## 4-vectors

In three-dimensional space we define a position vector  $\vec{x}$  (or  $\vec{r}$ ) as  $\vec{x} = (x, y, z)$  [or  $\vec{r} = xi + yj + zk$ ] In special relativity space and time are considered together Define a 4-vector  $x'' = (ct, x, y, z) = (x^{\circ}, x', x^{2}, x^{3})$ where x'=ct, x'=x,  $x^2=y$ ,  $x^3=Z$ where c is the speed of light in vacuum Note that the index  $\mu$  takes the values  $\mu=0,1,2,3$ x is called a contravariant vector (index upstairs) We also define a covariant vector Xm (index downstairs)  $X_{\mu} = (x_0, x_1, x_2, x_3) = (ct, -x, -y, -z)$ So  $x' = x_0$ ,  $x' = -x_1$ ,  $x^2 = -x_2$ ,  $x^3 = -x^3$ 

In relativity the squared length  $x^2ty^2+z^2$  is not invariant under Lorentz transformations  $\rightarrow$  contraction seen by moving observer However  $c^2t^2-x^2-y^2-z^2$  is invariant Note that  $x^Mx_\mu=x^2x_0+x^1x_1+x^2x_2+x^3x_3=c^2t^2-x^2-y^2-z^2$  where we used the summation convention that repeated indices are summed over, i.e.  $x^Mx_\mu=\sum_{\mu=0}^{\infty}x^{\mu}x_{\mu}$ 

These considerations apply to any four-vector A

At is contravariant vector  $A^{H} = (A^{\circ}, A^{\dagger}, A^{2}, A^{3})$  with  $A^{\dagger} = A_{\times}, A^{2} = A_{y}, A^{3} = A_{z}$ Aµ is covariant vector  $A_{\mu}=(A_0,A_1,A_2,A_3)=(A^0,-A^1,-A^2,-A^3)$ and  $A^2 = A \cdot A = A^{\mu} A_{\mu} = A^{\circ} A_{\circ} + A^{\dagger} A_{1} + A^{2} A_{2} + A^{3} A_{3} = (A^{\circ})^{2} - (A^{\dagger})^{2} - (A^{2})^{2} - (A^{3})^{2}$ is the dot (scalar) product of the vector with itself, an invariant For brevity we can also write  $A^{H}=(A^{\circ}, \overline{A})$  where  $\overline{A}=(A^{\circ}, A^{2}, A^{3})$  is a 3-vector e.g.  $x^{M}=(ct, \overline{x})$  where  $\overline{x}=(x', x^{2}, x^{3})=(x, y, z)$  and  $A_{\mu}=(A^{\circ}, -\overline{A})$ 

metric tensor

symmetric

gur=gru An = ghr Ar where ghr is the In flat spacetime (special relativity) So  $A^{\circ} = g^{\circ r} A_{r} = g^{\circ o} A_{o} + g^{\circ l} A_{l} + g^{\circ 2} A_{2} + g^{\circ 3} A_{3}$ =1.A<sub>o</sub> +0.A<sub>l</sub> + 0.A<sub>2</sub> + 0.A<sub>3</sub> = A<sub>o</sub> A'=g'rAr===-A, , etc. Also A2 = AMA = 9 ArA = 9 ArAr and A2= AMA == AM g N AV = g N AMA"

Energy-momentum 4-vector

 $\rho^{\mathsf{M}} = (\rho^{\circ}, \vec{\rho}) = (\underline{E}, \vec{\rho}) = (\underline{E}, \rho_{\mathsf{X}}, \rho_{\mathsf{Y}}, \rho_{\mathsf{Z}})$  $P_{\mu}=(P_0,-\vec{p})=(\frac{E}{C},-\vec{p})=(\frac{E}{C},-P_x,-P_y,-P_z)$ 

Then  $p^2 = p \cdot p = p^M p_M = \frac{E^2}{C^2} - \vec{p}^2 = m^2 c^2$  a relativistic invariant

E=\frac{1}{p^2c^2+m^2c^4} Also E=ymc where the time dilation factor is  $\gamma = \frac{1}{\sqrt{1-v^2}}$ 

Also An=ghv Ar with ghv=9

 $A \cdot B = A^{\mu} B_{\mu} = g_{\mu r} A^{\mu} B^{r} = A^{\circ} B - A \cdot B$ =  $A_{\mu} B^{\mu} = g^{\mu r} A_{\mu} B^{r} = A^{\circ} B^{\circ} - A^{i} B^{i} - A^{2} B^{2} - A^{3} B^{3}$ 

Invariant differential spacetime squared length ds2 = dx dx dx = qurx dx We define  $\partial_{\mu} = \frac{\partial}{\partial x^{\mu}} = \left(\frac{\partial}{\partial x^{0}}, \frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}\right) = \left(\frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}\right) = \left(\frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}\right) = \left(\frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}\right) = \left(\frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x^{3}}, \frac{\partial}{\partial x^{2}}, \frac{\partial}{\partial x$ Then  $\partial^{M} = \left(\frac{1}{C} \frac{\partial}{\partial t}, -\vec{\nabla}\right)$  and  $\partial^{M} = g^{Mr} \partial_{r}$ Here  $\nabla = (\frac{3}{3x}, \frac{3}{3y}, \frac{3}{3z})$  is the gradient The d'Alembertian is  $\partial^{\mu} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \vec{\nabla} \cdot \vec{\nabla} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2$ where  $\nabla^2 = \frac{3^2}{3x^2} + \frac{3^2}{3y^2} + \frac{3^2}{3z^2}$  is the Laplacian. So  $3^M 3_H = \frac{1}{c^2} \frac{3^2}{3t^2} - \frac{3^2}{3x^2} - \frac{3^2}{3y^2} - \frac{3^2}{3z^2}$ More index gymnastics AMB\_= AMB\_ since \u00ed, v are dummy indices when repeated

More index gymnostics  $A^{\mu}B_{\mu} = A^{\nu}B_{\nu}$  since  $\mu, \nu$  are dummy indices when repeated  $A_{\mu} = g_{\mu\nu} A^{\nu}$  and  $A^{\nu} = g^{\nu}P_{\mu}A_{\rho}$ . Then  $A_{\mu} = g_{\mu\nu} g^{\nu}P_{\mu}A_{\rho} = g_{\mu}P_{\mu}A_{\rho}$  where  $g_{\mu} = 0$  if  $\mu \neq \rho$ .

So  $A_{\mu} = g_{\mu}P_{\mu}A_{\rho}$  and  $A^{\mu} = g_{\rho}P_{\mu}A_{\rho}$ .

Also  $g^{\mu\rho}g_{\nu\rho} = g_{\nu}P_{\nu}$  and  $g^{\mu\rho}g_{\rho}P_{\nu} = g_{\mu\nu}P_{\nu}P_{\nu}$ .