



# 오차역전파

계산 그래프, 연쇄법칙, 역전파



비타민 13기 4조 | 이예령, 엄성원, 임형수, 차용진





# 발표 순서

역전파 간단 소개



계산 그래프



연쇄법칙 (Chain Rule)

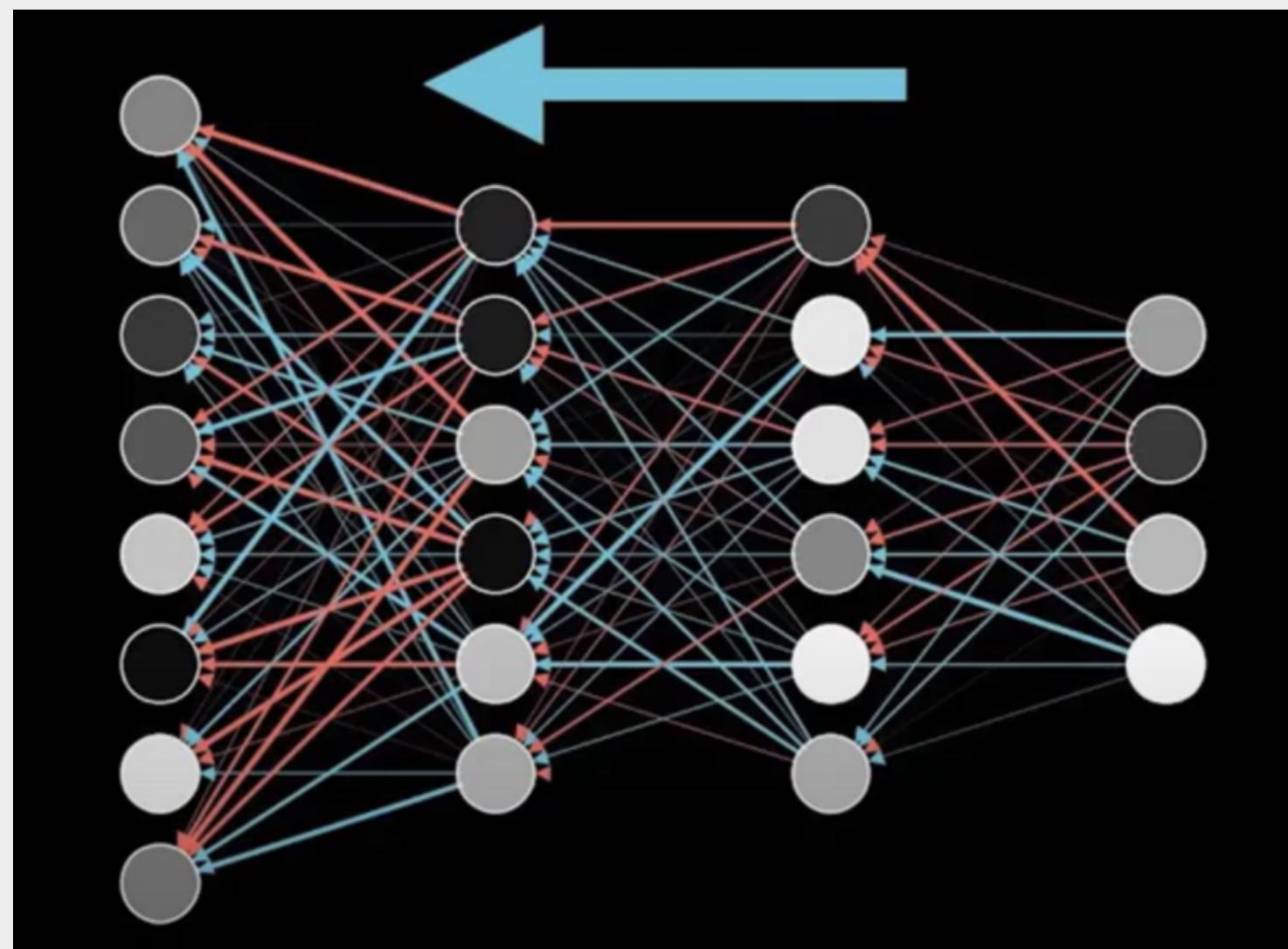


역전파





# 역전파 간단 소개



## 역전파 알고리즘의 작동 방식

손실함수 오차값 (실제값 - 예측값) 계산 후, 거꾸로 뒤로 전파해 가며 각 노드가 가지고 있는 가중치 매개변수 값, 즉 weight 값을 갱신해나가는 과정



