

7/3/19

## EE6337: Deep Learning

Today: • Review

- Adam

- Batch Normalization

- Regularization: norm penalty, early stopping, dropout

- Adam: Adaptive Moments - a combination of RMS prop & momentum

- $\underline{s} \leftarrow \rho_1 \underline{s} + (1-\rho_1) g$

$\rho_1, \rho_2$ : hyperparameters

- $\underline{r} \leftarrow \rho_2 \cdot \underline{r} + (1-\rho_2) \cdot g \odot g$

- $\hat{\underline{s}} = \frac{\underline{s}}{1-\rho_1 t}$  (bias correction)  $t$ : iteration count

- $\hat{\underline{r}} = \frac{\underline{r}}{1-\rho_2 t}$  (bias correction).

- $\Delta \theta = -\frac{\epsilon}{\sqrt{\hat{s} + \hat{r}}} \odot \hat{\underline{s}}$

- $\theta \leftarrow \theta + \Delta \theta$

Batch normalization:  $\hat{y}_i = w_1 \dots w_L x$

$$\underline{w} = [w_1 \dots w_L]^T$$

$$\underline{w} \leftarrow \underline{w} - \epsilon g$$

$$g = [g_1 \dots g_L]^T$$

$$\hat{y}_{i+1} = (w_1 - \epsilon g_1) \dots (w_L - \epsilon g_L) \cdot x$$

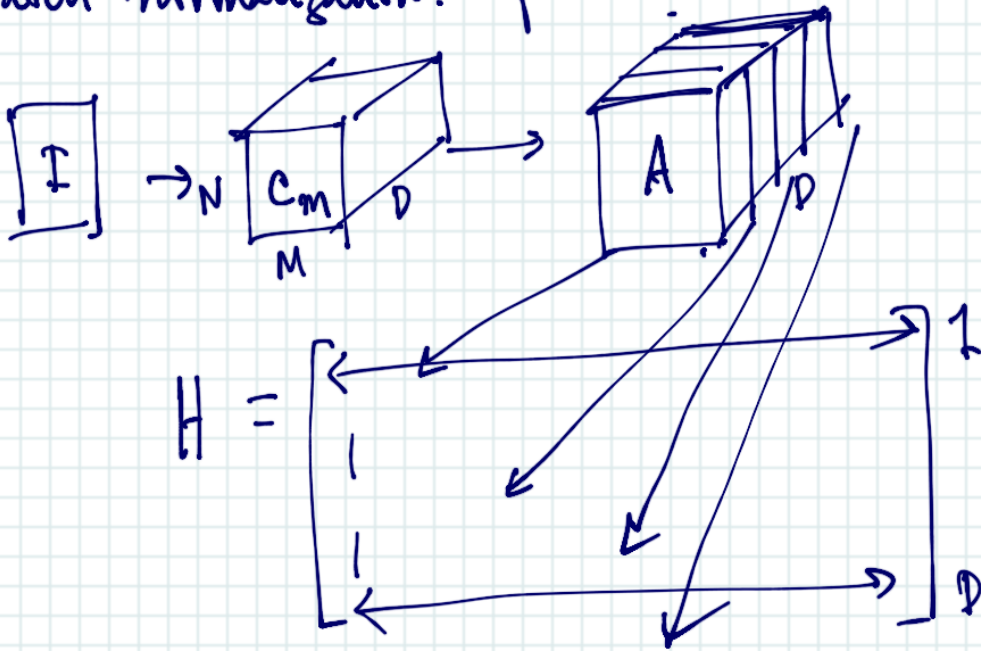
$$= \dots + \epsilon^2 g_1 g_2 \prod_{i=2}^L w_i + \epsilon^L g_1 \dots g_L$$

observation: The choice of  $\epsilon$  should be such that the contribution of the second order gradient relation is reduced, while also reducing the contribution of the other powers of  $\epsilon$ .

This is a hard problem. ( $h_i = \underline{h}_i \cdot w_i$ ,  $h_i$ : output at  $i^{\text{th}}$  layer,  $w_i$ : weight of  $i^{\text{th}}$  layer)

How can batch normalization help?

Batch normalization: of



$$H' = \frac{H - \mu}{\sigma}$$