assignment2

April 25, 2021

1 [COM6513] Assignment 2: Text Classification with a Feedforward Network

1.0.1 Instructor: Nikos Aletras

The goal of this assignment is to develop a Feedforward neural network for text classification.

For that purpose, you will implement:

- Text processing methods for transforming raw text data into input vectors for your network (2 marks)
- A Feedforward network consisting of:
 - One-hot input layer mapping words into an Embedding weight matrix (2 marks)
 - One hidden layer computing the mean embedding vector of all words in input followed by a ReLU activation function (2 marks)
 - Output layer with a softmax activation. (2 marks)
- The Stochastic Gradient Descent (SGD) algorithm with **back-propagation** to learn the weights of your Neural network. Your algorithm should:
 - Use (and minimise) the Categorical Cross-entropy loss function (2 marks)
 - Perform a **Forward pass** to compute intermediate outputs (**5 marks**)
 - Perform a Backward pass to compute gradients and update all sets of weights (12 marks)
 - Implement and use **Dropout** after each hidden layer for regularisation (4 marks)
- Discuss how did you choose hyperparameters? You can tune the learning rate (hint: choose small values), embedding size {e.g. 50, 300, 500}, the dropout rate {e.g. 0.2, 0.5} and the learning rate. Please use tables or graphs to show training and validation performance for each hyperparameter combination (5 marks).
- After training a model, plot the learning process (i.e. training and validation loss in each epoch) using a line plot and report accuracy. Does your model overfit, underfit or is about right? (2 marks).
- Re-train your network by using pre-trained embeddings (GloVe) trained on large corpora. Instead of randomly initialising the embedding weights matrix, you should initialise it with the pre-trained weights. During training, you should not update them (i.e. weight freezing) and backprop should stop before computing gradients for updating embedding weights. Report results by performing hyperparameter tuning and plotting the learning process. Do you get better performance? (7 marks).

- Extend you Feedforward network by adding more hidden layers (e.g. one more or two). How does it affect the performance? Note: You need to repeat hyperparameter tuning, but the number of combinations grows exponentially. Therefore, you need to choose a subset of all possible combinations (8 marks)
- Provide well documented and commented code describing all of your choices. In general, you are free to make decisions about text processing (e.g. punctuation, numbers, vocabulary size) and hyperparameter values. We expect to see justifications and discussion for all of your choices (5 marks).
- Provide efficient solutions by using Numpy arrays when possible. Executing the whole notebook with your code should not take more than 10 minutes on any standard computer (e.g. Intel Core i5 CPU, 8 or 16GB RAM) excluding hyperparameter tuning runs and loading the pretrained vectors. You can find tips in Intro to Python for NLP (2 marks).

1.0.2 Data

The data you will use for the task is a subset of the AG News Corpus and you can find it in the ./data_topic folder in CSV format:

- data_topic/train.csv: contains 2,400 news articles, 800 for each class to be used for training.
- data_topic/dev.csv: contains 150 news articles, 50 for each class to be used for hyperparameter selection and monitoring the training process.
- data_topic/test.csv: contains 900 news articles, 300 for each class to be used for testing.

1.0.3 Pre-trained Embeddings

You can download pre-trained GloVe embeddings trained on Common Crawl (840B tokens, 2.2M vocab, cased, 300d vectors, 2.03 GB download) from here. No need to unzip, the file is large.

1.0.4 Save Memory

To save RAM, when you finish each experiment you can delete the weights of your network using del W followed by Python's garbage collector gc.collect()

1.0.5 Submission Instructions

You should submit a Jupyter Notebook file (assignment2.ipynb) and an exported PDF version (you can do it from Jupyter: File->Download as->PDF via Latex).

You are advised to follow the code structure given in this notebook by completing all given functions. You can also write any auxilliary/helper functions (and arguments for the functions) that you might need but note that you can provide a full solution without any such functions. Similarly, you can just use only the packages imported below but you are free to use any functionality from the Python Standard Library, NumPy, SciPy (excluding built-in softmax functions) and Pandas. You are not allowed to use any third-party library such as Scikit-learn (apart from metric functions already provided), NLTK, Spacy, Keras, Pytorch etc.. You should mention if you've used Windows to write and test your code because we mostly use Unix based machines for marking (e.g. Ubuntu, MacOS).

There is no single correct answer on what your accuracy should be, but correct implementations usually achieve F1-scores around 80% or higher. The quality of the analysis of the results is as important as the accuracy itself.

This assignment will be marked out of 60. It is worth 60% of your final grade in the module.

The deadline for this assignment is **23:59** on Fri, **23** Apr **2021** and it needs to be submitted via Blackboard. Standard departmental penalties for lateness will be applied. We use a range of strategies to **detect unfair means**, including Turnitin which helps detect plagiarism. Use of unfair means would result in getting a failing grade.

1.1 Transform Raw texts into training and development data

First, you need to load the training, development and test sets from their corresponding CSV files (tip: you can use Pandas dataframes).

```
[2]: train_data = pd.read_csv('./data_topic/train.csv', header=None)
  dev_data = pd.read_csv('./data_topic/dev.csv', header=None)
  test_data = pd.read_csv('./data_topic/test.csv', header=None)
```

```
[3]: #sample of the data
train_data.head(5)
#dev_data.head(5)
#test_data.head(5)
```

[3]: 0 1

O 1 Reuters - Venezuelans turned out early\and in ...
1 1 Reuters - South Korean police used water canno...
2 1 Reuters - Thousands of Palestinian\prisoners i...
3 1 AFP - Sporadic gunfire and shelling took place...
4 1 AP - Dozens of Rwandan soldiers flew into Suda...

```
[4]: #info about the each dataset
    train_data.info()
    dev_data.info()
    test_data.info()
    <class 'pandas.core.frame.DataFrame'>
    RangeIndex: 2400 entries, 0 to 2399
    Data columns (total 2 columns):
        Column Non-Null Count Dtype
        ----- -----
     0
                2400 non-null
                               int64
     1
        1
                2400 non-null
                               object
    dtypes: int64(1), object(1)
    memory usage: 37.6+ KB
    <class 'pandas.core.frame.DataFrame'>
    RangeIndex: 150 entries, 0 to 149
    Data columns (total 2 columns):
        Column Non-Null Count Dtype
        -----
     0
        \cap
                150 non-null
                                int64
     1
        1
                150 non-null
                               object
    dtypes: int64(1), object(1)
    memory usage: 2.5+ KB
    <class 'pandas.core.frame.DataFrame'>
    RangeIndex: 900 entries, 0 to 899
    Data columns (total 2 columns):
        Column Non-Null Count Dtype
        -----
                900 non-null
                               int64
     1
        1
                900 non-null
                               object
    dtypes: int64(1), object(1)
    memory usage: 14.2+ KB
[5]: #distribution of the class and check for missing entries
    print(train_data[0].value_counts('1'))
    print(dev_data[0].value_counts('1'))
    print(test_data[0].value_counts('1'))
        0.333333
    3
    1
        0.333333
        0.333333
    Name: 0, dtype: float64
        0.333333
    2
        0.333333
        0.333333
    1
    Name: 0, dtype: float64
    3
        0.333333
    2
        0.333333
```

1 0.333333

Name: 0, dtype: float64

```
[6]: #check for any Null values
print("Train_data:", sum(np.isnan(train_data[0])))
print("Validation_data:", sum(np.isnan(dev_data[0])))
print("Test_data:", sum(np.isnan(test_data[0])))
```

Train_data: 0
Validation_data: 0
Test_data: 0

No missing values found in the datasets and all the three classes are equally distributed in train, dev and test sets indicating a balanced dataset.

