



International Institute of Forecasters

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Social Good •  
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# *Probabilistic Forecasting in Python*

Aug 2024

Presented by

**Sankalp Gilda, Ph.D.**

# Probabilistic Forecasting in Python

# Content

Why Forecasting

Why PF

Types of PFs

Methods for PF

Evaluating Forecasts

Python Ecosystem

August 2024

## Why Time Series?

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*"The amount of time series data being stored across organizations has increased 15x over the past 3 years."*

--Timescale, "The State of Time Series Data 2023" report

*"By 2027, 28.8% of the Global DataSphere will be real-time data."*

-- IDC, "Global DataSphere Forecast, 2023-2027"  
(Published in May 2023)

*"78% of respondents report that the amount of time series data they are managing has increased over the past 12 months."*

-- InfluxData's "State of Time Series Data Management Report" for 2022



## What is Forecasting?

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Forecasting is the process of making predictions about future events based on past and present time series data.

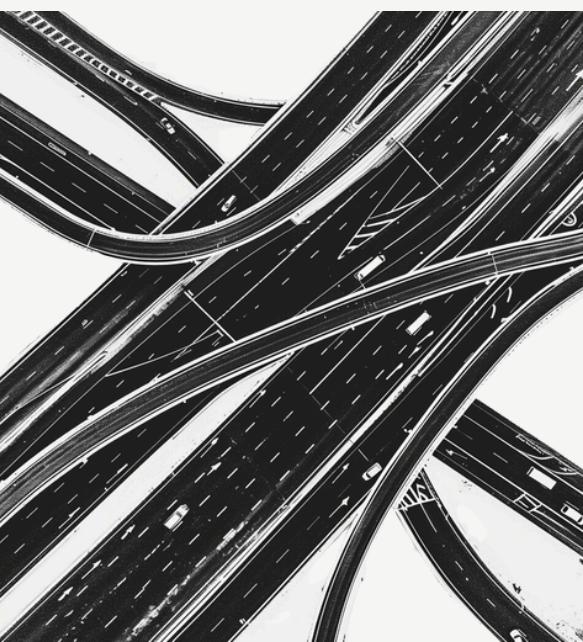
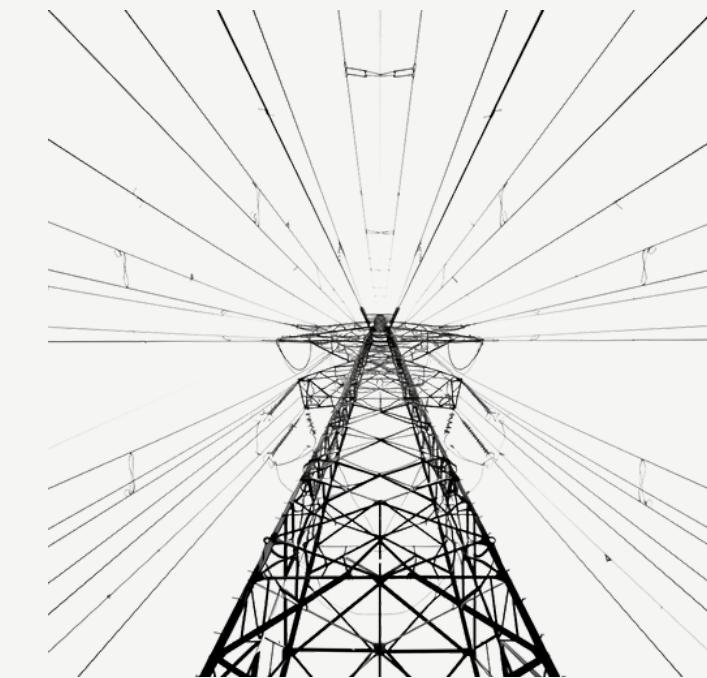
- Uses historical data and current trends
- Applies to various fields (e.g., weather, economics, business)
- Combines science, data analysis, and intuition
- Essential for planning and decision-making



*Remember: All forecasts come with inherent uncertainty*

# Why Forecasting?

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# Why Forecasting?

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**Weather and Climate**

# Why Forecasting?

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Weather and Climate



Finance and Economics

# Why Forecasting?

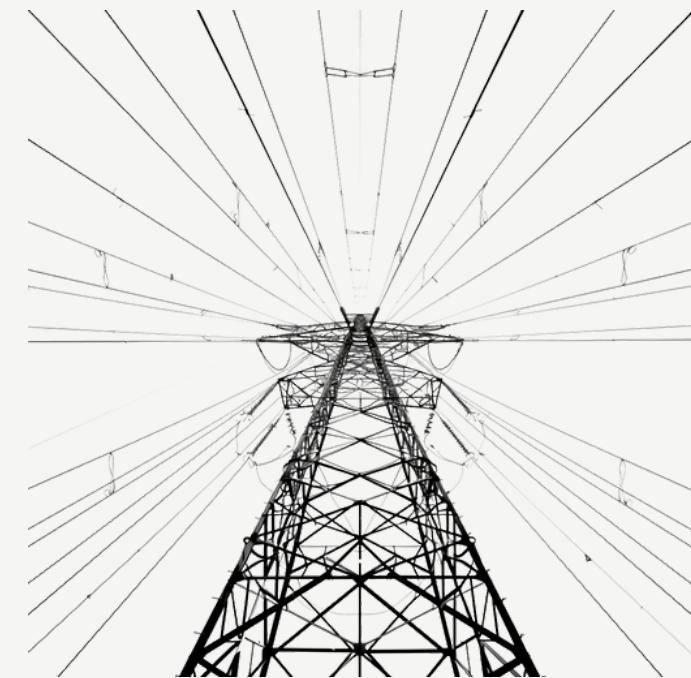
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Weather and Climate



Finance and Economics



Energy

# Why Forecasting?

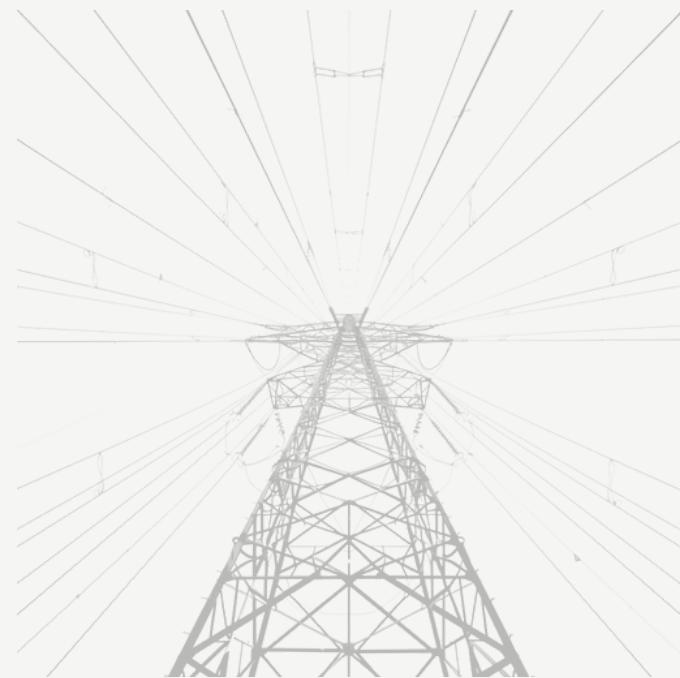
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Weather and Climate



Finance and Economics



Energy



Healthcare

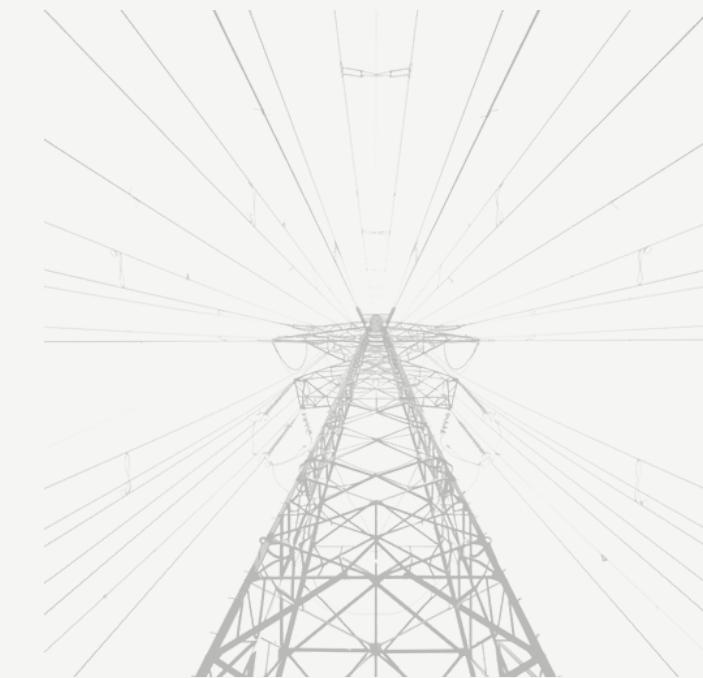
# Why Forecasting?



