source file is a temporary file generated by a preprocessor.



Project>Options>C/C++ Compiler>Output>Object module name

--no_clustering

Syntax --no_clustering

Description Use this option to disable static clustering optimizations.

Note: This option has no effect at optimization levels None and Low.

See also Static clustering, page 172.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Static clustering

--no code motion

Syntax --no_code_motion

Description Use this option to disable code motion optimizations.

Note: This option has no effect at optimization levels below Medium.

See also *Code motion*, page 171.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Code motion

--no cross call

Syntax --no_cross_call

Description Use this option to disable the cross-call optimization. This is highly recommended if

your target processor has a hardware stack or a small internal return stack segment,

RSTACK, because this option reduces the usage of RSTACK.

This optimization is performed at size optimization, level High. Note that, although the optimization can drastically reduce the code size, this optimization increases the

execution time.

See also --cross call passes, page 196, Cross call, page 172.

X

Project>Options>C/C++ Compiler>Optimizations>Enabled optimizations>Cross call

--no cse

Syntax --no_cse

Description Use this option to disable common subexpression elimination.

Note: This option has no effect at optimization levels below Medium.

See also *Common subexpression elimination*, page 170.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Common subexpression elimination

--no inline

Syntax --no_inline

Description Use this option to disable function inlining.

Note: This option has no effect at optimization levels below High.

See also Function inlining, page 170.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Function inlining

--no_path_in_file_macros

Syntax --no_path_in_file_macros

Description Use this option to exclude the path from the return value of the predefined preprocessor

symbols __FILE__ and __BASE_FILE__.

See also Descriptions of predefined preprocessor symbols, page 294.

X

This option is not available in the IDE.

--no_rampd

Syntax --no_rampd

Description Use this option to make the compiler use the RAMPZ register instead of RAMPD. This

option corresponds to the instructions LDS and STS.

Note that this option is only useful on processor variants with more than 64 Kbytes data

(-v4 and -v6).

X

To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--no_static_destruction

Syntax --no_static_destruction

Description Normally, the compiler emits code to destroy C++ static variables that require

destruction at program exit. Sometimes, such destruction is not needed.

Use this option to suppress the emission of such code.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--no_system_include

Syntax --no_system_include

Description By default, the compiler automatically locates the system include files. Use this option

to disable the automatic search for system include files. In this case, you might need to

set up the search path by using the -I compiler option.

See also --clib, page 195, --dlib, page 201, --dlib_config, page 202, and --system_include_dir,

page 225.



Project>Options>C/C++ Compiler>Preprocessor>Ignore standard include directories

--no_tbaa

Syntax --no_tbaa

Description Use this option to disable type-based alias analysis.

See also *Type-based alias analysis*, page 171.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Type-based alias analysis

--no_typedefs_in_diagnostics

Syntax --no_typedefs_in_diagnostics

Description Use this option to disable the use of typedef names in diagnostics. Normally, when a

type is mentioned in a message from the compiler, most commonly in a diagnostic message of some kind, the typedef names that were used in the original declaration are

used whenever they make the resulting text shorter.

Example typedef int (*MyPtr)(char const *);

MyPtr p = "foo";

will give an error message like this:

Error[Pe144]: a value of type "char *" cannot be used to initialize an entity of type "MyPtr"

If the --no_typedefs_in_diagnostics option is used, the error message will be like

Error[Pe144]: a value of type "char *" cannot be used to initialize an entity of type "int (*)(char const *)"



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--no_ubrof_messages

Syntax --no_ubrof_messages

Description Use this option to minimize the size of your application object file by excluding

messages from the UBROF files. A file size decrease of up to 60% can be expected. Note that the XLINK diagnostic messages will, however, be less useful when you use this $\dot{}$

option.

X

To set related options, choose:

Project>Options>C/C++ Compiler>Output>No error messages in output files

--no_warnings

Syntax --no_warnings

Description By default, the compiler issues warning messages. Use this option to disable all warning

messages.

X

This option is not available in the IDE.

--no_wrap_diagnostics

Syntax --no_wrap_diagnostics

Description By default, long lines in diagnostic messages are broken into several lines to make the

message easier to read. Use this option to disable line wrapping of diagnostic messages.



This option is not available in the IDE.

-O

Syntax -O[n|1|m|h|hs|hz]

Parameters

n None* (Best debug support)

1 (default) Low*

m Medium

h High, balanced. Corresponds to the option -s9.

hs High, favoring speed

hz High, favoring size. Corresponds to the option -z9.

*The most important difference between None and Low is that at None, all non-static variables will live during their entire scope.

Description

Use this option to set the optimization level to be used by the compiler when optimizing the code. If no optimization option is specified, the optimization level Low is used by default. If only -0 is used without any parameter, the optimization level High balanced

is used.

A low level of optimization makes it relatively easy to follow the program flow in the debugger, and, conversely, a high level of optimization makes it relatively hard.

See also

Controlling compiler optimizations, page 168, -O, page 217, and -z, page 229.



--omit_types

Project>Options>C/C++ Compiler>Optimizations

--omit_types

Syntax

Description

By default, the compiler includes type information about variables and functions in the object output. Use this option if you do not want the compiler to include this type information in the output, which is useful when you build a library that should not contain type information. The object file will then only contain type information that is a part of a symbol's name. This means that the linker cannot check symbol references for type correctness.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--only_stdout

Syntax --only_stdout

Description

Use this option to make the compiler use the standard output stream (stdout) also for messages that are normally directed to the error output stream (stderr).



This option is not available in the IDE.

--output, -o

Parameters

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 188.

Description

By default, the object code output produced by the compiler is located in a file with the same name as the source file, but with the extension r90. Use this option to explicitly specify a different output filename for the object code output.



This option is not available in the IDE.

--predef_macros

Syntax --predef_macros {filename|directory}

Parameters For information about specifying a filename, see *Rules for specifying a filename or*

directory as parameters, page 188.

Description Use this option to list the predefined symbols. When using this option, make sure to also

use the same options as for the rest of your project.

If a filename is specified, the compiler stores the output in that file. If a directory is specified, the compiler stores the output in that directory, in a file with the predef

filename extension.

Note that this option requires that you specify a source file on the command line.



This option is not available in the IDE.

--preinclude

Syntax --preinclude includefile

Parameters For information about specifying a filename, see *Rules for specifying a filename or*

directory as parameters, page 188.

Description

Use this option to make the compiler read the specified include file before it starts to

read the source file. This is useful if you want to change something in the source code

for the entire application, for instance if you want to define a new symbol.



Project>Options>C/C++ Compiler>Preprocessor>Preinclude file

--preprocess

Syntax --preprocess[=[c][n][1]] {filename|directory}

Parameters

c Preserve comments

n Preprocess only

1 Generate #line directives

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 188.

Description

Use this option to generate preprocessed output to a named file.



Project>Options>C/C++ Compiler>Preprocessor>Preprocessor output to file

--public_equ

Syntax --public_equ symbol[=value]

Parameters

symbolThe name of the assembler symbol to be definedvalueAn optional value of the defined assembler symbol

Description

This option is equivalent to defining a label in assembler language using the EQU directive and exporting it using the PUBLIC directive. This option can be used more than once on the command line.



This option is not available in the IDE.

--relaxed_fp

Syntax

--relaxed fp

Description

Use this option to allow the compiler to relax the language rules and perform more aggressive optimization of floating-point expressions. This option improves performance for floating-point expressions that fulfill these conditions:

- The expression consists of both single- and double-precision values
- The double-precision values can be converted to single precision without loss of accuracy
- The result of the expression is converted to single precision.

Note that performing the calculation in single precision instead of double precision might cause a loss of accuracy.

Example

```
float F(float a, float b)
{
  return a + b * 3.0;
}
```

The C standard states that 3.0 in this example has the type double and therefore the whole expression should be evaluated in double precision. However, when the

--relaxed_fp option is used, 3.0 will be converted to float and the whole expression can be evaluated in float precision.



Project>Options>General Options>Language>Relaxed floating-point precision

--remarks

Syntax --remarks

Description The least severe diagnostic messages are called remarks. A remark indicates a source

code construct that may cause strange behavior in the generated code. By default, the compiler does not generate remarks. Use this option to make the compiler generate

remarks.

See also Severity levels, page 185.



Project>Options>C/C++ Compiler>Diagnostics>Enable remarks

--require_prototypes

Syntax --require_prototypes

Description

Use this option to force the compiler to verify that all functions have proper prototypes. Using this option means that code containing any of the following will generate an error:

- A function call of a function with no declaration, or with a Kernighan & Ritchie C declaration
- A function definition of a public function with no previous prototype declaration
- An indirect function call through a function pointer with a type that does not include a prototype.



Project>Options>C/C++ Compiler>Language>Require prototypes

--root variables

Syntax --root_variables

Description Use this option to apply the __root extended keyword to all global and static variables.

This will make sure that the variables are not removed by the IAR XLINK Linker.

Note: The --root_variables option is always available, even if you do not specify the compiler option -e, language extensions.



To set related options, choose:

Project>Options>C/C++ Compiler>Code>Force generation of all global and static variables

-s

Syntax -s[2|3|6|9]

Parameters

2 None* (Best debug support)

3 (default) Low*
6 Medium

9 High (Maximum optimization)

*The most important difference between -s2 and -s3 is that at level 2, all non-static variables will live during their entire scope.

Description

Use this option to make the compiler optimize the code for maximum execution speed. If no optimization option is specified, the optimization level 3 is used by default.

A low level of optimization makes it relatively easy to follow the program flow in the debugger, and, conversely, a high level of optimization makes it relatively hard.

Note: The -s and -z options cannot be used at the same time.

See also -O, page 217



Project>Options>C/C++ Compiler>Optimizations>Speed

--segment

Syntax --segment __memory_attribute=NEWSEGMENTNAME

Description

The compiler places functions and data objects into named segments which are referred to by the IAR XLINK Linker. Use the --segment option to place all functions or data

objects declared with the __memory_attribute in segments with names that begin with NEWSEGMENTNAME.

This is useful if you want to place your code or data in different address ranges and you find the @ notation, alternatively the #pragma location directive, insufficient. Note that any changes to the segment names require corresponding modifications in the linker configuration file.

Example I This command places the __near int a; defined variable in the MYDATA_Z segment:

--segment __near=MYDATA

Example2 This command names the segmet that contains interrupt vectors to MYINTS instead of

the default name INTVEC:

--segment intvec=MYINTS

See also Controlling data and function placement in memory, page 164 and Summary of extended

keywords, page 249.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--separate_cluster_for_initialized_variables

Syntax --separate_cluster_for_initialized_variables

Description Use this option to separate initialized and non-initialized variables when using variable

clustering. The option makes the *_ID segments smaller but can generate larger code.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--silent

Syntax --silent

Description By default, the compiler issues introductory messages and a final statistics report. Use this option to make the compiler operate without sending these messages to the standard

output stream (normally the screen).

This option does not affect the display of error and warning messages.

This option is not available in the IDE.

--spmcr_address

Syntax --spmcr_address address

Parameters

address The SPMCR address, where 0x37 is the default.

Description Use this option to set the SPMCR address.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--strict

Syntax --strict

Description By default, the compiler accepts a relaxed superset of Standard C and C++. Use this

option to ensure that the source code of your application instead conforms to strict

Standard C and C++.

Note: The -e option and the --strict option cannot be used at the same time.

See also Enabling language extensions, page 137.



Project>Options>C/C++ Compiler>Language>Language conformance>Strict

--string_literals_in_flash

Syntax --string_literals_in_flash

Description Use this option to put "string" in the __nearflash or __farflash segment depending

on the processor option.

When this option is used, library functions taking a string literal as a parameter will no

longer be type-compatible. Use the *_P library function variants (for example

printf_P).

See also AVR-specific library functions, page 310



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--system_include_dir

Syntax --system_include_dir path

Parameters

path The path to the system include files. For information about

specifying a path, see Rules for specifying a filename or directory as

parameters, page 188.

Description By default, the compiler automatically locates the system include files. Use this option

to explicitly specify a different path to the system include files. This might be useful if

you have not installed IAR Embedded Workbench in the default location.

See also --clib, page 195, --dlib, page 201, --dlib_config, page 202, and --no_system_include,

page 215.

X

This option is not available in the IDE.

--use_c++_inline

Syntax --use_c++_inline

Description Standard C uses slightly different semantics for the inline keyword than C++ does.

Use this option to get C++ semantics when compiling a Standard C source code file.

The main difference in semantics is that in Standard C you cannot in general simply supply an inline definition in a header file. You need to supply an external definition in one of the compilation units, possibly by designating the inline definition as being external in that compilation unit.

emerican in that compilation unit

X

Project>Options>C/C++ Compiler>Language>C dialect>C99>C++ inline semantics

-v

Syntax

-v{0|1|2|3|4|5|6}

Parameters

| Parameter | Description |
|-------------|--|
| 0 (default) | The code space is physically limited to 8 Kbytes, and the RCALL/RJMP instructions are used for reaching the code space. Interrupt vectors are 2 bytes long. The compiler assumes that the index registers X, Y, and Z are eight bits wide when accessing the built-in SRAM. It also assumes that it is not possible to attach any external memory to the microcontroller and that it therefore should not gen erate any constant segment in data space (_C segment). Instead the compiler adds an implicit -y command line option. It will also try to place all aggregate initializers in flash memory, that is, the implicitinitializers_in_flash option is also added to the command line. Relative function calls are made. |
| 1 | The code space is physically limited to 8 Kbytes, and the RCALL/RJMP instructions are used for reaching the code space. Interrupt vectors are 2 bytes long. The compiler assumes that it is possible to have external memory and will therefore generate $_$ C segments. Relative function calls are made. |
| 2 | The code space is physically limited to 128 Kbytes, and, if possible, the RCALL/RJMP instructions are used for reaching the code space. If that is not possible, CALL/JMP is used. Function calls through function pointers use ICALL/IJMP. 2 bytes are used for all function pointers. Interrupt vectors are 4 bytes long. The compiler assumes that the index registers X, Y, and Z are eight bits wide when accessing the built-in SRAM. It also assumes that it is not possible to attach any external memory to the microcontroller and that it should therefore not generate any constant segment in data space (_C segment). Instead the compiler adds an implicit $^-\mathrm{y}$ command line option. It will also try to place all aggregate initializers in flash memory, that is, the implicitinitializers_in_flash option is also added to the command line. |
| 3 | The code space is physically limited to 128 Kbytes, and, if possible, the RCALL/RJMP instructions are used for reaching the code space. If that is not possible, CALL/JMP is used. Function calls through function pointers use ICALL/IJMP. 2 bytes are used for all function pointers. Interrupt vectors are 4 bytes long. The compiler assumes that it is possible to have external memory and will therefore generate _C segments. |

| Parameter | Description |
|-----------|--|
| 4 | The code space is physically limited to 128 Kbytes, and, if possible, the |
| | $\ensuremath{\mathtt{RCALL}}/\ensuremath{\mathtt{RJMP}}$ instructions are used for reaching the code space. If that is not |
| | possible, CALL/JMP is used. Function calls through function pointers use |
| | <code>ICALL/IJMP</code> . 2 bytes are used for all function pointers. Interrupt vectors are 4 $$ |
| | bytes long. The compiler assumes that it is possible to have external memory and |
| | will therefore generate _C segments. |
| 5 | Allows function calls through farfunc function pointers to cover the entire 8 |
| | Mbyte code space by using EICALL/EIJMP. 3 bytes are used for function point |
| | ers. Interrupt vectors are 4 bytes long. The compiler assumes that it is possible to |
| | have external memory and will therefore generate _C segments. |
| 6 | Allows function calls through farfunc function pointers to cover the entire 8 |
| | Mbyte code space by using EICALL/EIJMP. 3 bytes are used for function point. |
| | ers. Interrupt vectors are 4 bytes long. The compiler assumes that it is possible to |
| | have external memory and will therefore generate _C segments. |

Description

See also

,--cpu, page 196 and Processor configuration, page 30.



To set related options, choose:

Project>Options>General Options>Processor configuration

--version1_calls

Syntax --version1_calls

Description Use this option to make all functions and function calls use the calling convention of the

A90 IAR Compiler, ICCA90, which is described in Calling convention, page 123.

To change the calling convention of a single function, use the __version_1 function

type attribute. See __version_1, page 263 for detailed information.

See also Function storage, page 47

Project>Options>C/C++ Compiler>Code>Use ICCA90 1.x calling convention

--vla

Syntax --vla

Description Use this option to enable support for C99 variable length arrays. This option requires

Standard C and cannot be used together with the --c89 compiler option.

Note: --vla should not be used together with the longjmp library function, as that can lead to memory leakages.

See also *C language overview*, page 135.

Project>Options>C/C++ Compiler>Language>C dialect>Allow VLA

--warnings_affect_exit_code

Syntax --warnings_affect_exit_code

Description By default, the exit code is not affected by warnings, because only errors produce a

non-zero exit code. With this option, warnings will also generate a non-zero exit code.

This option is not available in the IDE.

--warnings_are_errors

Syntax --warnings_are_errors

Description Use this option to make the compiler treat all warnings as errors. If the compiler

encounters an error, no object code is generated. Warnings that have been changed into

remarks are not treated as errors.

Note: Any diagnostic messages that have been reclassified as warnings by the option --diag_warning or the #pragma diag_warning directive will also be treated as

errors when --warnings_are_errors is used.

See also --diag warning, page 200.

Project>Options>C/C++ Compiler>Diagnostics>Treat all warnings as errors

-у

Syntax -y

Description Use this option to override the default placement of constants and literals.

Without this option, constants and literals are placed in an external const segment, segmentbasename_C. With this option, constants and literals will instead be placed in the initialized segmentbasename_I data segments that are copied from the segmentbasename_ID segments by the system startup code.

Note that -y is implicit in the tiny memory model.

This option can be combined with the option --initializers_in_flash.

See also --initializers in flash, page 208

X

To set related options, choose:

Project>Options>C/C++ Compiler>Code

-Z

Syntax -z[2|3|6|9]

Parameters

None* (Best debug support)

3 (default) Low*
6 Medium

9 High (Maximum optimization)

*The most important difference between -z2 and -z3 is that at level 2, all non-static variables will live during their entire scope.

Description

Use this option to make the compiler optimize the code for minimum size. If no optimization option is specified, the optimization level 3 is used by default.

A low level of optimization makes it relatively easy to follow the program flow in the debugger, and, conversely, a high level of optimization makes it relatively hard.

Note: The -s and -z options cannot be used at the same time.

See also

-O, page 217

X

Project>Options>C/C++ Compiler>Optimizations>Size

--zero_register

Syntax --zero_register

Description

Use this option to make the compiler use register R15 as zero register, which means that register R15 is assumed to always contain zero.

This option can in some cases reduce the size of the generated code, especially in the Large memory model. The option might be incompatible with the supplied runtime libraries. The linker will issue a link-time error if any incompatibilities arise.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

Data representation

This chapter describes the data types, pointers, and structure types supported by the compiler.

See the chapter Efficient coding for embedded applications for information about which data types and pointers provide the most efficient code for your application.

Alignment

Every C data object has an alignment that controls how the object can be stored in memory. Should an object have an alignment of, for example, 4, it must be stored on an address that is divisible by 4.

The reason for the concept of alignment is that some processors have hardware limitations for how the memory can be accessed.

Assume that a processor can read 4 bytes of memory using one instruction, but only when the memory read is placed on an address divisible by 4. Then, 4-byte objects, such as long integers, will have alignment 4.

Another processor might only be able to read 2 bytes at a time; in that environment, the alignment for a 4-byte long integer might be 2.

A structure type will have the same alignment as the structure member with the most strict alignment. To decrease the alignment requirements on the structure and its members, use #pragma_pack.

All data types must have a size that is a multiple of their alignment. Otherwise, only the first element of an array would be guaranteed to be placed in accordance with the alignment requirements. This means that the compiler might add pad bytes at the end of the structure.

Note that with the #pragma data_alignment directive you can increase the alignment demands on specific variables.

ALIGNMENT ON THE AVR MICROCONTROLLER

The AVR microcontroller does not have any alignment restrictions.

Byte order

The AVR microcontroller stores data in little-endian byte order.

In the little-endian byte order, the *least* significant byte is stored at the lowest address in memory. The *most* significant byte is stored at the highest address.

In the big-endian byte order, the *most* significant byte is stored at the lowest address in memory. The *least* significant byte is stored at the highest address. It might be necessary to use the #pragma bitfields=reversed directive to be compatible with code for other compilers and I/O register definitions of some devices, see *Bitfields*, page 233.

Basic data types

The compiler supports both all Standard C basic data types and some additional types.

INTEGER TYPES

This table gives the size and range of each integer data type:

| Data type | Size | Range | Alignment |
|--------------------|---------|--|-----------|
| bool | 8 bits | 0 to I | I |
| char | 8 bits | 0 to 255 | 1 |
| signed char | 8 bits | -128 to 127 | 1 |
| unsigned char | 8 bits | 0 to 255 | 1 |
| signed short | 16 bits | -32768 to 32767 | I |
| unsigned short | 16 bits | 0 to 65535 | 1 |
| signed int | 16 bits | -32768 to 32767 | 1 |
| unsigned int | 16 bits | 0 to 65535 | 1 |
| signed long | 32 bits | -2 ³¹ to 2 ³¹ -1 | 1 |
| unsigned long | 32 bits | 0 to 2 ³² -I | 1 |
| signed long long | 64 bits | -2 ⁶³ to 2 ⁶³ -1 | 1 |
| unsigned long long | 64 bits | 0 to 2 ⁶⁴ -1 | 1 |

Table 36: Integer types

Signed variables are represented using the two's complement form.

Bool

The bool data type is supported by default in the C++ language. If you have enabled language extensions, the bool type can also be used in C source code if you include the file stdbool.h. This will also enable the boolean values false and true.

The long long type

The long long data type is supported with one restriction: The CLIB runtime library does not support the long long type

The enum type

The compiler will use the smallest type required to hold enum constants, preferring signed rather than unsigned.

When IAR Systems language extensions are enabled, and in C++, the enum constants and types can also be of the type long, unsigned long, long long, or unsigned long long.

To make the compiler use a larger type than it would automatically use, define an enum constant with a large enough value. For example:

The char type

The char type is by default unsigned in the compiler, but the --char_is_signed compiler option allows you to make it signed. Note, however, that the library is compiled with the char type as unsigned.

The wchar_t type

The wchar_t data type is an integer type whose range of values can represent distinct codes for all members of the largest extended character set specified among the supported locals.

The wchar_t data type is supported by default in the C++ language. To use the wchar_t type also in C source code, you must include the file stddef.h from the runtime library.

Note: The IAR CLIB Library has only rudimentary support for wchar_t.

Bitfields

In Standard C, int, signed int, and unsigned int can be used as the base type for integer bitfields. In standard C++, and in C when language extensions are enabled in the compiler, any integer or enumeration type can be used as the base type. It is implementation defined whether a plain integer type (char, short, int, etc) results in a signed or unsigned bitfield.

In the IAR C/C++ Compiler for AVR, plain integer types are treated as signed.

Bitfields in expressions are treated as int if int can represent all values of the bitfield. Otherwise, they are treated as the bitfield base type.

Each bitfield is placed into a container of its base type from the least significant bit to the most significant bit. If the last container is of the same type and has enough bits available, the bitfield is placed into this container, otherwise a new container is allocated.

If you use the directive #pragma bitfield=reversed, bitfields are placed from the most significant bit to the least significant bit in each container. See *bitfields*, page 267.

Example

Assume this example:

```
struct BitfieldExample
{
  uint32_t a : 12;
  uint16_t b : 3;
  uint16_t c : 7;
  uint8_t d;
};
```

To place the first bitfield, a, the compiler allocates a 32-bit container at offset 0 and puts a into the least significant 12 bits of the container.

To place the second bitfield, b, a new container is allocated at offset 4, because the type of the bitfield is not the same as that of the previous one. b is placed into the least significant three bits of this container.

The third bitfield, c, has the same type as b and fits into the same container.

The fourth member, d, is allocated into the byte at offset 6. d cannot be placed into the same container as b and c because it is not a bitfield, it is not of the same type, and it would not fit.

When using reverse order, each bitfield is instead placed starting from the most significant bit of its container.

MSB LSB MSB LSB a С b uint32 t uint I 6_t = padding MSB LSB MSB LSB MSB LSB MSB LSB MSB LSB MSB LSB MSB a a С b С d 2 3 5 MSB LSB MSB MSB LSB MSB LSB MSB LSB MSB MSB LSB LSB d reversed С Ь a С LSB LSB MSB uint32_t uint I 6_t b С

This is the layout of bitfield_example:

Figure 5: Layout of bitfield_example for disjoint types

FLOATING-POINT TYPES

In the IAR C/C++ Compiler for AVR, floating-point values are represented in standard IEEE 754 format. The sizes for the different floating-point types are:

| Туре | Size ifdouble=32 | Size ifdouble=64 |
|-------------|-------------------|------------------|
| float | 32 bits | 32 bits |
| double | 32 bits (default) | 64 bits |
| long double | 32 bits | 64 bits |

Table 37: Floating-point types

Note: The size of double and long double depends on the --64bit_doubles option, see --64bit_doubles, page 194. The type long double uses the same precision as double.

Floating-point environment

Exception flags are not supported. The feraiseexcept function does not raise any exceptions.

32-bit floating-point format

The representation of a 32-bit floating-point number as an integer is:

| 3 I | 30 | 23 22 | 0 |
|-----|----------|----------|---|
| S | Exponent | Mantissa | |

The exponent is 8 bits, and the mantissa is 23 bits.

The value of the number is:

The range of the number is at least:

The precision of the float operators (+, -, *, and /) is approximately 7 decimal digits.

64-bit floating-point format

The representation of a 64-bit floating-point number as an integer is:

| 63 | 62 | 52 51 | | 0 |
|----|----------|-------|----------|---|
| S | Exponent | | Mantissa | |

The exponent is 11 bits, and the mantissa is 52 bits.

The value of the number is:

The range of the number is at least:

The precision of the float operators (+, -, *, and /) is approximately 15 decimal digits.

Representation of special floating-point numbers

This list describes the representation of special floating-point numbers:

- Zero is represented by zero mantissa and exponent. The sign bit signifies positive or negative zero.
- Infinity is represented by setting the exponent to the highest value and the mantissa to zero. The sign bit signifies positive or negative infinity.

- Not a number (NaN) is represented by setting the exponent to the highest positive value and the mantissa to a non-zero value. The value of the sign bit is ignored.
- Subnormal numbers are used for representing values smaller than what can be represented by normal values. The drawback is that the precision will decrease with smaller values. The exponent is set to 0 to signify that the number is denormalized, even though the number is treated as if the exponent was 1. Unlike normal numbers, denormalized numbers do not have an implicit 1 as the most significant bit (the MSB) of the mantissa. The value of a denormalized number is:

$$(-1)^{S} * 2^{(1-BIAS)} * 0.Mantissa$$

where BIAS is 127 and 1023 for 32-bit and 64-bit floating-point values, respectively.