2 Create input representations

To train your Feedforward network, you first need to obtain input representations given a vocabulary. One-hot encoding requires large memory capacity. Therefore, we will instead represent documents as lists of vocabulary indices (each word corresponds to a vocabulary index).

2.1 Text Pre-Processing Pipeline

To obtain a vocabulary of words. You should: - tokenise all texts into a list of unigrams (tip: you can re-use the functions from Assignment 1) - remove stop words (using the one provided or one of your preference) - remove unigrams appearing in less than K documents - use the remaining to create a vocabulary of the top-N most frequent unigrams in the entire corpus.

```
[8]: train_data_txt = list(train_data[1])
  dev_data_txt = list(dev_data[1])
  test_data_txt = list(test_data[1])
```

2.1.1 Unigram extraction from a document

You first need to implement the extract_ngrams function. It takes as input:

- x_raw: a string corresponding to the raw text of a document
- ngram_range: a tuple of two integers denoting the type of ngrams you want to extract, e.g. (1,2) denotes extracting unigrams and bigrams.

- token_pattern: a string to be used within a regular expression to extract all tokens. Note that data is already tokenised so you could opt for a simple white space tokenisation.
- stop_words: a list of stop words
- vocab: a given vocabulary. It should be used to extract specific features.

and returns:

• a list of all extracted features.

```
[9]: def extract_ngrams(x_raw, ngram_range=(1,3),__
      \rightarrowtoken_pattern=r'\b[A-Za-z][A-Za-z]+\b',
                        stop_words=[], vocab=set()):
         tokenRE = re.compile(token_pattern)
         # first extract all unigrams by tokenising
         x uni = [w for w in tokenRE.findall(str(x raw).lower(),) if w not in_
      →stop_words]
         # this is to store the ngrams to be returned
         x = []
         if ngram_range[0] == 1:
             x = x_uni
         # generate n-grams from the available unigrams x_uni
         ngrams = []
         for n in range(ngram_range[0], ngram_range[1]+1):
         # ignore unigrams
             if n==1: continue
             # pass a list of lists as an argument for zip
             arg_list = [x_uni]+[x_uni[i:] for i in range(1, n)]
             # extract tuples of n-grams using zip
             # for bigram this should look: list(zip(x_uni, x_uni[1:]))
             # align each item x[i] in x_uni with the next one x[i+1].
             # Note that x_uni and x_uni[1:] have different lenghts
             # but zip ignores redundant elements at the end of the second list
             # Alternatively, this could be done with for loops
             x_ngram = list(zip(*arg_list))
             ngrams.append(x_ngram)
```

```
for n in ngrams:
    for t in n:
        x.append(t)

if len(vocab)>0:
    x = [w for w in x if w in vocab]

return x
```

```
['reuters', 'venezuelans', 'turned', 'out', 'early', 'large', 'numbers',
'sunday', 'vote', 'historic']
['govern', 'next', 'two']
```

2.1.2 Create a vocabulary of n-grams

Then the get_vocab function will be used to (1) create a vocabulary of ngrams; (2) count the document frequencies of ngrams; (3) their raw frequency. It takes as input:

- X_raw: a list of strings each corresponding to the raw text of a document
- ngram_range: a tuple of two integers denoting the type of ngrams you want to extract, e.g. (1,2) denotes extracting unigrams and bigrams.
- token_pattern: a string to be used within a regular expression to extract all tokens. Note that data is already tokenised so you could opt for a simple white space tokenisation.
- stop_words: a list of stop words
- min_df: keep ngrams with a minimum document frequency.
- keep_topN: keep top-N more frequent ngrams.

and returns:

- vocab: a set of the n-grams that will be used as features.
- df: a Counter (or dict) that contains ngrams as keys and their corresponding document frequency as values.
- ngram_counts: counts of each ngram in vocab

```
df = Counter()
  ngram_counts = Counter()
  vocab = set()
  # interate through each raw text
  for x in X_raw:
      x_ngram = extract_ngrams(x, ngram_range=ngram_range,_
→token pattern=token pattern,
                                stop_words=stop_words)
       #update doc and ngram frequencies
      df.update(list(set(x_ngram)))
      ngram_counts.update(x_ngram)
  # obtain a vocabulary as a set.
   # Keep elements with doc frequency > minimum doc freq (min df)
  # Note that df contains all te
  vocab = set([w for w in df if df[w]>=min df])
  # keep the top N most fregent
  if keep topN>0:
      vocab = set([w[0] for w in ngram_counts.most_common(keep_topN)
                    if w[0] in vocab])
  return vocab, df, ngram_counts
```

Now you should use get_vocab to create your vocabulary and get document and raw frequencies of unigrams:

The vocabulary for sentiment analysis is created by choosing the parameters of min_df, keep_topN to be 3 and 2500 respectively so as to restrict the size of vocabulary and to reduce the sparcity of the feature vector matrix.

Then, you need to create vocabulary id -> word and word -> vocabulary id dictionaries for reference:

```
[14]: id2word_bow = {i:list(vocab_bow)[i] for i in range(len(vocab_bow))}
word2id_bow = {list(vocab_bow)[i]:i for i in range(len(vocab_bow))}
```

2.1.3 Convert the list of unigrams into a list of vocabulary indices

Storing actual one-hot vectors into memory for all words in the entire data set is prohibitive. Instead, we will store word indices in the vocabulary and look-up the weight matrix. This is equivalent of doing a dot product between an one-hot vector and the weight matrix.

First, represent documents in train, dev and test sets as lists of words in the vocabulary:

```
[16]: #sample extracted n-grams of the document train_bow[5]
```

```
[16]: ['reuters',
       'rwandan',
       'troops',
       'sunday',
       'sudan',
       'darfur',
       'first',
       'foreign',
       'force',
       'protect',
       'observers',
       'monitoring',
       'cease',
       'fire',
       'between',
       'sudanese',
       'government',
       'rebels',
       'troubled',
       'western',
```

'region']

```
Then convert them into lists of indices in the vocabulary:
```

```
[17]: #conversion of bow to bow indices for each dataset
    train_boi = [[word2id_bow.get(item,item) for item in doc] for doc in train_bow]
    dev_boi = [[word2id_bow.get(item,item) for item in doc] for doc in dev_bow]
    test_boi = [[word2id_bow.get(item,item) for item in doc] for doc in test_bow]

[18]: #sample list of word indices of the document
    train_boi[5]

[18]: [64,
    2333,
    1581,
    107,
    828,
```

1932, 1974, 471,

1013, 540, 860, 2344,

1632,

1398,

534,

1655,

1536,

1552,

1225,

2076,

1389]

Put the labels Y for train, dev and test sets into arrays:

```
[19]: #create label variables
    train_data_lbl = np.array(train_data[0])
    dev_data_lbl = np.array(dev_data[0])
    test_data_lbl = np.array(test_data[0])
```

3 Network Architecture

Your network should pass each word index into its corresponding embedding by looking-up on the embedding matrix and then compute the first hidden layer \mathbf{h}_1 :

$$\mathbf{h}_1 = \frac{1}{|x|} \sum_i W_i^e, i \in x$$

where |x| is the number of words in the document and W^e is an embedding matrix $|V| \times d$, |V| is the size of the vocabulary and d the embedding size.

