

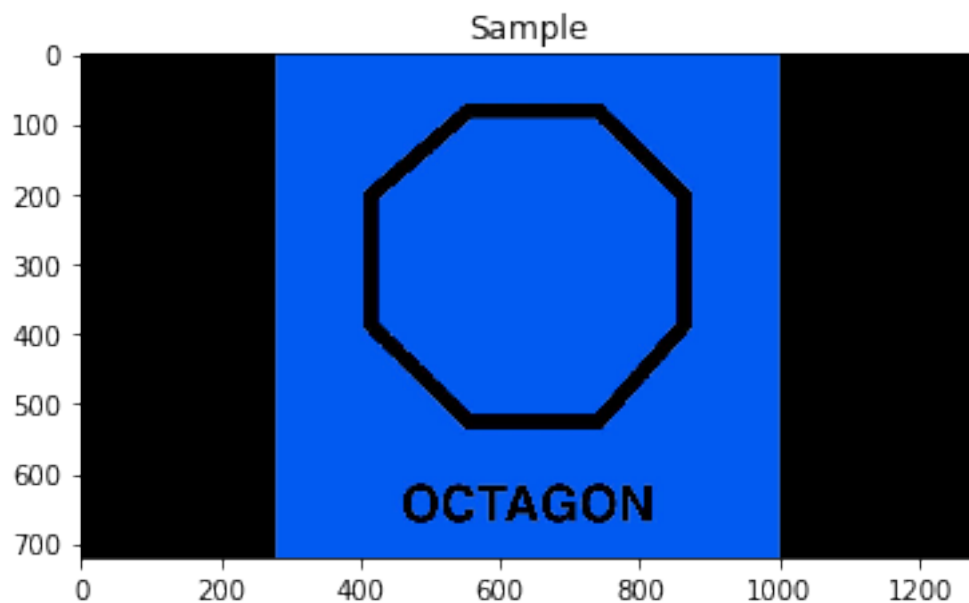
# Edge Detection

April 28, 2019

## 0.0.1 Edge Detection

```
In [1]: import cv2
import numpy as np
from matplotlib import pyplot as plt
```

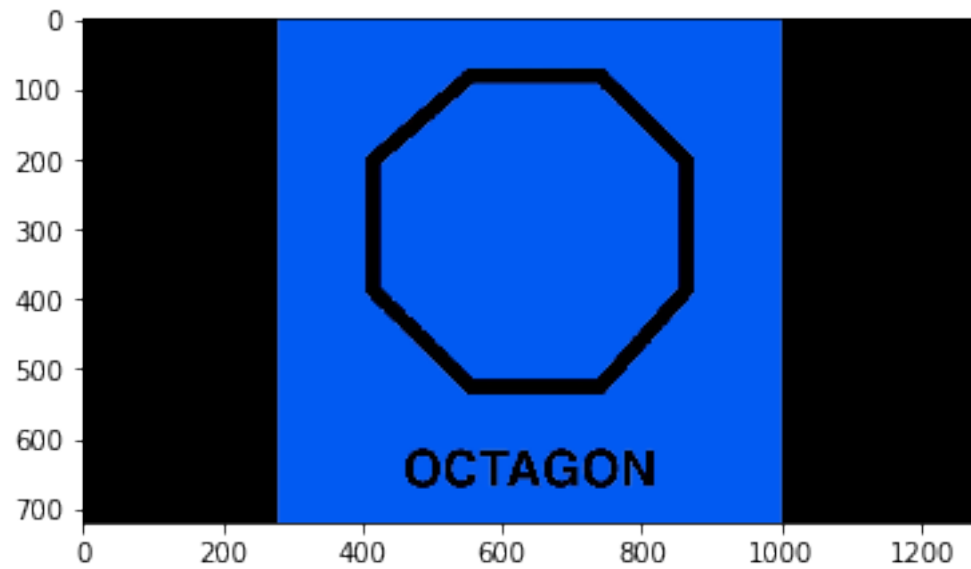
```
In [2]: img = cv2.imread('sample5.jpg')
plt.imshow(img)
plt.title('Sample')
plt.show()
```



```
In [3]: blur = cv2.fastNlMeansDenoisingColored(img, None, 10, 10, 7, 21)
```

```
In [4]: plt.imshow(blur, cmap='gray')
```

