

The Geometry of Choice: Path-Constrained Rationality and Reachability Equilibrium*

*Working Paper Summary. Full draft available upon request.

Chaeyeon Renée Eunice Xon

School of Economics

Yonsei University

Seoul, Republic of Korea

eunixon@yonsei.ac.kr

Abstract—This paper challenges the classical view of economic choice as a static optimization problem. We propose a geometric framework, termed Xon’s Reachability Equilibrium (XRE), where rationality is modeled as motion over a structured, frictional terrain. Strategies are not points but paths, and the costs of traversing these paths—due to cognitive, institutional, or physical frictions—are explicitly incorporated into the equilibrium concept. This approach recasts behavioral phenomena like loss aversion and status quo bias not as evidence of irrationality, but as necessary features of optimal paths in a non-Euclidean choice space. We define a generalized optimization problem with asymmetric adjustment costs and introduce the concept of a reachability-constrained strategy space. The resulting equilibrium is path-dependent and local, offering a unified architecture that integrates findings from behavioral, micro, and macroeconomic theory by treating constraints as the primary determinants of observed behavior.

Index Terms—Path-Constrained Rationality, Economic Dynamics, Bounded Rationality, Game Theory, Optimal Control, Asymmetric Adjustment Costs

I. INTRODUCTION: FROM PSYCHOLOGICAL FIXES TO GEOMETRIC STRUCTURE

Classical economic theory, built on the axiom of the frictionless rational agent [41], struggles to explain systematic behavioral deviations [21]. Behavioral economics addressed these anomalies with psychological modifications, often creating a “patchwork” of models [16]. This paper proposes a fundamental shift: observed behavioral patterns are not signs of flawed rationality [34], but signals of a complex economic ‘terrain’ that conventional models treat as flat. The true dichotomy is not ‘rational versus behavioral,’ but ‘frictionless versus frictional’ modeling. Our framework, Xon’s Reachability Equilibrium (XRE), provides a more general geometry of choice that can subsume both classical and behavioral models as special cases.

II. THEORETICAL FOUNDATION

We retain the classical assumption of optimizing agents but redefine the structure in which optimization occurs. Rationality is not a pointwise maximization but a trajectory-based solution under constraint.

In this view, loss aversion becomes a slope: moving backward is steeper than moving forward. Status quo bias becomes a basin: escape is costly, not irrational. We reinterpret behavioral insights as signals that standard models insufficiently account for structural constraints on behavior.

III. FORMAL FRAMEWORK: RATIONALITY AS MOTION

We redefine the agent’s problem from a static choice to finding an optimal *path* through a state space, using tools from optimal control theory [30].

A. Asymmetric Adjustment Costs

The central innovation is a generalized cost function, $\Phi(\dot{u}(t))$, that penalizes the velocity of change. Crucially, this cost can be asymmetric. The agent’s objective is to minimize a cost functional $J(u)$:

$$J(u) = \int_0^T [L(x, u) + \frac{1}{2}\lambda_+[\dot{u}]_+^2 + \frac{1}{2}\lambda_-[\dot{u}]_-^2] dt \quad (1)$$

where $L(x, u)$ is the standard loss function, and (λ_+, λ_-) act as a ‘friction tensor,’ defining the local geometry and ‘anisotropy’ (direction-dependence) of the choice space. This structure endogenously generates loss aversion when $\lambda_- > \lambda_+$ and status quo bias when moving away from $\dot{u} = 0$ is costly.

B. Reachability Equilibrium (XRE)

We define the **Reachability-Constrained Strategy Space**, $S_i^{\text{reachable}}$, as the subset of strategies an agent can reach with finite cost. Some states may be unreachable due to ‘topological obstructions’ (e.g., if the space is a non-orientable manifold like a Klein bottle).

A strategy profile s^* is a **Xon’s Reachability Equilibrium (XRE)** if no agent has a *profitable and feasible* deviation. An XRE is stable not because no one *wants* to deviate, but because no one can *afford* to, making the equilibrium inherently dynamic, local, and path-dependent.

IV. AN INTEGRATIVE ARCHITECTURE FOR ECONOMICS

The XRE framework provides a common language to unify disparate fields. The cost function $\Phi(u)$ is a universal mathematical object representing different frictions:

- **Microeconomics:** Models cognitive/transaction costs, explaining inertia and default effects as rational path optimization.
- **Macroeconomics:** Captures institutional/policy frictions, explaining policy lags and asymmetric responses (e.g., monetary tightening vs. easing).
- **Game Theory:** Replaces the frictionless strategy space with the more realistic $S_i^{\text{reachable}}$, altering predictions about equilibrium and credibility.
- **Behavioral Economics:** Reframes 'biases' as consequences of the underlying geometry.
- **Econometrics:** Suggests that observed behavior reflects a trajectory shaped by motion costs. Estimation should focus on mapping these 'frictional surfaces' rather than assuming static responses.