Then \mathbf{h}_1 should be passed through a ReLU activation function:

$$\mathbf{a}_1 = relu(\mathbf{h}_1)$$

Finally the hidden layer is passed to the output layer:

$$\mathbf{y} = \operatorname{softmax}(\mathbf{a}_1 W)$$

where W is a matrix $d \times |\mathcal{Y}|$, $|\mathcal{Y}|$ is the number of classes.

During training, \mathbf{a}_1 should be multiplied with a dropout mask vector (elementwise) for regularisation before it is passed to the output layer.

You can extend to a deeper architecture by passing a hidden layer to another one:

$$\mathbf{h_i} = \mathbf{a}_{i-1} W_i$$

$$\mathbf{a_i} = relu(\mathbf{h_i})$$

4 Network Training

First we need to define the parameters of our network by initiliasing the weight matrices. For that purpose, you should implement the network_weights function that takes as input:

- vocab_size: the size of the vocabulary
- embedding_dim: the size of the word embeddings
- hidden_dim: a list of the sizes of any subsequent hidden layers. Empty if there are no hidden layers between the average embedding and the output layer
- num_classes: the number of the classes for the output layer

and returns:

• W: a dictionary mapping from layer index (e.g. 0 for the embedding matrix) to the corresponding weight matrix initialised with small random numbers (hint: use numpy.random.uniform with from -0.1 to 0.1)

Make sure that the dimensionality of each weight matrix is compatible with the previous and next weight matrix, otherwise you won't be able to perform forward and backward passes. Consider also using np.float32 precision to save memory.

```
W[i] = np.random.
→uniform(-init_val,init_val,(vocab_size,embedding_dim)).astype('float32')
       elif i == 1:
           W[i] = np.random.
→uniform(-init_val,init_val,(embedding_dim,hidden_dim[i-1])).astype('float32')
       else:
           W[i] = np.random.
→uniform(-init_val,init_val,(hidden_dim[i-2],hidden_dim[i-1])).
→astype('float32')
   #weights for the output layer
  if len(hidden dim) == 0:
       W[len(hidden_dim)+1] = np.random.
→uniform(-init_val,init_val,(embedding dim,num_classes)).astype('float32')
   else:
       W[len(hidden_dim)+1] = np.random.
→uniform(-init_val,init_val,(hidden_dim[-1],num_classes)).astype('float32')
  return W
```

Then you need to develop a softmax function (same as in Assignment 1) to be used in the output layer. It takes as input z (array of real numbers) and returns sig (the softmax of z)

```
[22]: def softmax(z):
    num = np.exp(z)
    sum_num = np.sum(num, axis=0)
    sig = num/sum_num
    return sig
```

Now you need to implement the categorical cross entropy loss by slightly modifying the function from Assignment 1 to depend only on the true label y and the class probabilities vector y_preds:

```
[23]: def categorical_loss(y, y_preds):
    y_preds = np.where(y_preds==0.0, 1e-5, y_preds)
    y_preds_up = np.where(y_preds==1.0, 0.99999, y_preds)
    l = -np.log(y_preds_up[y-1])
    return 1
```

Then, implement the relu function to introduce non-linearity after each hidden layer of your network (during the forward pass):

```
relu(z_i) = max(z_i, 0)
```

and the relu_derivative function to compute its derivative (used in the backward pass): relu_derivative(z_i)=0, if z_i <=0, 1 otherwise.

Note that both functions take as input a vector z

Hint use .copy() to avoid in place changes in array z

```
[24]: def relu(z):
    a = np.maximum(z,0)
    return a

def relu_derivative(z):
    dz = z.copy()
    dz[z <= 0] = 0;
    dz[z > 0] = 1;
    return dz
```

During training you should also apply a dropout mask element-wise after the activation function (i.e. vector of ones with a random percentage set to zero). The dropout_mask function takes as input:

- size: the size of the vector that we want to apply dropout
- dropout_rate: the percentage of elements that will be randomly set to zeros

and returns:

• dropout_vec: a vector with binary values (0 or 1)

```
[25]: def dropout_mask(size, dropout_rate):
    dropout_vec = np.ones(size, dtype=float)
    idx = np.random.choice(range(size), round(size*dropout_rate), replace=False)
    #rounding to the integer value
    dropout_vec[idx] = 0

    return dropout_vec
```

```
[26]: print(dropout_mask(10, 0.2)) print(dropout_mask(10, 0.2))
```

```
[0. 1. 1. 1. 0. 1. 1. 1. 1. 1.]
[1. 1. 1. 0. 1. 0. 1. 1. 1. 1.]
```

Now you need to implement the forward_pass function that passes the input x through the network up to the output layer for computing the probability for each class using the weight matrices in W. The ReLU activation function should be applied on each hidden layer.

- x: a list of vocabulary indices each corresponding to a word in the document (input)
- W: a list of weight matrices connecting each part of the network, e.g. for a network with a hidden and an output layer: W[0] is the weight matrix that connects the input to the first hidden layer, W[1] is the weight matrix that connects the hidden layer to the output layer.
- dropout_rate: the dropout rate that is used to generate a random dropout mask vector applied after each hidden layer for regularisation.

and returns:

• out_vals: a dictionary of output values from each layer: h (the vector before the activation function), a (the resulting vector after passing h from the activation function), its dropout mask vector; and the prediction vector (probability for each class) from the output layer.

```
[27]: def forward_pass(x, W, dropout_rate=0.2):
          out_vals = {}
          h_vecs = []
          a_vecs = []
          dropout_vecs = []
          for layer in range(len(W)-1):
              if layer == 0:
                  w_vec = [W[layer][indx] for indx in x]
                  h_i = np.sum(w_vec,axis=0)/len(x)
              else:
                  h_i = np.dot(ad_i, W[layer])
              h_vecs.append(h_i)
              a_i = relu(h_i)
              a_vecs.append(a_i)
              #print(a_i)
              #print(a_vecs)
              d_i = dropout_mask(len(a_i), dropout_rate)
              dropout_vecs.append(d_i)
              ad_i = np.multiply(a_i, d_i) #activation output with dropout
          #predictions at the output layer
          pred = softmax(np.dot(ad_i,W[len(W)-1]))
          out_vals['h'] = h_vecs
          out_vals['a'] = a_vecs
          out_vals['d'] = dropout_vecs
          out_vals['y_pred'] = pred
          return out_vals
```

The backward_pass function computes the gradients and updates the weights for each matrix in the network from the output to the input. It takes as input

- x: a list of vocabulary indices each corresponding to a word in the document (input)
- y: the true label
- W: a list of weight matrices connecting each part of the network, e.g. for a network with a hidden and an output layer: W[0] is the weight matrix that connects the input to the first hidden layer, W[1] is the weight matrix that connects the hidden layer to the output layer.
- out_vals: a dictionary of output values from a forward pass.
- learning_rate: the learning rate for updating the weights.
- freeze_emb: boolean value indicating whether the embedding weights will be updated.

and returns:

• W: the updated weights of the network.

