## NPTEL » Artificial Intelligence Search Methods For Problem Solving

Unit 6 - Week 4

Course outline

Week 1

Week 2

Week 3

Week 4

How to access the portal

Pre-requisite Assignment

TSP: Greedy methods

Optimization I: Simulated

Week 4- Feedback : Artificial

Intelligence Search Methods

Tabu search

Annealing

Week 10

Week 11

Week 12

Week 13

Week 14

Week 15

Live Sessions

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Assignment 4 The due date for submitting this assignment has passed. As per our records you have not submitted this assignment.

the ordering A, B, .., Z.

none of the above

Accepted Answers:

Tabu Search

Random Walk

Accepted Answers:

Tabu Search

Random Walk

Accepted Answers: None of the above

Iterated Hill Climbing

 Simulated Annealing None of the above

No, the answer is incorrect.

 Hill Climbing, Random Walk Random Walk, Hill Climbing

No, the answer is incorrect.

Hill Climbing, Random Walk

No, the answer is incorrect.

Accepted Answers:

None of the above

Accepted Answers:

No, the answer is incorrect.

Accepted Answers:

Simulated Annealing, Tabu Search

Tabu Search, Simulated Annealing

6) Which of the following is/are true for Tabu Search?

It randomly marks some moves as taboo

It never moves to a state worse than the current state

7) In Iterated Hill Climbing which of the following are true?

The algorithm always finds the global optimum

Iterated Hill Climbing

Simulated Annealing

No, the answer is incorrect.

Score: 0

Score: 0

Score: 0

Score: 0

Score: 0

Score: 0

L,B,E ☐ M,C,L E,L,Q □ T,Q,M

Score: 0

Score: 0

Score: 0

Score: 0

Your

edge

current state

M,C,L T,Q,M

true?

none of the above

Accepted Answers:

No, the answer is incorrect.

No, the answer is incorrect.

Annealing behaves like

Random Walk, Hill Climbing

Hill Climbing, Random Walk

Random Walk, Tabu Search

No, the answer is incorrect.

Random Walk, Hill Climbing

(H, G, F, D, C, E, B, A) (H, G, B, C, D, E, F, A) □ (H, G, F, A, B, C, D, E) (H, B, F, E, G, C, D, A)

No, the answer is incorrect.

No, the answer is incorrect.

(Type: String) D,E,C,A,B,F,143

No, the answer is incorrect.

(Type: String) A,B,D,E,C,F,245

No, the answer is incorrect.

(Type: String) F,D,E,A,B,C,194

(Type: String) F, D, E, A, B, C, 194

Accepted Answers:

(Type: String) A, B, D, E, C, F, 245

Accepted Answers:

(Type: String) D, E, C, A, B, F, 143

Accepted Answers:

Score: 0

list of

list of

Score: 0

Yes ○ No

Score: 0

Score: 0

No

Cannot say

Accepted Answers:

No, the answer is incorrect.

No, the answer is incorrect.

Accepted Answers:

16) Which of the following is/are true of Simulated Annealing (SA)?

SA generates one neighbour randomly and always moves to it if it is better SA generates one neighbour randomly and may move to it even if it is worse

SA generates one neighbour randomly and may move to it even if it is worse

heuristic value is given to you in the following table.

Score: 0

Accepted Answers: (H, G, B, C, D, E, F, A) (H, G, F, A, B, C, D, E)

Accepted Answers:

exchange?

Iterated Hill Climbing, Hill Climbing

Hill Climbing, Iterated Hill Climbing

Accepted Answers:

Tabu Search

No, the answer is incorrect.

the tendency to explore newer areas in the search space

3) Which of the following is/are a deterministic search technique?

4) Which of the following search algorithm(s) is/are complete in a finite search space?

is an extreme of exploitation and

It can move forward even if the best neighbour is worse than the current node

Having moved off a local optimum it avoids returning to it immediately

It can move forward even if the best neighbour is worse than the current node

Having moved off a local optimum it avoids returning to it immediately

■ The algorithm makes deterministic moves from the current state

The algorithm makes stochastic moves from the same start state

The algorithm uses different start states chosen randomly

The algorithm makes deterministic moves from the current state

Which of the runs succeed in finding a path to the goal node.

Iterated Hill Climbing randomly picks any one of the k neighbours and moves to it. Iterated Hill Climbing always picks the best one of the k neighbours and moves to it

 Random Walk randomly picks any one of the k neighbours and moves to it Random Walk always picks the best one of the k neighbours and moves to it

Random Walk randomly picks any one of the k neighbours and moves to it

Iterated Hill Climbing picks the best one of the k neighbours and moves to it only if it is better than the current state

Random Walk randomly picks any one of the k neighbours and moves to it only if it is better than the current state

Iterated Hill Climbing picks the best one of the k neighbours and moves to it only if it is better than the

Fill in the blanks. For higher values of temperature T, Simulated Annealing behaves like.

The algorithm uses different start states chosen randomly

the willingness to go against the heuristic value

Please DO NOT ENTER ANY BLANKS. This assessment is evaluated by a program that does exact string matching. Any blank in the answer will result in even a correct answer being evaluated as wrong.