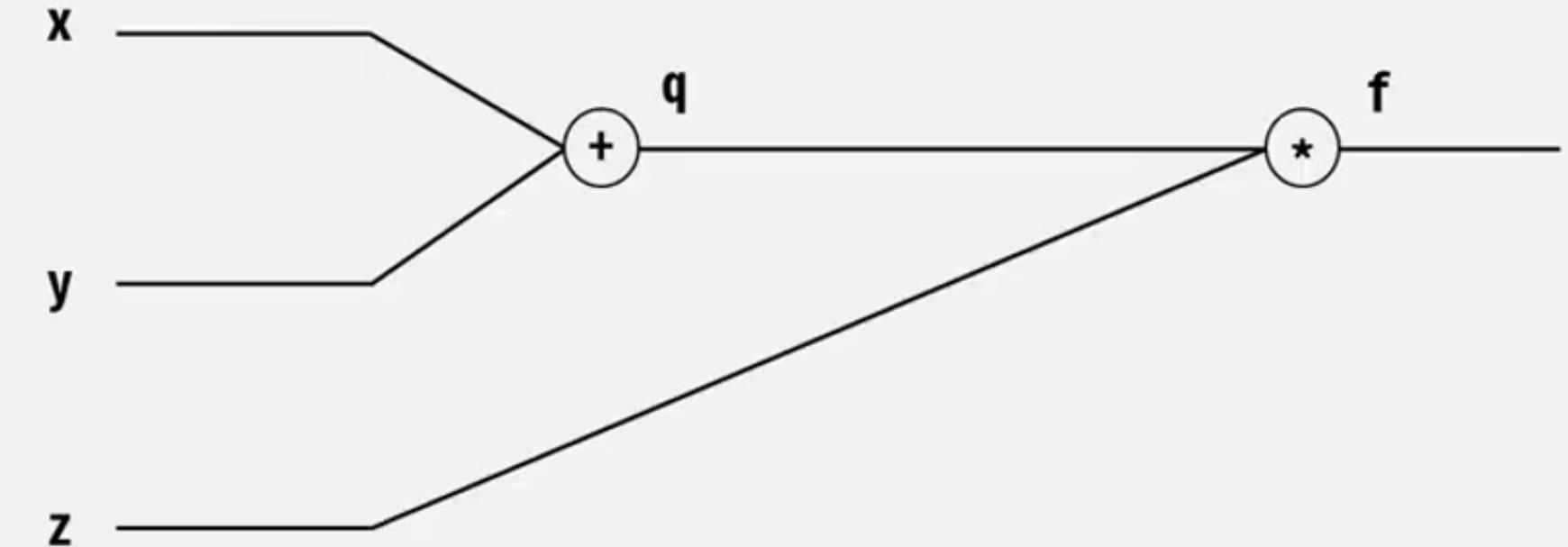
# 계산 그래프



$$f(x, y, z) = (x + y)z$$

$$q = x + y$$

$$f = qz$$





# 계산 그래프

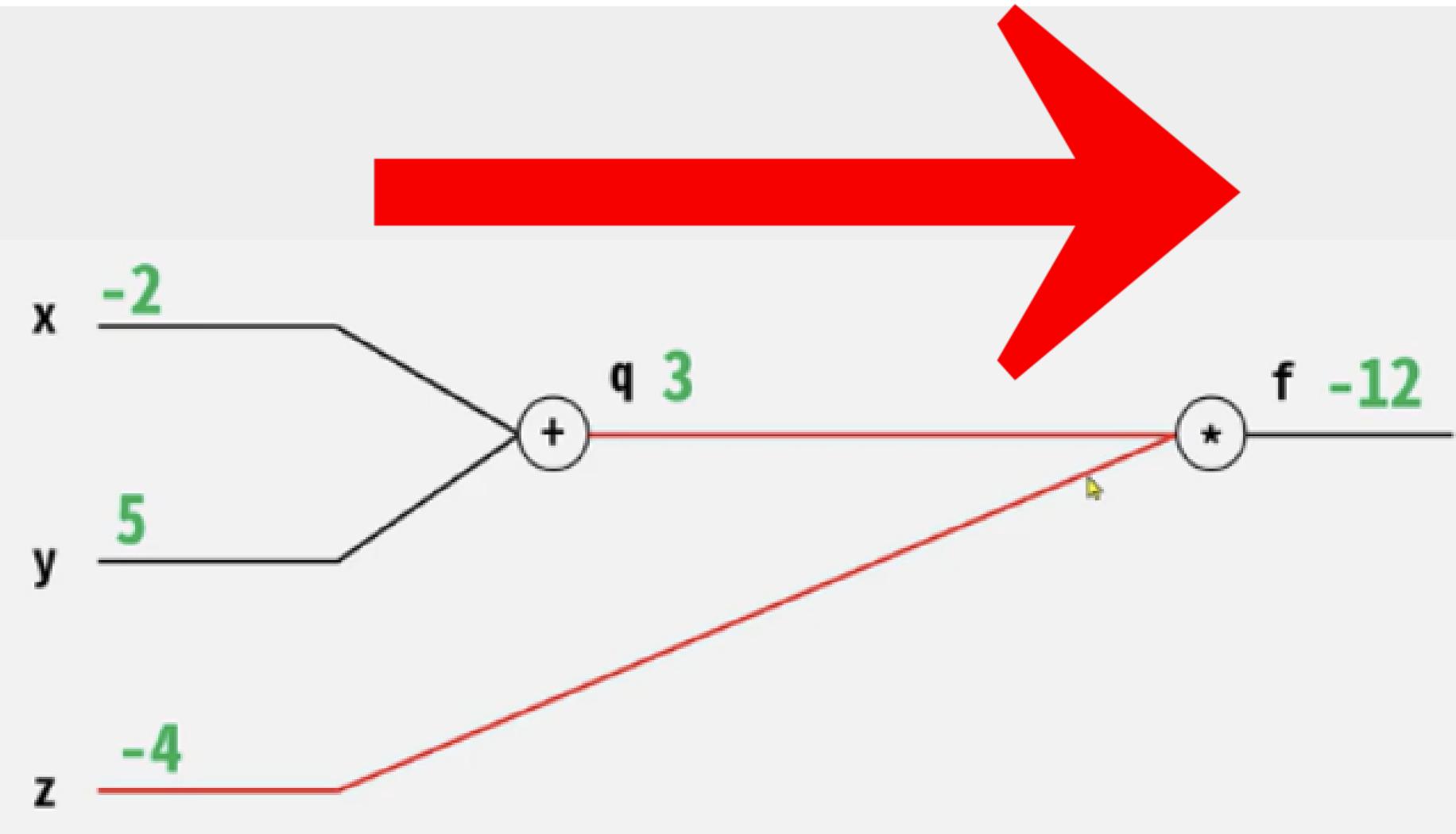


$$f(x, y, z) = (x + y)z$$

$$q = x + y$$

$$f = qz$$

$$x=-2, \quad y=5, \quad z=-4$$



Forward Pass (순전파)

# 계산 그래프



$$\frac{\partial q}{\partial x} = ?$$

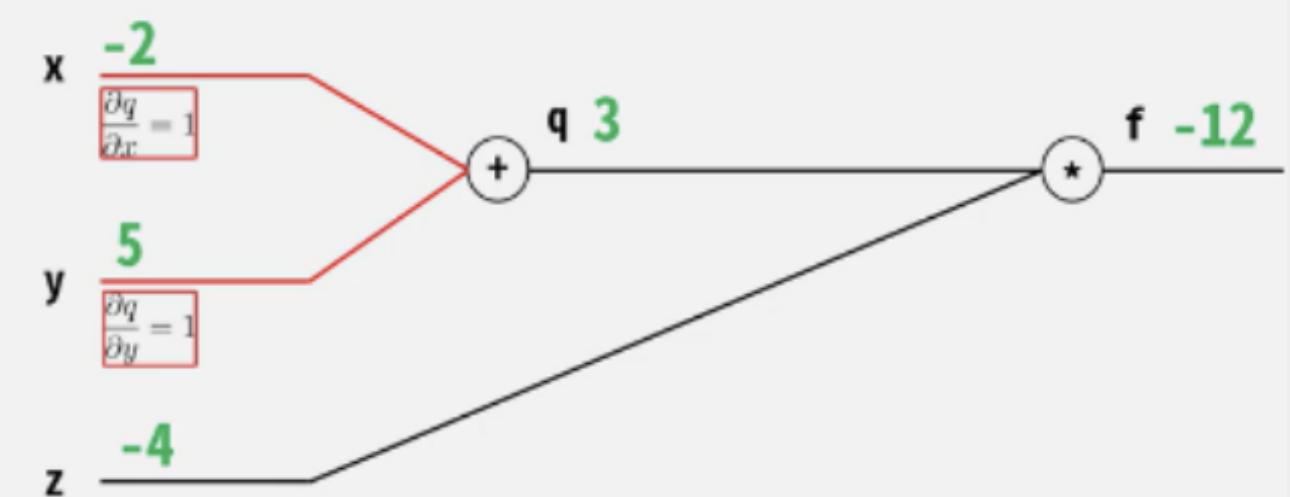
$$\frac{\partial q}{\partial y} = ?$$

$$f(x, y, z) = (x + y)z$$

$$x = -2, \quad y = 5, \quad z = -4$$

$$q = x + y$$

$$\frac{\partial q}{\partial x} = 1 \quad \frac{\partial q}{\partial y} = 1$$





Q1.  $df/dy$  (f에 대한 y의 미분값) ???



$$\frac{\partial f}{\partial y} = ?$$





## 연쇄 법칙 (Chain Rule)



$$f = qz$$

$$\frac{\partial f}{\partial q} = ?$$

$$\frac{\partial f}{\partial z} = ?$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x}$$





## 연쇄 법칙 (Chain Rule)



$$f = qz$$

$$\frac{\partial f}{\partial q} = ?$$

$$\frac{\partial f}{\partial z} = ?$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x}$$



