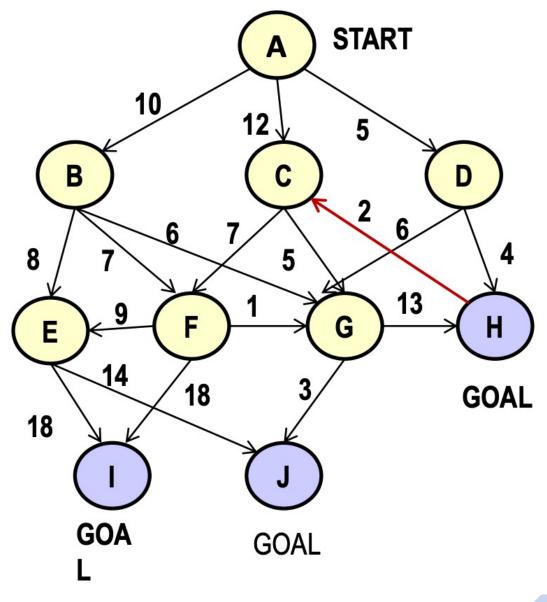
## ARTIFICIAL INTELLIGENCE (AI) STATE SPACE AND SEARCH ALGORITHMS

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SEARCHING STATE SPACE GRAPHS WITH EDGE COSTS

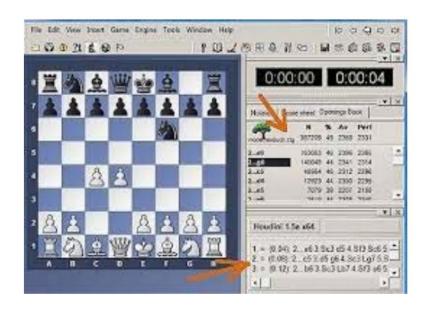


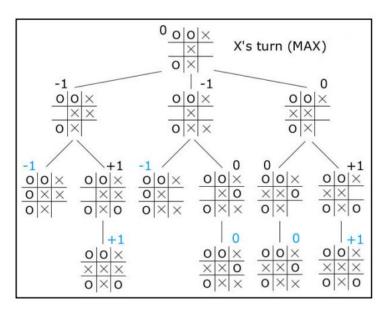
#### **ALGORITHM IDA\***

#### **ITERATIVE DEEPENING A\* (IDA\*)**

- 1. Set Cut-off Bound to f(s)
- Perform DFBB with Cut-off Bound. Backtrack from any node whose f(n) > Cut-off Bound.
- 3. If Solution is Found, at the end of one Iteration, Terminate with Solution
- 4. If Solution is not found in any iteration, then update Cut-off Bound to the lowest f(n) among all nodes from which the algorithm Backtracked.
- 5. Go to Step 2
- 6. PROPERTIES OF DFBB AND IDA\*: Solution Cost, Memory, Node expansions, Heuristic Accuracy, Performance on Trees / Graphs

#### **GAMES**

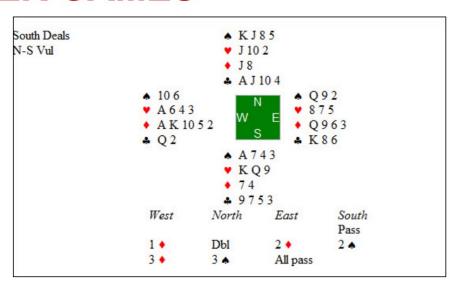






#### **MULTI-PLAYER GAMES**





#### **PROBABILISTIC GAMES**



# W<sub>c</sub> T<sub>t</sub>P<sub>er</sub> h<sub>c</sub>, h<sub>c</sub>, h<sub>c</sub>, r RISER Q<sub>t</sub> RISER RISER

**BLOCK DIAGRAM OF A BOILER SYSTEM** 

### **ROBOT GAMES**



#### PRISONER'S DILEMMA

- Two members of a criminal gang are arrested and imprisoned. Each prisoner is in solitary confinement with no means of communicating with the other.
- The prosecutors lack sufficient evidence to convict the pair on the principal charge, but they have enough to convict both on a lesser charge.
- Simultaneously, the prosecutors offer each prisoner a bargain

#### PRISONER'S DILEMMA

		PRISONER B	
		Prisoner B stays silent (cooperates)	Prisoner B betrays (defects)
PRISONER A	Prisoner A stays silent (cooperates)	Each serves 1 year	Prisoner A: 3 yrs Prisoner B: goes free
	Prisoner A betrays (defects)	Prisoner A: goes free Prisoner B: 3 yrs	Each serves 2 yrs

