ep-neural-network-vs-mf-with-keras

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1 Practice: Deep neural network vs MF with Keras

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M2 IAII

In this lab I use just 10M from 20M dataset

1.1 1. Dataset Loading and Preprocessing

dataset:

```
userId movieId rating movie_idx
0
       0
                1
                       3.5
1
        0
                28
                       3.5
                                   29
2
        0
                31
                       3.5
                                   32
3
        0
                45
                       3.5
                                   47
                48
                       3.5
                                   50
```

```
[21]: # Step 4: Preprocess the data
# Label encode user and movie IDs for compatibility with neural networks
user_encoder = LabelEncoder()
movie_encoder = LabelEncoder()
```

Training data shape: (80000, 4) Testing data shape: (20000, 4)

1.2 2. Matrix Factorization (MF) with Keras:

702 8227

```
[31]: embedding_size = 50  # You can adjust this based on your requirements

# Input layers
user_input = Input(shape=(1,), name='user_input')
movie_input = Input(shape=(1,), name='movie_input')

# Embedding layers
user_embedding = Embedding(input_dim=n_users, output_dim=embedding_size,___
input_length=1, name='user_embedding')(user_input)
```

```
movie_embedding = Embedding(input_dim=n_movies, output_dim=embedding_size,_
input_length=1, name='movie_embedding')(movie_input)

# Dot product layer
dot_product = Dot(axes=2, name='dot_product')([user_embedding, movie_embedding])
dot_product_flat = Flatten(name='dot_product_flat')(dot_product)

# Model
model_MF = Model(inputs=[user_input, movie_input], outputs=dot_product_flat)
model_MF.compile(optimizer=Adam(lr=0.001), loss='mean_squared_error',_
emetrics=[MeanSquaredError()])

# Display the model summary
print(model_MF.summary())
```

WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning_rate` or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.

Model: "model_5"

Layer (type)	Output Shape	Param #	Connected to
=======================================			
<pre>user_input (InputLayer)</pre>	[(None, 1)]	0	
<pre>movie_input (InputLayer)</pre>	[(None, 1)]	0	[]
<pre>user_embedding (Embedding) ['user_input[0][0]']</pre>	(None, 1, 50)	35100	
<pre>movie_embedding (Embedding ['movie_input[0][0]'])</pre>	(None, 1, 50)	411350	
<pre>dot_product (Dot) ['user_embedding[0][0]', 'movie_embedding[0][0]']</pre>	(None, 1, 1)	0	
<pre>dot_product_flat (Flatten) ['dot_product[0][0]']</pre>	(None, 1)	0	

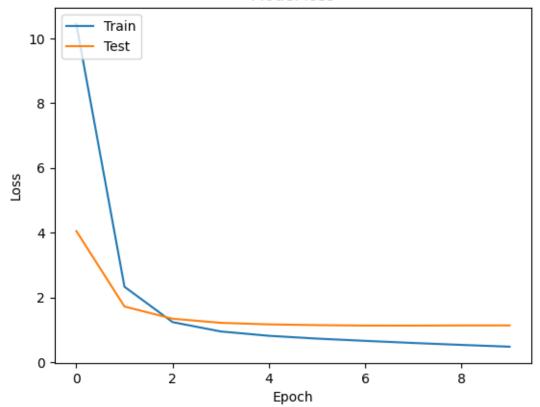
Total params: 446450 (1.70 MB)
Trainable params: 446450 (1.70 MB)
Non-trainable params: 0 (0.00 Byte)

```
None
[32]: # Step 8: Train the MF model on the training set
    history_MF = model_MF.fit([train_data['userId'], train_data['movieId']],_u
    ⇔train_data['rating'],
                 epochs=10, batch_size=64,_
    →validation_data=([test_data['userId'], test_data['movieId']],
     ⇔test_data['rating']))
   Epoch 1/10
   mean_squared_error: 10.5937 - val_loss: 4.1341 - val_mean_squared_error: 4.1341
   Epoch 2/10
   mean squared error: 2.3600 - val loss: 1.7323 - val mean squared error: 1.7323
   Epoch 3/10
   mean_squared_error: 1.2432 - val_loss: 1.3435 - val_mean_squared_error: 1.3435
   Epoch 4/10
   1250/1250 [============ ] - 4s 3ms/step - loss: 0.9488 -
   mean_squared_error: 0.9488 - val_loss: 1.2229 - val_mean_squared_error: 1.2229
   Epoch 5/10
   mean_squared error: 0.8155 - val_loss: 1.1700 - val_mean_squared error: 1.1700
   mean_squared_error: 0.7281 - val_loss: 1.1484 - val_mean_squared_error: 1.1484
   mean_squared_error: 0.6586 - val_loss: 1.1338 - val_mean_squared_error: 1.1338
   Epoch 8/10
   mean_squared_error: 0.5946 - val_loss: 1.1306 - val_mean_squared_error: 1.1306
   Epoch 9/10
   mean_squared_error: 0.5333 - val_loss: 1.1362 - val_mean_squared_error: 1.1362
   Epoch 10/10
   mean_squared_error: 0.4769 - val_loss: 1.1391 - val_mean_squared_error: 1.1391
[33]: # Step 9: Evaluate the model's performance on the test set
    test_loss = model_MF.evaluate([test_data['userId'], test_data['movieId']],_u
    →test_data['rating'])
```