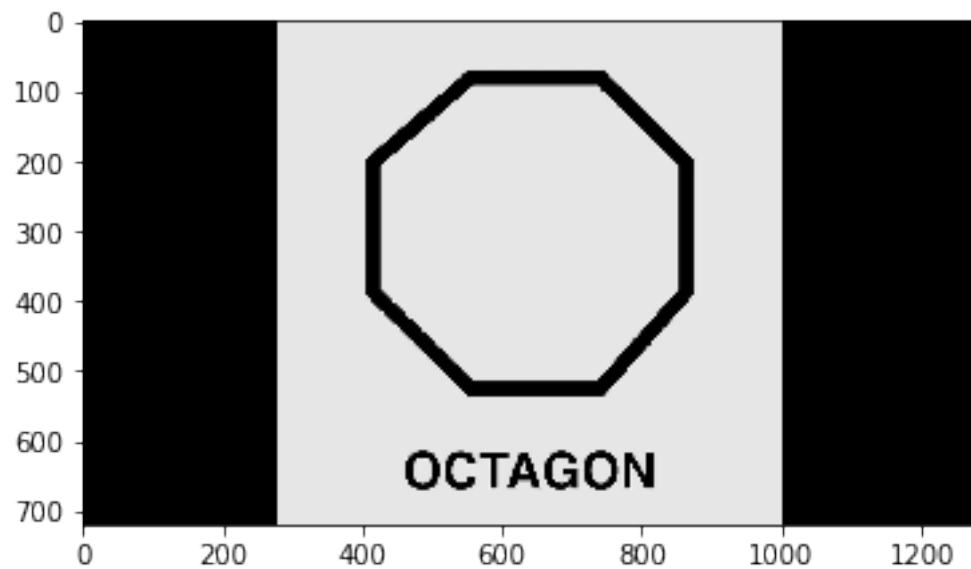
```
Out[4]: <matplotlib.image.AxesImage at 0x11a1daf28>
```



```
In [5]: gray = cv2.cvtColor(blur, cv2.COLOR_BGR2GRAY)
```

```
In [6]: plt.imshow(gray,cmap='gray')
```

```
Out[6]: <matplotlib.image.AxesImage at 0x1bf20e80>
```



```
In [7]: print(gray.shape)
```

(720, 1280)

```
In [8]: def pad(img,shp):
        p=np.zeros((shp[0]+2,shp[1]+2))
        p[1:-1,1:-1]=np.copy(img)
        p[0,1:-1],p[-1,1:-1]=img[0],img[-1]
        p[1:-1,0],p[1:-1,-1]=img[:,0],img[:,-1]
        p[0,0],p[0,-1]=img[0,0],img[0,-1]
        p[-1,0],p[-1,-1]=img[-1,0],img[-1,-1]
        return p

In [9]: def sobel_filter(img):
        sabel_x = np.array([[ -1,0,1],[ -2,0,2],[ -1,0,1]])
        sabel_y = np.array([[ -1,-2,-1],[ 0,0,0],[ 1,2,1]])
        shp = img.shape
        shpm=(3,3)
        padded_img=pad(img,shp)
        grad_matrix=np.zeros(shp)
        out=np.zeros(shp)
        exp = np.zeros(shp)
        for i in range(shp[0]):
            for j in range(shp[1]):
                g_x=np.multiply(padded_img[i:i+shpm[0],j:j+shpm[1]],sabel_x).sum()
                g_y=np.multiply(padded_img[i:i+shpm[0],j:j+shpm[1]],sabel_y).sum()
                if g_y!=0 or g_x!=0:
                    if g_x==0:
                        rad=np.arctan2(g_y,g_x)
                    else:
                        rad=np.arctan2(g_y,g_x)
                    deg=rad*(180/np.pi)
                    rad_rev = deg*(np.pi/180)
                    #print(rad*(180/np.pi),end=" ")
                    #print(rad_rev)
                    grad_matrix[i][j]=deg
                    if grad_matrix[i][j]<0:
                        exp[i][j] = grad_matrix[i][j]
                    out[i][j] = np.sqrt(np.square(g_x)+np.square(g_y))
                else:
                    out[i,j]=255
                    grad_matrix[i][j]=255
        out=np.array(out, dtype = np.uint8)
        grad_matrix=np.array(grad_matrix,dtype= np.uint8)

        return out,grad_matrix,exp

In [10]: def prewitt_filter(img):
        prewitt_x = np.array([[ -1,0,1],[ -1,0,1],[ -1,0,1]])
```

```

prewitt_y = np.array([[1,1,1],[0,0,0],[-1,-1,-1]])
shp = img.shape
shpm=(3,3)
padded_img=pad(img,shp)
grad_matrix=np.zeros(shp)
out=np.zeros(shp)
exp = np.zeros(shp)
for i in range(shp[0]):
    for j in range(shp[1]):
        g_x=np.multiply(padded_img[i:i+shpm[0],j:j+shpm[1]],prewitt_x).sum()
        g_y=np.multiply(padded_img[i:i+shpm[0],j:j+shpm[1]],prewitt_y).sum()
        if g_y!=0 or g_x!=0:
            if g_x==0:
                rad=np.arctan2(g_y,g_x)
            else:
                rad=np.arctan2(g_y,g_x)
            deg=rad*(180/np.pi)
            rad_rev = deg*(np.pi/180)
            #print(rad*(180/np.pi),end=" ")
            #print(rad_rev)
            grad_matrix[i][j]=deg
            if grad_matrix[i][j]<0:
                exp[i][j] = grad_matrix[i][j]
                print(exp[i][j])
            out[i][j] = np.sqrt(np.square(g_x)+np.square(g_y))
        else:
            out[i,j]=255
            grad_matrix[i][j]=255
out=np.array(out, dtype = np.uint8)

return out,grad_matrix,exp

