Dep(n,y) = p(y/a) p(n) = p(a/y) p(y)
by Bayes Theorem

And, in the statistical setting, we aim
to get an estimate for the absolute best model $\hat{y}(\hat{x}) \quad \text{for SSE cost fune}$

$$E(\vec{x}) = E((y-\hat{y})^2)$$

$$E(\vec{x}) = \iint (y(\vec{x}) - \hat{y}(\vec{x}))^2 p(n, y) d\vec{x} dy$$

for the best $\hat{y}(\vec{x})$, minnige $\vec{E}(\vec{x})$ wit \hat{y}

$$\frac{d}{d\hat{y}(\vec{x})} = (\vec{x}) = 0$$

 $\frac{d}{d\hat{y}(\vec{n})} \iint (y-\hat{y})^2 \rho(x,y) d\vec{n} dy = 0$

a Styplandy of fightery daidy p(n,y) - p (y|a) p(n) [] & p(y/2) p(x) (y-g) dx dy =0 $\iint \left(y p(y|x) dy\right) p(n) dx = \iint \hat{y} p(n,y) dn dy$ y p(n,y)dn dy $=\iint \mathbb{E}(y|n) p(n) dx =$ E(yla) is independent of 2 E - Sp(n)dn=1 6 Sp(n; y) dn dy = 1 => [y= E(ylàr)]

i.e., y(n)

i.e., y(n)

i) is the arbitrary model's label estimate

y'(n) is the absolute best model for the given

data

then :-

$$E(\vec{x}) = Cost function = E((g-\hat{g})^2)$$

$$= E((y-y^{*}+y^{*}-\hat{y})^{2})$$

Considu E ((y-y)(y*-9))

=
$$\iint (y-y^*)(y^*-\hat{y}) p(x,y) dx dy$$

$$= \int_{\alpha} \left[\int_{\gamma} (y-y^*) (y^*-\hat{y}) \rho(y|n) dy \right] \rho(n) dx$$

$$\int \rho(y|a) dy = 1 \quad \text{if } y \text{ in independent } y \text{ is } y = 1 \text{ in }$$

$$\mp \mathbb{E}_{\mathbf{b}}((g-\hat{g})^{2}) = \mathbb{E}((g-y^{*})^{2}) + \mathbb{E}((g-\mathbb{E}_{\mathbf{b}}(g))^{2}) \\
+ \mathbb{E}_{\mathbf{b}}((g)^{2} + y^{*})^{2}) \\
+ \mathbb{E}_{\mathbf{b}}((g)^{2} + y^{*})^{2}) \\
+ \mathbb{E}((g-y^{*})^{2}) = \text{noise}$$

$$\mathbb{E}((g-y^{*})^{2}) = \text{Noise}$$

© H = { o g g g is - estimate y - label for the statistical betting (> p(y/a) must be manimized ? We know the I samples follows plyln) & plaly) ply) and for optimal solution y* for which argain (Edf (4,9)) = Exy (4(y,g)) - Ex (Exx 4(y,g)) = Ex [St(n)) p (yla) dy] now since discrete, S-> E = Ex [SEG (9,9) p(yla)) det $\hat{y} = k'$ $k' \in Cu$ Ex [Lf(y, E') pr(y=1/2) + Lf(y, K') pr(y=2/2) = Ex [\lefta pr(y=k) - pr(y=k'|2)]

for optimal solutions

Ex [1-Pr(y=k'|x)] is minimized

of (y=k'/x) is manimized

 $y^*(\vec{x}) = \underset{y=C_k}{\text{arg max }} p(y=k|\vec{x})$

which is intuitive and what we try to do which is intuitive and what we try to do in lack and every classification problem -> in lack and every classification problem > or a label given of a label given of a label given of