Weather and Climate



Finance and Economics



Energy



Healthcare



Retail and E-Commerce

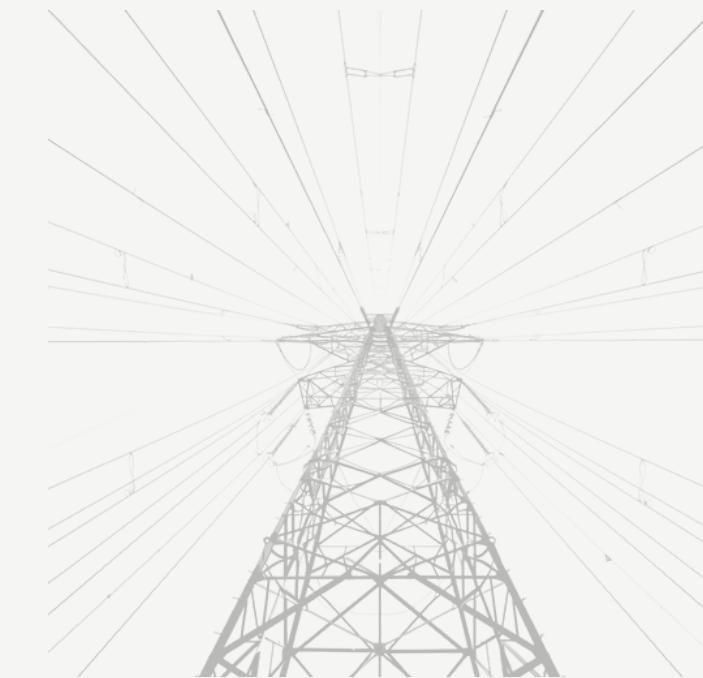
# Why Forecasting?



Weather and Climate



Finance and Economics



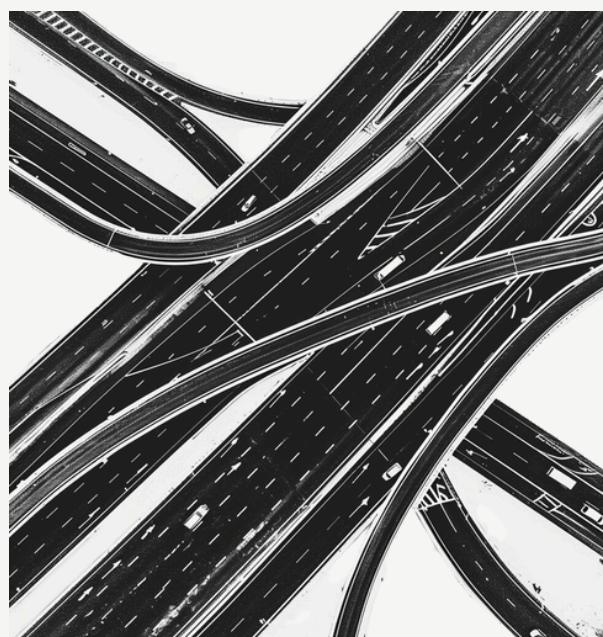
Energy



Healthcare



Retail and E-Commerce



Transportation and Logistics

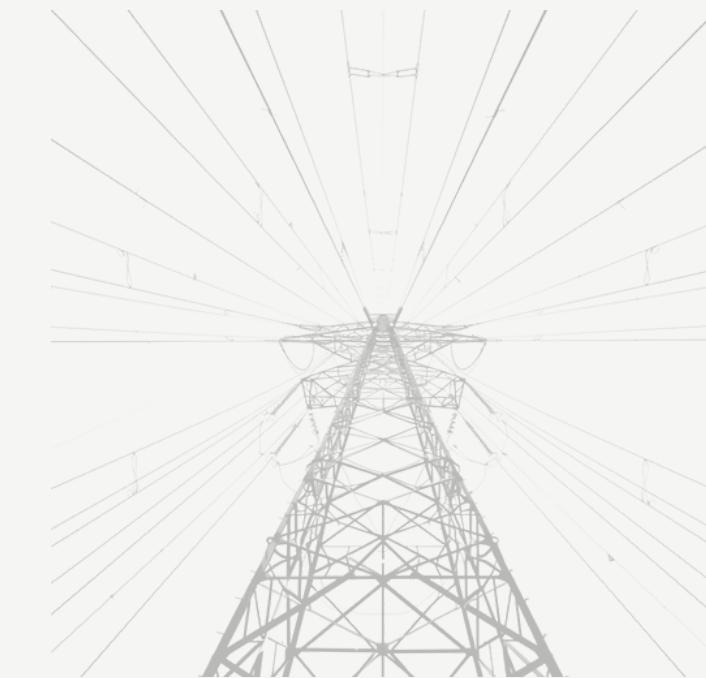
# Why Forecasting?



Weather and Climate



Finance and Economics



Energy



Healthcare



Retail and E-Commerce



Transportation and Logistics



Disaster Management

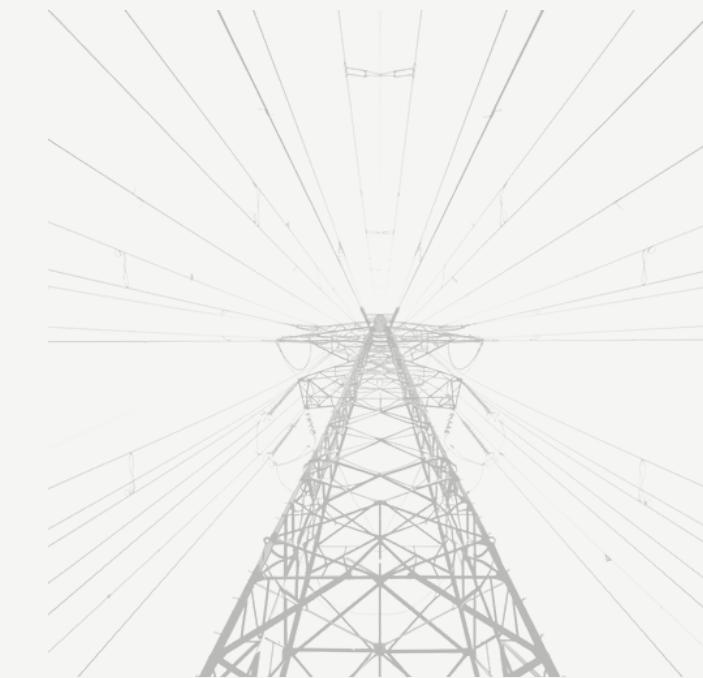
# Why Forecasting?



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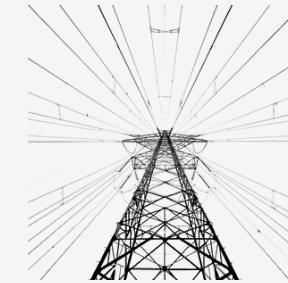