```

In [11]: output, grad\_matrix,exp = sobel\_filter(gray)

In [ ]:

In [12]: plt.imshow(exp,cmap='gray')

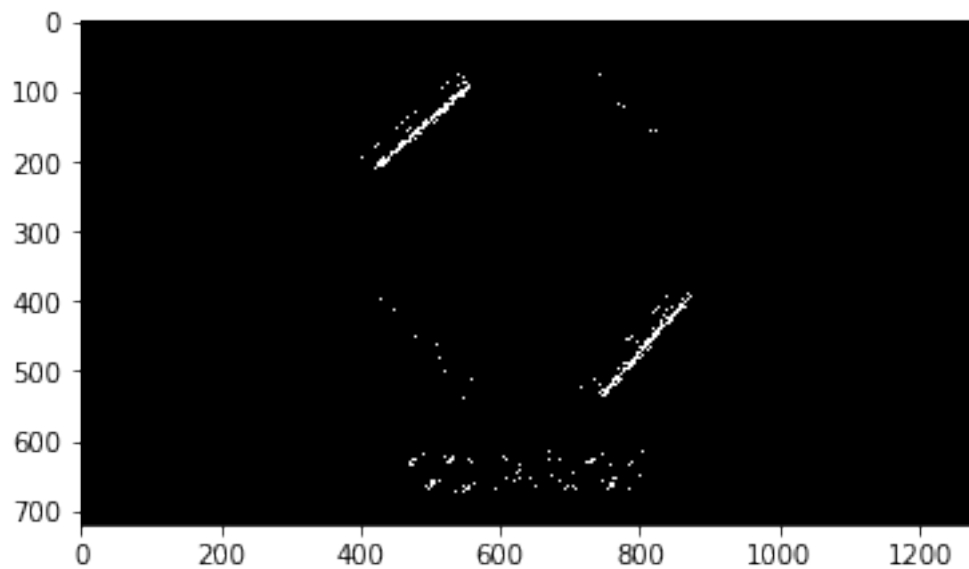
Out[12]: <matplotlib.image.AxesImage at 0x11c227dd8>



-48.03403964694501  
-34.99202019855866  
-47.48955292199916  
-40.91438322002513  
-57.10767025676035  
-40.539151741483444  
-45.0  
-57.885169399703265  
-38.736509385665464  
-43.97696981133217  
-41.18592516570965  
-45.0  
-49.899092453787766  
-45.0  
-45.0  
-57.52880770915151  
-45.0  
-45.0  
-39.472459848343824  
-44.13194855025446  
-45.0  
-49.899092453787766  
-47.48955292199916  
-45.0  
-58.10920819815429  
-32.9052429229879  
-45.0  
-45.0  
-45.0  
-45.0  
-50.19442890773481  
-33.690067525979785  
-45.0  
-45.0  
-45.0  
-59.03624346792648  
-45.0  
-45.0  
-53.13010235415598  
-55.00797980144134  
-47.12109639666146  
-45.0  
-30.96375653207352  
-56.309932474020215  
-45.0  
-45.0  
-56.309932474020215  
-56.309932474020215