Note: The IAR CLIB Library does not fully support the special cases of floating-point numbers, such as infinity, NaN, and subnormal numbers. A library function which gets one of these special cases of floating-point numbers as an argument might behave unexpectedly.

Pointer types

The compiler has two basic types of pointers: function pointers and data pointers.

FUNCTION POINTERS

The size of function pointers is always 16 or 24 bits, and they can address the entire memory. The internal representation of a function pointer is the actual address it refers to divided by two.

These function pointers are available:

| Keyword | Address range | Pointer size | Description |
|----------|---------------|--------------|-------------------------------------|
| nearfunc | 0-0x1FFFE | 2 bytes | Can be called from any part of the |
| | | | code memory, but must reside in the |
| | | | first 128 Kbytes of that space. |
| farfunc | 0-0x7FFFFE | 3 bytes | No restrictions on code placement. |

Table 38: Function pointers

DATA POINTERS

Data pointers have three sizes: 8, 16, or 24 bits. These data pointers are available:

| Keyword | Pointer size | Memory space | Index type | Address range |
|---------|-----------------|-----------------|-------------|---------------|
| tiny | I byte | Data | signed char | 0x0-0xFF |

Table 39: Data pointers

| Keyword | Pointer size | Memory space | Index type | Address range |
|-----------|--------------------|-----------------|---------------------------|--|
| near | 2 bytes | Data | signed int | 0x0-0xFFFF |
| far | 3 bytes | Data | signed int | 0x0-0xFFFFFF (16-bit arithmetics) |
| huge | 3 bytes | Data | signed long | 0x0-0xFFFFFF |
| tinyflash | I byte | Code | signed char | 0x0-0xFF |
| flash | 2 bytes | Code | signed int | 0x0-0xFFFF |
| farflash | 3 bytes | Code | signed int | $0 \times 0 - 0 \times FFFFFFF$ (16-bit arithmetics) |
| hugeflash | 3 bytes | Code | signed long | 0x0-0xFFFFFF |
| eeprom | I byte | EEPROM | signed char | 0x0-0xFF |
| eeprom | 2 bytes | EEPROM | signed int | 0x0-0xFFFF |
| generic | 2 bytes 3 bytes | Data/Code | signed int signed long | The most significant bit (MSB) determines whethergeneric points to CODE (I) or DATA (0). The small generic pointer is generated for the processor options _v0 and _v1. |

Table 39: Data pointers (Continued)

CASTING

Casts between pointers have these characteristics:

- Casting a *value* of an integer type to a pointer of a smaller type is performed by truncation
- Casting a *value* of an integer type to a pointer of a larger type is performed by zero extension
- Casting a *pointer type* to a smaller integer type is performed by truncation
- Casting a pointer type to a larger integer type is performed via casting to the largest possible pointer that fits in the integer
- Casting a data pointer to a function pointer and vice versa is illegal
- Casting a function pointer to an integer type gives an undefined result
- Casting from a smaller pointer to a larger pointer is performed by zero extension
- Casting from a larger pointer to a smaller pointer gives an undefined result.

size t

size_t is the unsigned integer type required to hold the maximum size of an object. This table shows the typedef of size_t depending on the processor option:

| Generic processor option | Typedef |
|--|---------------|
| -v0 and -v1 | unsigned int |
| -v2, $-v3$, $-v4$, $-v5$, and $-v6$ | unsigned long |
| Table 40: size t typedef | |

When using the Large or Huge memory model, the typedef for size_t is unsigned long int.

ptrdiff_t

ptrdiff_t is the type of the signed integer required to hold the difference between two pointers to elements of the same array. This table shows the typedef of ptrdiff_t depending on the processor option:

| Generic processor option | Typedef |
|--|-------------|
| -v0 and -v1 | signed int |
| -v2, $-v3$, $-v4$, $-v5$, and $-v6$ | signed long |

Table 41: ptrdiff_t typedef

Note: Subtracting the start address of an object from the end address can yield a negative value, because the object can be larger than what the ptrdiff_t can represent. See this example:

intptr_t

intptr_t is a signed integer type large enough to contain a void *. In the IAR C/C++ Compiler for AVR, the size of intptr_t is long int when using the Large or Huge memory model and int in all other cases.

uintptr_t

uintptr_t is equivalent to intptr_t, with the exception that it is unsigned.

Structure types

The members of a struct are stored sequentially in the order in which they are declared: the first member has the lowest memory address.

ALIGNMENT

The struct and union types inherit the alignment requirements of their members. In addition, the size of a struct is adjusted to allow arrays of aligned structure objects.

GENERAL LAYOUT

Members of a struct are always allocated in the order specified in the declaration. Each member is placed in the struct according to the specified alignment (offsets).

Example

```
struct First
{
   char c;
   short s;
} s:
```

This diagram shows the layout in memory:



Figure 6: Structure layout

The alignment of the structure is 1 byte, and the size is 3 bytes.

Type qualifiers

According to the C standard, volatile and const are type qualifiers.

DECLARING OBJECTS VOLATILE

By declaring an object volatile, the compiler is informed that the value of the object can change beyond the compiler's control. The compiler must also assume that any

accesses can have side effects—thus all accesses to the volatile object must be preserved.

There are three main reasons for declaring an object volatile:

- Shared access; the object is shared between several tasks in a multitasking environment
- Trigger access; as for a memory-mapped SFR where the fact that an access occurs has an effect
- Modified access; where the contents of the object can change in ways not known to the compiler.

Definition of access to volatile objects

The C standard defines an abstract machine, which governs the behavior of accesses to volatile declared objects. In general and in accordance to the abstract machine:

- The compiler considers each read and write access to an object declared volatile as an access
- The unit for the access is either the entire object or, for accesses to an element in a composite object—such as an array, struct, class, or union—the element. For example:

```
char volatile a;
a = 5;   /* A write access */
a += 6;   /* First a read then a write access */
```

- An access to a bitfield is treated as an access to the underlying type
- Adding a const qualifier to a volatile object will make write accesses to the
 object impossible. However, the object will be placed in RAM as specified by the C
 standard.

However, these rules are not detailed enough to handle the hardware-related requirements. The rules specific to the IAR C/C++ Compiler for AVR are described below.

Rules for accesses

In the IAR C/C++ Compiler for AVR, accesses to volatile declared objects are subject to these rules:

- All accesses are preserved
- All accesses are complete, that is, the whole object is accessed
- All accesses are performed in the same order as given in the abstract machine
- All accesses are atomic, that is, they cannot be interrupted.

The compiler adheres to these rules for all 8-bit types.

These object types are treated in a special way:

| Type of object | Treated as | |
|--|---|--|
| Global register variables | Treated as non-triggering volatiles | |
| io declared variables located in $0 \mathbf{x}{-}0 \mathbf{x}1 \mathbf{F}$ | An assignment to a bitfield always generates a write access, in some cases also a read access. If only one bit is updated—set or cleared—the sci/cbi instructions are executed. | |

Table 42: Type of volatile accesses treated in a special way

For all combinations of object types not listed, only the rule that states that all accesses are preserved applies.

DECLARING OBJECTS VOLATILE AND CONST

If you declare a volatile object const, it will be write-protected but it will still be stored in RAM memory as the C standard specifies.

To store the object in read-only memory instead, but still make it possible to access it as a const volatile object, follow this example:

```
/* Header */
extern int const xVar;
#define x (*(int const volatile *) &xVar)
/* Source that uses x */
int DoSomething()
{
   return x;
}
/* Source that defines x */
#pragma segment = "FLASH"
int const xVar @ "FLASH" = 6;
```

The segment FLASH contains the initializers. They must be flashed manually when the application starts up.

Thereafter, the initializers can be reflashed with other values at any time.

DECLARING OBJECTS CONST

The const type qualifier is used for indicating that a data object, accessed directly or via a pointer, is non-writable. A pointer to const declared data can point to both constant and non-constant objects. It is good programming practice to use const

declared pointers whenever possible because this improves the compiler's possibilities to optimize the generated code and reduces the risk of application failure due to erroneously modified data.

Static and global objects declared const are allocated in ROM. If no ROM is available in the DATA memory space, use the compiler option -y to control the placement of constants. For more information, see -y, page 229.

In C++, objects that require runtime initialization cannot be placed in ROM.

Data types in C++

In C++, all plain C data types are represented in the same way as described earlier in this chapter. However, if any Embedded C++ features are used for a type, no assumptions can be made concerning the data representation. This means, for example, that it is not supported to write assembler code that accesses class members.

243

Data types in C++

Extended keywords

This chapter describes the extended keywords that support specific features of the AVR microcontroller and the general syntax rules for the keywords. Finally the chapter gives a detailed description of each keyword.

For information about the address ranges of the different memory areas, see the chapter Segment reference.

General syntax rules for extended keywords

To understand the syntax rules for the extended keywords, it is important to be familiar with some related concepts.

The compiler provides a set of attributes that can be used on functions or data objects to support specific features of the AVR microcontroller. There are two types of attributes—type attributes and object attributes:

- Type attributes affect the *external functionality* of the data object or function
- Object attributes affect the *internal functionality* of the data object or function.

The syntax for the keywords differs slightly depending on whether it is a type attribute or an object attribute, and whether it is applied to a data object or a function.

For information about how to use attributes to modify data, see the chapter *Data storage*. For information about how to use attributes to modify functions, see the chapter *Functions*. For more information about each attribute, see *Descriptions of extended keywords*, page 250.

Note: The extended keywords are only available when language extensions are enabled in the compiler.



In the IDE, language extensions are enabled by default.



Use the -e compiler option to enable language extensions. See -e, page 203 for more information.

TYPE ATTRIBUTES

Type attributes define how a function is called, or how a data object is accessed. This means that if you use a type attribute, it must be specified both when a function or data object is defined and when it is declared.

You can either place the type attributes explicitly in your declarations, or use the pragma directive #pragma type_attribute.

Type attributes can be further divided into *memory type attributes* and *general type attributes*. Memory type attributes are referred to as simply *memory attributes* in the rest of the documentation.

Memory attributes

A memory attribute corresponds to a certain logical or physical memory in the microcontroller.

- Available function memory attributes: __near_func and __far_func
- Available data memory attributes: __tiny, __near, __far, __huge, __regvar, __eeprom, __tinyflash, __flash, __farflash, __hugeflash, __generic, __io, and __ext_io.

Data objects, functions, and destinations of pointers or C++ references always have a memory attribute. If no attribute is explicitly specified in the declaration or by the pragma directive #pragma type_attribute, an appropriate default attribute is used. You can specify one memory attribute for each level of pointer indirection.

General type attributes

These general type attributes are available:

- Function type attributes affect how the function should be called: __interrupt, __task, and __version_1
- Data type attributes: const and volatile.

You can specify as many type attributes as required for each level of pointer indirection.

For more information about the type qualifiers const and volatile, see *Type qualifiers*, page 240.

Syntax for type attributes used on data objects

In general, type attributes for data objects follow the same syntax as the type qualifiers const and volatile.

The following declaration assigns the $__{far}$ type attribute to the variables i and j; in other words, the variable i and j is placed in far memory. The variables k and l behave in the same way:

```
__far int i, j;
int __far k, 1;
```

Note that the attribute affects both identifiers.

This declaration of i and j is equivalent with the previous one:

```
#pragma type_attribute=__far
int i, j;
```

The advantage of using pragma directives for specifying keywords is that it offers you a method to make sure that the source code is portable. Note that the pragma directive has no effect if a memory attribute is already explicitly declared.

For more examples of using memory attributes, see *More examples*, page 42.

An easier way of specifying storage is to use type definitions. These two declarations are equivalent:

```
typedef char __far Byte;
typedef Byte *BytePtr;
Byte b;
BytePtr bp;
and
__far char b;
char __far *bp;
```

Note that #pragma type_attribute can be used together with a typedef declaration.

Syntax for type attributes on data pointers

The syntax for declaring pointers using type attributes follows the same syntax as the type qualifiers const and volatile:

Syntax for type attributes on functions

The syntax for using type attributes on functions differs slightly from the syntax of type attributes on data objects. For functions, the attribute must be placed either in front of the return type, or in parentheses, for example:

```
__interrupt void my_handler(void);
or
void (__interrupt my_handler)(void);
```

This declaration of my_handler is equivalent with the previous one:

```
#pragma type_attribute=__interrupt
void my_handler(void);
```

Syntax for type attributes on function pointers

To declare a function pointer, use this syntax:

```
int (__farfunc * fp) (double);
```

After this declaration, the function pointer fp points to farfunc memory.

An easier way of specifying storage is to use type definitions:

```
typedef __farfunc void FUNC_TYPE(int);
typedef FUNC_TYPE *FUNC_PTR_TYPE;
FUNC_TYPE func();
FUNC_PTR_TYPE funcptr;
```

Note that #pragma type_attribute can be used together with a typedef declaration.

OBJECT ATTRIBUTES

Normally, object attributes affect the internal functionality of functions and data objects, but not directly how the function is called or how the data is accessed. This means that an object attribute does not normally need to be present in the declaration of an object. Any exceptions to this rule are noted in the description of the attribute.

These object attributes are available:

- Object attributes that can be used for variables: __no_init and __no_runtime_init
- Object attributes that can be used for functions and variables: location, @, and
- Object attributes that can be used for functions: __intrinsic, __monitor, __nested, __noreturn, and vector.

You can specify as many object attributes as required for a specific function or data object.

For more information about location and @, see *Controlling data and function placement in memory*, page 164. For more information about vector, see *vector*, page 282.

Syntax for object attributes

The object attribute must be placed in front of the type. For example, to place myarray in memory that is not initialized at startup:

```
__no_init int myarray[10];
```

The #pragma object_attribute directive can also be used. This declaration is equivalent to the previous one:

```
#pragma object_attribute=__no_init
int myarray[10];
```

Note: Object attributes cannot be used in combination with the typedef keyword.

Summary of extended keywords

This table summarizes the extended keywords:

| Extended keyword | Description |
|------------------|---|
| eeprom | Controls the storage of data objects in code memory space |
| ext_io | Controls the storage of data objects in I/O memory space Supports I/O instructions; used for SFRs |
| far | Controls the storage of data objects in data memory space |
| farflash | Controls the storage of data objects in code memory space |
| farfunc | Controls the storage of functions in code memory space |
| flash | Controls the storage of data objects in code memory space |
| generic | Declares a generic pointer |
| huge | Controls the storage of data objects in data memory space |
| hugeflash | Controls the storage of data objects in code memory space |
| interrupt | Supports interrupt functions |
| intrinsic | Reserved for compiler internal use only |
| io | Controls the storage of data objects in I/O memory space Supports I/O instructions; used for SFRs |
| monitor | Supports atomic execution of a function |
| near | Controls the storage of data objects in data memory space |
| nearfunc | Controls the storage of functions in code memory space |
| nested | Implements a nested interrupt |
| no_init | Supports non-volatile memory |

Table 43: Extended keywords summary

| Extended keyword | Description |
|------------------|---|
| no_runtime_init | Declares initialized variables that are not initialized at runtime. |
| noreturn | Informs the compiler that the function will not return |
| raw | Prevents saving used registers in interrupt functions |
| regvar | Places a data object in a register |
| root | Ensures that a function or variable is included in the object code even if unused |
| task | Relaxes the rules for preserving registers |
| tiny | Controls the storage of data objects in data memory space |
| tinyflash | Controls the storage of data objects in code memory space |
| version_1 | Specifies the old calling convention; available for backward compatibility |

Table 43: Extended keywords summary (Continued)

Descriptions of extended keywords

These sections give detailed information about each extended keyword.

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __eeprom memory attribute overrides the default storage of variables given by the selected memory model and places individual initialized and non-initialized variables in the built-in EEPROM of the AVR microcontroller. These variables can be used like any other variable and provide a convenient way to access the built-in EEPROM.

You can also override the supplied support functions to make the __eeprom memory attribute access an EEPROM or flash memory that is placed externally but not on the normal data bus, for example on an I2C bus.

To do this, you must write a new EEPROM library routines file and include it in your project. The new file must use the same interface as the eeprom. s90 file in the avr\src\lib directory (visible register use, the same entry points and the same semantics).

Variables declared __eeprom are initialized only when a downloadable linker output file is downloaded to the system, and not every time the system startup code is executed.

You can also use the __eeprom attribute to create a pointer explicitly pointing to an object located in the EEPROM memory.

Storage information

- Memory space: EEPROM memory space
- Address range: 0-0xFF (255 bytes) if --eeprom_size ≤ 256 bytes, and 0-0xFFFF (64 Kbytes) if --eeprom_size > 256 bytes.
- Maximum object size: 255 bytes if --eeprom_size ≤ 256 bytes, and 65535 bytes if --eeprom_size > 256 bytes.
- Pointer size: 1byte if --eeprom_size ≤ 256 bytes, and 2 bytes if --eeprom_size
 > 256 bytes.

Example

__eeprom int x;

See also

Memory types, page 39 and --eeprom size, page 204.

__ext_io

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __ext_io memory attribute overrides the default storage of variables given by the selected memory model and allows individual objects to be accessed by use of the special I/O instructions in the AVR microcontroller. The __ext_io memory attribute implies that the object is __no_init and volatile.

Your application may access the AVR I/O system by using the memory-mapped internal special function registers (SFRs). To access the AVR I/O system efficiently, the __ext_io memory attribute should be included in the code.

Storage information

- Memory space: Data memory space
- Address range: 0x100-0xFFFF (64 Kbytes)
- Maximum object size: 4 bytes.
- Pointer size: Pointers not allowed.

Example

__ext_io int x;

See also

Memory types, page 39.

far

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __far memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in far memory. You can also use the __far attribute to create a pointer explicitly pointing to an object located in the far memory.

Storage information

- Memory space: Data memory space
- Address range: 0-0xffff (64 Kbytes)
- Maximum object size: 32 Kbytes. An object cannot cross a 64-Kbyte boundary.
- Pointer size: 2 bytes. Arithmetics is only performed on the two lower bytes, except comparison which is always performed on the entire 24-bit address.

Example

__far int x;

See also

Memory types, page 39.

farflash

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __farflash memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in flash (code) memory. You can also use the __farflash attribute to create a pointer explicitly pointing to an object located in the flash (code) memory.

Note: It is preferable to declare flash objects as const. The __farflash memory attribute is only available for AVR chips with more than 64 Kbytes of flash memory.

Storage information

- Memory space: Code memory space
- Address range: 0-0x7FFFFF (8 Mbytes)
- Maximum object size: 32 Kbytes. An object cannot cross a 64-Kbyte boundary.
- Pointer size: 3 bytes. Arithmetics is only performed on the two lower bytes, except comparison which is always performed on the entire 24-bit address.

Example

__farflash int x;

See also

Memory types, page 39.

__farfunc

Syntax

Follows the generic syntax rules for memory type attributes that can be used on functions, see *Type attributes*, page 245.

Description

The __farfunc memory attribute overrides the default storage of functions given by the selected code model and places individual functions in code memory. You can also use the __farfunc attribute to create a pointer explicitly pointing to a function located in FARCODE memory (0-0xFFFFFF).

The default code pointer for the -v5 and -v6 processor options is __farfunc, and it only affects the size of the function pointers.

Note that pointers with function memory attributes have restrictions in implicit and explicit casts when casting between pointers and also when casting between pointers and integer types.

It is possible to call a __nearfunc function from a __farfunc function and vice versa. Only the size of the function pointer is affected.

Storage information

- Memory space: Code memory space
- Address range: 0-0x7FFFFE (8 Mbytes)
- Pointer size: 3 bytes

Example

__farfunc void myfunction(void);

See also

Function storage, page 47.

__flash

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __flash memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in flash (code) memory.

Note that it is preferable to declare flash objects as constant. The __flash keyword is available for all AVR processors.

Because the AVR microcontrollers have only a small amount of on-board RAM, this memory should not be wasted on data that could be stored in flash memory (of which there is much more). However, because of the architecture of the processor, a default pointer cannot access the flash memory. The __flash keyword is used to identify that the constant should be stored in flash memory.

A header file called pgmspace.h is installed in the avr\inc directory, to provide some standard C library functions for taking strings stored in flash memory as arguments.

You can also use the __flash attribute to create a pointer explicitly pointing to an object located in the flash (code) memory.

Note: The __flash option cannot be used in a reduced ATtiny core.

Storage information

- Memory space: Code memory space
- Address range: 0-0xFFFF (64 Kbytes)
- Maximum object size: 32 Kbytes.
- Pointer size: 2 bytes.

Examples

A program defines a couple of strings that are stored in flash memory:

```
__flash char str1[] = "Message 1";
__flash char str2[] = "Message 2";
```

The program creates a __flash pointer to point to one of these strings, and assigns it to str1:

```
char __flash *msg;
  msg=str1:
```

Using the strcpy_P function declared in pgmspace.h, a string in flash memory can be copied to another string in RAM as follows:

```
strcpy_P(dest, msg);
```

See also

Memory types, page 39.

__generic

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __generic pointer type attribute declares a generic pointer that can point to objects in both code and data space. The size of the generic pointer depends on which processor option is used.

The most significant bit (MSB) determines whether __generic points to Code (MSB=1) or Data (MSB=0).

It is not possible to place objects in a generic memory area, only to point to it. When using generic pointers, make sure that objects that have been declared __far and __huge are located in the range 0x0-0x7FFFFF. Objects may still be placed in the entire data address space, but a generic pointer cannot point to objects in the upper half of the data address space.

The __generic keyword cannot be used with the #pragma type_attribute directive for a pointer.

Access through a __generic pointer is implemented with inline code. Because this type of access is slow and generates a lot of code, __generic pointers should be avoided when possible.

Storage information

- Memory space: Data or code memory space
- Address range: 0-0x7FFF (32 Kbytes) for the processor options -v0 and -v1, 0-07FFFFF (8 Mbytes) for the processor options -v2 to -v6
- Generic pointer size: 1 + 15 bits when the processor options -v0 and -v1 are used.
 1 + 23 bits when the processor options -v2 to -v6 are used.

See also

Memory types, page 39.

__huge

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __huge memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in huge memory. You can also use the __huge attribute to create a pointer explicitly pointing to an object located in the huge memory.

Storage information

Memory space: Data memory space

Address range: 0-0xfffffff (16 Mbytes)

Maximum object size: 16 Mbytes.

• Pointer size: 3 bytes.

Example

__huge int x;

See also

Memory types, page 39.

hugeflash

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __hugeflash memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in flash (code) memory. You can also use the __hugeflash attribute to create a pointer explicitly pointing to an object located in the flash (code) memory.

Note that it is preferable to declare flash objects as constant. The __hugeflash memory attribute is only available for AVR microcontrollers with at least 64 Kbytes of flash memory.

Storage information

Memory space: Code memory space

Address range: 0-0x7FFFFF (8 Mbytes)

Maximum object size: 8 Mbytes.

Pointer size: 3 bytes.

Example

__hugeflash int x;

See also

Memory types, page 39.

interrupt

Syntax

Follows the generic syntax rules for type attributes that can be used on functions, see Type attributes, page 245.

Description

The __interrupt keyword specifies interrupt functions. To specify one or several interrupt vectors, use the #pragma vector directive. The range of the interrupt vectors depends on the device used. It is possible to define an interrupt function without a vector, but then the compiler will not generate an entry in the interrupt vector table.

An interrupt function must have a void return type and cannot have any parameters.

The header file iodevice.h, where device corresponds to the selected device,

contains predefined names for the existing interrupt vectors.

Example #pragma vector=0x14

__interrupt void my_interrupt_handler(void);

See also Interrupt functions, page 48, vector, page 282, INTVEC, page 327.

__intrinsic

Description The __intrinsic keyword is reserved for compiler internal use only.

__io

Syntax Follows the generic syntax rules for memory type attributes that can be used on data

objects, see Type attributes, page 245.

Description The __io memory attribute overrides the default storage of variables given by the

selected memory model and places individual variables and constants in I/O memory.

Storage information • Memory space: Data memory space

• Address range: 0-0xFFFF (64 Kbytes)

• Maximum object size: 8 bytes (64 bits).

• Pointer size: Pointers not allowed.

Example __io int x;

See also *Memory types*, page 39.

monitor

Syntax Follows the generic syntax rules for object attributes that can be used on functions, see

Object attributes, page 248.

Description The __monitor keyword causes interrupts to be disabled during execution of the

function. This allows atomic operations to be performed, such as operations on semaphores that control access to resources by multiple processes. A function declared with the __monitor keyword is equivalent to any other function in all other respects.

See also *Monitor functions*, page 49. For information about the intrinsic functions, see

__disable_interrupt, page 285, __enable_interrupt, page 285, __get_interrupt_state,

page 287, and __set_interrupt_state, page 290, respectively.

__near

Syntax

Follows the generic syntax rules for memory type attributes that can be used on data objects, see *Type attributes*, page 245.

Description

The __near memory attribute overrides the default storage of variables given by the selected memory model and places individual variables and constants in near memory. You can also use the __near attribute to create a pointer explicitly pointing to an object located in the near memory.

Storage information

• Memory space: Data memory space

• Address range: 0-0xFFFF (64 Kbytes)

Maximum object size: 32 Kbytes.

• Pointer size: 2 bytes.

Example

__near int x;

See also

Memory types, page 39.

nearfunc

Syntax

Follows the generic syntax rules for memory type attributes that can be used on functions, see *Type attributes*, page 245.

Description

The __nearfunc memory attribute overrides the default storage of functions given by the selected code model and places individual functions in near memory.

Functions declared __nearfunc can be called from the entire code memory area, but must reside in the first 128 Kbytes of the code memory.

The default for the -v0 to -v4 processor options is $__nearfunc$, and it only affects the size of the function pointers.

Note that pointers with function memory attributes have restrictions in implicit and explicit casts when casting between pointers and also when casting between pointers and integer types.

It is possible to call a __nearfunc function from a __farfunc function and vice versa. Only the size of the function pointer is affected.

You can also use the __nearfunc attribute to create a pointer explicitly pointing to a function located in CODE memory (0-0xFFFF).

Storage information

• Memory space: Code memory space

• Address range: 0-0x1FFFE (128 Kbytes)

• Pointer size: 2 bytes

See also Function storage, page 47.

__nested

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 245.

interrupt can be served inside an interrupt function. A nested interrupt service routine acts like a normal interrupt service routine except that it sets the interrupt enable bit

before any registers are saved.

Example __nested __interrupt void myInterruptFunction()

__no_init

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 248.

that the initialization of the variable, for example at system startup, is suppressed.

Example __no_init int myarray[10];

__no_runtime_init

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 248.