Disaster Management



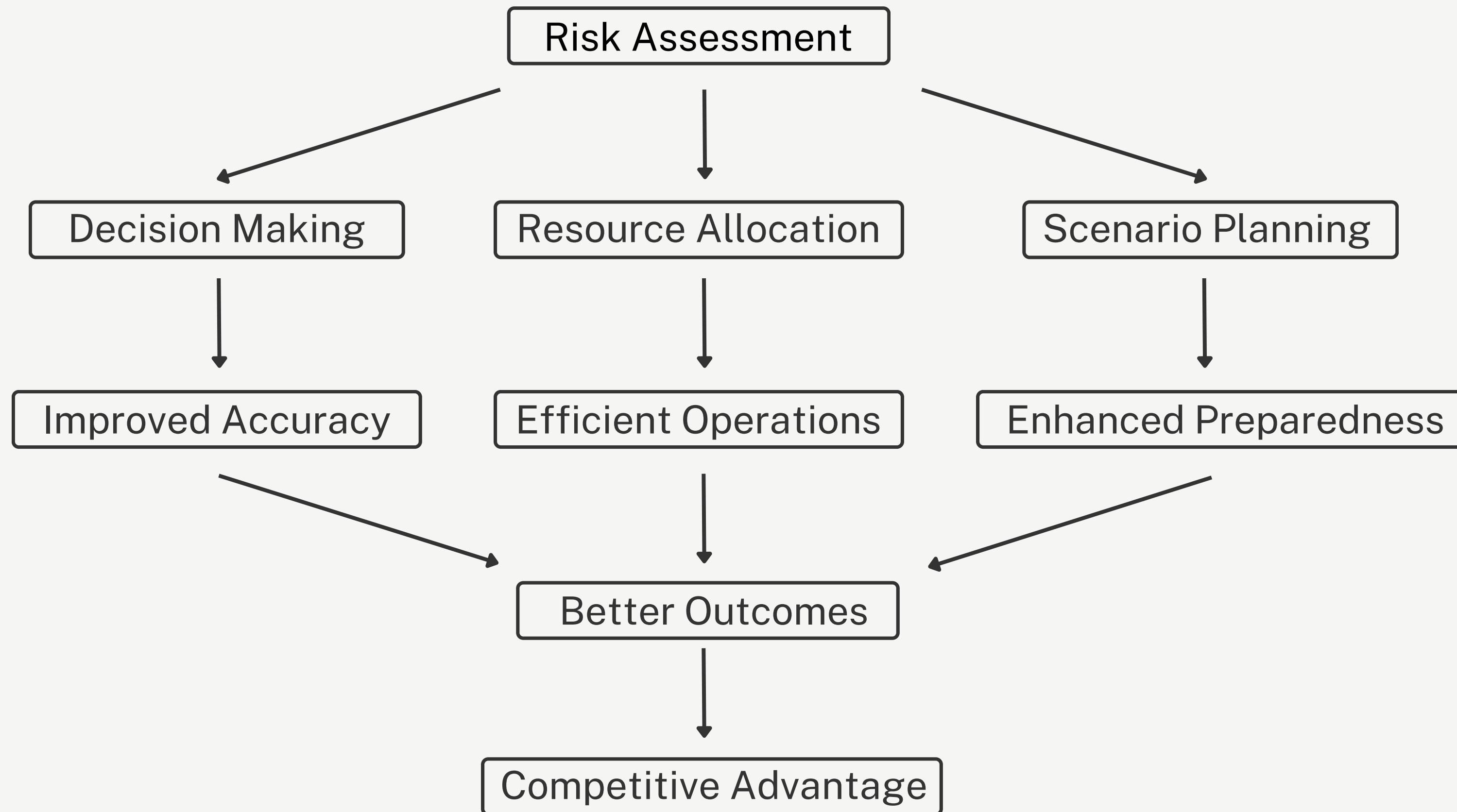
Agriculture

# Why Probabilistic Forecasting?



<b>Scenario A</b>	Sunny weekend forecast	GDP growth projection	Summer peak demand
<b>What ifs A</b>	<ul style="list-style-type: none"> <li>1. 30% chance of rain?</li> <li>2. Hourly precipitation probability?</li> </ul>	<ul style="list-style-type: none"> <li>1. Range of GDP growth scenarios?</li> <li>2. Likelihood of recession?</li> </ul>	<ul style="list-style-type: none"> <li>1. Probability distributions for peak demand?</li> <li>2. Likelihood of extreme heat waves?</li> </ul>
<b>Scenario B</b>	Seasonal winter prediction	Company sales forecast	Wind farm energy production
<b>What ifs B</b>	<ul style="list-style-type: none"> <li>1. Probability distributions for winter severity?</li> <li>2. Likelihood of extreme cold snaps?</li> </ul>	<ul style="list-style-type: none"> <li>1. Probability distributions for sales outcomes?</li> <li>2. Likelihood of market disruptions?</li> </ul>	<ul style="list-style-type: none"> <li>1. Probability ranges for wind speeds?</li> <li>2. Likelihood of prolonged low-wind periods?</li> </ul>

# Why Probabilistic Forecasting?



## Point Forecasts

A point forecast is a single-value prediction representing the most likely future outcome, based on current data and models.

$$\hat{y}_{t+k|t} = \mathbb{E}[Y_{t+k} | \mathcal{M}, \Omega_t, \theta_t]$$

where:

$\hat{y}_{t+k|t}$  : forecast for time  $t + k$  made at time  $t$

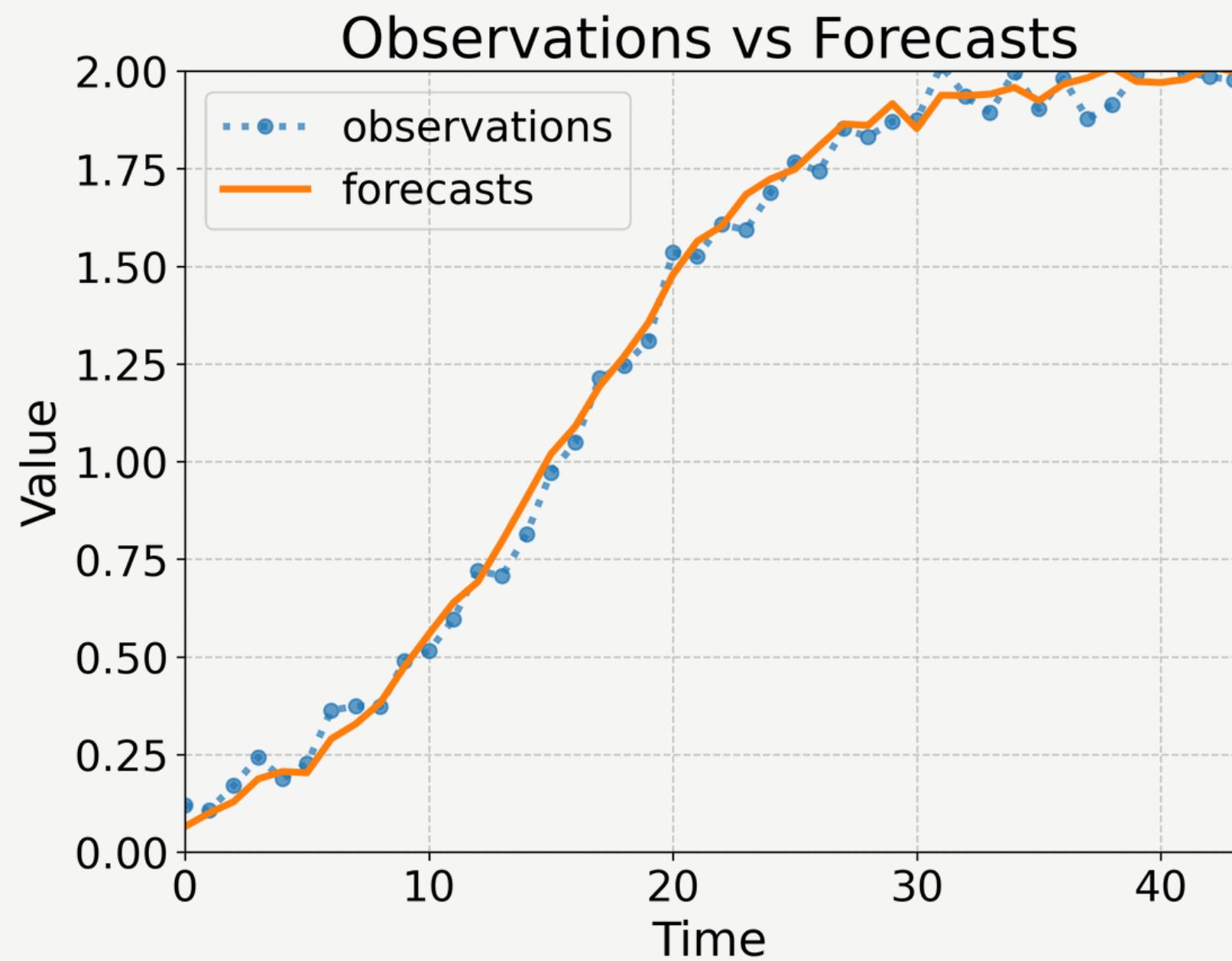
$\mathbb{E}[\cdot]$  : expected value

$Y_{t+k}$  : actual value at time  $t + k$

$\mathcal{M}$  : forecasting model

$\Omega_t$  : information set available at time  $t$

$\theta_t$  : model parameters estimated at time  $t$

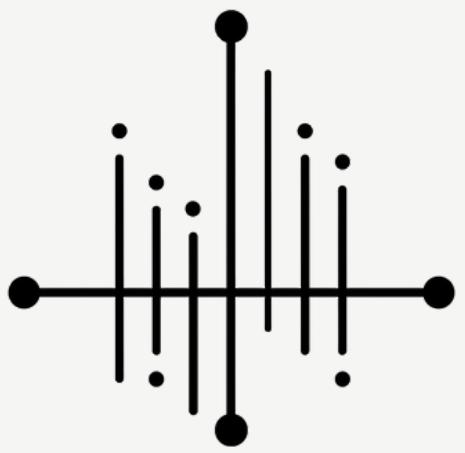
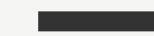


