

# Solving Linear Equations

---

MATHEMATICS FOR COMPUTING (IT1030)

# Linear System

---

In mathematics a system of linear equations (or linear system) is a collection of linear equations involving the same set of variables.

For example,

$$x_1 + 2x_2 + x_3 = 1$$

$$-2x_1 + 3x_2 - x_3 = -7$$

$$x_1 + 4x_2 - 2x_3 = -7$$

# Different Types of Solutions

---

A solution of a linear system is an assignment of values to the variables  $x_1, x_2, \dots, x_n$  such that each of the equations is satisfied. The set of all possible solutions is called the solution set.

A linear system may behave in any one of three possible ways:

1. The system has infinitely many solutions.
2. The system has a single unique solution.
3. The system has no solution.

# Solving Linear Equations – Method I

---

We can convert the linear system in to a matrix form that is  $AX = b$ .

i.e

$$AX = b.$$

$$A^{-1}AX = A^{-1}b$$

We know  $A^{-1}A = I$

$$I X = A^{-1}b$$

$$X = A^{-1}b$$

Where  $X$  means unknown variables,  $A^{-1}$  is inverse matrix and  $d$  is a constant matrix.

Consider now the case in which  $A$  is an arbitrary square matrix. If the inverse of  $A$  exists, then multiplication of on the left by  $A^{-1}$  leads to the solution vector

$$X = A^{-1}b = \frac{\text{adj}A}{\det A} b$$

# Example

---

Solve the linear system.

$$x_1 + 2x_2 - x_3 = 1$$

$$x_2 - x_3 = -7$$

$$x_1 - x_2 - 2x_3 = -7$$

So

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -1 \\ 1 & -1 & -2 \end{bmatrix} x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, b = \begin{bmatrix} 1 \\ -7 \\ -7 \end{bmatrix}$$

$$A^{-1} = -\frac{1}{4} \begin{bmatrix} -3 & 5 & -1 \\ -1 & -1 & 1 \\ -1 & 3 & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \frac{\text{adj}A}{\det A} b = A^{-1} \begin{bmatrix} 1 \\ -7 \\ -7 \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} -3 & 5 & -1 \\ -1 & -1 & 1 \\ -1 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -7 \\ -7 \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} -31 \\ -1 \\ -29 \end{bmatrix}$$

$$\text{Therefore } x_1 = \frac{31}{4}, x_2 = \frac{1}{4}, x_3 = \frac{29}{4}$$

# Solving Linear Equations – Method II (Cramer's Rule)

---

Suppose  $AX = b$  is a square linear system in the variables  $X = x_1, x_2, x_3 \dots x_n$

With the property that  $\det A \neq 0$ . Then the (unique) solution to the system is given by

$$x_i = \frac{\det(A_i)}{\det(A)} \quad i = 1, 2, 3, \dots, n$$

where  $A_i$  is the matrix formed by replacing the  $i^{\text{th}}$  column of  $A$  by the column vector  $b$ .

# Example

---

Solve the following system using Cramer's rule.

$$x_1 + x_2 - x_3 = 6$$

$$x_1 - x_2 + x_3 = 2$$

$$x_1 - 2x_3 = 0$$

$$A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 0 & -2 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 1 & 6 & -1 \\ 1 & 2 & 1 \\ 1 & 0 & -2 \end{bmatrix}$$

$$A_1 = \begin{bmatrix} 6 & 1 & -1 \\ 2 & -1 & 1 \\ 0 & 0 & -2 \end{bmatrix}$$

$$A_3 = \begin{bmatrix} 1 & 1 & 6 \\ 1 & -1 & 2 \\ 1 & 0 & 0 \end{bmatrix}$$

# Example

---

$$\begin{aligned}\det A &= a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13} \\ &= 1(-1)^{1+1}M_{11} + 1(-1)^{1+2}M_{12} + (-1)(-1)^{1+3}M_{13} \\ &= \begin{vmatrix} -1 & 1 \\ 0 & -2 \end{vmatrix} - \begin{vmatrix} 1 & 1 \\ 1 & -2 \end{vmatrix} - \begin{vmatrix} 1 & -1 \\ 1 & 0 \end{vmatrix} \\ &= (2 - 0) - (-2 - 1) - (0 + 1) \\ &= 4\end{aligned}$$

