Connectivity

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In [18]: class pixel:
             def __init__(self,x,y):
                 self.x = x
                 self.y = y
In [23]: def four_way_check(p1,p2):
             x1, y1 = p1.x, p1.y
             x2, y2 = p2.x, p2.y
             if x2==x1:
                 if y2-1==y1:
                     return True
                 elif y2+1==y2:
                     return True
             elif y2==y1:
                 if x2-1==x1:
                     return True
                 elif x2+1==x1:
                     return True
             else:
                 return False
In [29]: def four_way(p1):
             x1, y1 = p1.x, p1.y
             neig_four = [(x1-1,y1),(x1+1,y1),(x1,y1-1),(x1,y1+1)]
             return neig_four
In [31]: def d_way(p1):
             x1, y1 = p1.x, p1.y
             neig_d = [(x1-1,y1-1),(x1-1,y1+1),(x1+1,y1-1),(x1+1,y1+1)]
             return neig_d
In [33]: def eight_way(p1):
             x1, y1 = p1.x, p1.y
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eight = [(x1-1,y1-1),(x1-1,y1),(x1-1,y1+1),(x1,y1-1),(x1,y1+1),(x1+1,y1-1),(x1+1,y1-1)]
             return eight
In [38]: print(four_way(p2))
[(0, 0), (2, 0), (1, -1), (1, 1)]
In [39]: print(d_way(p2))
[(0, -1), (0, 1), (2, -1), (2, 1)]
In [40]: print(eight_way(p2))
[(0, -1), (0, 0), (0, 1), (1, -1), (1, 1), (2, -1), (2, 0), (2, 1)]
In [21]: p1 = pixel(0,0)
         p2 = pixel(1,0)
         print(four_way(p1))
True
In [7]: p3 = pixel(1,1)
        print(four_way(p1,p3))
False
In [24]: def d_way_check(p1,p2):
             x1, y1 = p1.x, p1.y
             x2, y2 = p2.x, p2.y
             if x2-1==x1 and y2-1==y1:
                 return True
             elif x2-1==x1 and y2+1==y1:
                 return True
             elif x2+1==x1 and y2-1==y1:
                 return True
             elif x2+1==x1 and y2+1==y1:
                 return True
             else:
                 return False
In [9]: d_way(p1,p2)
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Out[9]: False
In [10]: d_way(p1,p3)
Out[10]: True
In [25]: def eight_way_check(p1,p2):
                                                     x1, y1 = p1.x, p1.y
                                                     x2, y2 = p2.x, p2.y
                                                     eight = [(x1-1,y1-1),(x1-1,y1),(x1-1,y1+1),(x1,y1-1),(x1,y1+1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(x1+1,y1-1),(
                                                     if (x2,y2) in eight:
                                                                     return True
                                                     else:
                                                                     return False
In [12]: eight_way(p1,p2)
Out[12]: True
In [13]: p4 = pixel(2,3)
In [14]: eight_way(p1,p4)
Out[14]: False
In [26]: def m_way_check(p1,p2):
                                                     x1, y1 = p1.x, p1.y
                                                     x2, y2 = p2.x, p2.y
                                                     eight = [(x1-1,y1-1),(x1-1,y1),(x1-1,y1+1),(x1,y1-1),(x1,y1+1),(x1+1,y1-1),(x1+1,y1-1)]
                                                     if (x2,y2) in eight:
                                                                      return True
                                                     else:
                                                                      return False
In [16]: m_way(p1,p2)
Out[16]: True
In [17]: m_way(p1,p4)
Out[17]: False
In []:
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