Hint: the gradients on the output layer are similar to the multiclass logistic regression.

```
[28]: def backward_pass(x, y, W, out_vals, lr=0.001, freeze_emb=False):
          for layer in range(len(W)-1,0,-1):
              if layer == len(W)-1:
                  y_cls = np.zeros(W[layer].shape[1])
                  y_cls[y-1] = 1
                  g_l = out_vals['y_pred'] - y_cls
                  ad_l = np.multiply(out_vals['a'][-1],out_vals['d'][-1]).
       \rightarrowreshape(W[layer].shape[0],1)
                  dw_l = np.dot(ad_l, g_l.reshape(1,W[layer].shape[1]))
                  g_l = np.multiply(np.dot(W[layer],g_l).reshape(1,W[layer].
       ⇒shape[0]), out_vals['d'][layer-1])
                  W[layer] = W[layer] - lr*dw l
              else:
                  g_l = np.multiply(g_l, relu_derivative(out_vals['h'][layer]).
       →reshape(1, W[layer+1].shape[0]))
                  ad 1 = np.multiply(out_vals['a'][layer-1], out_vals['d'][layer-1]).
       →reshape(W[layer].shape[0],1)
                  dw l = np.dot(ad l, g l)
                  g_l = np.multiply(np.dot(W[layer],g_l.T).reshape(1,W[layer].

¬shape[0]), out_vals['d'][layer-1])
                  W[layer] = W[layer] - lr*dw_l
          if not freeze_emb:
              x_{en} = np.zeros([W[0].shape[0],1])
              x_en[x] = 1
              g_1 = g_1 * relu_derivative(out_vals['h'][0]).reshape(1, W[0].shape[1])
              dw_1 = np.dot(x_en,g_1)
              W[0] = W[0] - lr*dw_1
          return W
```

Finally you need to modify SGD to support back-propagation by using the forward_pass and backward_pass functions.

The SGD function takes as input:

- X_tr: array of training data (vectors)
- Y_tr: labels of X_tr
- W: the weights of the network (dictionary)
- X_dev: array of development (i.e. validation) data (vectors)
- Y_dev: labels of X_dev
- 1r: learning rate
- dropout: regularisation strength
- epochs: number of full passes over the training data
- tolerance: stop training if the difference between the current and previous validation loss is smaller than a threshold
- freeze_emb: boolean value indicating whether the embedding weights will be updated (to be used by the backward pass function).
- print_progress: flag for printing the training progress (train/validation loss)

and returns:

- weights: the weights learned
- training_loss_history: an array with the average losses of the whole training set after each epoch
- validation_loss_history: an array with the average losses of the whole development set after each epoch

```
[29]: def SGD(X_tr, Y_tr, W, X_dev=[], Y_dev=[], lr=0.001,
              dropout=0.2, epochs=5, tolerance=0.001, freeze_emb=False,
              print progress=True):
          training_loss_history = []
          validation loss history = []
          stop train = False
          for epoch in range(epochs): # loop over the dataset multiple times
              #randomise train set
              index = list(range(len(X_tr)))
              random.Random(epoch).shuffle(index)
              x_tr = (np.array(X_tr)[index]).tolist()
              y_tr = Y_tr[index]
              running_loss = 0.0
              loss = 0.0
              le_tr = len(x_tr)
              for i in range(len(X_tr)):
                  if len(x tr[i]) != 0: #check for empty indices input
                      out_vals = forward_pass(x_tr[i], W, dropout_rate=dropout)
                      W = backward_pass(x_tr[i], y_tr[i], W, out_vals, lr=lr,_
       →freeze emb=freeze emb)
```

```
running_loss = categorical_loss(y_tr[i], out_vals['y_pred'])
              loss += running_loss
          else:
              le_tr = le_tr-1 #if empty reducing the size of the input
       #training
      avg_loss = loss/le_tr
      training_loss_history.append(avg_loss)
       # print progress
      if(print_progress):
           print('train_epoch: %d, loss: %.4f' % (epoch + 1, avg_loss))
       #validation
       if len(X_dev) !=0 and len(Y_dev) !=0:
          running_loss_dev = 0.0
          loss_dev = 0.0
          le_dev = len(X_dev)
          for i in range(len(X_dev)):
              if len(X_dev[i]) != 0:
                  out_vals = forward_pass(X_dev[i], W, dropout_rate=dropout)
                  running_loss_dev =
loss_dev += running_loss_dev
              else:
                  le_dev = le_dev-1
          avg_loss_dev = loss_dev/le_dev
          validation_loss_history.append(avg_loss_dev)
           # print progress
          if(print_progress):
              print('dev_epoch: %d, loss: %.4f' % (epoch + 1, avg_loss_dev))
           if (epoch > 3 and abs(validation_loss_history[epoch-1] -__
→validation_loss_history[epoch]) < tolerance):</pre>
              break
  training_loss_history = np.array(training_loss_history)
  validation_loss_history = np.array(validation_loss_history)
  return W, training_loss_history, validation_loss_history
```

Now you are ready to train and evaluate your neural net. First, you need to define your network using the network_weights function followed by SGD with backprop:

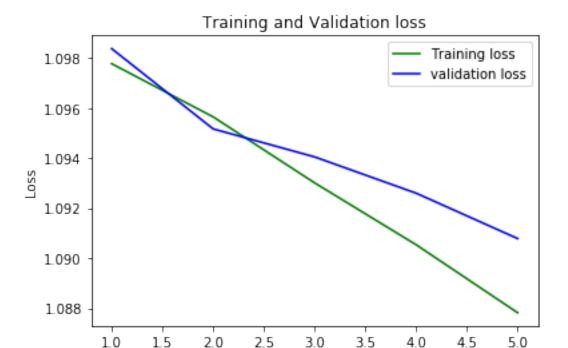
```
Shape W0 (2492, 300)
Shape W1 (300, 3)
train_epoch: 1, loss: 1.0978
dev_epoch: 1, loss: 1.0984
train_epoch: 2, loss: 1.0956
dev_epoch: 2, loss: 1.0952
train_epoch: 3, loss: 1.0930
dev_epoch: 3, loss: 1.0940
train_epoch: 4, loss: 1.0905
dev_epoch: 4, loss: 1.0926
train_epoch: 5, loss: 1.0878
dev_epoch: 5, loss: 1.0908
```

Plot the learning process:

```
[31]: #function to plot the training and validation loss history

def plot_loss(training_loss, validation_loss):
    epochs = np.linspace(1,len(training_loss),len(training_loss))
    plt.plot(epochs, training_loss, 'g', label='Training loss')
    plt.plot(epochs, validation_loss, 'b', label='validation loss')
    plt.title('Training and Validation loss')
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.legend()
    plt.show()
```

```
[32]: plot_loss(loss_tr, dev_loss)
```