Description The __no_runtime_init keyword is used for declaring initialized variables for which

the initialization is performed when programming the device. These variables are not

initialized at runtime during system startup.

Note: The __no_runtime_init keyword cannot be used in combination with the

typedef keyword.

Example __no_runtime_init int myarray[10];

noreturn

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 248.

Description

The __noreturn keyword can be used on a function to inform the compiler that the function will not return. If you use this keyword on such functions, the compiler can

optimize more efficiently. Examples of functions that do not return are abort and exit.

Example __noreturn void terminate(void);

__raw

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 248.

Description This keyword prevents saving used registers in interrupt functions.

Interrupt functions preserve the contents of all used processor registers at function entrance and restore them at exit. However, for some very special applications, it can be desirable to prevent the registers from being saved at function entrance. This can be

accomplished by the use of the keyword __raw.

Example __raw __interrupt void my_interrupt_function()

__regvar

Syntax Follows the generic syntax rules for type attributes that can be used on data, see *Type*

attributes, page 245.

Description The __regvar extended keyword is used for declaring that a *global* or *static* variable

should be placed permanently in the specified register or registers. The registers R4-R15 can be used for this purpose, provided that they have been locked with the

--lock_regs compiler option.

Note:

- An object declared __regvar cannot have an initial value.
- The_regvar option cannot be used in a reduced ATtiny core.

Example __regvar __no_init int counter @ 14;

This will create the 16-bit integer variable counter, which will always be available in R15:R14. At least two registers must be locked.

Storage information

• Memory space: Data memory space

• Address range: 4-F

• Maximum object size: 4 bytes (32 bits).

• Pointer size: Pointers not allowed.

See also

--memory_model, -m, page 211, --lock_regs, page 210, and Preserved registers, page 126

root

Syntax

Follows the generic syntax rules for object attributes, see *Object attributes*, page 248.

Description

A function or variable with the __root attribute is kept whether or not it is referenced from the rest of the application, provided its module is included. Program modules are always included and library modules are only included if needed.

Example

__root int myarray[10];

See also

For more information about modules, segments, and the link process, see the *IAR Linker* and *Library Tools Reference Guide*.

task

Syntax

Follows the generic syntax rules for type attributes that can be used on functions, see *Type attributes*, page 245.

Description

This keyword allows functions to relax the rules for preserving registers. Typically, the keyword is used on the start function for a task in an RTOS.

By default, functions save the contents of used preserved registers on the stack upon entry, and restore them at exit. Functions that are declared __task do not save all registers, and therefore require less stack space.

Because a function declared __task can corrupt registers that are needed by the calling function, you should only use __task on functions that do not return or call such a function from assembler code.

The function main can be declared __task, unless it is explicitly called from the application. In real-time applications with more than one task, the root function of each task can be declared __task.

Example

__task void my_handler(void);

__tiny

Syntax Follows the generic syntax rules for memory type attributes that can be used on data

objects, see Type attributes, page 245.

Description The __tiny memory attribute overrides the default storage of variables given by the

selected memory model and places individual variables and constants in tiny memory. You can also use the __tiny attribute to create a pointer explicitly pointing to an object

located in the tiny memory.

Storage information • Memory space: Data memory space

• Address range: 0-0xff (256 bytes)

Maximum object size: 127 bytes.

• Pointer size: 1 byte.

Example __tiny int x;

See also *Memory types*, page 39.

__tinyflash

Syntax Follows the generic syntax rules for memory type attributes that can be used on data

objects, see Type attributes, page 245.

Description The __tinyflash memory attribute overrides the default storage of variables given by

the selected memory model and places individual variables and constants in flash (code) memory. You can also use the __tinyflash attribute to create a pointer explicitly

pointing to an object located in the flash (code) memory.

Storage information • Memory space: Code memory space

• Address range: 0-0xff (256 bytes)

• Maximum object size: 127 bytes.

• Pointer size: 1 byte.

Example __tinyflash int x;

See also *Memory types*, page 39.

__version_1

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 245.

Description The __version_1 keyword is available for backward compatibility of the interface for

calling assembler routines from C. It makes a function use the calling convention of the A90 IAR C Compiler instead of the default calling convention. The __version_1

calling convention is preferred when calling assembler functions from C.

Example __version_1 int func(int arg1, double arg2)

See also *Calling convention*, page 123.

Descriptions of extended keywords

Pragma directives

This chapter describes the pragma directives of the compiler.

The #pragma directive is defined by Standard C and is a mechanism for using vendor-specific extensions in a controlled way to make sure that the source code is still portable.

The pragma directives control the behavior of the compiler, for example how it allocates memory for variables and functions, whether it allows extended keywords, and whether it outputs warning messages.

The pragma directives are always enabled in the compiler.

Summary of pragma directives

This table lists the pragma directives of the compiler that can be used either with the #pragma preprocessor directive or the _Pragma() preprocessor operator:

| Pragma directive | Description |
|-------------------------|--|
| basic_template_matching | Makes a template function fully memory-attribute aware |
| bitfields | Controls the order of bitfield members |
| constseg | Places constant variables in a named segment |
| data_alignment | Gives a variable a higher (more strict) alignment |
| dataseg | Places variables in a named segment |
| diag_default | Changes the severity level of diagnostic messages |
| diag_error | Changes the severity level of diagnostic messages |
| diag_remark | Changes the severity level of diagnostic messages |
| diag_suppress | Suppresses diagnostic messages |
| diag_warning | Changes the severity level of diagnostic messages |
| error | Signals an error while parsing |
| include_alias | Specifies an alias for an include file |
| inline | Controls inlining of a function |
| language | Controls the IAR Systems language extensions |

Table 44: Pragma directives summary

| Pragma directive | Description |
|-----------------------|--|
| location | Specifies the absolute address of a variable, or places groups of functions or variables in named segments |
| message | Prints a message |
| object_attribute | Changes the definition of a variable or a function |
| optimize | Specifies the type and level of an optimization |
| pack | Specifies the alignment of structures and union members |
| printf_args | Verifies that a function with a printf-style format string is called with the correct arguments |
| required | Ensures that a symbol that is needed by another symbol is included in the linked output |
| rtmodel | Adds a runtime model attribute to the module |
| scanf_args | Verifies that a function with a scanf-style format string is called with the correct arguments |
| section | This directive is an alias for #pragma segment |
| segment | Declares a segment name to be used by intrinsic functions |
| STDC CX_LIMITED_RANGE | Specifies whether the compiler can use normal complex mathematical formulas or not |
| STDC FENV_ACCESS | Specifies whether your source code accesses the floating-point environment or not. |
| STDC FENV_ACCESS | Specifies whether the compiler is allowed to contract floating-point expressions or not. |
| type_attribute | Changes the declaration and definitions of a variable or function |
| vector | Specifies the vector of an interrupt or trap function |

Table 44: Pragma directives summary (Continued)

Note: For portability reasons, see also *Recognized pragma directives (6.10.6)*, page 340.

Descriptions of pragma directives

This section gives detailed information about each pragma directive.

basic_template_matching

Syntax #pragma basic_template_matching

Description Use this pragma directive in front of a template function declaration to make the

function fully memory-attribute aware, in the rare cases where this is useful. That template function will then match the template without the modifications, see *Templates*

and data memory attributes, page 151.

Example #pragma basic_template_matching

template<typename T> void fun(T *);

bitfields

Syntax #pragma bitfields={reversed|default}

Parameters

reversed Bitfield members are placed from the most significant bit to the

least significant bit.

default Bitfield members are placed from the least significant bit to the

most significant bit.

Description Use this pragma directive to control the order of bitfield members.

Example #pragma bitfields=reversed

```
/* Structure that uses reversed bitfields. */
struct S
{
   unsigned char error : 1;
   unsigned char size : 4;
   unsigned short code : 10;
};
#pragma bitfields=default /* Restores to default setting. */
```

See also *Bitfields*, page 233.

constseg

Syntax #pragma constseg=[__memoryattribute]{SEGMENT_NAME|default}

Parameters

__memoryattribute An optional memory attribute denoting in what memory the

segment will be placed; if not specified, default memory is used.

SEGMENT_NAME A user-defined segment name; cannot be a segment name

predefined for use by the compiler and linker.

default Uses the default segment for constants.

Description

Use this pragma directive to place constant variables in a named segment. The segment name cannot be a segment name predefined for use by the compiler and linker. The setting remains active until you turn it off again with the #pragma constseg=default directive.

Example

#pragma constseg=__huge MY_CONSTANTS
const int factorySettings[] = {42, 15, -128, 0};
#pragma constseg=default

data alignment

Syntax #pragma data_alignment=expression

Parameters

expression A constant which must be a power of two (1, 2, 4, etc.).

Description

Use this pragma directive to give a variable a higher (more strict) alignment of the start address than it would otherwise have. This directive can be used on variables with static and automatic storage duration.

When you use this directive on variables with automatic storage duration, there is an upper limit on the allowed alignment for each function, determined by the calling convention used.

Note: Normally, the size of a variable is a multiple of its alignment. The data_alignment directive only affects the alignment of the variable's start address, and not its size, and can thus be used for creating situations where the size is not a multiple of the alignment.

dataseg

Parameters

__memoryattribute An optional memory attribute denoting in what memory the

segment will be placed; if not specified, default memory is used.

SEGMENT_NAME A user-defined segment name; cannot be a segment name

predefined for use by the compiler and linker.

default Uses the default segment.

Description Use this pragma directive to place variables in a named segment. The segment name

cannot be a segment name predefined for use by the compiler and linker. The variable will not be initialized at startup, and can for this reason not have an initializer, which means it must be declared __no_init. The setting remains active until you turn it off

again with the #pragma dataseg=default directive.

__no_init char myBuffer[1000];

#pragma dataseg=default

diag_default

Syntax #pragma diag_default=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe117.

Description Use this pragma directive to change the severity level back to the default, or to the

severity level defined on the command line by any of the options --diag_error, --diag_remark, --diag_suppress, or --diag_warnings, for the diagnostic

messages specified with the tags.

See also *Diagnostics*, page 185.

diag_error

Syntax #pragma diag_error=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe117.

Description Use this pragma directive to change the severity level to error for the specified

diagnostics.

See also Diagnostics, page 185.

diag_remark

Syntax #pragma diag_remark=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe177.

Description Use this pragma directive to change the severity level to remark for the specified

diagnostic messages.

See also Diagnostics, page 185.

diag_suppress

Syntax #pragma diag_suppress=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe117.

Description Use this pragma directive to suppress the specified diagnostic messages.

See also *Diagnostics*, page 185.

diag_warning

Syntax #pragma diag_warning=tag[,tag,...]

Parameters

tag The number of a diagnostic message, for example the message

number Pe826.

Description Use this pragma directive to change the severity level to warning for the specified

diagnostic messages.

See also Diagnostics, page 185.

error

Syntax #pragma error message

Parameters

message A string that represents the error message.

Description Use this pragma directive to cause an error message when it is parsed. This mechanism

is different from the preprocessor directive #error, because the #pragma error directive can be included in a preprocessor macro using the _Pragma form of the

directive and only causes an error if the macro is used.

Example #if FOO_AVAILABLE

#define FOO ...

#else

#define FOO _Pragma("error\"Foo is not available\"")

#endif

If FOO_AVAILABLE is zero, an error will be signaled if the FOO macro is used in actual

source code.

include_alias

#pragma include_alias (<orig_header> , <subst_header>)

Parameters

orig_header The name of a header file for which you want to create an alias.

 $subst_header$ The alias for the original header file.

Description

Use this pragma directive to provide an alias for a header file. This is useful for substituting one header file with another, and for specifying an absolute path to a relative

file.

This pragma directive must appear before the corresponding #include directives and subst header must match its corresponding #include directive exactly.

Example

#pragma include_alias (<stdio.h> , <C:\MyHeaders\stdio.h>)

#include <stdio.h>

This example will substitute the relative file stdio.h with a counterpart located

according to the specified path.

See also

Include file search procedure, page 182.

inline

Syntax

#pragma inline[=forced|=never]

Parameters

No parameter Has the same effect as the inline keyword.

forced Disables the compiler's heuristics and forces inlining.

never Disables the compiler's heuristics and makes sure that the function

will not be inlined.

Description

Use #pragma inline to advise the compiler that the function whose declaration follows immediately after the directive should be expanded inline into the body of the calling function. Whether the inlining actually occurs is subject to the compiler's heuristics.

#pragma inline is similar to the C++ keyword inline. The difference is that the compiler uses C++ inline semantics for the #pragma inline directive, but uses the Standard C semantics for the inline keyword.

Specifying #pragma inline=never disables the compiler's heuristics and makes sure that the function will not be inlined.

Specifying #pragma inline=forced will force the compiler to treat the function declared immediately after the directive as a candidate for inlining, regardless of the compiler's heuristics. If the compiler fails to inline the candidate function for some reason, for example due to recursion, a warning message is emitted.

Inlining is normally performed only on the High optimization level. Specifying #pragma inline=forced will enable inlining of the function in question also on the Medium optimization level.

See also Function inlining, page 170.

language

Parameters

extended Enables the IAR Systems language extensions from the first use of

the pragma directive and onward.

default From the first use of the pragma directive and onward, restores

the settings for the IAR Systems language extensions to whatever

that was specified by compiler options.

save restore Saves and restores, respectively, the IAR Systems language

extensions setting around a piece of source code.

Each use of save must be followed by a matching restore in the

same file without any intervening #include directive.

Description Use this pragma directive to control the use of language extensions.

Example I At the top of a file that needs to be compiled with IAR Systems extensions enabled:

#pragma language=extended
/* The rest of the file. */

Example 2 Around a particular part of the source code that needs to be compiled with IAR Systems

extensions enabled, but where the state before the sequence cannot be assumed to be the

same as that specified by the compiler options in use:

#pragma language=save
#pragma language=extended
/* Part of source code. */
#pragma language=restore

See also -e, page 203 and --strict, page 224.

location

Syntax #pragma location={address|NAME}

Parameters

address The absolute address of the global or static variable for which you

want an absolute location.

NAME A user-defined segment name; cannot be a segment name

predefined for use by the compiler and linker.

Description Use this pragma directive to specify the location—the absolute address—of the global

or static variable whose declaration follows the pragma directive. The variables must be declared either __no_init or const. Alternatively, the directive can take a string specifying a segment for placing either a variable or a function whose declaration follows the pragma directive. Do not place variables declared as __no_init and

variables declared as const in the same named segment.

Example #pragma location=0x2000

__no_init volatile char PORT1; /* PORT1 is located at address

0x2000 */

#pragma location="foo"

char PORT1; /* PORT1 is located in segment foo */

/* A better way is to use a corresponding mechanism */

#define FLASH _Pragma("location=\"FLASH\"")

. . .

FLASH int i; /* i is placed in the FLASH segment */

See also Controlling data and function placement in memory, page 164.

message

Syntax #pragma message(message)

Parameters

message The message that you want to direct to the standard output

stream.

Description Use this pragma directive to make the compiler print a message to the standard output

stream when the file is compiled.

Example: #ifdef TESTING

#pragma message("Testing")

#endif

object_attribute

Syntax #pragma object_attribute=object_attribute[,object_attribute,...]

Parameters For information about object attributes that can be used with this pragma directive, see

Object attributes, page 248.

Description Use this pragma directive to declare a variable or a function with an object attribute. This

directive affects the definition of the identifier that follows immediately after the directive. The object is modified, not its type. Unlike the directive #pragma

type_attribute that specifies the storing and accessing of a variable or function, it is

not necessary to specify an object attribute in declarations.

char bar;

See also General syntax rules for extended keywords, page 245.

optimize

Syntax #pragma optimize=[goal][level][no_optimization...]

Parameters

goal Choose between:

balanced, optimizes balanced between speed and size

size, optimizes for size speed, optimizes for speed.

1evel Specifies the level of optimization; choose between none, low,

medium, or high.

no_optimization

Disables one or several optimizations; choose between:

 ${\tt no_code_motion,\, disables\,\, code\,\, motion}$

no_cse, disables common subexpression elimination

no_inline, disables function inlining no_tbaa, disables type-based alias analysis no_unroll, disables loop unrolling.

Description

Use this pragma directive to decrease the optimization level, or to turn off some specific optimizations. This pragma directive only affects the function that follows immediately after the directive.

The parameters speed, size, and balanced only have effect on the high optimization level and only one of them can be used as it is not possible to optimize for speed and size at the same time. It is also not possible to use preprocessor macros embedded in this pragma directive. Any such macro will not be expanded by the preprocessor.

Note: If you use the #pragma optimize directive to specify an optimization level that is higher than the optimization level you specify using a compiler option, the pragma directive is ignored.

Example

```
#pragma optimize=speed
int SmallAndUsedOften()
{
    /* Do something here. */
}

#pragma optimize=size
int BigAndSeldomUsed()
{
    /* Do something here. */
}
```

pack

Syntax

```
#pragma pack(n)
#pragma pack()
#pragma pack({push|pop}[,name] [,n])
```

Parameters

n Sets an optional structure alignment; one of: 1, 2, 4, 8, or 16

Empty list Restores the structure alignment to default push Sets a temporary structure alignment

pop Restores the structure alignment from a temporarily pushed

alignment

name An optional pushed or popped alignment label

Description Use this pragma directive to specify the maximum alignment of struct and union

members.

The #pragma pack directive affects declarations of structures following the pragma directive to the next #pragma pack or the end of the compilation unit.

Note: This can result in significantly larger and slower code when accessing members of the structure.

See also Structure types, page 240.

__printf_args

Syntax #pragma __printf_args

Description Use this pragma directive on a function with a printf-style format string. For any call to

that function, the compiler verifies that the argument to each conversion specifier (for

example %d) is syntactically correct.

Example #pragma __printf_args

```
int printf(char const *,...);

void PrintNumbers(unsigned short x)
{
  printf("%d", x); /* Compiler checks that x is an integer */
```

required

Syntax #pragma required=symbol

Parameters

symbol Any statically linked function or variable.

Description Use this pragma directive to ensure that a symbol which is needed by a second symbol

is included in the linked output. The directive must be placed immediately before the

second symbol.

Use the directive if the requirement for a symbol is not otherwise visible in the application, for example if a variable is only referenced indirectly through the segment it resides in.

Example

```
const char copyright[] = "Copyright by me";
#pragma required=copyright
int main()
{
    /* Do something here. */
}
```

Even if the copyright string is not used by the application, it will still be included by the linker and available in the output.

rtmodel

Syntax #pragma rtmodel="key", "value"

Parameters

" key" A text string that specifies the runtime model attribute.

"value" A text string that specifies the value of the runtime model

attribute. Using the special value * is equivalent to not defining the

attribute at all.

Description

Use this pragma directive to add a runtime model attribute to a module, which can be used by the linker to check consistency between modules.

This pragma directive is useful for enforcing consistency between modules. All modules that are linked together and define the same runtime attribute key must have the same value for the corresponding key, or the special value *. It can, however, be useful to state explicitly that the module can handle any runtime model.

A module can have several runtime model definitions.

Note: The predefined compiler runtime model attributes start with a double underscore. To avoid confusion, this style must not be used in the user-defined attributes.

Example #pragma rtmodel="I2C", "ENABLED"

The linker will generate an error if a module that contains this definition is linked with a module that does not have the corresponding runtime model attributes defined.

See also *Checking module consistency*, page 103.

scanf args

Syntax

#pragma __scanf_args

Description

Use this pragma directive on a function with a scanf-style format string. For any call to that function, the compiler verifies that the argument to each conversion specifier (for example %d) is syntactically correct.

Example

```
#pragma __scanf_args
int scanf(char const *,...);
int GetNumber()
 int nr;
 scanf("%d", &nr); /* Compiler checks that
                        the argument is a
                        pointer to an integer */
  return nr;
```

segment

Syntax

#pragma segment="NAME" [__memoryattribute] [align]

alias

#pragma section="NAME" [__memoryattribute] [align]

Parameters

NAME

The name of the segment.

__memoryattribute An optional memory attribute identifying the memory the segment

will be placed in; if not specified, default memory is used.

align

Specifies an alignment for the segment part. The value must be a

constant integer expression to the power of two.

Description

Use this pragma directive to define a segment name that can be used by the segment operators __segment_begin, __segment_end, and __segment_size. All segment declarations for a specific segment must have the same memory type attribute and alignment.

If an optional memory attribute is used, the return type of the segment operators __segment_begin and __segment_end is:

```
void __memoryattribute *.
```

Example #pragma segment="MYHUGE" __huge 4

See also Dedicated segment operators, page 139. For more information about segments and

segment parts, see the chapter Placing code and data.

STDC CX LIMITED RANGE

Parameters

ON Normal complex mathematic formulas can be used.

OFF Normal complex mathematic formulas cannot be used.

DEFAULT Sets the default behavior, that is OFF.

Description Use this pragma directive to specify that the compiler can use the normal complex

mathematic formulas for x (multiplication), / (division), and abs.

Note: This directive is required by Standard C. The directive is recognized but has no

effect in the compiler.

STDC FENV_ACCESS

Syntax #pragma STDC FENV_ACCESS {ON|OFF|DEFAULT}

Parameters

ON Source code accesses the floating-point environment. Note that

this argument is not supported by the compiler.

OFF Source code does not access the floating-point environment.

DEFAULT Sets the default behavior, that is OFF.

Description Use this pragma directive to specify whether your source code accesses the

floating-point environment or not.

Note: This directive is required by Standard C.

STDC FP_CONTRACT

Syntax #pragma STDC FP_CONTRACT {ON|OFF|DEFAULT}

Parameters

ON The compiler is allowed to contract floating-point expressions.

OFF The compiler is not allowed to contract floating-point expressions.

Note that this argument is not supported by the compiler.

DEFAULT Sets the default behavior, that is ON.

Description Use this pragma directive to specify whether the compiler is allowed to contract

floating-point expressions or not. This directive is required by Standard C.

Example #pragma STDC_FP_CONTRACT=ON

type_attribute

Syntax #pragma type_attribute=type_attribute[,type_attribute,...]

Parameters For information about type attributes that can be used with this pragma directive, see

Type attributes, page 245.

Description Use this pragma directive to specify IAR-specific *type attributes*, which are not part of

Standard C. Note however, that a given type attribute might not be applicable to all kind

of objects.

This directive affects the declaration of the identifier, the next variable, or the next

function that follows immediately after the pragma directive.

Example In this example, an int object with the memory attribute __near is defined:

#pragma type_attribute=__near

int x;

This declaration, which uses extended keywords, is equivalent:

__near int x;

See also See the chapter *Extended keywords* for more information.

vector

Syntax #pragma vector=vector1[, vector2, vector3, ...]

Parameters

vectorN The vector number(s) of an interrupt or trap function.

Description Use this pragma directive to specify the vector(s) of an interrupt or trap function whose

declaration follows the pragma directive. Note that several vectors can be defined for

each function.

Example #pragma vector=0x14

__interrupt void my_handler(void);

Intrinsic functions

This chapter gives reference information about the intrinsic functions, a predefined set of functions available in the compiler.

The intrinsic functions provide direct access to low-level processor operations and can be very useful in, for example, time-critical routines. The intrinsic functions compile into inline code, either as a single instruction or as a short sequence of instructions.

Summary of intrinsic functions

To use intrinsic functions in an application, include the header file intrinsics.h.

Note that the intrinsic function names start with double underscores, for example:

__disable_interrupt

This table summarizes the intrinsic functions:

| Intrinsic function | Description |
|--|---|
| delay_cycles | Inserts a time delay |
| DES_decryption | Decrypts according to Digital Encryption Standard |
| DES_encryption | Encrypts according to Digital Encryption Standard |
| disable_interrupt | Disables interrupts |
| enable_interrupt | Enables interrupts |
| extended_load_program_memory | Returns one byte from code memory |
| fractional_multiply_signed | Generates an FMULS instruction |
| fractional_multiply_signed_with_unsigned | Generates an FMULSU instruction |
| fractional_multiply_unsigned | Generates an FMUL instruction |
| get_interrupt_state | Returns the interrupt state |
| indirect_jump_to | Generates an IJMP instruction |
| insert_opcode | Assigns a value to a processor register |
| lac | Provides access to the LAC instruction |

Table 45: Intrinsic functions summary

| Intrinsic function | Description |
|-------------------------------|--|
| las | Provides access to the LAS instruction |
| lat | Provides access to the ${\tt LAT}$ instruction |
| load_program_memory | Returns one byte from program memory |
| multiply_signed | Generates a MULS instruction |
| multiply_signed_with_unsigned | Generates a \mathtt{MULSU} instruction |
| multiply_unsigned | Generates a \mathtt{MUL} instruction |
| no_operation | Inserts a NOP instruction |
| require | Sets a constant literal as required |
| restore_interrupt | Restores the interrupt flag |
| reverse | Reverses the byte order of a value |
| save_interrupt | Saves the state of the interrupt flag |
| set_interrupt_state | Restores the interrupt state |
| sleep | Inserts a SLEEP instruction |
| swap_nibbles | Swaps bit 0-3 with bit 4-7 |
| watchdog_reset | Inserts a watchdog reset instruction |
| xch | Provides access to the XCH instruction |

Table 45: Intrinsic functions summary (Continued)

Descriptions of intrinsic functions

This section gives reference information about each intrinsic function.

__delay_cycles

Syntax void __delay_cycles(unsigned long int);

Description Makes the compiler generate code that takes the given amount of cycles to perform, that

is, it inserts a time delay that lasts the specified number of cycles.

The specified value must be a constant integer expression and not an expression that is evaluated at runtime.

__DES_decryption

 ${\bf Syntax} \qquad \qquad {\bf unsigned \ long \ long \ _DES_decryption(unsigned \ long \ long \ data,}$

unsigned long long key);

where:

data The data to decrypt

key The key to decrypt against

Description Decrypts according to the Digital Encryption Standard (DES). __DES_decryption

performs a DES decryption of data against key and returns the decrypted data.

Note: This intrinsic function is available only for cores with support for the DES

instruction.

__DES_encryption

Syntax unsigned long long __DES_encryption(unsigned long long data,

unsigned long long key);

where:

data The data to encrypt

key The key to encrypt against

Description Encrypts according to the Digital Encryption Standard (DES). __DES_encryption

performs a DES encryption of data against key and returns the encrypted data.

This intrinsic function is available only for cores with support for the DES instruction.

__disable_interrupt

Syntax void __disable_interrupt(void);

Description Disables interrupts by inserting the CLI instruction.

__enable_interrupt

Syntax void __enable_interrupt(void);

Description Enables interrupts by inserting the SEI instruction.

__extended_load_program_memory

Syntax unsigned char __extended_load_program_memory(unsigned char

__farflash *);

Description Returns one byte from code memory.

Use this intrinsic function to access constant data in code memory.

__fractional_multiply_signed

Syntax signed int __fractional_multiply_signed(signed char, signed

char);

Description Generates an FMULS instruction.