# 연쇄 법칙 (Chain Rule)

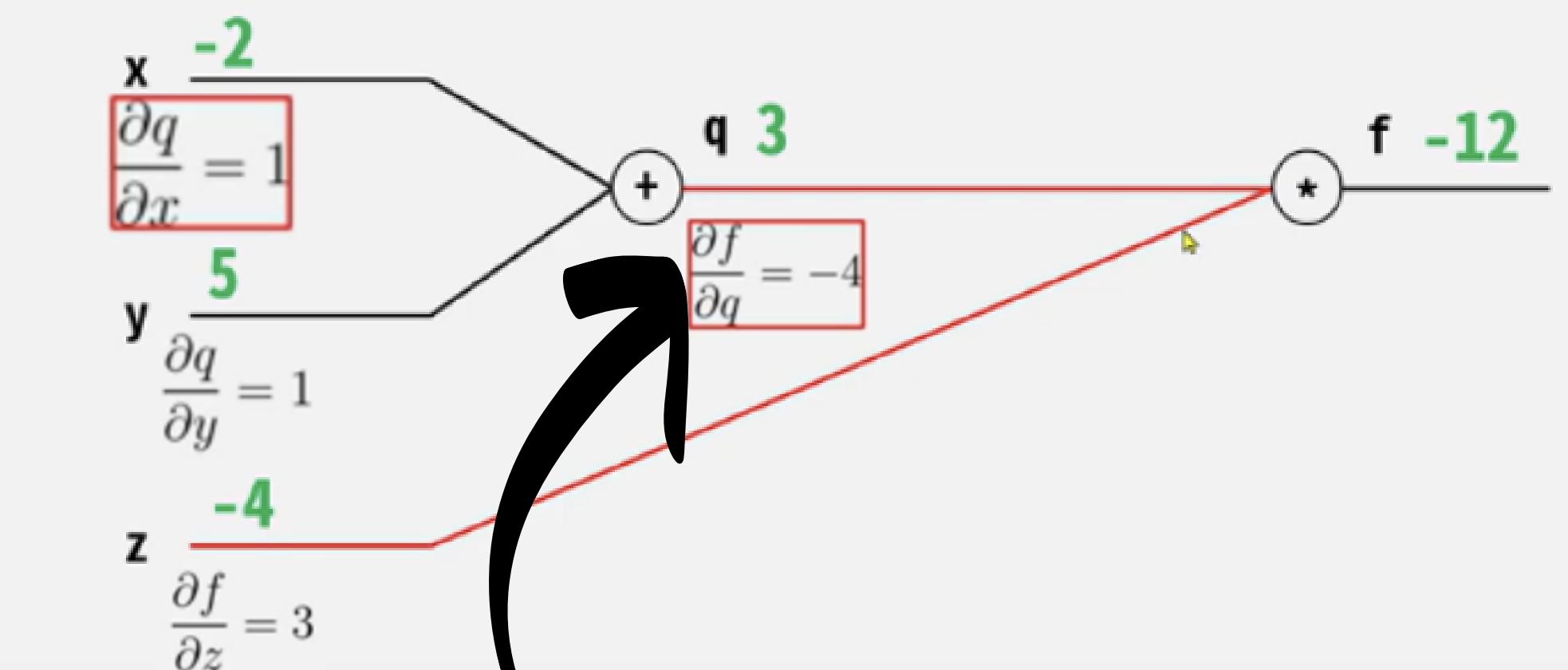


$$f(x, y, z) = (x + y)z$$

$$q = x + y$$

$$f = qz$$

$$x=-2, \quad y=5, \quad z=-4$$



$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x}$$

Q1.  $df/dy$  (f에 대한 y의 미분값) 정답

$$\frac{\partial f}{\partial y} = ?$$



$$f(x, y, z) = (x + y)z$$

$$x = -2, \quad y = 5, \quad z = -4$$

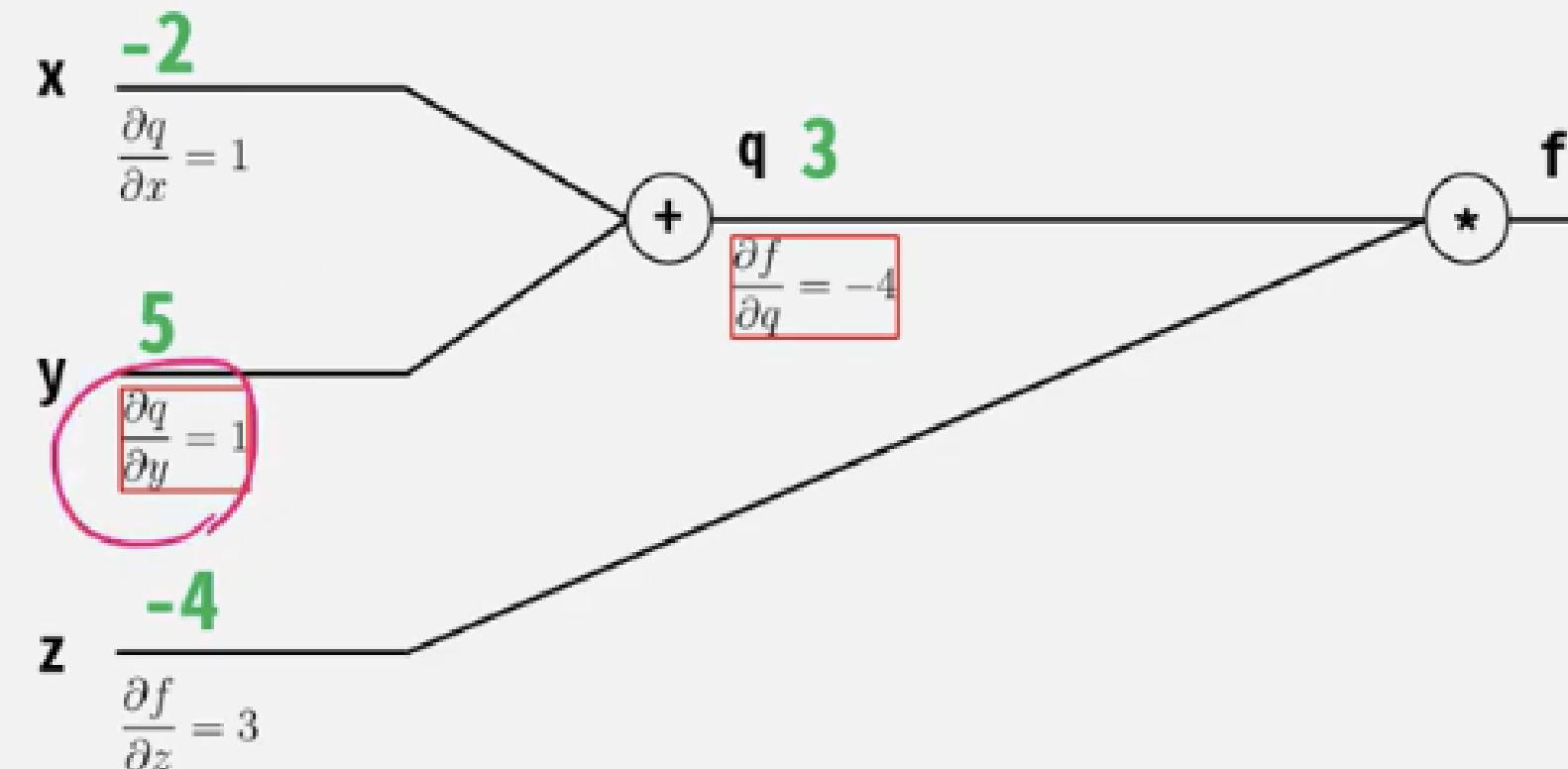
$$q = x + y$$

$$f = qz$$

Chain Rule

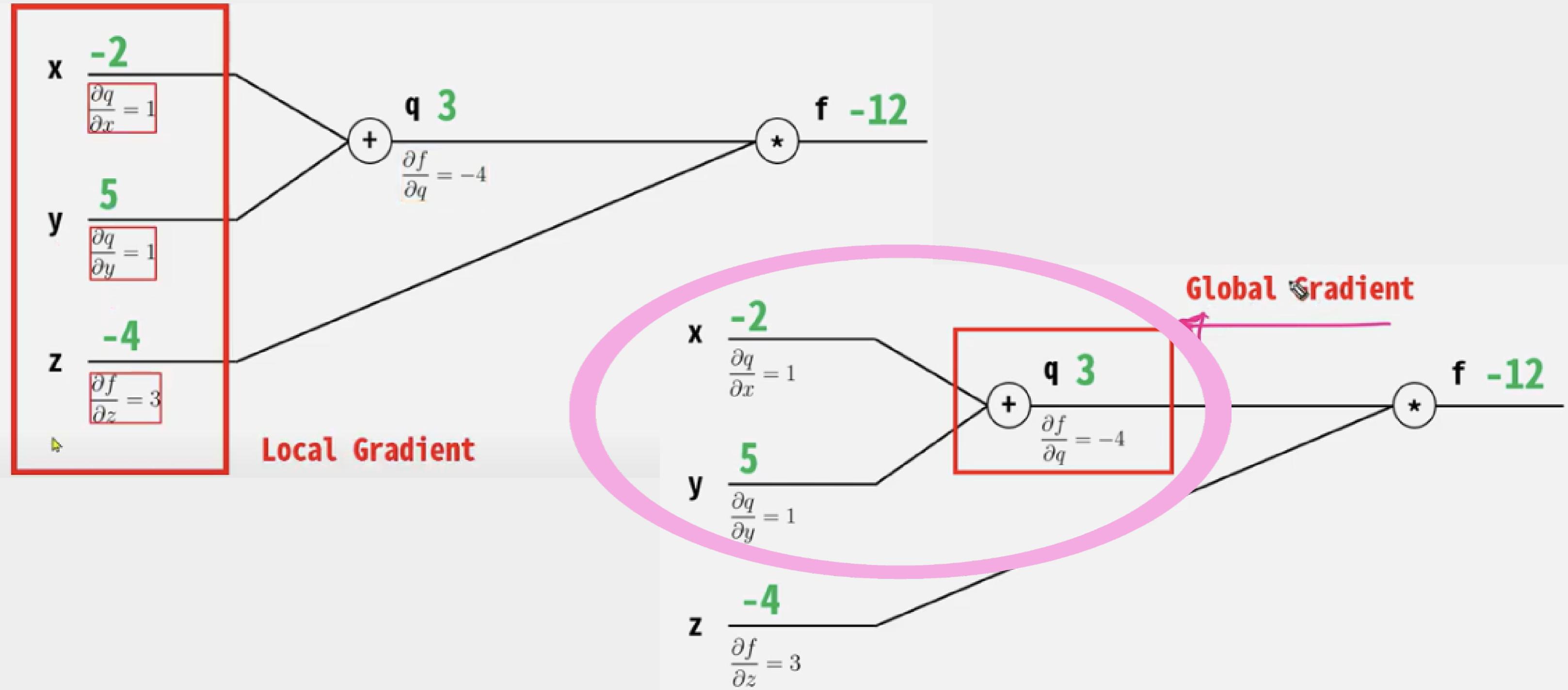
$$\frac{\partial f}{\partial x} = -4$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y} =$$





