

```
In[ ]:= Remove["Global`*"]
```

Bounded Trajectories

Numerically solving the equations parametrically, with parameter μ (mass ratio) for bounded trajectories and generating plots for various μ .

$$\frac{d}{dt}v(t) = (r(t) \omega(t)^2 + g \cos(\theta(t) - \mu)) / (1 + \mu)$$

$$\frac{d}{dt}\omega(t) = (-2v(t)\omega(t) - g \sin(\theta(t))) / r(t)$$

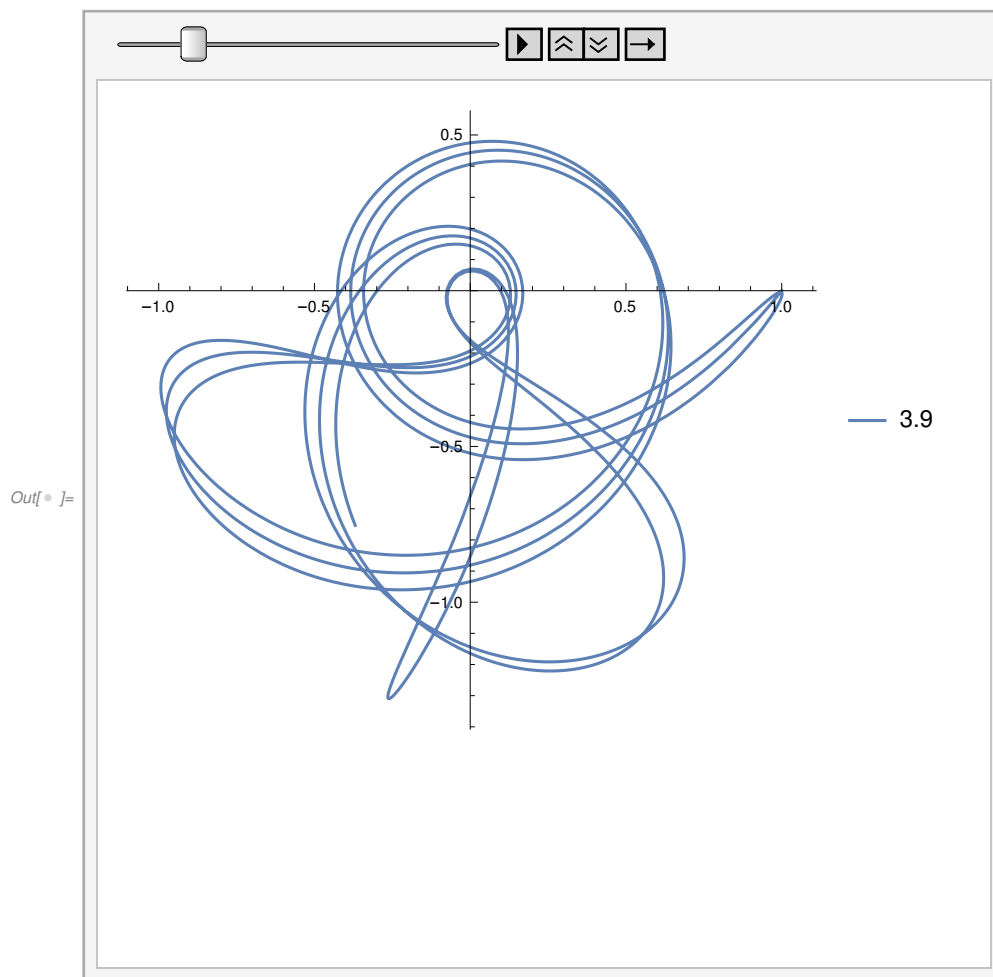
with initial conditions $r(0) = 1$, $\theta(0) = 90^\circ$, $v(0) = 0$, $\omega(0) = 0$

```
In[ ]:= sol = ParametricNDSolve[{v'[t] == (r[t] * ω[t]^2 + 9.8 (Cos[θ[t]] - μ)) / (1 + μ),
  ω'[t] == (-2 v[t] * ω[t] - 9.8 Sin[θ[t]]) / r[t], r'[t] == v[t], θ'[t] == ω[t], r[0] == 1,
  θ[0] == Pi / 2, v[0] == 0, ω[0] == 0}, {r, v, θ, ω}, {t, 0, 100}, {μ}, MaxSteps -> 200 000]
```

```
Out[ ]:= {r -> ParametricFunction[ Expression: r  
Parameters: {μ}],
  v -> ParametricFunction[ Expression: v  
Parameters: {μ}],
  θ -> ParametricFunction[ Expression: θ  
Parameters: {μ}],
  ω -> ParametricFunction[ Expression: ω  
Parameters: {μ}]}
```

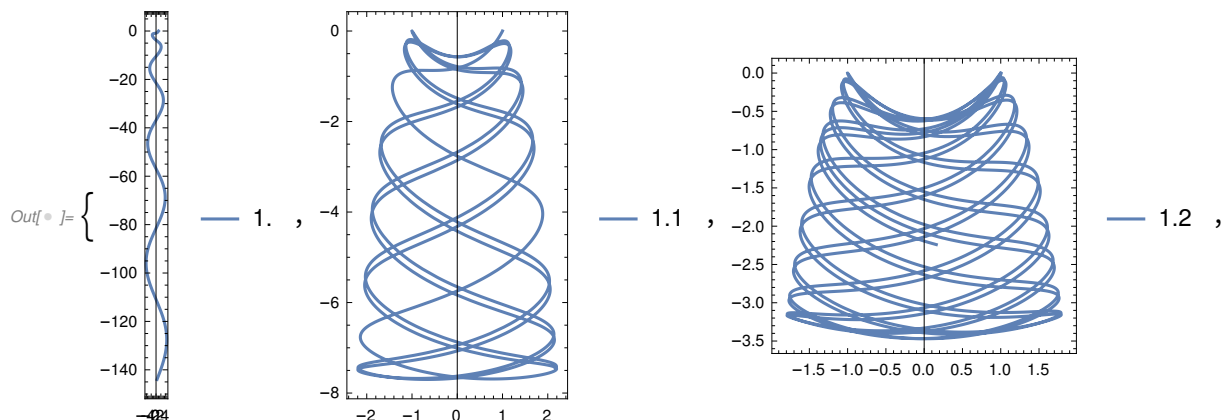
```
In[ ]:= fr = Table[ParametricPlot[Evaluate[{r[μ][t] Sin[θ[μ][t]], -r[μ][t] Cos[θ[μ][t]]} /. sol],
  {t, 0, 10}, PlotLegends -> {μ}], {μ, 1, 20, 0.1}];
```

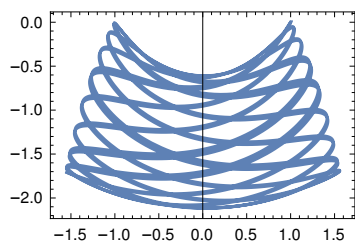
In[]:= ListAnimate[fr]



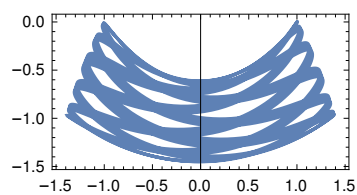
Plots for varying μ , with μ indicated on right edge

In[]:= Table[ParametricPlot[Evaluate[{r[μ][t] Sin[θ[μ][t]], -r[μ][t] Cos[θ[μ][t]]} /. sol],
 {t, 0, 50}, PlotLegends → {μ}, Frame → True], {μ, 1, 10, 0.1}]