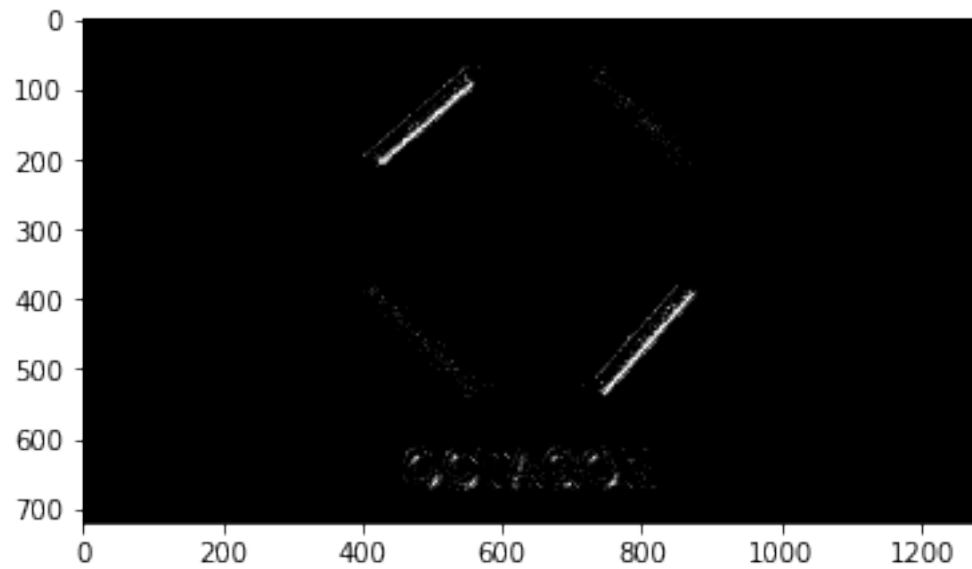
```
-33.690067525979785
-45.0
-36.86989764584402
-45.0
-45.0
-45.0
-45.0
-56.309932474020215
-45.0
-45.0
-45.0
-45.0
-59.03624346792648
-45.0
-45.0
-53.13010235415598
-45.0
```

```
In [25]: plt.imshow(filtered2,cmap="gray")
         cv2.imshow('image',filtered2)
         cv2.waitKey()
         cv2.destroyAllWindows()
```



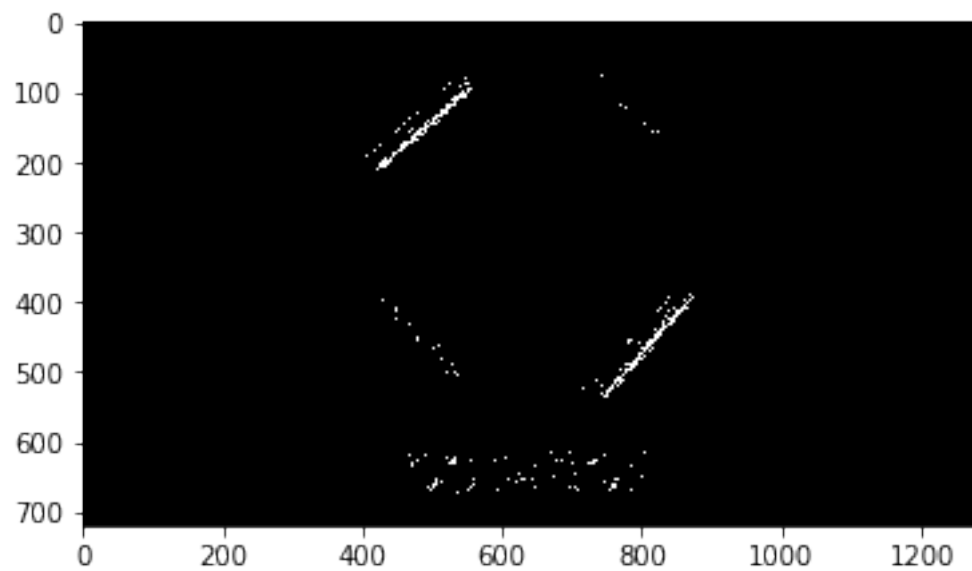
```
In [26]: smo_fil = cv2.GaussianBlur(filtered2,(5,5),0)
```

```
In [27]: plt.imshow(smo_fil,cmap='gray')
         plt.imsave('output_edge.png',smo_fil,cmap='gray')
```



In [ ]:

```
In [28]: plt.imshow(filtered,cmap="gray")
cv2.imshow('image',filtered)
cv2.waitKey()
cv2.destroyAllWindows()
```





```
In [29]: x = np.array([-1, +1, +1, -1])
          y = np.array([-1, -1, +1, +1])

          np.arctan2(y,x)*180/np.pi

Out[29]: array([-135., -45.,  45., 135.])

In [ ]:

In [ ]:
```