__fractional_multiply_signed_with_unsigned

Syntax signed int __fractional_multiply_signed_with_unsigned(signed

char, unsigned char);

Description Generates an FMULSU instruction.

__fractional_multiply_unsigned

Syntax unsigned int __fractional_multiply_unsigned(unsigned char,

unsigned char);

Description Generates an FMUL instruction.

__get_interrupt_state

Syntax __istate_t __get_interrupt_state(void);

Description Returns the global interrupt state. The return value can be used as an argument to the

__set_interrupt_state intrinsic function, which will restore the interrupt state.

Example #include "intrinsics.h"

```
void CriticalFn()
{
    __istate_t s = __get_interrupt_state();
    __disable_interrupt();

    /* Do something here. */
    __set_interrupt_state(s);
}
```

The advantage of using this sequence of code compared to using

__disable_interrupt and __enable_interrupt is that the code in this example will not enable any interrupts disabled before the call of __get_interrupt_state.

__indirect_jump_to

Syntax void __indirect_jump_to(unsigned long);

Description Jumps to the address specified by the argument by using the IJMP or EIJMP instruction,

depending on the generic processor option:

IJMP -v0 **to** -v4

EIJMP -v5 **and** -v6

__insert_opcode

Syntax void __insert_opcode(unsigned short);

Description Inserts a DW unsigned directive.

__lac

Syntax unsigned char __lac(unsigned char, unsigned char *);

Description Provides access to the LAC (Load And Clear) instruction.

__las

Syntax unsigned char __las(unsigned char, unsigned char *);

Description Provides access to the LAS (Load And Set) instruction.

__lat

Syntax unsigned char __lat(unsigned char, unsigned char *);

Description Provides access to the LAT (Load And Toggle) instruction.

__load_program_memory

Syntax unsigned char __load_program_memory(unsigned char __flash *);

Description Returns one byte from code memory. The constants must be placed within the first 64

Kbytes of memory.

__multiply_signed

Syntax signed int __multiply_signed(signed char, signed char);

Description Generates a MULS instruction.

__multiply_signed_with_unsigned

Syntax signed int __multiply_signed_with_unsigned(signed char, unsigned

char);

Description Generates a MULSU instruction.

__multiply_unsigned

Syntax unsigned int __multiply_unsigned(unsigned char, unsigned char);

Description Generates a MUL instruction.

__no_operation

Syntax void __no_operation(void);

Description Inserts a NOP instruction.

__require

Syntax void __require(void *);

Description Sets a constant literal as required.

One of the prominent features of the IAR XLINK Linker is its ability to strip away anything that is not needed. This is a very good feature because it reduces the resulting code size to a minimum. However, in some situations you may want to be able to explicitly include a piece of code or a variable even though it is not directly used.

The argument to __require could be a variable, a function name, or an exported assembler label. It must, however, be a constant literal. The label referred to will be treated as if it would be used at the location of the __require call.

Example

In this example, the copyright message will be included in the generated binary file even though it is not directly used.

```
#include <intrinsics.h>
char copyright[] = "Copyright 2011 by XXXX";
void main(void)
{
    __require(copyright);
    [... the rest of the program ...]
```

__restore_interrupt

Syntax void __restore_interrupt(unsigned char oldState);

Description Restores the interrupt flag to the specified state.

Note: The value of *oldState* must be the result of a call to the __save_interrupt intrinsic function.

__reverse

Syntax unsigned int __reverse(unsigned int);

Description Reverses the byte order of the value given as parameter. Avoid using __reverse in

complex expressions as it might introduce extra register copying.

Example signed int __reverse(signed int);

void __hugeflash * __reverse(void __hugeflash *);

/* Only on -v2 through -v6 with > 64k flash memory */

__save_interrupt

Syntax unsigned char __save_interrupt(void);

Description Saves the state of the interrupt flag in the byte returned. This value can then be used for

restoring the state of the interrupt flag with the __restore_interrupt intrinsic

function.

Example unsigned char oldState;

```
oldState = __save_interrupt();
__disable_interrupt();

/* Critical section goes here */
__restore_interrupt(oldState);
```

__set_interrupt_state

Syntax void __set_interrupt_state(__istate_t);

Descriptions Restores the interrupt state to a value previously returned by the

__get_interrupt_state function.

For information about the __istate_t type, see get interrupt state, page 287.

__sleep

Syntax void __sleep(void);

Description Inserts a SLEEP instruction.

__swap_nibbles

Syntax unsigned char __swap_nibbles(unsigned char);

Description Swaps bit 0-3 with bit 4-7 of the parameter and returns the swapped value.

__watchdog_reset

Syntax void __watchdog_reset(void);

Description Inserts a watchdog reset instruction.

__xch

Syntax unsigned char __xch(unsigned char, unsigned char *);

Description Provides access to the XCH (Exchange) instruction.

Descriptions of intrinsic functions

The preprocessor

This chapter gives a brief overview of the preprocessor, including reference information about the different preprocessor directives, symbols, and other related information.

Overview of the preprocessor

The preprocessor of the IAR C/C++ Compiler for AVR adheres to Standard C. The compiler also makes these preprocessor-related features available to you:

• Predefined preprocessor symbols

These symbols allow you to inspect the compile-time environment, for example the time and date of compilation. For more information, see *Descriptions of predefined preprocessor symbols*, page 294.

- User-defined preprocessor symbols defined using a compiler option
 In addition to defining your own preprocessor symbols using the #define directive, you can also use the option -D, see -D, page 197.
- Preprocessor extensions

There are several preprocessor extensions, for example many pragma directives; for more information, see the chapter *Pragma directives* in this guide. For information about the corresponding _Pragma operator and the other extensions related to the preprocessor, see *Descriptions of miscellaneous preprocessor extensions*, page 299.

Preprocessor output

Use the option --preprocess to direct preprocessor output to a named file, see --preprocess, page 219.

To specify a path for an include file, use forward slashes:

```
#include "mydirectory/myfile"
```

In source code, use forward slashes:

```
file = fopen("mydirectory/myfile","rt");
```

Note that backslashes can also be used. In this case, use one in include file paths and two in source code strings.

Descriptions of predefined preprocessor symbols

This table describes the predefined preprocessor symbols:

| Predefined symbol | Identifies |
|-------------------|---|
| BASE_FILE | A string that identifies the name of the base source file (that is, not the header file), being compiled. See alsoFILE, page 295, and _no_path_in_file_macros, page 214. |
| BUILD_NUMBER | A unique integer that identifies the build number of the compiler currently in use. The build number does not necessarily increase with a compiler that is released later. |
| CORE | An integer that identifies the processor variant in use. The symbol corresponds to the processor option $-vn$ in use. |
| cplusplus | An integer which is defined when the compiler runs in any of the C++ modes, otherwise it is undefined. When defined, its value is 199711L. This symbol can be used with #ifdef to detect whether the compiler accepts C++ code. It is particularly useful when creating header files that are to be shared by C and C++ code.* |
| CPU | A symbol that identifies the processor variant in use. This symbol expands to a number which corresponds to the processor option $-vn$ in use. |
| DATE | A string that identifies the date of compilation, which is returned in the form "Mmm dd yyyyy", for example "Oct 30 2010". * |
| device | A symbol that identifies the processor variant in use. This symbol corresponds to the processor variant that you have specified with thecpu compiler option. device corresponds exactly to the device name, except for FpSLic, which uses the predefined symbolAT94Kxx For example, the symbol isAT90S2313 when thecpu=2313 option is used, andATmega163, whencpu=m163 is used. |
| DOUBLE | An integer that identifies the size of the data type double. The symbols is defined to 32 or 64, depending on the setting of the option64bit_doubles. |

Table 46: Predefined symbols

| Predefined symbol | Identifies |
|--------------------|---|
| embedded_cplusplus | An integer which is defined to 1 when the compiler runs in any of the C++ modes, otherwise the symbol is undefined. This symbol can be used with #ifdef to detect whether the compiler accepts C++ code. It is particularly useful when creating header files that are to be shared by C and C++ code.* |
| FILE | A string that identifies the name of the file being compiled, which can be both the base source file and any included header file. See alsoBASE_FILE, page 294, and _no_path_in_file_macros, page 214.* |
| func | A predefined string identifier that is initialized with the name of the function in which the symbol is used. This is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 203. See alsoPRETTY_FUNCTION, page 297. |
| FUNCTION | A predefined string identifier that is initialized with the name of the function in which the symbol is used. This is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 203. See alsoPRETTY_FUNCTION, page 297. |
| HAS_EEPROM | A symbol that determines whether there is internal EEPROM available or not. When this symbol is defined, there is internal EEPROM available. When this symbol is not defined, there is no internal EEPROM available. |
| HAS_EIND | A symbol that determines whether the instruction \texttt{EIND} is available or not. When this symbol is defined, the instruction \texttt{EIND} is available. When this symbol is not defined, the \texttt{EIND} instruction is not available. |
| HAS_ELPM | A symbol that determines whether the instruction \mathtt{ELPM} is available or not. When this symbol is defined, the instruction \mathtt{ELPM} is available. When this symbol is not defined, the \mathtt{ELPM} instruction is not available. |
| HAS_ENHANCED_CORE | A symbol that determines whether the enhanced core is used or not. The symbol reflects theenhanced_core option and is defined when the enhanced core is used. When this symbol is not defined, the enhanced core is not used. |

Table 46: Predefined symbols (Continued)

| Predefined symbol | Identifies |
|-------------------|--|
| HAS_FISCR | A symbol that determines whether the instruction FISCR is available or not. When this symbol is defined, the instruction FISCR is available. When this symbol is not defined, the FISCR instruction is not available. |
| HAS_MUL | A symbol that determines whether the instruction MUL is available or not. When this symbol is defined, the instruction MUL is available. When this symbol is not defined, the MUL instruction is not available. |
| HAS_RAMPD | A symbol that determines whether the register RAMPD is available or not. When this symbol is defined, the register RAMPD is available. When this symbol is not defined, the register RAMPD is not available. |
| HAS_RAMPX | A symbol that determines whether the register RAMPX is available or not. When this symbol is defined, the register RAMPX is available. When this symbol is not defined, the register RAMPX is not available. |
| HAS_RAMPY | A symbol that determines whether the register RAMPY is available or not. When this symbol is defined, the register RAMPY is available. When this symbol is not defined, the register RAMPY is not available. |
| HAS_RAMPZ | A symbol that determines whether the register RAMPZ is available or not. When this symbol is defined, the register RAMPZ is available. When this symbol is not defined, the register RAMPZ is not available. |
| IAR_SYSTEMS_ICC | An integer that identifies the IAR compiler platform. The current value is 9. Note that the number could be higher in a future version of the product. This symbol can be tested with #ifdef to detect whether the code was compiled by a compiler from IAR Systems. |
| ICCAVR | An integer that is set to 1 when the code is compiled with the IAR C/C++ Compiler for AVR. |
| LINE | An integer that identifies the current source line number of the file being compiled, which can be both the base source file and any included header file.* |
| LITTLE_ENDIAN | An integer that is defined to $1\ \mbox{because}$ the AVR byte order is little-endian. |

Table 46: Predefined symbols (Continued)

| Predefined symbol | Identifies |
|-------------------|--|
| MEMORY_MODEL | An integer that identifies the memory model in use. The symbol reflects thememory_model option and is defined to I for the Tiny memory model, 2 for the Small memory model, and 3 for the Large memory model. |
| PRETTY_FUNCTION | A string that identifies the function name, including parameter types and return type, of the function in which the symbol is used, for example "void func(char)". This symbol is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 203. See alsofunc, page 295. |
| STDC | An integer that is set to 1, which means the compiler adheres to Standard C. This symbol can be tested with $\#ifdef$ to detect whether the compiler in use adheres to Standard C.* |
| STDC_VERSION | An integer that identifies the version of the C standard in use. The symbol expands to $199901L$,unless the $c89$ compiler option is used in which case the symbol expands to $199409L$. This symbol does not apply in EC++ mode.* |
| SUBVERSION | An integer that identifies the subversion number of the compiler version number, for example 3 in 5.30.3. |
| TIME | A string that identifies the time of compilation in the form " $\mathtt{hh}:\mathtt{mm}:\mathtt{ss}".^*$ |

Table 46: Predefined symbols (Continued)

| Predefined symbol | Identifies |
|-------------------|--|
| TID | A symbol that expands to the target identifier which contains |
| | these parts: |
| | ulletA target identifier (t) unique for each IAR compiler. For the |
| | AVR microcontroller, the target indentifier is 90. |
| | • The value (c) of the cpu or $-v$ option. |
| | The value (m) corresponding to thememory_model |
| | option in use; where the value I corresponds to Tiny, the |
| | value 2 corresponds to Small, and the value 3 to Large. |
| | TheTID value is constructed as: |
| | ((t << 8) (c << 4) m) |
| | You can extract the values as follows: |
| | $t = (_TID >> 8) \& 0x7F; /* target id */$ |
| | $c = (_TID >> 4) \& 0x0F; /* cpu core */$ |
| | $m = \{TID}_{\& 0x0F};$ /* memory model *, |
| | To find the value of the target identifier for the current |
| | compiler, execute: |
| | printf("%ld",(TID >> 8) & 0x7F) |
| | Note: The use ofTID is not recommended. We |
| | recommend that you use the symbolsICCAVR andCORE instead. |
| TINY_AVR | A symbol that determines whether the reduced tiny AVR |
| | core is used or not. When this symbol is defined, the |
| | reduced tiny AVR core is used. When this symbol is not |
| | defined, the reduced tiny AVR core is not used. |
| VER | An integer that identifies the version number of the IAR |
| | compiler in use. The value of the number is calculated in this |
| | way: (100 * the major version number + the |
| | minor version number). For example, for compiler |
| | version 3.34, 3 is the major version number and 34 is the |
| | minor version number. Hence, the value ofVER is 334 |
| VERSION_1_CALLS_ | |
| VERSION_I_CADDS_ | the old calling convention used in compiler version 1.x. If |
| | zero, the new calling convention is used. For more |
| | information about the calling conventions, see Calling |
| | convention, page 123. |
| WHEN CODE | 1 3 |
| XMEGA_CORE | A symbol that determines whether the xmega core is used or |
| | not. When this symbol is defined, the xmega core is used. |
| | When this symbol is not defined, the xmega core is not used |

Table 46: Predefined symbols (Continued)

^{*} This symbol is required by Standard C.

Descriptions of miscellaneous preprocessor extensions

This section gives reference information about the preprocessor extensions that are available in addition to the predefined symbols, pragma directives, and Standard C directives.

NDEBUG

Description

This preprocessor symbol determines whether any assert macros you have written in your application shall be included or not in the built application.

If this symbol is not defined, all assert macros are evaluated. If the symbol is defined, all assert macros are excluded from the compilation. In other words, if the symbol is:

- **defined**, the assert code will *not* be included
- not defined, the assert code will be included

This means that if you write any assert code and build your application, you should define this symbol to exclude the assert code from the final application.

Note that the assert macro is defined in the assert.h standard include file.

See also

Assert, page 98.



In the IDE, the NDEBUG symbol is automatically defined if you build your application in the Release build configuration.

#warning message

Syntax

#warning message

where message can be any string.

Description

Use this preprocessor directive to produce messages. Typically, this is useful for assertions and other trace utilities, similar to the way the Standard C #error directive is used. This directive is not recognized when the --strict compiler option is used.

Descriptions of miscellaneous preprocessor extensions

Library functions

This chapter gives an introduction to the C and C++ library functions. It also lists the header files used for accessing library definitions.

At the end of this chapter, all AVR-specific library functions are described.

For detailed reference information about the library functions, see the online help system.

Library overview

The compiler provides two different libraries:

- IAR DLIB Library is a complete library, compliant with Standard C and C++. This
 library also supports floating-point numbers in IEEE 754 format and it can be
 configured to include different levels of support for locale, file descriptors,
 multibyte characters, et cetera.
- IAR CLIB Library is a light-weight library, which is not fully compliant with Standard C. Neither does it fully support floating-point numbers in IEEE 754 format or does it support C++.

Note that different customization methods are normally needed for these two libraries. For more information, see the chapter *The DLIB runtime environment* and *The CLIB runtime environment*, respectively.

For detailed information about the library functions, see the online documentation supplied with the product. There is also keyword reference information for the DLIB library functions. To obtain reference information for a function, select the function name in the editor window and press F1.

For more information about library functions, see the chapter *Implementation-defined behavior* in this guide.

HEADER FILES

Your application program gains access to library definitions through header files, which it incorporates using the #include directive. The definitions are divided into several different header files, each covering a particular functional area, letting you include just those that are required.

It is essential to include the appropriate header file before making any reference to its definitions. Failure to do so can cause the call to fail during execution, or generate error or warning messages at compile time or link time.

LIBRARY OBJECT FILES

Most of the library definitions can be used without modification, that is, directly from the library object files that are supplied with the product. For information about how to choose a runtime library, see *Basic project configuration*, page 29. The linker will include only those routines that are required—directly or indirectly—by your application.

ALTERNATIVE MORE ACCURATE LIBRARY FUNCTIONS

The default implementation of cos, sin, tan, and pow is designed to be fast and small. As an alternative, there are versions designed to provide better accuracy. They are named __iar_xxx_accuratef for float variants of the functions and __iar_xxx_accuratel for long double variants of the functions, and where xxx is cos, sin, etc.

To use any of these more accurate versions, use the -e linker option.

REENTRANCY

A function that can be simultaneously invoked in the main application and in any number of interrupts is reentrant. A library function that uses statically allocated data is therefore not reentrant.

Most parts of the DLIB library are reentrant, but the following functions and parts are not reentrant because they need static data:

- Heap functions—malloc, free, realloc, calloc, and the C++ operators new and delete
- Locale functions—localecony, setlocale
- Multibyte functions—mbrlen, mbrtowc, mbsrtowc, mbtowc, wcrtomb, wcsrtomb, wctomb
- Rand functions—rand, srand
- Time functions—asctime, localtime, gmtime, mktime
- The miscellaneous functions atexit, strerror, strtok
- Functions that use files or the heap in some way. This includes printf, sprintf, scanf, sscanf, getchar, and putchar.

For the CLIB library, the question and functions that use files in some way are non-reentrant. This includes printf, scanf, getchar, and putchar. However, the functions sprintf and sucanf are reentrant.

Functions that can set errno are not reentrant, because an errno value resulting from one of these functions can be destroyed by a subsequent use of the function before it is read. This applies to math and string conversion functions, among others.

Remedies for this are:

- Do not use non-reentrant functions in interrupt service routines
- Guard calls to a non-reentrant function by a mutex, or a secure region, etc.

THE LONGJMP FUNCTION



A longjmp is in effect a jump to a previously defined setjmp. Any variable length arrays or C++ objects residing on the stack during stack unwinding will not be destroyed. This can lead to resource leaks or incorrect application behavior.

IAR DLIB Library

The IAR DLIB Library provides most of the important C and C++ library definitions that apply to embedded systems. These are of the following types:

- Adherence to a free-standing implementation of Standard C. The library supports
 most of the hosted functionality, but you must implement some of its base
 functionality. For additional information, see the chapter *Implementation-defined*behavior in this guide.
- Standard C library definitions, for user programs.
- C++ library definitions, for user programs.
- CSTARTUP, the module containing the start-up code, see the chapter The DLIB runtime environment in this guide.
- Runtime support libraries; for example low-level floating-point routines.
- Intrinsic functions, allowing low-level use of AVR features. See the chapter *Intrinsic functions* for more information.
- Special compiler support for accessing strings in flash memory, see *AVR-specific library functions*, page 310.

In addition, the IAR DLIB Library includes some added C functionality, see *Added C functionality*, page 307.

C HEADER FILES

This section lists the header files specific to the DLIB library C definitions. Header files may additionally contain target-specific definitions; these are documented in the chapter *Using C*.

This table lists the C header files:

| Header file | Usage |
|-------------|---|
| assert.h | Enforcing assertions when functions execute |
| complex.h | Computing common complex mathematical functions |
| ctype.h | Classifying characters |
| errno.h | Testing error codes reported by library functions |
| fenv.h | Floating-point exception flags |
| float.h | Testing floating-point type properties |
| inttypes.h | Defining formatters for all types defined in ${\tt stdint.h}$ |
| iso646.h | Using Amendment I—iso646.h standard header |
| limits.h | Testing integer type properties |
| locale.h | Adapting to different cultural conventions |
| math.h | Computing common mathematical functions |
| setjmp.h | Executing non-local goto statements |
| signal.h | Controlling various exceptional conditions |
| stdarg.h | Accessing a varying number of arguments |
| stdbool.h | Adds support for the bool data type in C. |
| stddef.h | Defining several useful types and macros |
| stdint.h | Providing integer characteristics |
| stdio.h | Performing input and output |
| stdlib.h | Performing a variety of operations |
| string.h | Manipulating several kinds of strings |
| tgmath.h | Type-generic mathematical functions |
| time.h | Converting between various time and date formats |
| uchar.h | Unicode functionality (IAR extension to Standard C) |
| wchar.h | Support for wide characters |
| wctype.h | Classifying wide characters |

Table 47: Traditional Standard C header files—DLIB

C++ HEADER FILES

This section lists the C++ header files.

Embedded C++

This table lists the Embedded C++ header files:

| Header file | Usage |
|-------------|---|
| complex | Defining a class that supports complex arithmetic |
| fstream | Defining several I/O stream classes that manipulate external files |
| iomanip | Declaring several I/O stream manipulators that take an argument |
| ios | Defining the class that serves as the base for many I/O streams classes |
| iosfwd | Declaring several I/O stream classes before they are necessarily defined |
| iostream | Declaring the I/O stream objects that manipulate the standard streams |
| istream | Defining the class that performs extractions |
| new | Declaring several functions that allocate and free storage |
| ostream | Defining the class that performs insertions |
| sstream | Defining several I/O stream classes that manipulate string containers |
| streambuf | Defining classes that buffer I/O stream operations |
| string | Defining a class that implements a string container |
| strstream | Defining several I/O stream classes that manipulate in-memory character sequences |

Table 48: Embedded C++ header files

Extended Embedded C++ standard template library

The following table lists the Extended EC++ standard template library (STL) header files:

| Header file | Description |
|-------------|--|
| algorithm | Defines several common operations on sequences |
| deque | A deque sequence container |
| functional | Defines several function objects |
| hash_map | A map associative container, based on a hash algorithm |
| hash_set | A set associative container, based on a hash algorithm |
| iterator | Defines common iterators, and operations on iterators |
| list | A doubly-linked list sequence container |
| map | A map associative container |
| memory | Defines facilities for managing memory |
| numeric | Performs generalized numeric operations on sequences |

Table 49: Standard template library header files

| Header file | Description |
|-------------|---|
| queue | A queue sequence container |
| set | A set associative container |
| slist | A singly-linked list sequence container |
| stack | A stack sequence container |
| utility | Defines several utility components |
| vector | A vector sequence container |

Table 49: Standard template library header files (Continued)

Using Standard C libraries in C++

The C++ library works in conjunction with some of the header files from the Standard C library, sometimes with small alterations. The header files come in two forms—new and traditional—for example, cassert and assert.h.

This table shows the new header files:

| Header file | Usage |
|-------------|---|
| cassert | Enforcing assertions when functions execute |
| ccomplex | Computing common complex mathematical functions |
| cctype | Classifying characters |
| cerrno | Testing error codes reported by library functions |
| cfenv | Floating-point exception flags |
| cfloat | Testing floating-point type properties |
| cinttypes | Defining formatters for all types defined in stdint.h |
| ciso646 | Using Amendment I—iso646.h standard header |
| climits | Testing integer type properties |
| clocale | Adapting to different cultural conventions |
| cmath | Computing common mathematical functions |
| csetjmp | Executing non-local goto statements |
| csignal | Controlling various exceptional conditions |
| cstdarg | Accessing a varying number of arguments |
| cstdbool | Adds support for the bool data type in C. |
| cstddef | Defining several useful types and macros |
| cstdint | Providing integer characteristics |
| cstdio | Performing input and output |

Table 50: New Standard C header files—DLIB

| Header file | Usage |
|-------------|--|
| cstdlib | Performing a variety of operations |
| cstring | Manipulating several kinds of strings |
| ctgmath | Type-generic mathematical functions |
| ctime | Converting between various time and date formats |
| cwchar | Support for wide characters |
| cwctype | Classifying wide characters |

Table 50: New Standard C header files—DLIB (Continued)

LIBRARY FUNCTIONS AS INTRINSIC FUNCTIONS

Certain C library functions will under some circumstances be handled as intrinsic functions and will generate inline code instead of an ordinary function call, for example memcpy, memset, and strcat.

ADDED C FUNCTIONALITY

The IAR DLIB Library includes some added C functionality.

The following include files provide these features:

- fenv.h
- stdio.h
- stdlib.h
- string.h
- time.h

fenv.h

In fenv.h, trap handling support for floating-point numbers is defined with the functions fegettrapenable and fegettrapdisable. No floating-point status flags are supported.

stdio.h

These functions provide additional I/O functionality:

| fdopen | Opens a file based on a low-level file descriptor. |
|--------|--|
| fileno | Gets the low-level file descriptor from the file descriptor ($FILE*$). |
| gets | Corresponds to fgets on stdin. |

| getw | Gets a wchar_t character from stdin. |
|-------------|--------------------------------------|
| putw | Puts a wchar_t character to stdout. |
| ungetchar | Corresponds to ungetc on stdout. |
| write_array | Corresponds to fwrite on stdout. |

string.h

These are the additional functions defined in string.h:

| strdup | Duplicates a string on the heap. |
|-------------|--|
| strcasecmp | Compares strings case-insensitive. |
| strncasecmp | Compares strings case-insensitive and bounded. |

strnlen Bounded string length.

time.h

There are two interfaces for using time_t and the associated functions time, ctime, difftime, gmtime, localtime, and mktime:

- The 32-bit interface supports years from 1900 up to 2035 and uses a 32-bit integer
 for time_t. The type and function have names like __time32_t, __time32, etc.
 This variant is mainly available for backwards compatibility.
- The 64-bit interface supports years from -9999 up to 9999 and uses a signed long long for time_t. The type and function have names like __time64_t, __time64, etc.

The interfaces are defined in the system header file time.h.

An application can use either interface, and even mix them by explicitly using the 32-or 64-bit variants. By default, the library and the header redirect time_t, time etc. to

the 32-bit variants. However, to explicitly redirect them to their 64-bit variants, define _DLIB_TIME_USES_64 in front of the inclusion of time.h or ctime.

See also, Time, page 164.

SYMBOLS USED INTERNALLY BY THE LIBRARY

The following symbols are used by the library, which means that they are visible in library source files, etc:

```
__assignment_by_bitwise_copy_allowed
This symbol determines properties for class objects.
```

__constrange()

Determines the allowed range for a parameter to an intrinsic function and that the parameter must be of type const.

