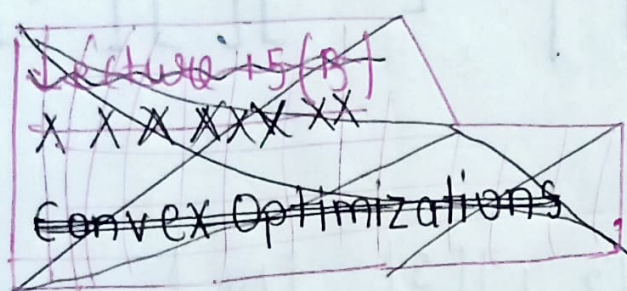


Positive Definite

$$\Omega(\vec{x}, \vec{x}) = \vec{x}^T \vec{x} = \sum_{i=1}^n x_i^2$$

$$\begin{aligned} &> 0 \quad \text{if } \vec{x} \neq \vec{0} \\ &= 0 \quad \text{if } \vec{x} = \vec{0} \end{aligned}$$

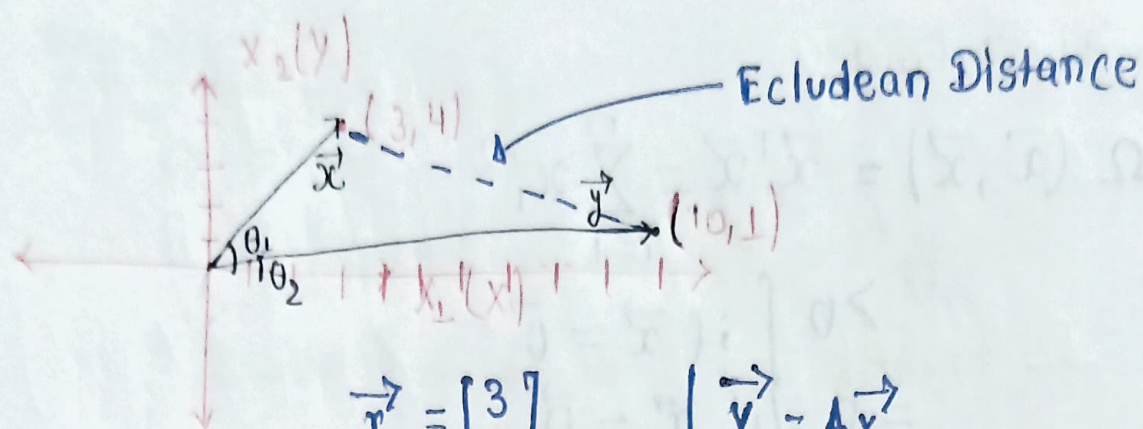
Hence Ω is positive Definite.



Lecture - 18 (07/10/24)

Lecture-19

- ▷ Distance function
- ▷ Orthogonal vectors
- ▷ orthonormal vectors
- ▷ Orthogonal matrix



$$\vec{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \quad \left| \quad \vec{y}_1 = A_1 \vec{x} \right.$$

$$A_1 = \begin{bmatrix} 2 & 1 \\ -3 & -1 \end{bmatrix} \quad \left| \quad = \begin{bmatrix} 2 & 1 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 10 \\ -13 \end{bmatrix} \right.$$

$$A = \begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix}$$

$$\vec{y} = A \vec{x} = \begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 10 \\ 1 \end{bmatrix}$$

① $d: V \rightarrow \mathbb{R}$ is a distance function

iff $\forall \vec{x}, \vec{y} \in V$ and $\alpha \in \mathbb{R}$

i) $d(\vec{x}, \vec{y}) = \|\vec{x} - \vec{y}\|$

ii) $d(\vec{x}, \vec{y}) = \begin{cases} 0, & \text{if } \vec{x} = \vec{y} \\ > 0, & \text{if } \vec{x} \neq \vec{y} \end{cases}$

iii) $d(\alpha \vec{x}, \alpha \vec{y}) = |\alpha| d(\vec{x}, \vec{y})$

② Orthogonal vector:

$\vec{x}, \vec{y} \in \vec{V}$ are orthogonal
if $\langle \vec{x}, \vec{y} \rangle = 0$ and $\vec{x}, \vec{y} \neq \vec{0}$

