



Article

# Enhancing Fashion Classification with Vision Transformer (ViT) and Developing Recommendation Fashion Systems Using DINOVA2

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Abstract: As e-commerce platforms grow, consumers increasingly purchase clothes online; however, they often need clarification on clothing choices. Consumers and stores interact through the clothing recommendation system. A recommendation system can help customers to find clothing that they are interested in and can improve turnover. This work has two main goals: enhancing fashion classification and developing a fashion recommendation system. The main objective of fashion classification is to apply a Vision Transformer (ViT) to enhance performance. ViT is a set of transformer blocks; each transformer block consists of two layers: a multi-head self-attention layer and a multilayer perceptron (MLP) layer. The hyperparameters of ViT are configured based on the fashion images dataset. CNN models have different layers, including multiconvolutional layers, multi-max pooling layers, multi-dropout layers, multi-fully connected layers, and batch normalization layers. Furthermore, ViT is compared with different models, i.e., deep CNN models, VGG16, DenseNet-121, Mobilenet, and ResNet50, using different evaluation methods and two fashion image datasets. The ViT model performs the best on the Fashion-MNIST dataset (accuracy = 95.25, precision = 95.20, recall = 95.25, F1-score = 95.20). ViT records the highest performance compared to other models in the fashion product dataset (accuracy = 98.53, precision = 98.42, recall = 98.53, F1-score = 98.46). A recommendation fashion system is developed using Learning Robust Visual Features without Supervision (DINOv2) and a nearest neighbor search that is built in the FAISS library to obtain the top five similarity results for specific images.

**Keywords:** classification of fashion images; Vision Transformer (ViT); deep learning; ensemble learning; stacking; convolutional neural networks; recommendation system



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### 1. Introduction

Artificial intelligence (AI) is one of the most researched topics related to understanding the real world in terms of various data types. AI is applied to different problems, such as classification, object recognition, and recommendation [1,2]. Deep learning (DL) is mainly used to classify images compared with traditional machine learning. Deep learning can automatically extract image features to speed up the processing time [3]. Many researchers use convolutional neural networks (CCN) to improve the performance of image classification applications such as fashion image classification. CNNs are an extension of artificial neural networks (ANNs) [3,4] that can extract more depth features from images using

different layers [5]. Fashion image classification is rapidly expanding with increasing e-commerce and online shopping. Several studies focus on recognition [6], retrieval [7], recommendation [8], and fashion trend prediction [9].

Transformers have proven successful in natural language processing, and new research attempts to apply them directly to images. Due to the necessity of self-attention, every pixel must pay attention to all other pixels. Due to the large number of pixels in images, this is a costly process [10]. Data augmentation plays a pivotal role in reducing overfitting and equipping a Vision Transformer with the capability to handle real-world complexities. Data augmentation includes some transformation operations, such as normalization and random rotation, that enable the model to generalize better and perform effectively under various conditions.

Recommendation systems are machine learning or AI programs that leverage big data based on previous purchases, search history, demographic data, and other aspects to advise or recommend more products to consumers [11–13]. Recommendation systems are valuable since they help users to find products and services that they would not have discovered otherwise. RSS has is in demand in every industry and domain, as satisfying a user's preferences is essential in modern-day business [14]. Image recommendation deals with finding the most similar objects for a given object, where the object is present as an image. A fashion recommendation system involves matching features between fashion products and consumers; it can be defined as a set of criteria used to match fashion products with users or consumers [15,16].

This study has two main goals: enhancing fashion classification and developing a fashion recommendation system. The main objective of fashion classification is to apply a Vision Transformer (ViT) to enhance performance. ViT consists of a set of transformer blocks; each transformer block consists of two layers: a multi-head self-attention layer and a multilayer perceptron (MLP) layer. The hyperparameters of ViT are configured based on a fashion image dataset. CNN models have different layers, including multi-convolutional layers, multi-max pooling layers, multi-dropout layers, multi-fully connected layers, and batch normalization layers. Furthermore, ViT is compared with different models, i.e., deep CNN models, VGG16, DenseNet-121, Mobilenet, and ResNet50, using different evaluation methods and two fashion image datasets.

The main contributions of this work are as follows.

- Applying a Vision Transformer (ViT) to enhance the performance of fashion classification.
- Developing CNN models consisting of different layers of multiple convolutional layers, multiple max pooling, multiple batch normalization, multiple dropouts, flattening, and fully connected layers to compare with the ViT model.
- Developing an efficient and faster recommendation system using the DINOv2 model for feature extraction and FAISS for an efficient nearest neighbor search.
- Testing the recommendation system using private fashion images and fashion product datasets.

The paper is composed as follows. Section 2 presents the related works. Section 3 describes the methodology related to fashion image classification and recommendation. Section 4 discusses the experiments. Section 5 shows the limitations of our work. Finally, Section 6 concludes the paper.

# 2. Literature Review

Many authors have used deep learning models and pre-trained CNN models to classify fashion images, and others have developed a fashion recommendation system.