Epochs

Compute accuracy, precision, recall and F1-Score:

```
[34]: #evaluation of metrics on the validation data get_evaluation_metrics(dev_boi, dev_data_lbl, W)
```

```
[35]: #evaluation of metrics on the test data
      get_evaluation_metrics(test_boi, test_data_lbl, W)
     Accuracy: 0.6618464961067854
     Precision: 0.6816487024737411
     Recall: 0.6615198810850984
     F1-Score: 0.6427287572304755
     4.0.1 Discuss how did you choose model hyperparameters?
[36]: random.seed(123)
      np.random.seed(123)
[37]: lr=[0.001,0.01,0.1]
      epochs=[30,50,100]
      tolerance=[0.01]
      dropout = [0.2, 0.5, 0.7]
      embedding_dim = [100, 300, 500]
      hidden_dim = []
[38]: # Implementation of hyperparameter tuning
      def hypertune(X_tr, Y_tr, X_dev, Y_dev, iterate=10, print_metrics=True,_
       →use_pretrained=False):
          eval_ht = []
          param_ht = []
          hd_d = []
          for i in range(iterate):
              a,b,c,d = random.Random(i).choices(range(3), k=4)
              if len(embedding_dim) == 1:
              if len(epochs) == 1:
                  d = 0
              if len(hidden_dim) != 0:
                  hd d = hidden dim[random.Random(i).choice(range(len(hidden dim)))]
              w =
       →network weights(vocab size=len(vocab bow), embedding dim=embedding dim[a],
       →hidden_dim=hd_d, num_classes=3, init_val = 0.1)
              if use_pretrained:
                  w[0] = w_glove
                  w, tl, vl = SGD(X_tr, Y_tr, w, X_dev, Y_dev, lr[b], dropout[c], u
       →epochs=epochs[d], freeze_emb=True, tolerance=0.01, print_progress=False)
              else:
                  w, tl, vl = SGD(X_tr, Y_tr, w, X_dev, Y_dev, lr[b], dropout[c],
       →epochs=epochs[d], freeze_emb=False, tolerance=0.01, print_progress=False)
              \#training\_loss\_ht.append(tl)
              #validation_loss_ht.append(vl)
```

```
preds_te = [np.argmax(forward_pass(x, w, dropout_rate=0.0)['y_pred'])+1
                for x,y in zip(X_dev,Y_dev)]
            eval_dict = {'Ac':accuracy_score(Y_dev,preds_te), 'Pr':

→precision_score(Y_dev,preds_te,average='macro'),
                     'Re':recall_score(Y_dev,preds_te,average='macro'), 'F1':

→f1 score(Y dev,preds te,average='macro')}
            eval_ht.append(eval_dict)
            param_ht.append({'lr':lr[b], 'epochs':epochs[d], 'dropout':dropout[c],__

    -- 'embedding_dim': embedding_dim[a], 'hidden_dim': hd_d,
                            'epochs threshold dev':len(vl)})
         indx = sorted(range(len(eval_ht)), key=lambda k: eval_ht[k]['Ac'],
      →reverse=True)
        eval_ht_sorted = [eval_ht[i] for i in indx]
        param_ht_sorted = [param_ht[i] for i in indx]
        if print_metrics:
            print("Evaluation Metrics:", np.array(eval_ht_sorted[:5]))
            print("\nParameters:", np.array(param ht sorted[:5]))
[40]: ##hypertuning with subset of randomly chosen values of all possible iterations_
      \rightarrow (81)
     #hypertune(train_boi, train_data_lbl, dev_boi, dev_data_lbl, 50, True)
    0.9133333333333334, 'F1': 0.9143278018278019}
     'F1': 0.9079306250802207}
     'F1': 0.9079306250802207}
     {'Ac': 0.9, 'Pr': 0.9074317738791423, 'Re': 0.9, 'F1': 0.9014987401748696}
     {'Ac': 0.9, 'Pr': 0.9074317738791423, 'Re': 0.9, 'F1': 0.9014987401748696}]
    Parameters: [{'lr': 0.01, 'epochs': 30, 'dropout': 0.7, 'embedding dim': 300,
     'hidden_dim': [], 'epochs_threshold_dev': 22}
     {'lr': 0.01, 'epochs': 30, 'dropout': 0.5, 'embedding_dim': 100, 'hidden_dim':
     [], 'epochs threshold dev': 15}
     {'lr': 0.01, 'epochs': 100, 'dropout': 0.5, 'embedding_dim': 500, 'hidden_dim':
     [], 'epochs_threshold_dev': 19}
     {'lr': 0.01, 'epochs': 50, 'dropout': 0.5, 'embedding_dim': 100, 'hidden_dim':
     [], 'epochs_threshold_dev': 16}
     {'lr': 0.01, 'epochs': 100, 'dropout': 0.2, 'embedding_dim': 300, 'hidden_dim':
     [], 'epochs_threshold_dev': 10}]
```

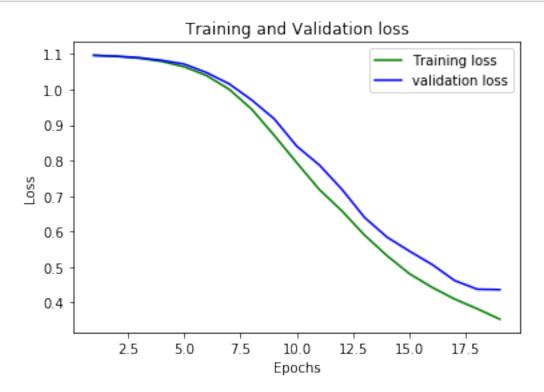
Below is the table with top 5 best performed combinations of hypertuned parameters

	lr	dropout	embedding_dim	accuracy	f1-score	epoch
1	0.01	0.7	300	0.9133	0.9143	30
2	0.01	0.5	100	0.9066	0.9079	30
3	0.01	0.5	500	0.9066	0.9079	100
4	0.01	0.5	100	0.9074	0.9014	50
5	0.01	0.2	300	0.9074	0.9014	100

Accuracy and the F-1 score of the validation is improved with hypertuning. The best performance for validation is achieved with higher dropout_rate (0.7) and learning rate(0.01), and the default value for embedding_dim(300) and epochs(30).

train_epoch: 1, loss: 1.0972 dev_epoch: 1, loss: 1.0959 train_epoch: 2, loss: 1.0936 dev_epoch: 2, loss: 1.0940 train_epoch: 3, loss: 1.0884 dev epoch: 3, loss: 1.0899 train_epoch: 4, loss: 1.0795 dev_epoch: 4, loss: 1.0824 train_epoch: 5, loss: 1.0644 dev_epoch: 5, loss: 1.0720 train_epoch: 6, loss: 1.0394 dev_epoch: 6, loss: 1.0478 train_epoch: 7, loss: 1.0008 dev_epoch: 7, loss: 1.0162 train_epoch: 8, loss: 0.9448 dev_epoch: 8, loss: 0.9706 train_epoch: 9, loss: 0.8707 dev_epoch: 9, loss: 0.9173 train_epoch: 10, loss: 0.7935 dev_epoch: 10, loss: 0.8403 train_epoch: 11, loss: 0.7181 dev_epoch: 11, loss: 0.7873 train_epoch: 12, loss: 0.6580 dev_epoch: 12, loss: 0.7188
train_epoch: 13, loss: 0.5898
dev_epoch: 13, loss: 0.6398
train_epoch: 14, loss: 0.5316
dev_epoch: 14, loss: 0.5840
train_epoch: 15, loss: 0.4806
dev_epoch: 15, loss: 0.5443
train_epoch: 16, loss: 0.5443
train_epoch: 16, loss: 0.5068
train_epoch: 17, loss: 0.4094
dev_epoch: 17, loss: 0.4616
train_epoch: 18, loss: 0.3821
dev_epoch: 18, loss: 0.4372
train_epoch: 19, loss: 0.3526
dev_epoch: 19, loss: 0.4360

[42]: plot_loss(loss_tr, dev_loss)



The model looks a good fit as the validation loss and training loss are close and follow a similar pattern.