# 연쇄 법칙 (Chain Rule)



# 연쇄 법칙 (Chain Rule)



## Forward Pass

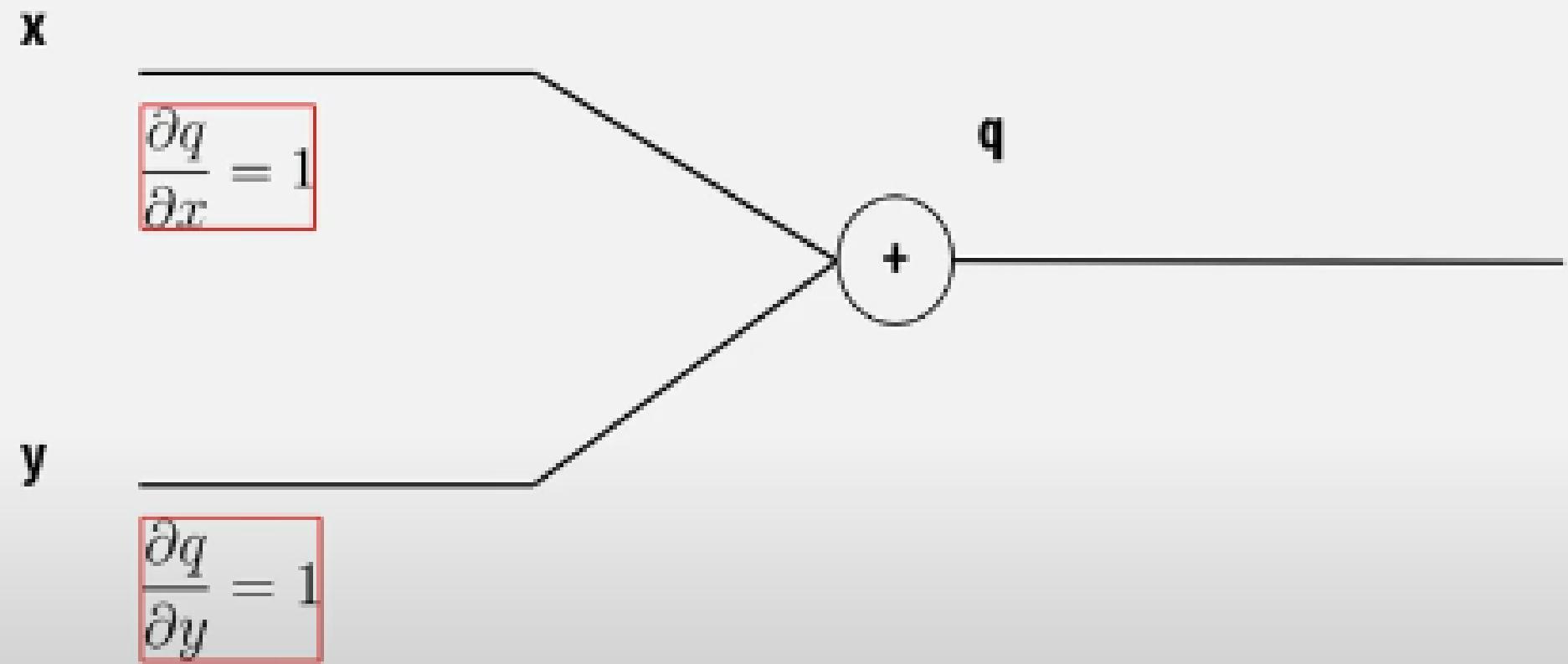
$$q = x + y$$

$$\frac{\partial q}{\partial x} = 1 \quad \frac{\partial q}{\partial y} = 1$$

$$f = qz$$

$$\frac{\partial f}{\partial q} = z \quad \frac{\partial f}{\partial z} = q$$

Forward Pass 시 우리는 Local Gradient를 미리 구하여 저장할 수 있다!



$$q = x + y$$

$$\frac{\partial q}{\partial x} = 1 \quad \frac{\partial q}{\partial y} = 1$$

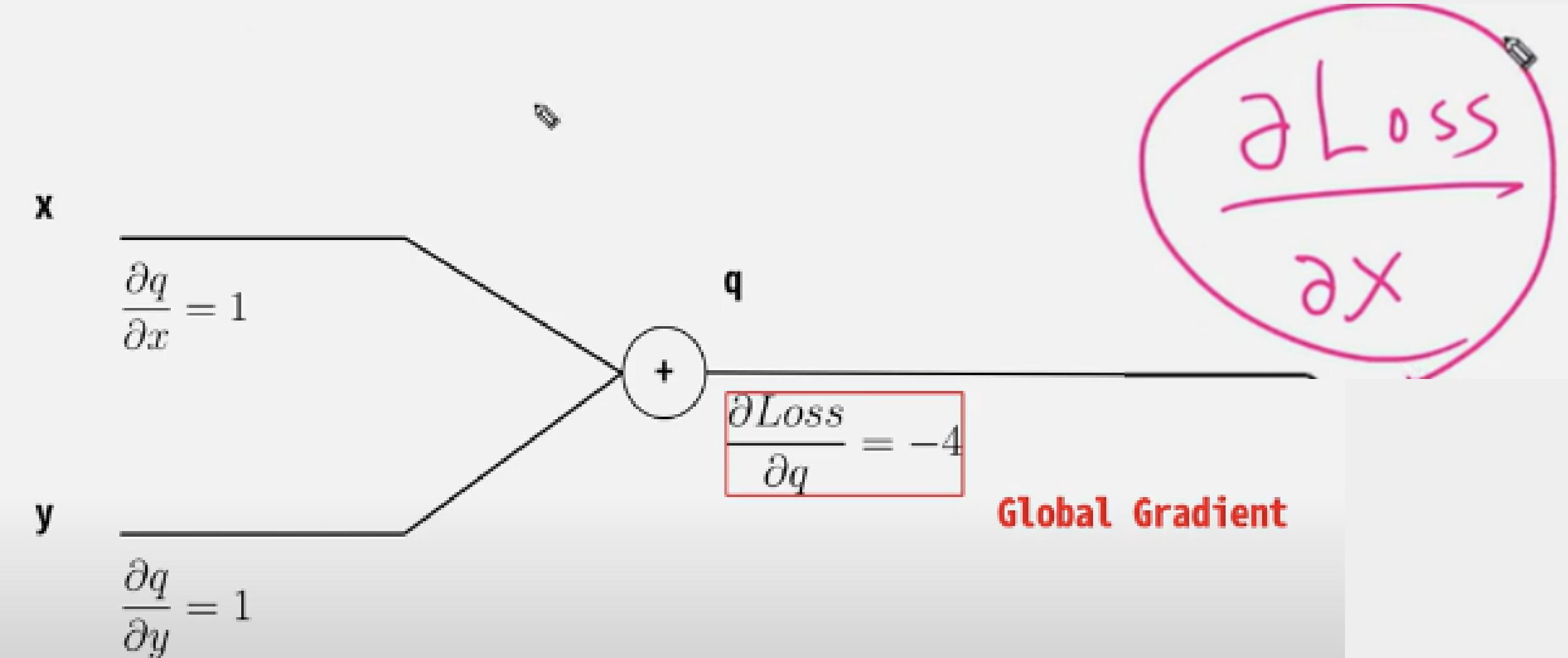
$$f = qz$$

$$\frac{\partial f}{\partial q} = z \quad \frac{\partial f}{\partial z} = q$$

# 연쇄 법칙 (Chain Rule)



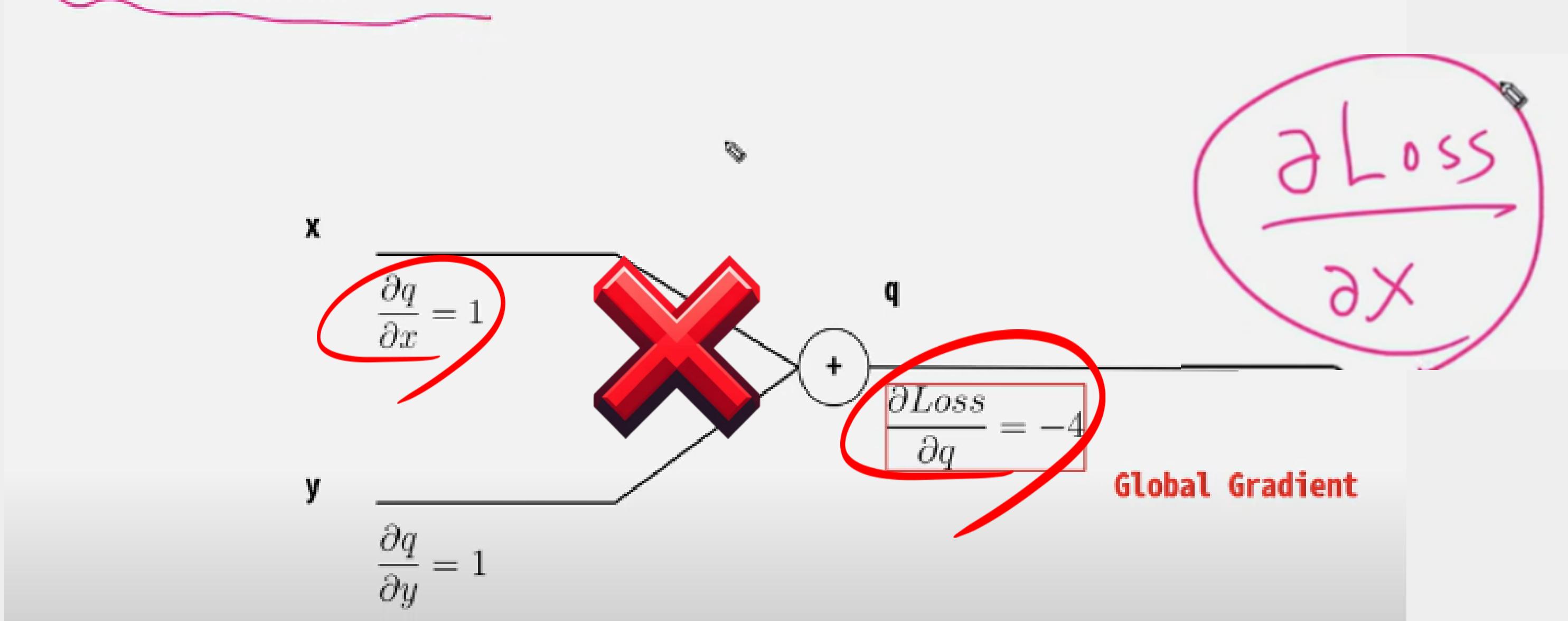
## Backward Pass



# 연쇄 법칙 (Chain Rule)



## Backward Pass



연쇄 법칙(Chain Rule)을 활용하여  
Local Gradient \* Global Gradient를 곱하여 계산

# 연쇄 법칙 (Chain Rule)



**Chain Rule 을 활용하여  
Local Gradient \* Global Gradient를 곱하여 계산한다.**

$\frac{\partial q}{\partial x} = 1 \quad x$

$\frac{\partial Loss}{\partial x} = \frac{\partial Loss}{\partial q} \frac{\partial q}{\partial x} = (-4)(1) = -4$

