Total 1	No.	of (	<b>Questions</b>	:	10]	
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[4758]-539

T.E. (E & TC)

## DIGITAL SIGNAL PROCESSING

(2012 Course) (Semester - I) (304182) (End Semester)

Time: 2½ Hours] [Max. Marks:70

Instructions to the candidates:

- 1) Neat diagrams must be drawn wherever necessary.
- 2) Figures to the right indicate full marks.
- 3) Use of logarithmic tables slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- 4) Assume suitable data, if necessary.
- Q1) a) Consider the analog signal  $x_a(t)$  as  $x_a(t) = 6 \cos 50 \pi t + 3 \sin 200 \pi t 3 \cos 100 \pi t$  [5]
  - i) Determine the minimum sampling frequency.
  - ii) Determine x(n) at minimum sampling frequency.
  - iii) Sketch the waveform and show the sampling points.
  - b) Determine the transfer function and impulse response of the LTI system given by the difference equation. [5]

$$y(n) + \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) + x(n-1)$$

OR

- **Q2)** a) State and prove convolution property of Z transform. [5]
  - b) Compute 4- points DFT of the sequence given by  $x(n) = (-1)^n$  using DIT FFT algorithm. [5]

- Q3) a) State four important advantages of digital signal processing over analog signal processing.[4]
  - b) For the following sequences, [6]

$$x_{1}(n) = \begin{cases} 1 & 0 \le n \le 2\\ 0 & \text{otherwise} \end{cases}$$

$$x_2(n) = \begin{cases} 1 & 0 \le n \le 2 \\ 0 & \text{otherwise} \end{cases}$$

Compute linear convolution using circular convolution.

OR

**Q4)** a) Using partial fraction expansion, find inverse Z-Transform of following system function and verify it using long division method, [5]

$$H(Z) = \frac{1+2 Z^{-1}}{1-0.4Z^{-1}-0.12 Z^{-2}}$$
 if  $h(n)$  is causal.

- b) State and prove circular time shift property of DFT [5]
- **Q5)** a) Design a butterworth digital IIR lowpass filter using bilinear transformation to satisfy following specifications: [10]

$$0.6 \le |H(e^{jw})| \le 1.0$$
  $0 \le w \le 0.35\pi$   
 $|H(e^{jw})| \le 0.1$   $0.7\pi \le w < \pi$ . Use T = 0.1 seconds.

- b) Compare between Bilinear transformation method and impulse invariant method. [3]
- c) Draw direct form I & direct form II realisations for the second order system given by: [4]

$$y(n) = 2b \cos w_0 y(n-1) - b^2 y(n-2) + x(n) - b \cos w_0 x(n-1)$$

OR

**Q6)** a) The system function of an analog filter is given by

$$H(s) = \frac{s + 0.2}{(s + 0.2)^2 + 9}$$

Convert it to digital filter using Impulse Invariant technique. Assume T = 1 second.

- b) Given  $H(s) = \frac{1}{s+1}$ . Apply impulse invariant method to obtain digital filter transfer function and difference equation. Assume T = 1 second. [4]
- c) For the system given by following equation [9]

$$H(z) = \frac{1 - z^{-1}}{1 - 0.2z^{-1} - 0.15z^{-2}}.$$

Draw cascade and parallel realisation.

- Q7) a) Design a linear phase FIR band pass filter using hamming window with cut off frequencies 0.2 rad/sec & 0.3 rad/sec. M = 7.[9]
  - b) Explain the characteristics of window function. [4]
  - c) Distinguish between FIR and IIR filter. [4]

OR

- **Q8)** a) Design a linear phase FIR lowpass filter with a cutoff frequency of 0.5 rad/sample by taking 11 samples of ideal frequency response. [9]
  - b) What is Gibb's phenomenon? How it is reduced? [4]
  - c) Show that the filter with symmetric impulse response has linear phase response. [4]

- **Q9)** a) With the help of neat diagram, and waveform explain sampling rate conversion by non-integer factor. [4]
  - b) Sampling rate is to be reduced from 96kHz to 1 kHz. Highest frequency of interest is 450 Hz  $\delta_p = 0.01$ ,  $\delta_s = 0.001$ . Design a decimator with decimating factors of 32 and 3. [6]
  - c) Write short notes on [6]
    - i) MAC unit
    - ii) Barrel shifter

OR

- Q10)a) What is the role of anti aliasing filter & anti imaging filter in decimator & interpolator, respectively.
  - b) Describe four important features of a digital signal processor. [6]
  - c) Explain the architecture of TMS 320C67XX digital signal processor.[6]

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