Inner product

In addition,

③ \vec{x}, \vec{y} are orthonormal if $\|\vec{x}\| = 1$
 $\|\vec{y}\| = 1$

④ Orthogonal Matrix

A matrix $A \in \mathbb{R}^n$ is orthogonal if

(i) the column vectors of A are orthonormal

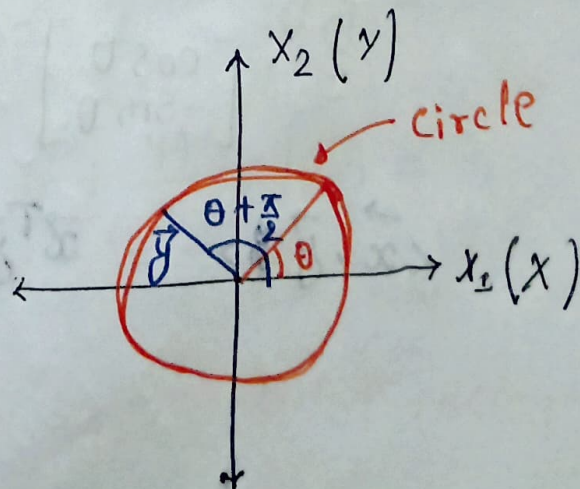
$$\left. \begin{array}{l} \text{(ii)} \quad AA^T = I \\ \text{(iii)} \quad A^T = A^{-1} \end{array} \right\} \Rightarrow AA^T = I = A^T A$$

Example:

$$V = \mathbb{R}^2$$

$$\vec{x} = \begin{bmatrix} \sin \theta \\ \cos \theta \end{bmatrix}$$

$$\|\vec{x}\| = \sin^2 \theta + \cos^2 \theta = 1$$



$$\vec{y} = \begin{bmatrix} \sin(\theta + \frac{\pi}{2}) \\ \cos(\theta + \frac{\pi}{2}) \end{bmatrix}$$

$$\|\vec{y}\| = 1$$

$$\sin(A+B) = \sin A \cos B + \cos A \sin B$$

$$\cos(A+B) = \cos A \cos B - \sin A \sin B$$

$$\vec{y} = \begin{bmatrix} \sin(\theta + \frac{\pi}{2}) \\ \cos(\theta + \frac{\pi}{2}) \end{bmatrix}$$

$$= \begin{bmatrix} \sin \theta \cos \frac{\pi}{2} + \cos \theta \sin \frac{\pi}{2} \\ \cos \theta \cos \frac{\pi}{2} - \sin \theta \sin \frac{\pi}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta \\ -\sin \theta \end{bmatrix}$$

$$\vec{x}^T \vec{y} = \begin{bmatrix} \sin \theta & \cos \theta \end{bmatrix} \cdot \begin{bmatrix} \cos \theta \\ -\sin \theta \end{bmatrix}$$

$$\langle \vec{x}, \vec{y} \rangle = \vec{x}^T \vec{y} = \sin \theta \cos \theta - \cos \theta \sin \theta = 0$$

Example

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = [\vec{b}_1, \vec{b}_2]$$

$$\langle \vec{b}_1, \vec{b}_2 \rangle = 0$$

$$\vec{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

A is orthogonal, B is orthogonal

$$A\vec{x} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$B\vec{x} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} \frac{-1}{\sqrt{2}} \\ \frac{7}{\sqrt{2}} \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$\longrightarrow \text{Length} = \sqrt{\vec{x}^T \vec{x}} = 5$$

$$\vec{y} = B\vec{x} = \begin{bmatrix} \frac{-1}{\sqrt{2}} \\ \frac{7}{\sqrt{2}} \end{bmatrix}$$

$$\longrightarrow \text{Length} = \sqrt{\vec{y}^T \vec{y}}$$

$$= \sqrt{\frac{1}{2} + \frac{49}{2}} = \sqrt{25} = 5$$

Orthogonal matrix multiply by a matrix & vector preserves the length!!