**Local Gradient**

$\frac{\partial q}{\partial y} = 1 \quad y$

$\frac{\partial Loss}{\partial y} = \frac{\partial Loss}{\partial q} \frac{\partial q}{\partial y} = (-4)(1) = -4$

**Global Gradient**



Q2



손실함수와 기울기 값을 통해 가중치, 즉 웨이트 값을 업데이트하는 과정을 모델이 ( )한다고 말한다.





## Q2. 손실함수와 기울기 값을 통해 웨이트 값을 업데이트하는 과정



$$q = x + y$$

$$\frac{\partial q}{\partial x} = 1 \quad \frac{\partial q}{\partial y} = 1$$

$$f = qz$$

$$\frac{\partial f}{\partial q} = z \quad \frac{\partial f}{\partial z} = q$$





## 결론



### 내용 요약

아무리 깊고 복잡한 층으로 구성되어 있다 하더라도  
Chain Rule을 활용하여 미분 값을 얻어낼 수 있다.

Forward Pass 시 Local Gradient를 미리 계산하여 저장해둔다.

저장해둔 Local Gradient와 Global Gradient를 Backward Pass시  
곱하여 최종 미분 값을 얻는다.

Q3. Loss에 대한 최종 미분값을 구하기 위해서는  
두 가지 값을 곱하면 된다. 그 두 가지 값에 해당하는 것?

A3.  $() * ()$



# 오차역전파

계산 그래프, 연쇄법칙, 역전파



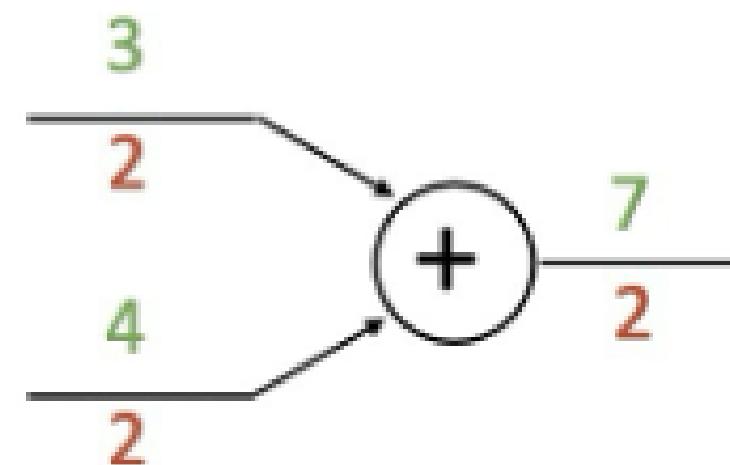
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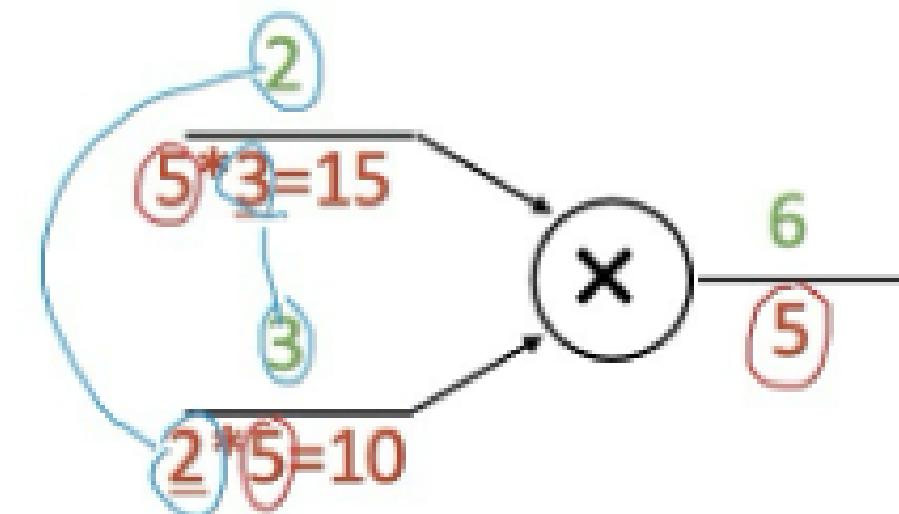
# 역전파 시 연산의 특성



