IT1160-DiscreteMathematics

LabSheet 08

Part A

Graphs

A small airline company maps its flight routes as a directed graph. Cities are vertices, and flights are directed edges. The company wants to analyze this graph for optimization.

Cities (Vertices): A, B, C, D, E Flights (Edges): $(A \rightarrow B)$, $(B \rightarrow C)$, $(C \rightarrow D)$, $(C \rightarrow E)$, $(E \rightarrow D)$, $(C \rightarrow B)$

- 01) Write a Python program to,
 - a) Represent this graph as both an adjacency list and an adjacency matrix
 - b) Display the graph using a visualization
- 02) The airline wants to analyze the degree of connectivity of each city. Write a Python program to,
 - a) Find the in-degree and out-degree of each city
 - b) Check if there are any self-loops
- 03) The airline wants to check if it's possible to fly from City A to City D, and also find all simple paths from A to D. Write a Python program to,
 - a) Check if D is reachable from A
 - b) Print all simple paths from A to D
 - c) Check for any cycles in the graph
- 04) A travel app wants to discover the shortest flight route (in terms of stops) from A to other cities. Implement Breadth-First Search (BFS) starting from A. Find,
 - a) The order of visited nodes
 - b) The BFS tree structure
- 05) The network admin wants to explore all possible paths deeply from City A. Implement Depth-First Search (DFS) from vertex A, and,
 - a) Record discovery and finishing times of each city
 - b) Display the DFS forest if disconnected

Trees

06) A school's student ranking list (based on GPA) got jumbled due to a system glitch. Use the HEAPIFY algorithm to correct the ranking starting from a specific position in the heap.

$$GPA_list = [4.0, 3.8, 2.5, 3.2, 3.9, 2.0]$$

07) You're given a binary tree represented as a list. Write a function to check if it is a full binary tree (i.e., every node has 0 or 2 children).

Binary Tree (as array) - [1, 2, 3, 4, 5, None, None]

08) A school's student ranking list (based on GPA) got jumbled due to a system glitch. Use the HEAPIFY algorithm to correct the ranking starting from a specific position in the heap.

$$GPA_list = [4.0, 3.8, 2.5, 3.2, 3.9, 2.0]$$

- 09) The government of Tech Island is planning to set up a communication network between four towns: A, B, C, and D. Since the island has limited resources, the goal is to connect all towns using underground fiber-optic cables in a way that:
 - All towns are connected
 - The total cost is minimized
 - There is no cyclic connection (no redundant paths)

The engineering team has conducted a survey and estimated the following costs (in millions) to lay cables between the towns:

From	То	Cost
A	В	2
Α	D	6
В	С	3
В	D	8
С	D	5

As the lead engineer for this project, you are assigned to design the most cost-efficient plan to connect the towns using a Minimum Spanning Tree (MST) approach.

- a) Model the problem as a weighted undirected graph
- b) Find the Minimum Spanning Tree using Prim's algorithm
- c) Display the selected cable connections and their costs
- d) Show the total installation cost

You are part of the Intergalactic Navigation Bureau, mapping routes between star systems in the Milky Way. Each star system is a node, and travel routes are directed edges. Your mission begins by mapping the network.

Star Systems: Sol, Alpha, Vega, Sirius, Betelgeuse Travel Routes: (Sol \rightarrow Alpha), (Alpha \rightarrow Vega), (Vega \rightarrow Sirius), (Vega \rightarrow Betelgeuse), (Betelgeuse \rightarrow Sirius), (Vega \rightarrow Alpha)

- 06) Write a Python program to:
 - a) Build the star map as a directed graph
 - b) Display the adjacency list and adjacency matrix
 - c) Visualize the network using a space-themed style
- 07) To avoid space traffic congestion, mission control wants to analyze how busy each starport is. Write a Python program to,
 - a) Compute the in-degree and out-degree of each star system
 - b) Identify any self-loops (loops in wormholes)
- 08) You are plotting a mission from Earth's system (Sol) to reach Sirius. Mission control needs all possible safe routes. Write a Python program to,
 - a) Check if Sirius is reachable from Sol
 - b) List all simple paths from Sol to Sirius
 - c) Identify if there are any cycles in the network
- 09) Your exploration drone performs a breadth-first scan from Sol to map the galaxy with the least number of fuel jumps. Implement Breadth-First Search (BFS) from Sol. Find,
 - The visit order
 - The BFS tree
- 10) To analyze deep space mysteries, the crew uses Depth-First Search to explore all reachable star systems and record discovery timestamps. Write a recursive DFS function that,
 - a) Records discovery and finishing times of each star system
 - b) Prints the DFS tree (or forest)
- 11) Given a nearly max-heap GPA list [4.0, 3.8, 2.5, 3.2, 3.9, 2.0], apply HEAPIFY from index 1 to fix the heap.