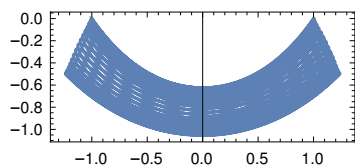




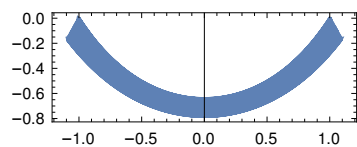
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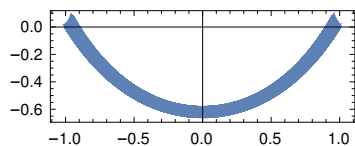
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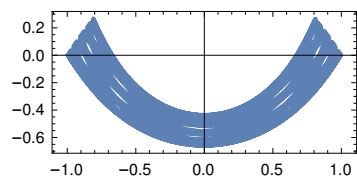
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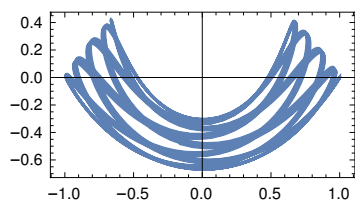
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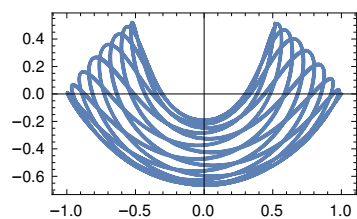
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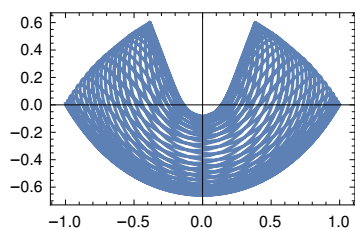
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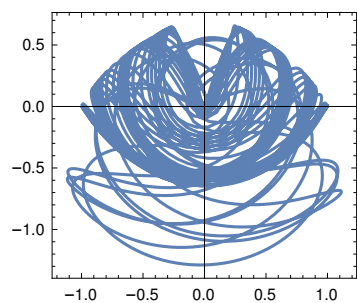
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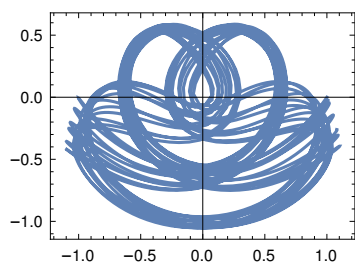
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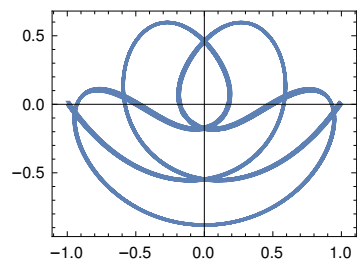
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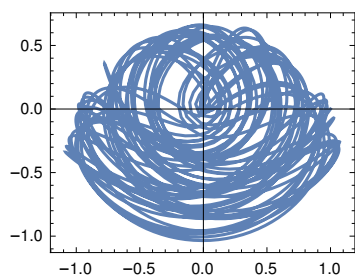
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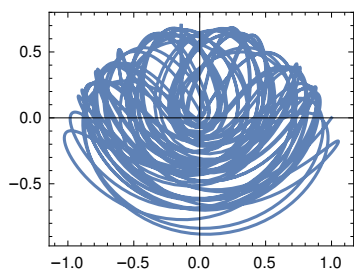
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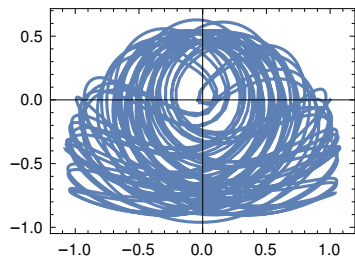
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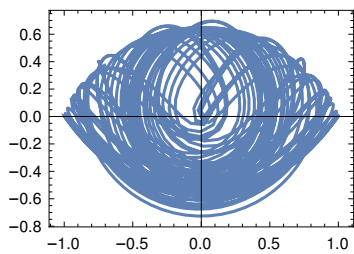
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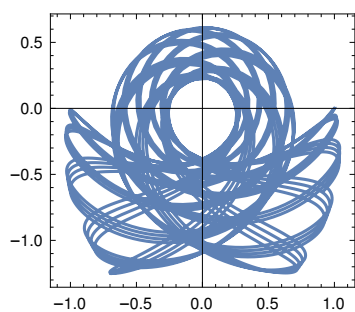
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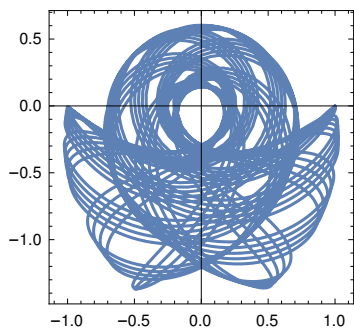
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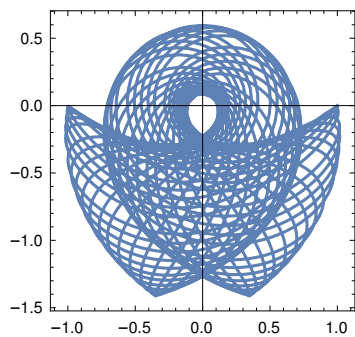
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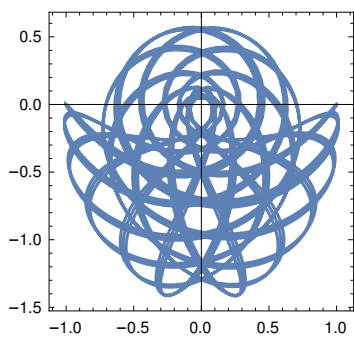
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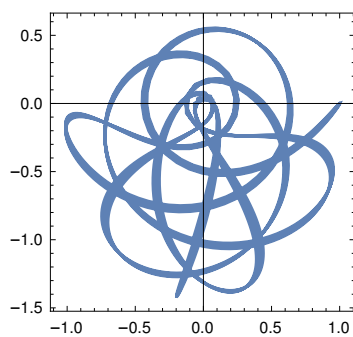
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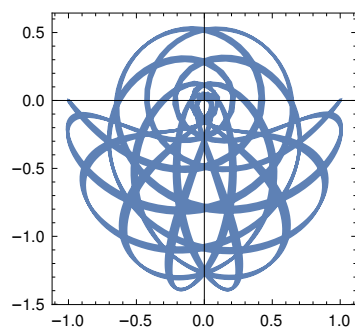
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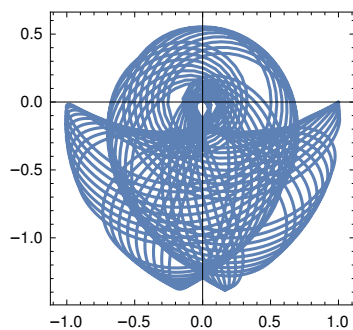
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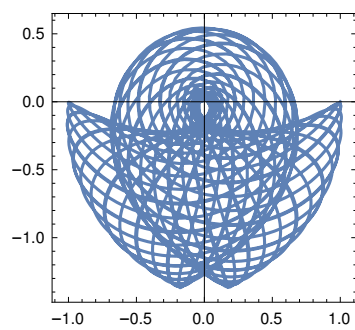
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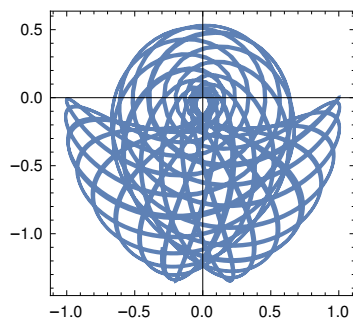
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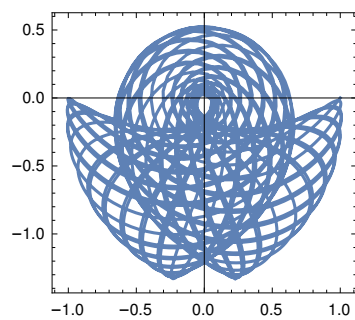
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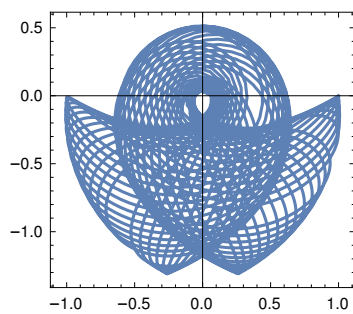
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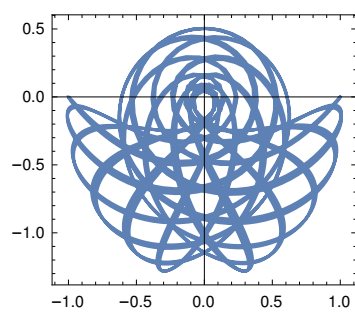
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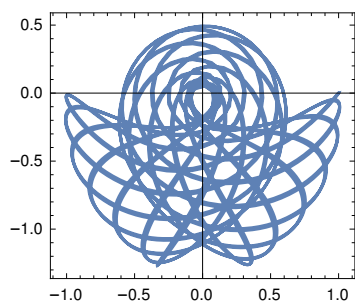
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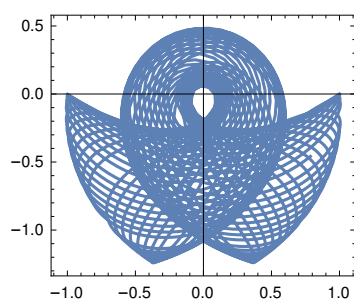
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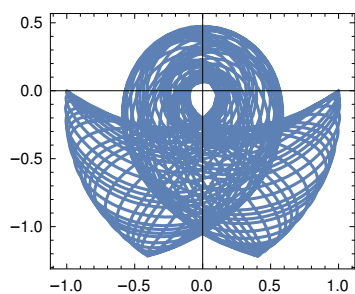
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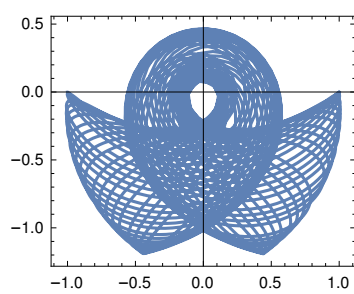
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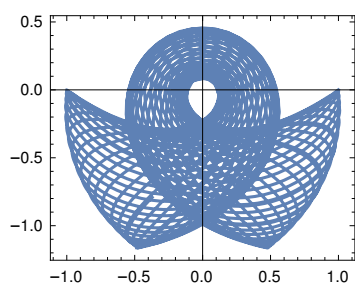
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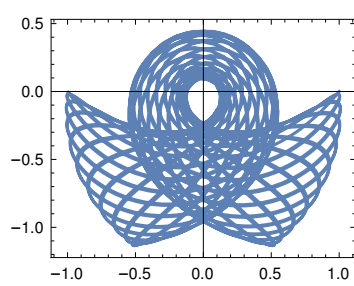
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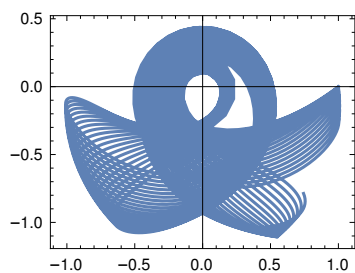
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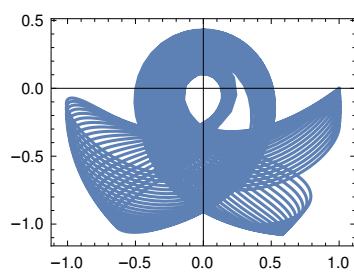
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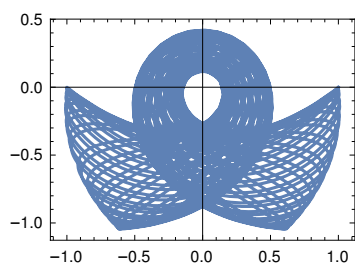
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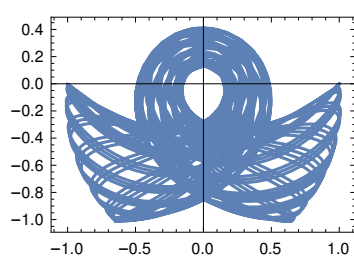
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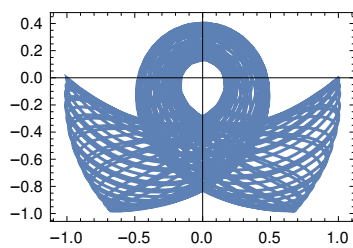
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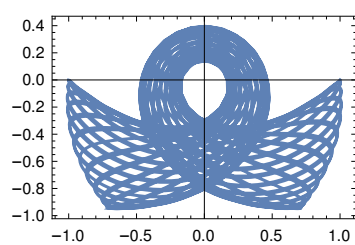
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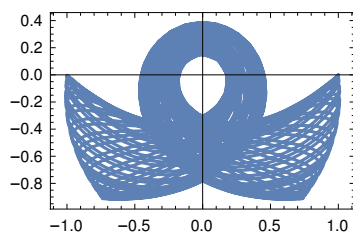
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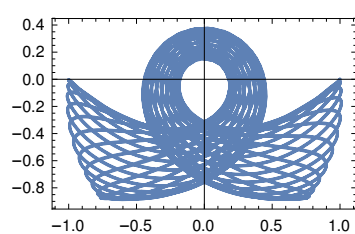
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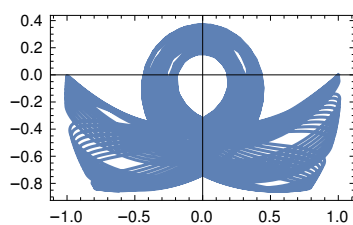
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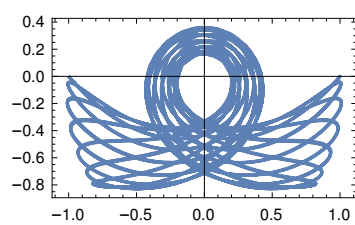
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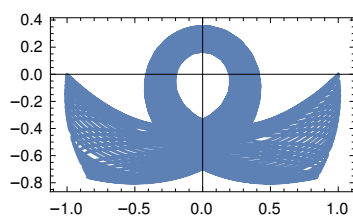
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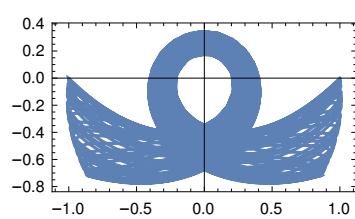
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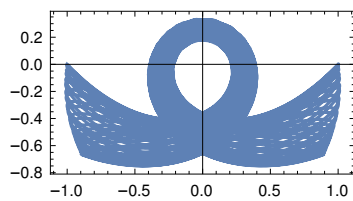
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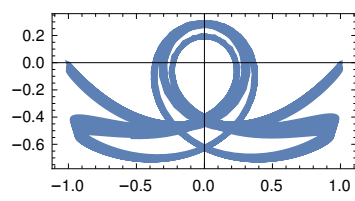
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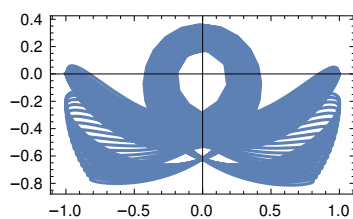
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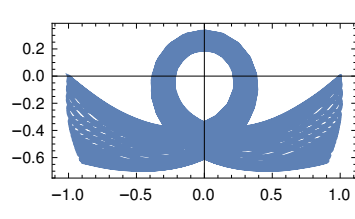
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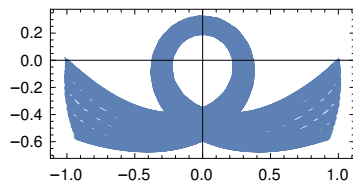
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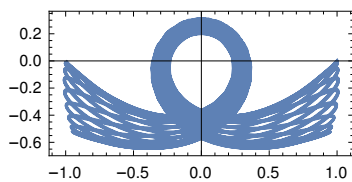
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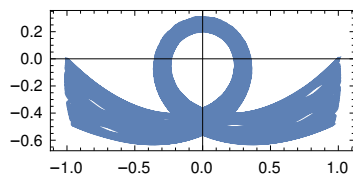
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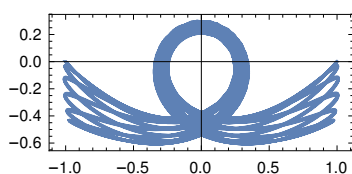
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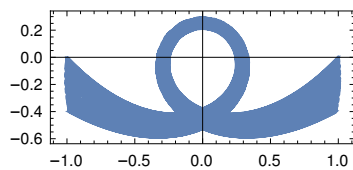
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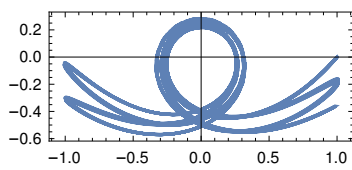
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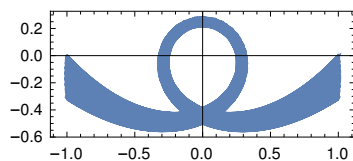
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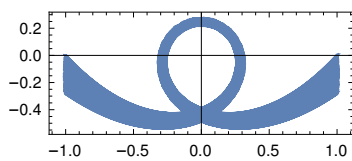
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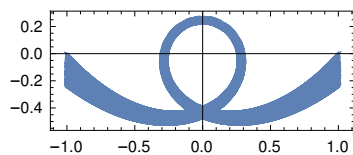
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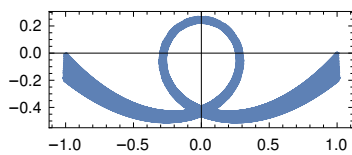
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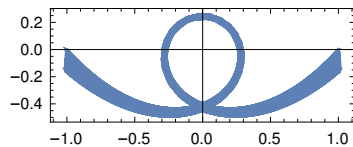
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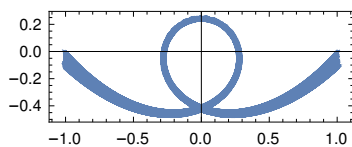
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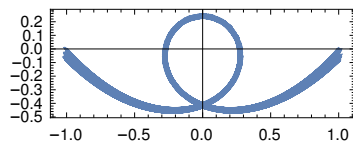
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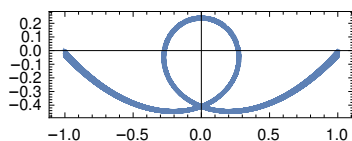
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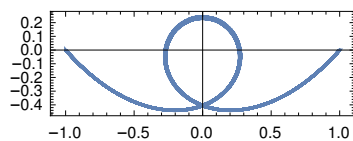
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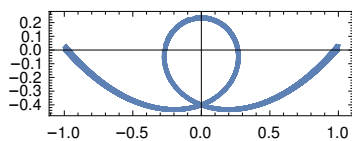
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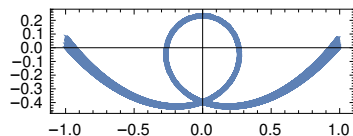
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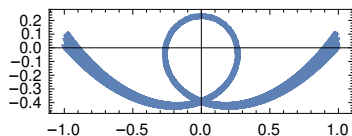
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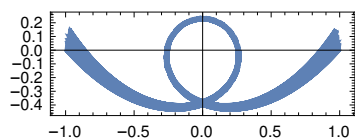
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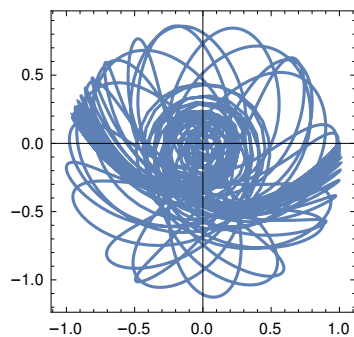
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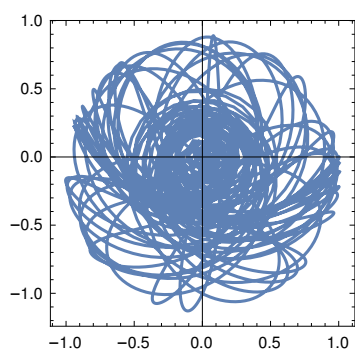
— 8. ,