print(f"\nTest Loss: {test_loss[0]}, Test MSE: {test_loss[1]}")

Test Loss: 1.139132022857666, Test MSE: 1.139132022857666

Model loss



1.3 3. Deep Neural Network (DNN) Recommender

```
[27]: from keras.models import Model
     from keras.layers import Input, Embedding, Flatten, Dense, Concatenate
     from keras.optimizers import Adam
     from keras.metrics import MeanSquaredError
     # Step 11: Design a Deep Neural Network architecture for recommendation
     embedding size = 50
     dense_units = 128
     # Input layers
     user_input_dnn = Input(shape=(1,), name='user_input_dnn')
     movie_input_dnn = Input(shape=(1,), name='movie_input_dnn')
     # Embedding layers
     user_embedding_dnn = Embedding(input_dim=n_users, output_dim=embedding_size,_
       movie_embedding_dnn = Embedding(input_dim=n_movies, output_dim=embedding_size,__
       →input_length=1, name='movie_embedding_dnn')(movie_input_dnn)
     # Flatten embeddings
     user_flat_dnn = Flatten(name='user_flat_dnn')(user_embedding_dnn)
     movie_flat_dnn = Flatten(name='movie_flat_dnn')(movie_embedding_dnn)
     # Concatenate flattened embeddings
     concatenated_dnn = Concatenate(name='concatenated_dnn')([user_flat_dnn,__
       →movie_flat_dnn])
     # Dense layers
     dense1 = Dense(units=dense_units, activation='relu',_
       →name='dense1')(concatenated_dnn)
     dense2 = Dense(units=dense units, activation='relu', name='dense2')(dense1)
     # Output layer
     output_dnn = Dense(units=1, activation='linear', name='output_dnn')(dense2)
     # Model
     model_dnn = Model(inputs=[user_input_dnn, movie_input_dnn], outputs=output_dnn)
     model_dnn.compile(optimizer=Adam(lr=0.001), loss='mean_squared_error',u
       →metrics=[MeanSquaredError()])
     # Display the DNN model summary
     print(model_dnn.summary())
```

WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning_rate` or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.

Model: "model_4"

None

Layer (type)	Output Shape	=======		Connected to
<pre>user_input_dnn (InputLayer)</pre>	[(None, 1)]		0	[]
<pre>movie_input_dnn (InputLaye r)</pre>	[(None, 1)]		0	[]
<pre>user_embedding_dnn (Embedd ['user_input_dnn[0][0]'] ing)</pre>	(None, 1, 50)		35100	
<pre>movie_embedding_dnn (Embed ['movie_input_dnn[0][0]'] ding)</pre>	(None, 1, 50)		411350	
<pre>user_flat_dnn (Flatten) ['user_embedding_dnn[0][0]']</pre>	(None, 50)		0	
<pre>movie_flat_dnn (Flatten) ['movie_embedding_dnn[0][0]'</pre>	(None, 50)		0	
<pre>concatenated_dnn (Concaten ['user_flat_dnn[0][0]', ate) 'movie_flat_dnn[0][0]']</pre>	(None, 100)		0	
<pre>dense1 (Dense) ['concatenated_dnn[0][0]']</pre>	(None, 128)		12928	
dense2 (Dense) ['dense1[0][0]']	(None, 128)		16512	
<pre>output_dnn (Dense) ['dense2[0][0]']</pre>	(None, 1)		129	
		========		
Total params: 476019 (1.82 M Trainable params: 476019 (1. Non-trainable params: 0 (0.0	32 MB)			