For the classification of fashion images, Seo, Y., and Shin, K.S [17] proposed Hierarchical Convolutional Neural Networks (H-CNN) with two architectures (VGG16 and VGG19) to classify apparel using the Fashion-MNIST dataset. Results showed that the VGG16 H-CNN model achieved better performance. Kadam et al. [18] used a variety of five architectures with varying convolutional layers, filter sizes, and fully connected layers. Meshkini et al. [19] compared DL architectures to find the best performance in classify-

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ing the Fashion-MNIST dataset. Then, they proposed a simple modification to the best architecture (SqueezeNet) to improve and accelerate the learning process. Duan et al. [20] used several consecutive  $3\times3$  convolution cores to replace the larger convolution cousin AlexNet for the VGG-11 model with a batch normalization layer. The results showed that VGG-11 with the batch normalization layer was more accurate than the original VGG-11. Vijayaraj et al. [21] used two algorithms, CNN and ANN, to address the problem of distinguishing clothing elements in fashion photographs by using the Fashion-MNIST dataset.

Regarding fashion recommendation systems, Chen et al. [11] proposed an intelligent shopping recommender for image searching. They used two CNN models (VGG16 and AlexNet) versus the SVM model to classify the categories of product images. They used Jaccard to calculate the similarity scores between the two images. Tuinhof et al. [13] proposed a recommendation system consisting of a two-stage approach. First, they used a CNN (AlexNet) and the batch-normalized inception (BN inception) classifier to extract features, and then submitted them to the k-NN ranking algorithm and returned the top-N matching style recommendations. Sridevi et al. [15] proposed novel fashion recommendations for the user based on the input given. First, they extracted the features of the image using the ResNet50 classifier, and then uploaded fashion images from a website and generated similar images based on the input image's features and texture. Wazarkar et al. [22] proposed an improved fashion recommendation system using five pre-trained models (VGG, ResNet50, AlexNet, Google Net, and Xception), which recommended fashion items according to the body type of the customer. Khalid et al. [23] proposed a system that recognizes and recommends similar images based on a stacked CNN. The results showed that the stacked CNN model accurately recommended similar photos. Abdul Hussien et al. [24] proposed a recommendation system (RS) to solve RS challenges such as cold starts, sparsity, diversity, and scalability based on a personalized recommendation algorithm. Tayade et al. [25] proposed an intelligent clothing recommendation system based on the VGG16 model and cosine similarity. The results showed that the system performed well in clothing recommendations. Liu et al. [26] proposed a content-based fashion recommendation system based on clothing images' styles using the ResNet-50 model.

# 3. Materials and Methods

The proposed system consists of a classification stage and a recommendation stage, as shown in Figure 1.

### 3.1. Classification Stage

Fashion images are classified using pre-trained models, proposed CNN models, and ViT models.

### **Fashion Image Datasets**

We used two public fashion image datasets, Fashion-MNIST and the fashion product dataset, to train and evaluate the models and develop a recommendation system.

- The Fashion-MNIST dataset [27] consists of grayscale images classified into 10 categories. There are 60,000 images of Zalando's fashion objects in the training dataset and 10,000 examples in the test dataset. Each image is a 48 × 48 grayscale image. Each image in the dataset is associated with a label from 10 classes: t-shirt/top, trouser, pullover, dress, coat, sandal, shirt, sneaker, bag, and ankle boot, and the dataset contains four files: the labels, the images, and the images with labels.
- The fashion product dataset comprises fashion product category samples obtained via Kaggle using this platform [28]. Each sample of an item includes images, data for eight different categories, and the item's name. (1) Gender: male, women, boys, and girls are among the attribute groups. (2) General category: clothing, footwear, sporting goods, and domestic items.

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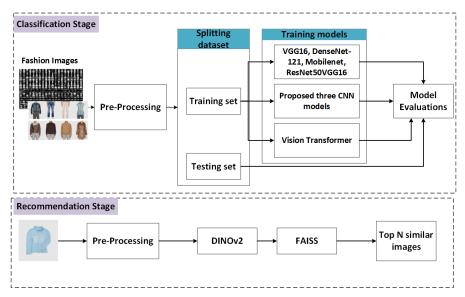


Figure 1. The main stages of classification system.

### 3.2. Pre-Trained CNN Models

- VGG16 is a neural network based on the CNN architecture, which is frequently employed for image classification applications. Thirteen convolutional layers and three fully linked layers comprise the 16 layers that make up VGG16 [29]. Five blocks comprise the convolutional layer arrangement; each has two or three 3 × 3 convolutional layers, followed by a max pooling layer. At the last level, a softmax classifier for classification is followed by fully connected layers with 4096 neurons each [30]. The uniform architecture of VGG16 is characterized by the fact that all convolutional layers and max pooling layers have the same filter size of 3 × 3 with a stride of 1 and 2 × 2 with a stride of 2, respectively [31]. This architecture performs well in various picture classification tasks with simple implementation and tuning tasks.
- DenseNet-121 is based on a convolutional neural network (CNN) architecture and was created by Huang et al. in 2017 to address the vanishing gradient issue in deep neural networks by altering the conventional CNN architecture and streamlining the connectivity pattern across layers [32]. It has been demonstrated that DenseNet-121 performs well in computer vision tasks like object detection and semantic segmentation. The main concept of DenseNet is to connect each feedforward layer to every other layer, rather than merely to the surrounding layers [33].
- MobileNet was created by Google in 2017 as a member of the CNN family. Its architecture was created for successful operation on mobile and embedded devices with constrained computational resources, providing a practical method for the development of deep learning models for mobile applications [34]. MobileNet is built on a simplified architecture that combines depthwise separable convolutions and pointwise convolutions [35].
- ResNet50 is a deep neural network architecture introduced by Microsoft Research in 2015 as part of the residual network (ResNet) family models built around residual learning. Skip connections are employed in residual learning to allow the network to pick up residual functions, which are represented as the difference between an input and an output from a layer [36–38].