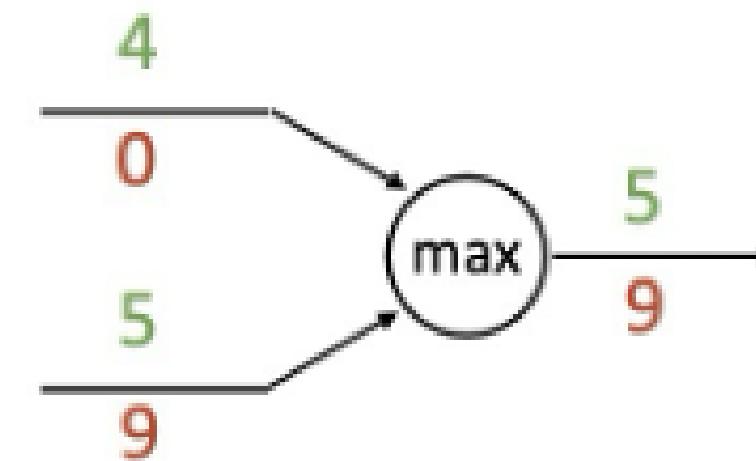
**add gate: gradient distributor**



**mul gate: "swap multiplier"**



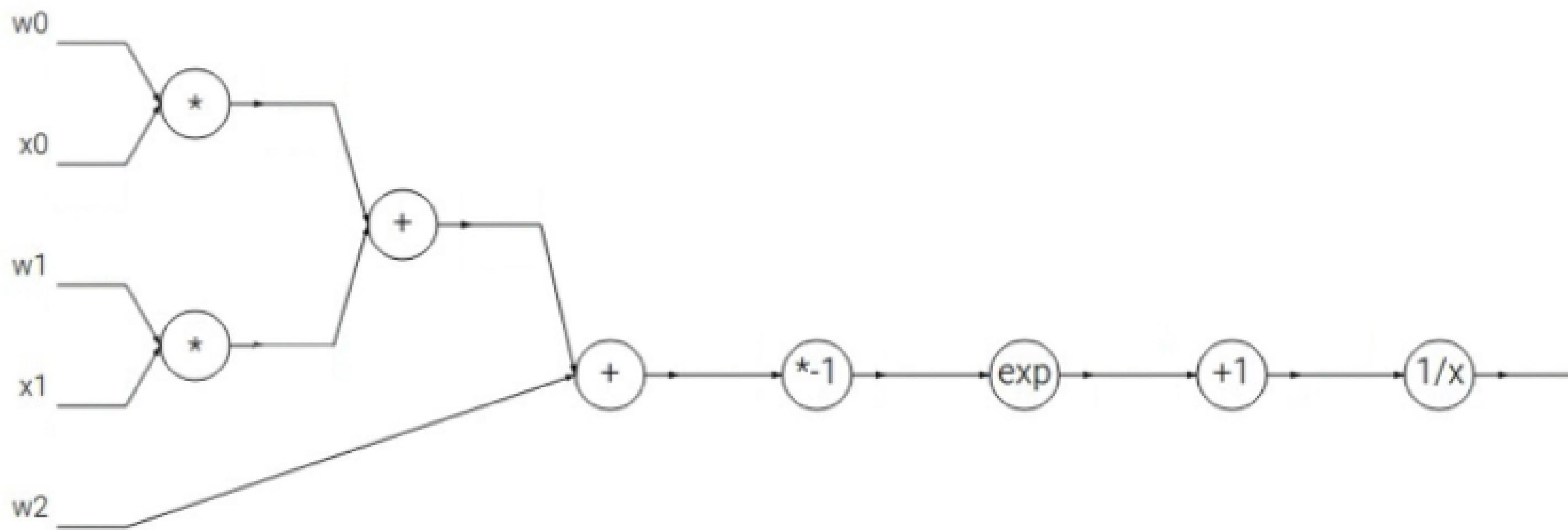
**max gate: gradient router**





# 역전파

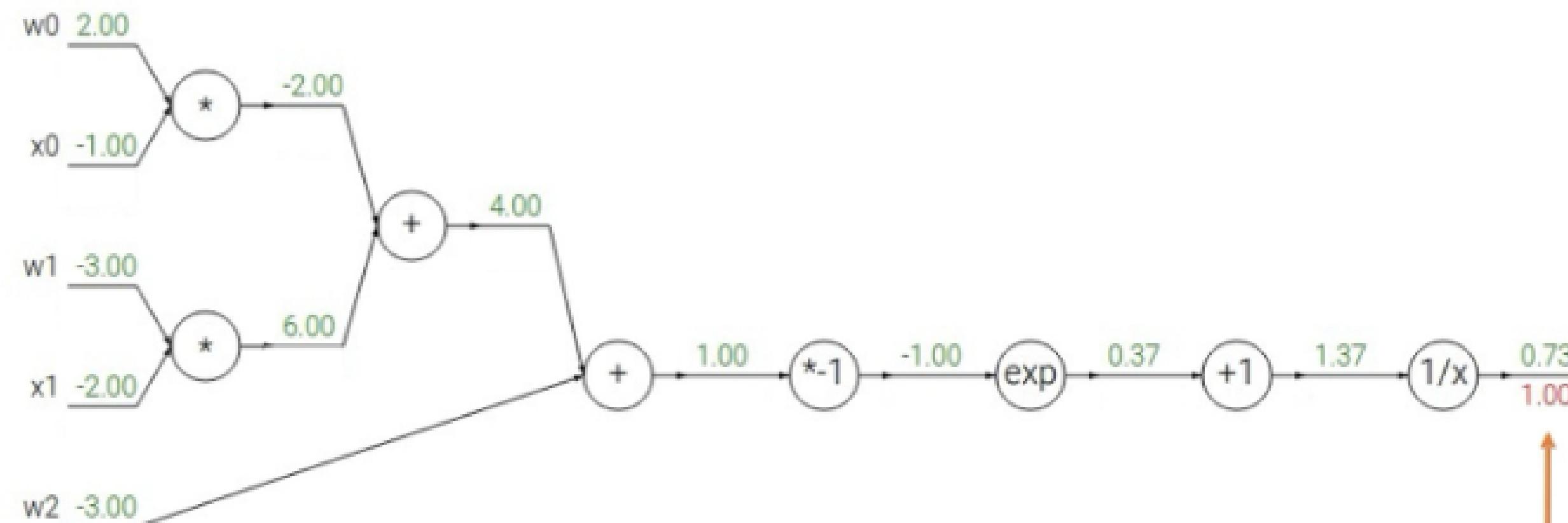
$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



# 역전파



$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



Base Case  
(for simplicity)