[44]: #evaluation of metrics on the test data with hypertuned model get_evaluation_metrics(test_boi, test_data_lbl, W)

Accuracy: 0.8531701890989989

Precision: 0.8551698361224064 Recall: 0.8531475287997027 F1-Score: 0.8523707229104804

The hypertune method is executed for a combination of higher learning rates (lr), dropout rate and lower epochs along with the mix of embedding_dimension. Higher learning rates are chosen so that the learning process will be faster and reduces the number of training steps the network need to converge. As the learning rate values are increased the epoch size is reduced which should be sufficient for the model to converge given the tolerance and the default model(converged in 5 epochs). The dropout rate (regularisation) will help in penalizing the network to be sensitive to the specific weights of neurons which can lead to overfitting, and results in achieving a network with better generalization rather than having any affect on the performance.

The accuracy is improved significantly with the hypertuned model. A higher dropout rate is obtained from the tuning putting regularisation/restriction on picking up any patterns or unwanted noise.

5 Use Pre-trained Embeddings

Now re-train the network using GloVe pre-trained embeddings. You need to modify the backward_pass function above to stop computing gradients and updating weights of the embedding matrix. Use the function below to obtain the embedding matrix for your vocabulary. Generally, that should work without any problem. If you get errors, you can modify it.

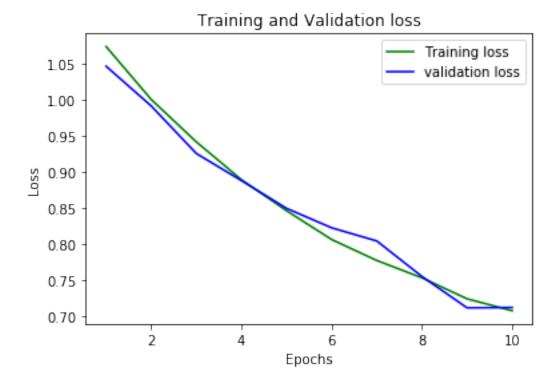
```
[46]: #choosing the embedding_dim default value

w_glove = get_glove_embeddings("glove.840B.300d.zip","glove.840B.300d.

→txt",word2id_bow, vocab=vocab_bow)
```

First, initialise the weights of your network using the network_weights function. Second, replace the weights of the embedding matrix with w_glove. Finally, train the network by freezing the embedding weights:

```
[47]: W = network_weights(vocab_size=len(vocab_bow), embedding_dim=300,__
       →hidden_dim=[], num_classes=3, init_val = 0.1)
      #replace the embedding weigths with w glove
      W[0] = w \text{ glove}
      for i in range(len(W)):
          print('Shape W'+str(i), W[i].shape)
     Shape W0 (2492, 300)
     Shape W1 (300, 3)
[48]: W, loss_tr, dev_loss = SGD(train_boi, train_data_lbl,
                                   W,
                                  X_dev=dev_boi,
                                   Y_dev=dev_data_lbl,
                                   lr=0.001,
                                   dropout=0.2,
                                   freeze_emb=True,
                                   tolerance=0.01,
                                   epochs=100)
     train_epoch: 1, loss: 1.0743
     dev_epoch: 1, loss: 1.0469
     train_epoch: 2, loss: 1.0008
     dev_epoch: 2, loss: 0.9917
     train_epoch: 3, loss: 0.9418
     dev_epoch: 3, loss: 0.9256
     train_epoch: 4, loss: 0.8892
     dev_epoch: 4, loss: 0.8880
     train_epoch: 5, loss: 0.8460
     dev_epoch: 5, loss: 0.8493
     train_epoch: 6, loss: 0.8060
     dev_epoch: 6, loss: 0.8223
     train_epoch: 7, loss: 0.7769
     dev_epoch: 7, loss: 0.8040
     train_epoch: 8, loss: 0.7528
     dev_epoch: 8, loss: 0.7547
     train_epoch: 9, loss: 0.7236
     dev_epoch: 9, loss: 0.7111
     train_epoch: 10, loss: 0.7070
     dev_epoch: 10, loss: 0.7115
[49]: plot_loss(loss_tr, dev_loss)
```



```
[50]: #evaluation of metrics on the validation data get_evaluation_metrics(dev_boi, dev_data_lbl, W)
```

Accuracy: 0.86666666666667 Precision: 0.8745627186406796 Recall: 0.866666666666667 F1-Score: 0.868055555555557

```
[51]: #evaluation of metrics on the test data get_evaluation_metrics(test_boi, test_data_lbl, W)
```

Accuracy: 0.8798665183537263 Precision: 0.8798635663121063 Recall: 0.8798327759197324 F1-Score: 0.8797433980414181

5.0.1 Discuss how did you choose model hyperparameters?

```
embedding_dim = [300] #choosing the value from average_embedding hypertuned_ \rightarrow model
```

```
[54]: ##hypertuning the model with pretrained embeddings
#hypertune(train_boi, train_data_lbl, dev_boi, dev_data_lbl, 15,
→print_metrics=True, use_pretrained=True)

Evaluation Metrics: [{'Ac': 0.94, 'Pr': 0.9416863672182821, 'Re': 0.94, 'F1': 0.9400641359404246}
```

```
'hidden_dim': [], 'epochs_threshold_dev': 14}

{'lr': 0.1, 'epochs': 30, 'dropout': 0.2, 'embedding_dim': 300, 'hidden_dim':

[], 'epochs_threshold_dev': 5}

{'lr': 0.01, 'epochs': 30, 'dropout': 0.2, 'embedding_dim': 300, 'hidden_dim':

[], 'epochs_threshold_dev': 13}

{'lr': 0.1, 'epochs': 30, 'dropout': 0.5, 'embedding_dim': 300, 'hidden_dim':

[], 'epochs_threshold_dev': 5}

{'lr': 0.1, 'epochs': 30, 'dropout': 0.7, 'embedding_dim': 300, 'hidden_dim':
```

Below is the table with top 5 best performed combinations of hypertuned parameters

[], 'epochs_threshold_dev': 5}]

	lr	dropout	accuracy	f1-score	embedding	epoch
1	0.1	0.7	0.94	0.9400	300	30
2	0.1	0.2	0.9333	0.9336	300	30
3	0.01	0.2	0.9333	0.9333	300	30
4	0.03	0.001	0.9333	0.9331	300	30
5	0.03	0.001	0.9266	0.9267	300	30

Accuracy of the validation is improved with hypertuning. The best performance for validation is achieved with higher learning rate, dropout than the default ones and the model is trained again with the tuned parameters.

```
[55]: W = network_weights(vocab_size=len(vocab_bow), embedding_dim=300, 

→hidden_dim=[], num_classes=3, init_val = 0.1)

#replace the embedding weights with w_glove
W[0] = w_glove
```