## The CNN Models

The CNN models DeepCNN1, DeepCNN2, and DeepCNN3 consist of different layers of multiple convolutional layers, multiple max pooling, multiple batch normalization, multiple dropouts, flatten, and fully connected layers, as shown in Figure 2. The different layers included in CNN models are as follows.

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• The convolutional layer is the CNN's first layer, and its primary component executes convolution processes by utilizing kernel filters. Kernels have more depth than pictures but are smaller [39]. The kernel size and number are two key hyperparameters for convolution processes. Kernels are shared across all picture locations in convolution processes, which also require weight sharing. Weight sharing in convolutional operations has the following properties: (1) kernels can learn local patterns by moving across all image positions; (2) to learn the spatial hierarchies of feature patterns, downsampling and pooling can be used; (3) compared to other neural networks, a fully connected neural network has fewer parameters to determine [39].

- The pooling layer reduces the feature map dimensions, reducing the learning parameters and network computation. It summarizes the features in a region generated by a convolution layer. It is divided into average and maximum pooling [40]. A max pooling method returns the maximum value from a region covered by a kernel in an image. With average pooling, all the values in the kernel image are averaged. Most of the CNNs use the max pooling method [40].
- Flatten layer
- The fully connected layer (FC), consisting of neurons, weights, and biases, links neurons from various layers. A completely connected layer exists between every neuron in the preceding layer, whether fully connected, pooling, or convolutional. Fully connected layers cannot be followed by convolutional layers because they are not spatially localized [41]. The Rectified Linear Unit (ReLU) is an activation function that adds nonlinearity to a deep learning model while addressing the vanishing gradient problem.
- Dropout layers reduce some neurons' connections to the following layer while leaving others alone. Input vectors can be reduced by applying this method. Hidden layers can also be reduced using this method. A dropout layer in CNN training is essential to prevent overfitting [42].
- An output layer that has a number of neurons equal to the number of classes and uses
  the softmax function is used to activate multiclass classification. This step normalizes
  the real output values for the target class to probabilities.

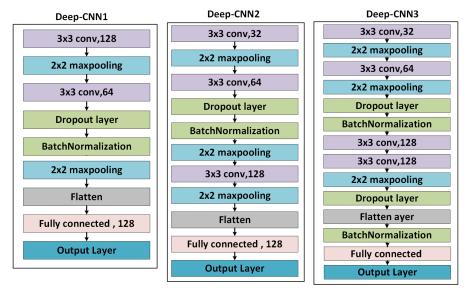


Figure 2. The CNN models.

### 3.3. Vision Transformer (ViT)

ViT has emerged as a compelling alternative to traditional CNNs for image classification. Our study builds upon the foundation laid by Dosovitskiy et al. [43], who demonstrated that a pure transformer applied directly to sequences of image patches can achieve remarkable performance in image classification tasks. Our proposed model

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architecture represents the systematic integration of ViT in image classification. This architectural blueprint unfolds through discrete layers, each meticulously designed to address specific facets of image comprehension and classification.

- 1. Input and Augmentation: The initial stage encompasses the reception of input images with dimensions of  $28 \times 28$  and a single channel. Augmentation techniques are employed, involving normalization, resizing to dimensions, and controlled geometric transformations such as rotations and zooms. This preprocessing stage is paramount, as it ensures both input homogeneity and exposure to a diverse array of visual scenarios, ultimately enhancing model adaptability and generalization. In the augmentation layer, some transformation operations are applied.
  - Input Layer: We define the expected input image shape, ensuring uniformity during training.
  - Normalization: Pixel values are standardized, promoting stable learning by adjusting the mean and standard deviation.
  - Resizing: Images are resized to a consistent dimension, ensuring uniformity and preventing bias due to different image sizes.
  - Random Rotation: A controlled random rotation is introduced, allowing the model to learn from diverse angles of the same object.
  - Random Zoom: Simulating variations in object scales and enriching the dataset.
- 2. Patching and Encoding: The subsequent phase involves partitioning images into non-overlapping patches through the 'patches' layer. These patches are subsequently encoded into 144 discrete patches, each represented by a 64-dimensional embedding facilitated by the 'PatchEncoder'. This step introduces granularity to the image representation, allowing the model to capture localized features effectively.
- 3. Transformer Layers: The heart of the architecture resides within a series of eight transformer layers, each contributing to the gradual transformation of patch embeddings.
  - Layer normalization introduces stabilization before feature extraction.
  - Multi-head self-attention mechanisms facilitate the capture of contextual relationships within and across patches.
  - Skip connections facilitate information flow between consecutive layers.
  - Layer normalization is reintroduced to preserve numerical stability.
  - MLP layers contribute to nonlinearity, aiding in capturing complex patterns.
  - Concluding each layer, another skip connection combines transformed features.
- 4. Flattening and Feature Processing: Following the transformer layers, the narrative transitions to a flattening stage, where the embedding is transformed from a patch-based structure to a linear format. This transformation is augmented by 'dropout' regularization, enhancing the model's resilience to overfitting.
- 5. MLP Head: The subsequent 'MLP head' section consists of two dense layers with 2048 and 1024 hidden units, respectively. This feature processing phase enables the model to refine the abstract representations generated by the transformer layers, facilitating higher-level abstraction and discrimination.
- 6. Output Layer: The ultimate layer consists of a dense output layer with ten units corresponding to the number of classes in the Fashion-MNIST dataset.

