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# Stat 151a Lecture Notes 23

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Chae Yeon Lee

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## 1 OVERVIEW

Today:

- More Generalized Linear Models

Relevant Readings:

- Fox 15.1 - 15.3 (Skip 15.2.2, 15.3.4)

## 2 BRIEF RECAP

- If  $\vec{y}$  domain is not  $\mathbb{R}$  (like if it is binary), we might prefer to assume a different parametric distribution on  $\vec{y}$  rather than that  $\vec{y}$  is linear and normal.
- GLMs are a framework that allow this
- Now we cover their estimates and inferences.

## 3 GENERALIZED LINEAR MODELS

GLM is a framework to allow  $\vec{y}$  to follow various parametric distribution.

- **Bernoulli:**  $\vec{y}$  is binary
- **Poisson, Negative Binomial:**  $\vec{y} \in \mathbb{Z}^+$  (count data)
- **Exponential, Gamma:**  $\vec{y} \in \mathbb{R}^+$  (continuous data)
- **Multinomial:**  $\vec{y}$  is a count of occurrences of K different outcomes.

## The GLM "recipe":

1. Specify the conditional distribution of  $y_i | \vec{x}_i^T$  (not necessarily normal; e.g.  $y_i \sim \text{Ber}(\pi_i)$ )
2. Consider the parameters of the distribution in 1, their relation to  $\mathbb{E}[y_i | \vec{x}_i^T]$ , and their domain.  
e.g.  $y_i | \vec{x}_i^T \sim \text{Bernoulli}(\pi_i)$ . The mean of Bernoulli RV is  $\pi_i$ . Note that  $\pi \in (0, 1)$ .
3. Find a link function  $g$  that transforms  $\mathbb{E}[y_i | \vec{x}_i^T]$  into the range  $(-\infty, \infty)$ .  
e.g.  $y_i \sim \text{Ber}(\pi_i)$ . Let  $g$  be the logit function.  $g(\pi_i) = \log(\frac{\pi_i}{1-\pi_i})$   
Then  $g : (0, 1) \rightarrow (-\infty, \infty)$  as desired. Here, we are inputting  $\pi_i$  but  $\pi_i$  is what we are actually estimating.
4.  $g(\pi_i)$  can be modelled linearly:

$$g(\pi_i) = \vec{x}_i^T \vec{\beta}$$

And, we define the inverse link function,  $g^{-1}$ . e.g.  $y_i|\vec{x}_i^T \sim \text{Bernoulli}(\pi_i)$

$$\begin{aligned} g(\pi_i) &= \log\left(\frac{\pi_i}{1-\pi_i}\right) = \vec{x}_i^T \vec{\beta} \\ \Rightarrow \frac{\pi_i}{1-\pi_i} &= \exp(\vec{x}_i^T \vec{\beta}) \\ \Rightarrow \pi_i &= \exp(\vec{x}_i^T \vec{\beta}) - \pi_i \exp(\vec{x}_i^T \vec{\beta}) \\ \Rightarrow \pi_i &= \frac{\exp(\vec{x}_i^T \vec{\beta})}{1 + \exp(\vec{x}_i^T \vec{\beta})} \end{aligned}$$

**(Explicit or inverse logit function)**

$$\Rightarrow \frac{1}{1 + \exp(-\vec{x}_i^T \vec{\beta})}$$

$$:= g^{-1}(\vec{x}_i^T \vec{\beta})$$

**Notes:**

- A whole variety of Link function could make  $\pi_i$  to  $(-\infty, \infty)$
- The logit function is the canonical link; The **canonical link functions** are based on the likelihood function and are the most popular. Canonical link functions can be derived from the likelihood functions.
- if  $y_i | \vec{x}_i^T \sim \text{Poisson}(\lambda_i)$ ,  $\lambda_i \in (0, \infty)$ .
- Logit link is the framework for logistic regression.

**Table 15.2** Canonical Link, Response Range, and Conditional Variance Function for Exponential Families

Family	Canonical Link	Range of $Y_i$	$V(Y_i \eta_i)$
Gaussian	Identity	$(-\infty, +\infty)$	$\phi$
Binomial	Logit	$0, 1, \dots, n_i$	$\frac{\mu_i(1 - \mu_i)}{n_i}$
Poisson	Log	$0, 1, 2, \dots$	$\mu_i$
Gamma	Inverse	$(0, \infty)$	$\frac{\phi \mu_i^2}{\mu_i}$
Inverse-Gaussian	Inverse-square	$(0, \infty)$	$\frac{\phi \mu_i^3}{\mu_i}$

NOTE:  $\phi$  is the dispersion parameter,  $\eta_i$  is the linear predictor, and  $\mu_i$  is the expectation of  $Y_i$  (the response). In the binomial family,  $n_i$  is the number of trials.