## Probabilistic Forecasting in Python

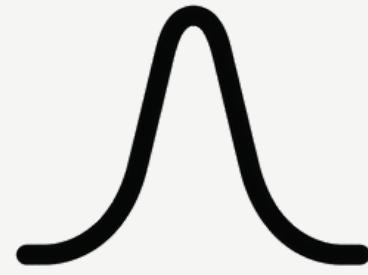
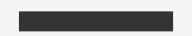
# *Types of Probabilistic Forecasts*



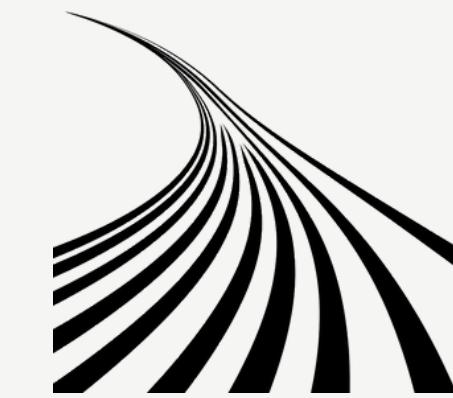
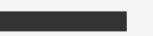
Interval



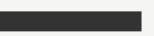
Quantile



Distribution



Scenario



## Interval Forecasts

A prediction interval is an interval within which power generation may lie, with a certain probability.

$$\hat{I}_{t+k|t}^{(\alpha)} = [\hat{s}_{t+k|t}^{(q=\alpha/2)}, \hat{s}_{t+k|t}^{(q=1-\alpha/2)}]$$

where:

$\hat{I}_{t+k|t}^{(\alpha)}$  : prediction interval

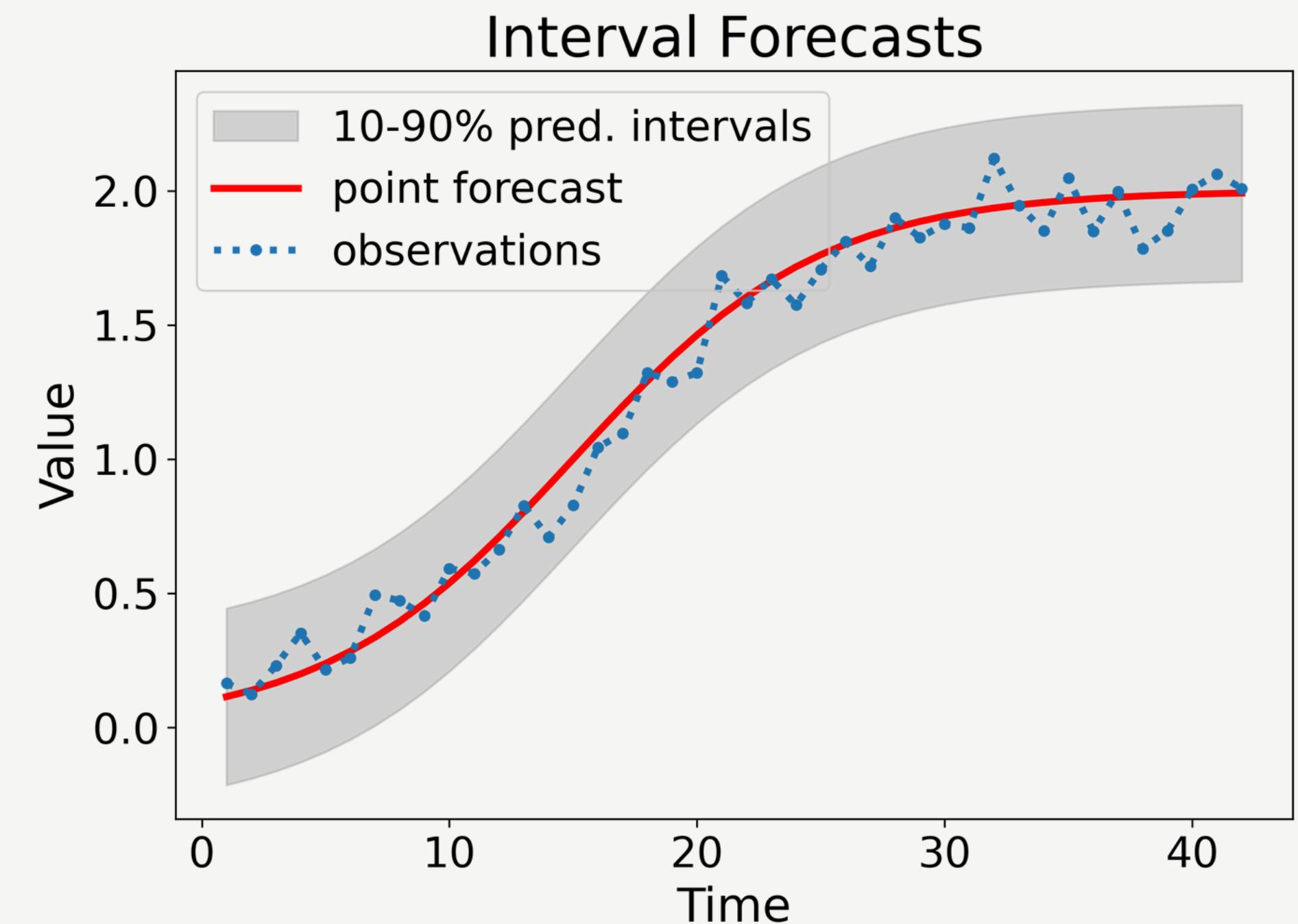
$\hat{s}_{t+k|t}^{(q)}$  : quantiles of the predictive distribution

$\alpha$  : nominal coverage

(e.g., 0.9 for 90% interval)

$t + k$  : forecast horizon

$t$  : current time



## Quantile Forecasts

A quantile forecast provides a value that the future observation is expected to be below with a specified probability.

$$\begin{aligned} P[Y_{t+k|t} \leq \hat{s}_{t+k|t}^{(q)} | g, \Omega_t, \hat{\Theta}_t] \\ = q\hat{s}_{t+k|t}^{(q)} = \hat{F}_{t+k|t}^{-1}(q) \end{aligned}$$

where:

$Y_{t+k|t}$  : random variable representing the future observation

$\hat{s}_{t+k|t}^{(q)}$  : quantile forecast

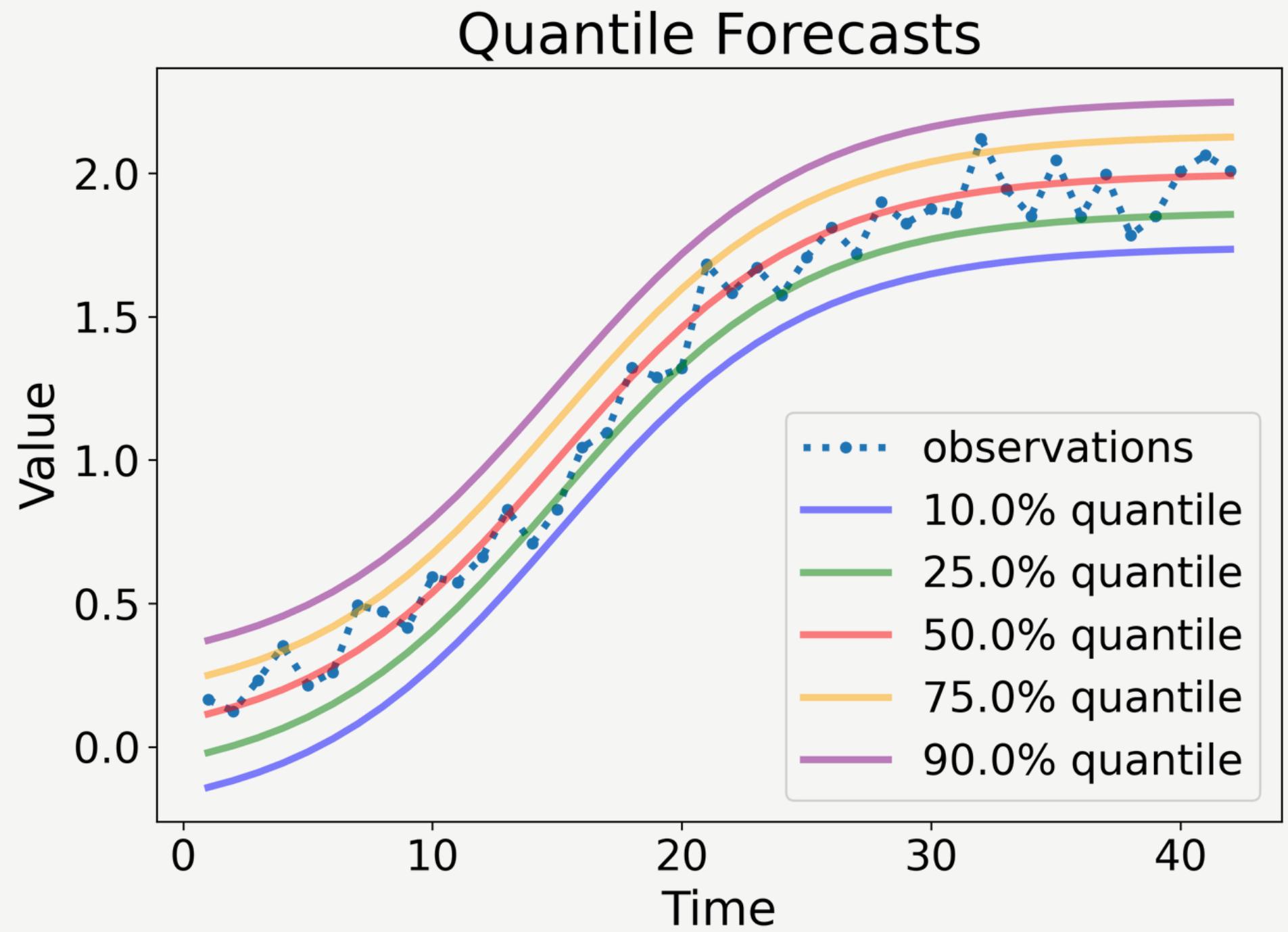
$q$  : nominal level (quantile)

$g$  : forecasting model

$\Omega_t$  : information set available at time  $t$

$\hat{\Theta}_t$  : estimated model parameters at time  $t$

$\hat{F}_{t+k|t}$  : estimated cumulative distribution function (CDF)



## Distribution Forecasts

A comprehensive probabilistic forecast capturing the full range of potential outcomes across all time horizons.

$$\Omega_{t+k} \sim \hat{\Phi}_{t+k|t}$$

where:

$\Omega_{t+k}$  : Future value at time  $t + k$

$\hat{f}_{t+k|t}$  : Estimated predictive density function  
for time  $t + k$  given information up to time  $t$

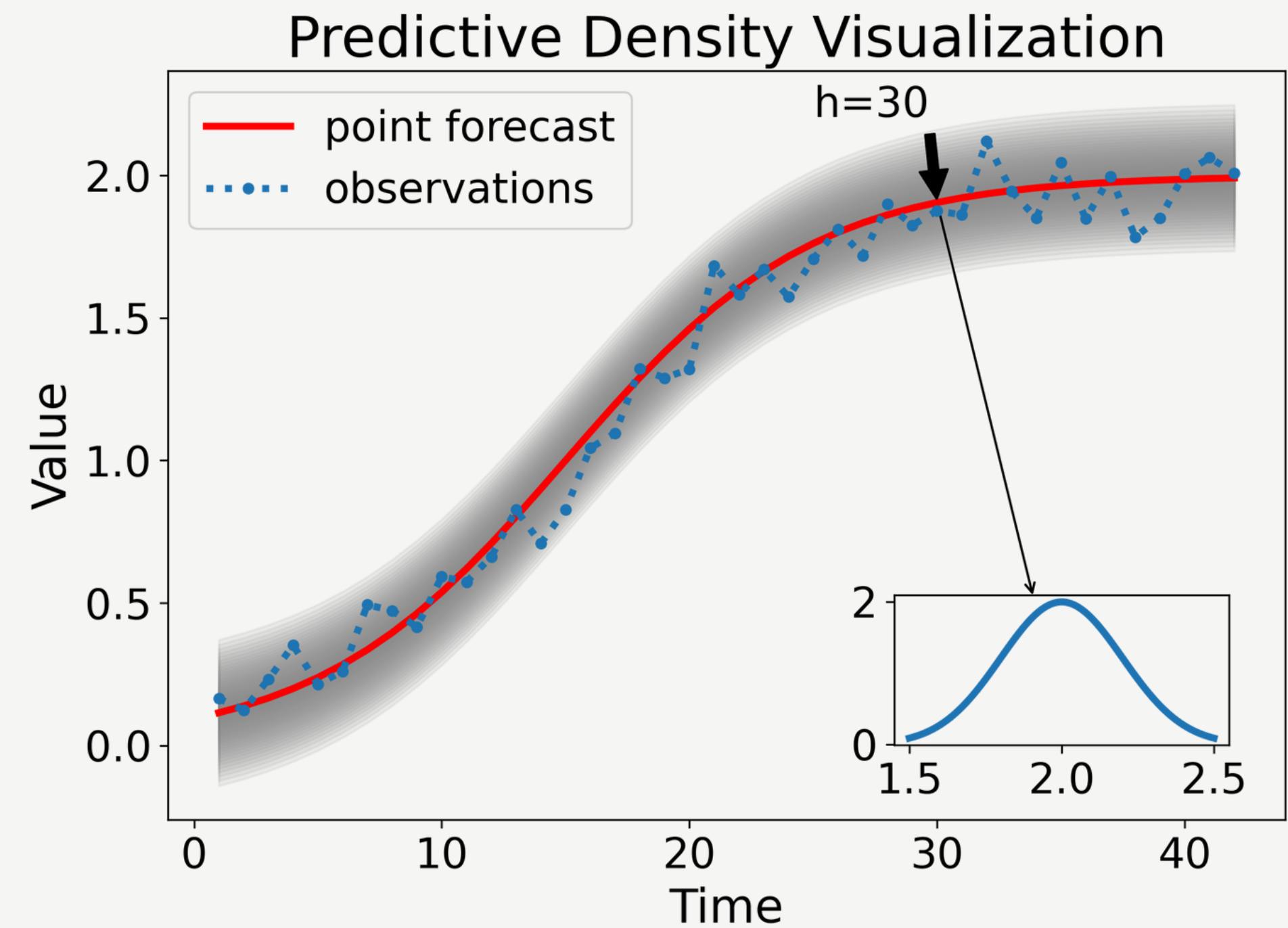
$t$  : Current time

$k$  : Forecast horizon

$\sim$  : denotes “distributed according to”

and:

$$\begin{aligned}\hat{\Phi}_{t+k|t}(x) &= P(\Omega_{t+k} \leq x \mid \text{information up to time } t) \\ &= \int_{-\infty}^x \hat{f}_{t+k|t}(u) du\end{aligned}$$



## Scenario Forecasts

A spectrum of potential futures derived from probabilistic modeling to inform decision-making under uncertainty.

$$\xi^{(i)} \sim \hat{\Psi}$$

where:

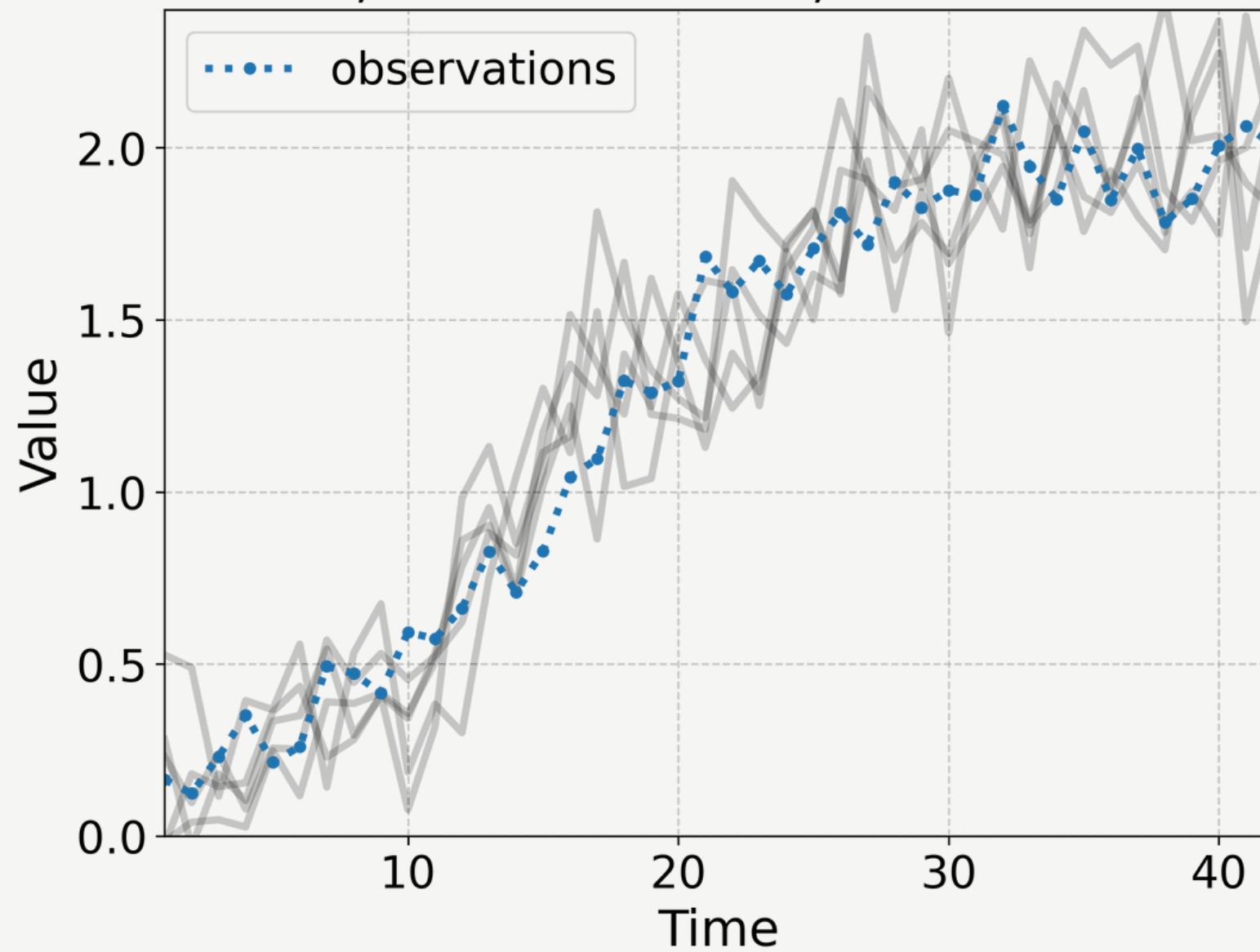
$\hat{\Psi}$  : estimated multivariate predictive distribution of  $\mathbf{X}_t$

$\xi^{(i)}$  : the  $i$ -th trajectory (scenario)

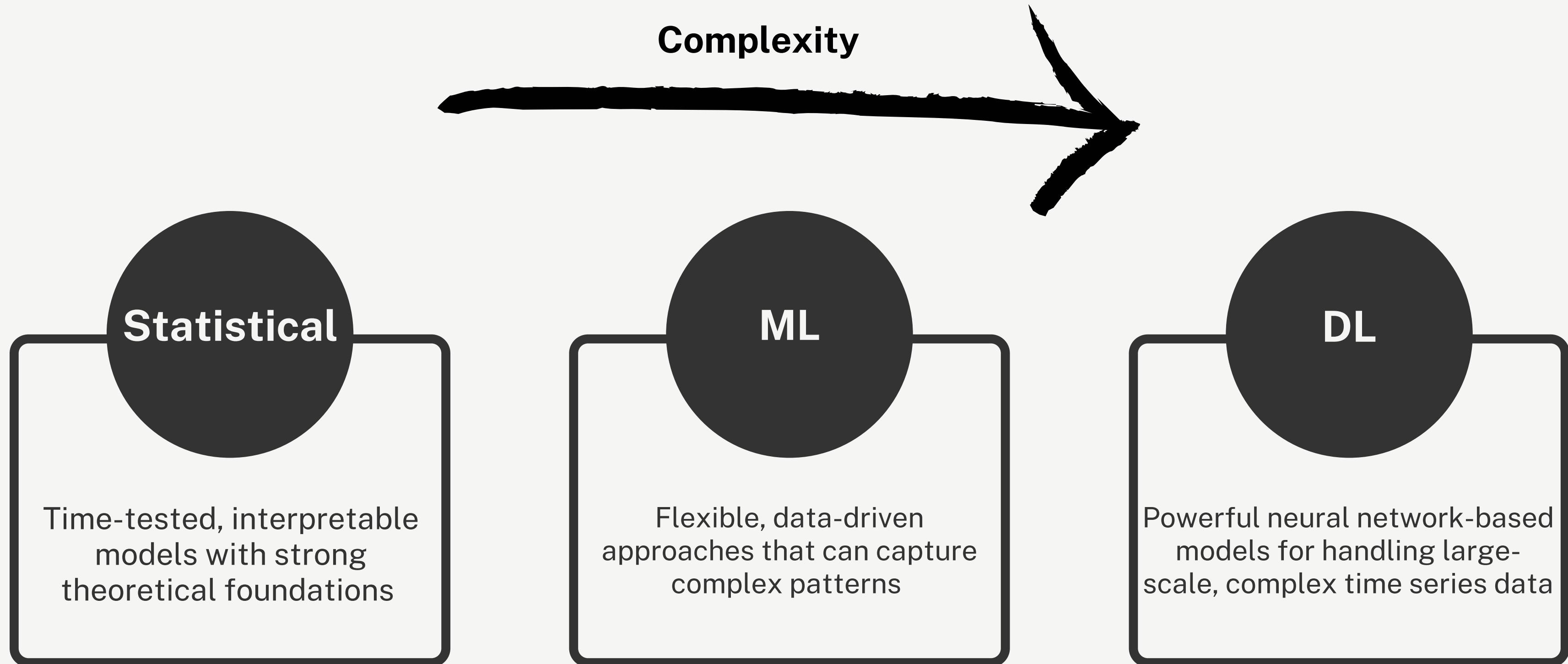
$\mathbf{X}_t$  : vector of future observations

$\sim$  : denotes “sampled from”

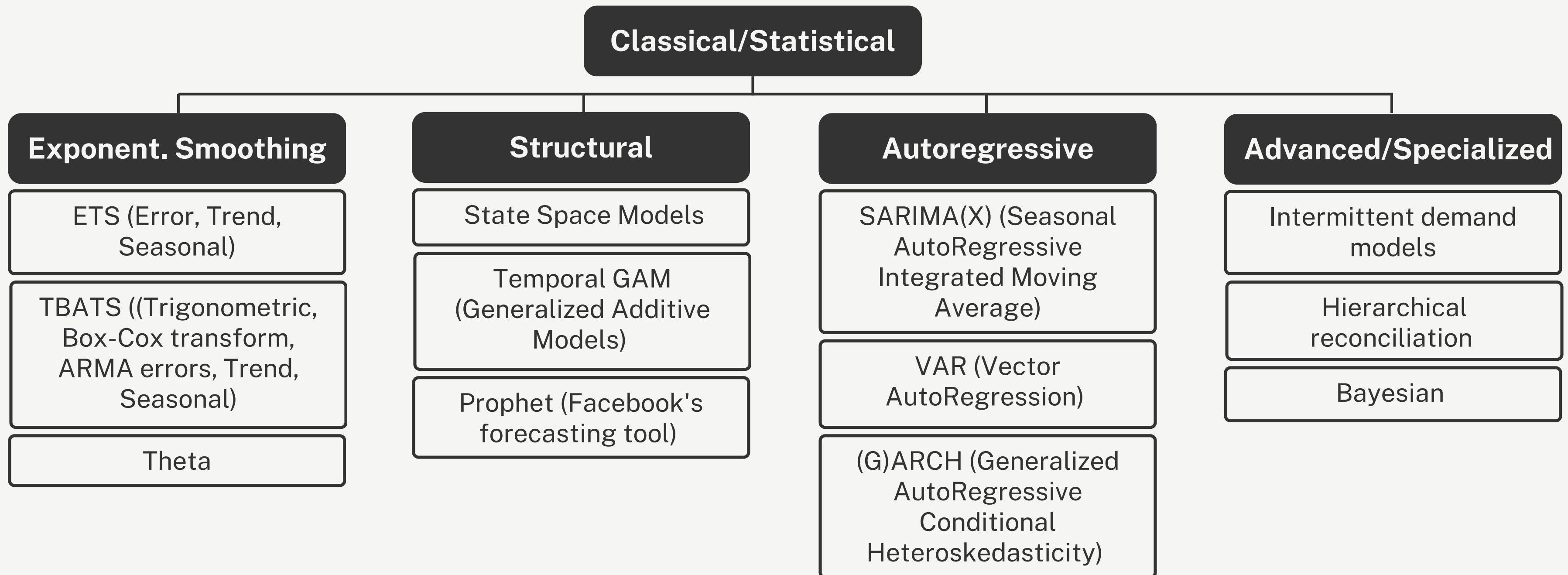
Scenarios, Point Forecast, and Observations