## Hyperparameter Configuration

We adapt the transformer-based architecture to process image patches. Our innovation lies in working with our images as chunks of data and feeding them into the model, enabling our model to understand the images and learn from them. The hyperparameter configuration includes image\_size, learning\_rate, weight\_decay, and architectural dimensions. These settings are meticulously adjusted using a guided experimentation process that facilitates optimal performance. These configurations collectively define the architecture and hyperparameters of the ViT model. They influence how the model processes and learns from the input data, ultimately affecting its performance.

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- input\_size refers to the size of a single side of the input image;
- input\_shape specifies the shape of the input data for the model; for grayscale images, the shape is defined as (height, width, channels), where the number of channels is 1;
- learning\_rate determines the step size at which the model adjusts its parameters during training;
- weight decay is a regularization technique that discourages large weights in the model; it adds a penalty term to the loss function based on the magnitude of the weights, which helps to prevent overfitting;
- batch\_size indicates how many images are processed together in a single iteration of training; the value of batch\_size is 256;
- num\_epochs is the number of times that the entire dataset is used to train the model; each pass through the dataset is called an epoch; the value of num\_epochs is 30;
- image\_size means that the size of the input images is resized before being processed by the model; larger image sizes can capture more details but might require more computation; the value of image\_size is 7;
- projection\_dim is the dimensionality of the projected feature embeddings in the transformer; this parameter controls the size of the intermediate representations in the transformer layers; the value of projection\_dim is 64;
- num\_heads is the number of attention heads in the multi-head self-attention mechanism;
   more heads allow the model to focus on different input parts simultaneously;
- transformer\_units is the dimensionality of the feedforward sub-layers within each transformer block; it is a list representing the number of neurons in each feedforward layer;
- transformer\_layers is the number of transformer blocks stacked on top of each other; each block consists of multi-head self-attention and feedforward layers;
- mlp\_head\_units means that the architecture of the multilayer perceptron (MLP) head takes the transformer outputs and processes them for the final classification; it is a list representing the number of neurons in each MLP layer.

### 3.4. Fashion Recommendation System

RS is a software tool and a method of presenting suggestions and recommendations for items that users will find helpful. In addition to buying, watching, listening to, or reading news, users make many other decisions related to these suggestions. Different applications have been developed with recommendation systems. Systems that recommend items aim to match the user's needs with items that fit their needs [44]. It provides the best outfit combinations for users lacking fashion knowledge [45]. There are different traditional approaches to developing a recommendation system, such as cosine similarity and Pearson correlation. We develop an efficient and faster recommendation system using the DINOv2 model for feature extraction and FAISS for an efficient nearest neighbor search.

- Cosine similarity provides a helpful indicator of how similar two objects are. It is a straightforward mathematical tool to understand and apply computationally. Cosine similarity is a metric that may be applied in recommendation systems and is based on the cosine distance between two objects [46]. It serves as a distance measurement metric between two places in the plane and is represented as the cosine of the angle between two vectors [46].
- Pearson correlation is the linear correlation between two sets of data. It is effectively a normalized measurement of the covariance, with the result always falling between 0 and 1 [47]. It is the ratio between the covariance of two variables and the product of their standard deviations. The measure can only depict a linear connection of variables, similar to covariance itself [48]. It is determined as the ratio between the covariance of the two sample variables and the product of their standard deviations, where a and b are the individual sample points indexed with i [49].
- The Euclidean distance between two users is determined by the length of the connecting line segments. Available items make up the preference area, and user-rated items make up the axes. We look for products that customers with similar tastes favor based

on user evaluations [50]. The likelihood that two people will appreciate comparable items increases with decreasing distance [51].

The Proposed Recommendation System Using DINOv2 Model and FAISS

This section outlines the methodology used to implement the recommendation system using the DINOv2 model for feature extraction and FAISS for an efficient nearest neighbor search. This methodology aims to demonstrate the effectiveness of DINOv2 features in retrieving nearest neighbor images from a given dataset.

Firstly, we employ the Gradio library [52] to create a user-friendly interface for interaction with the instance retrieval system. The interface allows users to upload images and immediately visualize the nearest neighbor images retrieved from the dataset. There are several main steps required to build a recommendation system, as shown in Figure 3.