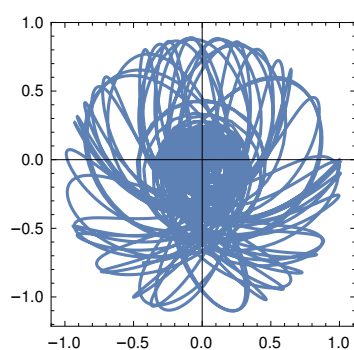
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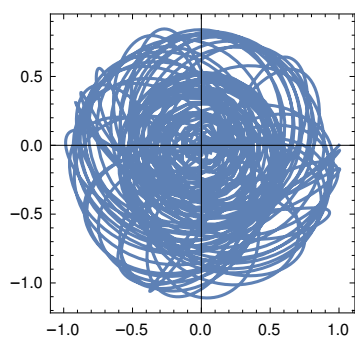
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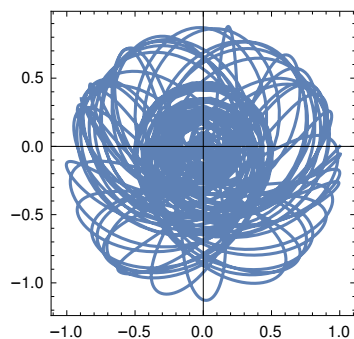
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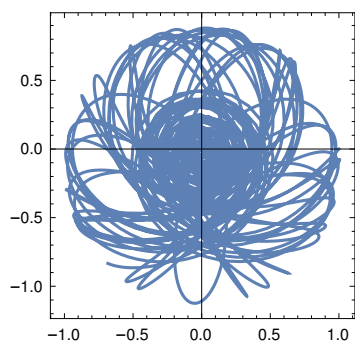
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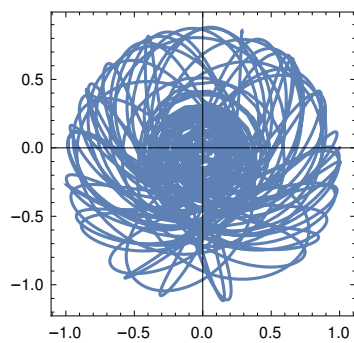
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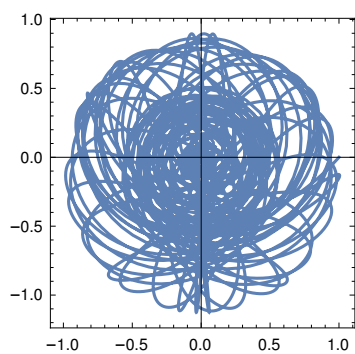
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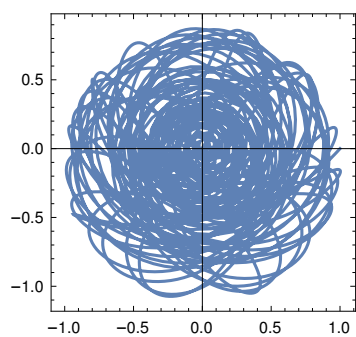
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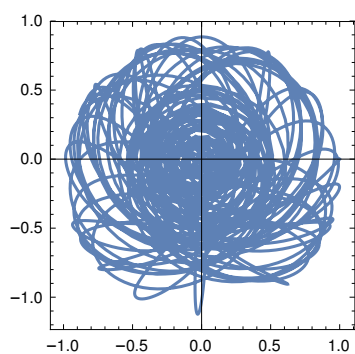
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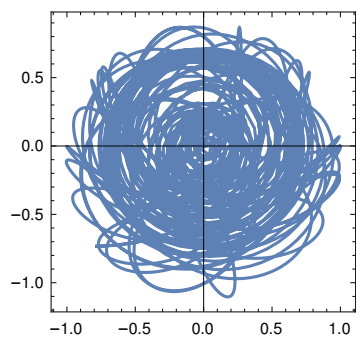
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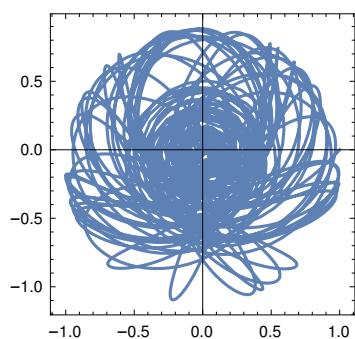
9. ,