#### **GAMETREE**

- A tree with three types of nodes, namely Terminal nodes, Min nodes and Max nodes.
- Terminal nodes have no children. The tree has alternating levels of Max and Min nodes, representing the turns of Player-I and Player-2 in making moves
- All nodes represent some state of the game
- Terminal nodes are labeled with the payoff for Player-I. It could be Boolean (such as WON or LOST). In large games, where looking ahead up to the WON / LOST states is not feasible, the payoff at a terminal node may represent a heuristic cost representing the quality of the state of the game from Player-I's perspective
- The payoff at a Min node is the minimum among the payoffs of its successors
- The payoff at a Max node is the maximum among the payoffs of its successors
- If Player-I aims to maximize its payoff, then it represents Max nodes, else it represents Min nodes

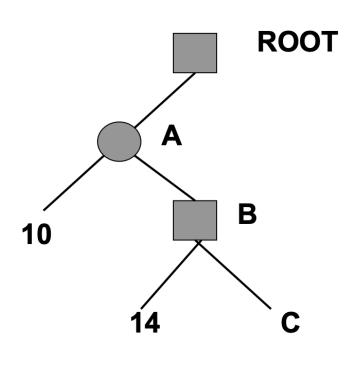
# **SAMPLE GAME TREE** Max node: Player-1 Min node: Player-2

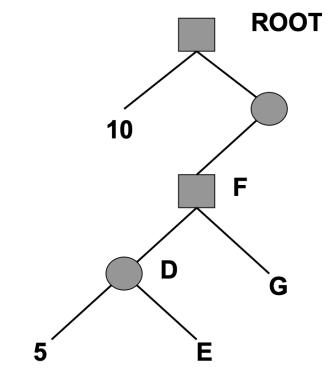
# **GAME TREE: MINMAX VALUE** Max node: Player-1 Min node: Player-2 6 5

#### **Shallow and Deep Pruning**

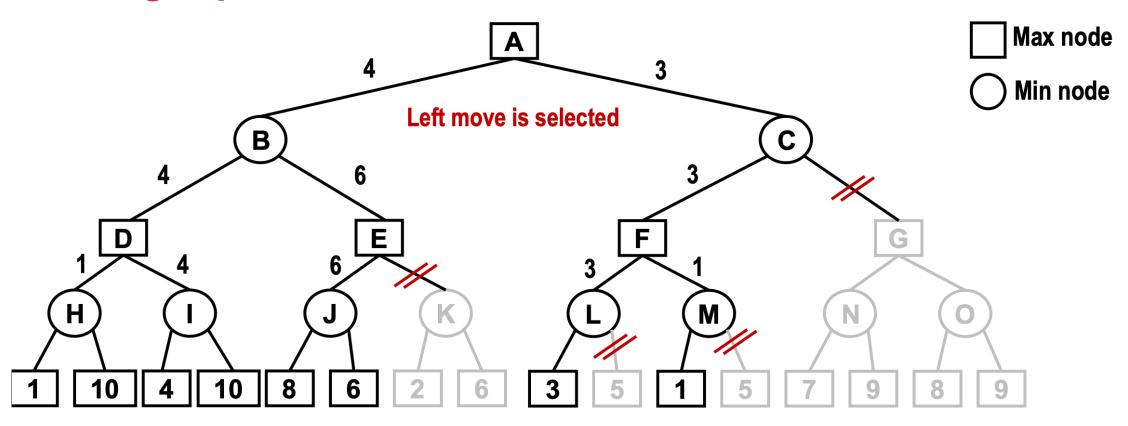
Max node

Min node





#### **Pruning explained**



#### **ALPHA-BETA PRUNING IN GAME TREE SEARCH**

- Alpha Bound of  $J(\alpha)$ :
  - The max current payoff of all MAX ancestors of J (Lower Bound)
  - Exploration of a min node, J, is stopped when its payoff β (Upper Bound) equals or falls below alpha.
- Beta Bound of J (β):
  - The min current payoff of all MIN ancestors of J (Upper Bound)
  - Exploration of a max node, J, is stopped when its payoff  $\alpha$  (Lower Bound) equals or exceeds beta
- In a max node, we update alpha or Lower Bound
- In a min node, we update beta or Upper Bound
- In both min and max nodes, we return when  $\alpha \ge \beta$

#### ALPHA-BETA PRUNING PROCEDURE $V(J;\alpha,\beta)$

- 1. If J is a terminal, return V(J) = h(J).
- 2. If J is a max node:

For each successor  $J_k$  of J in succession:

```
Set \alpha = \max \{ \alpha, V(J_k; \alpha, \beta) \}
```

If  $\alpha \geq \beta$  then return  $\beta$ , else continue

Return  $\alpha$ 

3. If J is a min node:

For each successor  $J_k$  of J in succession:

Set 
$$\beta = \min \{ \beta, V(J_k; \alpha, \beta) \}$$

If  $\alpha \geq \beta$  then return  $\alpha$ , else continue

**Return** β

The initial call is with  $V(Root; -\infty, +\infty)$