- 1. The interface allows users to upload an image, and then some of the transformation operations, such as resizing, tensor conversion, and normalization, are applied to the input image. Then, the extract\_features function that is built into the DINOv2 model is applied to the transformed image to extract the features of the input image.
- 2. We apply a nearest neighbor search with flat L2 index (Euclidean) distances to retrieve the similarity images from the database that is built in the FAISS library [53]. FAISS contains several similarity search methods. It assumes that the instances are represented as vectors and identified by an integer. The vectors can be compared with L2 (Euclidean) distances or dot products. Similar vectors are those with the lowest L2 distance or the highest dot product with the query vector. Our approach employs the FAISS library for an efficient nearest neighbor search. Central to this efficiency is the utilization of a flat L2 index. This data structure allows for the rapid retrieval of nearest neighbors based on Euclidean distances in the feature space. The following steps outline the process.
  - Index Creation: The feature vectors of the dataset images are indexed using the flat L2 index structure. This step preprocesses the dataset to facilitate quick distance calculations.
  - Distance Calculation: Given a query image's feature vector, the flat L2 index computes the Euclidean distances between the query vector and all indexed vectors in the dataset.
  - Nearest Neighbor Identification: The index identifies the indices of dataset vectors with the smallest Euclidean distances to the query vector. These indices correspond to the nearest neighbor images.
  - Retrieval: The images associated with the nearest neighbor indices are retrieved from the dataset. These retrieved images are the nearest neighbors of the query image.

# Input image Retrieved image The state of images Retrieved image

Figure 3. Example of steps of recommendation system.

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# 4. Experimental Results

## 4.1. Experimental Setup

In our study, we implemented the CNNs and pre-trained models using Keras, its Python API, running on a desktop PC with an Intel i7-6850K CPU and an NVIDIA GPU. The datasets were split into an 80% training set and a 20% testing set. We adapted some parameters for the CNN and pre-trained models: the number of epochs was 50, the activation function was softmax, the optimizer was Adam, and the loss function was categorical\_crossentropy, with learning rate = 0.1. In the ViT model, some of the hyperparameters were adapted as shown in Table 1.

**Table 1.** Hyperparameter configuration for ViT model.

Parameter	Value	
input_size	28	
learning_rate	0.001	
weight_decay	0.0001	
batch_size	256	
num_epochs	50	
image_size	72	
num_patches	(72 // 6) × 2	
projection_dim	64	
num_heads	4	
transformer_units	$[64 \times 2, 64]$	
transformer_layers	8	
mlp_head_units	[2048, 1024]	
normalization		
resizing	ring 72 × 72	
random rotation	0.02	
random zoom	0.02	
loss function	categorical_crossentropy	
activation function	softmax	

# **Evaluating Models**

Accuracy, precision, recall, the F1-score, the AUC, and ROC curves are metrics used to assess classification performance, as well as positive and negative predictions (TP and FP). TN refers to the true negative state, FN refers to the false negative state, TP refers to the true positive state, and FP refers to the false positive state, as demonstrated.

Accuracy: During the classification of correctly classified instances, it shows the
percentage of instances that are correctly classified.

$$Accuracy = \frac{TP + TN}{TP + FP + TN + FN}. (1)$$

Precision: The ratio between true positives and all positives.

$$Precision = \frac{TP}{TP + FP} \tag{2}$$

The recall measures a model's ability to correctly identify true positives.

$$Recall = \frac{TP}{TP + FN} \tag{3}$$

• F1-score: The precision and recall of the test values are used to calculate the F1-score.

$$F1\text{-}score = \frac{2 \cdot precision \cdot recall}{precision + recall} \tag{4}$$

Receiver operating characteristic curves (ROC) show how well classification models
categorize data. It uses both the true positive and false positive parameters.
In the case of true positives (TPR), commonly known as recall,

True positive = 
$$\frac{\text{True positive}}{\text{True positive} + \text{False negative}}$$
 (5)

FPR stands for the false positive rate, and it is defined as follows:

False positive 
$$=$$
  $\frac{\text{False positive}}{\text{False positive} + \text{True negative}}$  (6)

On ROC curves, TPR and FPR are plotted against categorization levels. By lowering the categorization threshold, more items are classified as positive or false positive. As a result, both false positives and true positives increase.

## 4.2. The Results of Fashion-MNIST Dataset

This section compares the proposed stake model with other models. The results of models applied to Fashion-MNIST are shown in Table 2. As shown, the ViT model showed the highest performance (accuracy = 95.25, precision = 95.20, recall = 95.25, F1-score = 95.20), whereas Mobilenet showed the lowest performance (accuracy = 58.92, precision = 58.37, recall = 58.92, F1-score = 58.20).

We can see that the proposed CNN models recorded the highest performance compared to pre-trained models. Deep-CNN3 achieved the highest performance in terms of accuracy, precision, recall, and F1-score at 92.25, 92.36, 92.25, and 92.23, respectively, compared to DeepCNN1 and DeepCNN2. The ViT model improved the performance by 2% to 4% compared to the CNN models.