__construction_by_bitwise_copy_allowed

This symbol determines properties for class objects.

__has_constructor, __has_destructor

These symbols determine properties for class objects and they function like the sizeof operator. The symbols are true when a class, base class, or member (recursively) has a user-defined constructor or destructor, respectively.

__memory_of

Determines the class memory. A class memory determines which memory a class object can reside in. This symbol can only occur in class definitions as a class memory.

Note: The symbols are reserved and should only be used by the library.

Use the compiler option --predef_macros to determine the value for any predefined symbols.

IAR CLIB Library

The IAR CLIB Library provides most of the important C library definitions that apply to embedded systems. These are of the following types:

 Standard C library definitions available for user programs. These are documented in this chapter.

- The system startup code; see the chapter *The CLIB runtime environment* in this guide.
- Runtime support libraries; for example low-level floating-point routines.
- Intrinsic functions, allowing low-level use of AVR features. See the chapter *Intrinsic functions* for more information.
- Special compiler support for accessing strings in flash memory, see *AVR-specific library functions*, page 310.

LIBRARY DEFINITIONS SUMMARY

This table lists the header files specific to the CLIB library:

| Header file | Description |
|-------------|--|
| assert.h | Assertions |
| ctype.h* | Character handling |
| errno.h | Error return values |
| float.h | Limits and sizes of floating-point types |
| iccbutl.h | Low-level routines |
| limits.h | Limits and sizes of integral types |
| math.h | Mathematics |
| setjmp.h | Non-local jumps |
| stdarg.h | Variable arguments |
| stdbool.h | Adds support for the bool data type in C |
| stddef.h | Common definitions including size_t, NULL, ptrdiff_t, and offsetof |
| stdio.h | Input/output |
| stdlib.h | General utilities |
| string.h | String handling |

Table 51: IAR CLIB Library header files

AVR-specific library functions

This section lists the AVR-specific library functions declared in pgmspace.h that allow access to strings in flash memory. The _P functions exist in both the IAR CLIB Library and the IAR DLIB Library, but they allow access to strings in flash memory only. The

^{*} The functions isxxx, toupper, and tolower declared in the header file ctype. h evaluate their argument more than once. This is not according to the ISO/ANSI standard.

_G functions use the __generic pointer instead, which means that they allow access to both flash and data memory.

SPECIFYING READ AND WRITE FORMATTERS

You can override default formatters for the functions printf_P and scanf_P by editing the linker command file. Note that it is not possible to use the IAR Embedded Workbench IDE for overriding the default formatter for the AVR-specific library routines.

To override the default printf_P formatter, type any of the following lines in your linker command file:

```
-e_small_write_P=_formatted_write_P
-e_medium_write_P=_formatted_write_P
```

To override the default scanf_P formatter, type the following line in your linker command file:

```
-e_medium_read_P=_formatted_read_P
```

memcmp_G

Syntax int memcmp_G(const void *s1, const void __generic *s2, size_t

n)

Description Identical to memorp except that s2 can be located in flash or data memory.

memcpy_G

Syntax void * memcpy_G(void *s1, const void __generic *s2, size_t n);

Description Identical to memcpy except that it copies string s2 in flash or data memory to the location that s1 points to in data memory.

memcpy_P

Syntax void * memcpy_P(void *s1, PGM_P s2, size_t n);

Description Identical to memory except that it copies string s2 in flash memory to the location that s1 points to in data memory. This function is available in both the CLIB and the DLIB

library.

printf_P

Syntax int printf_P(PGM_P __format,...);

Description Similar to printf except that the format string is in flash memory, not in data memory.

This function is available in both the CLIB and the DLIB library. For information about how to override default formatter, see *Specifying read and write formatters*, page 311.

puts_G

Description Identical to puts except that the string to be written can be in flash *or* data memory.

puts_P

Syntax int puts_P(PGM_P __s);

Description Identical to puts except that the string to be written is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

scanf P

Syntax int scanf_P(PGM_P __format,...);

Description Identical to scanf except that the format string is in flash memory, not in data memory.

This function is available in both the CLIB and the DLIB library. For information about how to override the default formatter, see *Specifying read and write formatters*, page

311.

sprintf_P

Syntax int sprintf_P(char *__s, PGM_P __format,...);

Description Identical to sprintf except that the format string is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

sscanf P

Syntax int sscanf_P(const char *__s, PGM_P __format,...);

Description Identical to sscanf except that the format string is in flash memory, not in data memory.

This function is available in both the CLIB and the DLIB library.

strcat G

Syntax char *strcat_G(char *s1, const char __generic *s2);

Description Identical to streat except that string s2 can be in flash *or* data memory.

strcmp_G

Syntax int strcmp_G(const char *s1, const char __generic *s2);

Description Identical to strcmp except that string s2 can be in flash or data memory.

strcmp_P

Syntax int strcmp_P(const char *s1, PGM_P s2);

Description Identical to strcmp except that string s2 is in flash memory, not in data memory. This

function is available in both the CLIB and the DLIB library.

strcpy_G

Syntax char *strcpy_G(char *s1, const char __generic *s2);

Description Identical to stropy except that the string s2 being copied can be in flash or data

memory.

strcpy_P

Syntax char * strcpy_P(char *s1, PGM_P s2);

Description Identical to stropy except that the string s2 being copied is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

strerror_P

Syntax PGM_P strerror_P(int errnum);

Description Identical to strerror except that the string returned is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

strlen G

Syntax size_t strlen_G(const char __generic *s);

Description Identical to strlen except that the string being tested can be in flash or data memory.

strlen P

Syntax size_t strlen_P(PGM_P s);

Description Identical to strlen except that the string being tested is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

strncat G

Syntax char *strncat_G(char *s1, const char __generic *s2, size_t n);

Description Identical to strncmp except that the string s2 can be in flash *or* data memory.

strncmp_G

Description Identical to strncmp except that the string s2 can be in flash or data memory.

strncmp_P

Syntax int strncmp_P(const char *s1, PGM_P s2, size_t n);

Description Identical to strncmp except that the string s2 is in flash memory, not in data memory.

This function is available in both the CLIB and the DLIB library.

strncpy_G

Description Identical to strncpy except that the source string s2 can be in flash or data memory.

strncpy_P

Syntax char * strncpy_P(char *s1, PGM_P s2, size_t n);

Description Identical to strncpy except that the source string s2 is in flash memory, not in data

memory. This function is available in both the CLIB and the DLIB library.

AVR-specific library functions

Segment reference

The compiler places code and data into named segments which are referred to by the IAR XLINK Linker. Details about the segments are required for programming assembler language modules, and are also useful when interpreting the assembler language output from the compiler.

For more information about segments, see the chapter Placing code and data.

Summary of segments

The table below lists the segments that are available in the compiler:

| Segment | Description |
|----------|---|
| CHECKSUM | Holds the checksum generated by the linker. |
| CODE | Holds the program code. |
| CSTACK | Holds the stack used by C or C++ programs. |
| DIFUNCT | Holds pointers to code, typically C++ constructors, that should be executed by the system startup code before main is called. |
| EEPROM_I | Holdseeprom static and global initialized variables. |
| EEPROM_N | Holdsno_initeeprom static and global variables. |
| FARCODE | Holds program code declaredfarfunc. |
| FAR_C | Holdsfar constant data. |
| FAR_F | Holds static and globalfarflash variables. |
| FAR_HEAP | Holds the heap used for dynamically allocated data in far memory using the DLIB library. |
| FAR_I | Holdsfar static and global initialized variables. |
| FAR_ID | Holds initial values forfar static and global variables in FAR_I. |
| FAR_N | Holdsno_initfar static and global variables. |
| FAR_Z | Holds zero-initializedfar static and global variables. |
| HEAP | Holds the heap used for dynamically allocated data using the CLIB library. |
| HUGE_C | Holdshuge constant data. |
| HUGE_F | Holds static and globalhugeflash variables. |

Table 52: Segment summary

| Segment | Description |
|-----------|--|
| HUGE_HEAP | Holds the heap used for dynamically allocated data in huge memory using the DLIB library. |
| HUGE_I | Holdshuge static and global initialized variables. |
| HUGE_ID | Holds initial values for $__$ huge static and global variables in <code>HUGE_I</code> . |
| HUGE_N | Holdsno_inithuge static and global variables. |
| HUGE_Z | Holds zero-initializedhuge static and global variables. |
| INITTAB | Contains compiler-generated table entries that describe the segment initialization that will be performed at system startup. |
| INTVEC | Contains the reset and interrupt vectors. |
| NEAR_C | Holdstiny andnear constant data. |
| NEAR_F | Holds static and globalflash variables. |
| NEAR_HEAP | Holds the heap used for dynamically allocated data in near memory using the DLIB library. |
| NEAR_I | Holdsnear static and global initialized variables. |
| NEAR_ID | Holds initial values fornear static and global variables in NEAR_I. |
| NEAR_N | Holdsno_initnear static and global variables. |
| NEAR_Z | Holds zero-initializednear static and global variables. |
| RSTACK | Holds the internal return stack. |
| SWITCH | Holds switch tables for all functions. |
| TINY_F | Holds static and globaltinyflash variables. |
| TINY_HEAP | Holds the heap used for dynamically allocated data in tiny memory using the DLIB library. |
| TINY_I | Holdstiny static and global initialized variables. |
| TINY_ID | Holds initial values for $__tiny$ static and global variables in $TINY_I$. |
| TINY_N | Holdsno_inittiny static and global variables. |
| TINY_Z | Holds zero-initialized $__tiny$ static and global variables. |

Table 52: Segment summary (Continued)

Descriptions of segments

This section gives reference information about each segment.

The segments are placed in memory by the segment placement linker directives -Z and -P, for sequential and packed placement, respectively. Some segments cannot use packed placement, as their contents must be continuous.

In each description, the segment memory type—CODE, DATA, or XDATA—indicates whether the segment should be placed in ROM, RAM, or EEPROM memory; see Table 7, *XLINK segment memory types*, page 54.

For information about the -Z and the -P directives, see the *IAR Linker and Library Tools Reference Guide*.

For information about how to define segments in the linker configuration file, see *Customizing the linker configuration file*, page 54.

For more information about the extended keywords mentioned here, see the chapter *Extended keywords*.

CHECKSUM

Description Holds the checksum bytes generated by the linker. This segment also holds the

__checksum symbol. Note that the size of this segment is affected by the linker option

-J.

Segment memory type CODE

Memory placement This segment can be placed anywhere in ROM memory.

Access type Read-only

CODE

Description Holds __nearfunc program code, except the code for system initialization.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x01FFFE.

Access type Read-only

CSTACK

Description Holds the internal data stack.

Segment memory type DATA

Memory placement Data. The address range depends on the memory model:

In the Tiny memory model, this segment must be placed within the address range

0x0-0xFF.

In the Small memory model, this segment must be placed within the address range

0x0-0xFFFF.

In the Large and Huge memory models, this segment must be placed within the address range $0\times0-0\times FFFFFFF$. In the Large and Huge memory models, the stack can be a

maximum of 64 Kbytes, and CSTACK must not cross a 64-Kbyte boundary.

Access type Read/write

See also *The stack*, page 61.

DIFUNCT

Description Holds the dynamic initialization vector used by C++.

Segment memory type CODE

Memory placement In the small data model, this segment must be placed in the first 64 Kbytes of memory.

In other data models, this segment can be placed anywhere in memory.

Access type Read-only

EEPROM_I

Description Holds __eeprom static and global initialized variables initialized by copying from the

segment EEPROM_ID at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

This segment is not copied to EEPROM during system startup. Instead it is used for

programming the EEPROM during the download of the code.

Segment memory type XDATA

Memory placement This segment must be placed in EEPROM. Use the command line option

--eeprom_size to set the address range for this segment.

Access type Read-only

See also --eeprom size, page 204

EEPROM N

Description Holds static and global __no_init __eeprom variables.

Segment memory type XDATA

Memory placement This segment must be placed in EEPROM. Use the command line option

--eeprom_size to set the address range for this segment.

Access type Read-only

See also --eeprom size, page 204

FARCODE

Description Holds __farfunc program code. The __farfunc memory attribute is available when

using the -v5 and -v6 options, in which case the __farfunc is implicitly used for all

functions.

Segment memory type CODE

Memory placement This segment must be placed within the address range 0x0-0x7FFFFE in flash memory.

Access type Read-only

FAR C

Description Holds __far constant data. This can include constant variables, string and aggregate

literals, etc.

Note: This segment is located in external ROM. Systems without external ROM cannot

use this segment.

Segment memory type DATA

Memory placement External ROM. This segment must be placed within the address range 0x0-0xFFFFFFF.

Access type Read-only

FAR F

Description Holds the static and global __farflash variables and aggregate initializers.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x7ffffff.

Access type Read-only

FAR HEAP

Description Holds the heap used for dynamically allocated data in far memory, in other words data

allocated by far_malloc and far_free, and in C++, new and delete.

Note: This segment is only used when you use the DLIB library.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

See also The heap, page 64 and New and Delete operators, page 149.

FAR_I

Description Holds __far static and global initialized variables initialized by copying from the

segment FAR_ID at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -Z directive must be used.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xffffff.

Access type Read/write

FAR ID

Description Holds initial values for __far static and global variables in the FAR_I segment. These

values are copied from FAR_ID to FAR_I at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x7FFFFF.

Access type Read-only

FAR N

Description Holds static and global __no_init __far variables.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xffffff.

Access type Read/write

FAR Z

Description Holds zero-initialized __far static and global variables. The contents of this segment

is declared by the system startup code.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

HEAP

Description Holds the heap used for dynamically allocated data, in other words data allocated by

malloc and free, and in C++, new and delete.

Note: This segment is only used when you use the CLIB library.

Segment memory type DATA

Memory placement Data. The address range depends on the memory model.

In the Tiny memory model, this segment must be placed within the address range

 $0 \times 0 - 0 \times FF$.

In the Small memory model, this segment must be placed within the address range

0x0-0xFFFF.

In the Large and Huge memory models, this segment must be placed within the address

range 0x0-0xFFFFFF.

Access type Read/write

See also The heap, page 64.

HUGE_C

Description Holds __huge constant data. This can include constant variables, string and aggregate

literals, etc.

Note: This segment is located in external ROM. Systems without external ROM cannot

use this segment.

Segment memory type DATA

Memory placement External ROM. This segment must be placed within the address range 0x0-0xFFFFFFF.

Access type Read-only

HUGE_F

Description Holds the static and global __hugeflash variables and aggregate initializers.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0xFFFFFFF.

Access type Read-only

HUGE HEAP

Description Holds the heap used for dynamically allocated data in huge memory, in other words data

allocated by huge_malloc and huge_free, and in C++, new and delete.

Note: This segment is only used when you use the DLIB library.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

See also The heap, page 64 and New and Delete operators, page 149.

HUGE I

Description Holds __huge static and global initialized variables initialized by copying from the

segment HUGE_ID at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

When the -y compiler option is used, __huge constant data is located in this segment.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

HUGE_ID

Description Holds initial values for __huge static and global variables in the HUGE_I segment.

These values are copied from HUGE_ID to HUGE_I at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this segment in the linker configuration file, the -Z directive must be used.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x7ffffff.

Access type Read-only

HUGE N

Description Holds static and global __no_init __huge variables.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

HUGE Z

Description Holds zero-initialized __huge static and global variables. The contents of this segment

is declared by the system startup code.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -Z directive must be used.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xfffffff.

Access type Read/write

INITTAB

Description Holds compiler-generated table entries that describe the segment initialization which

will be performed at system startup.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0xFFFFF (0x7FFFFFF

if farflash is enabled).

Access type Read-only

INTVEC

Description Holds the interrupt vector table generated by the use of the __interrupt extended

keyword in combination with the #pragma vector directive.

Segment memory type CODE

Memory placement This segment can be placed anywhere in memory.

Access type Read-only

NEAR C

Description Holds __tiny and __near constant data. This can include constant variables, string

and aggregate literals, etc. TINY_I is copied from this segment, because TINY_C is not

a possible segment.

Note: This segment is located in external ROM. Systems without external ROM cannot

use this segment.

Segment memory type DATA

Memory placement External ROM. This segment must be placed within the address range 0x0-0xFFFF.

Access type Read-only

NEAR_F

Description Holds the static and global __flash variables and aggregate initializers.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0xffff.

Access type Read-only

NEAR HEAP

Description Holds the heap used for dynamically allocated data in near memory, in other words data

allocated by near_malloc and near_free, and in C++, new and delete.

Note: This segment is only used when you use the DLIB library.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFFFF.

Access type Read/write

See also The heap, page 64 and New and Delete operators, page 149.

NEAR I

Description Holds __near static and global initialized variables initialized by copying from the

segment NEAR_ID at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

When the -y compiler option is used, NEAR C data (near) is located in this segment.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFFFF.

Access type Read/write

NEAR ID

Description Holds initial values for __near static and global variables in the NEAR_I segment.

These values are copied from NEAR_ID to NEAR_I at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -Z directive must be used.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x7FFFFF.

Access type Read-only

NEAR_N

Description Holds static and global __no_init __near variables.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xffff.

Access type Read/write

NEAR_Z

Description Holds zero-initialized __near static and global variables. The contents of this segment

is declared by the system startup code.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFFFF.

Access type Read/write

RSTACK

Description Holds the internal return stack.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xffff.

Access type Read/write

SWITCH

Description Holds switch tables for all functions.

The SWITCH segment is for compiler internal use only and should always be defined. The segment allocates, if necessary, jump tables for C/C++ switch statements.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0xFFFF. If the

__farflash extended keyword and the --enhanced_core option are used, the segment must be placed within the range 0x0-0x7FFFFF. This segment must not cross

a 64-Kbyte boundary.

Access type Read-only

TINY F

Description Holds the static and global __tinyflash variables and aggregate initializers.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0xFF.

Access type Read-only

TINY HEAP

Description Holds the heap used for dynamically allocated data in tiny memory, in other words data

allocated by tiny_malloc and tiny_free, and in C++, new and delete.

Note: This segment is only used when you use the DLIB library.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFF.

Access type Read/write

See also The heap, page 64 and New and Delete operators, page 149.

TINY_I

Description Holds __tiny static and global initialized variables initialized by copying from the

segment TINY_ID at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -Z directive must be used.

When the -y compiler option is not used, NEAR_C data is located in this segment.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFF.

Access type Read/write

TINY ID

Description Holds initial values for __tiny static and global variables in the TINY_I segment.

These values are copied from TINY_ID to TINY_I at application startup.

This segment cannot be placed in memory by using the -P directive for packed placement, because the contents must be continuous. Instead, when you define this

segment in the linker configuration file, the -z directive must be used.

Segment memory type CODE

Memory placement Flash. This segment must be placed within the address range 0x0-0x7FFFFF.

Access type Read-only

TINY N

Description Holds static and global __no_init __tiny variables.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xff.

Access type Read/write

TINY_Z

Description Holds zero-initialized __tiny static and global variables. The contents of this segment

is declared by the system startup code.

This segment cannot be placed in memory by using the $\neg P$ directive for packed placement, because the contents must be continuous. Instead, when you define this segment in the linker configuration file, the $\neg Z$ directive must be used.

Segment memory type DATA

Memory placement Data. This segment must be placed within the address range 0x0-0xFF.

Access type Read/write

Implementation-defined behavior

This chapter describes how IAR Systems handles the implementation-defined areas of the C language.

Note: The IAR Systems implementation adheres to a freestanding implementation of Standard C. This means that parts of a standard library can be excluded in the implementation.

The text in this chapter applies to the DLIB library. Because the CLIB library does not follow Standard C, its implementation-defined behavior is not documented. For information about the CLIB library, see *The CLIB runtime environment*, page 109.

Descriptions of implementation-defined behavior

This section follows the same order as the C standard. Each item includes references to the ISO chapter and section (in parenthesis) that explains the implementation-defined behavior.

J.3.1 Translation

Diagnostics (3.10, 5.1.1.3)

Diagnostics are produced in the form:

filename, linenumber level[tag]: message

where filename is the name of the source file in which the error was encountered, linenumber is the line number at which the compiler detected the error, level is the level of seriousness of the message (remark, warning, error, or fatal error), tag is a unique tag that identifies the message, and message is an explanatory message, possibly several lines.

White-space characters (5.1.1.2)

At translation phase three, each non-empty sequence of white-space characters is retained.

J.3.2 Environment

The character set (5.1.1.2)

The source character set is the same as the physical source file multibyte character set. By default, the standard ASCII character set is used. However, if you use the --enable_multibytes compiler option, the host character set is used instead.

Main (5.1.2.1)

The function called at program startup is called main. No prototype is declared for main, and the only definition supported for main is:

```
int main(void)
```

To change this behavior for the IAR DLIB runtime environment, see *Customizing* system initialization, page 87.

The effect of program termination (5.1.2.1)

Terminating the application returns the execution to the startup code (just after the call to main).

Alternative ways to define main (5.1.2.2.1)

There is no alternative ways to define the main function.

The argy argument to main (5.1.2.2.1)

The argv argument is not supported.

Streams as interactive devices (5.1.2.3)

The streams stdin, stdout, and stderr are treated as interactive devices.

Signals, their semantics, and the default handling (7.14)

In the DLIB library, the set of supported signals is the same as in Standard C. A raised signal will do nothing, unless the signal function is customized to fit the application.

Signal values for computational exceptions (7.14.1.1)

In the DLIB library, there are no implementation-defined values that correspond to a computational exception.

Signals at system startup (7.14.1.1)

In the DLIB library, there are no implementation-defined signals that are executed at system startup.

Environment names (7.20.4.5)

In the DLIB library, there are no implementation-defined environment names that are used by the geteny function.

The system function (7.20.4.6)

The system function is not supported.

J.3.3 Identifiers

Multibyte characters in identifiers (6.4.2)

Additional multibyte characters may not appear in identifiers.

Significant characters in identifiers (5.2.4.1, 6.1.2)

The number of significant initial characters in an identifier with or without external linkage is guaranteed to be no less than 200.

J.3.4 Characters

Number of bits in a byte (3.6)

A byte contains 8 bits.

Execution character set member values (5.2.1)

The values of the members of the execution character set are the values of the ASCII character set, which can be augmented by the values of the extra characters in the host character set.

Alphabetic escape sequences (5.2.2)

The standard alphabetic escape sequences have the values a-7, b-8, f-12, n-10, r-13, t-9, and v-11.

Characters outside of the basic executive character set (6.2.5)

A character outside of the basic executive character set that is stored in a char is not transformed.

Plain char (6.2.5, 6.3.1.1)

A plain char is treated as an unsigned char.

Source and execution character sets (6.4.4.4, 5.1.1.2)

The source character set is the set of legal characters that can appear in source files. By default, the source character set is the standard ASCII character set. However, if you use the command line option --enable_multibytes, the source character set will be the host computer's default character set.

The execution character set is the set of legal characters that can appear in the execution environment. By default, the execution character set is the standard ASCII character set.

However, if you use the command line option --enable_multibytes, the execution character set will be the host computer's default character set. The IAR DLIB Library needs a multibyte character scanner to support a multibyte execution character set. See *Locale*, page 93.

Integer character constants with more than one character (6.4.4.4)

An integer character constant that contains more than one character will be treated as an integer constant. The value will be calculated by treating the leftmost character as the most significant character, and the rightmost character as the least significant character, in an integer constant. A diagnostic message will be issued if the value cannot be represented in an integer constant.

Wide character constants with more than one character (6.4.4.4)

A wide character constant that contains more than one multibyte character generates a diagnostic message.

Locale used for wide character constants (6.4.4.4)

By default, the C locale is used. If the --enable_multibytes compiler option is used, the default host locale is used instead.

Locale used for wide string literals (6.4.5)

By default, the C locale is used. If the --enable_multibytes compiler option is used, the default host locale is used instead.

Source characters as executive characters (6.4.5)

All source characters can be represented as executive characters.

J.3.5 Integers

Extended integer types (6.2.5)

There are no extended integer types.

Range of integer values (6.2.6.2)

The representation of integer values are in the two's complement form. The most significant bit holds the sign; 1 for negative, 0 for positive and zero.

For information about the ranges for the different integer types, see *Basic data types*, page 232.

The rank of extended integer types (6.3.1.1)

There are no extended integer types.

Signals when converting to a signed integer type (6.3.1.3)

No signal is raised when an integer is converted to a signed integer type.

Signed bitwise operations (6.5)

Bitwise operations on signed integers work the same way as bitwise operations on unsigned integers; in other words, the sign-bit will be treated as any other bit.

J.3.6 Floating point

Accuracy of floating-point operations (5.2.4.2.2)

The accuracy of floating-point operations is unknown.

Rounding behaviors (5.2.4.2.2)

There are no non-standard values of FLT ROUNDS.

Evaluation methods (5.2.4.2.2)

There are no non-standard values of FLT_EVAL_METHOD.

Converting integer values to floating-point values (6.3.1.4)

When an integral value is converted to a floating-point value that cannot exactly represent the source value, the round-to-nearest rounding mode is used (FLT_ROUNDS is defined to 1).

Converting floating-point values to floating-point values (6.3.1.5)

When a floating-point value is converted to a floating-point value that cannot exactly represent the source value, the round-to-nearest rounding mode is used (FLT_ROUNDS is defined to 1).

Denoting the value of floating-point constants (6.4.4.2)

The round-to-nearest rounding mode is used (FLT_ROUNDS is defined to 1).

Contraction of floating-point values (6.5)

Floating-point values are contracted. However, there is no loss in precision and because signaling is not supported, this does not matter.

Default state of FENV_ACCESS (7.6.1)

The default state of the pragma directive FENV_ACCESS is OFF.

Additional floating-point mechanisms (7.6, 7.12)

There are no additional floating-point exceptions, rounding-modes, environments, and classifications.

Default state of FP_CONTRACT (7.12.2)

The default state of the pragma directive FP_CONTRACT is OFF.

J.3.7 Arrays and pointers

Conversion from/to pointers (6.3.2.3)

For information about casting of data pointers and function pointers, see *Casting*, page 238.

ptrdiff_t (6.5.6)

For information about ptrdiff_t, see *ptrdiff_t*, page 239.

J.3.8 Hints

Honoring the register keyword (6.7.1)

User requests for register variables are not honored.

Inlining functions (6.7.4)

User requests for inlining functions increases the chance, but does not make it certain, that the function will actually be inlined into another function. See the pragma directive *inline*, page 272.

J.3.9 Structures, unions, enumerations, and bitfields

Sign of 'plain' bitfields (6.7.2, 6.7.2.1)

For information about how a 'plain' int bitfield is treated, see *Bitfields*, page 233.

Possible types for bitfields (6.7.2.1)

All integer types can be used as bitfields in the compiler's extended mode, see -e, page 203.