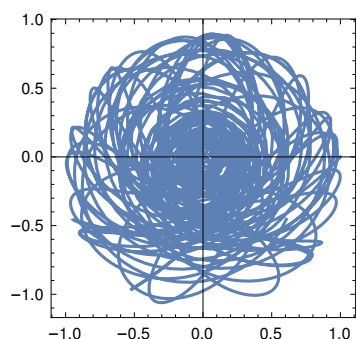
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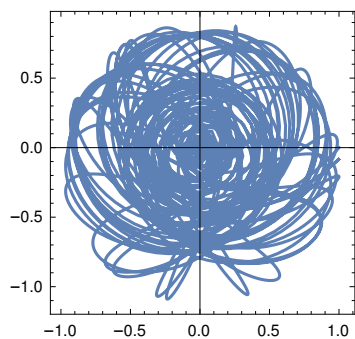
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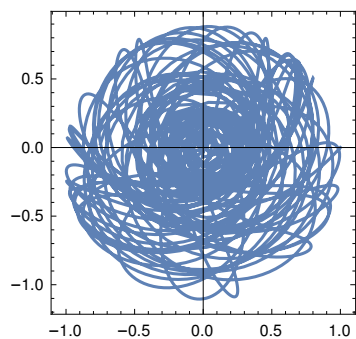
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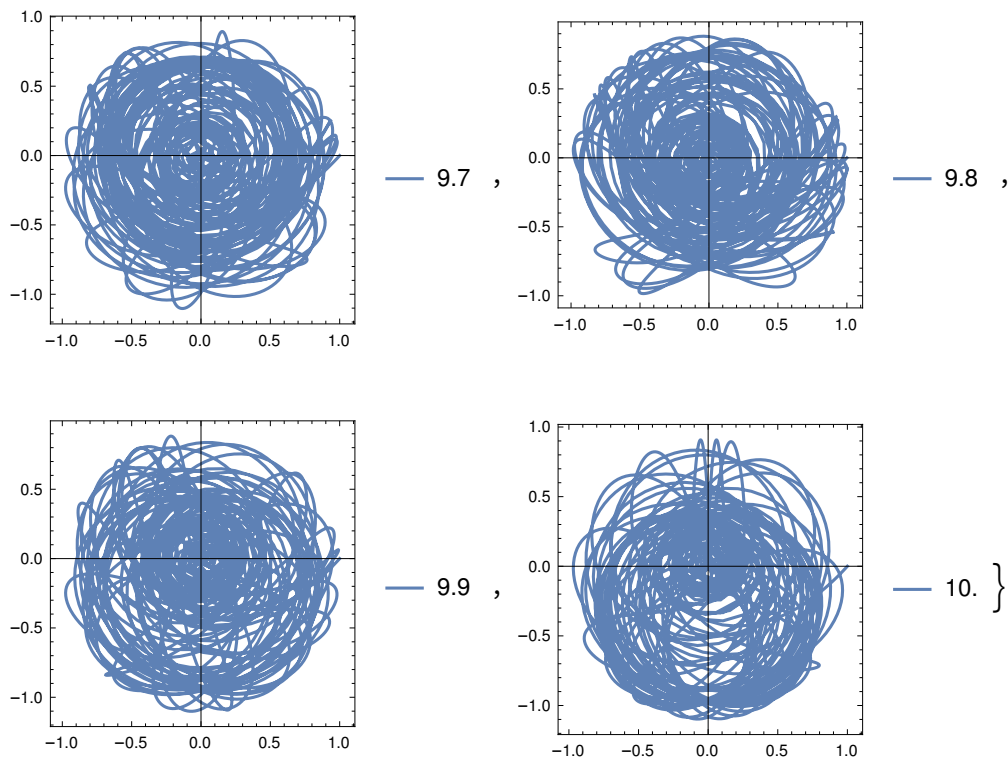
9.4 ,



9.5 ,



9.6 ,



Singular Trajectories

Numerically solving for singular trajectories with initial conditions $r(0) = 0$, $\theta(0) = 90^\circ$, $v(0) = 4$ and $\omega(0) = 0$ and generating plots:

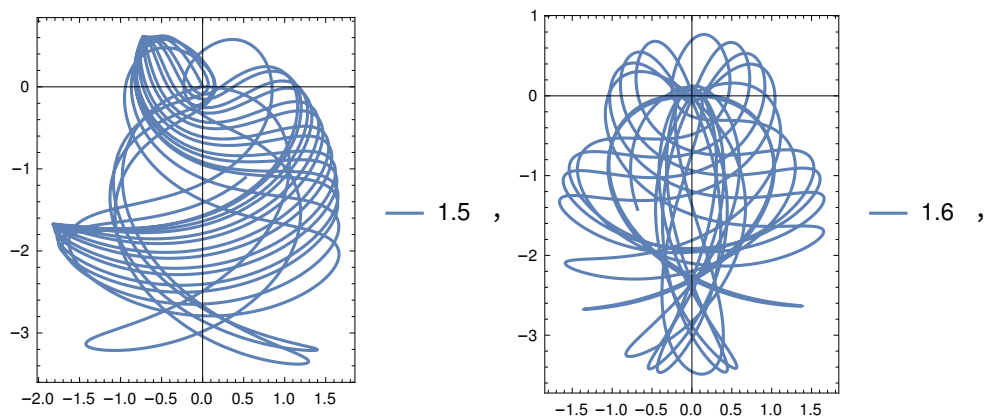
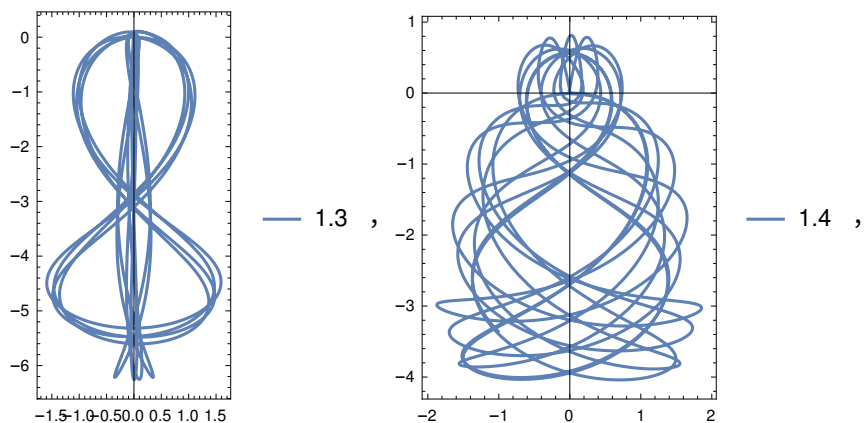
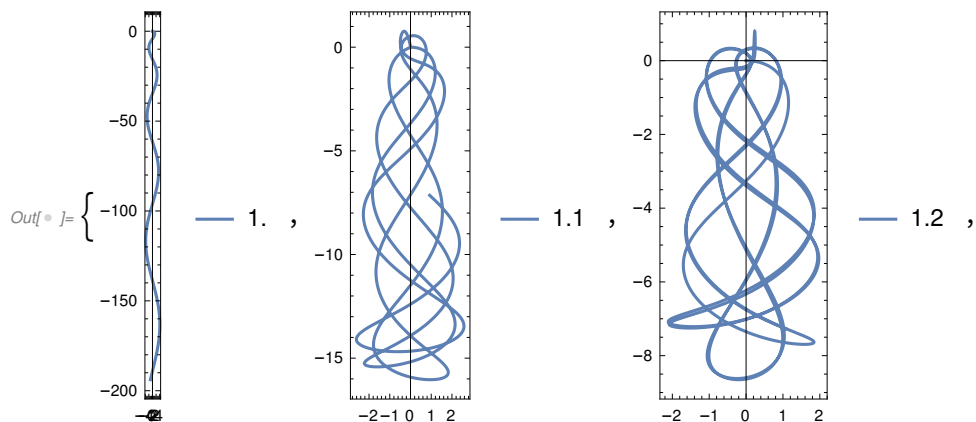
```
In[ ]:= sol1 = ParametricNDSolve[{v'[t] == (r[t] * ω[t]^2 + 9.8 (Cos[θ[t]] - μ)) / (1 + μ),
  ω'[t] == (-2 v[t] * ω[t] - 9.8 Sin[θ[t]]) / r[t], r'[t] == v[t], θ'[t] == ω[t], r[0] == 10^(-10),
  θ[0] == Pi/2, v[0] == 4, ω[0] == 0}, {r, v, θ, ω}, {t, 0, 100}, {μ}, MaxSteps -> 200 000]
```