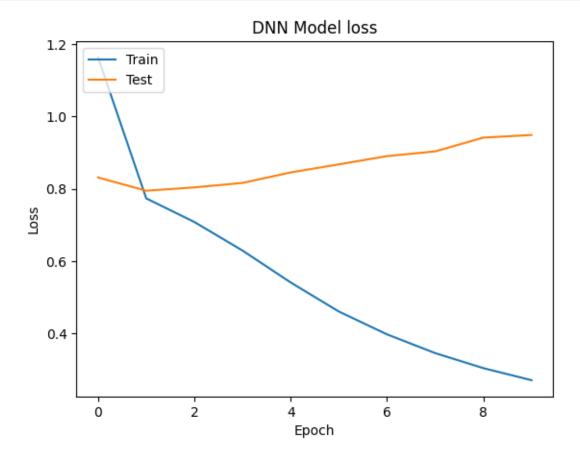
7

```
[28]: # Step 12: Train the DNN model on the training set
    history_dnn = model_dnn.fit([train_data['userId'], train_data['movieId']],__
     epochs=10, batch size=64,
     ⇔validation_data=([test_data['userId'], test_data['movieId']],
     ⇔test_data['rating']))
   Epoch 1/10
   mean_squared_error: 1.1634 - val_loss: 0.8315 - val_mean_squared_error: 0.8315
   Epoch 2/10
   mean_squared_error: 0.7737 - val_loss: 0.7949 - val_mean_squared_error: 0.7949
   Epoch 3/10
   mean_squared_error: 0.7083 - val_loss: 0.8040 - val_mean_squared_error: 0.8040
   Epoch 4/10
   mean_squared_error: 0.6293 - val_loss: 0.8164 - val_mean_squared_error: 0.8164
   Epoch 5/10
   1250/1250 [============= ] - 4s 3ms/step - loss: 0.5411 -
   mean_squared_error: 0.5411 - val_loss: 0.8454 - val_mean_squared_error: 0.8454
   Epoch 6/10
   mean_squared_error: 0.4608 - val_loss: 0.8678 - val_mean_squared_error: 0.8678
   Epoch 7/10
   mean_squared_error: 0.3976 - val_loss: 0.8905 - val_mean_squared_error: 0.8905
   Epoch 8/10
   1250/1250 [============= ] - 5s 4ms/step - loss: 0.3458 -
   mean_squared_error: 0.3458 - val_loss: 0.9037 - val_mean_squared_error: 0.9037
   Epoch 9/10
   mean_squared error: 0.3042 - val_loss: 0.9417 - val_mean_squared error: 0.9417
   Epoch 10/10
   mean_squared_error: 0.2708 - val_loss: 0.9490 - val_mean_squared_error: 0.9490
[29]: # Step 13: Evaluate the DNN model on the test set
    test_loss_dnn = model_dnn.evaluate([test_data['userId'], test_data['movieId']],u
    print(f"\nDNN Test Loss: {test_loss_dnn[0]}, DNN Test MSE: {test_loss_dnn[1]}")
   625/625 [============ ] - 1s 2ms/step - loss: 0.9490 -
   mean_squared_error: 0.9490
   DNN Test Loss: 0.9489825963973999, DNN Test MSE: 0.9489825963973999
```

```
[30]: # Step 14: Visualize and analyze the results

# You can use the 'history_dnn' object to plot training and validation loss
over epochs

# Plot training & validation loss values
plt.plot(history_dnn.history['loss'])
plt.plot(history_dnn.history['val_loss'])
plt.title('DNN Model loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



1.4 4. Model Comparison

```
[34]: # Assuming the models are already trained and evaluated
# model: Matrix Factorization
# model_dnn: Deep Neural Network
```

DNN Test Loss: 0.9489825963973999, DNN Test MSE: 0.9489825963973999

1.5 Observations and Discussion:

- 1. Performance Improvement with DNN:
- The DNN model has a lower test loss and MSE compared to the MF model.
- Lower MSE indicates that the DNN model is making more accurate .
- predictions on the test set.
- 2. Complexity of DNN Model:
- The DNN model, with its multiple layers and non-linear activation functions, has the capacity to capture more complex patterns and relationships in the data compared to the simpler MF model.

Interpreting MSE:

• MSE is a measure of how well the model's predictions match the actual ratings. A lower MSE indicates that the model is closer to the true ratings on average.

According to the result shown of the LOSS and Mean squared error values the Deep Neural Network performe better than Matrix Factorization for this dataset

1.6 Hyperparameter Tuning for DNN Model:

