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SEAT No.:	
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[Total No. of Pages :2

[5153] - 553 T.E. (E & TC)

MICROCONTROLLER AND APPLICATIONS

(2012 Pattern) (Semester - I) (End Sem.) (304183)

Time	e : 2	2½ Hours] [Max. Marks	:70
Instr	ucti	ions to the candidates;	
	1)	Answer Q1 or Q2, Q3 or Q4, Q5 or Q6, Q7 or Q8.	
	2)	Neat diagrams must be drawn wherever necessary.	
	<i>3)</i>	Figures to the right side indicate full marks.	
	<i>4)</i>	Use of calculator is allowed.	
	<i>5)</i>	Assume suitable data if necessary.	
Q 1)	a)	Differentiate RS232 and RS485 Serial Communication Protocol.	[6]
	b)	Explain the programming model of 8051.	[6]
	c)	Explain with example function of ALU in PIC for transfer of data.	[8]
		OR	
Q2)	a)	Explain in depth use of 12C protocol and state any two difference betwee 12C and SPI.	een [6]
	b)	Explain different addressing modes with example.	[6]
	c)	State features of PIC, draw and explain the data memory organization.	[8]
Q3)	a)	Draw and explain the port structure of PIC with different registers us in programming.	sed [8]
	b)	Explain in detail PWM mode in PIC.	[8]
		OR	
Q4)	a)	Differentiate between operating functions of Timer 0, 1 and 2 of Pl Draw and explain functional diagram of Timer 0 of PIC.	IC. [8]
	b)	one and 'SPPU' at 5th position on second line, write an embedded	

P.T.O.

Explain the SPI mode of MSSP structure used for serial communication. **Q5)** a) Explain the use of PIC ADC to interface the motion sensors used for b) accepting the location and display on LCD. [8] OR Explain the use of BRG register for calculation of baud rate with USART **Q6)** a) block diagram. [8] State fetures of RTC and draw an interfacing diagram with PIC, write an b) initialization program. [8] Draw Generalized block diagram of DAS and state its features. **Q7**) a) [8] Design a dC Motor controller circuit using PWM for motion control.[10] b) OR Design a frequency counter to display the pulses received from the tacho-**Q8)** a) meter. Design a DMM Using PIC controller to display AC and DC values of b) Electrical signals. [10]