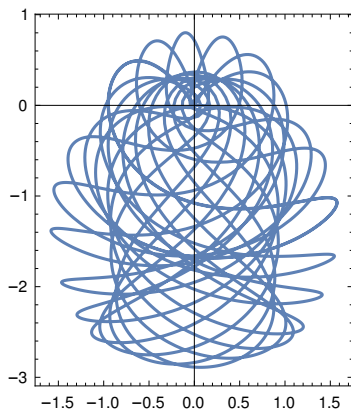
```
Out[ ]:= {r -> ParametricFunction[ Expression: r  
Parameters: {μ}],  
v -> ParametricFunction[ Expression: v  
Parameters: {μ}],  
θ -> ParametricFunction[ Expression: θ  
Parameters: {μ}],  
ω -> ParametricFunction[ Expression: ω  
Parameters: {μ}]}
```

```

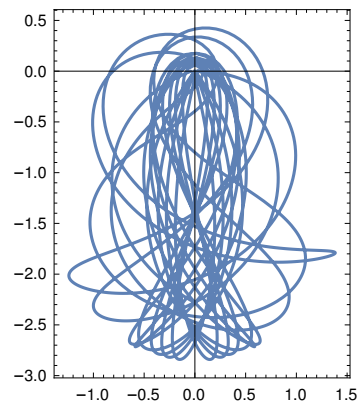
In[ ]:= fr1 = Table[ParametricPlot[Evaluate[{r[μ][t] Sin[θ[μ][t]], -r[μ][t] Cos[θ[μ][t]]} /. sol1],
  {t, 0, 50}, PlotLegends → {μ}, Frame -> True], {μ, 1, 10, 0.1}]

```

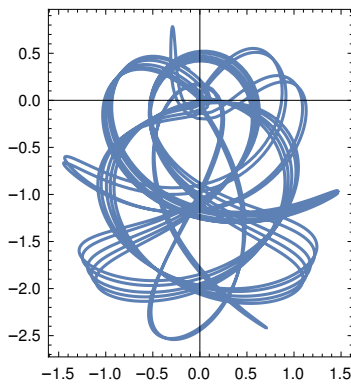




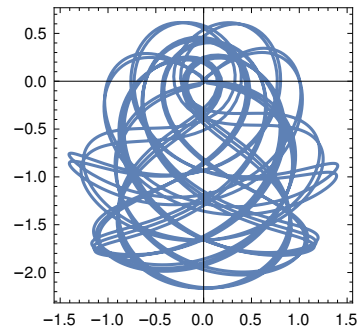
— 1.7 ,



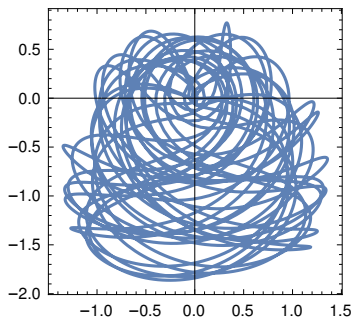
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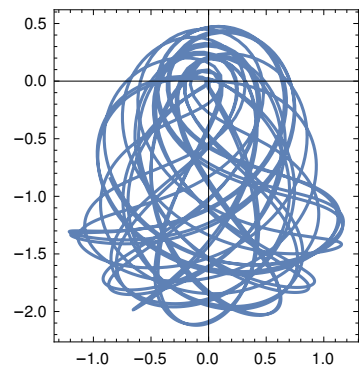
— 1.9 ,



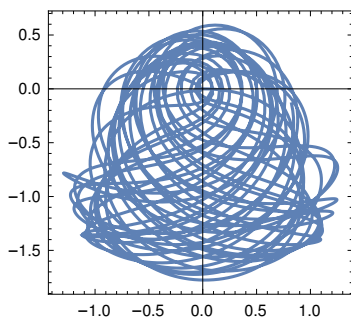
— 2. ,



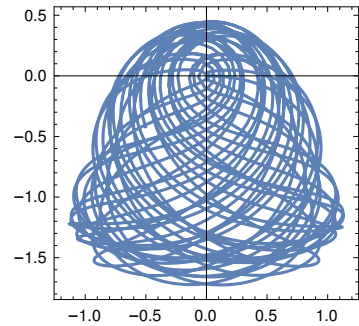
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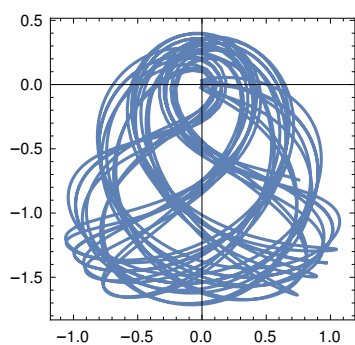
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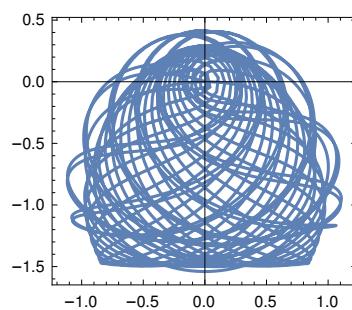
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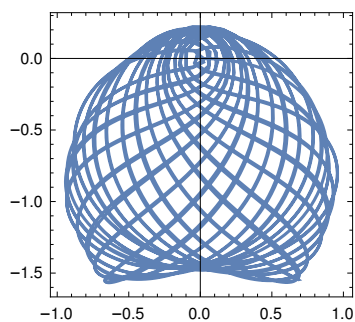
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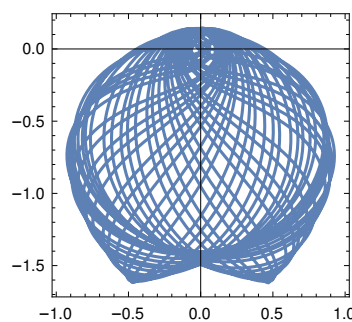
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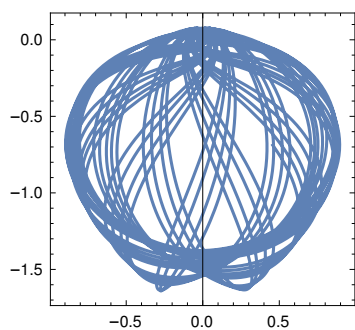
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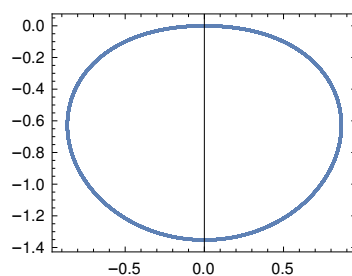
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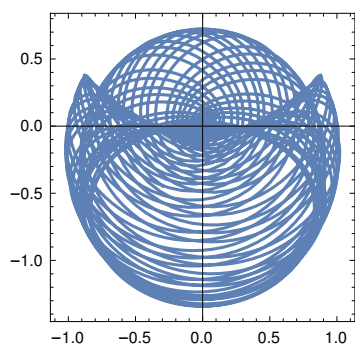
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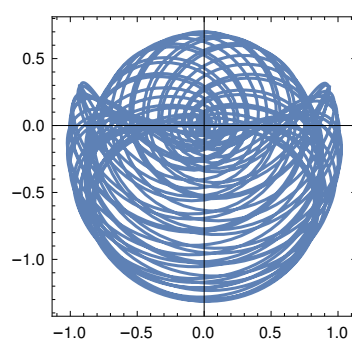
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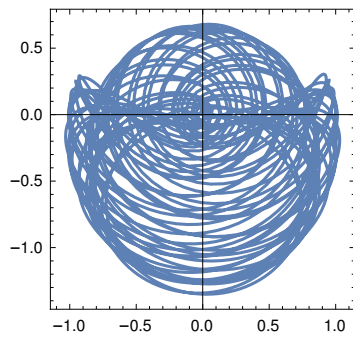
— 3. ,