Bitfields straddling a storage-unit boundary (6.7.2.1)

A bitfield is always placed in one—and one only—storage unit, which means that the bitfield cannot straddle a storage-unit boundary.

Allocation order of bitfields within a unit (6.7.2.1)

For information about how bitfields are allocated within a storage unit, see *Bitfields*, page 233.

Alignment of non-bitfield structure members (6.7.2.1)

The alignment of non-bitfield members of structures is the same as for the member types, see *Alignment*, page 231.

Integer type used for representing enumeration types (6.7.2.2)

The chosen integer type for a specific enumeration type depends on the enumeration constants defined for the enumeration type. The chosen integer type is the smallest possible.

J.3.10 Qualifiers

Access to volatile objects (6.7.3)

Any reference to an object with volatile qualified type is an access, see *Declaring* objects volatile, page 240.

J.3.11 Preprocessing directives

Mapping of header names (6.4.7)

Sequences in header names are mapped to source file names verbatim. A backslash '\' is not treated as an escape sequence. See *Overview of the preprocessor*, page 293.

Character constants in constant expressions (6.10.1)

A character constant in a constant expression that controls conditional inclusion matches the value of the same character constant in the execution character set.

The value of a single-character constant (6.10.1)

A single-character constant may only have a negative value if a plain character (char) is treated as a signed character, see --char is signed, page 195.

Including bracketed filenames (6.10.2)

For information about the search algorithm used for file specifications in angle brackets <>, see *Include file search procedure*, page 182.

Including quoted filenames (6.10.2)

For information about the search algorithm used for file specifications enclosed in quotes, see *Include file search procedure*, page 182.

Preprocessing tokens in #include directives (6.10.2)

Preprocessing tokens in an #include directive are combined in the same way as outside an #include directive.

Nesting limits for #include directives (6.10.2)

There is no explicit nesting limit for #include processing.

Universal character names (6.10.3.2)

Universal character names (UCN) are not supported.

Recognized pragma directives (6.10.6)

In addition to the pragma directives described in the chapter *Pragma directives*, the following directives are recognized and will have an indeterminate effect. If a pragma directive is listed both in the *Pragma directives* chapter and here, the information provided in the *Pragma directives* chapter overrides the information here.

alignment

```
baseaddr
building runtime
can_instantiate
codeseq
cspy_support
define_type_info
do_not_instantiate
early_dynamic_initialization
function
hdrstop
important_typedef
instantiate
keep_definition
memory
module_name
no_pch
once
public_equ
system_include
warnings
```

Default __DATE__ and __TIME__ (6.10.8)

The definitions for __TIME__ and __DATE__ are always available.

J.3.12 Library functions

Additional library facilities (5.1.2.1)

Most of the standard library facilities are supported. Some of them—the ones that need an operating system—requiere a low-level implementation in the application. For more information, see *The DLIB runtime environment*, page 71.

Diagnostic printed by the assert function (7.2.1.1)

The assert () function prints:

filename: linenr expression -- assertion failed

when the parameter evaluates to zero.

Representation of the floating-point status flags (7.6.2.2)

For information about the floating-point status flags, see *fenv.h*, page 307.

Feraiseexcept raising floating-point exception (7.6.2.3)

For information about the feraiseexcept function raising floating-point exceptions, see *Floating-point environment*, page 235.

Strings passed to the setlocale function (7.11.1.1)

For information about strings passed to the setlocale function, see *Locale*, page 93.

Types defined for float_t and double_t (7.12)

The FLT_EVAL_METHOD macro can only have the value 0.

Domain errors (7.12.1)

No function generates other domain errors than what the standard requires.

Return values on domain errors (7.12.1)

Mathematic functions return a floating-point NaN (not a number) for domain errors.

Underflow errors (7.12.1)

Mathematic functions set errno to the macro ERANGE (a macro in errno.h) and return zero for underflow errors.

fmod return value (7.12.10.1)

The fmod function returns a floating-point NaN when the second argument is zero.

The magnitude of remquo (7.12.10.3)

The magnitude is congruent modulo INT_MAX.

signal() (7.14.1.1)

The signal part of the library is not supported.

Note: Low-level interface functions exist in the library, but will not perform anything. Use the template source code to implement application-specific signal handling. See *Signal and raise*, page 96.

NULL macro (7.17)

The NULL macro is defined to 0.

Terminating newline character (7.19.2)

stdout stream functions recognize either newline or end of file (EOF) as the terminating character for a line.

Space characters before a newline character (7.19.2)

Space characters written to a stream immediately before a newline character are preserved.

Null characters appended to data written to binary streams (7.19.2)

No null characters are appended to data written to binary streams.

File position in append mode (7.19.3)

The file position is initially placed at the beginning of the file when it is opened in append-mode.

Truncation of files (7.19.3)

Whether a write operation on a text stream causes the associated file to be truncated beyond that point, depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 92.

File buffering (7.19.3)

An open file can be either block-buffered, line-buffered, or unbuffered.

A zero-length file (7.19.3)

Whether a zero-length file exists depends on the application-specific implementation of the low-level file routines.

Legal file names (7.19.3)

The legality of a filename depends on the application-specific implementation of the low-level file routines.

Number of times a file can be opened (7.19.3)

Whether a file can be opened more than once depends on the application-specific implementation of the low-level file routines.

Multibyte characters in a file (7.19.3)

The encoding of multibyte characters in a file depends on the application-specific implementation of the low-level file routines.

remove() (7.19.4.1)

The effect of a remove operation on an open file depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 92.

rename() (7.19.4.2)

The effect of renaming a file to an already existing filename depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 92.

Removal of open temporary files (7.19.4.3)

Whether an open temporary file is removed depends on the application-specific implementation of the low-level file routines.

Mode changing (7.19.5.4)

freopen closes the named stream, then reopens it in the new mode. The streams stdin, stdout, and stderr can be reopened in any new mode.

Style for printing infinity or NaN (7.19.6.1, 7.24.2.1)

The style used for printing infinity or NaN for a floating-point constant is inf and nan (INF and NAN for the F conversion specifier), respectively. The n-char-sequence is not used for nan.

%p in printf() (7.19.6.1, 7.24.2.1)

The argument to a *p conversion specifier, print pointer, to printf() is treated as having the type void *. The value will be printed as a hexadecimal number, similar to using the *x conversion specifier.

Reading ranges in scanf (7.19.6.2, 7.24.2.1)

A - (dash) character is always treated as a range symbol.

%p in scanf (7.19.6.2, 7.24.2.2)

The p conversion specifier, scan pointer, to p reads a hexadecimal number and converts it into a value with the type p void p.

File position errors (7.19.9.1, 7.19.9.3, 7.19.9.4)

On file position errors, the functions fgetpos, ftell, and fsetpos store EFPOS in errno.

An n-char-sequence after nan (7.20.1.3, 7.24.4.1.1)

An n-char-sequence after a NaN is read and ignored.

errno value at underflow (7.20.1.3, 7.24.4.1.1)

errno is set to ERANGE if an underflow is encountered.

Zero-sized heap objects (7.20.3)

A request for a zero-sized heap object will return a valid pointer and not a null pointer.

Behavior of abort and exit (7.20.4.1, 7.20.4.4)

A call to $\mathtt{abort}()$ or $\mathtt{_Exit}()$ will not flush stream buffers, not close open streams, and not remove temporary files.

Termination status (7.20.4.1, 7.20.4.3, 7.20.4.4)

The termination status will be propagated to __exit() as a parameter. exit() and _Exit() use the input parameter, whereas abort uses EXIT_FAILURE.

The system function return value (7.20.4.6)

The system function is not supported.

The time zone (7.23.1)

The local time zone and daylight savings time must be defined by the application. For more information, see *Time*, page 97.

Range and precision of time (7.23)

The implementation uses signed long for representing clock_t and time_t, based at the start of the year 1970. This gives a range of approximately plus or minus 69 years in seconds. However, the application must supply the actual implementation for the functions time and clock. See *Time*, page 97.

clock() (7.23.2.1)

The application must supply an implementation of the clock function. See *Time*, page 97.

%Z replacement string (7.23.3.5, 7.24.5.1)

By default, ":" is used as a replacement for %z. Your application should implement the time zone handling. See *Time*, page 97.

Math functions rounding mode (F.9)

The functions in math.h honor the rounding direction mode in FLT-ROUNDS.

J.3.13 Architecture

Values and expressions assigned to some macros (5.2.4.2, 7.18.2, 7.18.3)

There are always 8 bits in a byte.

MB_LEN_MAX is at the most 6 bytes depending on the library configuration that is used.

For information about sizes, ranges, etc for all basic types, see *Data representation*, page 231.

The limit macros for the exact-width, minimum-width, and fastest minimum-width integer types defined in stdint.h have the same ranges as char, short, int, long, and long long.

The floating-point constant FLT_ROUNDS has the value 1 (to nearest) and the floating-point constant FLT_EVAL_METHOD has the value 0 (treat as is).

The number, order, and encoding of bytes (6.2.6.1)

See Data representation, page 231.

The value of the result of the size of operator (6.5.3.4)

See Data representation, page 231.

J.4 Locale

Members of the source and execution character set (5.2.1)

By default, the compiler accepts all one-byte characters in the host's default character set. If the compiler option --enable_multibytes is used, the host multibyte characters are accepted in comments and string literals as well.

The meaning of the additional character set (5.2.1.2)

Any multibyte characters in the extended source character set is translated verbatim into the extended execution character set. It is up to your application with the support of the library configuration to handle the characters correctly.

Shift states for encoding multibyte characters (5.2.1.2)

Using the compiler option --enable_multibytes enables the use of the host's default multibyte characters as extended source characters.

Direction of successive printing characters (5.2.2)

The application defines the characteristics of a display device.

The decimal point character (7.1.1)

The default decimal-point character is a '.'. You can redefine it by defining the library configuration symbol _LOCALE_DECIMAL_POINT.

Printing characters (7.4, 7.25.2)

The set of printing characters is determined by the chosen locale.

Control characters (7.4, 7.25.2)

The set of control characters is determined by the chosen locale.

Characters tested for (7.4.1.2, 7.4.1.3, 7.4.1.7, 7.4.1.9, 7.4.1.10, 7.4.1.11, 7.25.2.1.2, 7.25.5.1.3, 7.25.2.1.7, 7.25.2.1.9, 7.25.2.1.10, 7.25.2.1.11)

The sets of characters tested are determined by the chosen locale.

The native environment (7.1.1.1)

The native environment is the same as the "C" locale.

Subject sequences for numeric conversion functions (7.20.1, 7.24.4.1)

There are no additional subject sequences that can be accepted by the numeric conversion functions

The collation of the execution character set (7.21.4.3, 7.24.4.4.2)

The collation of the execution character set is determined by the chosen locale.

Message returned by strerror (7.21.6.2)

The messages returned by the strerror function depending on the argument is:

| Argument | Message |
|------------|---------------------------|
| EZERO | no error |
| EDOM | domain error |
| ERANGE | range error |
| EFPOS | file positioning error |
| EILSEQ | multi-byte encoding error |
| <0 >99 | unknown error |
| all others | error nnn |

Table 53: Message returned by strerror()—IAR DLIB library

Implementation-defined behavior for C89

This chapter describes how the compiler handles the implementation-defined areas of the C language based on the C89 standard.

If you are using Standard C instead of C89, see *Implementation-defined behavior*, page 333. For a short overview of the differences between Standard C and C89, see *C language overview*, page 135.

Descriptions of implementation-defined behavior

This section follows the same order as the ISO appendix. Each item covered includes references to the ISO chapter and section (in parenthesis) that explains the implementation-defined behavior.

Translation

Diagnostics (5.1.1.3)

Diagnostics are produced in the form:

filename, linenumber level[tag]: message

where filename is the name of the source file in which the error was encountered, linenumber is the line number at which the compiler detected the error, level is the level of seriousness of the message (remark, warning, error, or fatal error), tag is a unique tag that identifies the message, and message is an explanatory message, possibly several lines.

Environment

Arguments to main (5.1.2.2.2.1)

The function called at program startup is called main. No prototype was declared for main, and the only definition supported for main is:

int main(void)

To change this behavior for the IAR DLIB runtime environment, see *Customizing system initialization*, page 87. To change this behavior for the IAR CLIB runtime environment, see *Customizing system initialization*, page 114.

Interactive devices (5.1.2.3)

The streams stdin and stdout are treated as interactive devices.

Identifiers

Significant characters without external linkage (6.1.2)

The number of significant initial characters in an identifier without external linkage is 200.

Significant characters with external linkage (6.1.2)

The number of significant initial characters in an identifier with external linkage is 200.

Case distinctions are significant (6.1.2)

Identifiers with external linkage are treated as case-sensitive.

Characters

Source and execution character sets (5.2.1)

The source character set is the set of legal characters that can appear in source files. The default source character set is the standard ASCII character set. However, if you use the command line option --enable_multibytes, the source character set will be the host computer's default character set.

The execution character set is the set of legal characters that can appear in the execution environment. The default execution character set is the standard ASCII character set. However, if you use the command line option <code>--enable_multibytes</code>, the execution character set will be the host computer's default character set. The IAR DLIB Library needs a multibyte character scanner to support a multibyte execution character set. The IAR CLIB Library does not support multibyte characters.

See Locale, page 93.

Bits per character in execution character set (5.2.4.2.1)

The number of bits in a character is represented by the manifest constant CHAR_BIT. The standard include file limits.h defines CHAR_BIT as 8.

Mapping of characters (6.1.3.4)

The mapping of members of the source character set (in character and string literals) to members of the execution character set is made in a one-to-one way. In other words, the same representation value is used for each member in the character sets except for the escape sequences listed in the ISO standard.

Unrepresented character constants (6.1.3.4)

The value of an integer character constant that contains a character or escape sequence not represented in the basic execution character set or in the extended character set for a wide character constant generates a diagnostic message, and will be truncated to fit the execution character set.

Character constant with more than one character (6.1.3.4)

An integer character constant that contains more than one character will be treated as an integer constant. The value will be calculated by treating the leftmost character as the most significant character, and the rightmost character as the least significant character, in an integer constant. A diagnostic message will be issued if the value cannot be represented in an integer constant.

A wide character constant that contains more than one multibyte character generates a diagnostic message.

Converting multibyte characters (6.1.3.4)

The only locale supported—that is, the only locale supplied with the IAR C/C++ Compiler—is the 'C' locale. If you use the command line option --enable_multibytes, the IAR DLIB Library will support multibyte characters if you add a locale with multibyte support or a multibyte character scanner to the library. The IAR CLIB Library does not support multibyte characters.

See Locale, page 93.

Range of 'plain' char (6.2.1.1)

A 'plain' char has the same range as an unsigned char.

Integers

Range of integer values (6.1.2.5)

The representation of integer values are in the two's complement form. The most significant bit holds the sign; 1 for negative, 0 for positive and zero.

See *Basic data types*, page 232, for information about the ranges for the different integer types.

Demotion of integers (6.2.1.2)

Converting an integer to a shorter signed integer is made by truncation. If the value cannot be represented when converting an unsigned integer to a signed integer of equal length, the bit-pattern remains the same. In other words, a large enough value will be converted into a negative value.

Signed bitwise operations (6.3)

Bitwise operations on signed integers work the same way as bitwise operations on unsigned integers; in other words, the sign-bit will be treated as any other bit.

Sign of the remainder on integer division (6.3.5)

The sign of the remainder on integer division is the same as the sign of the dividend.

Negative valued signed right shifts (6.3.7)

The result of a right-shift of a negative-valued signed integral type preserves the sign-bit. For example, shifting 0xFF00 down one step yields 0xFF80.

Floating point

Representation of floating-point values (6.1.2.5)

The representation and sets of the various floating-point numbers adheres to IEEE 854–1987. A typical floating-point number is built up of a sign-bit (s), a biased exponent (e), and a mantissa (m).

See *Floating-point types*, page 235, for information about the ranges and sizes for the different floating-point types: float and double.

Converting integer values to floating-point values (6.2.1.3)

When an integral number is cast to a floating-point value that cannot exactly represent the value, the value is rounded (up or down) to the nearest suitable value.

Demoting floating-point values (6.2.1.4)

When a floating-point value is converted to a floating-point value of narrower type that cannot exactly represent the value, the value is rounded (up or down) to the nearest suitable value.

Arrays and pointers

size_t (6.3.3.4, 7.1.1)

See *size_t*, page 239, for information about size_t.

Conversion from/to pointers (6.3.4)

See *Casting*, page 238, for information about casting of data pointers and function pointers.

ptrdiff_t (6.3.6, 7.1.1)

See ptrdiff t, page 239, for information about the ptrdiff t.

Registers

Honoring the register keyword (6.5.1)

User requests for register variables are not honored.

Structures, unions, enumerations, and bitfields

Improper access to a union (6.3.2.3)

If a union gets its value stored through a member and is then accessed using a member of a different type, the result is solely dependent on the internal storage of the first member.

Padding and alignment of structure members (6.5.2.1)

See the section *Basic data types*, page 232, for information about the alignment requirement for data objects.

Sign of 'plain' bitfields (6.5.2.1)

A 'plain' int bitfield is treated as a signed int bitfield. All integer types are allowed as bitfields.

Allocation order of bitfields within a unit (6.5.2.1)

Bitfields are allocated within an integer from least-significant to most-significant bit.

Can bitfields straddle a storage-unit boundary (6.5.2.1)

Bitfields cannot straddle a storage-unit boundary for the chosen bitfield integer type.

Integer type chosen to represent enumeration types (6.5.2.2)

The chosen integer type for a specific enumeration type depends on the enumeration constants defined for the enumeration type. The chosen integer type is the smallest possible.

Qualifiers

Access to volatile objects (6.5.3)

Any reference to an object with volatile qualified type is an access.

Declarators

Maximum numbers of declarators (6.5.4)

The number of declarators is not limited. The number is limited only by the available memory.

Statements

Maximum number of case statements (6.6.4.2)

The number of case statements (case values) in a switch statement is not limited. The number is limited only by the available memory.

Preprocessing directives

Character constants and conditional inclusion (6.8.1)

The character set used in the preprocessor directives is the same as the execution character set. The preprocessor recognizes negative character values if a 'plain' character is treated as a signed character.

Including bracketed filenames (6.8.2)

For file specifications enclosed in angle brackets, the preprocessor does not search directories of the parent files. A parent file is the file that contains the #include directive. Instead, it begins by searching for the file in the directories specified on the compiler command line.

Including quoted filenames (6.8.2)

For file specifications enclosed in quotes, the preprocessor directory search begins with the directories of the parent file, then proceeds through the directories of any grandparent files. Thus, searching begins relative to the directory containing the source file currently being processed. If there is no grandparent file and the file is not found, the search continues as if the filename was enclosed in angle brackets.

Character sequences (6.8.2)

Preprocessor directives use the source character set, except for escape sequences. Thus, to specify a path for an include file, use only one backslash:

```
#include "mydirectory\myfile"
Within source code, two backslashes are necessary:
file = fopen("mydirectory\\myfile","rt");
```

Recognized pragma directives (6.8.6)

In addition to the pragma directives described in the chapter *Pragma directives*, the following directives are recognized and will have an indeterminate effect. If a pragma directive is listed both in the *Pragma directives* chapter and here, the information provided in the *Pragma directives* chapter overrides the information here.

```
alignment
baseaddr
building_runtime
can instantiate
codeseq
cspy_support
define_type_info
do not instantiate
early_dynamic_initialization
function
hdrstop
important_typedef
instantiate
keep definition
library_requirement_override
library_provides
library requirement override
```

```
memory
module_name
no_pch
once
public_equ
system_include
warnings
```

Default __DATE__ and __TIME__ (6.8.8)

The definitions for __TIME__ and __DATE__ are always available.

IAR DLIB Library functions

The information in this section is valid only if the runtime library configuration you have chosen supports file descriptors. See the chapter *The DLIB runtime environment* for more information about runtime library configurations.

NULL macro (7.1.6)

The NULL macro is defined to 0.

Diagnostic printed by the assert function (7.2)

```
The assert () function prints:
```

filename: linenr expression -- assertion failed

when the parameter evaluates to zero.

Domain errors (7.5.1)

NaN (Not a Number) will be returned by the mathematic functions on domain errors.

Underflow of floating-point values sets errno to ERANGE (7.5.1)

The mathematics functions set the integer expression errno to ERANGE (a macro in errno.h) on underflow range errors.

fmod() functionality (7.5.6.4)

If the second argument to fmod() is zero, the function returns NaN; errno is set to EDOM.

signal() (7.7.1.1)

The signal part of the library is not supported.

Note: Low-level interface functions exist in the library, but will not perform anything. Use the template source code to implement application-specific signal handling. See Signal and raise, page 96.

Terminating newline character (7.9.2)

stdout stream functions recognize either newline or end of file (EOF) as the terminating character for a line.

Blank lines (7.9.2)

Space characters written to the stdout stream immediately before a newline character are preserved. There is no way to read the line through the stdin stream that was written through the stdout stream.

Null characters appended to data written to binary streams (7.9.2)

No null characters are appended to data written to binary streams.

Files (7.9.3)

Whether a write operation on a text stream causes the associated file to be truncated beyond that point, depends on the application-specific implementation of the low-level file routines. See File input and output, page 92.

remove() (7.9.4.1)

The effect of a remove operation on an open file depends on the application-specific implementation of the low-level file routines. See File input and output, page 92.

rename() (7.9.4.2)

The effect of renaming a file to an already existing filename depends on the application-specific implementation of the low-level file routines. See File input and output, page 92.

%p in printf() (7.9.6.1)

The argument to a %p conversion specifier, print pointer, to printf() is treated as having the type void *. The value will be printed as a hexadecimal number, similar to using the %x conversion specifier.

357

%p in scanf() (7.9.6.2)

The %p conversion specifier, scan pointer, to scanf() reads a hexadecimal number and converts it into a value with the type void *.

Reading ranges in scanf() (7.9.6.2)

A - (dash) character is always treated as a range symbol.

File position errors (7.9.9.1, 7.9.9.4)

On file position errors, the functions fgetpos and ftell store EFPOS in errno.

Message generated by perror() (7.9.10.4)

The generated message is:

usersuppliedprefix:errormessage

Allocating zero bytes of memory (7.10.3)

The calloc(), malloc(), and realloc() functions accept zero as an argument. Memory will be allocated, a valid pointer to that memory is returned, and the memory block can be modified later by realloc.

Behavior of abort() (7.10.4.1)

The abort () function does not flush stream buffers, and it does not handle files, because this is an unsupported feature.

Behavior of exit() (7.10.4.3)

The argument passed to the exit function will be the return value returned by the main function to cstartup.

Environment (7.10.4.4)

The set of available environment names and the method for altering the environment list is described in *Environment interaction*, page 95.

system() (7.10.4.5)

How the command processor works depends on how you have implemented the system function. See *Environment interaction*, page 95.

Message returned by strerror() (7.11.6.2)

The messages returned by strerror() depending on the argument is:

| Argument | Message |
|------------|---------------------------|
| EZERO | no error |
| EDOM | domain error |
| ERANGE | range error |
| EFPOS | file positioning error |
| EILSEQ | multi-byte encoding error |
| <0 >99 | unknown error |
| all others | error nnn |

Table 54: Message returned by strerror()—IAR DLIB library

The time zone (7.12.1)

The local time zone and daylight savings time implementation is described in *Time*, page 97.

clock() (7.12.2.1)

From where the system clock starts counting depends on how you have implemented the clock function. See *Time*, page 97.

IAR CLIB Library functions

NULL macro (7.1.6)

The NULL macro is defined to (void *) 0.

Diagnostic printed by the assert function (7.2)

The assert () function prints:

Assertion failed: expression, file Filename, line linenumber when the parameter evaluates to zero.

Domain errors (7.5.1)

HUGE_VAL, the largest representable value in a double floating-point type, will be returned by the mathematic functions on domain errors.

Underflow of floating-point values sets errno to ERANGE (7.5.1)

The mathematics functions set the integer expression errno to ERANGE (a macro in errno .h) on underflow range errors.

fmod() functionality (7.5.6.4)

If the second argument to fmod() is zero, the function returns zero (it does not change the integer expression errno).

signal() (7.7.1.1)

The signal part of the library is not supported.

Terminating newline character (7.9.2)

stdout stream functions recognize either newline or end of file (EOF) as the terminating character for a line.

Blank lines (7.9.2)

Space characters written to the stdout stream immediately before a newline character are preserved. There is no way to read the line through the stdin stream that was written through the stdout stream.

Null characters appended to data written to binary streams (7.9.2)

There are no binary streams implemented.

Files (7.9.3)

There are no other streams than stdin and stdout. This means that a file system is not implemented.

remove() (7.9.4.1)

There are no other streams than stdin and stdout. This means that a file system is not implemented.

rename() (7.9.4.2)

There are no other streams than stdin and stdout. This means that a file system is not implemented.

%p in printf() (7.9.6.1)

The argument to a %p conversion specifier, print pointer, to printf() is treated as having the type 'char *'. The value will be printed as a hexadecimal number, similar to using the %x conversion specifier.

%p in scanf() (7.9.6.2)

The %p conversion specifier, scan pointer, to scanf() reads a hexadecimal number and converts it into a value with the type 'void *'.

Reading ranges in scanf() (7.9.6.2)

A - (dash) character is always treated explicitly as a - character.

File position errors (7.9.9.1, 7.9.9.4)

There are no other streams than stdin and stdout. This means that a file system is not implemented.

Message generated by perror() (7.9.10.4)

perror() is not supported.

Allocating zero bytes of memory (7.10.3)

The calloc(), malloc(), and realloc() functions accept zero as an argument. Memory will be allocated, a valid pointer to that memory is returned, and the memory block can be modified later by realloc.

Behavior of abort() (7.10.4.1)

The abort () function does not flush stream buffers, and it does not handle files, because this is an unsupported feature.

Behavior of exit() (7.10.4.3)

The exit() function does not return.

Environment (7.10.4.4)

Environments are not supported.

system() (7.10.4.5)

The system() function is not supported.

Message returned by strerror() (7.11.6.2)

The messages returned by strerror() depending on the argument are:

| Argument | Message |
|------------|---------------|
| EZERO | no error |
| EDOM | domain error |
| ERANGE | range error |
| <0 >99 | unknown error |
| all others | error No.xx |

Table 55: Message returned by strerror()—IAR CLIB library

The time zone (7.12.1)

The time zone function is not supported.

clock() (7.12.2.1)

The clock() function is not supported.