12) Given a list of product ratings [4.9, 4.7, 4.5, 3.8, 4.8], apply HEAPIFY after updating the rating at index 3 to maintain heap structure.

SmartLogi Inc., a logistics and supply chain company, is setting up a centralized delivery network to connect its four key distribution centers located in cities P, Q, R, and S. The objective is to ensure:

- All centers are interconnected
- The overall road construction cost is minimized
- There are no redundant road paths (i.e., no loops)

After a ground survey, the estimated construction costs (in millions) for possible direct roads between centers are:

From	То	Cost
P	Q	4
P	S	7
Q	R	2
Q	S	6
R	S	3

As the system analyst responsible for route optimization, perform the following:

- 13. Model the above scenario as a weighted undirected graph using an appropriate Python library
- 14. Use Prim's Algorithm to compute the Minimum Spanning Tree (MST)
- 15. Display the selected route connections and costs, and print the total cost

Python Collections Module

from collections import namedtuple, deque, Counter, OrderedDict, defaultdict, ChainMap

namedtuple - Factory function for creating tuple subclasses with named fields

```
Point = namedtuple('Point', 'x y')
p = Point(1, 2)
print(p.x, p.y) # Output: 1 2
```

deque - List-like container with fast appends and pops on either end

```
d = deque([1, 2, 3])
d.append(4)
d.appendleft(0)
print(d) # Output: deque([0, 1, 2, 3, 4])
```

Counter - Dict subclass for counting hashable objects

```
cnt = Counter(['apple', 'banana', 'apple', 'orange', 'banana', 'apple'])
print(cnt) # Output: Counter({'apple': 3, 'banana': 2, 'orange': 1})
```

OrderedDict - Dict subclass that remembers the order entries were added

```
od = OrderedDict()
od['a'] = 1
od['b'] = 2
od['c'] = 3
print(od) # Output: OrderedDict([('a', 1), ('b', 2), ('c', 3)])
```

defaultdict - Dict subclass that calls a factory function for missing keys

```
dd = defaultdict(int)
```

```
dd['a'] += 1
print(dd['a']) # Output: 1
print(dd['b']) # Output: 0 (default value since 'b' doesn't exist)
```

ChainMap - Groups multiple dictionaries into a single view

```
dict1 = {'a': 1, 'b': 2}
dict2 = {'b': 3, 'c': 4}
cm = ChainMap(dict1, dict2)
print(cm['b']) # Output: 2 (from dict1, as it comes first)
print(cm['c']) # Output: 4 (from dict2)
```

Python networkx Library

import networkx as nx import matplotlib.pyplot as plt

Create an empty Graph (undirected)

```
G = nx.Graph()
G.add_node(1)
G.add_nodes_from([2, 3])
G.add_edge(1, 2)
G.add_edges_from([(2, 3), (3, 1)])

print("Nodes:", G.nodes()) # Output: Nodes: [1, 2, 3]

print("Edges:", G.edges()) # Output: Edges: [(1, 2), (1, 3), (2, 3)]
```

Create a Directed Graph

```
DG = nx.DiGraph()

DG.add_edges_from([(1, 2), (2, 3)])

print("Directed Edges:", DG.edges()) # Output: [(1, 2), (2, 3)]
```

Add node and edge attributes

```
G.nodes[1]['label'] = 'Start'

G.edges[1, 2]['weight'] = 4.2

print(G.nodes(data=True)) # Output includes attributes

print(G.edges(data=True)) # Output includes edge weights
```

Visualize the Graph

```
nx.draw(G, with_labels=True)
plt.show()
```

Shortest Path

```
shortest = nx.shortest_path(G, source=1, target=3)
print("Shortest path from 1 to 3:", shortest) # Output: [1, 3]
```

