| Total No. of Questions: 8] | SEAT No.: |
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T.E. (E&TC) (Semester - I)

MICROCONTROLLER AND APPLICATIONS (2012 Pattern) Time: 2½ Hours] [Max. Marks:70 Instructions to the candidates: Answer Q1 or Q2, Q3 or Q4, Q5 or Q6 and Q7 or Q8. 1) 2) Neat diagrams must be drawn wherever necessary. 3) Figures to the right indicate full marks. Use of Calculator is allowed. 4) Assume Suitable data if necessary. 5) Differentiate RS232 and RS485 Serial Communication Protocol. **Q1**) a) [6] Explain the programming model of 8051. b) [6] Explain with example function of ALU in PIC for transfer of data. c) [8] Explain in depth use of I2C protocol and state any two difference between *02*) a) 12C and SPI. Explain different addressing modes with example. b) State features of PIC, draw and explain the data memory organization. [8] c) OR Draw and explain the port structure of PIC with different registers used *Q3*) a) in programming. [8] Explain in detail PWM mode in PIC. b) [8] OR Differentiate between operating functions of Timer 0, 1 and 2 of PIC. *Q4*) a)

Draw and explain functional diagram of Timer() of PIC. [8]

| | b) | Draw an interfacing diagram to display 'GANESH' on 4 th position in line one and 'SPPU' at 5 th position on second line, write an embedded C |
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| | | program. [8] |
| Q5) | a) | Explain the SPI mode of MSSP structure used for serial communication. [8] |
| | b) | Explain the use of PIC ADC to interface the motion sensors used for accepting the location and display on LCD. [8] |
| | | OR |
| Q6) | a) | Explain the use of BRG register for calculation of baud rate with UART block diagram. [8] |
| | b) | State features of RTC and draw an interfacing diagram with PIC, write an initialization program. [8] |
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| Q 7) | a) | Draw Generalized block diagram of DAS and state its features. [8] |
| | b) | Design a DC Motor controller circuit using PWM for motion control.[10] OR |
| Q8) | a) | Design a frequency counter to display the pulses received from the tachometer. [8] |
| | b) | Design a DMM using PIC controller to display AC and DC values of electrical signals. [10] |
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