A

| abort | |
|--|---------|
| implementation-defined behavior | 345 |
| implementation-defined behavior (CLIB) | 361 |
| implementation-defined behavior (DLIB) | 358 |
| system termination (DLIB) | 86 |
| absolute location | |
| data, placing at (@) | 165 |
| language support for | 138 |
| #pragma location | 274 |
| address spaces, managing multiple | 68 |
| addressing. See memory attributes, | |
| and memory models | |
| algorithm (STL header file) | 305 |
| alignment | 231 |
| forcing stricter (#pragma data_alignment) | 268 |
| in structures (#pragma pack) | 277 |
| of an object (ALIGNOF) | 138 |
| of data types | 231 |
| alignment (pragma directive) | 40, 355 |
| ALIGNOF (operator) | 138 |
| anonymous structures | 162 |
| anonymous symbols, creating | 135 |
| application | |
| building, overview of | 28 |
| startup and termination (CLIB) | 113 |
| startup and termination (DLIB) | 84 |
| architecture | |
| more information about | 17 |
| of AVR | 37 |
| ARGFRAME (assembler directive) | 132 |
| argv (argument), implementation-defined behavior | 334 |
| arrays | |
| designated initializers in | 135 |
| hints about index type | 161 |
| implementation-defined behavior33 | 38, 353 |
| incomplete at end of structs | 135 |
| non-lvalue | 141 |

| of incomplete types | 140 |
|--|------|
| single-value initialization | 142 |
| asm,asm (language extension) | 136 |
| assembler code | |
| calling from C | 120 |
| calling from C++ | 122 |
| inserting inline | 119 |
| assembler directives | |
| for call frame information | 133 |
| for static overlay | 132 |
| using in inline assembler code | 119 |
| assembler instructions, inserting inline | 119 |
| assembler labels, making public (public_equ) | |
| assembler language interface | |
| calling convention. See assembler code | |
| assembler list file, generating | 209 |
| assembler output file | |
| assembler, inline | |
| asserts | |
| implementation-defined behavior of | |
| implementation-defined behavior of, (CLIB) | |
| implementation-defined behavior of, (DLIB) | |
| including in application | |
| assert.h (CLIB header file) | |
| assert.h (DLIB header file) | 304 |
| atomic operations | |
| monitor | 257 |
| attributes | |
| object | 248 |
| type | 245 |
| auto variables | . 44 |
| at function entrance | 127 |
| programming hints for efficient code | 173 |
| using in inline assembler code | 119 |
| AVR | |
| memory layout | . 37 |
| supported devices | |
| | |

| В | call frame information | |
|---|--|--------|
| | in assembler list file | |
| backtrace information See call frame information | in assembler list file (-lA) | |
| Barr, Michael | call stack | |
| baseaddr (pragma directive) | callee-save registers, stored on stack | 44 |
| BASE_FILE (predefined symbol)294 | calling convention | |
| basic_template_matching (pragma directive) | C++, requiring C linkage | |
| using152 | in compiler | |
| batch files | overriding default (version_1) | |
| error return codes | calloc (library function) | 45 |
| for building library from command line83 | See also heap | |
| binary streams | implementation-defined behavior of (CLIB) | . 361 |
| binary streams (CLIB) | implementation-defined behavior of (DLIB) | . 358 |
| binary streams (DLIB) | can_instantiate (pragma directive) | ., 355 |
| bit negation | cassert (library header file) | . 306 |
| bitfields | cast operators | |
| data representation of | in Extended EC++ | l, 154 |
| hints | missing from Embedded C++ | . 144 |
| implementation-defined behavior | casting | |
| implementation-defined behavior of | between pointer types | 42 |
| non-standard types in | of pointers and integers | |
| bitfields (pragma directive) | pointers to integers, language extension | . 140 |
| bits in a byte, implementation-defined behavior | ccomplex (library header file) | |
| bold style, in this guide | cctype (DLIB header file) | |
| bool (data type) | cerrno (DLIB header file) | |
| adding support for in CLIB | cfenv (library header file) | |
| adding support for in DLIB | CFI (assembler directive) | |
| building_runtime (pragma directive)341, 355 | cfloat (DLIB header file) | |
| BUILD_NUMBER (predefined symbol) | char (data type) | |
| byte order (of value), reversing | changing default representation (char_is_signed) | |
| byte order, identifying | changing representation (char_is_unsigned) | |
| byte order, identifying290 | implementation-defined behavior | |
| | signed and unsigned | |
| C | character set, implementation-defined behavior | |
| | characters, implementation-defined behavior of 335 | |
| C and C++ linkage | character-based I/O | , 550 |
| C/C++ calling convention. <i>See</i> calling convention | in CLIB | 111 |
| C header files | in DLIB | |
| C language, overview | overriding in runtime library | |

| char_is_signed (compiler option) | command prompt icon, in this guide |
|---------------------------------------|--|
| CHECKSUM (segment) | after preprocessor directives |
| cinttypes (DLIB header file) | C++ style, using in C code |
| ciso646 (library header file) | common block (call frame information) |
| class memory (extended EC++) | common subexpr elimination (compiler transformation) . 170 |
| class template partial specialization | disabling (no_cse) |
| matching (extended EC++)151 | compilation date |
| CLI (assembler instruction) | exact time of (TIME) |
| CLIB32, 309 | identifying (DATE)294 |
| documentation | compiler |
| runtime environment | environment variables |
| summary of definitions | invocation syntax |
| clib (compiler option) | output from |
| climits (DLIB header file) | compiler listing, generating (-1) |
| clocale (DLIB header file) | compiler object file |
| clock (CLIB library function), | |
| implementation-defined behavior of | including debug information in (debug, -r) |
| clock (DLIB library function), | output from compiler |
| implementation-defined behavior of | compiler optimization levels |
| clock (library function) | compiler options |
| implementation-defined behavior | passing to compiler |
| clock.c | reading from file (-f) |
| | specifying parameters |
| close (DLIB library function) | summary |
| clustering (compiler transformation) | syntax187 |
| disabling (no_clustering) | for creating skeleton code |
| cmath (DLIB header file) | initializers_in_flash226 |
| code | warnings_affect_exit_code |
| interruption of execution | compiler platform, identifying |
| verifying linked result | compiler subversion number |
| code motion (compiler transformation) | compiler transformations |
| disabling (no_code_motion) | compiler version number |
| code segments, used for placement | compiling |
| CODE (segment) | from the command line |
| codeseg (pragma directive) | syntax |
| command line options | complex numbers, supported in Embedded C++144 |
| part of compiler invocation syntax | complex (library header file) |
| passing | complex.h (library header file) |
| See also compiler options | |
| typographic convention 22 | compound literals |

| computer style, typographic convention | cstartup (system startup code) |
|---|---|
| configuration | customizing system initialization87 |
| basic project settings | process for overriding in runtime library |
| low_level_init | cstartup.s90 (system startup code) |
| configuration symbols | source files for (CLIB) |
| for file input and output | source files for (DLIB) |
| for locale | cstdarg (DLIB header file) |
| for printf and scanf91 | cstdbool (DLIB header file) |
| for strtod | cstddef (DLIB header file) |
| in library configuration files | cstdio (DLIB header file) |
| consistency, module | cstdlib (DLIB header file)307 |
| const | cstring (DLIB header file)307 |
| declaring objects | ctgmath (library header file) |
| non-top level | ctime (DLIB header file) |
| constants, placing in named segment | ctype.h (library header file) |
| constseg (pragma directive) | cwctype.h (library header file) |
| const_cast (cast operator) | ?C_EXIT (assembler label) |
| contents, of this guide | ?C_GETCHAR (assembler label)115 |
| control characters, | C_INCLUDE (environment variable) |
| implementation-defined behavior | ?C_PUTCHAR (assembler label) |
| conventions, used in this guide | C-SPY |
| copyright notice | debug support for C++151 |
| CORE (predefined symbol) | interface to system termination |
| core, identifying | low-level interface (CLIB) |
| cos (library function) | Terminal I/O window, including debug support for .79–80 |
| cplusplus (predefined symbol) | C++ |
| CPU (predefined symbol) | See also Embedded C++ and Extended Embedded C++ |
| cpu (runtime model attribute) | absolute location |
| cpu (compiler option)196 | calling convention |
| cpu_name (runtime model attribute) | dynamic initialization in |
| cpu, specifying on command line | header files |
| cross call (compiler transformation) | language extensions |
| cross_call_passes (compiler option)196 | special function types |
| csetjmp (DLIB header file) | static member variables |
| csignal (DLIB header file) | support for |
| cspy_support (pragma directive)341, 355 | C++ names, in assembler code |
| CSTACK (segment) | C++ objects, placing in memory type |
| example | C++ terminology |
| See also stack | C++-style comments |
| | |

| c89 (compiler option) | delay_cycles (intrinsic function) |
|--|--|
| _ | delete operator (extended EC++)149 |
| D | delete (keyword) |
| | denormalized numbers. See subnormal numbers |
| -D (compiler option) | dependencies (compiler option) |
| data | deque (STL header file) |
| alignment of231 | destructors and interrupts, using |
| different ways of storing37 | DES_decryption (intrinsic function)284 |
| located, declaring extern | DES_encryption (intrinsic function) |
| placing | device (predefined symbol)294 |
| at absolute location | diagnostic messages |
| representation of | classifying as compilation errors |
| storage | classifying as compilation remarks |
| verifying linked result67 | classifying as compiler warnings |
| data block (call frame information) | disabling compiler warnings |
| data bus, enabling external | disabling wrapping of in compiler |
| data memory attributes, using | enabling compiler remarks221 |
| data pointers | listing all used by compiler |
| data segments | suppressing in compiler |
| data types | diagnostics_tables (compiler option) |
| avoiding signed | diagnostics, implementation-defined behavior |
| floating point | diag_default (pragma directive) |
| in C++ | diag_error (compiler option) |
| integer types | diag_error (pragma directive) |
| dataseg (pragma directive) | diag_remark (compiler option)199 |
| data_alignment (pragma directive) | diag_remark (pragma directive) |
| DATE (predefined symbol) | diag_suppress (compiler option) |
| date (library function), configuring support for97 | diag_suppress (pragma directive) |
| debug (compiler option) | diag_warning (compiler option) |
| debug information, including in object file | diag_warning (pragma directive) |
| decimal point, implementation-defined behavior 347 | DIFUNCT (segment) |
| declarations | directives |
| empty | function for static overlay |
| in for loops | pragma34, 265 |
| Kernighan & Ritchie | directory, specifying as parameter |
| of functions | disable_direct_mode (compiler option) |
| declarations and statements, mixing | disable_interrupt (intrinsic function)285 |
| declarators, implementation-defined behavior | discard_unused_publics (compiler option)201 |
| define_type_info (pragma directive) | disclaimer |
| | |

| DLIB. 32, 303 eeprom (extended keyword) 238, 250 configurations .88 EEPROM_I (segment) .320 configuring. .72, 202 EEPROM_N (segment) .321 documentation .20 eeprom_size (compiler option) .204 including debug support. .78 ELPM (instruction) .194 reference information. See the online help system .301 Embedded C++ .143 runtime environment .71 differences from C++ .143 dlib (compiler option) .201 enabling .203 dlib_config (compiler option) .202 function linkage .125 DLib_Defaults.h (library configuration file) .83, 88 language extensions .143 document conventions .21 Embedded C++ Technical Committee .21 documentation embedded systems, IAR special support for .34 overview of guides .19 embedded_cplusplus (predefined symbol) .295 |
|---|
| configurations |
| documentation |
| documentation |
| including debug support |
| reference information. See the online help system301 runtime environment |
| runtime environment |
| dlib (compiler option) |
| dlib_config (compiler option) |
| DLib_Defaults.h (library configuration file) .83, 88 language extensions .143 DLIB_FILE_DESCRIPTOR (configuration symbol) .92 overview .143 document conventions .21 Embedded C++ Technical Committee .21 documentation embedded systems, IAR special support for .34 overview of guides .19 embedded_cplusplus (predefined symbol) .295 |
| DLIB_FILE_DESCRIPTOR (configuration symbol) |
| document conventions. |
| documentation embedded systems, IAR special support for |
| overview of guides |
| |
| documentation, library |
| domain errors, implementation-definedenable_interrupt (intrinsic function) |
| behavior |
| DOUBLE (predefined symbol) |
| double (data type) |
| avoiding |
| configuring size of floating-point type |
| identifying size of (_DOUBLE)294 enums |
| double_size (runtime model attribute) |
| do_cross_call (compiler option) |
| do_not_instantiate (pragma directive)341, 355 environment |
| DW (directive) |
| dynamic initialization |
| in C++ |
| dynamic memory |
| environment variables |
| C_INCLUDE |
| C_INCLUDE |
| -e (compiler option) |
| early_initialization (pragma directive) |
| ec++ (compiler option) |
| EC++ header files |
| edition, of this guide |
| eecr_address (compiler option) |
| errno.h (library header file) |

| error messages | external data bus, enabling |
|---|--|
| classifying for compiler | external memory |
| error return codes | ext_io (extended keyword) |
| error (pragma directive) | _ |
| error_limit (compiler option) | F |
| escape sequences, implementation-defined behavior 335 | - |
| exception handling, missing from Embedded C++ 143 | -f (compiler option) |
| exception vectors | far (extended keyword)252 |
| _Exit (library function) | FARCODE (segment)321 |
| exit (library function) | farflash (extended keyword) |
| implementation-defined behavior | farfunc (extended keyword) |
| _exit (library function) | farfunc (function pointer) |
| exit (library function) | FAR_C (segment) |
| export keyword, missing from Extended EC++ 151 | FAR_F (segment) |
| extended command line file | FAR_HEAP (segment) |
| for compiler | FAR_I (segment) |
| passing options | FAR_ID (segment) |
| Extended Embedded C++144 | FAR_N (segment) |
| enabling | FAR_Z (segment) |
| standard template library (STL)305 | fatal error messages |
| extended keywords | fdopen, in stdio.h |
| enabling (-e) | fegettrapdisable307 |
| overview | fegettrapenable |
| summary | FENV_ACCESS, implementation-defined behavior338 |
| syntax41 | fenv.h (library header file) |
| object attributes249 | additional C functionality |
| type attributes on data objects | fgetpos (library function), implementation-defined |
| type attributes on data pointers | behavior |
| type attributes on function pointers | field width, library support for |
| type attributes on functions | FILE (predefined symbol)295 |
| eeprom238 | file buffering, implementation-defined behavior343 |
| farflash238 | file dependencies, tracking |
| flash | file paths, specifying for #include files |
| | file position, implementation-defined behavior343 |
| hugeflash | file systems |
| root | file (zero-length), implementation-defined behavior343 |
| tinyflash238 | filename |
| extended_load_program_memory (intrinsic function) . 286 | extension for linker command file |
| extern "C" linkage | of object file |
| Ontolii C minugo140 | 01 00ject mc210 |

| search procedure for182 | FP_CONTRACT, implementation-defined behavior 338 |
|--|--|
| specifying as parameter | fractional_multiply_signed (intrinsic function)286 |
| filenames (legal), implementation-defined behavior 343 | fractional_multiply_signed_with_unsigned (intrinsic |
| fileno, in stdio.h | function) |
| files, implementation-defined behavior | fractional_multiply_unsigned (intrinsic function)286 |
| handling of temporary | fragmentation, of heap memory |
| multibyte characters in | free (library function). See also heap |
| opening | fsetpos (library function), implementation-defined |
| _flash (extended keyword) | behavior |
| flash memory | fstream (library header file) |
| library routines for accessing | ftell (library function), implementation-defined |
| placing aggregate initializers | behavior |
| float (data type) | Full DLIB (library configuration) |
| floating-point constants | func (predefined symbol) |
| hexadecimal notation | FUNCALL (assembler directive) |
| hints | FUNCTION (predefined symbol) |
| floating-point environment, accessing or not280 | function calls |
| floating-point expressions, contracting or not | calling convention |
| floating-point format | stack image after |
| hints | function declarations, Kernighan & Ritchie174 |
| implementation-defined behavior | function directives for static overlay |
| special cases | function inlining (compiler transformation) 170 |
| 32-bits | disabling (no_inline) |
| 64-bits | function pointers |
| floating-point numbers, support for in printf formatters 112 | function prototypes |
| floating-point status flags | enforcing |
| floating-point type, configuring size of double | function return addresses |
| float.h (library header file) | function storage |
| FLT_EVAL_METHOD, implementation-defined | function template parameter deduction (extended EC++). 152 |
| behavior | function type information, omitting in object output 218 |
| FLT_ROUNDS, implementation-defined | FUNCTION (assembler directive) |
| behavior | function (pragma directive) |
| fmod (library function), | functional (STL header file) |
| implementation-defined behavior | functions |
| for loops, declarations in | C++ and special function types |
| force_switch_type (compiler option) | declaring |
| formats | inlining |
| floating-point values | interrupt |
| standard IEEE (floating point) | intrinsic |
| formatted write (library function) | monitor |

| omitting type info | HAS_RAMPX (predefined symbol) |
|--|---|
| parameters | HAS_RAMPY (predefined symbol) |
| placing in memory | HAS_RAMPZ (predefined symbol) |
| recursive | hdrstop (pragma directive) |
| avoiding | header files |
| storing data on stack | C |
| reentrancy (DLIB) | C++ |
| related extensions | EC++305 |
| return values from | library |
| special function types48 | special function registers |
| verifying linked result | STL |
| | dlavr <i>libname</i> .h83 |
| C | DLib_Defaults.h |
| G | including stdbool.h for bool232 |
| generic (extended keyword) | including stddef.h for wchar_t |
| generic pointers, avoiding | header names, implementation-defined behavior 340 |
| getchar (library function) | header_context (compiler option)207 |
| getenv (library function), configuring support for95 | heap |
| getw, in stdio.h | DLIB support for multiple |
| getzone (library function), configuring support for | dynamic memory |
| getzone.c97 | segments for64 |
| get_interrupt_state (intrinsic function) | storing data |
| global variables, initialization | heap segments |
| guard_calls (compiler option) | CLIB |
| guidelines, reading | DLIB |
| 6 | FAR_F (segment)322 |
| LI | FAR_HEAP (segment)322 |
| H | HEAP (segment) |
| Harbison, Samuel P | HUGE_F (segment) |
| hardware support in compiler | HUGE_HEAP (segment) |
| hash_map (STL header file) | NEAR_F (segment) |
| hash_set (STL header file) | NEAR_HEAP (segment) |
| HAS_EEPROM (predefined symbol) | placing |
| HAS_EIND (predefined symbol) | TINY_F (segment) |
| HAS_ELPM (predefined symbol) | TINY_HEAP (segment)330 |
| HAS_ENHANCED_CORE (predefined symbol) 295 | heap size |
| HAS_FISCR (predefined symbol) | and standard I/O65 |
| HAS_MUL (predefined symbol) | changing default64 |
| HAS_RAMPD (predefined symbol) | HEAP (segment) |
| | |

| heap (zero-sized), implementation-defined behavior 345 hints | implementation-defined behavior |
|--|---|
| for good code generation | important_typedef (pragma directive)341, 355 |
| implementation-defined behavior | include files |
| using efficient data types | including before source files |
| huge (extended keyword) | specifying |
| hugeflash (extended keyword) | include_alias (pragma directive) |
| HUGE_C (segment) | indirect_jump_to (intrinsic function) |
| HUGE_F (segment) | infinity |
| HUGE_HEAP (segment) | infinity (style for printing), implementation-defined |
| HUGE_I (segment) | behavior |
| | inheritance, in Embedded C++ |
| HUGE_ID (segment) | initialization |
| HUGE_N (segment) | dynamic |
| HUGE_Z (segment) | single-value |
| _ | initialized data segments |
| | initializers_in_flash (compiler option) |
| - | initializers, static |
| -I (compiler option) | |
| IAR Command Line Build Utility83 | INITTAB (segment) |
| IAR Postlink (utility) | inline assembler |
| IAR Systems Technical Support | avoiding |
| iarbuild.exe (utility)83 | See also assembler language interface |
| iar_cos_accuratef (library function) | inline functions |
| iar_cos_accuratel (library function) | in compiler |
| iar_pow_accuratef (library function) | inline (pragma directive) |
| iar_pow_accuratel (library function)302 | inlining functions, implementation-defined behavior 339 |
| iar_sin_accuratef (library function)302 | insert_opcode (intrinsic function) |
| iar_sin_accuratel (library function)302 | installation directory |
| IAR_SYSTEMS_ICC (predefined symbol) 296 | instantiate (pragma directive) |
| iar_tan_accuratef (library function) | int (data type) signed and unsigned232 |
| iar_tan_accuratel (library function) | integer types |
| ICCAVR (predefined symbol)296 | casting |
| iccbutl.h (library header file)310 | implementation-defined behavior |
| icons, in this guide | intptr_t239 |
| IDE | ptrdiff_t |
| building a library from | size_t |
| building applications from, an overview28 | uintptr_t |
| identifiers, implementation-defined behavior 335, 350 | integers, implementation-defined behavior |
| IEEE format, floating-point values | integral promotion |
| | 1 |

| interrupt (extended keyword) |
|---|
| using in pragma directives |
| interrupt functions |
| placement in memory66 |
| interrupt state, restoring |
| interrupt vector |
| specifying with pragma directive |
| interrupt vector table |
| in linker command file |
| INITTAB segment |
| INTVEC segment |
| start address for |
| interrupts |
| disabling257 |
| during function execution |
| processor state |
| using with EC++ destructors |
| intptr_t (integer type) |
| intrinsic (extended keyword)257 |
| intrinsic functions |
| overview117 |
| summary |
| intrinsics.h (header file) |
| inttypes.h (library header file)304 |
| INTVEC (segment) |
| intwri.c (library source code) |
| invocation syntax |
| io (extended keyword) |
| iomanip (library header file) |
| ios (library header file) |
| iosfwd (library header file) |
| iostream (library header file)305 |
| iso646.h (library header file) |
| istream (library header file) |
| italic style, in this guide |
| iterator (STL header file) |
| I/O module, overriding in runtime library |
| I/O, character-based |
| |

| J |
|---|
| Josuttis, Nicolai M |
| K |
| N |
| keep_definition (pragma directive) |
| Kernighan & Ritchie function declarations |
| Kernighan, Brian W |
| keywords |
| extended, overview of |
| Catchided, Overview of |
| 1 |
| L |
| -l (compiler option) |
| for creating skeleton code |
| labels141 |
| assembler, making public220 |
| program_start85 |
| Labrosse, Jean J |
| lac (intrinsic function) |
| Lajoie, Josée |
| language extensions |
| Embedded C++ |
| enabling |
| enabling (-e) |
| language overview27 |
| language (pragma directive) |
| las (intrinsic function) |
| lat (intrinsic function) |
| libraries |
| definition of |
| standard template library |
| using a prebuilt73 |
| using a prebuilt (CLIB) |
| library configuration files |
| dlavr <i>libname</i> .h83 |
| DLIB |

| DLib_Defaults.h | library_default_requirements (pragma directive) 355 |
|---|---|
| modifying | library_module (compiler option) |
| specifying | library_provides (pragma directive) |
| library documentation | library_requirement_override (pragma directive) 355 |
| library features, missing from Embedded C++ 144 | lightbulb icon, in this guide22 |
| library functions | limits.h (library header file) |
| for accessing flash | LINE (predefined symbol) |
| summary, CLIB | linkage, C and C++ |
| summary, DLIB | linker command file |
| memcmp_G | customizing |
| memcpy_G311 | using the -P command |
| memcpy_P311 | using the -Z command |
| printf_P | linker map file67 |
| puts_G312 | linker output files |
| puts_P | linker segment. See segment |
| scanf_P | linking |
| sprintf_P | from the command line |
| sscanf_P313 | required input |
| strcat_G313 | Lippman, Stanley B |
| strcmp_G313 | list (STL header file) |
| strcmp_P | listing, generating |
| strcpy_G313 | literals, compound |
| strcpy_P313 | literature, recommended |
| strerror_P | LITTLE_ENDIAN (predefined symbol)296 |
| strlen_G | load_program_memory (intrinsic function) 288 |
| strlen_P | local variables, See auto variables |
| strncat_G | locale |
| strncmp_G | adding support for in library95 |
| strncmp_P | changing at runtime |
| strncpy_G315 | implementation-defined behavior |
| strncpy_P315 | removing support for |
| library header files | support for |
| library modules | locale.h (library header file) |
| creating | located data segments |
| overriding81 | located data, declaring extern |
| library object files | location (pragma directive) |
| library options, setting | LOCFRAME (assembler directive) |
| library project template | lock_regs (compiler option) |
| using 83 | long double (data type) 235 |

| long float (data type), synonym for double | memcpy_G (library function) |
|--|--|
| long long (data type) avoiding | memory |
| restrictions | accessing |
| longjmp, restrictions for using | allocating in C++ |
| loop-invariant expressions | dynamic |
| _low_level_init | external |
| iow_iever_init | flash |
| • | |
| low_level_init.c | heap |
| low-level processor operations | non-initialized |
| accessing | RAM, saving |
| lseek (library function) | releasing in C++ |
| 5.4 | stack |
| M | saving |
| • • | used by global or static variables |
| -m (compiler option) | memory attributes, summary40 |
| macros | memory consumption, reducing |
| embedded in #pragma optimize | memory layout, AVR |
| ERANGE (in errno.h) | memory management, type-safe |
| inclusion of assert | memory map |
| NULL, implementation-defined behavior 343, 356 | customizing the linker configuration file for 54 |
| substituted in #pragma directives | memory models |
| variadic | configuration |
| macro_positions_in_diagnostics (compiler option) 211 | identifying (MEMORY_MODEL) |
| main (function), definition | specifying on command line (memory_model) 211 |
| main (function), implementation-defined behavior334 | memory placement |
| malloc (library function) | using pragma directive |
| See also heap | using type definitions41, 247 |
| implementation-defined behavior | memory segment. See segment |
| Mann, Bernhard | memory types |
| map (STL header file) | C++43 |
| map, linker | hints162 |
| math functions rounding mode, | placing variables in |
| implementation-defined behavior | pointers |
| math.h (library header file) | specifying |
| MB_LEN_MAX, implementation-defined behavior 346 | structures |
| _medium_write (library function) | memory (pragma directive) |
| member functions, pointers to | memory (STL header file) |
| memcmp_G (library function) | MEMORY_MODEL (predefined symbol) 297 |
| r = 2 () | |

| memory_model (runtime model attribute) 106 |
|---|
| memory_model (compiler option) |
| memory_of, operator |
| message (pragma directive)274 |
| messages |
| disabling |
| forcing |
| Meyers, Scott |
| mfc (compiler option) |
| migration, from earlier IAR compilers |
| MISRA C |
| documentation |
| misrac (compiler option) |
| misrac_verbose (compiler option) |
| misrac1998 (compiler option) |
| misrac2004 (compiler option) |
| mode changing, implementation-defined behavior 344 |
| module consistency |
| rtmodel278 |
| module map, in linker map file |
| module name, specifying (module_name) |
| module summary, in linker map file 67 |
| module_name (compiler option) |
| module_name (pragma directive) |
| monitor (extended keyword) |
| monitor functions |
| multibyte character support |
| multibyte characters, implementation-defined |
| behavior |
| multiple address spaces, output for |
| multiple inheritance |
| in Extended EC++ |
| missing from Embedded C++ |
| missing from STL |
| multiple output files, from XLINK |
| multiply_signed (intrinsic function) |
| multiply_signed_with_unsigned (intrinsic function)288 |
| multiply_unsigned (intrinsic function) |
| multi-file compilation |
| mutable attribute in Extended EC 144 155 |

