

# Sudharshan Suresh

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PERSONAL	<a href="http://www.cs.cmu.edu/~sudhars1/">www.cs.cmu.edu/~sudhars1/</a>   <a href="mailto:suddhu@cmu.edu">suddhu@cmu.edu</a>   <a href="https://in.sudharshansuresh">/in/sudharshansuresh</a>	
EDUCATION	<b>Robotics Institute, Carnegie Mellon University</b> PhD in Robotics	2019 - ongoing
	<b>Robotics Institute, Carnegie Mellon University</b> M.S. in Robotics GPA: 4.09, <i>Advisor</i> : <a href="#">Prof. Michael Kaess</a> <i>Thesis</i> : <a href="#">Localization and Active Exploration in Indoor Underwater Environments</a>	2017 - 2019
	<b>National Institute of Technology, Tiruchirappalli, India</b> B.Tech (Hons) in Instrumentation and Control Engineering GPA: 9.45/10	2013 - 2017
PUBLICATIONS	<p><a href="#">S. Suresh</a>, E. Westman and M. Kaess, <b>Through-water Stereo SLAM with Refraction Correction for AUV Localization</b>, IEEE Robotics and Automation Letters, vol. 4, no. 2, pp. 692-699, Presented at ICRA 2019 and published in RA-L, April 2019. [<a href="#">PDF</a>, <a href="#">Poster</a>, <a href="#">Video</a>]</p> <p>J. Hsiung, A. Tallaksen, L. Papincak, <a href="#">S. Suresh</a>, H. Jones, W. Whittaker and M. Kaess, <b>Localized Imaging and Mapping for Underwater Fuel Storage Basins</b>, Proceedings of the Symposium on Waste Management, Phoenix, Arizona, Mar 2018. [<a href="#">PDF</a>, <a href="#">Slides</a>, <a href="#">Video</a>]</p> <p>R. K. Sarvadevabhatla, <a href="#">S. Suresh</a> and R. Venkatesh Babu, <b>Object Category Understanding via Eye Fixations on Freehand Sketches</b>, IEEE Transactions on Image Processing, vol. 26, no. 5, pp. 2508-2518, May 2017. [<a href="#">PDF</a>, <a href="#">Project</a>]</p> <p>E. Fang, <a href="#">S. Suresh</a> and W. Whittaker, <b>Camera-Only Kinematics for Small Lunar Rovers</b>, Annual Meeting of the Lunar Exploration Analysis Group, Vol. 1960, Nov 2016. [<a href="#">PDF</a>, <a href="#">Poster</a>]</p> <p><a href="#">S. Suresh</a>, E. Fang and W. Whittaker, <b>Optical Kinematic State Estimation of Planetary Rovers using Downward-Facing Monocular Fisheye Camera</b>, RISS Working Paper Journal, Nov 2016. [<a href="#">PDF</a>, <a href="#">Video</a>, <a href="#">Poster</a>]</p>	
RESEARCH EXPERIENCE	<b>Robotics Institute, Carnegie Mellon University</b> <i>Advisor</i> : <a href="#">Prof. Michael Kaess</a>	Aug 2017 - Aug 2019 <i>M.S. Student</i>
	Master's thesis research in the <a href="#">Robot Perception Lab</a> , focused on localization and exploration for autonomous underwater vehicles (AUVs). This comprised of (i) a novel through-water method for visual localization using landmarks above the water surface, (ii) an active SLAM framework for exploration and sonar mapping.	
	<b>Robotics Institute, Carnegie Mellon University</b> <i>Advisor</i> : <a href="#">Prof. William L. "Red" Whittaker</a>	June - Sep 2016 <i>RI Summer Scholar</i>
	Developed a novel visual state-estimation algorithm for planetary rovers via self-perception. Method uses a single downward-facing fisheye camera to robustly estimate 10-DoF kinematic state on rugged terrain.	
	<b>Video Analytics Lab, Indian Institute of Science</b> <i>Advisors</i> : <a href="#">Prof. R. Venkatesh Babu</a> , <a href="#">R. K. Sarvadevabhatla</a>	May - Aug 2015 <i>Research Intern</i>
	Research in object category understanding for freehand sketches. Created <i>SketchFix-160</i> , as open-source dataset of free-viewing user tests, and developed a computational model for sketch category prediction.	
	<b>Dept. of Instrumentation and Control, NIT Trichy</b> <i>Advisor</i> : <a href="#">Prof. M. Umapathy</a>	Jan - May 2017 <i>Bachelor's Thesis</i>
	Worked on the design and implementation of sliding mode control for electromechanical domains. Analyzed hyperplane design techniques for a cantilever beam system with input disturbance.	

INDEPENDENT PROJECTS	<b>DeepGeo: Photo Localization with Deep Neural Network</b> (10-701) [ <a href="#">arXiv</a> ] 2018 A deep network that beats humans at <a href="#">GeoGuessr</a> —trained on our <i>50States10K</i> dataset.
	<b>Task and Motion Planning for Robotic Food Preparation</b> (16-782) [ <a href="#">Report</a> ] 2018 Hierarchical task and motion planning for a 6-DOF robot arm—to prepare yogurt parfaits!
	<b>Thin Structure Reconstruction via 3D Lines and Points</b> (16-822) [ <a href="#">Poster</a> ] 2018 We combine edge data and sparse features in the SfM pipeline to recover thin objects in a scene.
	<b>Factor Graph Optimization for Dynamic Parameter Estimation</b> (16-711) [ <a href="#">Report</a> ] 2019 We implement a method for estimation of MAV poses and dynamic parameters during flight.
AWARDS AND HONORS	RECAL Alumni Award, 2017 ( <i>gold-medalist in undergraduate major</i> ) Sri. Avinash Memorial Award, 2017 ( <i>best outgoing male student in undergraduate major</i> ) <a href="#">OPJEMS Scholar</a> , 2017 ( <i>100 undergraduates across India</i> ) <a href="#">S. N. Bose</a> and <a href="#">Robotics Institute Summer Scholar</a> , 2016 <a href="#">Cargill Global Scholar</a> , 2015 - 2017 ( <i>10 undergraduate sophomores across India</i> )
ACTIVITIES	Admissions committee, CMU RI Summer Scholars program (2018, 2019) Mentor, Jiteshraj Scholarship, NIT Trichy (2018) Teaching Assistant, 16-833: Robot Localization and Mapping, CMU (2019)
TECHNICAL SKILLS	<b>Programming:</b> C/C++, Python, MATLAB, $\text{\LaTeX}$ <b>Tools and Libraries:</b> ROS, OpenCV, TensorFlow
RELEVANT COURSEWORK	<b>Graduate:</b> Convex Optimization (10-725)*, Kinematics, Dynamics and Control (16-711), Geometry-based Methods in Vision (16-822), Planning and Decision-making in Robotics (16-782), Robot Localization and Mapping (16-833), Introduction to Machine Learning (10-701), Computer Vision (16-720B), Mathematical Fundamentals for Robotics (16-811) <b>Undergraduate:</b> Data Structures and Algorithms, Computer Networks, Neural Networks and Fuzzy Logic, Image Processing, Basics of Programming, Control Systems, Logic and Distributed Control, Robotics, Signals and Systems, Circuit Theory, Digital Electronics, Embedded Systems, Linear Integrated Circuits, Sensors and Transducers, Material Science, Numerical Methods