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University of Minnesota Unofficial Transcript

Name Student ID Ku,Chahyon Lee 5839258 Birthdate 1 - 3

6.00

31.00

0.000 TERM TOTALS:

TERM GPA:

01/31/2024 Print Date: **Graduate Career Totals** MOST RECENT PROGRAMS

CUM GPA: 4.000 UM TOTALS:

University of Minnesota, Twin Cities College of Sci and Engineering Campus

Program
Plan
Degree Sought Robotics M S Master of Science Advisor Desingh,Karthik

***** End of Transcript *****

UM + TRANSFER TOTALS:

* * * * * Beginning of Graduate Record * * * * *

Fall Semester 2022 University of Minnesota, Twin Cities College of Sci and Engineering Robotics M S

Course		Descripti	<u>on</u>	Attempted	Earned	<u>Grade</u>	<u>Points</u>
CSCI	5561	Compute	Computer Vision		3.00	Α	12.000
CSCI	5980	Spec top	ics in CSci	3.00	3.00	Α	12.000
Course Topic:		NLP with	Deep Learning				
EE	5271	Robot Vi	Robot Vision		3.00	Α	12.000
ROB	8970	Robotics	Robotics Colloquium		1.00	S	0.000
TERM GPA :		4.000	TERM TOTALS :	10.00	10.00	9.00	36.000

Attempted Earned Grade

Dointe

Spring Semester 2023 University of Minnesota, Twin Cities College of Sci and Engineering Robotics M S

Course	Description	Attempted	Lameu	Grade	<u>r omts</u>
CSCI 5980	Spec topics in CSci	3.00	3.00	Α	12.000
Course Topic:	Robot Perception and Manip.				
ROB 8777	Thesis Credits Master's	3.00	3.00	NG	0.000
TERM GPA:	4.000 TERM TOTALS :	6.00	6.00	3.00	12.000

Fall Semester 2023

University of Minnesota, Twin Cities College of Sci and Engineering Robotics M S

<u>Course</u>		<u>Description</u>		Attempted	Earned	<u>Grade</u>	<u>Points</u>
CSCI	5527	Deep Learni	ng	3.00	3.00	Α	12.000
CSCI	8980	Spec Adv To	ppics CS	3.00	3.00	Α	12.000
Course Topic:		Perception for	or Field HRI				
ROB	8777	Thesis Credits Master's		3.00	3.00	NG	0.000
TERM GPA:		4.000	TERM TOTALS :	9.00	9.00	6.00	24.000

Spring Semester 2024
University of Minnesota, Twin Cities
College of Sci and Engineering
Robotics M S

Course		<u>Description</u>	Attempted	Earned	<u>Grade</u>	<u>Points</u>
ROB	5994	Directed Research	2.00	0.00		0.000
ROB	8777	Thesis Credits Master's	4.00	0.00		0.000