$A \in \mathbb{R}^{n \times n}$ is an orthogonal matrix.

$$\forall \vec{x} \in \mathbb{R}^n : \vec{y} = A \vec{x}$$

$$\|\vec{y}\| = \sqrt{\vec{y}^T \vec{y}}$$

$$= \sqrt{(A\vec{x})^T (A\vec{x})}$$

$$= \sqrt{(\vec{x}^T A^T) (A \vec{x})}$$

$$= \sqrt{\vec{x}^T (A^T A) \vec{x}}$$

$$= \sqrt{\vec{x}^T \underset{\downarrow}{I} \vec{x}} = \|\vec{x}\|$$

Orthonormal basis

If $B = \{\vec{b}_1, \vec{b}_2, \vec{b}_3\}$ is a basis for $V = \mathbb{R}^n$ then B is an orthonormal basis if.

B is an orthogonal matrix

$$\begin{cases} \langle \vec{b}_i, \vec{b}_j \rangle = 0 & i \neq j \\ B^T = B^{-1} & \rightarrow = 1 \quad i = j \end{cases}$$

▷ This limit, if it exists, is called the derivative of f at a and is denoted by $f'(a)$, $f''(a)$, $\frac{d(f(a))}{dx}$

Lecture 16 - Saturday Class (Missed)

Lecture 20 (A)

Problem: optimization (Minimize or Maximize)

Oracle access $\xrightarrow{f(x), f'(x), f''(x)}$ Some Subroutine exists (we don't go in details)

Goal: Find a $x \in \Omega$ optimising $f(x)$

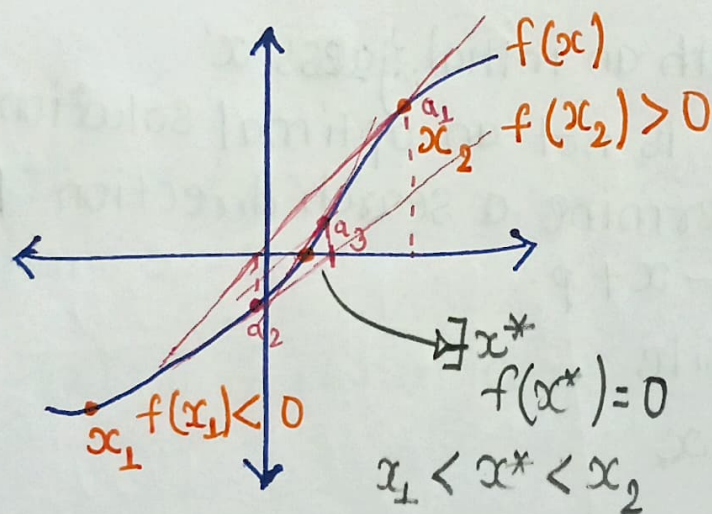
Algorithm

1. Start with an initial guess x
2. while x is not an optimal solution do
3. Determine a search direction p
4. $x \leftarrow x + p$
5. end while
6. Return x

Ex. $f(x) = x^2 - 2$

$f(x) = 0$

- Repeatedly check for local optimality
- Check if $f'(x) = 0$ and if $f''(x) \neq 0$
- calls for finding zeroes of $f'(x)$
- Search direction p (depends on optimality check)
- ▷ Global optimality is hard to find
- ▷ There exist efficient solution for linear and semi-definite case



Binary search between (x_1, x_2)

Newton's method \rightarrow Binary search

\triangleright Given oracle for f and f'

Goal: compute a x^* ~~saty~~ satisfying $f(x^*) = 0$

Algorithm:

1. Start with an initial guess ' x '
2. while $f(x) \neq 0$ and $f'(x) \neq 0$ do
3.
$$p \leftarrow \frac{f(x)}{f'(x)} ; x \leftarrow x + p; \text{ end while}$$

$\textcircled{3a}$

$\textcircled{3b}$

$\textcircled{3c}$

4. Return x

$$f(x) \neq 0$$

$$\frac{x_2 - x_1}{2^k} < \epsilon$$

$$|f(x)| > \epsilon$$

$$\Rightarrow 2^k > \frac{x_2 - x_1}{\epsilon}$$

$$\Rightarrow k > \log_2 \left(\frac{x_2 - x_1}{\epsilon} \right)$$

$$f'(x_0) = \lim_{x_1 \rightarrow x_0} \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

might possible
if I written it
wrong

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

Newton method Analysis

⚠ Note:
(study by yourself)

x_0 (initial guess)

x_k (guess after k iteration)

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

$$e_k = x_k - x^*$$

If the initial difference,

$$e_1 \leq 1$$

.