Topics: Travelling Salesman Problem, Tabu Search, Simulated Annealing

About the Course

The following policy applies throughout. If there is a tie between two or more nodes for being picked by the algorithm, then the tie is broken as followed – the node that comes earlier in the dictionary ordering is selected. For example, if there is a tie between M, F and R, then F is selected first because occurs earlier in

This "no blanks" policy will hold THROUGHOUT this course.

1) Exploitation in the context of heuristic search refers to taking unfair advantage of the CLOSED list the willingness to go against the heuristic value choosing the next node as indicated by the heuristic function moving along the steepest gradient on the surface

none of the above

No, the answer is incorrect. Score: 0 Accepted Answers: choosing the next node as indicated by the heuristic function moving along the steepest gradient on the surface

is an extreme of exploration.

8) Let Figure 3.2 (please use the same figure from Week 3 assignment) represent a solution space search problem in which each node is a candidate 1 point

used as the heuristic function. Each option below represents a run of the Iterated Hill Climbing (IHC) algorithm starting from the specified 3 start nodes.

9) Consider a state S in the search space for an instance of a problem P. Let moveGen(S) generate k neighbouring states. Which of the following is/are 1 point

11) Let the current state S for an instance of TSP be (H,G,F,E,D,C,B,A). Which of the following is/are the neighbour(s) of S, if moveGen(S) implements 2- 1 point

12) What is the tour generated by Greedy Heuristic for a TSP with six cities A, B, C, D, E and F? The edge costs are given in the adjacency matrix in Table 4.1.

D

30

21

12

0

5

8

13) Hand simulate the algorithm and report the tour generated by the Nearest Neighbour Algorithm starting at city A. Your answer must be a comma separated

14) Hand simulate the algorithm and report the tour generated by the Nearest Neighbour Algorithm starting at city F. Your answer must be a comma separated

Е

40

51

59

5

0

69

F

50

41

100

8

69

0

answer should start with the edge DE, and is a comma-separated list of cities, followed by the cost, for example, D,E,F,A,B,C,2000

С

20

31

0

12

59

100

TABLE 4.1

Α

0

10

20

30

40

50

cities starting with A, followed by the cost of the tour found. For example A,B,C,D,E,F,2000

cities starting with F, followed by the cost of the tour found. For example F,E,D,C,B,A,2000

15) Does the TSP problem in the above table appear to be Euclidean and satisfying the Triangle Inequality?

SA generates all neighbours and picks the best one. Then it decides to move to it with a certain probability

The following SAT formula is defined on the variables a, b, c, d, and e. A candidate solution is a corresponding vector represented by a 5-bit string (for

example 11010) and the Memory Vector M is represented by a vector of five digits (for example M = 20010 depicts the tabu tenure of the variables a, b, c, d,

 $((b \lor \neg c) \land (c \lor \neg d) \land (\neg b \lor c) \land (\neg a \lor \neg e) \land (\neg a \lor d) \land (\neg c \lor \neg d))$ 

The moveGen or neighbourhood function flips one bit. Tabu Search explores the SAT problem starting at the node (01101.20010). The tabu tenure is 2 and the heuristic function is the number of clauses satisfied. If two successors have the same heuristic value then the one that flips the bit on the left is chosen. The

С

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1

1

19) Which of the following bits are allowed to be flipped by Tabu search to generate successors of the start node (01101.20010)?

20) What is the FOURTH node inspected by Tabu search (remember the start node (01101.20010) is the first node)?

а

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1

1

1

1

17) Given the start node 10101, how many nodes, including the start node, does Hill Climbing end up visiting?

18) Given the start node 10101 does Hill Climbing end up in the solution node?

No, the answer is incorrect.

Accepted Answers: (Type: Numeric) 3

Score: 0

Yes ○ No

Score: 0

a 

 $\Box$  d е

Score: 0

Score: 0

b

Cannot say

Accepted Answers:

No, the answer is incorrect.

No, the answer is incorrect.

No, the answer is incorrect.

(Type: String) (00000.01200) (Type: String) 00000.01200

Accepted Answers:

Accepted Answers:

d

0

0

1

1

0

0

1

1

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1

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3

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4

5

4

1 point

1 point

1 point

1 point

SA generates only one neighbour randomly and then decides to move to it with a certain probability

SA generates only one neighbour randomly and then decides to move to it with a certain probability

and e respectively). We represent a node in the search tree by (candidate.M), for example (11010.20010).

Α

В

C

D

Е

F

В

10

0

31

21

51

41

solution. The edges represent the allowed perturbations. Node X is the solution or goal node, and there is no start node. The Manhattan distance on the grid

Exploration in the context of heuristic search refers to moving along the steepest gradient on the surface the tendency to explore newer areas in the search space

Week 5 Week 6 Week 7 Week 8 the willingness to go against the heuristic value the ability to head straight for the goal node Week 9

for problem Solving Quiz : Assignment 4

Announcements

Due on 2019-08-28, 23:59 IST.

Ask a Question

Progress

1 point

and for lower values of T, Simulated

1 point

1 point

1 point

1 point

1 point

1 point

Mentor