Figure 4 shows the ROC curve and AUC of DeepCNN3 for each class. Figure 5 shows each class's ROC curve and AUC for the ViT model. The ROC curve is a graphical representation of a model's performance across various threshold values for classification. It plots the true positive rate (TPR) against the false positive rate (FPR) as the threshold changes. The AUC is a single scalar value that quantifies the model's overall performance. It represents the area under the ROC curve. We can see that the ROC curve for the ViT model shows the strong ability of the model to distinguish between positive and negative classes at different thresholds. ViT recorded the highest AUC for each class compared to DeepCNN3. For ViT, the AUC of eight classes was 1.00, and the AUC of two classes was 0.99, while the AUC of six classes was 100, the AUC of three classes was 0.99, and that of one class was 0.98.

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Table 7	The reculte	of Hachion	-1/11/11/51	dataset

Approach	Model	Accuracy	Precision	Recall	F1-Score
Pre-trained models	VGG16	89.29	89.21	89.29	89.19
	DenseNet-121	88.00	88.11	88.0	87.84
	Mobilenet	58.92	58.37	58.92	58.20
	ResNet50	84.53	84.69	84.53	84.38
Proposed CNN models	DeepCNN1	91.92	91.97	91.92	91.91
	Deep-CNN2	91.90	91.91	91.9	91.89
	Deep-CNN3	92.25	92.36	92.25	92.23
Transformer model	ViT	95.25	95.20	95.25	95.20

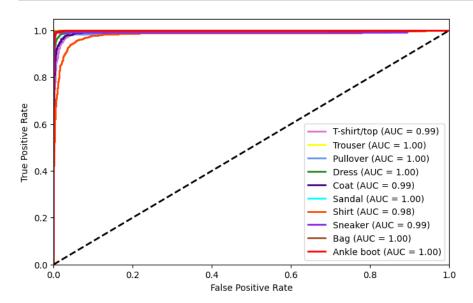


Figure 4. The ROC for DeepCNN3 model for Fashion-MNIST dataset.

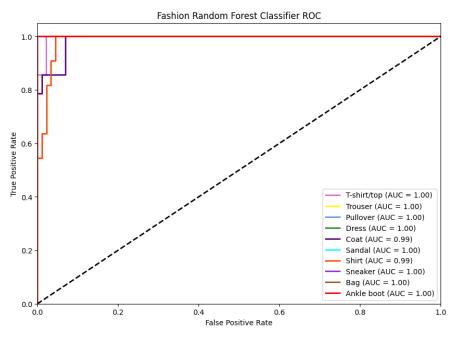


Figure 5. The ROC for ViT model for Fashion-MNIST dataset.

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### 4.3. The Results of Fashion Product Dataset

This section compares the proposed stake model with other models. The results of models applied to the fashion product dataset are shown in Table 3. As shown, ViT scored the highest results (accuracy = 98.76, precision = 98.50, recall = 98.76, F1-score = 98.50), whereas Mobilenet achieved the lowest results (accuracy = 75.55, precision = 75.82, recall = 75.69, F1-score = 75.55).

Approach	Model	Accuracy	Precision	Recall	F1-Score
Pre-trained model	VGG16	84.80	85.3	90.40	80.90
	DenseNet-121	77.66	77.918	78.75	77.11
	Mobilenet	75.55	75. 82	75.69	75.55
	ResNet50	82.23	82.53	82.23	82.53
Proposed CNN models	DeepCNN1	96.91	96.74	96.91	97.82
	Deep-CNN2	96.14	96.56	96.15	96.33
	Deep-CNN3	97.09	97.95	97.09	97.01
Transformer model	ViT	98.76	98.50	98.76	98.50

**Table 3.** The results of fashion product dataset.

We can see that the proposed CNN models recorded the highest performance compared to pre-trained models. Deep-CNN3 achieved the highest performance (accuracy = 97.09, precision = 97.95, recall = 97.09, F1-score = 97.01) compared to DeepCNN1 and DeepCNN2. The ViT model improved the performance by 1% to 2% compared to CNN models.

Figure 6 shows the ROC curve and AUC of DeepCNN3 for each class. Figure 7 shows each class's ROC curve and the AUC of the ViT model. The ROC curve is a graphical representation of a model's performance across various threshold values for classification. It plots the true positive rate (TPR) against the false positive rate (FPR) as the threshold changes. The AUC is a single scalar value that quantifies the model's overall performance. It represents the area under the ROC curve. We can see that the ROC curve for the ViT model shows the strong ability of the model to distinguish between positive and negative classes at different thresholds. ViT recorded the highest AUC for each class compared to DeepCNN3. For ViT, the AUC of five classes was 1.00, and the AUC of one class was 0.87.

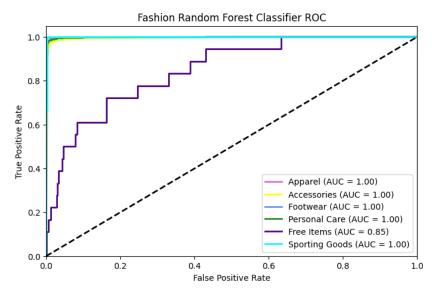


Figure 6. The ROC for DeepCNN3 model for fashion product dataset.

