## Midterm exam LA (with a solution) (100)

(1) (10) (a) Explain the geometrical<sup>1</sup> meaning of determinant. (b) Explain the geometrical meaning of eigenvectors.

Solution. Determinant of a matrix A represents the factor by which the transformation  $T_A$  changes the volume of objects. That is,

volume(image of an object under T) = det(A) (volume of object)

An eigenvector  $\mathbf{v}$  of a linear transformation T is a vector that is mapped by T into the line spanned by  $\mathbf{v}$ . That is, the image of the eigenvector  $(\mathbf{T}(\mathbf{v}))$  is a scalar multiple of the eigenvector  $(\lambda \mathbf{v})$  and the scalar  $(\lambda)$  is called the eigenvalue.

(2) (40) Find an invertible matrix P and a diagonal matrix D that diagonalize the matrix

$$A = \left[ \begin{array}{rrr} 1 & 0 & -1 \\ -3 & 0 & 3 \\ -1 & 0 & 1 \end{array} \right].$$

Solution. Let  $\lambda$  denote an eigenvalue of A. We then calculate

$$\begin{vmatrix} 1 - \lambda & 0 & -1 \\ -3 & -\lambda & 3 \\ -1 & 0 & 1 - \lambda \end{vmatrix} = -\lambda^2(\lambda - 2) = 0.$$

Hence, the eigenvalues are  $\lambda_1 = \lambda_2 = 0$  and  $\lambda_3 = 2$ .

When  $\lambda = 0$ ,

$$\begin{bmatrix} 1 & 0 & -1 \\ -3 & 0 & 3 \\ -1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Therefore,  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$  is eigenvector if  $x_1 = x_3$ .

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

Hence, the eigenspace  $E_0 = \operatorname{span}\begin{pmatrix} 1\\0\\1 \end{pmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}$ ).

<sup>&</sup>lt;sup>1</sup>looking at matrices as linear transformations

We obtain the eigenvector  $\begin{bmatrix} -1\\3\\1 \end{bmatrix}$  for  $\lambda=-2$  in a similar manner. Since there is enough

linearly independent eigenvectors we can diagonalize A. We put  $P = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ 1 & 0 & 1 \end{bmatrix}$  and thus A is diagonalized as

$$P^{-1}AP = D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix}.$$

(3) (30) Let a, b and c be eigenvalues of a matrix A with corresponding eigenvectors

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix},$$

respectively. Compute the 555-th power of A.

Solution. Since A has three linearly independent eigenvectors we can conclude from theory that A is diagonalizable for any choice of a, b and c. Moreover, for  $P = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix}$  we have that

$$P^{-1}AP = D = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}.$$

Therefore,  $A = PDP^{-1}$  and

$$A^{555} = (PDP^{-1})^{555} = PD^{555}P^{-1}$$

$$= \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} a^{555} & 0 & 0 \\ 0 & b^{555} & 0 \\ 0 & 0 & c^{555} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & -1 \\ 0 & 2 & 0 \end{bmatrix}$$
$$= \frac{1}{2} \begin{bmatrix} a^{555} + b^{555} & 0 & a^{555} - b^{555} \\ 0 & 2c^{555} & 0 & a^{555} + b^{555} \\ a^{555} - b^{555} & 0 & a^{555} + b^{555} \end{bmatrix}.$$

(4) (10) Prove that if A is a diagonalizable matrix with only one eigenvalue  $\lambda$ , then A is of the form  $A = \lambda I$ . (Such a matrix is called a **scalar matrix**.)

Solution. If A is diagonalizable with only one eigenvalue  $\lambda$ , then there exists an invertible matrix P such that

$$P^{-1}AP = \lambda I$$

and thus we see that

$$A = P(\lambda I)P^{-1} = \lambda I.$$

(5) (10) Let A be similar to B. Show that rank(A) = rank(B).

(Hint: Show first the following statement: If U is invertible, then rank(UV) = rank(V). To do so, consider the relation of the null spaces of U and UV.)

Solution. Let U be an invertible matrix. We first compare the nullspaces as suggested.

If  $\mathbf{u} \in \text{null}(V)$ , then  $V\mathbf{u} = \mathbf{0}$  and hence  $(UV)\mathbf{u} = U(V\mathbf{u}) = U\mathbf{0} = \mathbf{0}$ . We have just showed that

$$\operatorname{null}(V) \subseteq \operatorname{null}(UV)$$
.

On the other hand, when  $\mathbf{u} \in \text{null}(UV)$ , then  $(UV)\mathbf{u} = \mathbf{0}$  and thanks to the invertibility of U we have that  $U^{-1}(UV)\mathbf{u} = U^{-1}\mathbf{0}$  and hence  $V\mathbf{u} = \mathbf{0}$ . This shows that

$$\operatorname{null}(V) \supseteq \operatorname{null}(UV)$$
.

We conclude that

$$\operatorname{null}(V) = \operatorname{null}(UV).$$

Using the Rank theorem this implies that

$$rank(UV) = rank(V),$$

whenever U is invertible. Furthermore, as  $(VU)^T = U^TV^T$  and  $\operatorname{rank}(U) = \operatorname{rank}(U^T)$  we deduce that

$$rank(VU) = rank(V),$$

whenever U is invertible.

We now apply this to  $A \sim B$ . Since there exists an invertible P such that

$$AP = PB$$
,

we can now easily conclude that

$$rank(A) = rank(B)$$
.