Degree and Centrality Measures

```
degree_dict = dict(G.degree())
print("Degrees:", degree_dict)
centrality = nx.degree_centrality(G)
print("Degree Centrality:", centrality)
```

Cycle Detection

```
has_cycle = nx.cycle_basis(G)
print("Cycles in the graph:", has_cycle) # Output: [[1, 2, 3]]
```

Connected Components

```
components = list(nx.connected_components(G))
print("Connected Components:", components) # Output: [{1, 2, 3}]
```

Graph from Edgelist or Adjacency List

```
edge_list = [(1, 2), (2, 3), (3, 4)]

G_from_edges = nx.from_edgelist(edge_list)
print("Graph from edge list:", G_from_edges.edges())
```

Convert Graph to Adjacency Matrix

```
adj_matrix = nx.adjacency_matrix(G).todense()
print("Adjacency Matrix:\n", adj_matrix)
```

PageRank (for Directed Graphs)

```
pagerank = nx.pagerank(DG)
print("PageRank:", pagerank)
```

Clustering Coefficient

```
clustering = nx.clustering(G)
print("Clustering Coefficient:", clustering)
```

Minimum Spanning Tree (for weighted graphs)

```
MST = nx.minimum_spanning_tree(G)
print("Minimum Spanning Tree Edges:", MST.edges())
```

Community Detection (Greedy Modularity)

from networkx.algorithms.community import greedy_modularity_communities communities = greedy_modularity_communities(G) print("Communities:", [list(c) for c in communities])

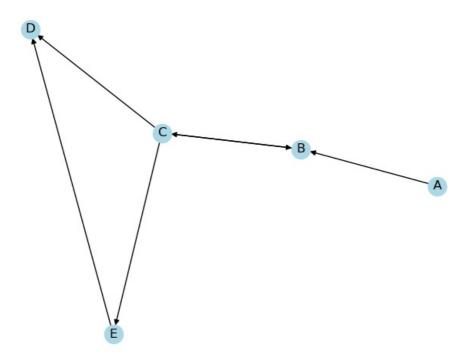
Export Graph to GraphML

nx.write_graphml(G, "example.graphml")

Question 01

```
In [2]: import networkx as nx
        import matplotlib.pyplot as plt
        G = nx.DiGraph()
        edges = [('A', 'B'), ('B', 'C'), ('C', 'D'), ('C', 'E'), ('E', 'D'), ('C', 'B')]
        G.add edges from(edges)
        print("Adjacency List:")
        for node in G.nodes():
         print(f"{node}: {list(G.adj[node])}")
        print("\nAdjacency Matrix:")
        print(nx.adjacency_matrix(G).todense())
        nx.draw(G, with_labels=True, node_color='lightblue', arrows=True)
        plt.title("Airline Route Map")
        plt.show()
       Adjacency List:
       A: ['B']
       B: ['C']
       C: ['D', 'E', 'B']
       D: []
       E: ['D']
       Adjacency Matrix:
       [[0 1 0 0 0]
        [0 0 1 0 0]
        [0 1 0 1 1]
        [0 0 0 0 0]
        [0 0 0 1 0]]
```

Airline Route Map



Question 02

```
In [3]:
    print("In-Degree and Out-Degree:")
    for node in G.nodes():
        print(f"{node} - In-degree: {G.in_degree(node)}, Out-degree: {G.out_degree(node)}")

    print("\nSelf-loops:")
    self_loops = list(nx.selfloop_edges(G))
    print("None" if not self_loops else self_loops)
```

```
In-Degree and Out-Degree:
A - In-degree: 0, Out-degree: 1
B - In-degree: 2, Out-degree: 1
C - In-degree: 1, Out-degree: 3
D - In-degree: 2, Out-degree: 0
E - In-degree: 1, Out-degree: 1
Self-loops:
None
```

Question 03

```
In [5]: print("Is D reachable from A?", nx.has_path(G, 'A', 'D'))
print("\nAll Simple Paths from A to D:")

for path in nx.all_simple_paths(G, source='A', target='D'):
    print(path)
    print("\nCycles in the Graph:")
    cycles = list(nx.simple_cycles(G))
    print("No cycles" if not cycles else cycles)

Is D reachable from A? True

All Simple Paths from A to D:
    ['A', 'B', 'C', 'D']
    ['A', 'B', 'C', 'E', 'D']

Cycles in the Graph:
    [['C', 'B']]
```