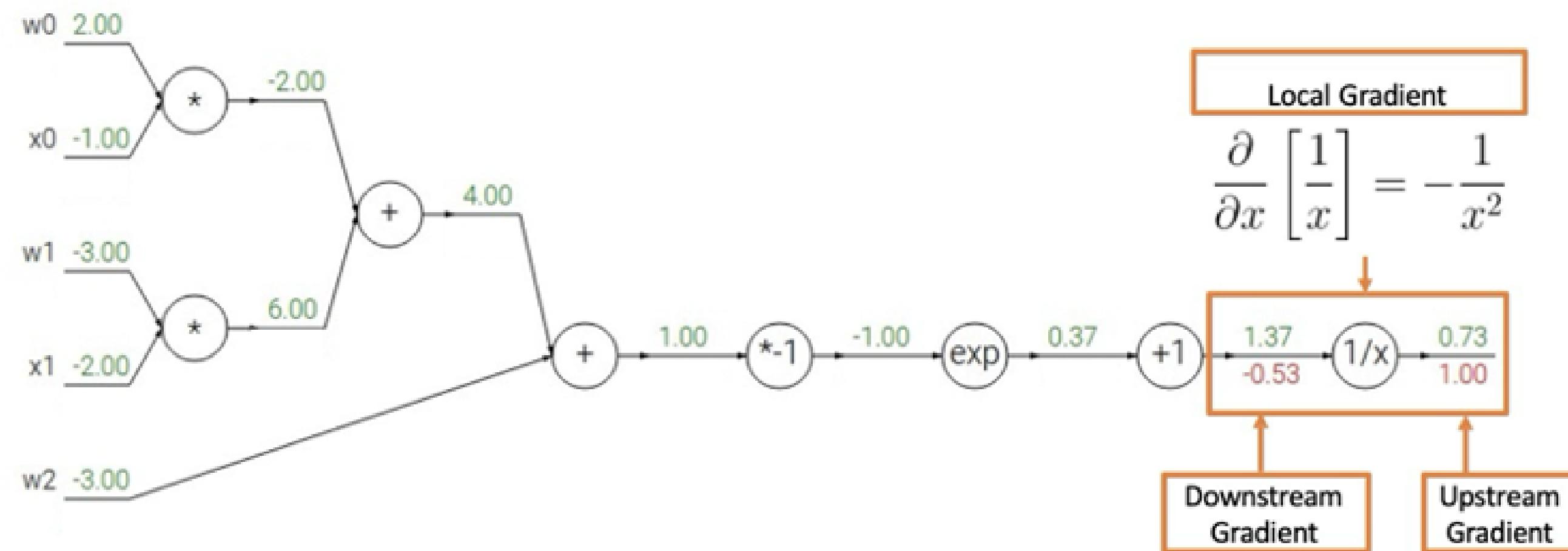
**Backward pass: Compute gradients**



# 역전파



$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



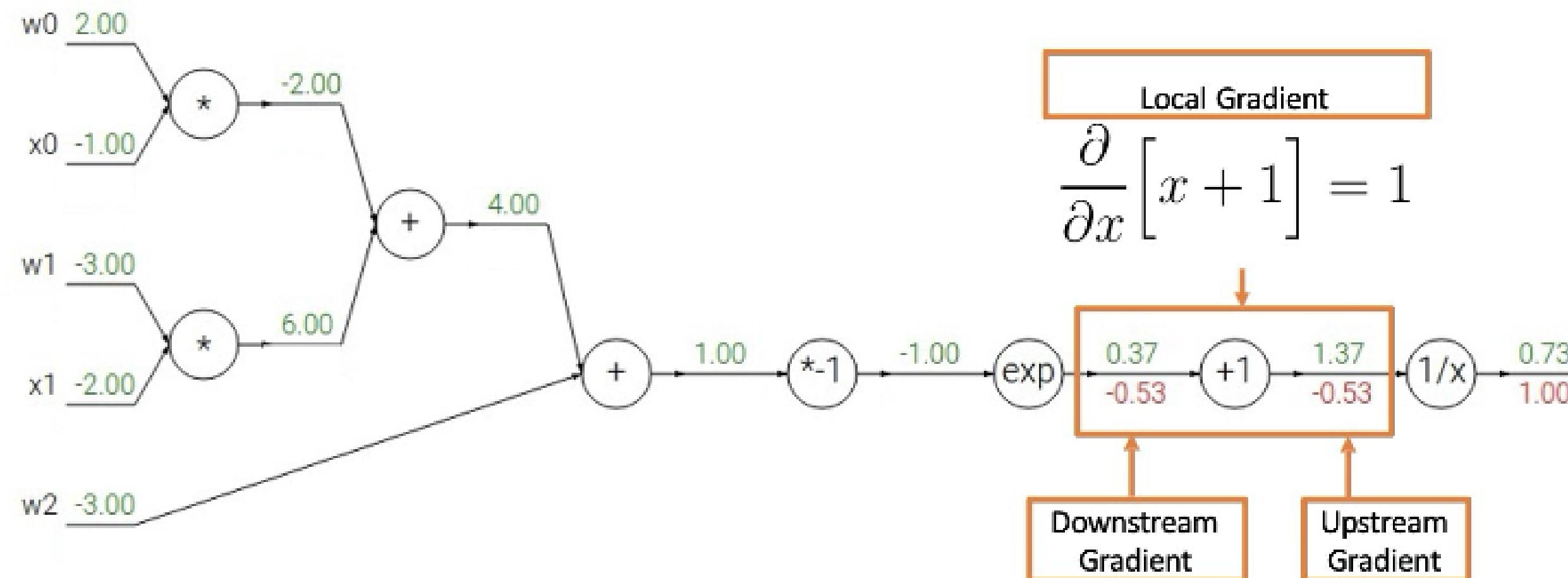
**Backward pass: Compute gradients**





# 역전파

$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



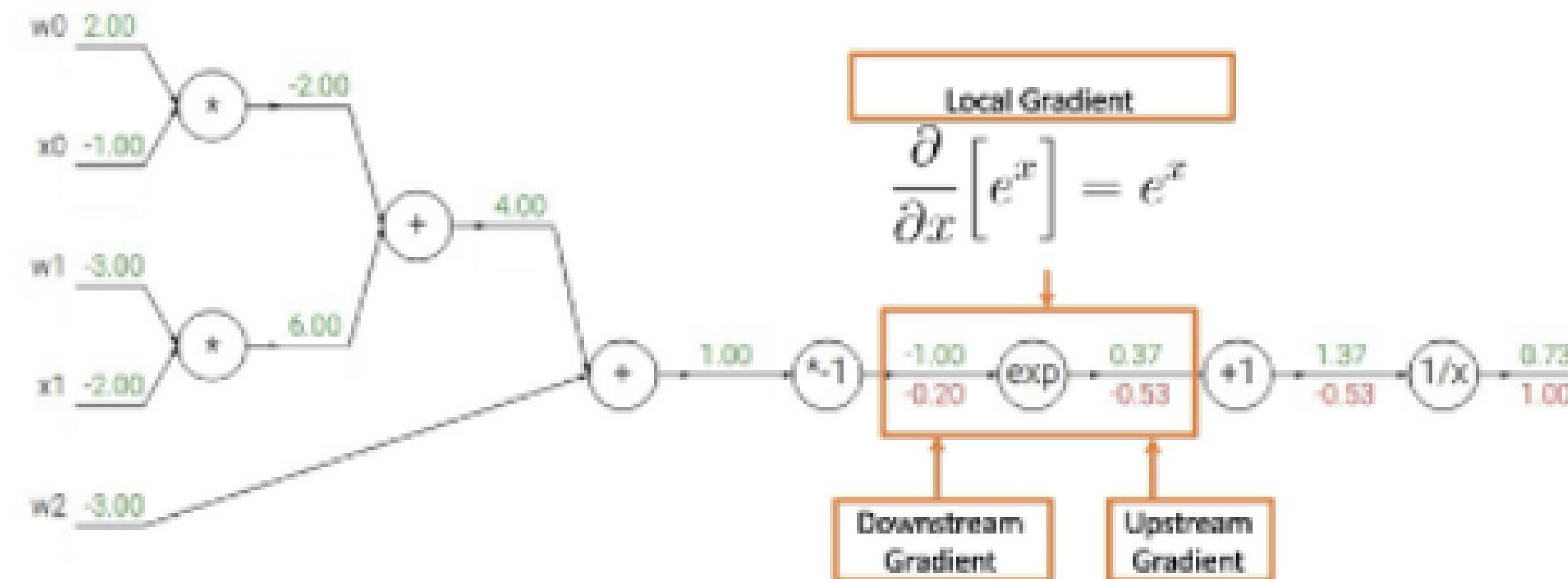
**Backward pass: Compute gradients**



# 역전파



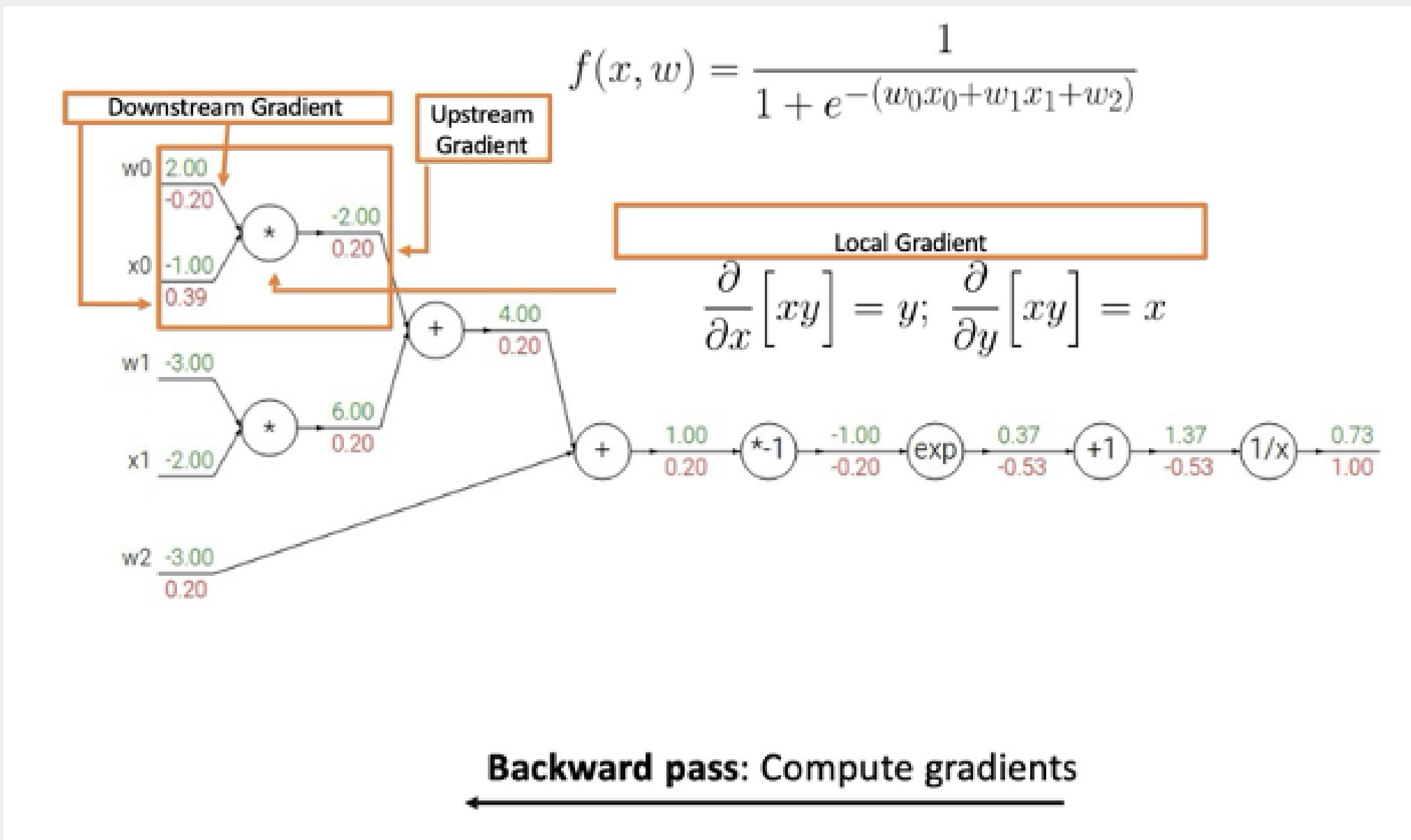
$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



Backward pass: Compute gradients



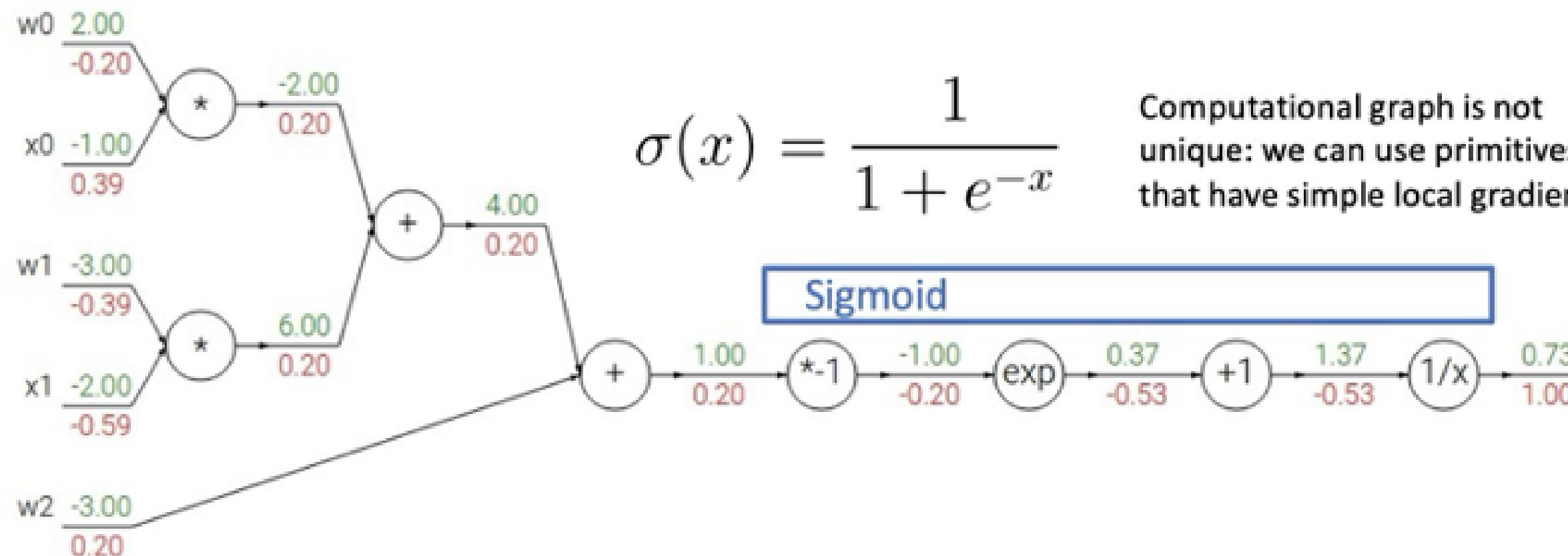
# 역전파



# 역전파



$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}} = \sigma(w_0x_0 + w_1x_1 + w_2)$$