K- Class Linear Discriminant Classifier buch class is separated by a hyperplane yk(x) = WX x + WKO Note: Till now we've been using is: 21 W $\chi \rightarrow \left[\begin{array}{cccc} \chi_0 & \lambda_1 & \dots & \lambda_d \end{array} \right]$ $X = \begin{bmatrix} \mathbf{x}_{0} & \mathbf{x}_{1} - \mathbf{x}_{d} \\ \mathbf{x}_{0}^{L} & \mathbf{x}_{1}^{L} - \mathbf{x}_{d}^{2} \end{bmatrix}$ X -> Column vector of components X - whole data in standard format To merge bias term, Consider) lost function = E((y-y)) Consider to as the edinate vector for an which will be of to a Column of K element, each dement being either (Consider the SSE Cost function $CF = E(\omega) = \sum_{i=1}^{\infty} \int_{i=1}^{i} y_{i} y_{ij}^{ij} 2$ for its sow of y and kth term (dimention) $CF = \left(y_{k}^{(i)} - \sum_{j=0}^{d} x_{j}^{(i)} w_{jk} \right)^{2}$ for optimal wo d CFik =0 > -2xi (yin d ci) Will d Wik =0 > -2xi (yin d ci) Will jeo ci) (yk jeo ci) Will j multidimensional In matrix format x (Y - XW) = 0 which yilds | W = (X x) X TY. In case of basis functions; W= (\$ T\$) T\$ TY d+1xK and their orders being (MHI) X K suspectively

O Fischer's Linear Discuminant Considu two class classification problem. Let mi = I san me: I & xin the main idea of Fischer's LDA is to privent overlap of classes during dimensionality reduction To get to a single dimension from multiple dimension vector, consider its component on a vector W of the same dimentionality m2-m, = WT (m2-m1) mk: wimk To restrict the wester itself, consider ||w||=1

To reduce intra-class borariance

and incuase inter-class variante, total

Fischer's witerion is used

$$J(\omega) = \frac{(m_2 - m_1)^2}{S_1^2 + S_1^2}$$

$$(m_2 - m_1)^2 = (\omega^{\dagger} \overrightarrow{m}_{k})^2$$

$$= \omega^{\dagger} \overrightarrow{m}_{k} \overrightarrow{m}_{k}^{\dagger} \omega$$

$$= \omega^{\dagger} \overrightarrow{m}_{k} \overrightarrow{m}_{k}^{\dagger} \omega$$

$$= class Covanianus matrix$$

$$= \sum_{n \in G} (y_1 - m_1)^2 + \sum_{n \in G} (y_1 - m_2)^2$$

$$= \sum_{n \in G} (w^{\dagger}x_n - m_1)^2 + \sum_{n \in G} (w^{\dagger}x_n - m_2)^2$$

$$= \sum_{n \in G} (w^{\dagger}x_n - m_1) (w^{\dagger}x_n - m_1)^{\dagger} + \sum_{n \in G} (w^{\dagger}x_n - m_2)^2$$

$$= W^{\dagger} S_W W$$

$$= \sum_{n \in G} (\vec{x}_n - \vec{m}_1)(\vec{x}_n - \vec{m}_1)^{\dagger} + \sum_{n \in G} (\vec{x}_n - \vec{m}_2)(\vec{x}_n - \vec{m}_1)^{\dagger}$$
Note that $S_B \vec{w} = (\vec{m}_2 - \vec{m}_1)(m_2 - m_1)^{\dagger} w$

$$= (\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)$$

$$\Rightarrow S_B \vec{w} = (\vec{m}_2 - \vec{m}_1)(m_2 - m_1)^{\dagger} w$$

$$= (\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)$$

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$$\Rightarrow S_B \vec{w} = (\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)$$

$$\Rightarrow S_B \vec{w} = (\vec{m}_2 - \vec{m}_1)(\vec{m}_2 - \vec{m}_1)(\vec{$$

$$\Rightarrow (\omega^{T} S_{w} w) (S_{gw}) = (\omega^{T} S_{gw}) (S_{ww})$$

Spw d m2-m, wTSww & wTSpw are scalars

$$\Rightarrow \left[\omega = S \omega \right] \left(\overrightarrow{m}_2 - \overrightarrow{m}_1 \right)$$

which is known as fischer's linear discre