Question 04

```
In [6]: from collections import deque
         def bfs(graph, start):
             visited = set()
             queue = deque([start])
             bfs_tree = {start: []}
             parent = {start: None}
             while queue:
                 node = queue.popleft()
                 visited.add(node)
                 for neighbor in graph[node]:
                      if neighbor not in visited and neighbor not in queue:
                          queue.append(neighbor)
                          parent[neighbor] = node
                          if parent[neighbor] not in bfs tree:
                              bfs_tree[parent[neighbor]] = []
                          bfs_tree[parent[neighbor]].append(neighbor)
             return visited, bfs_tree
         visited, bfs_tree = bfs(G.adj, 'A')
         print("BFS Visit Order:", visited)
         print("BFS Tree:", bfs_tree)
       BFS Visit Order: {'D', 'B', 'A', 'C', 'E'}
BFS Tree: {'A': ['B'], 'B': ['C'], 'C': ['D', 'E']}
```

Question 05

```
import networkx as nx

time = 0
    discovery = {}
    finishing = {}
    visited = set()

def dfs(graph, node):
        global time
        visited.add(node)
        time += 1
        discovery[node] = time

    for neighbor in graph[node]:
        if neighbor not in visited:
            dfs(graph, neighbor)

    time += 1
    finishing[node] = time
```

```
for node in G.nodes():
    if node not in visited:
        dfs(G.adj, node)

print("Discovery Times:", discovery)
print("Finishing Times:", finishing)

Discovery Times: {'A': 1, 'B': 2, 'C': 3, 'D': 4, 'E': 6}
Finishing Times: {'D': 5, 'E': 7, 'C': 8, 'B': 9, 'A': 10}
```

Question 07

```
In [8]:

def is_full_binary_tree(tree):
    n = len(tree)
    for i in range(n):
        left = 2 * i + 1
        right = 2 * i + 2
        if left < n and tree[left] is not None or right < n and tree[right] is not None:
            if not (left < n and tree[left] is not None and right < n and tree[right] is not None):
            return False
    return True

tree = [1, 2, 3, 4, 5, None, None]
    print("Is full binary tree?", is_full_binary_tree(tree))</pre>
```

Is full binary tree? True

Question 06

```
In [9]: #Method 01
def heapify(arr, n, i):
    largest = i
    l = 2 * i + 1
    r = 2 * i + 2

    if l < n and arr[l] > arr[largest]:
        largest = l
    if r < n and arr[r] > arr[largest]:
        largest = r

    if largest != i:
        arr[i], arr[largest] = arr[largest], arr[i]
        heapify(arr, n, largest)

GPA_list = [4.0, 3.8, 2.5, 3.2, 3.9, 2.0]
heapify(GPA_list, len(GPA_list), 1)
print("Heap after HEAPIFY from index 1:", GPA_list)
```

Heap after HEAPIFY from index 1: [4.0, 3.9, 2.5, 3.2, 3.8, 2.0]

```
In [10]: #Method 02
import heapq

GPA_list = [-4.0, -3.8, -2.5, -3.2, -3.9, -2.0]
heapq.heapify(GPA_list)

GPA_list = [-x for x in GPA_list]
print("Max-heapified GPA list:", GPA_list)
```

Max-heapified GPA list: [4.0, 3.9, 2.5, 3.2, 3.8, 2.0]

Question 08

```
In [1]: import networkx as nx

G = nx.Graph()

G.add_edge('A', 'B', weight=2)
G.add_edge('A', 'D', weight=6)
G.add_edge('B', 'C', weight=3)
G.add_edge('B', 'D', weight=8)
G.add_edge('C', 'D', weight=5)

mst = nx.minimum_spanning_tree(G, algorithm='prim')

print("Minimum Spanning Tree edges:")
for u, v, data in mst.edges(data=True):
    print(f"{u} - {v} \t weight: {data['weight']}")

total_weight = sum(data['weight'] for u, v, data in mst.edges(data=True))
print("Total weight of MST:", total_weight)
```

```
Minimum Spanning Tree edges:
A - B weight: 2
B - C weight: 3
D - C weight: 5
Total weight of MST: 10
```

In []:

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