$$e_k \leq \frac{1}{2^{2^k}}$$

Lecture 20(B)

Determinant

Geometric Interpretation

Laplace Expansion

Determinant and orthogonal matrix

For $A \in \mathbb{R}^2$

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$$A^{-1} = \frac{1}{\underbrace{a_{11}a_{22} - a_{12}a_{21}}_{\neq 0}} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}$$

Determinant of A

$$\Delta(A) \rightarrow \det(A) \text{ or } |A|$$

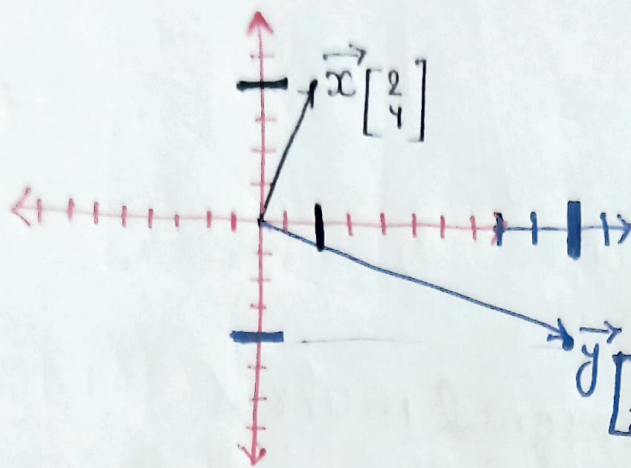
Ex.

$$A = \begin{bmatrix} 1 & 2 \\ -3 & -8 \end{bmatrix}$$

$$\rightarrow A^{-1} = \frac{1}{-11} \begin{bmatrix} -3 & -2 \\ -4 & 1 \end{bmatrix}$$

$$\det(A) = -3 - 8 = -11$$

$$\vec{x} \in \mathbb{R}^2, \vec{x} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$



$$\vec{y} = A\vec{x}$$

$$\begin{bmatrix} 1 & 2 \\ 4 & -3 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$= 2 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + 4 \begin{bmatrix} 2 \\ -3 \end{bmatrix}$$

$$= \begin{bmatrix} 2+8 \\ 8-12 \end{bmatrix}$$

$$= \begin{bmatrix} 10 \\ -4 \end{bmatrix}$$

length of \vec{x}

$$\|\vec{x}\|_2 = \sqrt{2^2 + 4^2}$$

length of \vec{y} $= \sqrt{20}$

$$\|\vec{y}\|_2 = \sqrt{10^2 + (-4)^2}$$

$$= \sqrt{116}$$

~~$$\|\vec{x}\|_2 \times \|\vec{y}\|_2 = |\det A|$$~~

Laplace transformation of a determinant

$$A \in \mathbb{R}^{n \times n}$$

$$\det(A) = \sum_{j=1}^n (-1)^{i+j} a_{ij} |A_{ij}| \text{ where}$$

'i' is any specific row of A
and 'j' varies from column 1 to n

a_{ij} = (i,j)th element of A

A_{ij} is a matrix of size $(n-1) \times (n-1)$ obtained by eliminating the 'ith' row and 'jth' column

A_{ij} is called minor of A

Ex.

$$A = \begin{bmatrix} 3 & 4 & 5 \\ 1 & 2 & 7 \\ 1 & 3 & 9 \end{bmatrix}$$

$$\det(A) = \overset{(11)}{3} \begin{vmatrix} 2 & 7 \\ 3 & 9 \end{vmatrix} - \overset{(12)}{4} \begin{vmatrix} 1 & 7 \\ 1 & 9 \end{vmatrix} + \overset{(13)}{5} \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix}$$

