master_project

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0.1 Derivation for the inner product of 3D rotational gradient operator acted on spherical harmonics

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with application in object/scenes response to a lighting environment, often represented using spherical harmonics, including complex global illumination effects

General reference about spherical harmonics: http://mathworld.wolfram.com/SphericalHarmonic.html

1 Spherical harmonics in SymPy

To get back the well known expressions in spherical coordinates we use full expansion:

```
In [3]: from sympy import Ynm, Symbol, expand_func
    from sympy.abc import n,m
    theta = Symbol("theta")
    phi = Symbol("phi")
    expand_func(Ynm(n, m, theta, phi))
```

Out[3]: sqrt((2*n + 1)*factorial(-m + n)/factorial(m + n))*exp(I*m*phi)*assoc_legendre(n, m, cos(theta))

 $Relevant\ page\ http://docs.sympy.org/latest/modules/functions/special.html?highlight=spherical\%20 harmonics\#sympy.full for spherical harmonics$

http://stsdas.stsci.edu/download/mdroe/plotting/entry1/index.html

2 Derivation

We try to derive the dot product of rotational gradient of spherical harmonics with spherical harmonics expansion.

$$\vec{R} = \begin{bmatrix} R_x \\ R_y \\ R_z \end{bmatrix} = \begin{bmatrix} -\frac{\cos\theta}{\sin\theta}\cos\phi\frac{\partial}{\partial\phi} - \sin\phi\frac{\partial}{\partial\theta} \\ -\frac{\cos\theta}{\sin\theta}\cos\phi\frac{\partial}{\partial\phi} + \cos\phi\frac{\partial}{\partial\theta} \\ \frac{\partial}{\partial\phi} \end{bmatrix}$$

$$R_{\alpha} = iL_{\alpha}, where \alpha = x, y, z$$

$$\vec{R} = \begin{bmatrix} R_x \\ R_y \\ R_z \end{bmatrix} = \begin{bmatrix} iL_x \\ iL_y \\ iL_z \end{bmatrix} = \begin{bmatrix} \frac{i}{2}(L_+ + L_-) \\ \frac{1}{2}(L_+ - L_-) \\ iL_z \end{bmatrix}$$

$$L_{+}Y_{l}^{m} = c_{l,m,1}Y_{l}^{m+1}$$

$$L_{-}Y_{l}^{m} = c_{l,m,2}Y_{l}^{m-1}$$

$$L_z Y_l^m = m Y_l^m$$

after some manipulations of the above identities, it can be shown that (details will be added later)

$$\vec{R}Y_{j}^{p} \cdot \vec{R}Y_{l}^{m} = -\frac{1}{2}[c_{j,p,1}c_{l,m,2}Y_{j}^{p+1}Y_{l}^{m-1} + c_{j,p,2}c_{l,m,1}Y_{j}^{p-1}Y_{l}^{m+1}] - mpY_{j}^{p}Y_{l}^{m}$$

$$= (-1) * (-1)^{m+p} \sum_{k=|l-j|}^{l+j} Y_k^{m+p} \left[\frac{1}{2} (c_{j,p,1} c_{l,m,2} \alpha_{l,m-1,j,p+1,k} + c_{j,p,2} C_{l,m,1} \alpha_{l,m+1,j,p-1,k}) + mp\alpha_{l,m,j,p,k} \right]$$

where

$$\alpha_{l,m,j,p,k} = \int_0^{2\pi} \int_0^{\pi} Y_j^p Y_l^m Y_k^{-m-p} \sin\theta d\theta d\phi$$

$$= \left[\frac{(2l+1)(2j+1)(2k+1)}{4\pi} \right]^{1/2} * \begin{pmatrix} j & l & k \\ 0 & 0 & 0 \end{pmatrix} * \begin{pmatrix} j & l & k \\ p & m & -(m+p) \end{pmatrix}$$

here

$$\left(\begin{array}{ccc}
j & l & k \\
0 & 0 & 0
\end{array}\right)$$

is Wigner 3j symbol

3 Wigner 3j symbol

reference for Wigner 3j symbol(strange fraction here) http://docs.sympy.org/dev/modules/physics/wigner.html