```
[36]: from keras.optimizers import Adam
from keras.callbacks import EarlyStopping
from keras.layers import Dropout

# Example hyperparameters (you can adjust these)
dense_units = 128
dropout_rate = 0.3
```

```
learning_rate = 0.001
# Modify the DNN model with updated hyperparameters
user_input_dnn = Input(shape=(1,), name='user_input_dnn')
movie_input_dnn = Input(shape=(1,), name='movie_input_dnn')
user_embedding_dnn = Embedding(input_dim=n_users, output_dim=embedding_size,_
 →input_length=1, name='user_embedding_dnn')(user_input_dnn)
movie_embedding_dnn = Embedding(input_dim=n_movies, output_dim=embedding_size,_
 →input_length=1, name='movie_embedding_dnn')(movie_input_dnn)
user_flat_dnn = Flatten(name='user_flat_dnn')(user_embedding_dnn)
movie_flat_dnn = Flatten(name='movie_flat_dnn')(movie_embedding_dnn)
concatenated dnn = Concatenate(name='concatenated dnn')([user flat dnn, |
 →movie_flat_dnn])
dense1 = Dense(units=dense_units, activation='relu', __
 →name='dense1')(concatenated_dnn)
dropout1 = Dropout(rate=dropout_rate, name='dropout1')(dense1)
dense2 = Dense(units=dense_units, activation='relu', name='dense2')(dropout1)
output_dnn = Dense(units=1, activation='linear', name='output_dnn')(dense2)
model dnn tuned = Model(inputs=[user input dnn, movie input dnn],
 →outputs=output_dnn)
optimizer = Adam(lr=learning_rate)
model_dnn_tuned.compile(optimizer=optimizer, loss='mean_squared_error',_
 →metrics=[MeanSquaredError()])
# Use early stopping to prevent overfitting
early_stopping = EarlyStopping(monitor='val_loss', patience=3,__
 →restore_best_weights=True)
# Train the tuned DNN model
history_dnn_tuned = model_dnn_tuned.fit(
    [train data['userId'], train data['movieId']], train data['rating'],
    epochs=20, batch_size=64, validation_data=([test_data['userId'],__
 →test_data['movieId']], test_data['rating']),
    callbacks=[early_stopping]
)
WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning_rate`
or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.
Epoch 1/20
mean_squared_error: 1.1804 - val_loss: 0.8272 - val_mean_squared_error: 0.8272
Epoch 2/20
mean_squared_error: 0.8096 - val_loss: 0.7963 - val_mean_squared_error: 0.7963
Epoch 3/20
```

Tuned DNN Test Loss: 0.7962550520896912, Tuned DNN Test MSE: 0.7962550520896912

Tuned DNN Test Loss: 0.7962550520896912, Tuned DNN Test MSE: 0.7962550520896912

1.6.1 Discussion:

as we can notice that Compare the test losses and Mean Squared Errors of the MF and the 1st DNN models. this Tuned DNN model provied Lower values indicate better performance.

1.7 5. Final Report and Submission

Based on the practical implementation of Matrix Factorization and Deep Neural Network for recommender systems, here are the key findings and insights:

- 1. Matrix Factorization Model:
- Simple collaborative filtering approach.
- Embeds users and items into a lower-dimensional space.
- Less complex compared to DNN models.
- 2. Deep Neural Network Model:
- Utilizes a more complex architecture with multiple layers.
- Able to capture intricate patterns and relationships in the data.
- Requires careful tuning of hyperparameters for optimal performance.
- 3. Performance Comparison:
- DNN model outperformed the MF model in terms of Mean Squared Error on the test set.

- Lower MSE indicates better accuracy in predicting ratings.
- 4. Hyperparameter Tuning:
- Experimentation with hyperparameters such as the number of layers, units per layer, dropou
- Fine-tuning hyperparameters can lead to improved model performance.