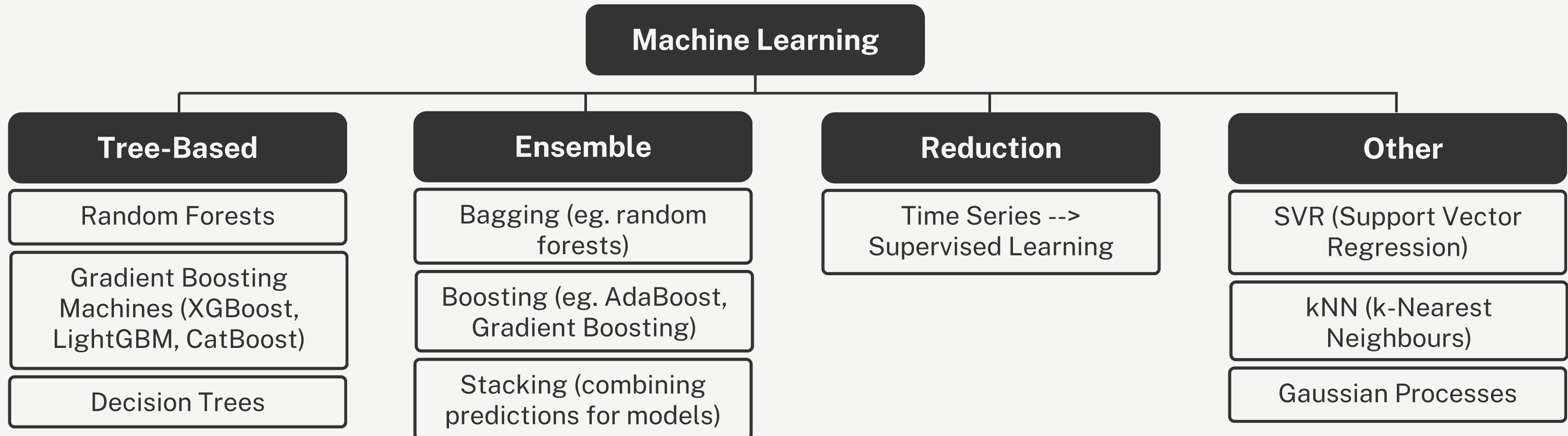
# Methods for (Probabilistic) Forecasting



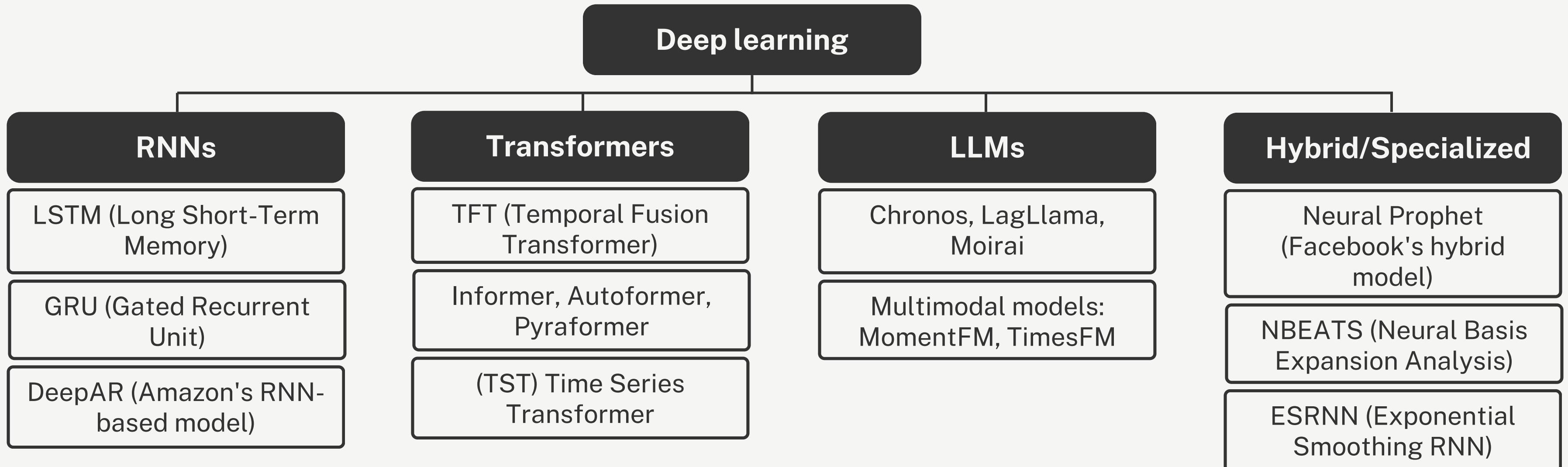
# Strategies for (Probabilistic) Forecasting



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# Strategies for (Probabilistic) Forecasting



# *Evaluating Forecasts*

# Forecasting Performance Metrics

Point	Probabilistic
$\text{bias}(k) = \frac{1}{T} \sum_{t=1}^T e_{t+k t}$	$L_\alpha(y, q) = \begin{cases} \alpha(y - q) & \text{if } y \geq q \\ (1 - \alpha)(q - y) & \text{if } y < q \end{cases}$
$\text{MAE}(k) = \frac{1}{T} \sum_{t=1}^T  e_{t+k t} $	$\text{CRPS} = \frac{1}{T} \sum_{t=1}^T \int_{-\infty}^{\infty} (F_t(y) - \mathbf{1}\{y \geq y_t\})^2 dy$
$\text{RMSE}(k) = \left[ \frac{1}{T} \sum_{t=1}^T e_{t+k t}^2 \right]^{1/2}$	$\text{LogS} = -\frac{1}{T} \sum_{t=1}^T \log(p_t(y_t))$

## Key attributes of high-quality probabilistic forecasts

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- **Reliability (Calibration)**
  - Consistency between forecasted probabilities and observed frequencies

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  - Improvement over a reference forecast (e.g., climatology)

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*Balancing act: Achieving reliability while maximizing sharpness and skill*

# Traps to Avoid When Assessing Probabilistic Models

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- **Oversimplifying Accuracy Metrics**

- *Issue:* Reducing probabilistic forecasts to binary outcomes loses valuable information
  - *Example:* Merely counting hits within a confidence interval overlooks forecast precision

# Traps to Avoid When Assessing Probabilistic Models

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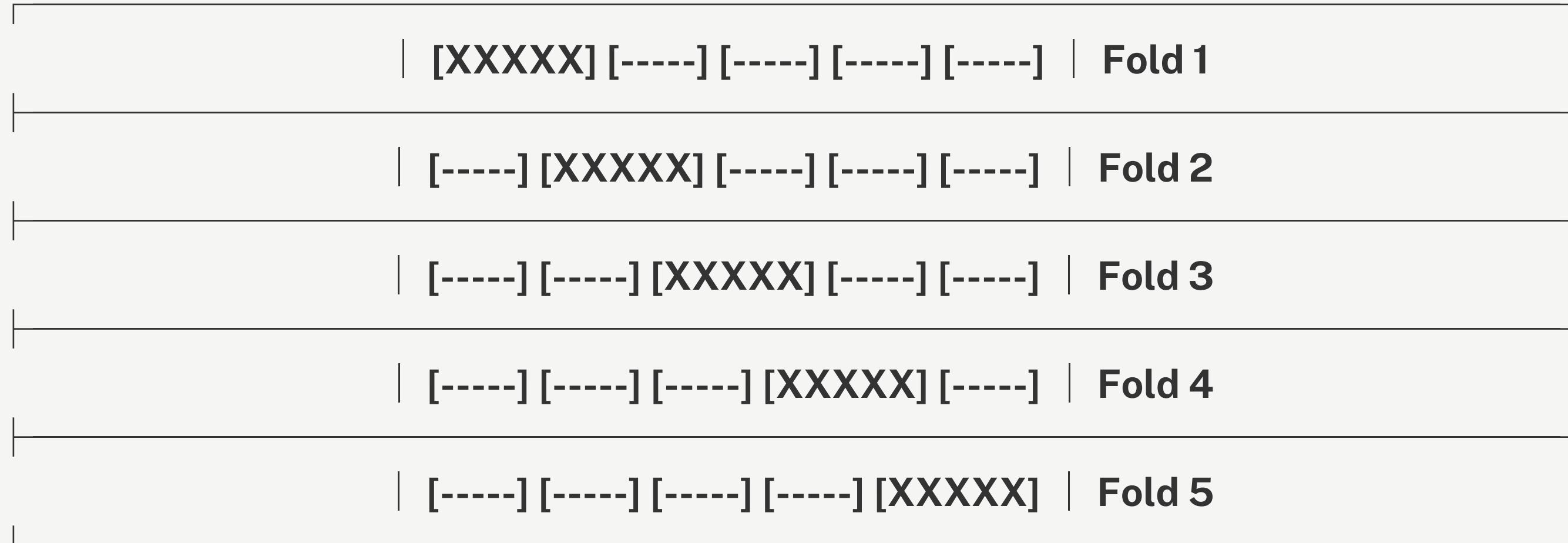
- **Oversimplifying Accuracy Metrics**
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- **Misapplying Traditional Error Measures**
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  - *Technical note:*  $E[f(X)] \neq f(E[X])$  due to Jensen's inequality