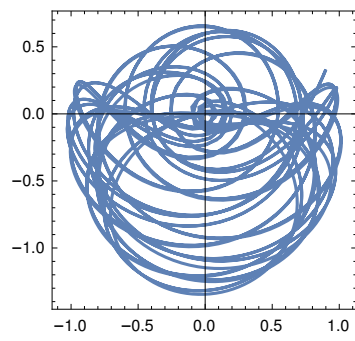
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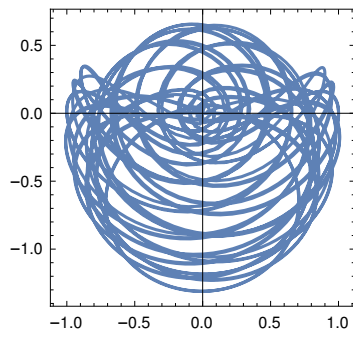
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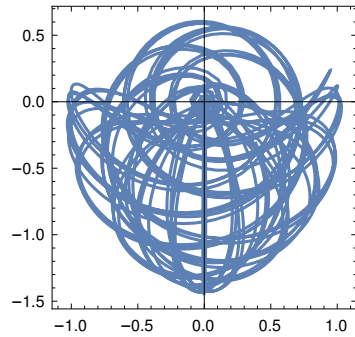
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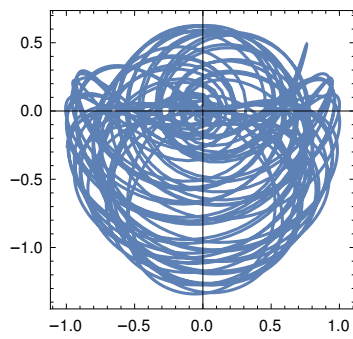
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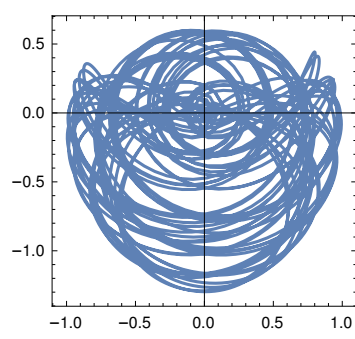
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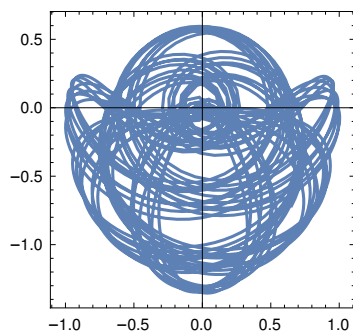
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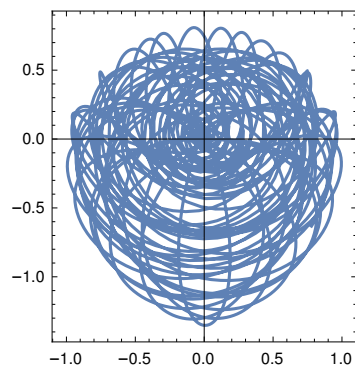
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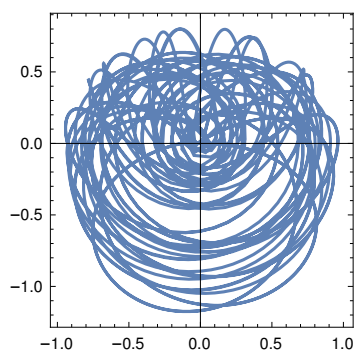
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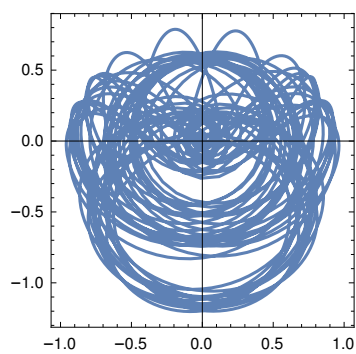
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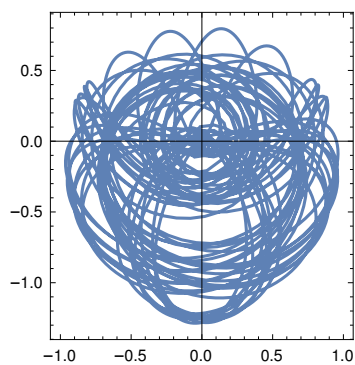
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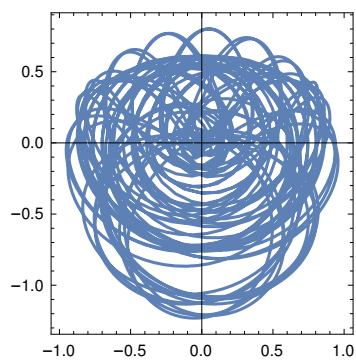
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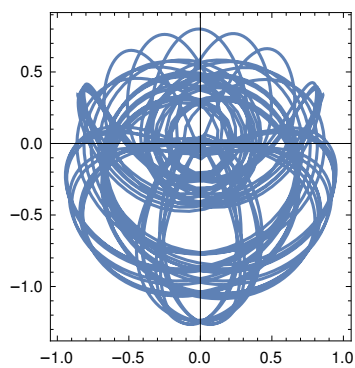
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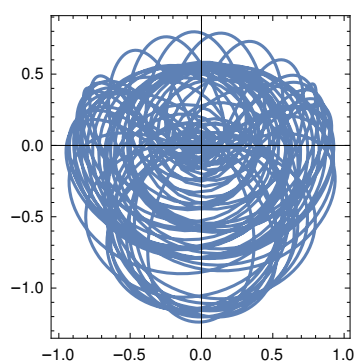
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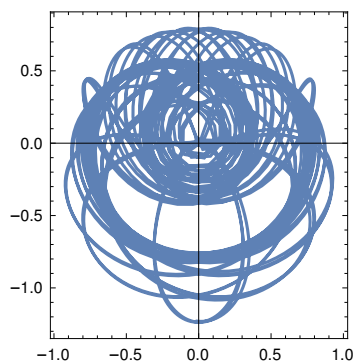
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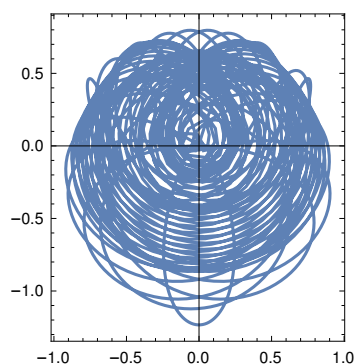
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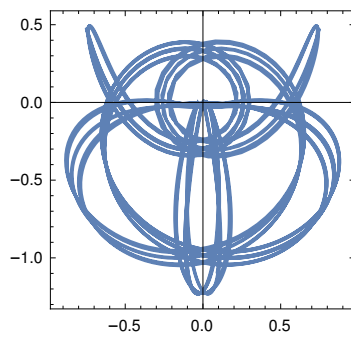
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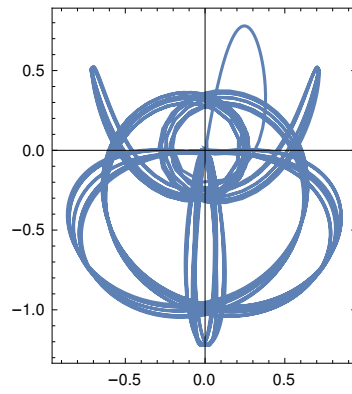
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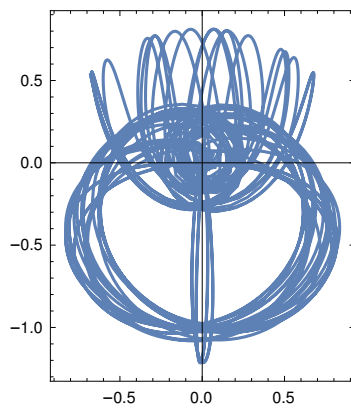
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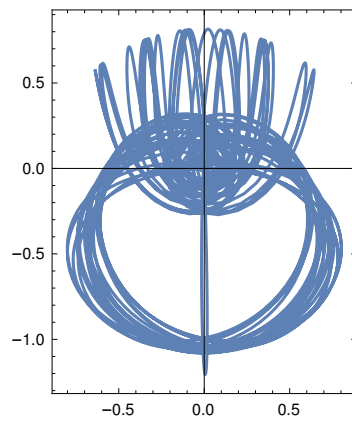
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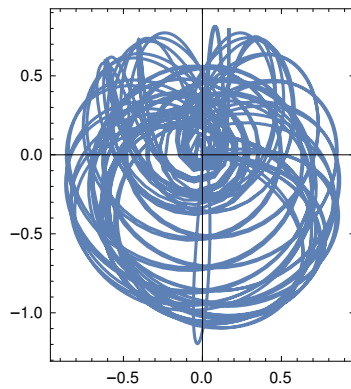
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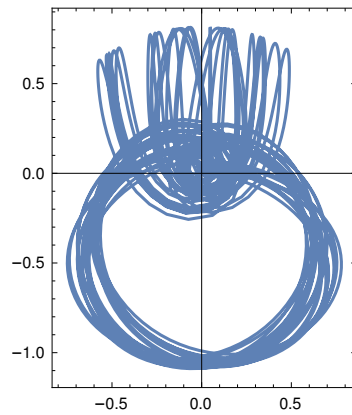
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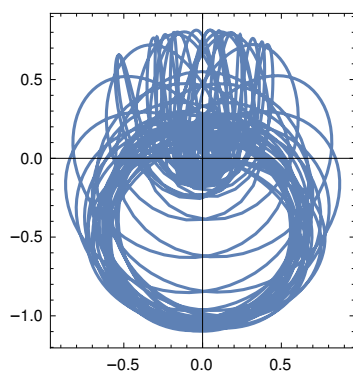
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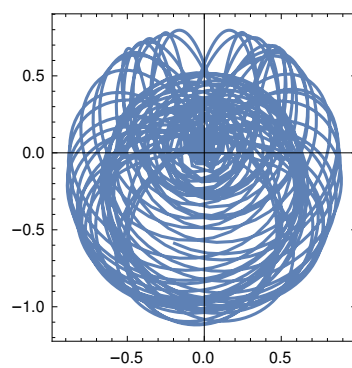
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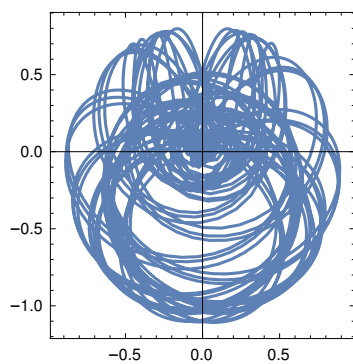
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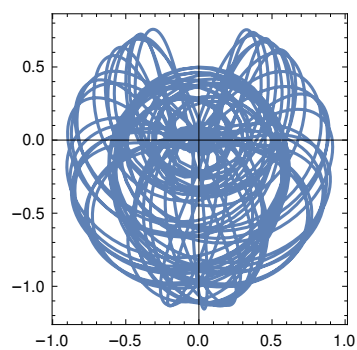
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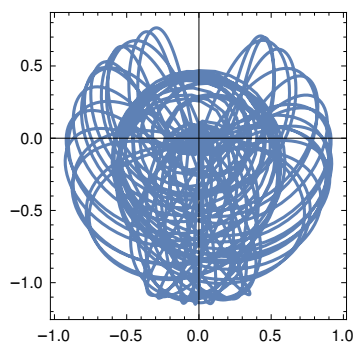
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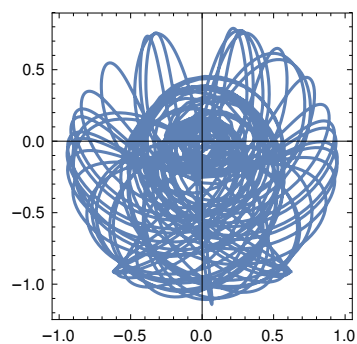
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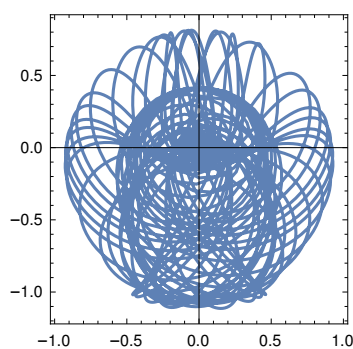
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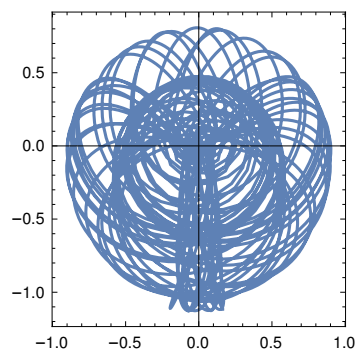
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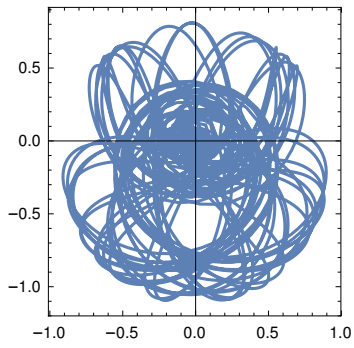
— 6. ,