N

| no_inline (compiler option) | for cast, in Extended EC++ | 4 |
|--|---|----|
| no_operation (intrinsic function)289 | for cast, missing from Embedded C++14 | 4 |
| no_path_in_file_macros (compiler option) | for segment control | 9 |
| no_pch (pragma directive) | in inline assembler | 6 |
| no_rampd (runtime model attribute) | new and delete | .9 |
| no_rampd (compiler option)214 | precision for 32-bit float | 6 |
| no_runtime_init (extended keyword) | precision for 64-bit float | 6 |
| no_static_destruction (compiler option) | sizeof, implementation-defined behavior | 6 |
| no_system_include (compiler option) | variants for cast | 4 |
| no_tbaa (compiler option) | _Pragma (preprocessor) | 5 |
| no_typedefs_in_diagnostics (compiler option)216 | ALIGNOF, for alignment control | 8 |
| no_ubrof_messages (compiler option) | memory_of | .7 |
| no_warnings (compiler option) | ?, language extensions for | |
| no_wrap_diagnostics (compiler option) | @4 | |
| NULL | optimization | |
| implementation-defined behavior | clustering, disabling21 | 2 |
| in library header file (CLIB) | code motion, disabling21 | |
| pointer constant, relaxation to Standard C 140 | common sub-expression elimination, disabling 21 | 3 |
| NULL (macro), implementation-defined behavior 356, 359 | configuration | |
| numeric conversion functions, | disabling | |
| implementation-defined behavior | function inlining, disabling (no_inline) | 4 |
| numeric (STL header file)305 | hints17 | 2 |
| | size, specifying | 9 |
| 0 | specifying (-O) | 7 |
| O | speed, specifying | 2 |
| -O (compiler option) | techniques | 0 |
| -o (compiler option) | type-based alias analysis, disabling (tbaa)21 | 5 |
| object attributes | using inline assembler code | 9 |
| object filename, specifying (-o) | using pragma directive27 | 5 |
| object module name, specifying (module_name) 212 | optimization levels | 9 |
| object_attribute (pragma directive) | optimize (pragma directive) | 5 |
| offsetof | option parameters | |
| old calling convention | options, compiler. See compiler options | |
| omit_types (compiler option) | Oram, Andy | 0 |
| once (pragma directive) | ostream (library header file) | 15 |
| only_stdout (compiler option) | output | |
| _open (library function) | from preprocessor | 9 |
| operators | multiple files from linker | |
| See also @ (operator) | specifying for linker2 | |
| · • | | |

| supporting non-standard | powXp (library function) |
|---|--|
| | basic_template_matching, using |
| P | for absolute located data |
| | list of all recognized |
| pack (pragma directive) | pack |
| parameters | type_attribute, using41 |
| function | _Pragma (preprocessor operator) |
| hidden | precision arguments, library support for |
| non-scalar, avoiding | predefined symbols |
| register127 | overview |
| rules for specifying a file or directory | summary |
| specifying | predef_macro (compiler option)219 |
| stack | preinclude (compiler option) |
| typographic convention | preprocess (compiler option) |
| part number, of this guide | preprocessor |
| permanent registers | operator (_Pragma) |
| perror (library function), | output219 |
| implementation-defined behavior | overview of |
| placement | preprocessor directives |
| code and data | comments at the end of |
| in named segments | implementation-defined behavior340, 354 |
| plain char, implementation-defined behavior | #pragma |
| pointer types | preprocessor extensions |
| differences between | VA_ARGS135 |
| mixing | #warning message |
| using the best | preprocessor symbols |
| pointers | defining |
| casting | preserved registers |
| data | PRETTY_FUNCTION (predefined symbol) 297 |
| function | primitives, for special functions |
| implementation-defined behavior | print formatter, selecting |
| polymorphism, in Embedded C++ | printf (library function) |
| porting, code containing pragma directives266 | choosing formatter |
| Postlink (utility) | configuration symbols |
| postlink.htm | customizing |
| pow (library function) | implementation-defined behavior |
| alternative implementation of 302 | selecting |

| printf_args (pragma directive)277 | RAM |
|--|---|
| printf_P (library function)312 | non-zero initialized variables |
| printing characters, implementation-defined behavior347 | saving memory |
| processor configuration | RAMPZ (register) |
| processor operations | range errors, in linker |
| accessing | raw (extended keyword) |
| low-level | read (library function)93 |
| program entry label85 | customizing |
| program termination, implementation-defined behavior 334 | read formatter, selecting |
| programming hints | reading guidelines |
| program_start (label) | reading, recommended |
| projects | realloc (library function)45 |
| basic settings for | implementation-defined behavior |
| setting up for a library | See also heap |
| prototypes, enforcing | recursive functions |
| ptrdiff_t (integer type) | avoiding |
| PUBLIC (assembler directive) | storing data on stack |
| publication date, of this guide | reentrancy (DLIB) |
| public_equ (compiler option)220 | reference information, typographic convention22 |
| public_equ (pragma directive)341, 356 | register keyword, implementation-defined behavior 338 |
| putchar (library function) | register parameters |
| putenv (library function), absent from DLIB95 | registered trademarks |
| puts_G (library function) | registers |
| puts_P (library function) | callee-save, stored on stack |
| putw, in stdio.h | for function returns |
| | implementation-defined behavior |
| \mathbf{O} | in assembler-level routines |
| • | preserved |
| QCCAVR (environment variable) | scratch |
| qualifiers | regvar (extended keyword) |
| const and volatile | reinterpret_cast (cast operator) |
| implementation-defined behavior | relaxed_fp (compiler option) |
| queue (STL header file) | remark (diagnostic message) |
| _ | classifying for compiler |
| R | enabling in compiler |
| | remarks (compiler option) |
| -r (compiler option) | remove (library function) |
| raise (library function), configuring support for 96 | implementation-defined behavior 344, 357, 360 |
| raise.c | remquo, magnitude of |

| rename (library function) | filename syntax | |
|--|---|------|
| implementation-defined behavior 344, 357, 360 | overriding modules in | |
| ReportAssert (library function)98 | setting up from command line | |
| require (intrinsic function) | setting up from IDE | |
| required (pragma directive)277 | using a prebuilt | . 73 |
| require_prototypes (compiler option)221 | runtime model attributes | 103 |
| restore_interrupt (intrinsic function) | runtime model definitions2 | 278 |
| return address stack, changing default size of | runtime type information, missing from Embedded C++ . 1 | 143 |
| return addresses | | |
| return data stack | S | |
| reducing usage of | 3 | |
| using cross-call optimizations | -s (compiler option) | 222 |
| return values, from functions | save_interrupt (intrinsic function) | |
| Ritchie, Dennis M | scanf (library function) | |
| _root (extended keyword) | choosing formatter (DLIB) | |
| root_variables (compiler option) | configuration symbols | |
| routines, time-critical | implementation-defined behavior | |
| RSTACK (segment) | scanf_args (pragma directive) | |
| example | scanf_P (library function) | |
| See also stack | scratch registers | |
| rtmodel (assembler directive) | | |
| rtmodel (pragma directive) | section (pragma directive) | |
| rtti support, missing from STL | segment group name | |
| rt_version (runtime model attribute) | segment map, in linker map file | |
| runtime environment | segment memory types, in XLINK | |
| CLIB | segment (pragma directive) | |
| DLIB | segments3 | |
| setting options for | code | |
| setting options for | data | |
| runtime libraries (CLIB) | definition of | |
| introduction | initialized data | |
| | introduction | |
| filename syntax | located data | |
| setting up from command line | naming | |
| setting up from IDE | packing in memory | |
| using a prebuilt | placing in sequence | |
| runtime libraries (DLIB) | static memory | |
| introduction | summary | |
| customizing system startup code | too long for address range | |
| customizing without rebuilding75 | too long, in linker | . 67 |
| | | |

| declaring (#pragma segment)279 | signed long (data type) |
|---|--|
| HEAP64 | signed short (data type)232 |
| INITTAB | signed values, avoiding |
| RSTACK | silent (compiler option) |
| reducing usage of | silent operation, specifying in compiler |
| using cross-call optimizations | sin (library function) |
| specifying (segment)222 | 64-bits (floating-point format) |
| SWITCH | size optimization, specifying229 |
| _segment_begin (extended operator) | size_t (integer type) |
| segment_end (extended operator) | skeleton code, creating for assembler language interface . 120 |
| segment_size (extended operator)139 | skeleton.s90 (assembler source output) |
| SEI (assembler instruction) | SLEEP (assembler instruction) |
| emaphores | slist (STL header file) |
| C example | _small_write (library function) |
| operations on | software_interrupt (intrinsic function) |
| -separate_cluster_for_initialized_variables (compiler | source files, list all referred |
| option) | space characters, implementation-defined behavior 343 |
| tet (STL header file) | special function registers (SFR) |
| etjmp.h (library header file) | special function types |
| petlocale (library function) | overview |
| settings, basic for project configuration | speed optimization, specifying |
| _set_interrupt_state (intrinsic function) | spmcr_address (compiler option) |
| severity level, of diagnostic messages | sprintf (library function) |
| specifying | choosing formatter |
| SFR | customizing |
| accessing special function registers | sprintf_P (library function) |
| declaring extern special function registers | sscanf (library function) |
| shared object | choosing formatter (DLIB) |
| short (data type) | sscanf_P (library function) |
| ignal (library function) | sstream (library header file) |
| configuring support for96 | stack |
| implementation-defined behavior | advantages and problems using |
| ignals, implementation-defined behavior334 | changing default size of |
| at system startup | cleaning after function return |
| ignal.c96 | contents of |
| ignal.h (library header file) | |
| eigned char (data type) | layout |
| specifying | saving space |
| signed int (data type) | size |
| gigned long long (data type) | stack parameters |
| | |

| stack pointer | stdin |
|--|---|
| stack pointer register, considerations | implementation-defined behavior357, 360 |
| stack segment | stdint.h (library header file)304, 306 |
| CSTACK | stdio.h (library header file) |
| placing in memory | stdio.h, additional C functionality307 |
| RSTACK329 | stdlib.h (library header file) |
| stack (STL header file) | stdout |
| Standard C | implementation-defined behavior |
| library compliance with | Steele, Guy L |
| specifying strict usage | STL153 |
| standard error, redirecting in compiler | strcasecmp, in string.h |
| standard input | strcat_G (library function) |
| standard output | strcmp_G (library function) |
| specifying in compiler | strcmp_P (library function)313 |
| standard template library (STL) | strcpy_G (library function) |
| in Extended EC++ | strcpy_P (library function) |
| missing from Embedded C++ | strdup, in string.h |
| startup system. See system startup | streambuf (library header file) |
| statements, implementation-defined behavior354 | streams |
| static clustering (compiler transformation) | implementation-defined behavior |
| static data, in linker command file | supported in Embedded C++ |
| static memory segments | strerror (library function) |
| static overlay | implementation-defined behavior |
| static variables | strerror (library function), implementation-defined |
| initialization59 | behavior |
| taking the address of | strerror_P (library function) |
| static_assert() | strict (compiler option)224 |
| static_cast (cast operator) | string (library header file)305 |
| status flags for floating-point | strings, supported in Embedded C++ |
| std namespace, missing from EC++ | string_literals_in_flash (compiler option) |
| and Extended EC++ | string.h (library header file) |
| stdarg.h (library header file) | string.h, additional C functionality |
| stdbool.h (library header file) | strlen_G (library function) |
| STDC (predefined symbol) | strlen_P (library function)314 |
| STDC CX_LIMITED_RANGE (pragma directive) 280 | strncasecmp, in string.h |
| STDC FENV_ACCESS (pragma directive) | strncat_G (library function) |
| STDC FP_CONTRACT (pragma directive) | strncmp_G (library function) |
| STDC_VERSION (predefined symbol) | strncmp_P (library function)314 |
| stddef.h (library header file) | strncpy_G (library function) |
| stderr93, 218 | strncpy_P (library function) |

| strnlen, in string.h | system (library function system_include (pragr |
|---|--|
| strstream (library header file) | system_include_dir |
| strtod (library function), configuring support for 97 | ., |
| structure types | — |
| alignment | |
| layout of | tan (library function). |
| structures | • |
| aligning | task (extended keyv technical support, IAF |
| anonymous | • • |
| implementation-defined behavior | template support |
| placing in memory type | in Extended EC++ |
| | missing from Embe |
| subnormal numbers | Terminal I/O window |
| SUBVERSION (predefined symbol) | making available (|
| support, technical | making available (l |
| Sutter, Herb21 | not supported when |
| swap_nibbles (intrinsic function) | terminal I/O, debugge |
| SWITCH (segment) | terminal output, speed |
| symbols | termination of system. |
| anonymous, creating | termination status, imp |
| including in output277 | terminology |
| listing in linker map file | tgmath.h (library head |
| overview of predefined | 32-bits (floating-point |
| preprocessor, defining | this (pointer) |
| syntax | class memory |
| command line options | referring to a class |
| extended keywords | TID (predefined |
| invoking compiler | TIME (predefine |
| system function, implementation-defined behavior 335, 345 | time zone (library fun |
| system startup | implementation-define |
| CLIB | time zone (library fun |
| customizing | behavior |
| DLIB | time-critical routines. |
| system termination | time.c |
| CLIB | time.h (library header |
| C-SPY interface to | additional C function |
| DLIB | time32 (library function |
| system (library function) | time64 (library function |
| implementation-defined behavior | tiny (extended keyw |
| implementation defined behavior | minj (catchaca key w |

| system (library function), configuring support for |
|---|
| Т |
| tan (library function) |
| task (extended keyword)261 |
| technical support, IAR Systems |
| template support |
| in Extended EC++ |
| missing from Embedded C++ |
| Terminal I/O window |
| making available (CLIB) |
| making available (DLIB) |
| not supported when |
| terminal I/O, debugger runtime interface for79 |
| terminal output, speeding up |
| termination of system. See system termination |
| termination status, implementation-defined behavior 345 |
| terminology21 |
| tgmath.h (library header file) |
| 32-bits (floating-point format) |
| this (pointer) |
| class memory |
| referring to a class object |
| TID (predefined symbol) |
| TIME (predefined symbol) |
| time zone (library function) |
| implementation-defined behavior |
| time zone (library function), implementation-defined |
| behavior |
| time-critical routines |
| time.c |
| time.h (library header file) |
| additional C functionality |
| time32 (library function), configuring support for97 |
| time64 (library function), configuring support for |
| tiny (extended keyword) |

| tinyflash (extended keyword) | underflow range errors, |
|--|---|
| TINY_AVR (predefined symbol) | implementation-defined behavior |
| TINY_F (segment) | ungetchar, in stdio.h |
| TINY_HEAP (segment) | unions |
| TINY_I (segment) | anonymous |
| TINY_ID (segment) | implementation-defined behavior |
| TINY_N (segment) | universal character names, implementation-defined |
| TINY_Z (segment) | behavior |
| tips, programming | unsigned char (data type) |
| tools icon, in this guide | changing to signed char |
| trademarks | unsigned int (data type) |
| transformations, compiler | unsigned long long (data type) |
| translation, implementation-defined behavior333, 349 | unsigned long (data type) |
| trap vectors, specifying with pragma directive | unsigned short (data type) |
| | use_c++_inline (compiler option) |
| type attributes | utility (STL header file) |
| specifying | dunity (812 header me) |
| type definitions, used for specifying memory storage . 41, 247 | \/ |
| type information, omitting | V |
| type qualifiers | ('1 ') |
| const and volatile | -v (compiler option) |
| implementation-defined behavior | variable type information, omitting in object output218 |
| typedefs | variables |
| excluding from diagnostics | auto |
| repeated | defined inside a function |
| type_attribute (pragma directive) | global |
| type-based alias analysis (compiler transformation) 171 | initialization of |
| disabling | placement in memory |
| type-safe memory management | hints for choosing |
| typographic conventions | local. See auto variables |
| | non-initialized |
| U | omitting type info |
| • | placing at absolute addresses |
| UBROF | placing in named segments |
| format of linkable object files | static |
| specifying, example of | placement in memory |
| uchar.h (library header file) | taking the address of |
| uintptr_t (integer type) | static and global, initializing59 |
| underflow errors, implementation-defined behavior 342 | variadic macros |
| - | vector (pragma directive) |

| vector (STL header file) | write_buffered (DLIB library function) |
|---|--|
| version compiler subversion number | X |
| IAR Embedded Workbench .2 of compiler .298 _version_1 (extended keyword) .263 _VERSION_1_CALLS (predefined symbol) .298 | xch (intrinsic function) |
| version1_calls (compiler option) | XLINK options -O |
| void, pointers to.140volatile.242and const, declaring objects.240declaring objects.240protecting simultaneously accesses variables.175rules for access.241 | -y 68 XLINK segment memory types 54 _XMEGA_CORE (predefined symbol) 298 xreportassert.c 98 |
| W | -y (compiler option) |
| #warning message (preprocessor extension) 299 warnings | z (compiler option) |
| warnings (pragma directive) | _Exit (library function) |
| wchar_t (data type), adding support for in C233wchar.h (library header file).304, 307wctype.h (library header file).304web sites, recommended.21white-space characters, implementation-defined behavior 333_write (library function).93customizing.89write formatter, selecting.112-113_write_array, in stdio.h.308 | in DLIB |

| BUILD_NUMBER (predefined symbol)294 | get_interrupt_state (intrinsic function) |
|--|--|
| close (library function) | has_constructor, symbol used in library |
| constrange(), symbol used in library | has_destructor, symbol used in library309 |
| construction_by_bitwise_copy_allowed, symbol used in li- | HAS_EEPROM (predefined symbol) |
| brary | HAS_EIND (predefined symbol) |
| CORE (predefined symbol) | HAS_ELPM (predefined symbol) |
| cplusplus (predefined symbol) | HAS_ENHANCED_CORE (predefined symbol) 295 |
| cpu (runtime model attribute) | HAS_FISCR (predefined symbol) |
| cpu_name (runtime model attribute) | HAS_MUL (predefined symbol) |
| CPU (predefined symbol) | HAS_RAMPD (predefined symbol) |
| DATE (predefined symbol) | HAS_RAMPX (predefined symbol) |
| delay_cycles (intrinsic function)284 | HAS_RAMPY (predefined symbol) |
| DES_decryption (intrinsic function) | HAS_RAMPZ (predefined symbol) |
| DES_encryption (intrinsic function) | huge (extended keyword) |
| device (predefined symbol)294 | hugeflash (extended keyword) |
| disable_interrupt (intrinsic function)285 | huge_size_t |
| DLIB_FILE_DESCRIPTOR (configuration symbol) 92 | IAR_SYSTEMS_ICC (predefined symbol) 296 |
| double_size (runtime model attribute) | ICCAVR (predefined symbol)296 |
| DOUBLE (predefined symbol) | indirect_jump_to (intrinsic function) |
| eeprom (extended keyword) | insert_opcode (intrinsic function) |
| embedded_cplusplus (predefined symbol) 295 | interrupt (extended keyword) |
| enable_interrupt (intrinsic function) | using in pragma directives |
| enhanced_core (runtime model attribute) 106 | intrinsic (extended keyword) |
| exit (library function) | io (extended keyword) |
| extended_load_program_memory (intrinsic function) . 286 | lac (intrinsic function) |
| ext_io (extended keyword) | las (intrinsic function) |
| far (extended keyword) | lat (intrinsic function) |
| farflash (extended keyword) | LINE (predefined symbol) |
| farfunc (extended keyword) | LITTLE_ENDIAN (predefined symbol)296 |
| farfunc (function pointer) | load_program_memory (intrinsic function) 288 |
| FILE (predefined symbol)295 | low_level_init |
| flash (extended keyword) | low_level_init, customizing |
| fractional_multiply_signed (intrinsic function)286 | lseek (library function) |
| fractional_multiply_signed_with_unsigned (intrinsic | memory_model (runtime model attribute) 106 |
| function) | MEMORY_MODEL (predefined symbol) 297 |
| fractional_multiply_unsigned (intrinsic function)286 | memory_of, operator |
| FUNCTION (predefined symbol) | memory_of, symbol used in library |
| func (predefined symbol) | monitor (extended keyword) |
| generic (extended keyword) | multiply_signed (intrinsic function) |
| gets, in stdio.h | |

| multiply_signed_with_unsigned (intrinsic function)288 | tiny (extended keyword) |
|---|--|
| multiply_unsigned (intrinsic function) | tinyflash (extended keyword) |
| near (extended keyword) | TINY_AVR (predefined symbol) |
| nearfunc (extended keyword) | ungetchar, in stdio.h |
| nearfunc (function pointer) | VA_ARGS (preprocessor extension) |
| nested (extended keyword) | version_1 (extended keyword) |
| noreturn (extended keyword) | VERSION_1_CALLS (predefined symbol) 298 |
| no_init (extended keyword) | VER (predefined symbol) |
| no_operation (intrinsic function) | watchdog_reset (intrinsic function) |
| no_rampd (runtime model attribute) | write (library function) |
| no_runtime_init (extended keyword) | customizing |
| open (library function) | write_array, in stdio.h |
| PRETTY_FUNCTION (predefined symbol) 297 | write_buffered (DLIB library function) |
| printf_args (pragma directive)277 | _xch (intrinsic function) |
| program_start (label) | XMEGA_CORE (predefined symbol) 298 |
| raw (extended keyword) | 64bit_doubles (runtime model attribute)105 |
| read (library function)93 | -D (compiler option)197 |
| customizing | -e (compiler option) |
| regvar (extended keyword) | -f (compiler option) |
| ReportAssert (library function)98 | -I (compiler option) |
| require (intrinsic function) | -l (compiler option)209 |
| require, adding | for creating skeleton code |
| restore_interrupt (intrinsic function) | -m (compiler option)211 |
| root (extended keyword) | -O (compiler option)217 |
| rt_version (runtime model attribute) | -o (compiler option) |
| save_interrupt (intrinsic function)290 | -O (XLINK option) |
| scanf_args (pragma directive) | -r (compiler option) |
| segment_begin (extended operator | -s (compiler option) |
| segment_end (extended operators) | -v (compiler option) |
| segment_size (extended operators) | -y (compiler option) |
| set_interrupt_state (intrinsic function) | -y (XLINK option) |
| software_interrupt (intrinsic function) | -z (compiler option) |
| STDC_VERSION (predefined symbol) | char_is_signed (compiler option)195 |
| STDC (predefined symbol) | char_is_unsigned (compiler option)195 |
| SUBVERSION (predefined symbol) | clib (compiler option) |
| swap_nibbles (intrinsic function) | cpu (compiler option)196 |
| _task (extended keyword) | cross_call_passes (compiler option)196 |
| TID (predefined symbol) | c89 (compiler option) |
| TIME (predefined symbol) | debug (compiler option) |

| dependencies (compiler option) | no_rampd (compiler option) | . 214 |
|--|--|--------|
| diagnostics_tables (compiler option) | no_static_destruction (compiler option) | . 215 |
| diag_error (compiler option) | no_system_include (compiler option) | . 215 |
| diag_remark (compiler option)199 | no_typedefs_in_diagnostics (compiler option) | . 216 |
| diag_suppress (compiler option) | no_ubrof_messages (compiler option) | . 216 |
| diag_warning (compiler option)200 | no_warnings (compiler option) | . 217 |
| disable_direct_mode (compiler option) | no_wrap_diagnostics (compiler option) | . 217 |
| discard_unused_publics (compiler option)201 | omit_types (compiler option) | . 218 |
| dlib (compiler option) | only_stdout (compiler option) | . 218 |
| dlib_config (compiler option) | output (compiler option) | . 218 |
| do_cross_call (compiler option)202 | predef_macro (compiler option) | . 219 |
| ec++ (compiler option) | preinclude (compiler option) | |
| eecr_address (compiler option) | preprocess (compiler option) | |
| eec++ (compiler option) | relaxed_fp (compiler option) | |
| eeprom_size (compiler option)204 | remarks (compiler option) | . 221 |
| enable_external_bus (compiler option) | require_prototypes (compiler option) | . 221 |
| enable_multibytes (compiler option) | root_variables (compiler option) | |
| enhanced_core (compiler option) | segment (compiler option) | . 222 |
| error_limit (compiler option) | separate_cluster_for_initialized_variables (compiler | |
| force_switch_type (compiler option) | option) | . 223 |
| guard_calls (compiler option) | silent (compiler option) | . 223 |
| header_context (compiler option)207 | spmcr_address (compiler option) | . 224 |
| initializers_in_flash (compiler option) 208, 226 | strict (compiler option) | . 224 |
| library_module (compiler option)210 | string_literals_in_flash (compiler option) | . 224 |
| lock_regs (compiler option) | system_include_dir (compiler option) | . 225 |
| macro_positions_in_diagnostics (compiler option) 211 | use_c++_inline (compiler option) | . 225 |
| memory_model (compiler option) | version1_calls (compiler option) | . 227 |
| mfc (compiler option) | vla (compiler option) | . 228 |
| misrac (compiler option) | warnings_affect_exit_code (compiler option) 184 | , 228 |
| misrac_verbose (compiler option) | warnings_are_errors (compiler option) | . 228 |
| misrac1998 (compiler option) | zero_register (compiler option) | . 230 |
| misrac2004 (compiler option) | 64bit_doubles (compiler option) | . 194 |
| module_name (compiler option)212 | 64k_flash (compiler option) | |
| no_clustering (compiler option) | ?C_EXIT (assembler label) | . 115 |
| no_code_motion (compiler option) | ?C_GETCHAR (assembler label) | . 115 |
| no_cross_call (compiler option)213 | ?C_PUTCHAR (assembler label) | . 115 |
| no_cse (compiler option) | @ (operator) | 48 |
| no_inline (compiler option) | placing at absolute address | . 165 |
| no_path_in_file_macros (compiler option) | placing in segments | . 166 |
| | #include files, specifying | 2, 208 |

| #warning message (preprocessor extension)299 |
|--|
| %Z replacement string, implementation-defined behavior |
| impenentation defined behavior |
| Numerics |
| Numerics |
| 32-bits (floating-point format) |
| 64bit_doubles (runtime model attribute)105 |
| 64bit_doubles (compiler option) |
| 64k_flash (compiler option) |
| 64 hit data trings avoiding |
| 64-bit data types, avoiding |