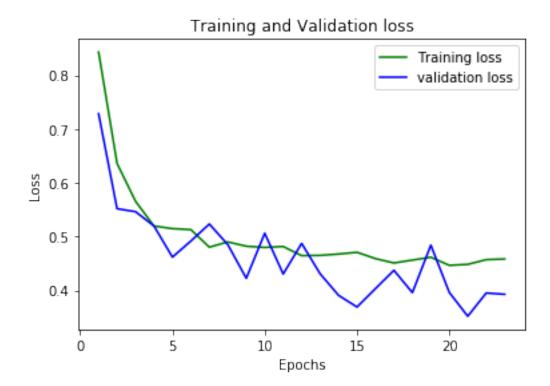
```
for i in range(len(W)):
    print('Shape W'+str(i), W[i].shape)
```

Shape W0 (2492, 300) Shape W1 (300, 3)

train_epoch: 1, loss: 0.8429 dev epoch: 1, loss: 0.7283 train_epoch: 2, loss: 0.6360 dev_epoch: 2, loss: 0.5519 train_epoch: 3, loss: 0.5657 dev_epoch: 3, loss: 0.5463 train_epoch: 4, loss: 0.5197 dev_epoch: 4, loss: 0.5198 train_epoch: 5, loss: 0.5148 dev_epoch: 5, loss: 0.4619 train_epoch: 6, loss: 0.5129 dev_epoch: 6, loss: 0.4919 train_epoch: 7, loss: 0.4804 dev_epoch: 7, loss: 0.5234 train_epoch: 8, loss: 0.4901 dev epoch: 8, loss: 0.4851 train_epoch: 9, loss: 0.4822 dev_epoch: 9, loss: 0.4226 train_epoch: 10, loss: 0.4799 dev_epoch: 10, loss: 0.5062 train_epoch: 11, loss: 0.4816 dev_epoch: 11, loss: 0.4306 train_epoch: 12, loss: 0.4647 dev_epoch: 12, loss: 0.4874 train_epoch: 13, loss: 0.4651 dev_epoch: 13, loss: 0.4310 train_epoch: 14, loss: 0.4676 dev_epoch: 14, loss: 0.3909 train_epoch: 15, loss: 0.4708 dev_epoch: 15, loss: 0.3692 train_epoch: 16, loss: 0.4591

dev_epoch: 16, loss: 0.4034
train_epoch: 17, loss: 0.4510
dev_epoch: 17, loss: 0.4374
train_epoch: 18, loss: 0.4564
dev_epoch: 18, loss: 0.3959
train_epoch: 19, loss: 0.4617
dev_epoch: 19, loss: 0.4841
train_epoch: 20, loss: 0.4466
dev_epoch: 20, loss: 0.3963
train_epoch: 21, loss: 0.4485
dev_epoch: 21, loss: 0.3521
train_epoch: 22, loss: 0.4572
dev_epoch: 22, loss: 0.3952
train_epoch: 23, loss: 0.3929

[57]: plot_loss(loss_tr, dev_loss)



The model might just be right with the validation loss picking up some oscillating noise and follow decreasing trend with the decrease in the training loss.

Accuracy: 0.8887652947719689

Precision: 0.8896361942175189 Recall: 0.8887365291713119 F1-Score: 0.8884159249258259

The hypertune method is executed for a combination of higher learning rates (lr) and higher dropout rates along with the default values selected. Higher learning rates are chosen so that the learning process will be faster and reduces the number of training steps the network need to converge. Higher values for dropout rate will put higher regularization affect on the network and gives more generalized results.

The accuracy is slightly improved with the hypertuned model. A higher learning rate and dropout rate is obtained from the tuning putting restriction on picking up any patterns or unwanted noise.

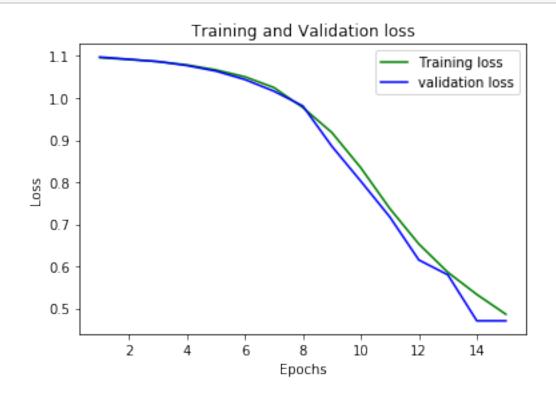
6 Extend to support deeper architectures

Extend the network to support back-propagation for more hidden layers. You need to modify the backward_pass function above to compute gradients and update the weights between intermediate hidden layers. Finally, train and evaluate a network with a deeper architecture. Do deeper architectures increase performance?

```
[59]: W =_{\sqcup}
       -network_weights(vocab_size=len(vocab_bow),embedding_dim=300,hidden_dim=[200,100],__
       \rightarrownum classes=3, init val = 0.1)
      W[0] = w_glove
      for i in range(len(W)):
          print('Shape W'+str(i), W[i].shape)
     Shape W0 (2492, 300)
     Shape W1 (300, 200)
     Shape W2 (200, 100)
     Shape W3 (100, 3)
[60]: W, loss tr, dev loss = SGD(train boi, train data lbl,
                                    W,
                                   X_dev=dev_boi,
                                    Y_dev=dev_data_lbl,
                                    lr=0.001,
                                    dropout=0.2,
                                    freeze_emb=True,
                                    tolerance=0.01,
                                    epochs=50)
     train_epoch: 1, loss: 1.0961
     dev_epoch: 1, loss: 1.0976
     train epoch: 2, loss: 1.0917
     dev_epoch: 2, loss: 1.0923
     train epoch: 3, loss: 1.0868
     dev_epoch: 3, loss: 1.0869
     train_epoch: 4, loss: 1.0789
```

dev_epoch: 4, loss: 1.0774 train_epoch: 5, loss: 1.0671 dev_epoch: 5, loss: 1.0643 train_epoch: 6, loss: 1.0507 dev epoch: 6, loss: 1.0442 train_epoch: 7, loss: 1.0252 dev_epoch: 7, loss: 1.0166 train_epoch: 8, loss: 0.9776 dev_epoch: 8, loss: 0.9813 train_epoch: 9, loss: 0.9183 dev_epoch: 9, loss: 0.8856 train_epoch: 10, loss: 0.8343 dev_epoch: 10, loss: 0.8025 train_epoch: 11, loss: 0.7374 dev_epoch: 11, loss: 0.7174 train_epoch: 12, loss: 0.6533 dev_epoch: 12, loss: 0.6153 train_epoch: 13, loss: 0.5859 dev_epoch: 13, loss: 0.5800 train_epoch: 14, loss: 0.5333 dev_epoch: 14, loss: 0.4706 train_epoch: 15, loss: 0.4863 dev_epoch: 15, loss: 0.4706