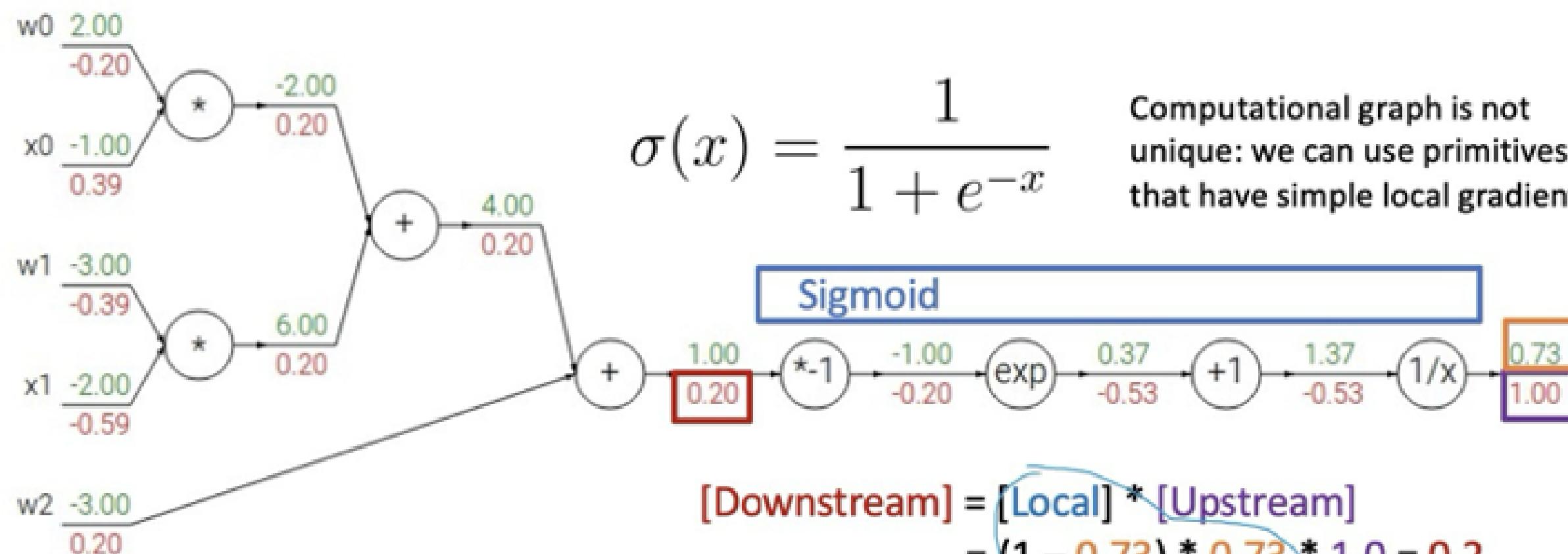
Sigmoid local gradient:  $\frac{\partial}{\partial x} [\sigma(x)] = \frac{e^{-x}}{(1 + e^{-x})^2} = \left( \frac{1 + e^{-x} - 1}{1 + e^{-x}} \right) \left( \frac{1}{1 + e^{-x}} \right) = (1 - \sigma(x))\sigma(x)$

Backward pass: Compute gradients

# 역전파



$$f(x, w) = \frac{1}{1 + e^{-(w_0x_0+w_1x_1+w_2)}} = \sigma(w_0x_0 + w_1x_1 + w_2)$$



Sigmoid local gradient:

$$\frac{\partial}{\partial x} [\sigma(x)] = \frac{e^{-x}}{(1 + e^{-x})^2} = \left( \frac{1 + e^{-x} - 1}{1 + e^{-x}} \right) \left( \frac{1}{1 + e^{-x}} \right) = (1 - \sigma(x))\sigma(x)$$

Backward pass: Compute gradients





# 역전파



$$x \in \mathbb{R}, y \in \mathbb{R}$$

Regular derivative:

$$\frac{\partial y}{\partial x} \in \mathbb{R}$$

If  $x$  changes by a small amount, how much will  $y$  change?

$$x \in \mathbb{R}^N, y \in \mathbb{R}$$

Derivative is **Gradient**:

$$\frac{\partial y}{\partial x} \in \mathbb{R}^N \quad \left( \frac{\partial y}{\partial x} \right)_n = \frac{\partial y}{\partial x_n}$$

For each element of  $x$ , if it changes by a small amount then how much will  $y$  change?

$$x \in \mathbb{R}^N, y \in \mathbb{R}^M$$

Derivative is **Jacobian**:

$$\frac{\partial y}{\partial x} \in \mathbb{R}^{N \times M} \quad \left( \frac{\partial y}{\partial x} \right)_{n,m} = \frac{\partial y_m}{\partial x_n}$$

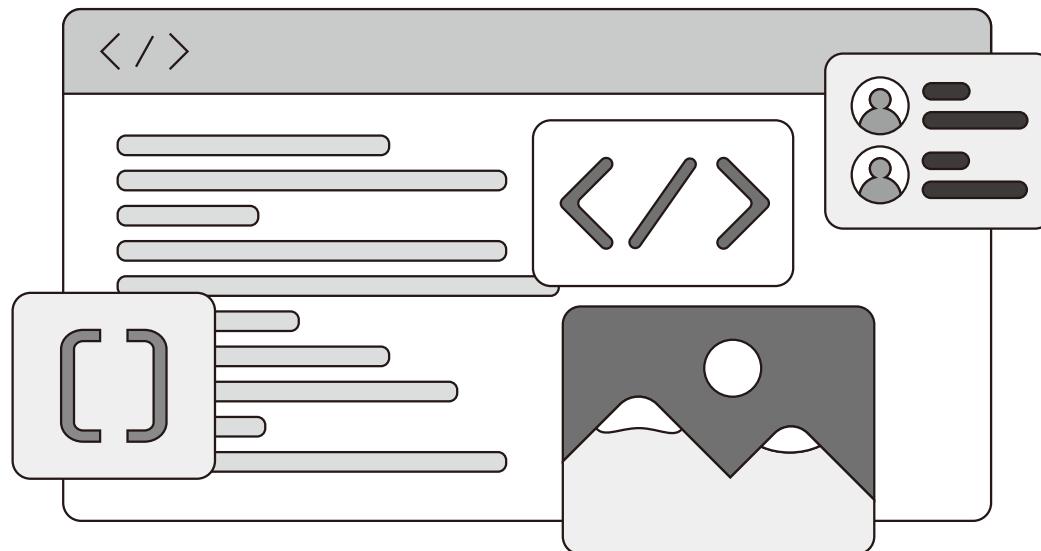
For each element of  $x$ , if it changes by a small amount then how much will each element of  $y$  change?



# 역전파



```
# 모델 학습
num_epochs = 5
for epoch in range(num_epochs):
    rnn_model.train()
    running_loss = 0.0
    for images, labels in train_loader:
        images, labels = images.to(device), labels.to(device)
        optimizer.zero_grad() # 기울기 초기화
        outputs = rnn_model(images) # 순전파
        loss = criterion(outputs, labels) # 손실 계산
        loss.backward() # 역전파
        optimizer.step() # 최적화
        running_loss += loss.item()
    print(f"Epoch {epoch+1}, Loss: {running_loss/len(train_loader)}")
```





역전파

## Q4. 코드 중 역전파를 구현하는 함수는?



```
# 모델 학습
num_epochs = 5
for epoch in range(num_epochs):
    rnn_model.train()
    running_loss = 0.0
    for images, labels in train_loader:
        images, labels = images.to(device), labels.to(device)
        optimizer.zero_grad() # 기울기 초기화
        outputs = rnn_model(images) # 순전파
        loss = criterion(outputs, labels) # 손실 계산
        loss.backward() # 역전파
        optimizer.step() # 최적화
        running_loss += loss.item()
    print(f"Epoch {epoch+1}, Loss: {running_loss/len(train_loader)}")
```





출처



[https://www.youtube.com/watch?v=1Q\\_etC\\_GHHk&t=269s](https://www.youtube.com/watch?v=1Q_etC_GHHk&t=269s)

<https://www.youtube.com/watch?v=qGuNJbGWVvl>



발표 경청해 주셔서 감사합니다.