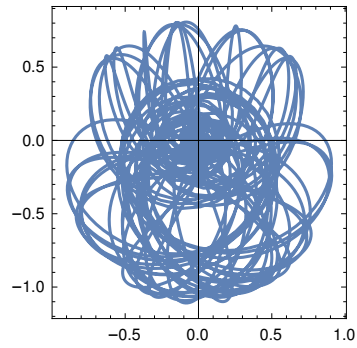
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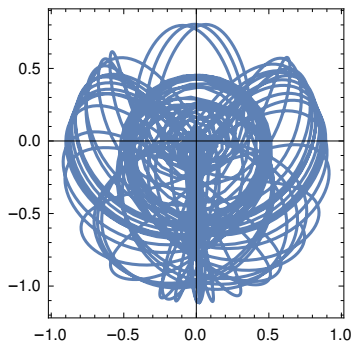
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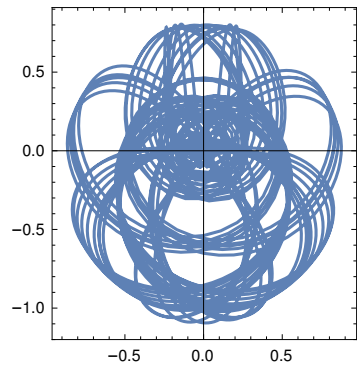
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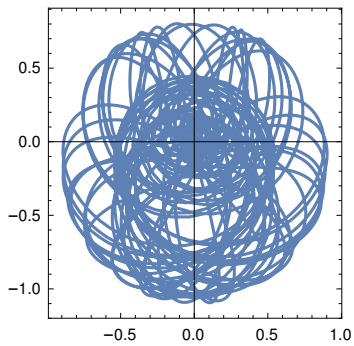
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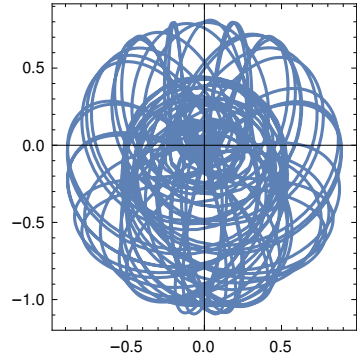
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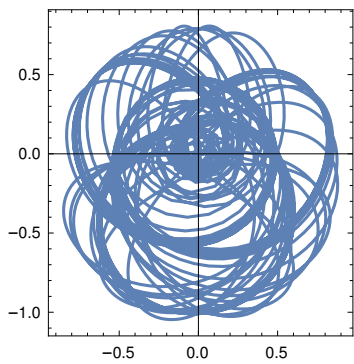
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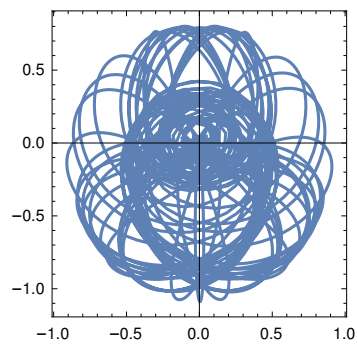
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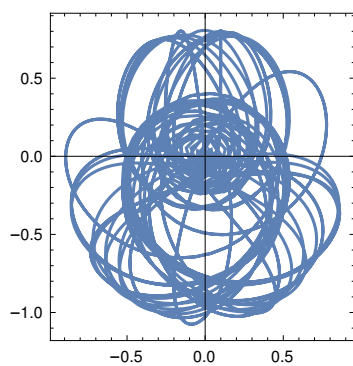
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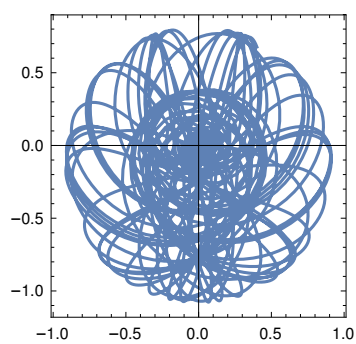
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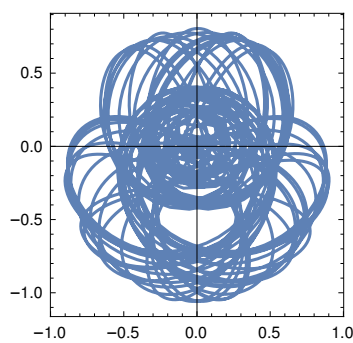
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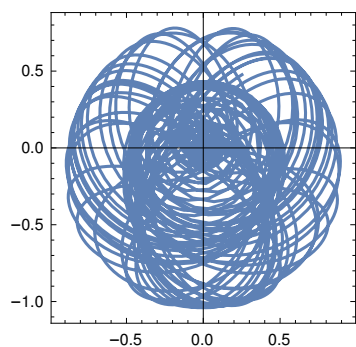
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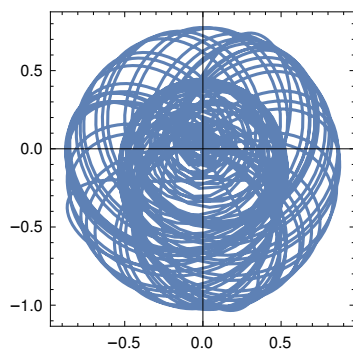
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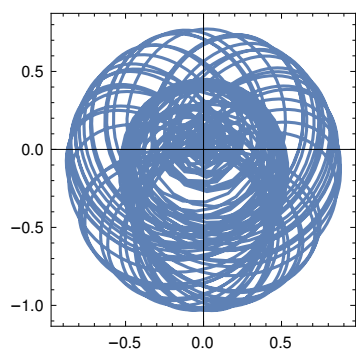
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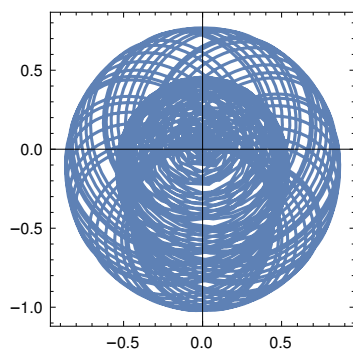
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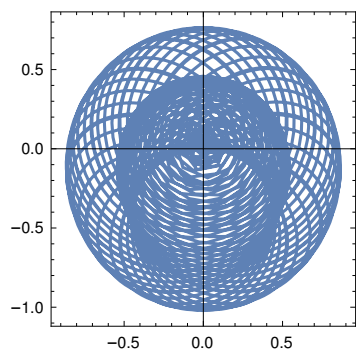
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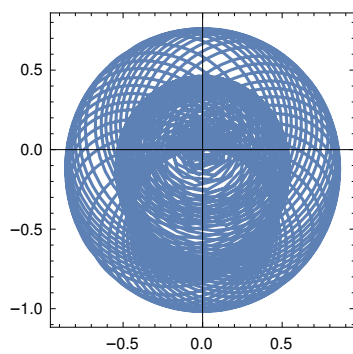
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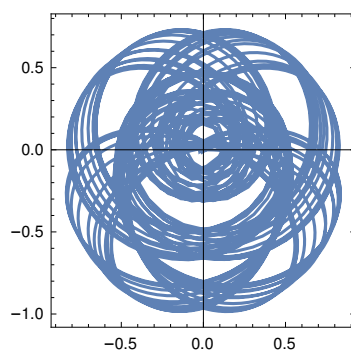
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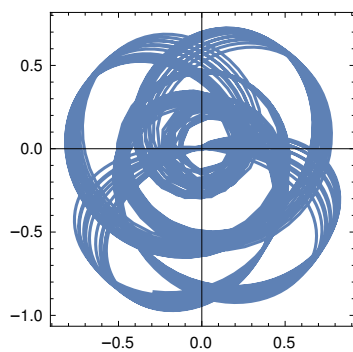
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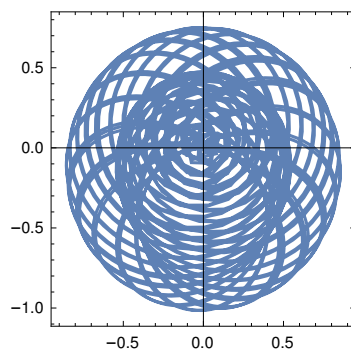
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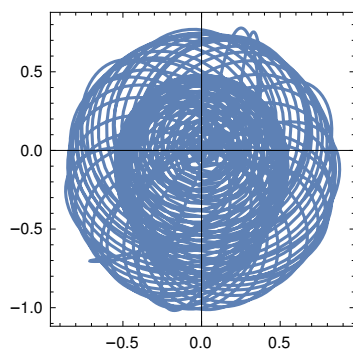
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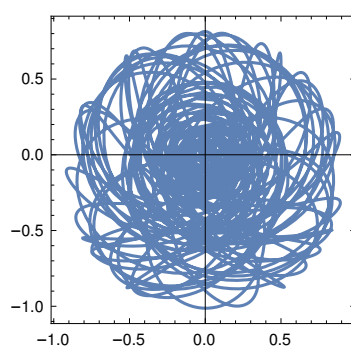
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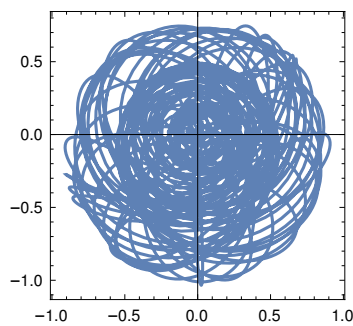
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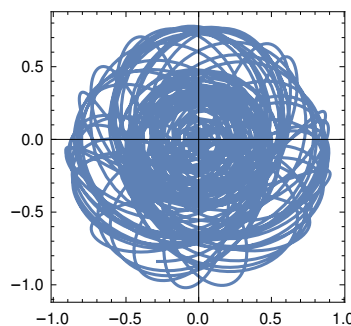
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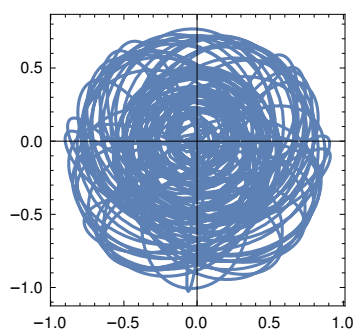
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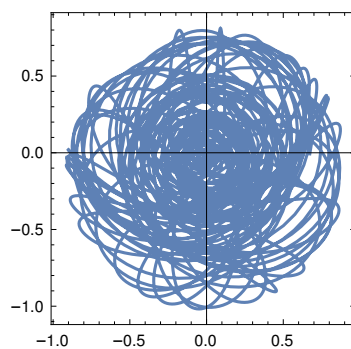
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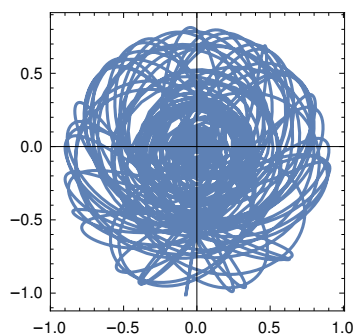
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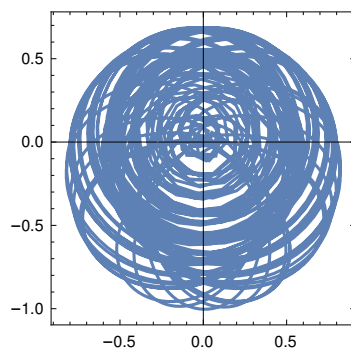
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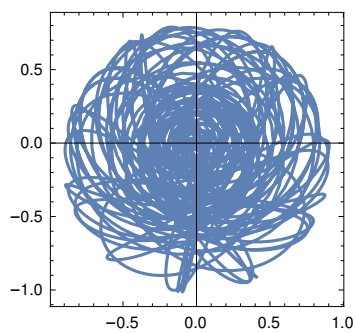
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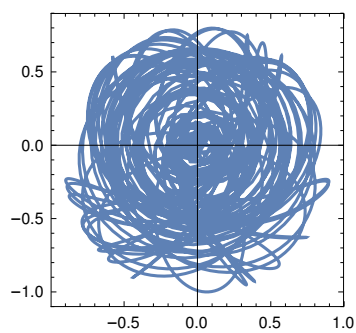
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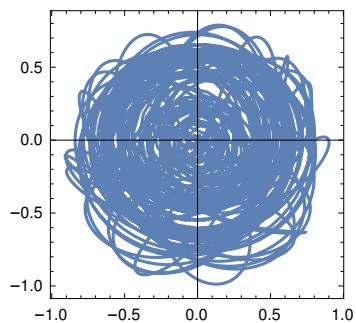
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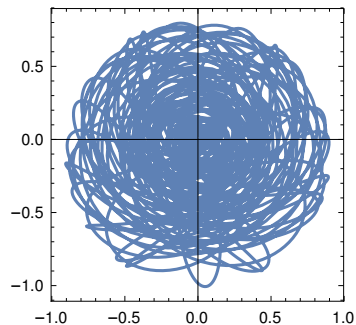
9.1 ,