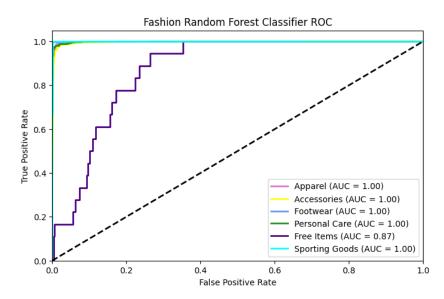


Figure 7. The ROC for ViT model for fashion product dataset.

# 4.4. The Best Models for Two Datasets

Figure 8 shows the best models for the Fashion-MNIST dataset. The highest results were recorded by ViT (accuracy = 95.25, precision = 95.20, recall = 95.25, F1-score = 95.20). The worst average rate was recorded by VGG16 (accuracy = 89.29, precision = 89.21, recall = 89.29, F1-score = 89.19).

Figure 9 shows the best models for the fashion product dataset. The highest results were recorded by ViT (accuracy = 98.76, precision = 98.50, recall = 98.76, F1-score = 98.50). The lowest were recorded by VGG16 (accuracy = 84.8, precision = 85.30, recall = 90.40, F1-score = 80.90).

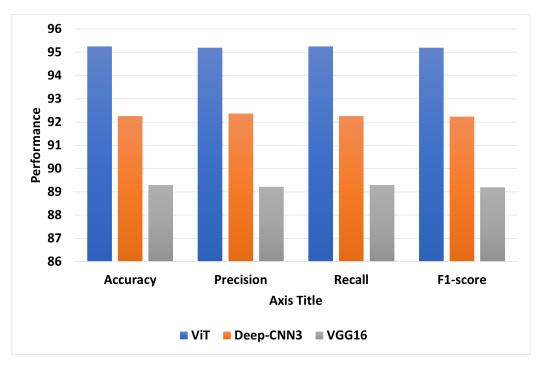
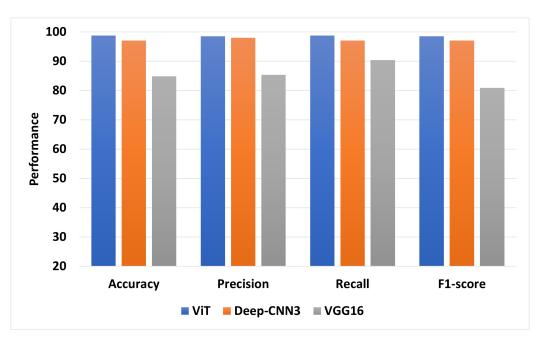


Figure 8. The best models for Fashion-MNIST dataset.



**Figure 9.** The best models for fashion product dataset.

## 4.5. Comparing the Proposed Model with Previous Studies

We compared the proposed model with other models, as shown in Table 4. The ViT models for the two datasets recorded the highest accuracy compared to other models. For Fashion-MNIST, the VGG16 H-CNN recorded 93% For fashion product images, ResNet-50 recorded 86.24% accuracy in [26]. In [54], the authors used a DNN with 83.29% accuracy.

Paper	Dataset	Model	Performance
[17]	Fashion-MNIST	VGG16 H-CNN	Accuracy = 93
[18]	Fashion-MNIST	CNN	Accuracy = 93.5
[19]	Fashion-MNIST	SqueezeNet	Accuracy = 93.50
[20]	Fashion-MNIST	VGG-11	Accuracy = 91.5
[21]	Fashion-MNIST	CNN	Accuracy = 90
[55]	Fashion-MNIST	MCNN15	Accuracy = 94.04
[26]	Fashion Product Images	ResNet-50	Accuracy = 86.24
[54]	Fashion Product Images	DNN	Accuracy = 83.29
[56]	Fashion Product Images	VGG16	Accuracy = 83.96
Our work	Fashion-MNIST	ViT	Accuracy = 95.25
Our work	Fashion Product Images	ViT	Accuracy = 98.76

**Table 4.** Comparing the proposed model with previous studies.

### Fashion Recommendation System Using DINOVA2

We test the fashion recommendation system using a private custom fashion image dataset collected from different resources and including different main categories, such as pullovers, shirts, trousers, watches, and shoes. We build an interface using the Gradio library [52] to allow users to upload images and visualize the retrieved similarity results, as shown in Figure 10. The coding of the fashion recommendation system has been uploaded to GitHub [57].

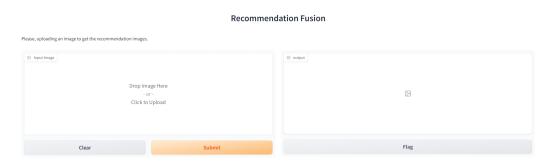


Figure 10. Interface of recommendation system.

The main steps are as follows. (1) The user uploads images, and transformation operations such as resizing, tensor conversion, and normalization are applied to the input image; then, the extract\_features function that is built into the DINOv2 model is applied to the transformed image to extract the features of the input image. (2) The similarity between the input image and the images from the database is calculated by the nearest neighbor search function that is built into the FAISS library with flat L2. It utilizes flat L2, a data structure that allows the rapid retrieval of nearest neighbors based on the Euclidean distances in the feature space. Using the flat L2 index significantly enhances the efficiency of the nearest neighbor search process, allowing for faster and more effective instance retrieval. Figures 11–13 show examples of images that were uploaded, and the recommendation fashion system retrieved similar images.