This implies that much of what we measure as 'preference' may be a reflection of the 'constraint' geometry, challenging revealed preference theory [9].

V. EMPIRICAL VALIDATION

The framework's tenets are empirically testable. Our analysis of diverse systems, from financial markets (Dot-com bubble, 1995-2005) to online platforms (YouTube policy changes), reveals consistent structural patterns:

- **Thresholds:** Behavior shifts only after shocks surpass a critical magnitude (e.g., $\hat{\tau} \approx -0.27$ for Nasdaq data), overcoming a 'basin of inaction'.
- **Asymmetries:** Responses to negative and positive shocks are systematically different, amplified by factors like the VIX.
- **Path Dependence:** The impact of a shock depends on prior history, creating a 'memory effect'.
- **Heterogeneity:** Agents cluster into distinct trajectories (e.g., gentle recovery, plunge and stagnation, rebound then stall), reflecting different cost structures.

These findings demonstrate that the geometry of choice is a measurable feature of real-world economic systems.

VI. CONCLUSION: TOWARDS AN INTEGRITY ARCHITECTURE

This paper argues that rationality was never broken, only modeled on an incomplete map. What looked like irrationality was merely motion through structure. The framework's strength lies in its mathematical necessity; fundamental theorems of calculus (e.g., Rolle's Theorem, Mean Value Theorem) guarantee the existence of the very behavioral patterns we observe. The rational agent still optimizes; they just cannot teleport.

This perspective offers an 'integrity architecture' for economics, restoring it as a self-sufficient system where

behavior arises from internal constraints. The deepest foundations may even lie in algebra; the non-commutativity of quaternions ($ab \neq ba$) provides a formal origin for directional asymmetry ($\lambda_+ \neq \lambda_-$), suggesting that economic laws might be deduced from first principles. The empirical challenge ahead is to map these economic terrains, transforming econometrics into a form of cartography.

REFERENCES

- [1] S. Amari, *Information Geometry and Its Applications*. Tokyo, Japan: Springer, 2016.
- [2] V. I. Arnold, *Mathematical Methods of Classical Mechanics*, 2nd ed. New York, NY, USA: Springer, 1989.
- [3] K. J. Arrow, S. Karlin, and H. Scarf, Eds., *Studies in Applied Probability and Management Science*. Stanford, CA, USA: Stanford Univ. Press, 1962.
- [4] T. Başar and G. J. Olsder, *Dynamic Noncooperative Game Theory*, 2nd ed. Philadelphia, PA, USA: SIAM, 1999.
- [5] R. Bellman, *Dynamic Programming*. Princeton, NJ, USA: Princeton Univ. Press, 1957.
- [6] D. P. Bertsekas, *Dynamic Programming and Optimal Control*, 4th ed., vol. 1. Belmont, MA, USA: Athena Scientific, 2012.
- [7] R. W. Brockett, *Finite Dimensional Linear Systems*. New York, NY, USA: Wiley, 1970.
- [8] P. Cisek, "Cortical mechanisms of action selection: the affordance competition hypothesis," *Philosophical Transactions of the Royal Society B*, vol. 362, no. 1485, pp. 1585–1599, 2007.
- [9] G. Debreu, "Representation of a Preference Ordering by a Numerical Function," in *Decision Processes*, R. M. Thrall, C. H. Coombs, and R. L. Davis, Eds. New York, NY, USA: Wiley, 1954.
- [10] A. K. Dixit and R. S. Pindyck, *Investment Under Uncertainty*. Princeton, NJ, USA: Princeton Univ. Press, 1994.
- [11] M. P. do Carmo, *Riemannian Geometry*. Boston, MA, USA: Birkhäuser, 1992.
- [12] M. Frick, R. Iijima, and T. Strzalecki, "Dynamic Random Subjective Expected Utility," *Journal of Economic Theory*, vol. 170, pp. 375–416, 2017.
- [13] K. Friston, "The free-energy principle: a unified brain theory?" *Nature Reviews Neuroscience*, vol. 11, no. 2, pp. 127–138, 2010.
- [14] D. Fudenberg and J. Tirole, *Game Theory*. Cambridge, MA, USA: MIT Press, 1991.
- [15] I. M. Gelfand and S. V. Fomin, *Calculus of Variations*. Mineola, NY, USA: Dover Publications, 2000.
- [16] G. Gigerenzer and R. Selten, Eds., *Bounded Rationality: The Adaptive Toolbox*. Cambridge, MA, USA: MIT Press, 2001.
- [17] H. Gintis, *The Bounds of Reason: Game Theory and the Unification of the Behavioral Sciences*. Princeton, NJ, USA: Princeton Univ. Press, 2009.
- [18] J. I. Gold and M. N. Shadlen, "Banburismus and the brain: decoding the relationship between sensory stimuli, decisions, and reward," *Neuron*, vol. 36, no. 2, pp. 299–308, 2002.
- [19] L. P. Hansen and T. J. Sargent, "Robust Control and Model Uncertainty," *American Economic Review*, vol. 91, no. 2, pp. 60–66, 2001.
- [20] J. Jost, *Riemannian Geometry and Geometric Analysis*, 7th ed. Cham, Switzerland: Springer, 2017.
- [21] D. Kahneman and A. Tversky, "Prospect Theory: An Analysis of Decision under Risk," *Econometrica*, vol. 47, no. 2, pp. 263–292, 1979.
- [22] R. E. Kalman, "A New Approach to Linear Filtering and Prediction Problems," *Journal of Basic Engineering*, vol. 82, no. 1, pp. 35–45, 1960.
- [23] F. E. Kydland and E. C. Prescott, "Time to Build and Aggregate Fluctuations," *Econometrica*, vol. 50, no. 6, pp. 1345–1370, 1982.
- [24] D. Liberzon, *Calculus of Variations and Optimal Control Theory: A Concise Introduction*. Princeton, NJ, USA: Princeton Univ. Press, 2012.
- [25] L. Ljung, *System Identification: Theory for the User*, 2nd ed. Upper Saddle River, NJ, USA: Prentice Hall, 1999.