$$\det A_1 = 16$$

$$\det A_2 = 16$$

$$\det A_3 = 8$$

Thus by Cramer's Rule

$$x_1 = \frac{\det A_1}{\det A} = \frac{16}{4} = 4$$

$$x_2 = \frac{\det A_2}{\det A} = \frac{16}{4} = 4$$

$$x_3 = \frac{\det A_3}{\det A} = \frac{8}{4} = 2$$



# Solving Linear Equations – Method III (Gaussian Elimination Method)

---

$$x + 2y + z = 1$$

$$-2x + 3y - z = -7$$

$$x + 4y - 2z = -7$$

Obtain the Augmented Matrix

$$\left[ \begin{array}{cccc} 1 & 2 & 1 & 1 \\ -2 & 3 & -1 & -7 \\ 1 & 4 & -2 & -7 \end{array} \right],$$

which is known as the **augmented matrix** for the system of equations. The elementary operations referred to previously become **elementary row operations on the matrix**. We can reproduce the steps above by the following more compact procedure:

# Example

---

$$\begin{aligned}
 & \begin{bmatrix} 1 & 2 & 1 & 1 \\ -2 & 3 & -1 & -7 \\ 1 & 4 & -2 & -7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 7 & 1 & -5 \\ 0 & 2 & -3 & -8 \end{bmatrix} \begin{pmatrix} r'_2 = r_2 + 2r_1 \\ r'_3 = r_3 - r_1 \end{pmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 7 & 1 & -5 \\ 0 & 0 & \frac{-23}{7} & \frac{-46}{7} \end{bmatrix} \begin{pmatrix} r'_3 = r_3 - \frac{2}{7}r_2 \end{pmatrix} \\
 & \rightarrow \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{7} & \frac{-5}{7} \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{pmatrix} r'_3 = -\frac{7}{23}r_3 \\ r'_2 = \frac{1}{7}r_2 \end{pmatrix} \\
 & x_1 = 1, \quad x_2 = -1, \quad x_3 = 2.
 \end{aligned}$$

Where the arrow ‘ $\rightarrow$ ’ means ‘is transformed into’. The final matrix is said to be in **echelon** form, that is, it has zeros below the diagonal elements starting from the top left. We can now solve the equations by back substitution as before.

# Incompatible set of Equations (No Solution)

---

$$\begin{aligned}x + y - z &= 3 \\ 3x - y + 3z &= 5 \\ x - y + 2z &= 2\end{aligned}$$

$$\begin{bmatrix} 1 & 1 & -1 & 3 \\ 3 & -1 & 3 & 5 \\ 1 & -1 & 2 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & -4 & 6 & -4 \\ 0 & -2 & 3 & -1 \end{bmatrix} \quad \left( \begin{array}{l} r_2' = r_2 - 3r_1 \\ r_3' = r_3 - r_1 \end{array} \right)$$

$$\rightarrow \begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & -4 & 6 & -4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \left( r_3' = r_3 - \frac{1}{2}r_2 \right)$$

Which is the echelon form for this set of equations. However, row 3 is inconsistent since  $0 \neq 1$ . Hence these equations can have no solutions.

# Compatible set of equations (Infinite Number of Solutions)

---

$$x + y - z = 1,$$

$$3x - y + 3z = 5,$$

$$x - y + 2z = 2,$$

$$\begin{bmatrix} 1 & 1 & -1 & 1 \\ 3 & -1 & 3 & 5 \\ 1 & -1 & 2 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 & 1 \\ 0 & -4 & 6 & 2 \\ 0 & -2 & 3 & 1 \end{bmatrix} \quad \begin{pmatrix} r'_2 = r_2 - 3r_1 \\ r'_3 = r_3 - r_1 \end{pmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 1 & -1 & 1 \\ 0 & -4 & 6 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \left( r'_3 = r_3 - \frac{1}{2}r_2 \right)$$

# Compatible set of equations (Infinite Number of Solutions)

---

Row 3 is now consistent, and row 2 is  $-4y + 6z = 2$ . Hence

$$y = -\frac{1}{4}(2 - 6z)$$

Thus  $z$  can take any value, say  $\lambda$ , so the full solution set is

and, from row 1,

$$x = 1 - y + z = \frac{3}{2} - \frac{1}{2}z.$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{3}{2} - \frac{1}{2}\lambda \\ -\frac{1}{2} + \frac{3}{2}\lambda \\ \lambda \end{bmatrix}$$

for any value of  $\lambda$ . It can be seen in this case that there exists an infinite number of solutions, a different one for each different value of  $\lambda$ .

# The End

---