$i=1$

$$= 3(18-21) - 4(9-7) + 5(3-2)$$

$$= -9 - 8 + 5$$

$$= \boxed{-12}$$

$$i=2 \quad \det(A) = -1 \times 1 \times \begin{vmatrix} 4 & 5 \\ 3 & 9 \end{vmatrix} + 1 \times 2 \begin{vmatrix} 3 & 5 \\ 1 & 9 \end{vmatrix} - 1 \times 7 \begin{vmatrix} 3 & 4 \\ 1 & 3 \end{vmatrix}$$

$$= -1(36-15) + 2(27-5) - 7(9-4)$$

$$= -21 + 44 - 35$$

$$= -56 + 44$$

$$= -12$$

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$B = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}$$

$$\det(A) = 1$$

$$\det(B) = 1$$

$$\vec{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

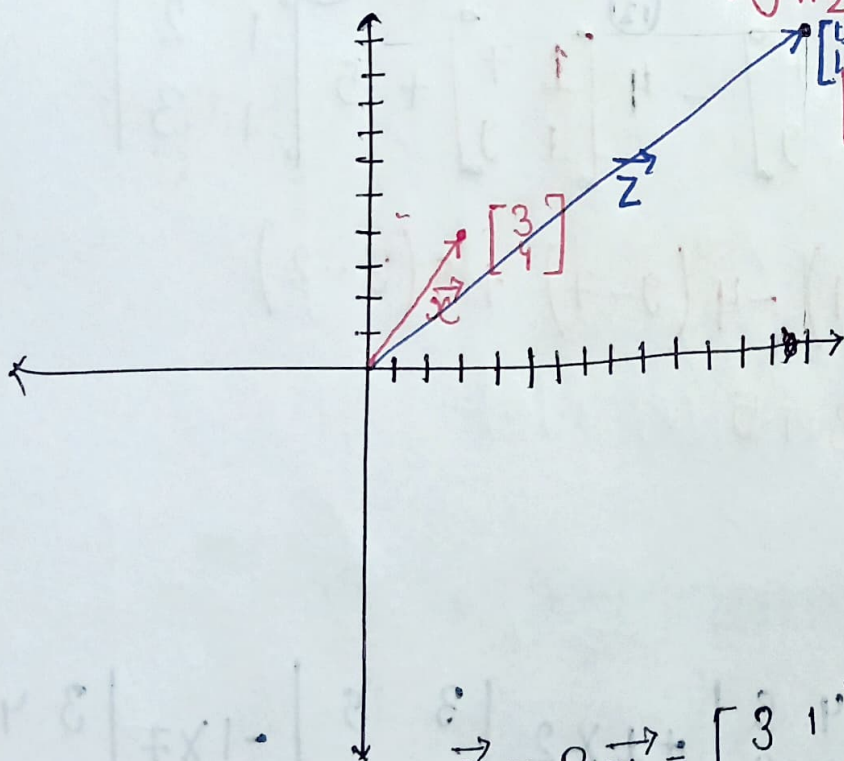
$$\vec{y} = A \vec{x} = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{7}{\sqrt{2}} \end{bmatrix}$$

$$\text{length}(\vec{x}) = \|\vec{x}\|_2 = \sqrt{3^2 + 4^2} = 5$$

$$\|\vec{y}\|_2 = \sqrt{\frac{1+49}{2}} = 5$$

$$\|\vec{z}\|_2 = \sqrt{13^2 + 10^2} = \sqrt{269}$$

16. something

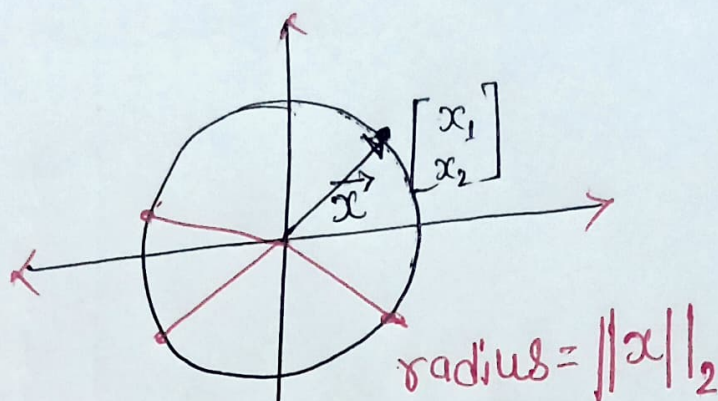


$$\vec{z} = B \vec{x} = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 13 \\ 10 \end{bmatrix}$$

▷ If A is an orthogonal matrix ($A \in \mathbb{R}^{n \times n}$)

$$\det(A) = \pm 1$$

$A\vec{x}$ and \vec{x} have the same length



$A\vec{x}$ always lie on the circumference of the circle if A is orthogonal matrix