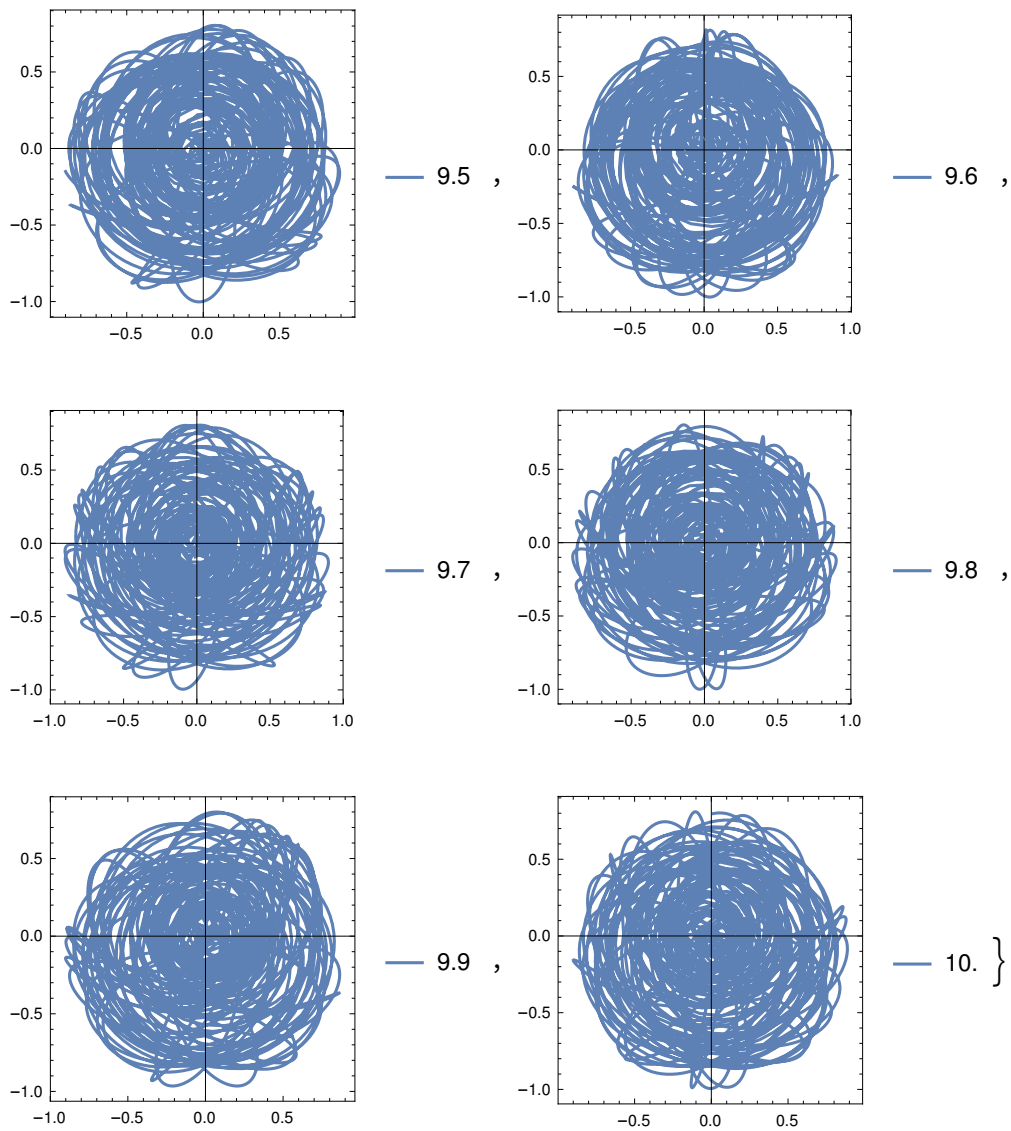
9.2 ,



9.3 ,



9.4 ,



Terminating Trajectories




Varying the initial angle $\theta(0)$ for mass ratio $\mu = 3$, we obtain terminating trajectories that always return to the origin

```

In[ ]:= sol2 = ParametricNDSolve[{ v'[t] == (r[t] * ω[t]^2 + 9.8 (Cos[θ[t]] - 3)) / (4),
    ω'[t] == (-2 v[t] * ω[t] - 9.8 Sin[θ[t]]) / r[t], r'[t] == v[t], θ'[t] == ω[t], r[0] == 10^(-10),
    θ[0] == θ0, v[0] == 4, ω[0] == 0}, {r, v, θ, ω}, {t, 0, 50}, {θ0}, MaxSteps -> 200 000]

```

```

Out[ ]:= {r -> ParametricFunction[ Expression: r
Parameters: {θ0}],
v -> ParametricFunction[ Expression: v
Parameters: {θ0}],
θ -> ParametricFunction[ Expression: θ
Parameters: {θ0}],
ω -> ParametricFunction[ Expression: ω
Parameters: {θ0}]}

```



```

In[ ]:= Table[ParametricPlot[Evaluate[{r[θ0][t] Sin[θ[θ0][t]], -r[θ0][t] Cos[θ[θ0][t]]] /. sol2],
  {t, 0, 50}, PlotLegends → {θ0}, Frame → True], {θ0, 0.6, Pi, 0.5}]

```