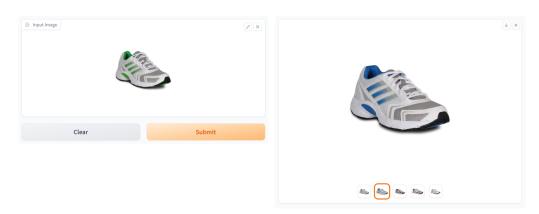
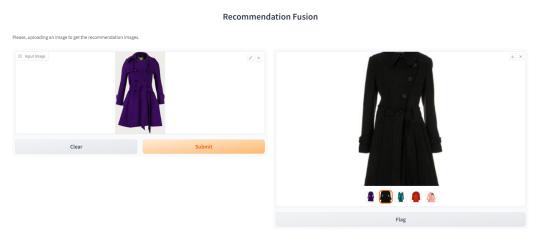


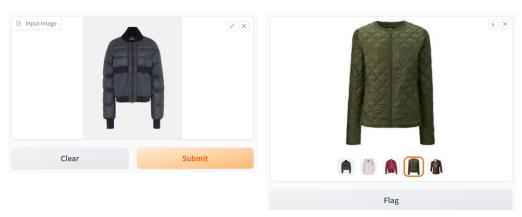
Figure 11. Example 1 of fashion recommendation system.



**Figure 12.** Example 2 of fashion recommendation system.

### **Recommendation Fusion**

Please, uploading an image to get the recommendation images.



**Figure 13.** Example 3 of fashion recommendation system.

### 5. Limitations

Despite the importance of our proposed model, it may bring several challenges related to the dataset and the implementation of the model, which could be summarized as follows.

- The performance of recommendation systems heavily relies on the availability and quality of data. One limitation is that our proposed system's effectiveness is contingent upon the availability of comprehensive and accurate data related to user preferences, item characteristics, and user–item interactions. Limited or biased data can impact the system's ability to generate accurate and diverse recommendations.
- The proposed system may face challenges in scenarios where there are limited or no
  historical data available for new users or items, which makes it difficult to personalize
  recommendations for users who have recently joined the platform or for new items
  that have a limited interaction history.
- As the user base and item catalog grow, the scalability of the recommendation system becomes crucial. The proposed system's performance and efficiency might be affected when dealing with large-scale datasets and a high volume of concurrent user interactions.
- Our proposed system aims to provide accurate recommendations; ensuring diversity
  in the recommended items is also important. The system may have limitations in
  terms of generating diverse recommendations, which can impact user satisfaction
  and engagement.
- Although our research focused on the development and evaluation of the recommendation system, we did not conduct specific user feedback or evaluation experiments.
   Gathering direct user feedback and conducting user studies to assess user satisfaction, preferences, and system usability would provide valuable insights and further validate the effectiveness of the proposed system.

### 6. Conclusions

The study's primary goal was to apply a Vision Transformer (ViT) to enhance the performance of the classification of fashion images using two public datasets. ViT is a set of transformer blocks consisting of a multi-head self-attention layer and a multilayer perceptron (MLP) layer. The hyperparameters of the ViT model were adapted to enhance the performance of the models. The ViT models were compared with CNN models and pre-trained models. CNN models consist of different layers, i.e., convolutional layers, multi-max pooling layers, multi-dropout layers, multi-fully connected layers, and a batch normalization layer. Accuracy, precision, recall, the F1-score, and the AUC were used to evaluate the models. The results showed that the proposed models achieved the highest

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performance values for two datasets. For the Fashion-MNIST dataset, ViT showed the highest performance (accuracy = 95.25, precision = 95.20, recall = 95.25, F1-score = 95.20) compared to other models. For the fashion product dataset, ViT LR showed the highest performance (accuracy = 98.53, precision = 98.42, recall = 98.53, F1-score = 98.46) compared to other models. A fashion recommendation system was developed using Learning Robust Visual Features without Supervision (DINOv2) and a nearest neighbor search built into the FAISS library to retrieve the top five similar images for specific images. The future work directions are as follows. (1) Conducting user studies and gathering direct user feedback are crucial steps to evaluate the proposed recommendation system. This can involve collecting user satisfaction ratings, conducting surveys or interviews to understand user preferences and perceptions, and comparing the system's recommendations with user expectations. Incorporating user feedback will provide valuable insights for further refinement and improvement. (2) We could consider incorporating contextual information such as temporal dynamics, location, or social connections into the recommendation system. Context-aware recommendation algorithms can enhance the system's ability to provide personalized and relevant recommendations by considering the situational context in which users interact with the system. (3) We could explore hybrid recommendation approaches that combine the strengths of different models or techniques. This could involve integrating content-based and collaborative filtering methods or combining deep learning models with traditional recommendation algorithms. (4) We could investigate methods to enhance the explainability and transparency of the recommendation system. Users often desire explanations as to why specific items are recommended to them. (5) We will consider evaluating the models using the Matthews correlation coefficient (MCC). (6) We intend to analyze the model from the complexity analysis perspective to ensure efficiency.

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