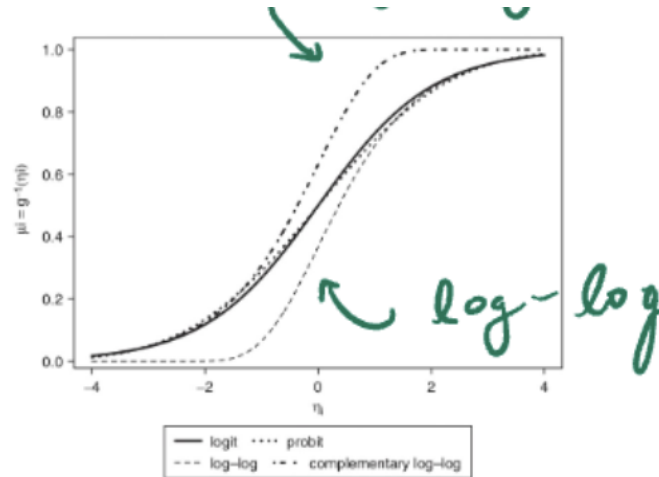
### 3.0.1 GLM vs OLS

Contrast the GLM framework from running OLS on some transformed outcome (via function  $g$ )

- OLS:  $\mathbb{E}[g(y_i)] = \vec{x}_i^T \vec{\beta}$
- GLM:  $g(\mathbb{E}[y_i]) = \vec{x}_i^T \vec{\beta}$  since  $\mathbb{E}[y_i] = g^{-1}(\vec{x}_i^T \vec{\beta})$
- Thus, OLS and GLM are not equal if  $g$  is nonlinear.
- The variance of  $y_i$  is now often tied to its mean, so it can fluctuate. For OLS, we assumed that the variance is constant. Now, it is not.

E.g. **Ber**( $\pi_i$ ) **variance** is  $\pi_i(1 - \pi_i)$ , **Pois**( $\lambda_i$ ) **variance** is  $\lambda_i$ .

- Some distributions – such as Normal, Negative Binomial, and Gamma – require that we estimate a separate dispersion parameter,  $\phi$ . For normal GLM,  $\phi = \sigma_\epsilon^2$ . Negative Binomial is equal to Poisson when  $\phi = 1$ .
- Sometimes, a non-canonical link is a better fit to the data. For example, we might think that the event probability ( $\pi_i$ ) is asymmetric in  $X$ .



**Figure 15.1** Logit, probit, log-log, and complementary log-log links for binomial data. The variances of the normal and logistic distributions have been equated to facilitate the comparison of the logit and probit links [by graphing the cumulative distribution function of  $N(0, \pi^2/3)$  for the probit link].

**Table 15.1** Some Common Link Functions and Their Inverses

Link	$\eta_i = g(\mu_i)$	$\mu_i = g^{-1}(\eta_i)$
Identity	$\mu_i$	$\eta_i$
Log	$\log_e \mu_i$	$e^{\eta_i}$
Inverse	$\mu_i^{-1}$	$\eta_i^{-1}$
Inverse-square	$\mu_i^{-2}$	$\eta_i^{-1/2}$
Square-root	$\sqrt{\mu_i}$	$\eta_i^2$
Logit	$\log_e \frac{\mu_i}{1 - \mu_i}$	$\frac{1}{1 + e^{-\eta_i}}$
Probit	$\Phi^{-1}(\mu_i)$	$\Phi(\eta_i)$
Log-log	$-\log_e[-\log_e(\mu_i)]$	$\exp[-\exp(-\eta_i)]$
Complementary log-log	$\log_e[-\log_e(1 - \mu_i)]$	$1 - \exp[-\exp(\eta_i)]$

NOTE:  $\mu_i$  is the expected value of the response,  $\eta_i$  is the linear predictor, and  $\Phi(\cdot)$  is the cumulative distribution function of the standard-normal distribution.

Figure 15.1 Annotation: x axis is  $\vec{x}_i^T \hat{B}$  and y axis predicted probability associated with that  $\vec{x}_i^T \hat{B}$ .

### 3.1 ESTIMATION

The data model for the Bernoulli set up is now  $y_i \sim \text{Ber}(g^{-1}(\vec{x}_i^T \vec{\beta}))$

- Bad News is that we this no longer corresponds to a least squares problem so we don't have a closed form solution for  $\hat{\beta}$
- Good news is that we can still write the Likelihood  $L(\hat{\beta}, \vec{y}, X)$ .  $\log(L(\hat{\beta}, \vec{y}, X))$  is convex for many GLM distributions, so it is straightforward to solve via common numerical methods.
- If dispersion ( $\phi$ ) parameter must be estimated, we can do alternating optimization.
  1. Init  $t = 0, \hat{\phi}_0$  while not converged:
  2.  $\hat{\beta}_{t+1} = \hat{\phi}_t$
  3.  $\hat{\phi}_{t+1} = \hat{\phi} | \hat{\beta}_{t+1}$  (can be  $\phi_{MLE}$  or  $\phi_{MOM}$ )
  4.  $t = t + 1$

### 3.2 PREDICTION

Once we optimize the GLM for  $\hat{\beta}$ , prediction is straight forward.

$$\hat{y}_i = \mathbb{E}[y_i | \vec{x}_i^T] = g^{-1}(\vec{x}_i^T \hat{\beta})$$

e.g. logistic regression  $\hat{y}_i = \frac{1}{1 + \exp(-\vec{x}_i^T \hat{\beta})}$

### 3.3 INFERENCE

How do we assess model performance?

1. Residual Deviance (Dm):

$$D_m := 2(\log L_s - \log L_m)$$

$L_m$  : Likelihood of our model  $L_s$  : Likelihood of saturated model. (i.e. model with one parameter for each observation.)

2. Example for logistic regression. For logistic regression,  $D_m = -2\log L_m$ . We will prove this: In saturated model, we can fit the training logits perfectly: (i.e. if  $y_i = 1$ , then  $y^{-1}(\hat{x}_i^T \hat{\beta}_{MLE}) \approx 1$ )

Fact: If  $\hat{\beta}_i$  is a MLE estimate, then  $\frac{\hat{\beta}_i - B_i}{\hat{SE}(\hat{\beta}_i)}$  is asymptotically normal.