[61]: plot_loss(loss_tr, dev_loss)



```
[62]: #evaluation of metrics on the validation data
     get_evaluation_metrics(dev_boi, dev_data_lbl, W)
    Accuracy: 0.9
    Precision: 0.9034391534391535
    Recall: 0.9
    F1-Score: 0.8999762604529238
[63]: #evaluation of metrics on the test data
     get_evaluation_metrics(test_boi, test_data_lbl, W)
    Accuracy: 0.8731924360400445
    Precision: 0.8737795864559987
    Recall: 0.8731475287997027
    F1-Score: 0.8727695647962433
    6.0.1 Discuss how did you choose model hyperparameters?
[66]: lr=[0.001,0.01,0.1]
     epochs=[30]
     tolerance=[0.01]
     dropout = [0.2, 0.5, 0.7]
     embedding dim = [300]
     hidden_dim = [[100,50], [200,100], [300,200]] #restricting to 2 hidden layers
[67]: #hypertuning the model with pretrained embeddings and added hidden layers
     hypertune(train_boi, train_data_lbl, dev_boi, dev_data_lbl, 25,__
      →print_metrics=True, use_pretrained=True)
    0.9333333333333332, 'F1': 0.9333393458393459}
     'F1': 0.9265899645244232}
     {'Ac': 0.92, 'Pr': 0.924388747747161, 'Re': 0.91999999999999999, 'F1':
    0.9195372976129018}
     {'Ac': 0.92, 'Pr': 0.9246411483253588, 'Re': 0.9199999999999999, 'F1':
    0.9198118923710492}
     {'Ac': 0.92, 'Pr': 0.9270248596631916, 'Re': 0.9199999999999999, 'F1':
    0.9201694362984686}]
    Parameters: [{'lr': 0.01, 'epochs': 30, 'dropout': 0.5, 'embedding_dim': 300,
     'hidden_dim': [200, 100], 'epochs_threshold_dev': 10}
     {'lr': 0.01, 'epochs': 30, 'dropout': 0.2, 'embedding_dim': 300, 'hidden_dim':
     [200, 100], 'epochs_threshold_dev': 5}
     {'lr': 0.1, 'epochs': 30, 'dropout': 0.2, 'embedding_dim': 300, 'hidden_dim':
     [100, 50], 'epochs_threshold_dev': 15}
     {'lr': 0.01, 'epochs': 30, 'dropout': 0.5, 'embedding_dim': 300, 'hidden_dim':
```

```
[200, 100], 'epochs_threshold_dev': 15}
{'lr': 0.1, 'epochs': 30, 'dropout': 0.5, 'embedding_dim': 300, 'hidden_dim':
[100, 50], 'epochs_threshold_dev': 26}]
```

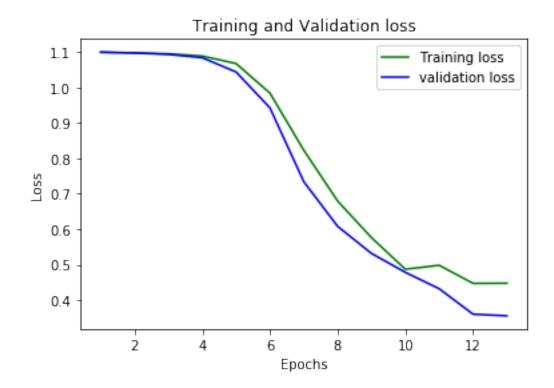
Below is the table with top 5 best performed combinations of hypertuned parameters

	lr	dropout	hidden_dim	accuracy	f1-score	embedding_dim	epoch
1	0.01	0.5	[200, 100]	0.9333	0.9333	300	30
2	0.01	0.2	[200, 100]	0.9266	0.9265	300	30
3	0.1	0.2	[100, 50]	0.92	0.9195	300	30
4	0.01	0.5	[200, 100]	0.92	0.9198	300	30
5	0.1	0.5	[100, 50]	0.92	0.9201	300	30

Accuracy of the validation is improved with hypertuning. The best performance for validation is achieved with higher learning rate, dropout than the default ones and for the default hidden_dim(layers and neuron_size) and the model is trained again with the tuned parameters.

train_epoch: 1, loss: 1.0983 dev_epoch: 1, loss: 1.0994 train_epoch: 2, loss: 1.0972 dev epoch: 2, loss: 1.0966 train_epoch: 3, loss: 1.0943 dev_epoch: 3, loss: 1.0928 train_epoch: 4, loss: 1.0882 dev_epoch: 4, loss: 1.0833 train_epoch: 5, loss: 1.0668 dev_epoch: 5, loss: 1.0431 train_epoch: 6, loss: 0.9835 dev_epoch: 6, loss: 0.9419 train_epoch: 7, loss: 0.8227 dev_epoch: 7, loss: 0.7340 train_epoch: 8, loss: 0.6794 dev_epoch: 8, loss: 0.6081 train_epoch: 9, loss: 0.5763 dev_epoch: 9, loss: 0.5318 train_epoch: 10, loss: 0.4873 dev_epoch: 10, loss: 0.4786 train_epoch: 11, loss: 0.4984 dev_epoch: 11, loss: 0.4324 train_epoch: 12, loss: 0.4475 dev_epoch: 12, loss: 0.3607 train_epoch: 13, loss: 0.4480 dev_epoch: 13, loss: 0.3560

[70]: plot_loss(loss_tr, dev_loss)



The model is about right as the validation loss follows a sillilar trend with training loss. Towards the though the training loss is increased the validation kept decreasing which indicates a possibility of further learning.

```
[71]: #evaluation of metrics on the test data with hypertuned model get_evaluation_metrics(test_boi, test_data_lbl, W)
```

Accuracy: 0.8909899888765295 Precision: 0.8909526323317394 Recall: 0.8908955778520995 F1-Score: 0.889925386417941

The hypertune method is executed for a combination of higher learning rates (lr), dropout rates

and a combination hidden_dim of neuron sizes(keeping it to 2 hidden layers) along with the default values selected. Higher learning rates are chosen so that the learning process will be faster and reduces the number of training steps the network need to converge. Higher values for dropout rate will put higher regularization affect on the network and gives more generalized results. A mixed hidden_dim is provided as per the commonly follwed rule that 'the optimal size of the hidden layer is usually between the size of the input and size of the output layers' to see if the neuron size have any impact on the performance.

The accuracy is slightly improved with the hypertuned model. A higher learning rate and dropout rate is obtained from the tuning so as to avoid overfitting.

6.1 Full Results

Add your final results here:

Model	Precision	Recall	F1-Score	Accuracy
Average	0.8551	0.8531	0.8523	0.8531
Embedding				
Average	0.8896	0.8887	0.8884	0.8887
Embedding				
(Pre-trained)				
Average	0.8909	0.8908	0.8899	0.8909
Embedding				
(Pre-trained) +				
X hidden layers				

Please discuss why your best performing model is better than the rest.

So overall, the average embedding with pre-trained weights and deep neural network architecture with two hidden layers achieved the best performance results. We can clearly see that the pretrained weights with default parameters has a better performance (Accuracy - 0.87) when compared to the default average embedding model (Accuracy - 0.66). By adding hidden layers the performance is further increased as the hidden layers add more abstraction, the models might tend to learn better and yield better results but this depends on the data and other aspects of the problem.

Please note that since the indices of the vocabulary keep changing everytime when the default get_vocab method is executed, the results might not reproduce as the embedding matrix changes. To achieve the reproducibility the get_vocab function can be modified to produce the same output for the vocab but in this case the default_method provided is used.

6.2 References

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