- [26] L. Ljungqvist and T. J. Sargent, *Recursive Macroeconomic Theory*, 4th ed. Cambridge, MA, USA: MIT Press, 2018.
- [27] J. E. Marsden and T. S. Ratiu, *Introduction to Mechanics and Symmetry*. New York, NY, USA: Springer, 1994.
- [28] R. B. Myerson, *Game Theory: Analysis of Conflict*. Cambridge, MA, USA: Harvard Univ. Press, 1991.
- [29] J. Nash, "The Imbedding Problem for Riemannian Manifolds," *Annals of Mathematics*, vol. 63, no. 1, pp. 20–63, 1956.
- [30] L. S. Pontryagin, V. G. Boltyanskii, R. V. Gamkrelidze, and E. F. Mishchenko, *The Mathematical Theory of Optimal Processes*. New York, NY, USA: Interscience, 1962.
- [31] A. Rubinstein, *Modeling Bounded Rationality*. Cambridge, MA, USA: MIT Press, 1998.
- [32] W. H. Sandholm, *Population Games and Evolutionary Dynamics*. Cambridge, MA, USA: MIT Press, 2010.
- [33] T. J. Sargent, *Bounded Rationality in Macroeconomics*. Oxford, UK: Oxford Univ. Press, 1993.
- [34] H. A. Simon, "Theories of Bounded Rationality," in *Decision and Organization*, C. B. McGuire and R. Radner, Eds. Amsterdam, The Netherlands: North-Holland, 1972.
- [35] C. A. Sims, "Implications of Rational Inattention," *Journal of Monetary Economics*, vol. 50, no. 3, pp. 665–690, 2003.
- [36] E. D. Sontag, *Mathematical Control Theory: Deterministic Finite-Dimensional Systems*, 2nd ed. New York, NY, USA: Springer, 2013.
- [37] N. L. Stokey and R. E. Lucas, Jr., with E. C. Prescott, *Recursive Methods in Economic Dynamics*. Cambridge, MA, USA: Harvard Univ. Press, 1989.
- [38] S. H. Strogatz, *Nonlinear Dynamics and Chaos*, 2nd ed. Boca Raton, FL, USA: CRC Press, 2018.
- [39] R. S. Sutton and A. G. Barto, *Reinforcement Learning: An Introduction*, 2nd ed. Cambridge, MA, USA: MIT Press, 2018.
- [40] E. Todorov and M. I. Jordan, "Optimal feedback control as a theory of motor coordination," *Nature Neuroscience*, vol. 5, no. 11, pp. 1226–1235, 2002.
- [41] J. von Neumann and O. Morgenstern, *Theory of Games and Economic Behavior*. Princeton, NJ, USA: Princeton Univ. Press, 1944.