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- **Overestimating Model Certainty**
  - *Issue:* Assuming the model's uncertainty estimates are infallible
  - *Caution:* Probabilistic outputs require critical evaluation, not blind acceptance

# Time Series Cross-Validation



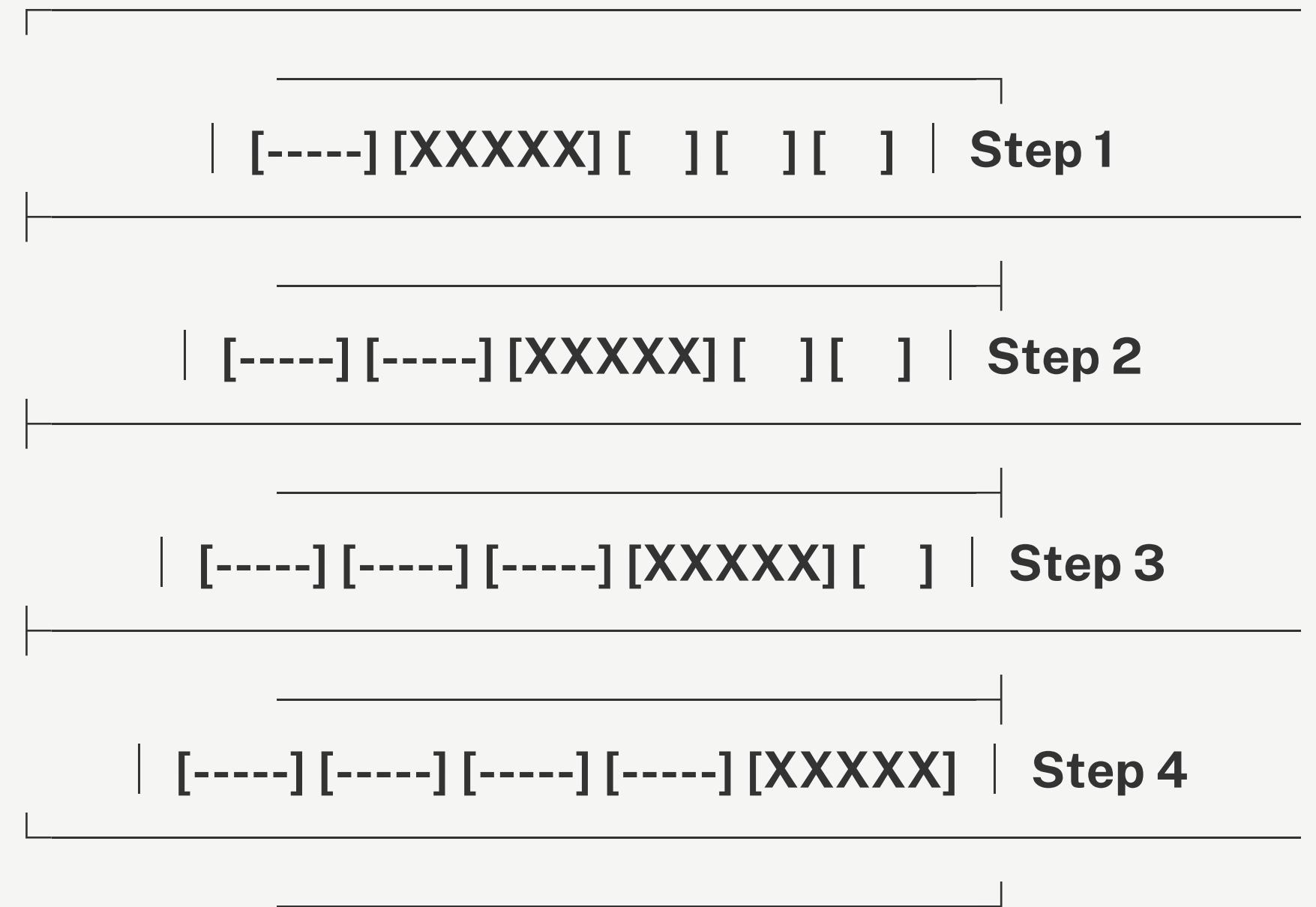
*K-Fold Cross Validation*

# Time Series Cross-Validation



# Time Series Cross-Validation

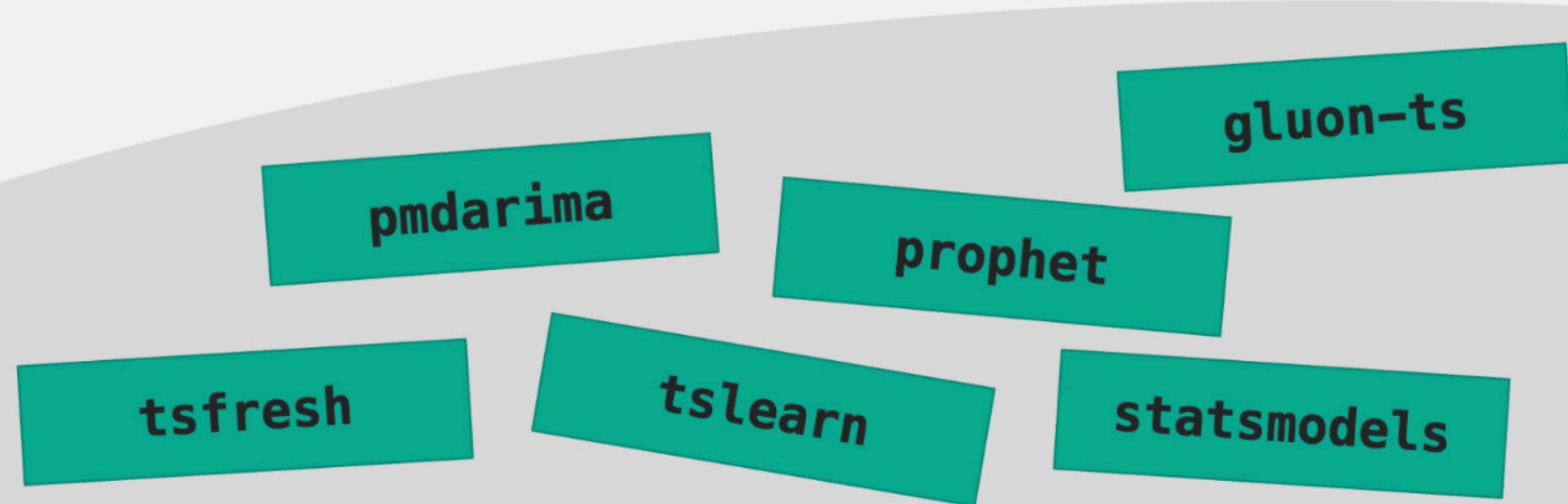
- Walk-Forward (Rolling Window) CV
- Expanding Window CV
- Gap Walk-Forward CV
- Purged CV
- Gap Walk-Forward with Purging CV
- Combinatorial Purged CV



Walk-Forward Cross Validation

# *Python for TS*

# A unified framework



`forecasting`

`classification`

`regression`

`transformations`

`...`