In [115]: from sympy.physics.wigner import wigner_3j
 wigner_3j(2, 6, 4, 0, 0, 0)

Out[115]:

 $\frac{\sqrt{715}}{143}$

In [164]: sqrt(S(5)/143)

Out[164]:

 $\frac{\sqrt{715}}{143}$

In [116]: wigner_3j(2, 6, 4, 0, 0, 1)

Out[116]:

0

and

$$Y_j^p = Y_j^p(\theta, \phi)$$

$$c_{l,m,1} = \sqrt{(l-m)(l+m+1)}$$

$$c_{l,m,2} = \sqrt{(l+m)(l-m+1)}$$

using some nice tricks of spherical harmonics, it can be shown that:

$$\frac{1}{2}(c_{j,p,1}c_{l,m,2}\alpha_{l,m-1,j,p+1,k} + c_{j,p,2}C_{l,m,1}\alpha_{l,m+1,j,p-1,k}) + mp\alpha_{l,m,j,p,k}$$

$$= \frac{1}{2}\left[\frac{(2l+1)(2j+1)(2k+1)}{4\pi}\right]^{1/2} * \begin{pmatrix} j & l & k \\ 0 & 0 & 0 \end{pmatrix} * \left[c_{j,p,1}c_{l,m,2}\begin{pmatrix} j & l & k \\ p+1 & m-1 & -(m+p) \end{pmatrix} + c_{j,p,2}c_{l,m,1}\begin{pmatrix} j & l \\ p-1 & m+1 & -(m+p) \end{pmatrix} + c_{j,p,2}c_{l,m,1}\begin{pmatrix} j & l \\ p-1 & m+1 & -(m+p) \end{pmatrix} = \frac{1}{2}\left[\frac{(2l+1)(2j+1)(2k+1)}{4\pi}\right]^{1/2} * \begin{pmatrix} j & l & k \\ 0 & 0 & 0 \end{pmatrix} * \begin{pmatrix} k & j & l \\ -(m+p) & p & m \end{pmatrix} * (k^2-j^2-l^2+k-j-(-2pm+2pm))$$

$$= \frac{1}{2}\left[\frac{(2l+1)(2j+1)(2k+1)}{4\pi}\right]^{1/2} * \begin{pmatrix} k & j & l \\ 0 & 0 & 0 \end{pmatrix} * \begin{pmatrix} k & j & l \\ -(m+p) & p & m \end{pmatrix} * (k^2-j^2-l^2+k-j-l)$$

$$= \alpha_{l,m,j,p,k} * \frac{1}{2}(k^2-j^2-l^2+k-j-l)$$

3.1 so, in the end we have

$$\vec{R}Y_j^p \cdot \vec{R}Y_l^m = (-1)^{m+p} \sum_{k=|l-j|}^{l+j} Y_k^{m+p} * \alpha_{l,m,j,p,k} * \frac{1}{2} (k^2 - j^2 - l^2 + k - j - l)$$

```
In [161]: from sympy import *
    from sympy.physics.wigner import wigner_3j
    init_printing(use_latex='mathjax')

def dot_rota_grad_SH(j, p, l, m, theta, phi):
    temp=0
    for k in range(abs(1-j), 1+j +1):
        temp+=Ynm(k, m+p, theta,phi)*alpha(1,m,j,p,k)/2*(k**2-j**2-l**2+k-j-1)

    return (-S(1))**(m+p)*temp

def alpha(1,m,j,p,k):
    return sqrt((2*l+1)*(2*j+1)*(2*k+1)/(4*pi))*wigner_3j(j, l, k, 0, 0, 0)*wigner_3j(j, l, k)

print dot_rota_grad_SH(2,6,2,2,0,0)
```

if num:

0

These codes are now incorporated in SymPy, feel free to contact the author if you need help

```
return wigner_3j(*self.args)
                                                             else:
                                                                           return self
                                  def alpha(1,m,j,p,k):
                                                return sqrt((2*l+1)*(2*j+1)*(2*k+1)/(4*pi)) * Wigner3j(j, 1, k, S(0), S(0), S(0))*Wigner3
                                  def dot_rota_grad_SH(j, p, l, m, theta, phi):
                                                j = sympify(j)
                                                p = sympify(p)
                                                1 = sympify(1)
                                                m = sympify(m)
                                                theta = sympify(theta)
                                                phi = sympify(phi)
                                                k = Dummy("k")
                                                return (-S(1))**(m+p) * Sum(Ynm(k, m+p, theta, phi)*alpha(1,m,j,p,k)/2 *(k**2-j**2-1**2+k) * (k**2-j**2-1**2+k) 
In [169]: var("j p l m theta phi")
                                   #dot_rota_grad_SH(1, 5, 1, 1, 1, 2)
                                  dot_rota_grad_SH(2,0,2,1,theta,phi)
Out [169]:
                          -\sum_{k=0}^{4} \frac{\sqrt{50k+25}}{4\sqrt{\pi}} \left(k^2+k-12\right) Y_k^1(\theta,\phi) Wigner 3j(2,2,k,0,0,0) Wigner 3j(2,2,k,0,1,-1)
In [170]: print _.doit()
-3*sqrt(5)*Ynm(2, 1, theta, phi)/(14*sqrt(pi)) + 2*sqrt(30)*Ynm(4, 1, theta, phi)/(7*sqrt(pi))
In [171]: _.expand(func=True)
Out[171]:
-\sum_{k=0}^{k} \left(\frac{\sqrt{(307.25)}}{(\frac{1}{164.10})^2} + \frac{1}{\sqrt{(44.10)}} + \frac{1}{64.10}} e^{-\frac{1}{16}} P_k^{(1)}(\cos(\theta)) Wigner3j(2,2_k,0,0,0) Wigner3j(2,2_k,0,1,-1) + \frac{\sqrt{(307.25)}}{(\frac{1}{164.10})^2} P_k^{(2)}(\cos(\theta)) Wigner3j(2,2_k,0,1,-1) - \frac{\sqrt{(307.25)}}{(\frac{1}{164.10})^2} P_k^{(2)}(\cos(\theta)) Wigner3j(2,2_k,0,0,0) Wi
In [173]: for j in range(2):
                                                for p in range(-j, j+1):
                                                             for 1 in range(2):
                                                                           for m in range(-1, 1+1):
                                                                                         print j, p, l, m, dot_rota_grad_SH(j, p, l, m, theta, phi).doit()
0 0 0 0 0
0 0 1 -1 0
0 0 1 0 0
0 0 1 1 0
1 -1 0 0 0
1 -1 1 -1 sqrt(30)*exp(-4*I*phi)*Ynm(2, 2, theta, phi)/(10*sqrt(pi))
1 -1 1 0 -sqrt(15)*exp(-2*I*phi)*Ynm(2, 1, theta, phi)/(10*sqrt(pi))
1 -1 1 Ynm(0, 0, theta, phi)/sqrt(pi) + sqrt(5)*Ynm(2, 0, theta, phi)/(10*sqrt(pi))
1 0 0 0 0
1 0 1 -1 -sqrt(15)*exp(-2*I*phi)*Ynm(2, 1, theta, phi)/(10*sqrt(pi))
1 0 1 0 -Ynm(0, 0, theta, phi)/sqrt(pi) + sqrt(5)*Ynm(2, 0, theta, phi)/(5*sqrt(pi))
1 0 1 1 sqrt(15)*Ynm(2, 1, theta, phi)/(10*sqrt(pi))
1 1 0 0 0
1 1 1 -1 Ynm(0, 0, theta, phi)/sqrt(pi) + sqrt(5)*Ynm(2, 0, theta, phi)/(10*sqrt(pi))
1 1 1 0 sqrt(15)*Ynm(2, 1, theta, phi)/(10*sqrt(pi))
1 1 1 1 sqrt(30)*Ynm(2, 2, theta, phi)/(10*sqrt(pi))
```

In []:

In []: