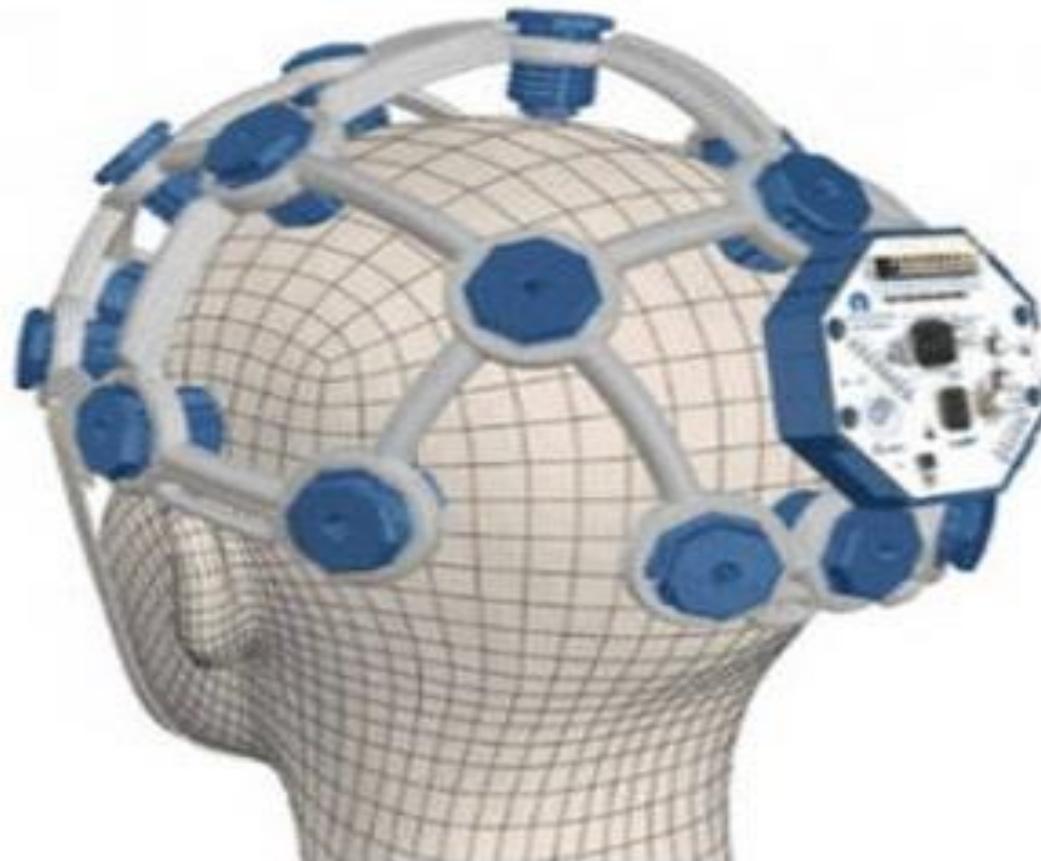


# NEURAL NETWORK



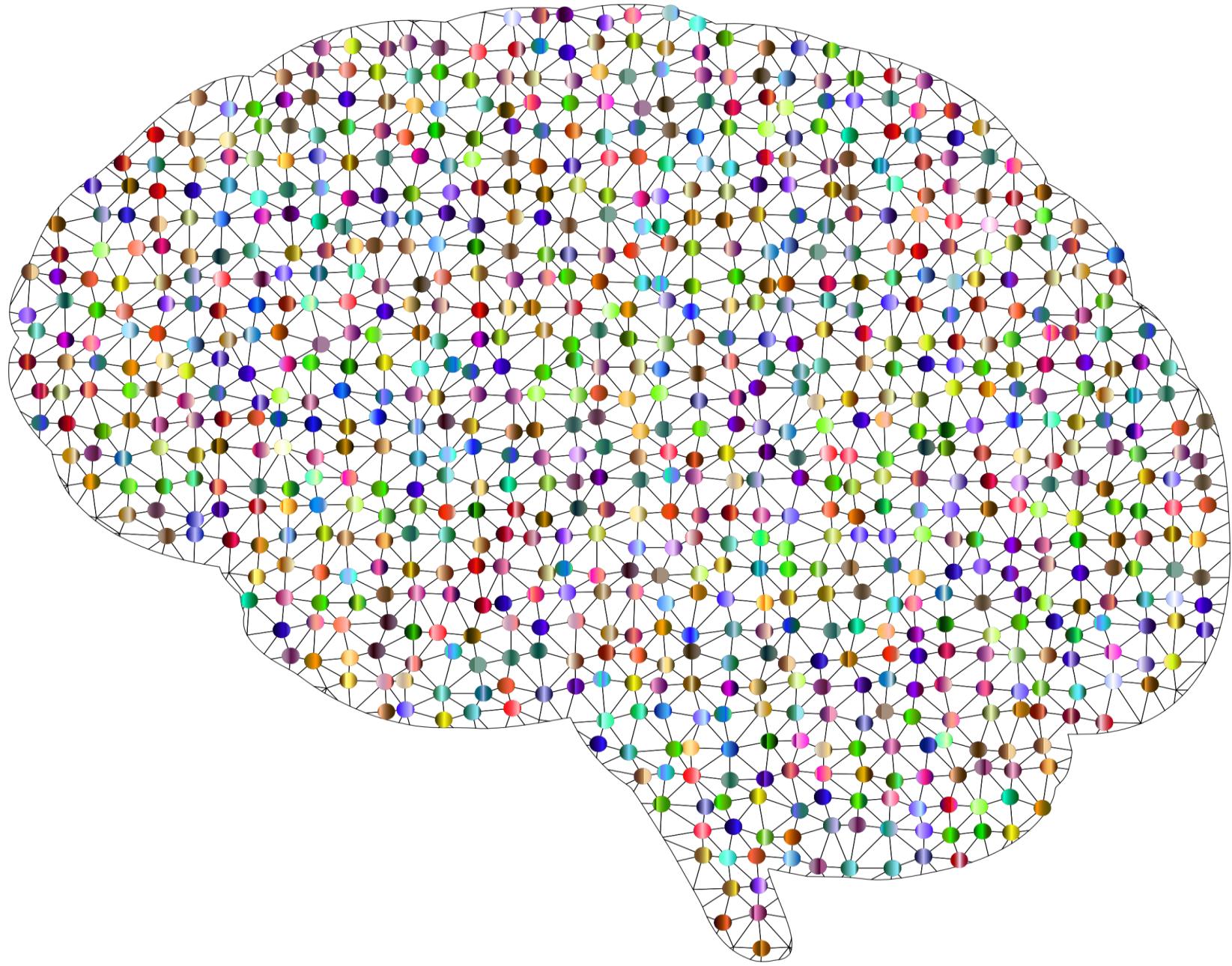
[www.chandanverma.com](http://www.chandanverma.com)

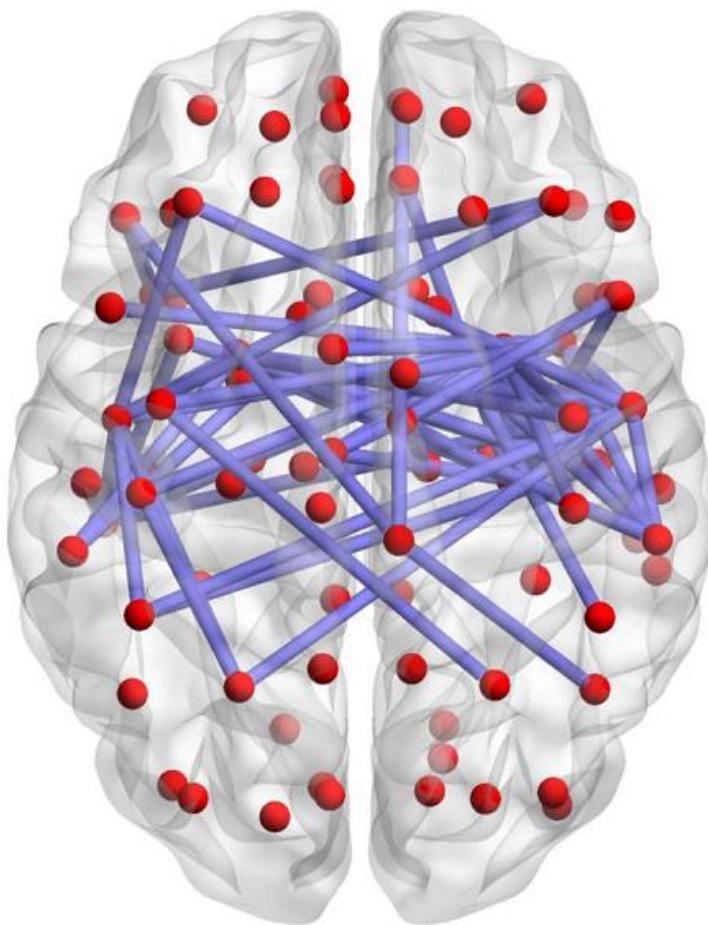
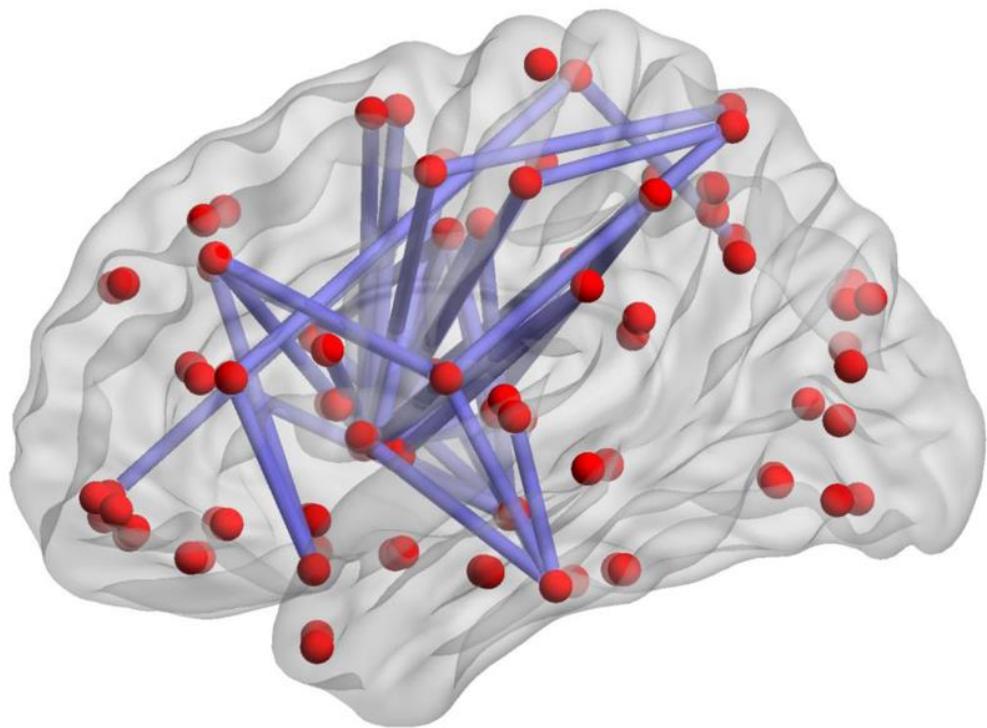
# BRAIN

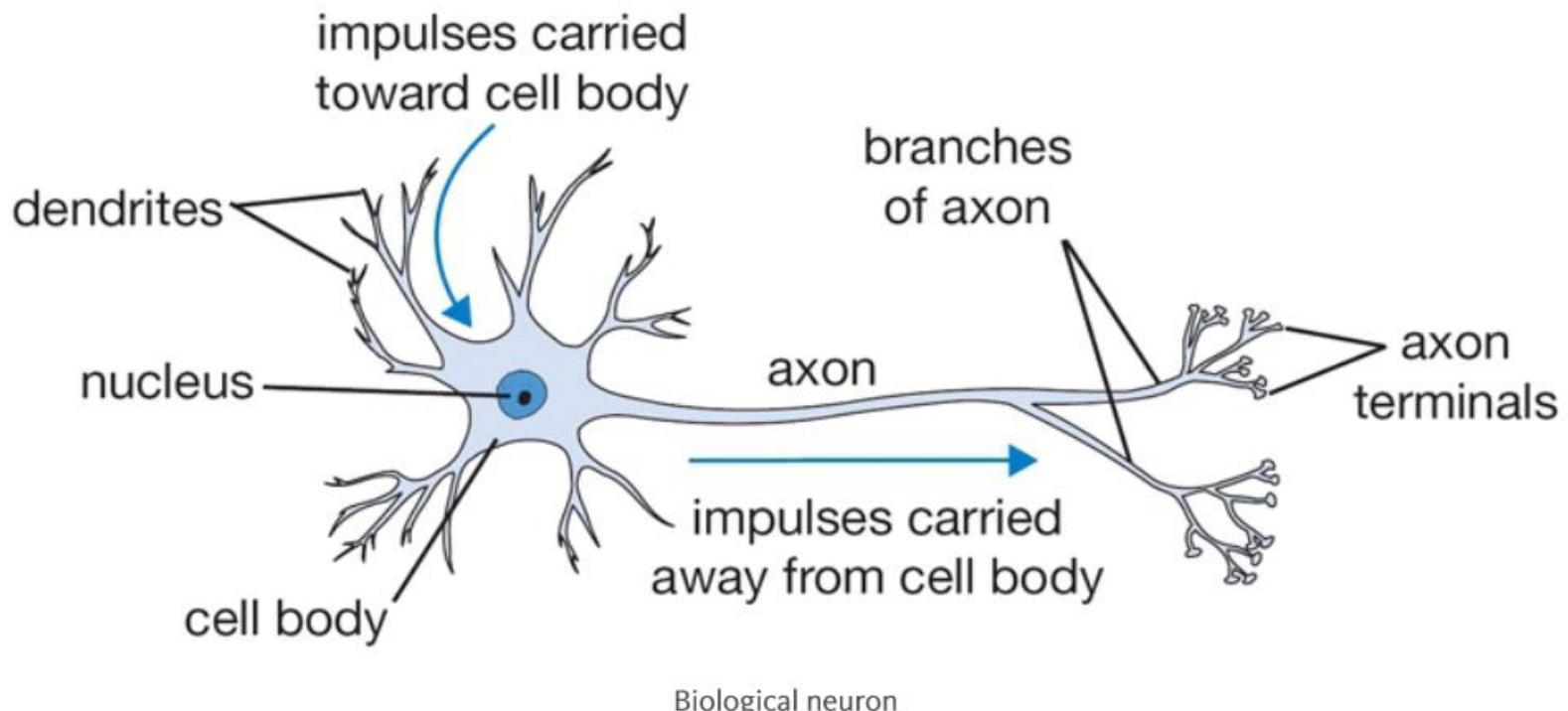
A typical brain contains something like 100 billion minuscule cells called **neurons**.

Each neuron is made up of a **cell body** (the central mass of the cell) with a number of connections coming off it.

The cell body contains the nucleus, the **storehouse of genetic** information, and gives rise to two types of cell processes, axons and dendrites







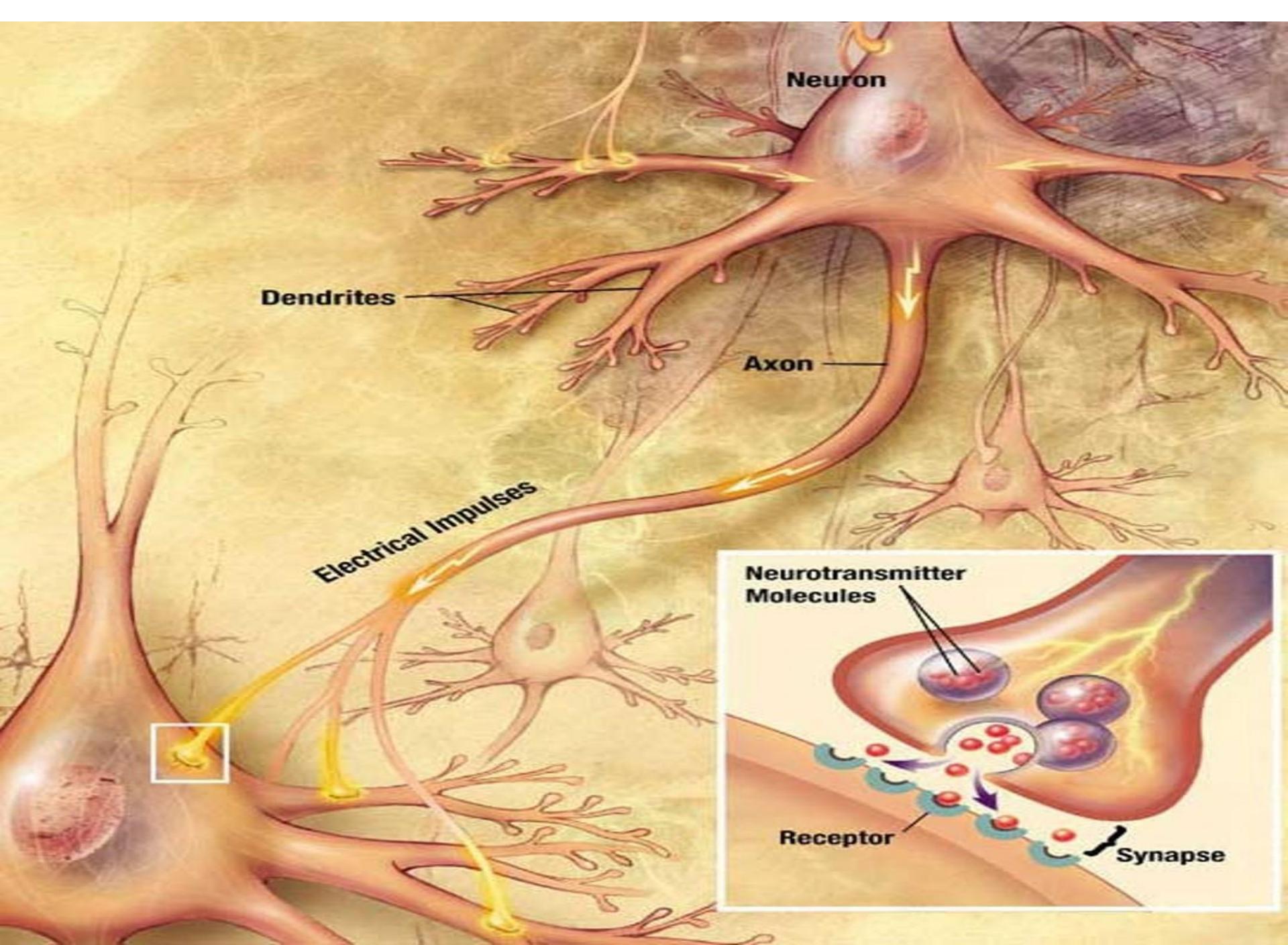
numerous **dendrites** (the cell's inputs—carrying information toward the cell body) and a single **axon** (the cell's output—carrying information away).

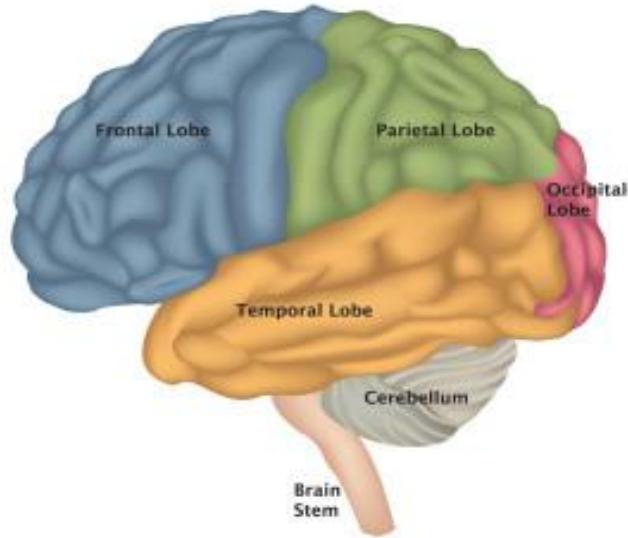
## Synapses

The connections between one neuron and another are called synapses. Information always leaves a neuron via its axon , and is then transmitted across a synapse to the receiving neuron.

## Neuron Firing

Neurons only fire when input is bigger than some threshold. It should, however, be noted that firing doesn't get bigger as the stimulus increases, its an all or nothing arrangement.



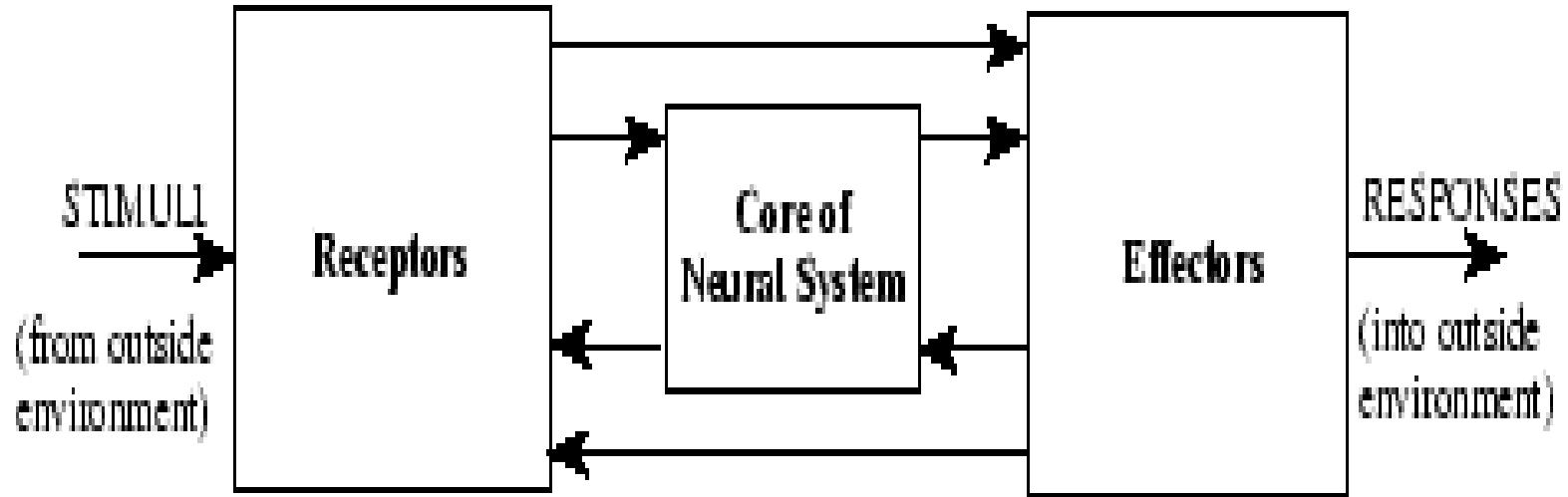


## Brain Structure is Parallel and Distributed

The human brain consists of billions of neurons which are interconnected by synapses. If “enough” synaptic inputs to the neuron fires, then the neuron will also fire. This process is called ***thinking.***

# Number of Neurons

Animal	Number of Neurons
Common Jellyfish	5,600
Ant	250,000
Frog	16,000,000
Cat	760,000,000
Humans	86,000,000,000
African Elephant	257,000,000,000



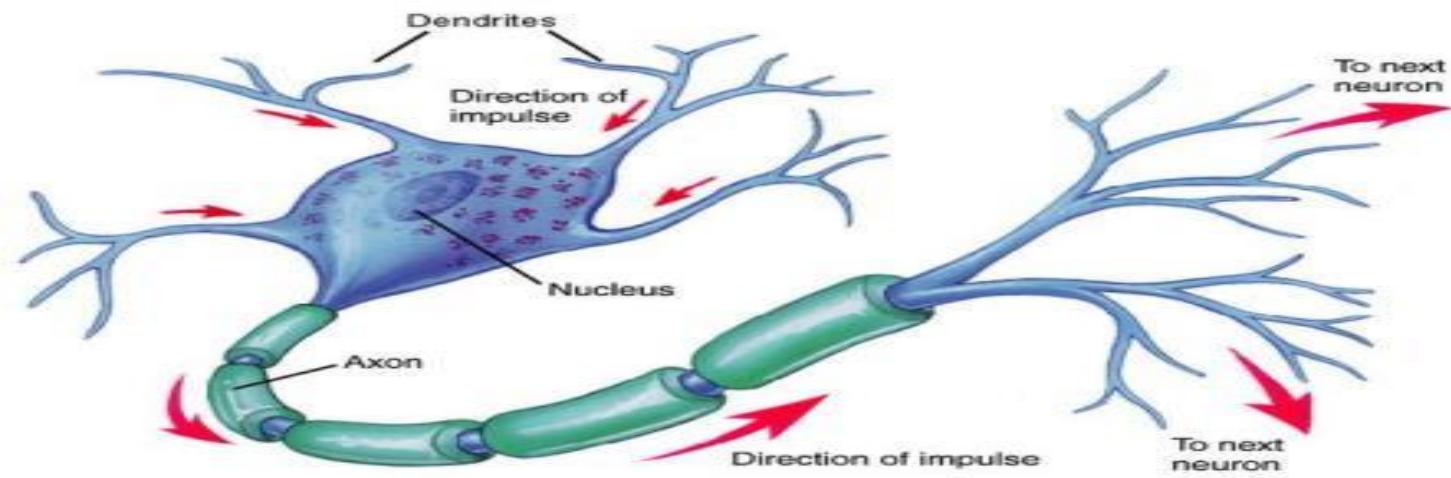
The brain receives the stimulus from the outside world, does the processing on the input, and then generates the output.

The neural system of the human body consists of three stages: **receptors**, **a neural network**, and **effectors**.

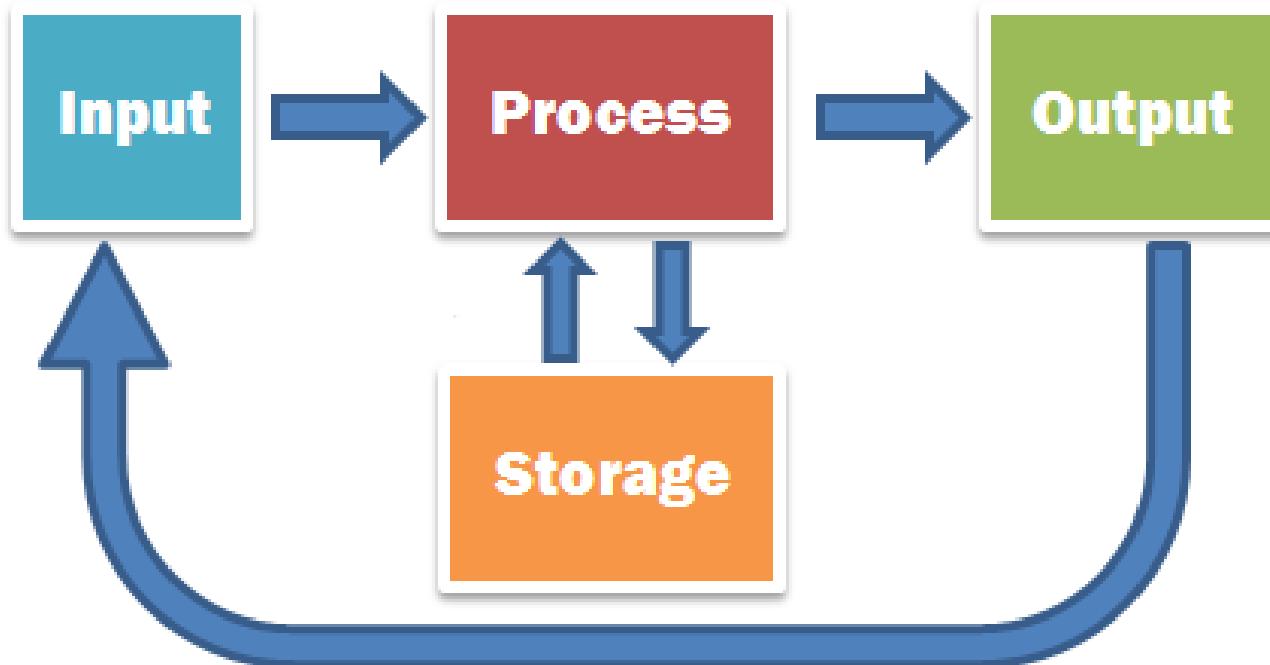
The receptors receive the stimuli either internally or from the external world, then pass the information into the neurons in a form of electrical impulses.

The neural network then processes the inputs then makes proper decision of outputs.

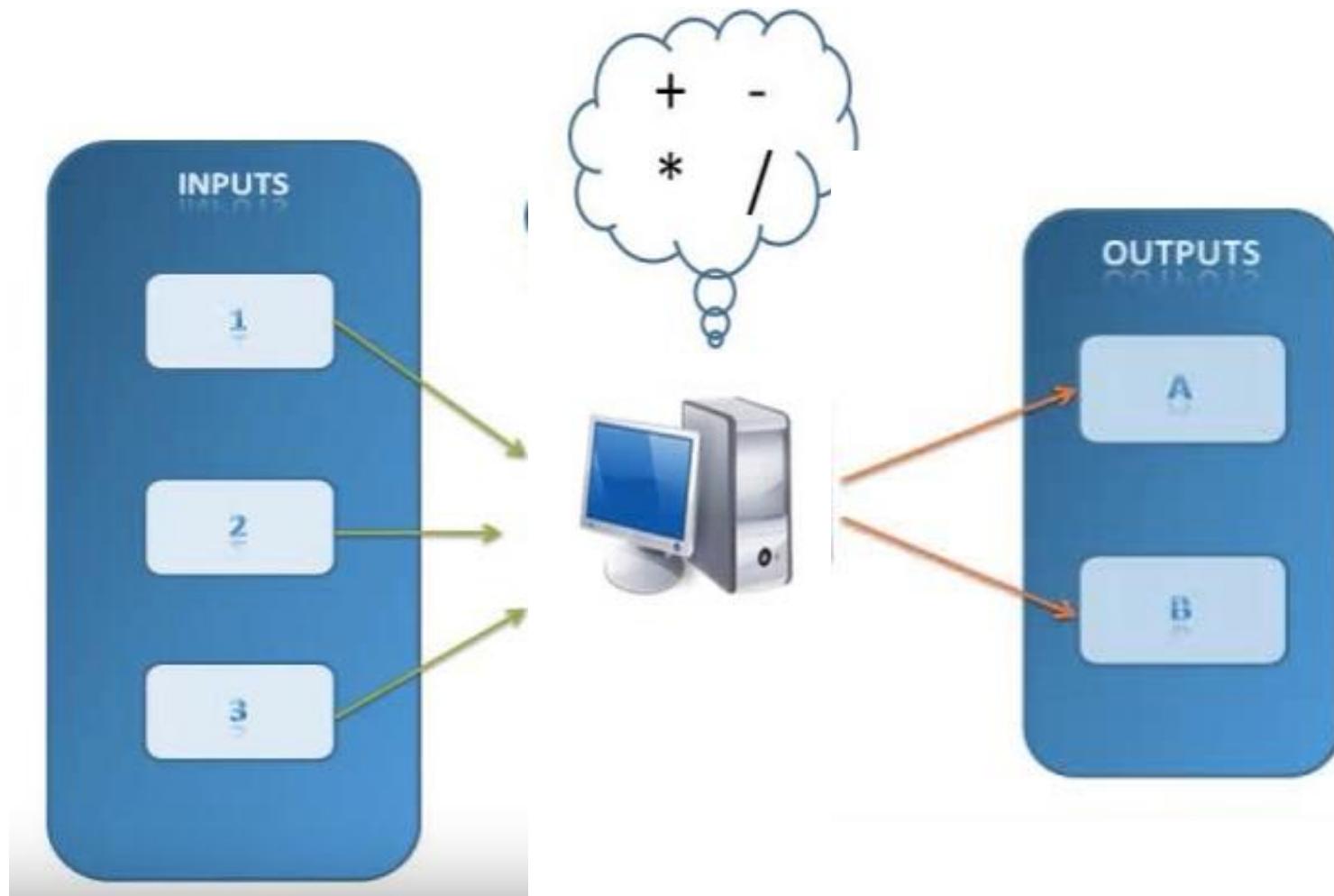
Finally, the effectors translate electrical impulses from the neural network into responses to the outside environment.



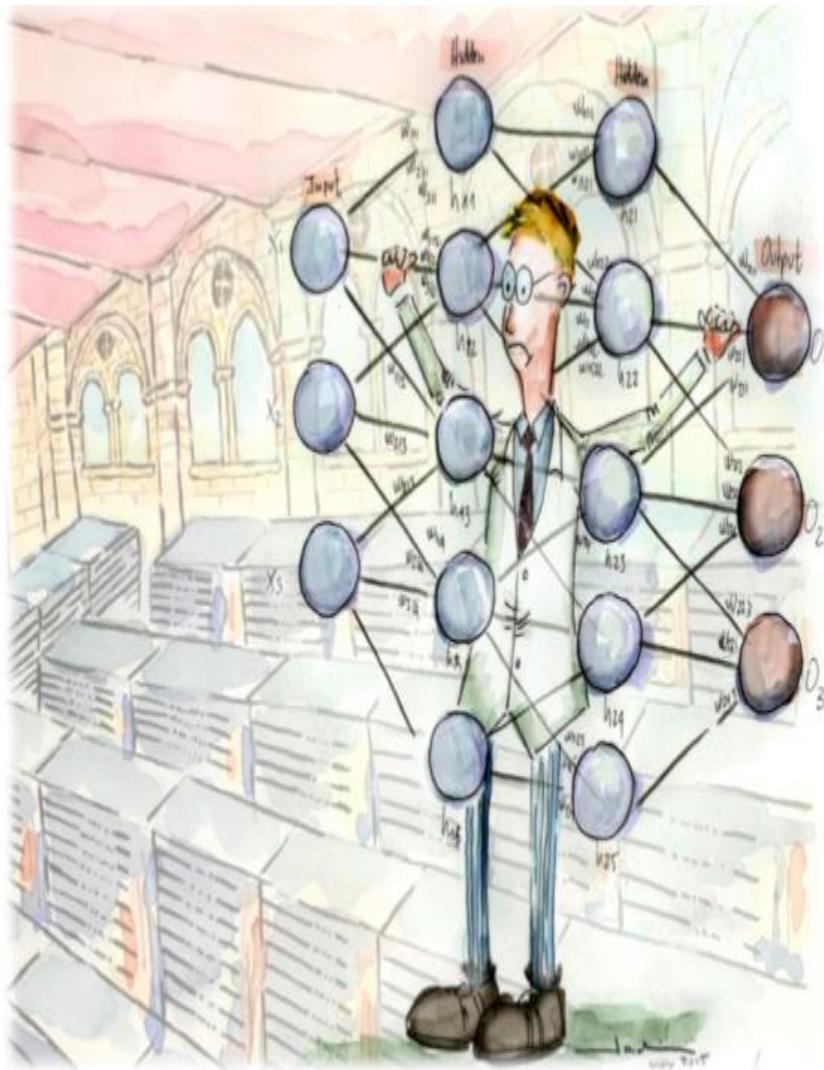
# How Computer Work



**Feedback**

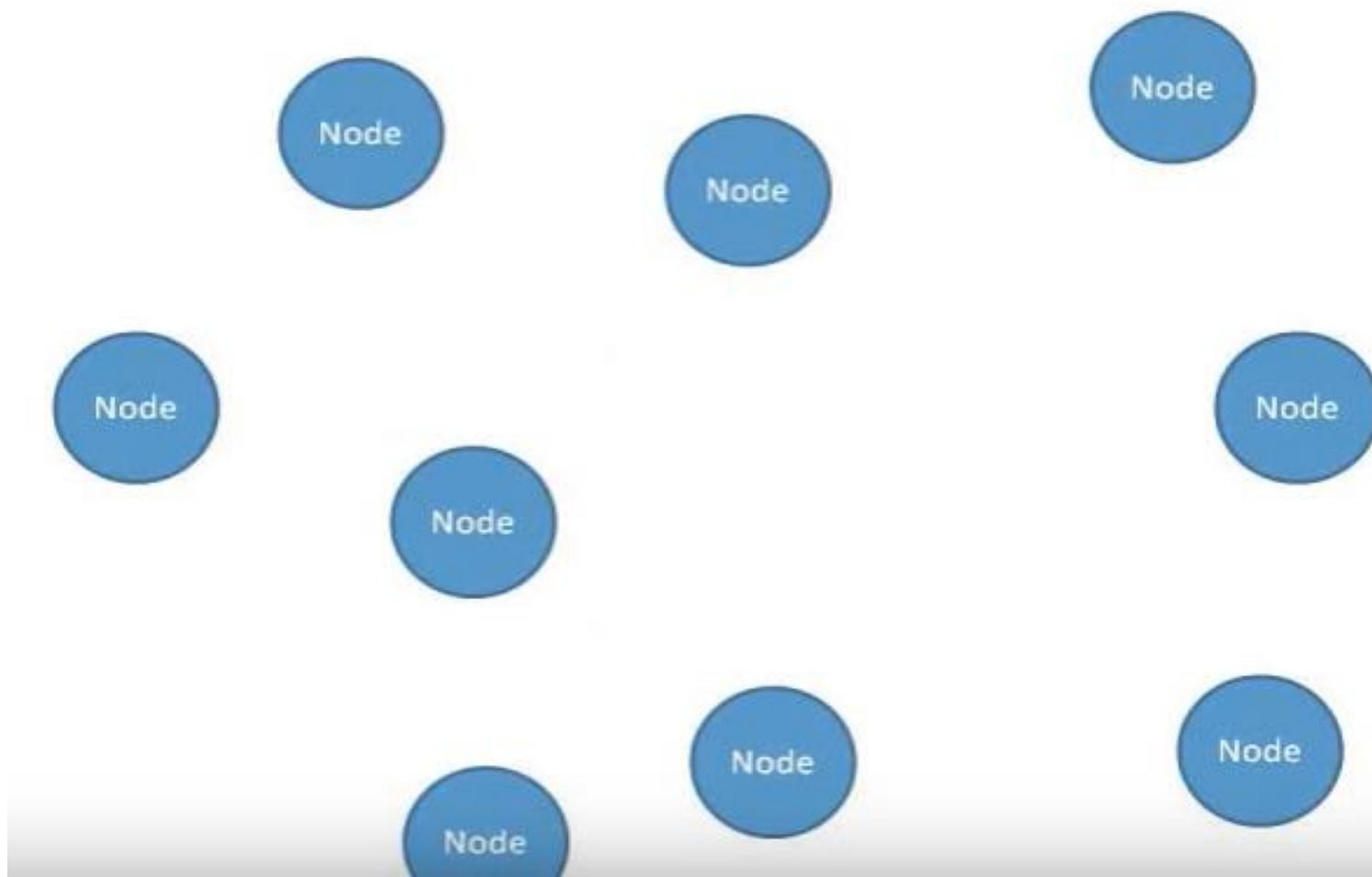


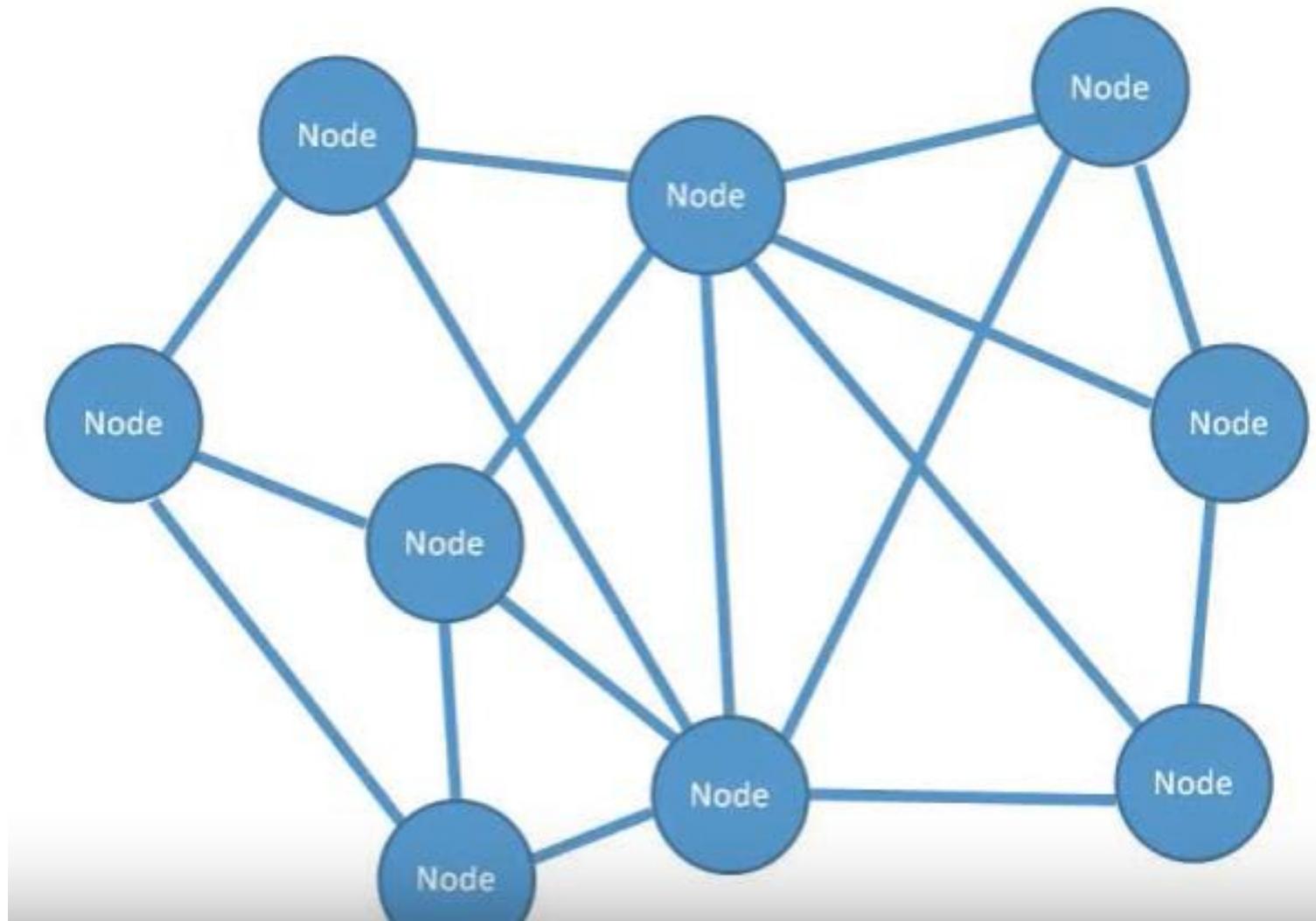
# New type of Computing is required

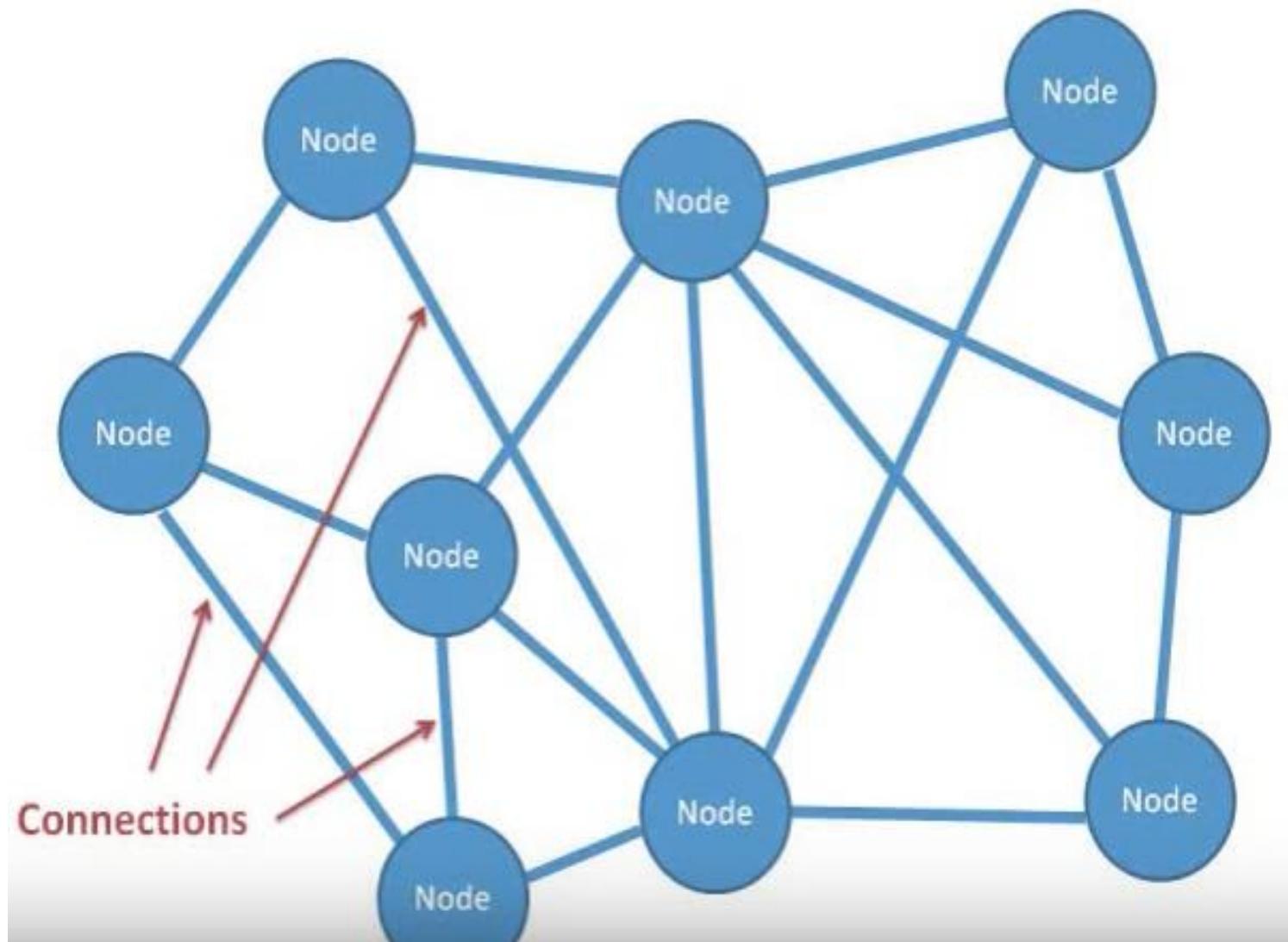


**Giving Computers a greater ability to understand information and to learn, to Reason , and act upon it**

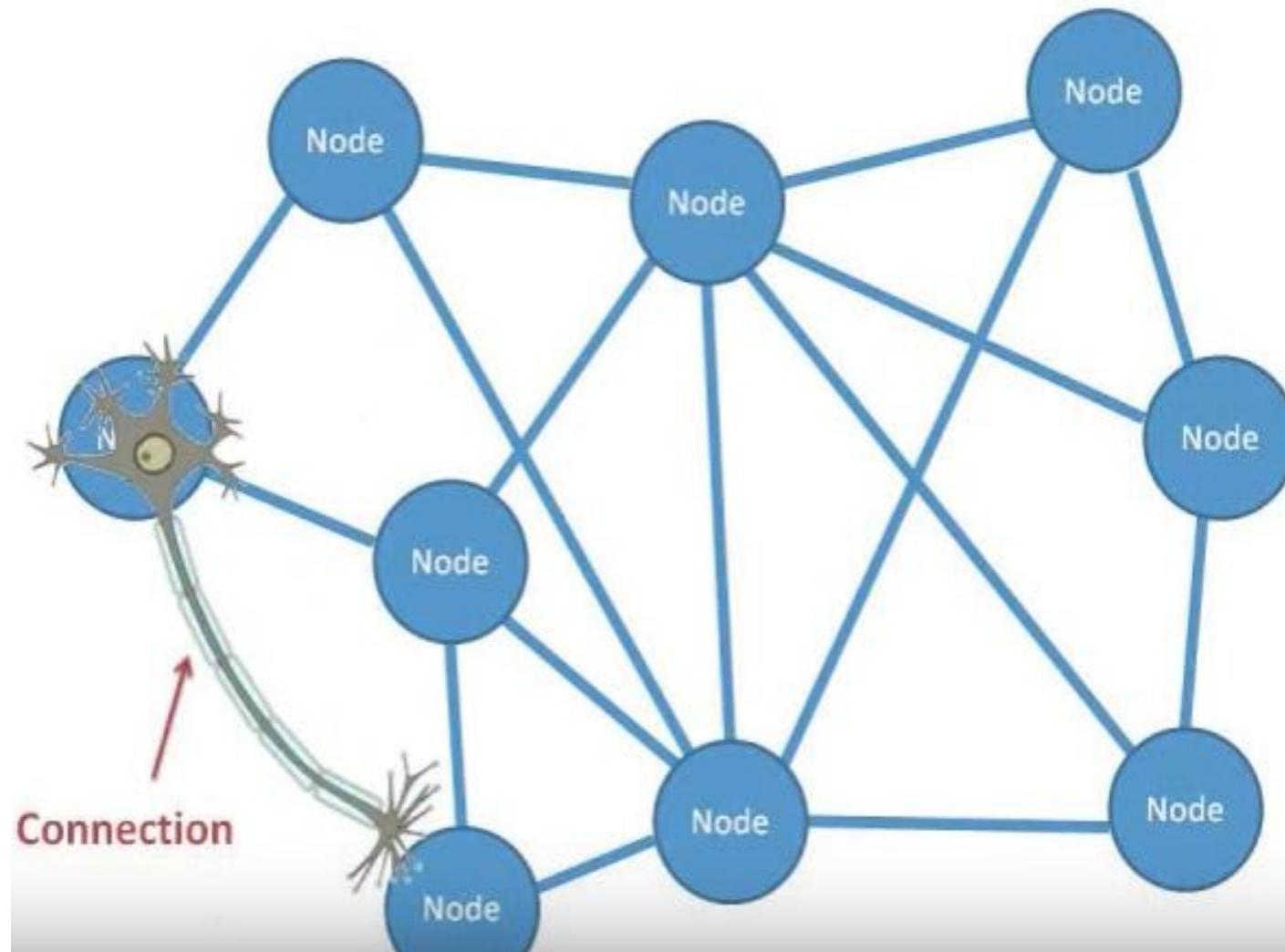
# Neural Network







# Modeling of Computer similar as Brain is.



Neural

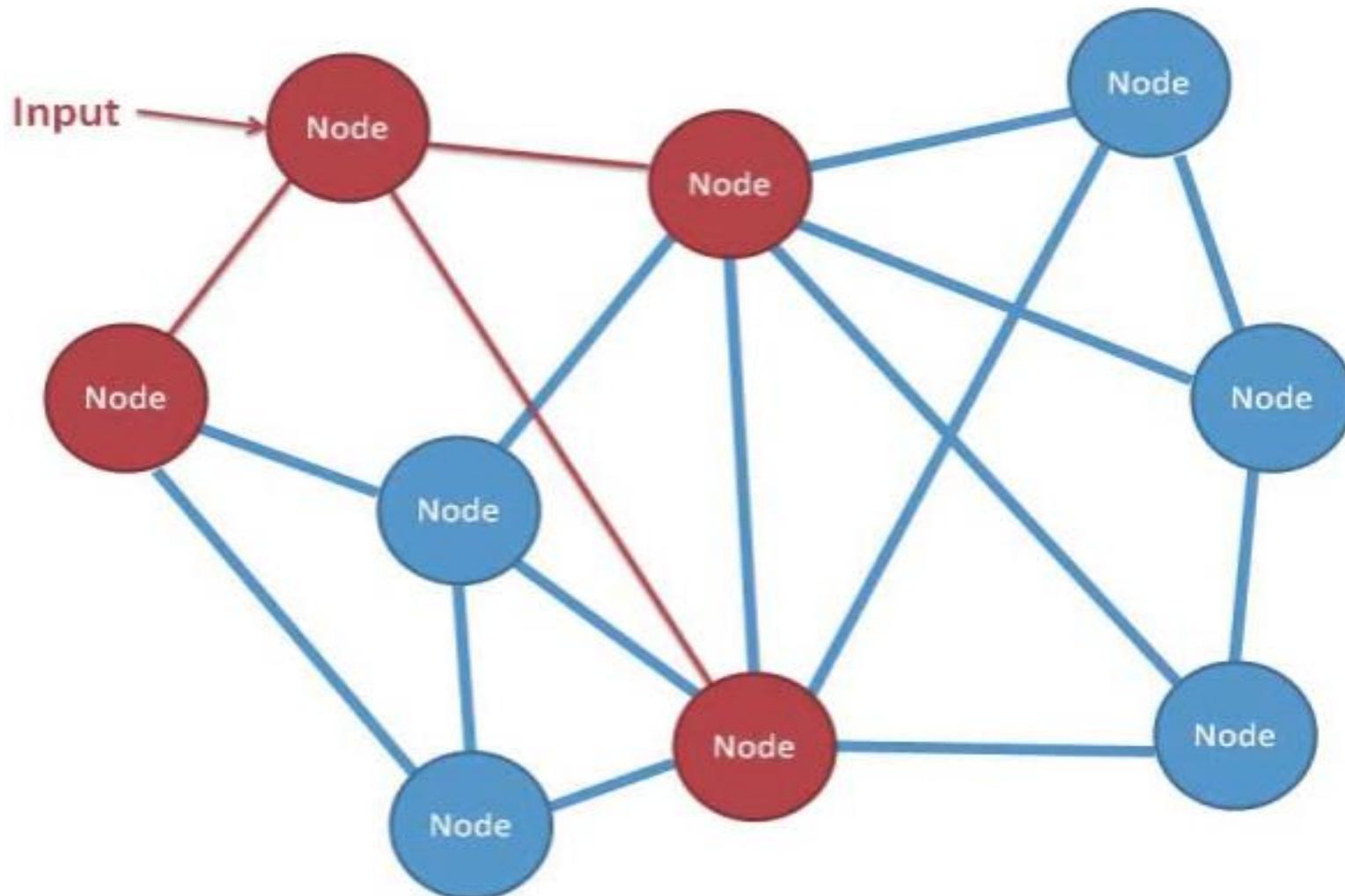


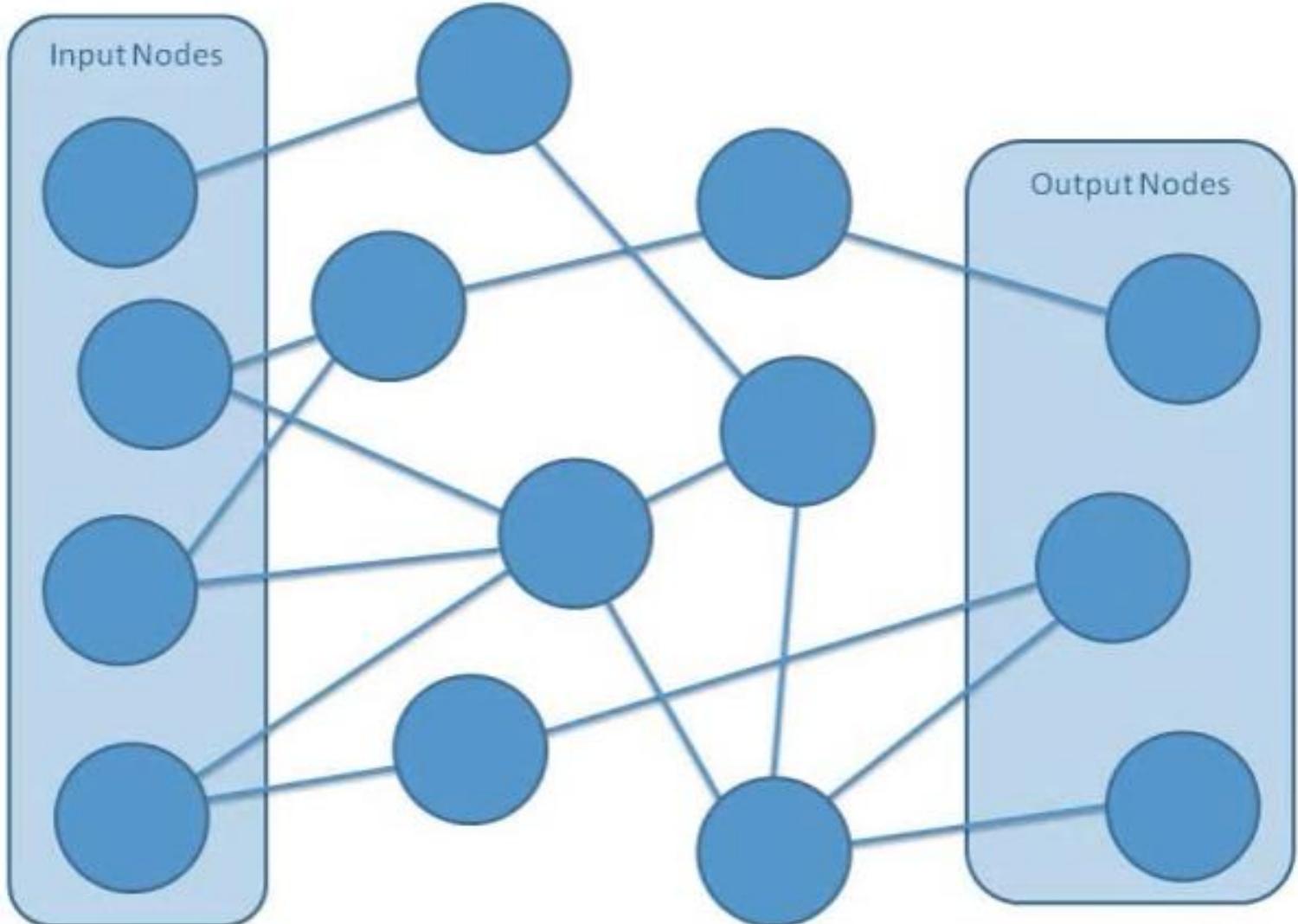
Real Neuron

No Relation

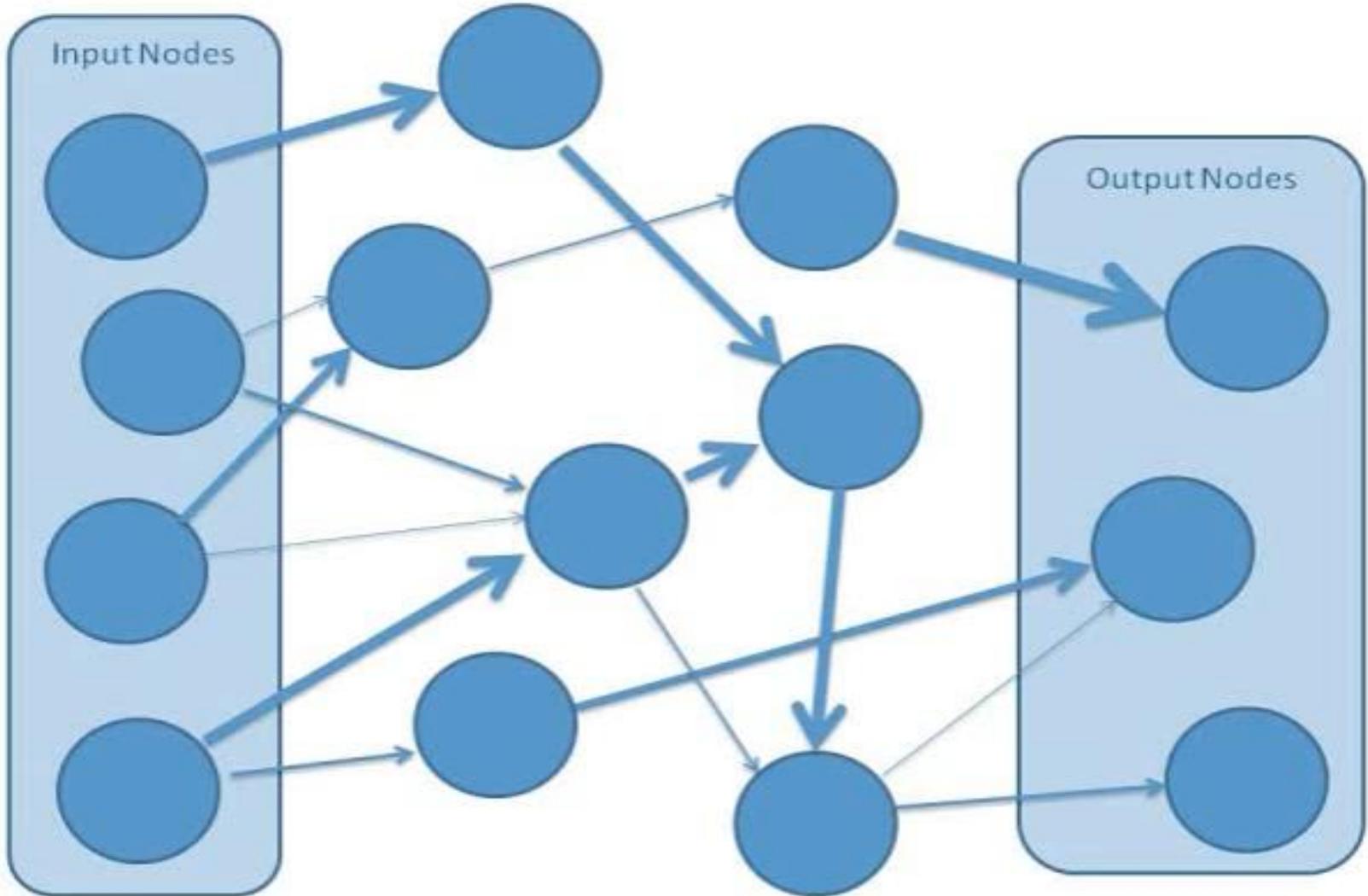
Artificial  
Neuron

# Neural Network Modeling

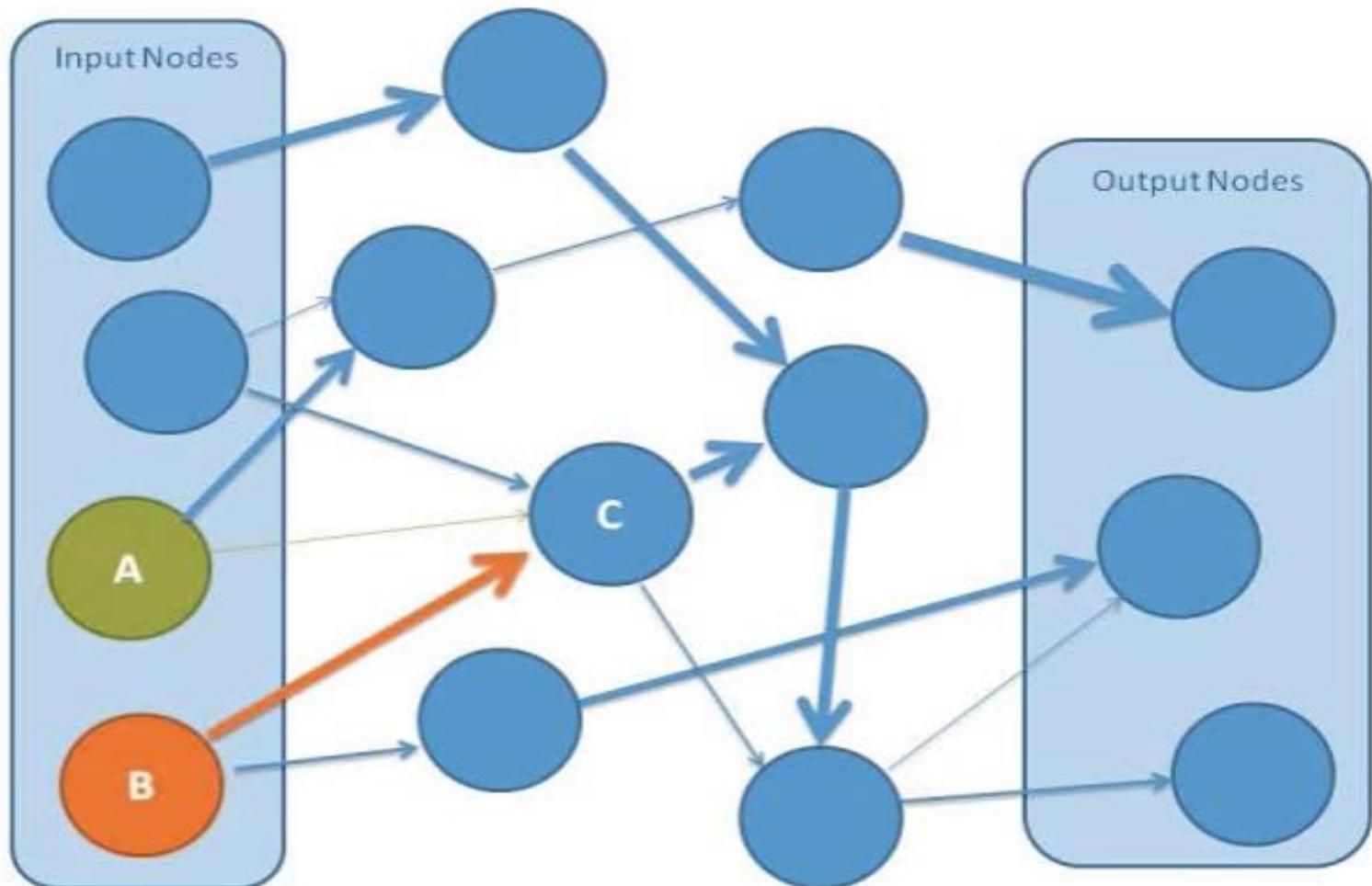


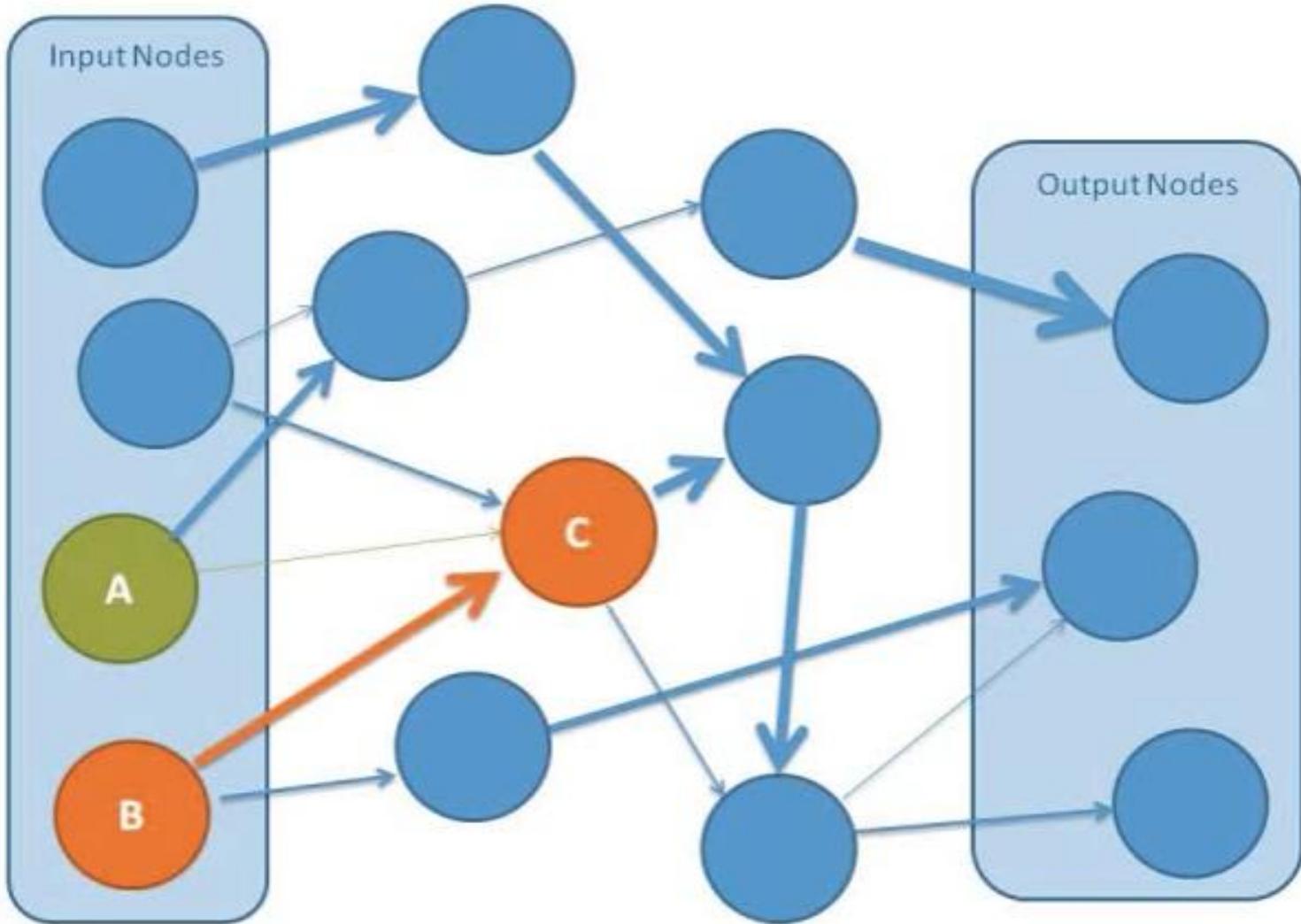


Connection Values Are Called Weights

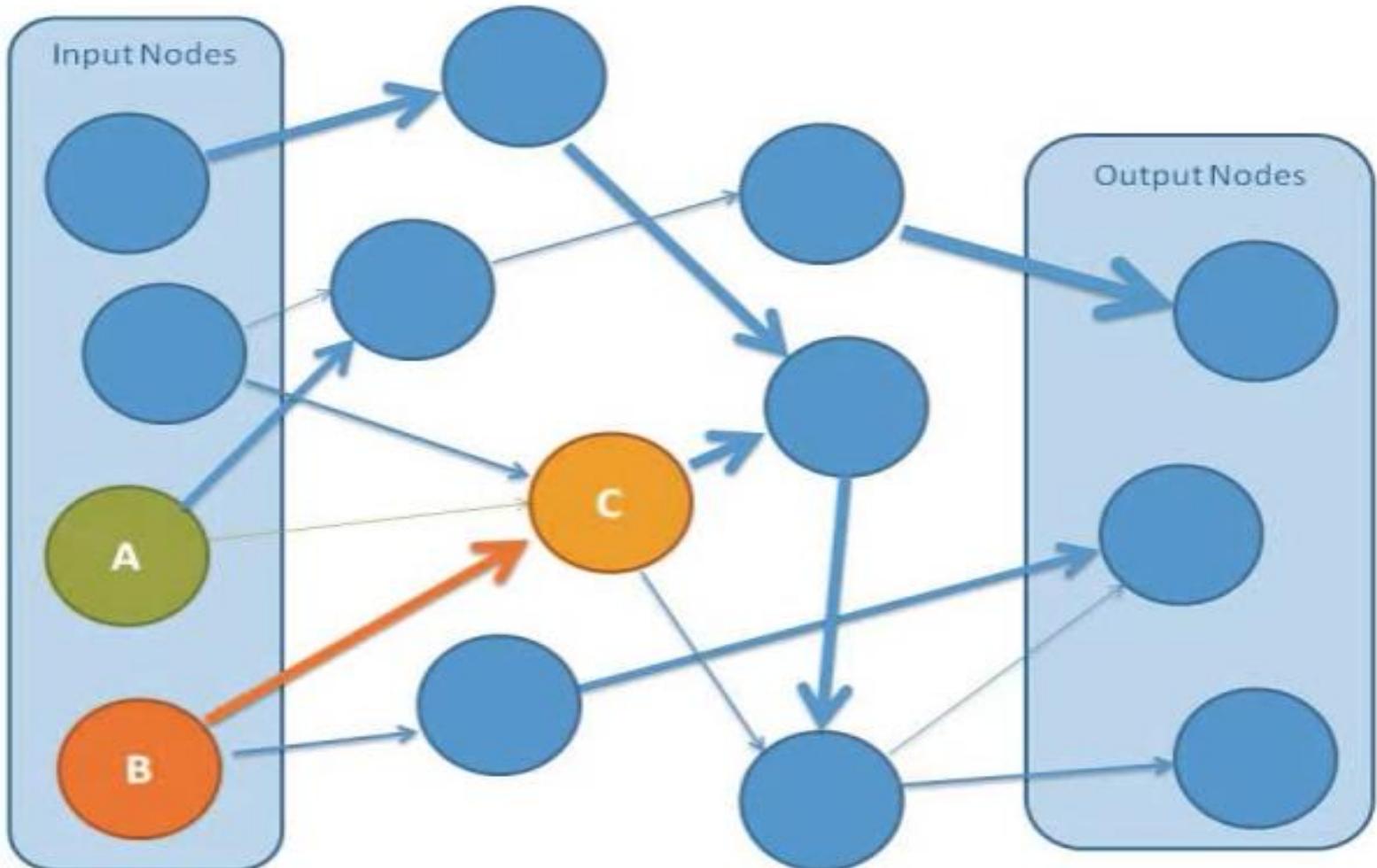


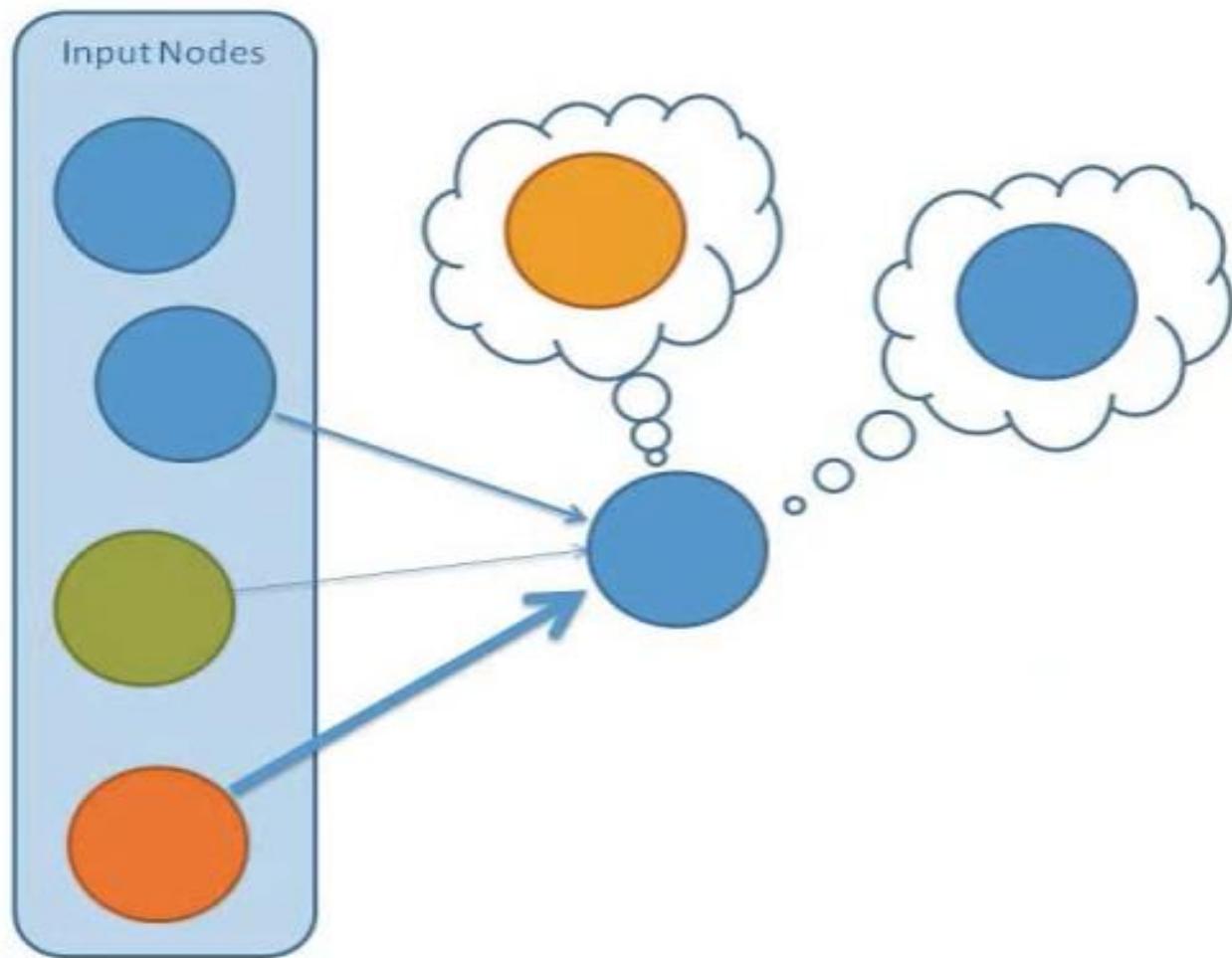
Different Weights



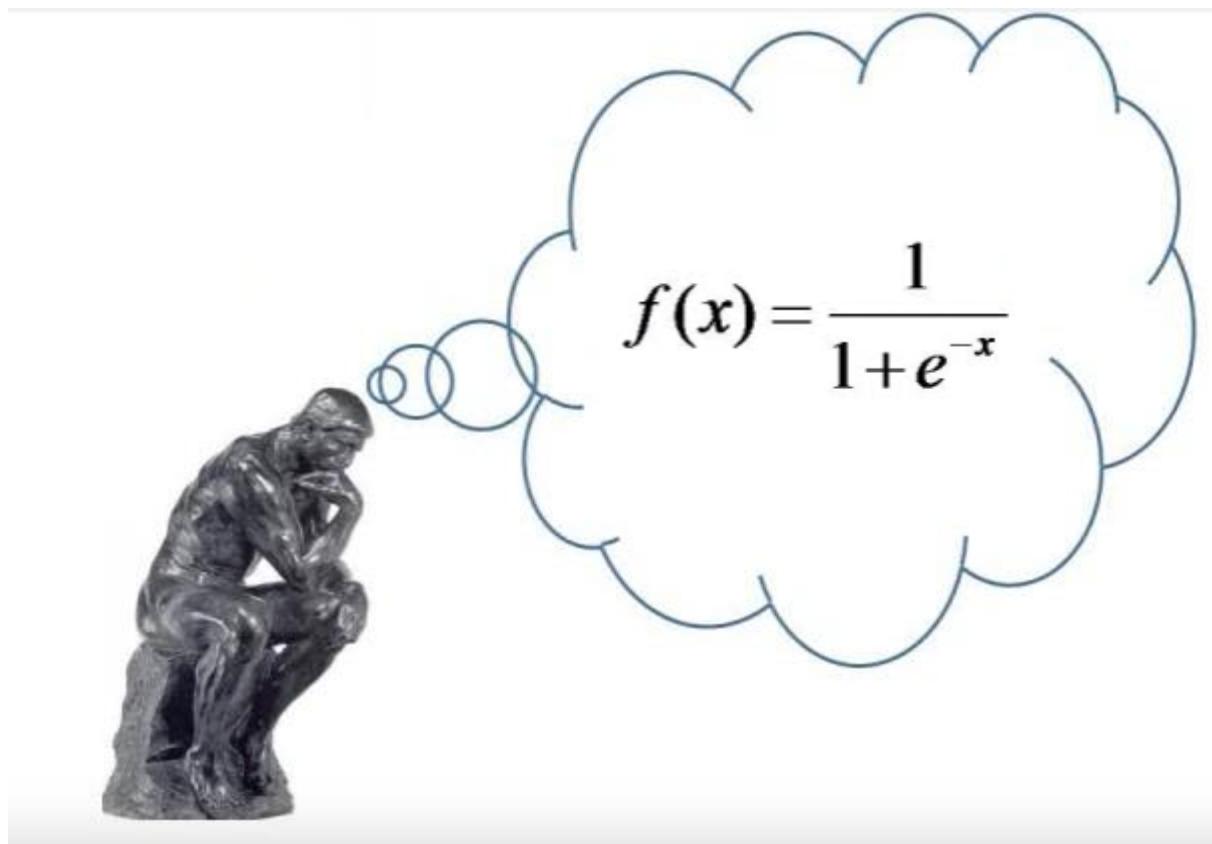


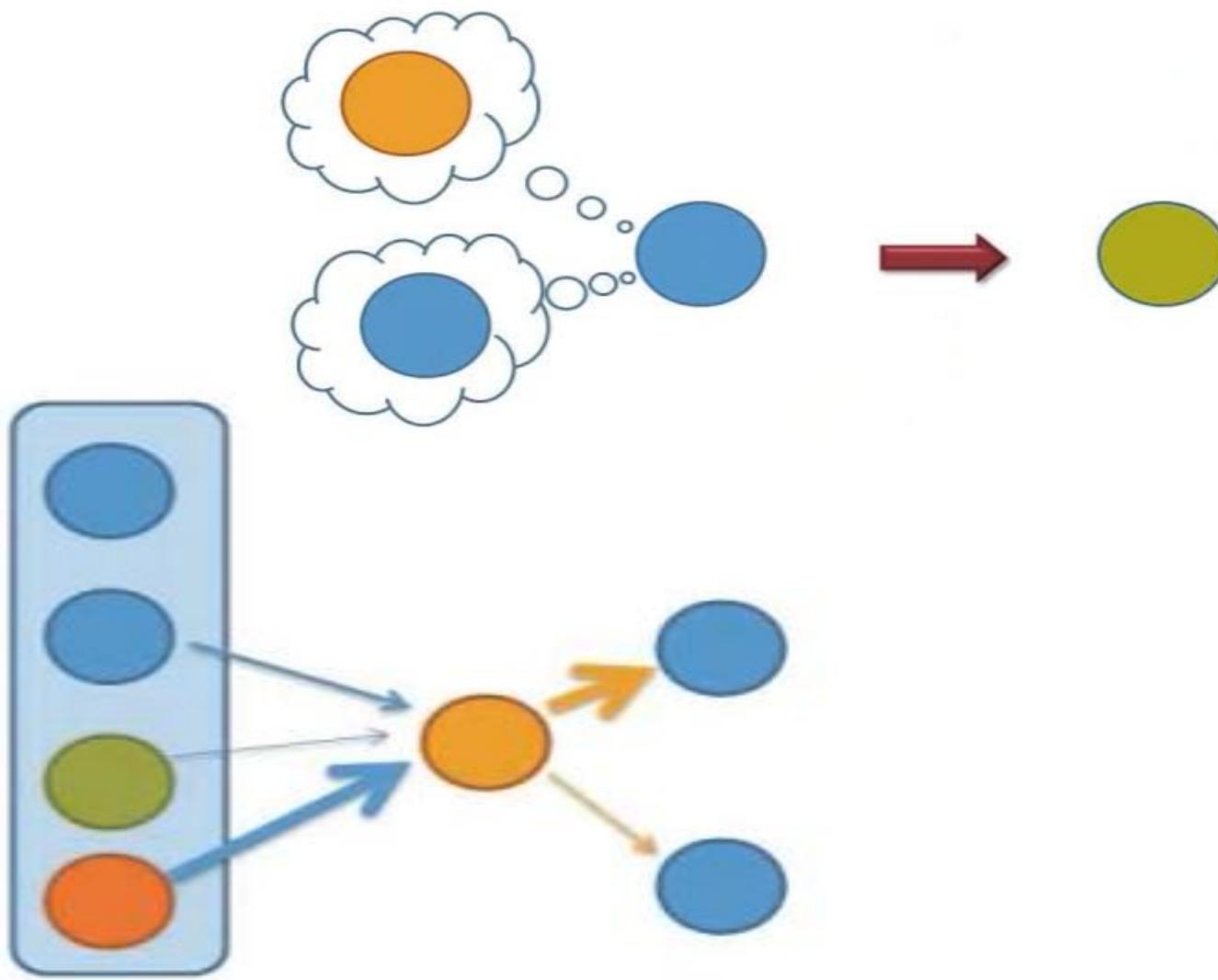
More often Node value design on the basis of  
**SUM** and **Average**



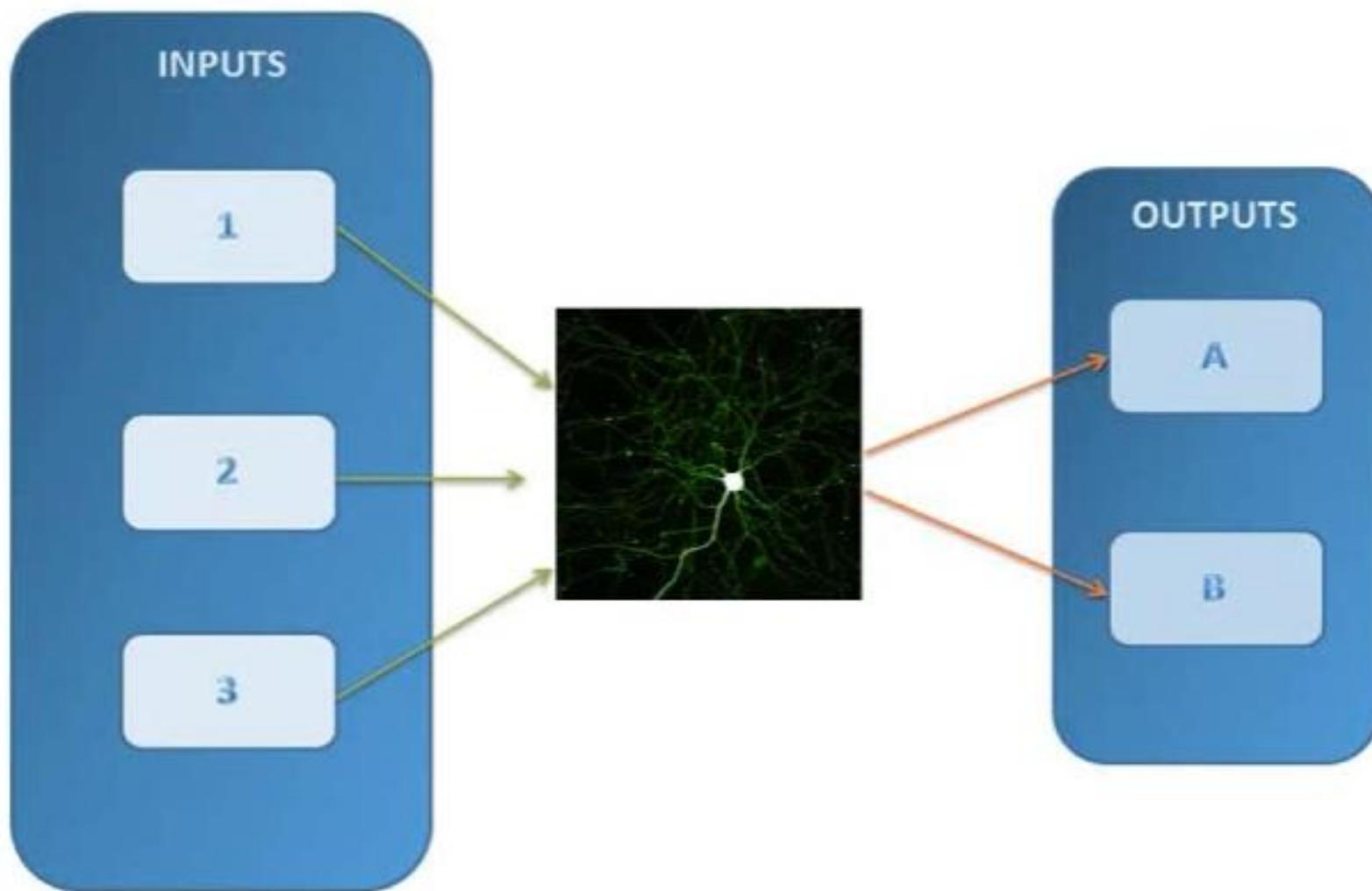


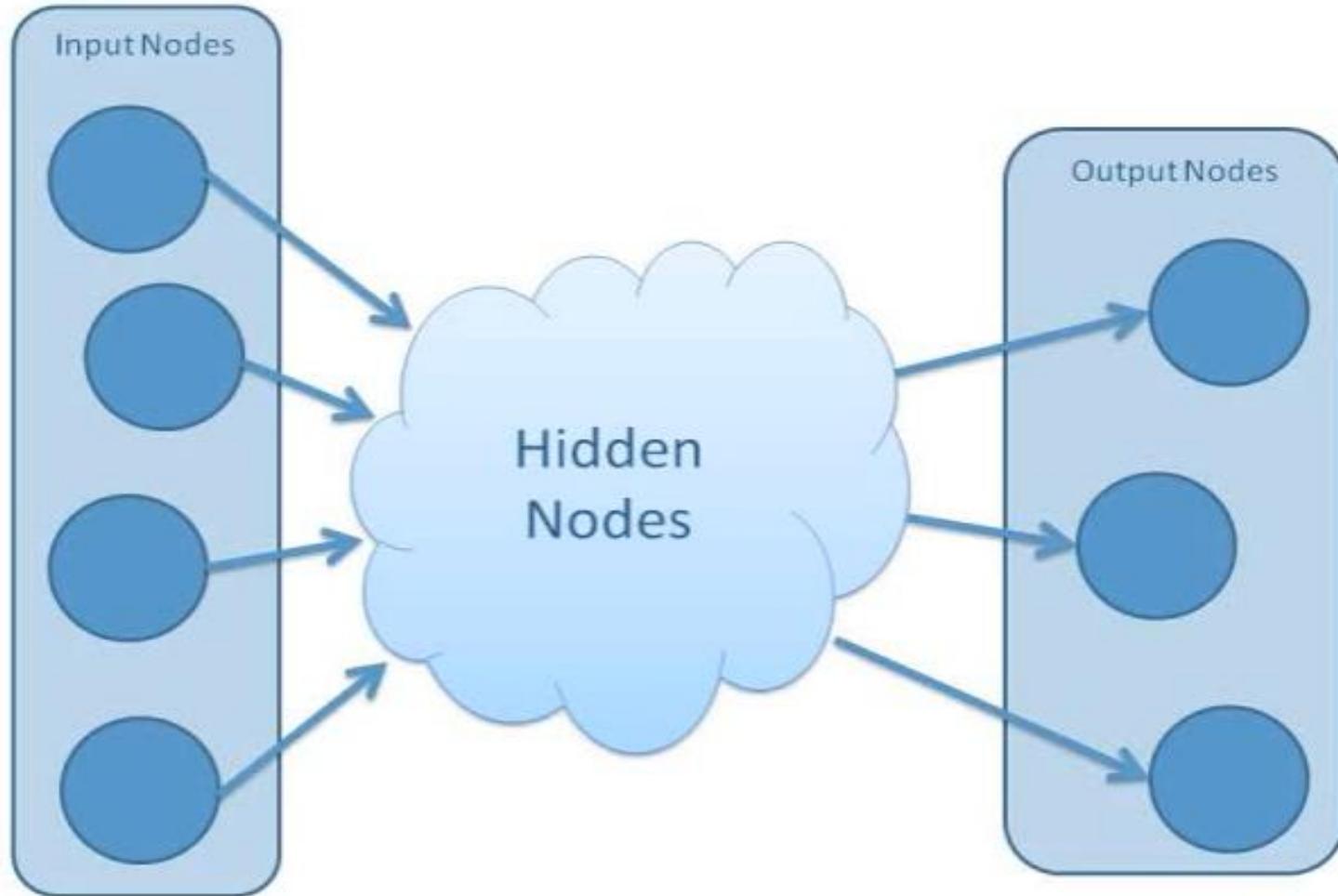
# Decision



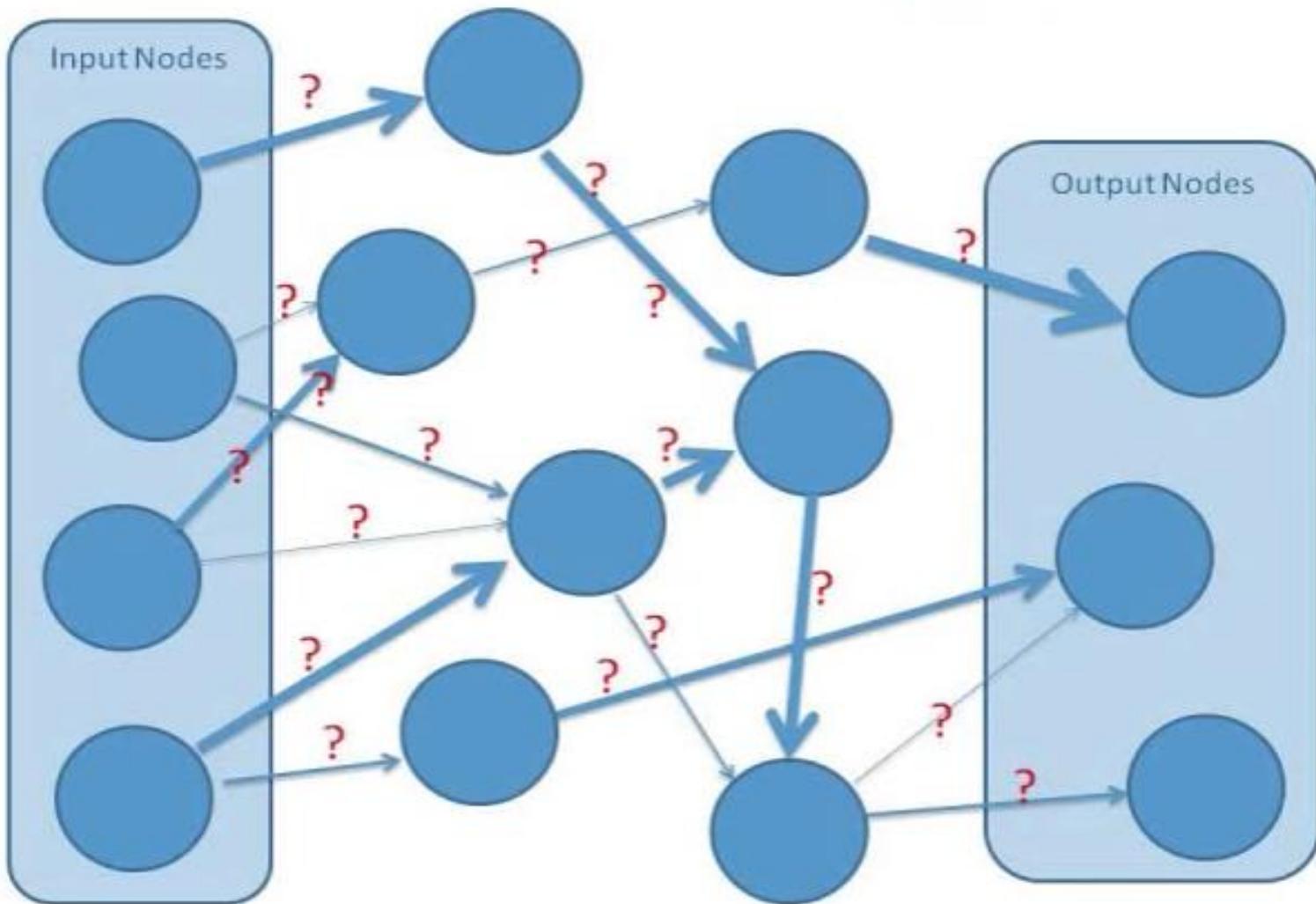


Using Connection Weight and Transfer Neural Network takes Input And Produce Output.



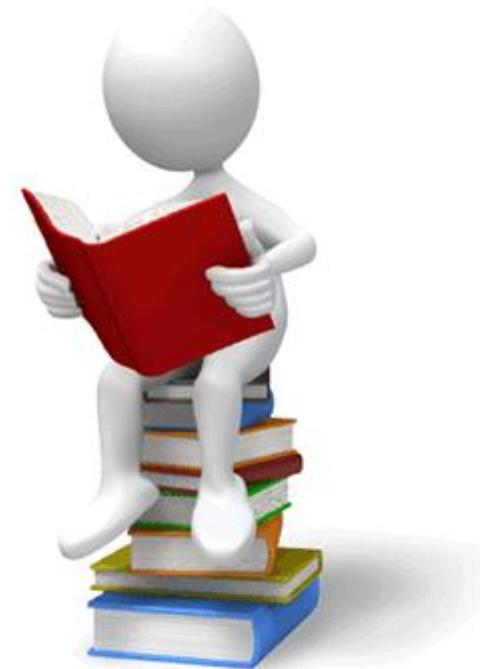


They Do most of work and get least Credit



**How Connection Weight Determent????**

# How We Solve Any Problem



Training By Example

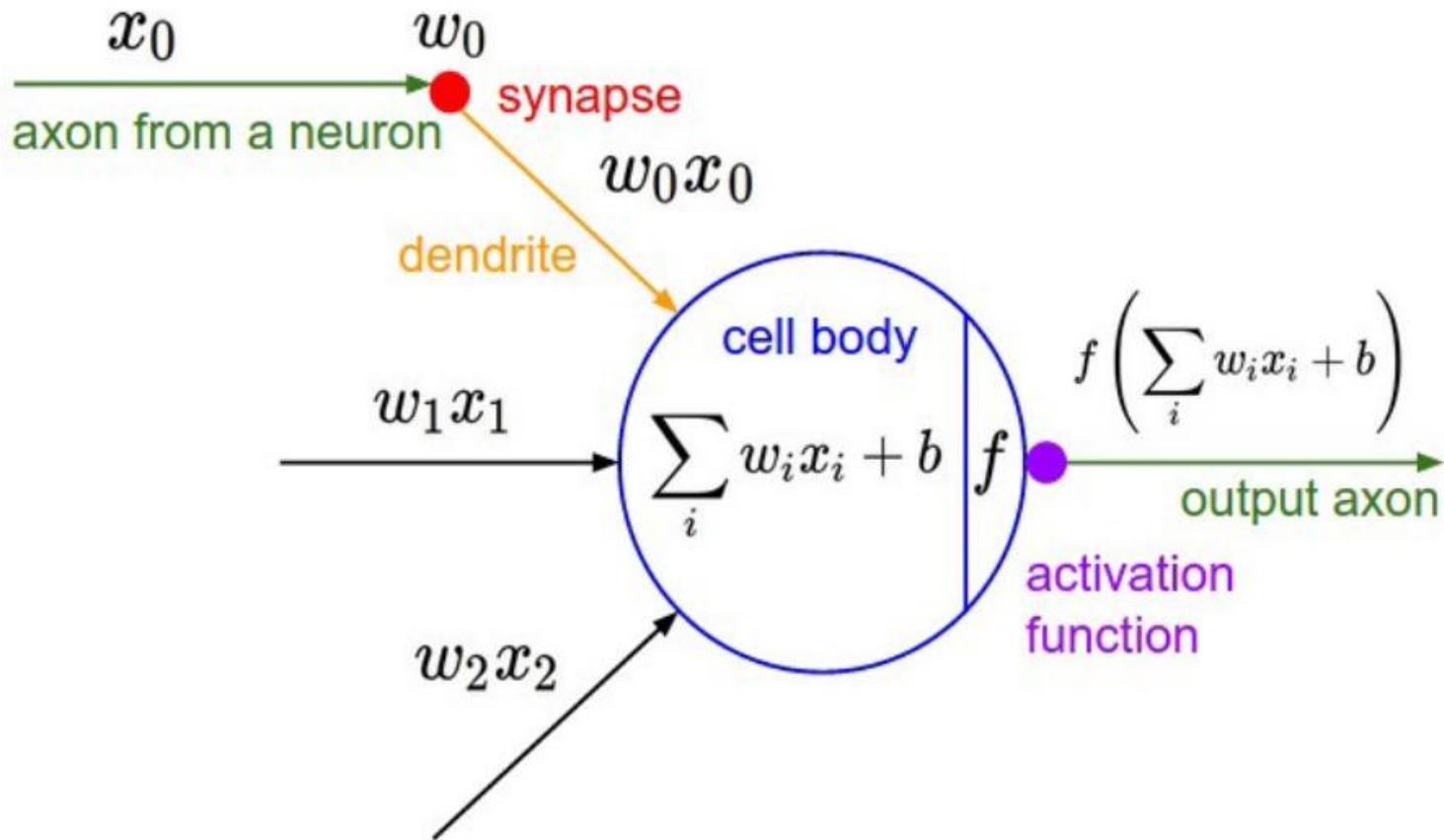
# **NEURAL NETWORK**

A Neural Network is a massively parallel distributed Processor that has a natural Propensity for **Storing Experimental Knowledge** and making it available for Use.

**ANN**-Training is Done by Example.

A neural network, is a collection of layers that transform the input in some way to produce an output

# Mathematical model of a neuron



**Data**, represented by  $x_0$ , travels through the connections between the neurons.

The strength of the connections are represented by their **weights** ( $w_0x_0$ ,  $w_1x_1$ , etc).

If the signal is strong enough, it fires the neuron via its “**activation function**” and makes the neuron “**active**.”

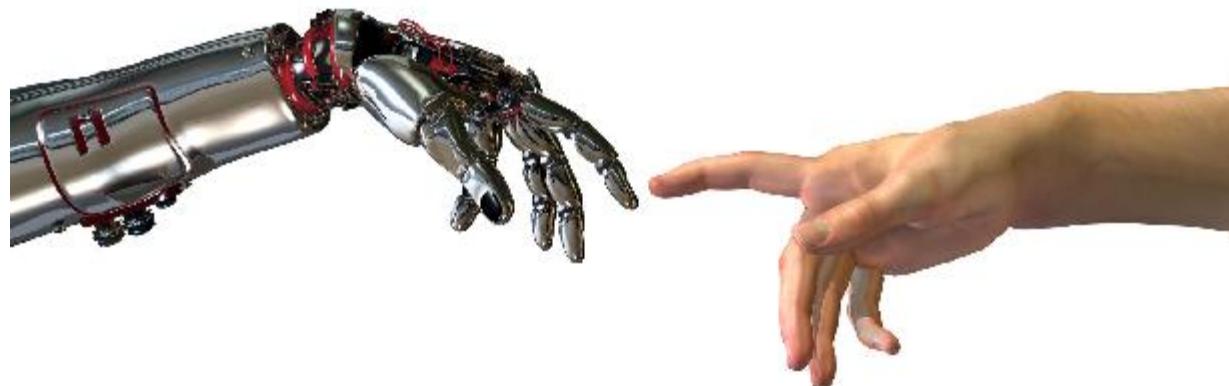
# INTELLIGENCE

- Perception (Concept or Senses)
- Problem Solving
- Reasoning
- Learning
- Control Uncertainties

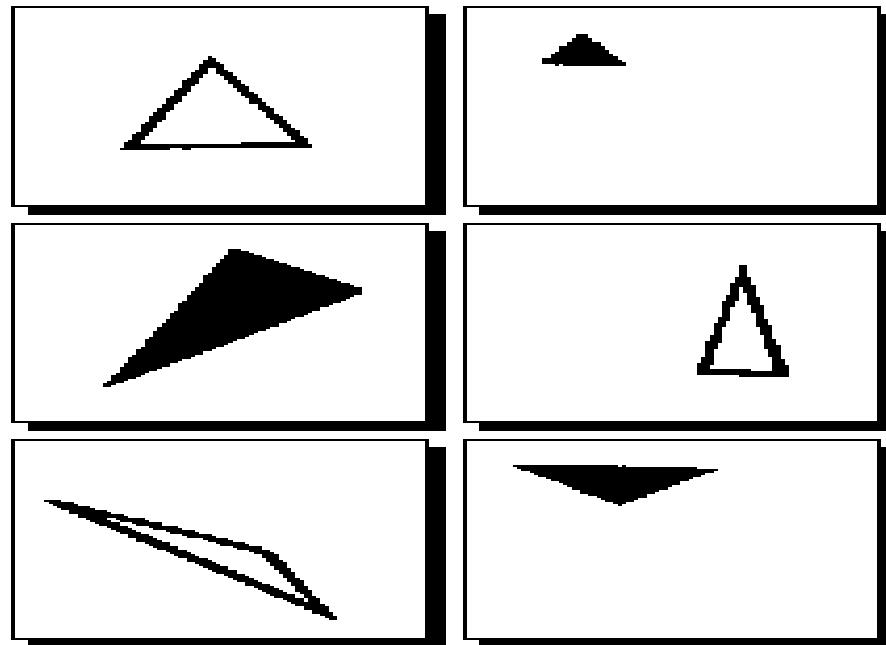
Intelligence is defined as general cognitive problem-solving skills.

# Artificial Intelligence

- Artificial Intelligence is a attribute of machines which gives it ability to mimic the Human thought process.



<b>Brain</b>	<b>10<sup>4</sup> Synapses</b>	<b>10-6 size</b>	<b>30W</b>	<b>100HZ</b>	<b>LEARN YES</b>
Computer	10 <sup>8</sup> Transistor	10-6 size	30W	10 <sup>9</sup> HZ	LITTLE (NO)



# Perceptrons

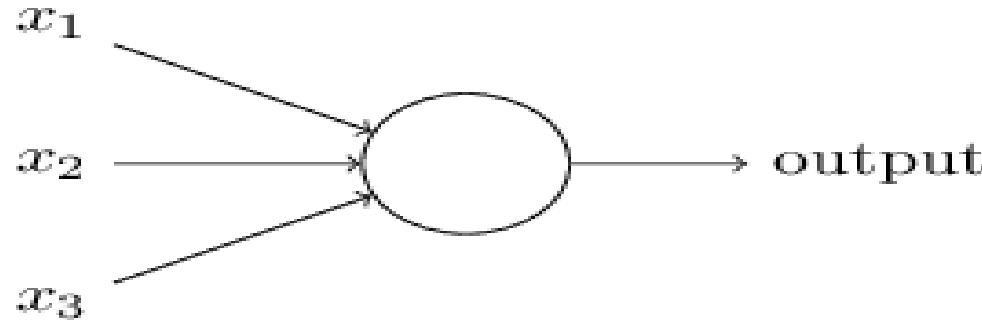
A simple neural network architecture is called perceptron.

The perceptron consists of two types of nodes: input nodes, which are used to represent the input attributes, and an output node, which is used to represent the model output.

In a perceptron, each input node is connected via a weighted link to the output Node.

This is one layer Network and use in The case of liner separable

This is a type of artificial neuron

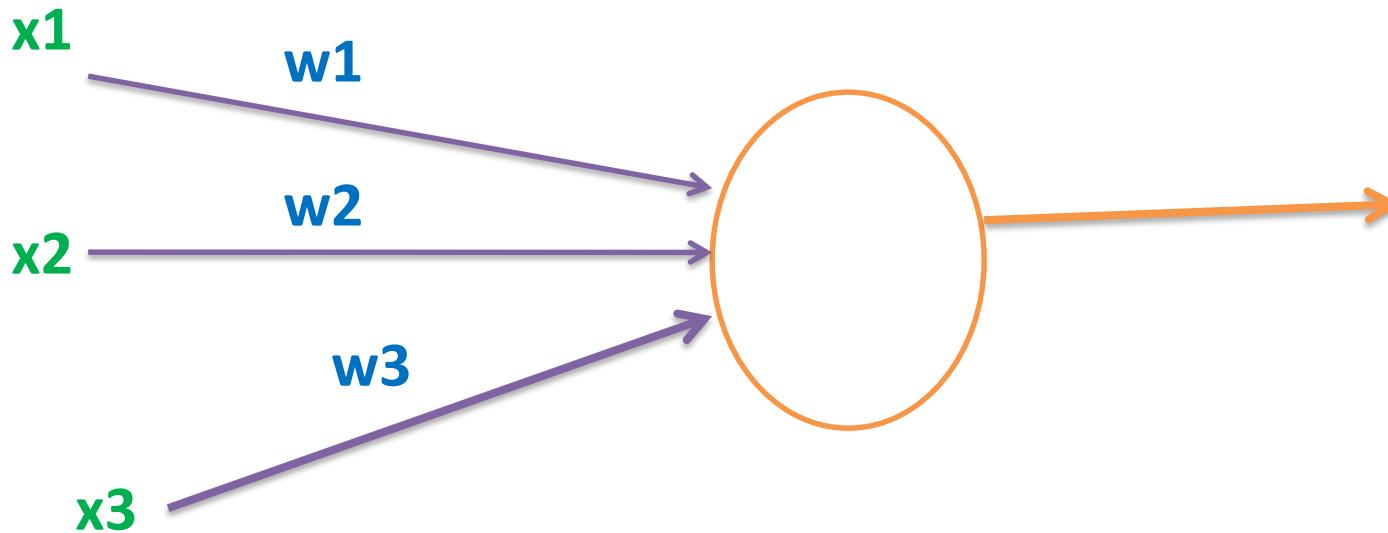


$$\text{output} = \begin{cases} 0 & \text{if } \sum_j w_j x_j \leq \text{threshold} \\ 1 & \text{if } \sum_j w_j x_j > \text{threshold} \end{cases}$$

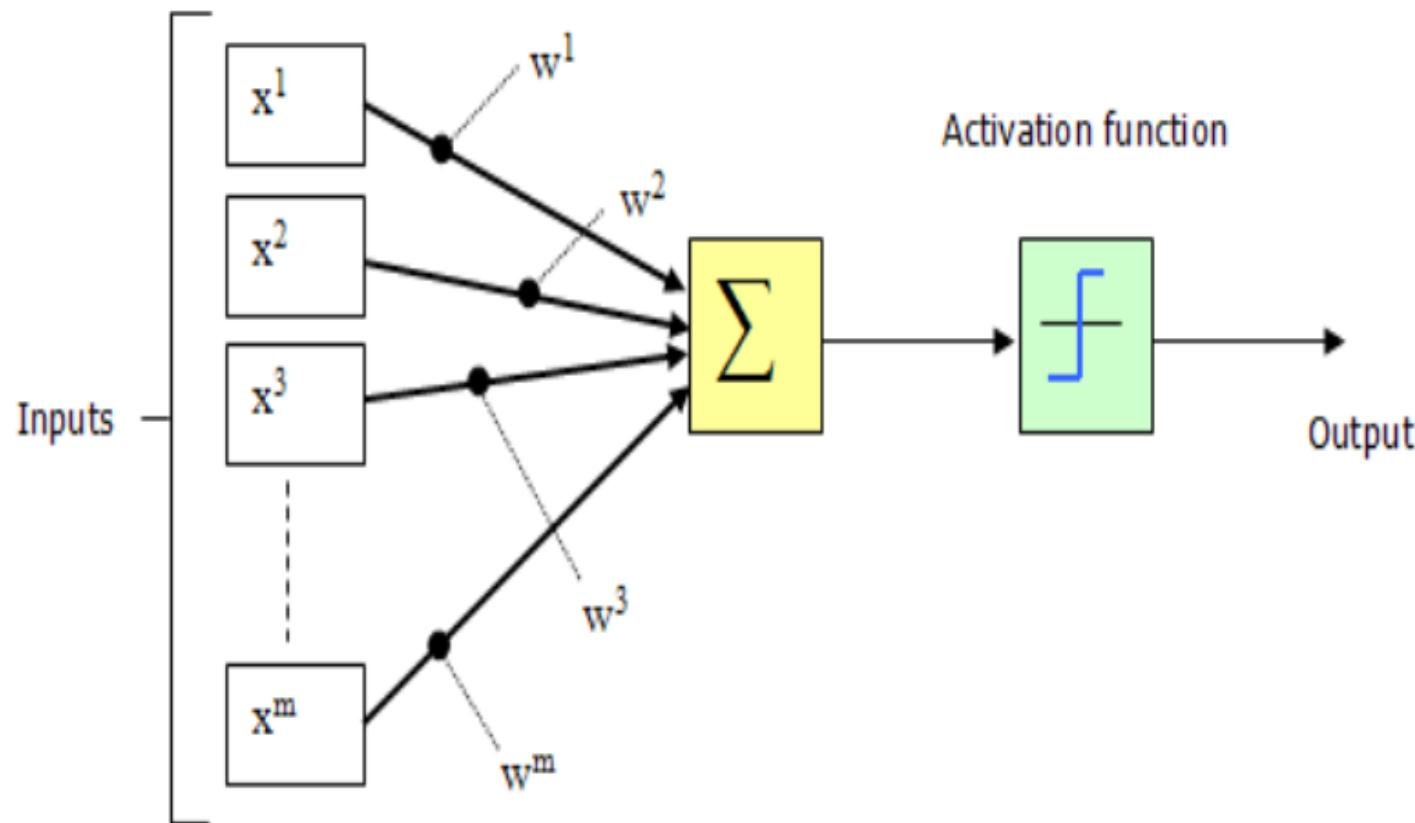
# Example

Suppose the weekend is coming up, and you've heard that there's going to be a cheese festival in your city. You like cheese, and are trying to decide whether or not to go to the festival.

1. Is the weather good?
2. Does your boyfriend or girlfriend want to accompany you?
3. Is the festival near public transit? (You don't own a car).



$x_1$	Weather	$X_2$	Friend	$X_3$	Transit
0	Not Good	0	Not GO	0	No
1	Good	1	Go	1	yes



Activation function

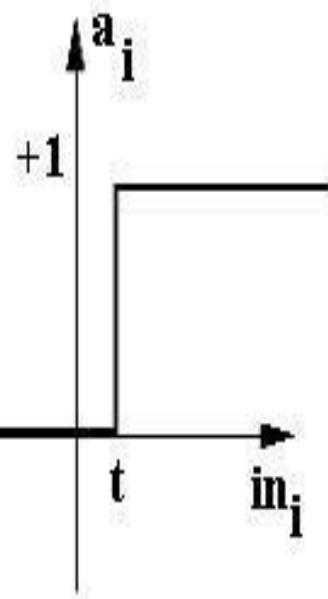
Inputs

Output

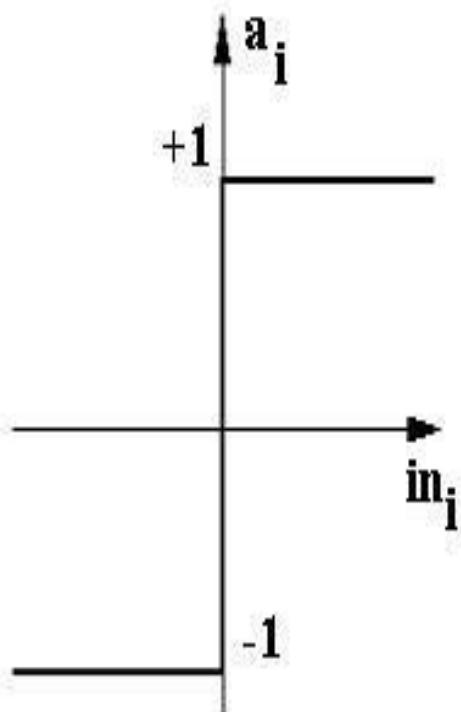
# Basic Element Of ANN

- Input and Output Nodes
- Weights
- Activation Function

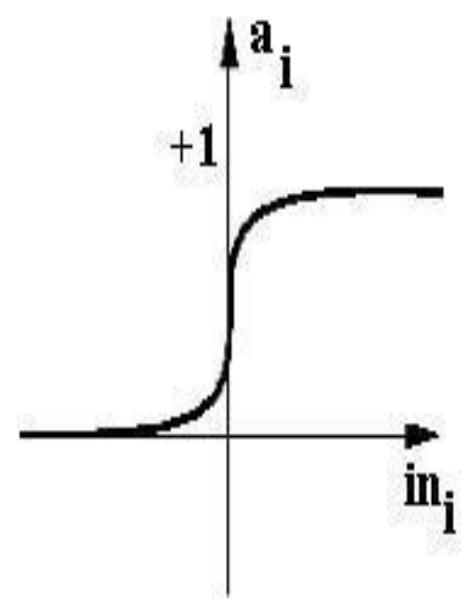
- Type of Neural Network
- Type of Activation Function
- Type of Learning Rule or Training



Step Function

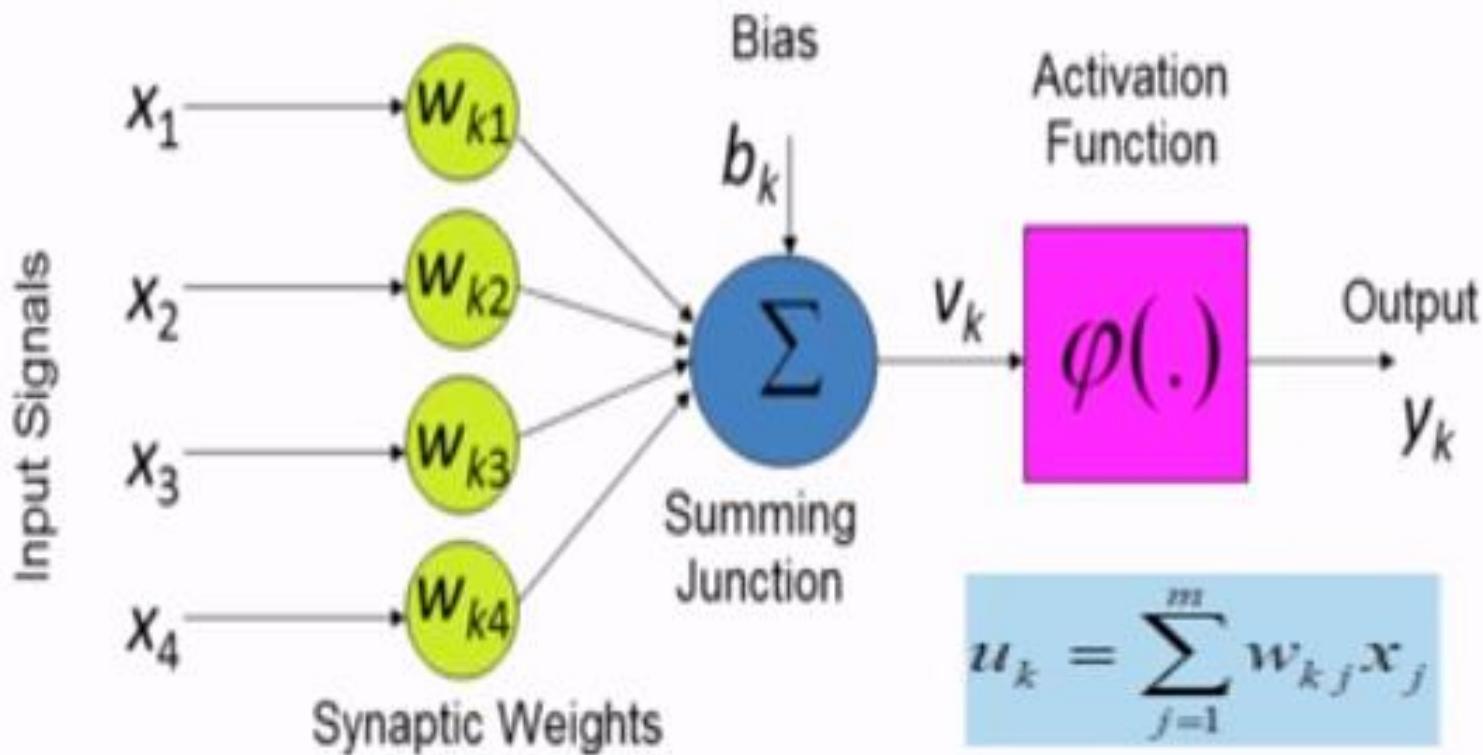


Sign Function



Sigmoid Function

# SINGLE-LAYER NEURAL NETWORKS (PERCEPTRONS)



$$y_k = \varphi(u_k + b_k)$$

**Input 1 ( $x_1$ ) = 0.6**

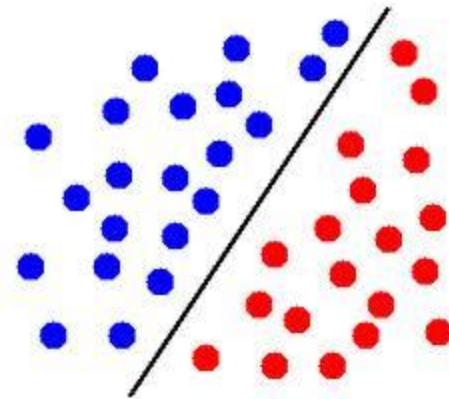
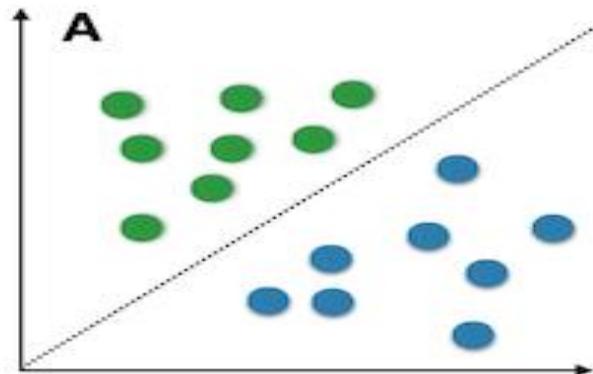
**Input 2 ( $x_2$ ) = 1.0**

**Weight 1 ( $w_1$ ) = 0.5**

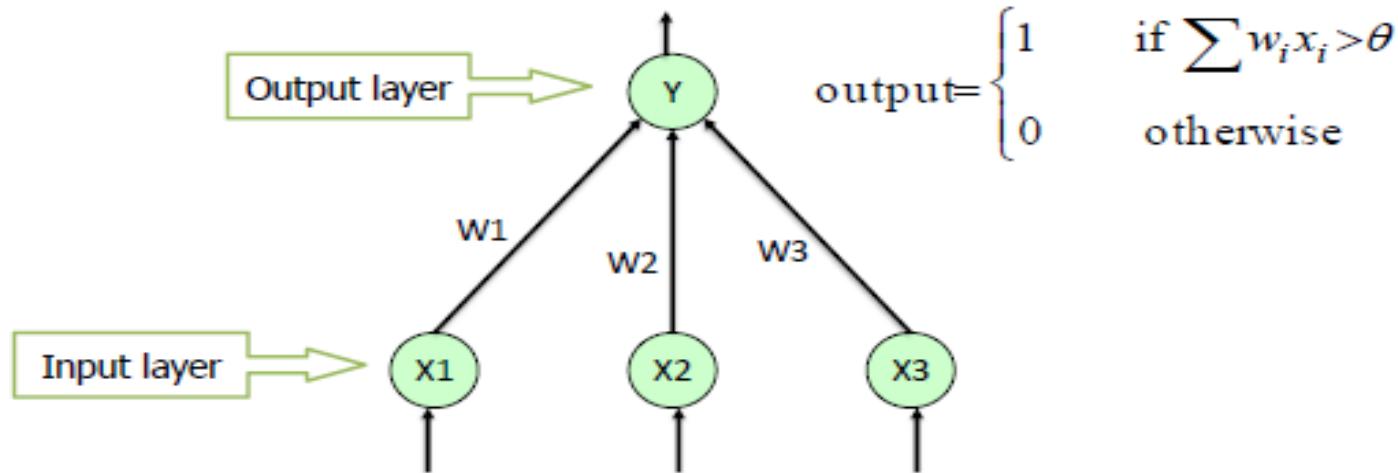
**Weight 2 ( $w_2$ ) = 0.8**

**Threshold = 1.0**

$$x_1w_1 + x_2w_2 = (0.6 \times 0.5) + (1 \times 0.8) = 1.1$$



Linearly separable



**The single layer perceptron does not have a priori knowledge, so the initial weights are assigned randomly. SLP sums all the weighted inputs and if the sum is above the threshold (some predetermined value), SLP is said to be activated (output=1).**

$$w_1 x_1 + w_2 x_2 + \dots + w_n x_n > \theta \quad \xrightarrow{\text{Output}} \quad 1$$

$$w_1 x_1 + w_2 x_2 + \dots + w_n x_n \leq \theta \quad \xrightarrow{\text{Output}} \quad 0$$

The input values are presented to the perceptron, and if the predicted output is the same as the desired output, then the performance is considered satisfactory and no changes to the weights are made. However, if the output does not match the desired output, then the weights need to be changed to reduce the error.

#### **Perceptron Weights Adjustment**

$$\Delta w = \eta \times d \times x$$

$d \rightarrow$  Predicted output - Desired output

$\eta \rightarrow$  Learning rate, usually less than 1

$x \rightarrow$  Input data

## The rule

The output node has a "threshold"  $t$ .

Rule: If summed input  $\geq t$ , then it "fires"  
(output  $y = 1$ ).

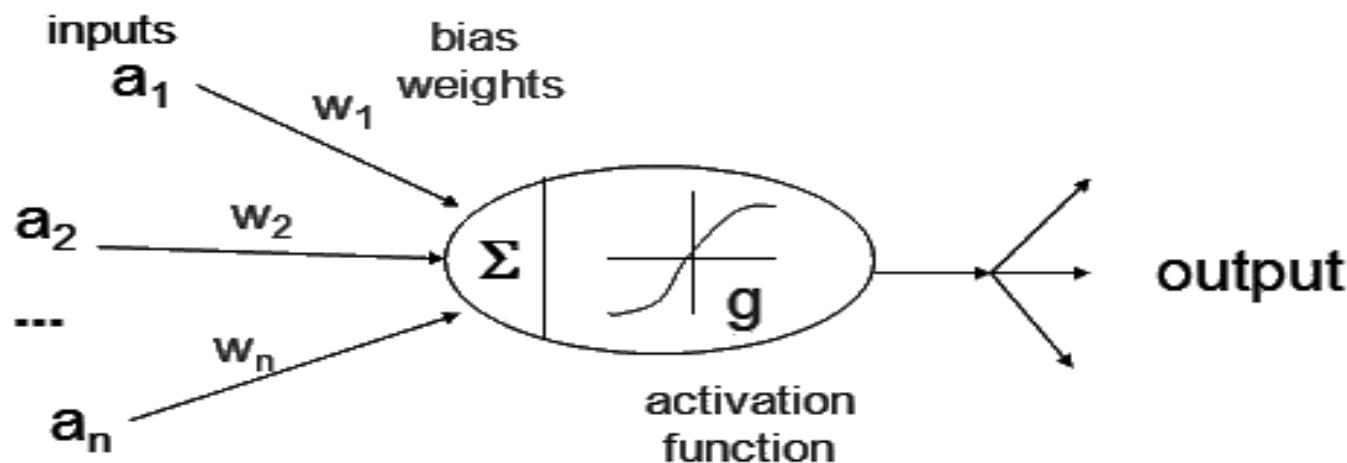
Else (summed input  $< t$ ) it doesn't fire  
(output  $y = 0$ ).

if  $\sum_i w_i I_i \geq t$  then  $y = 1$

else ( if  $\sum_i w_i I_i < t$  ) then  $y = 0$

# Learning Rule

- Update The Weight and Bias to minimize the error.
- The learning Rate helps us control how much we change the weight and bias.



Let input  $x = (I_1, I_2, \dots, I_n)$  where each  $I_i = 0$  or  $1$ . And let output  $y = 0$  or  $1$ .

Given input  $x = (I_1, I_2, \dots, I_n)$ . Perceptron produces output  $y$ . We are told correct output  $O$ .

If we had wrong answer, change  $w_i$ 's and  $t$ , otherwise do nothing.

Given input  $x = (I_1, I_2, \dots, I_n)$ . Perceptron produces output  $y$ . We are told correct output  $O$ .

For all  $i$ :

$$w_i := w_i + C(O-y) I_i$$

$$t := t - C(O-y)$$

Suppose you have the following classification problem and would like to solve it with a single vector input, two-element perceptron network.

$$\left\{ \mathbf{p}_1 = \begin{bmatrix} 2 \\ 2 \end{bmatrix}, t_1 = 0 \right\} \left\{ \mathbf{p}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, t_2 = 1 \right\} \left\{ \mathbf{p}_3 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}, t_3 = 0 \right\} \left\{ \mathbf{p}_4 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, t_4 = 1 \right\}$$

$$\mathbf{W}(0) = [0 \ 0] \quad b(0) = 0$$

Start by calculating the perceptron's output  $a$  for the first input vector  $\mathbf{p}_1$ , using the initial weights and bias.

$$\begin{aligned} a &= \text{hardlim}(\mathbf{W}(0)\mathbf{p}_1 + b(0)) \\ &= \text{hardlim}([0 \ 0][2 \ 2]' + 0) \\ &= \text{hardlim}(0) = 1 \end{aligned}$$

The output  $a$  does not equal the target value  $t_1$ , so use the perceptron rule to find the incremental changes to the weights and biases based on the error.

$$e = t_1 - \alpha = 0 - 1 = -1$$

$$\Delta \mathbf{W} = e \mathbf{p}^T = (-1)[2 \ 2] = [-2 \ -2]$$

$$\Delta b = e = (-1) = -1$$

new weights and bias using the perceptron update rules.

$$\mathbf{W}_{\text{new}} = \mathbf{W}_{\text{old}} + \mathbf{e} \mathbf{p}^T$$

$$= [0 \ 0] + [-2 \ -2] = [-2 \ -2] = \mathbf{W}(1)$$

$$b_{\text{new}} = b_{\text{old}} + e =$$

$$0 + (-1) = -1 = b(1)$$

next input vector,  $\mathbf{p}_2$ . The output is calculated below.

$$\alpha = \text{hardlim}(\mathbf{W}(1)\mathbf{p}_2 + b(1))$$

$$= \text{hardlim}([-2 \ -2][1 \ -2] - 1)$$

$$= \text{hardlim}(1) = 1$$

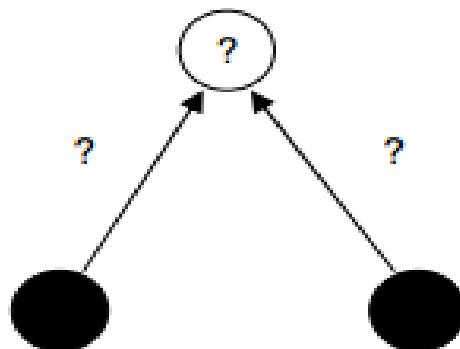
On this occasion, the target is 1, so the error is zero. Thus there are no changes in weights or bias, so  $\mathbf{W}(2) = \mathbf{W}(1) = [-2 \ -2]$  and  $b(2) = b(1) = -1$ .

# IMPLEMENTATION OF LOGICAL NOT, AND, AND OR

NOT	
in	out
0	1
1	0

AND		
in <sub>1</sub>	in <sub>2</sub>	out
0	0	0
0	1	0
1	0	0
1	1	1

OR		
in <sub>1</sub>	in <sub>2</sub>	out
0	0	0
0	1	1
1	0	1
1	1	1



AND

	T	F
T	T	F
F	F	F

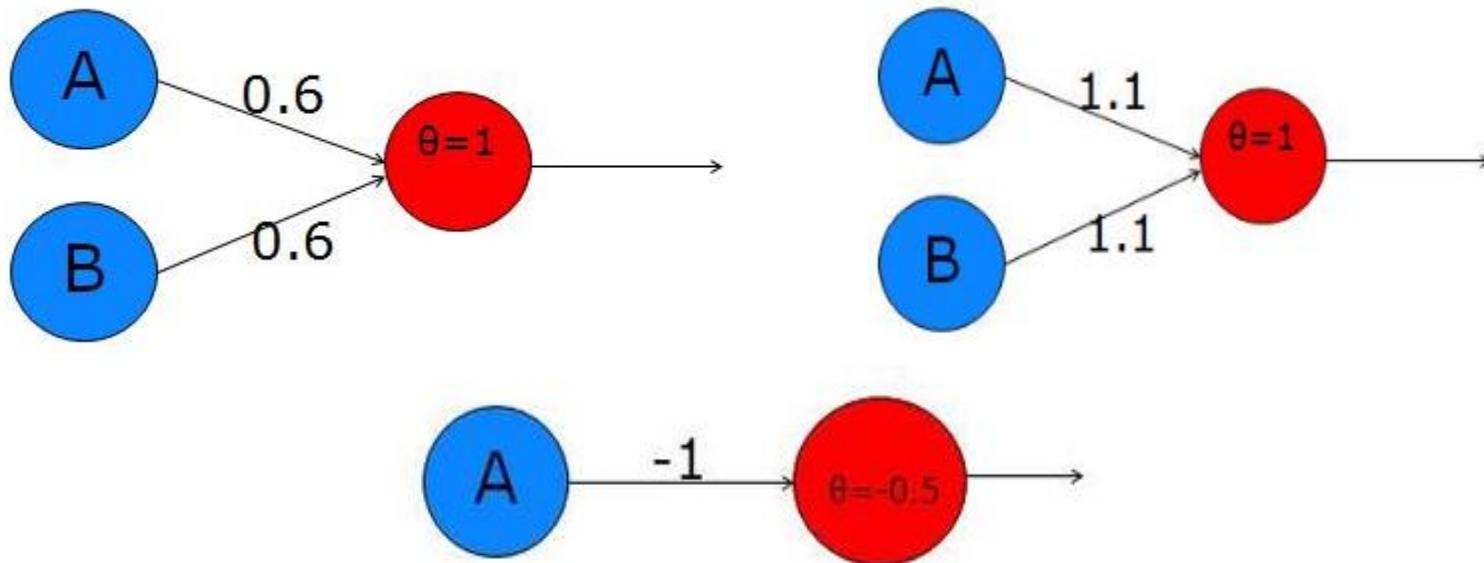
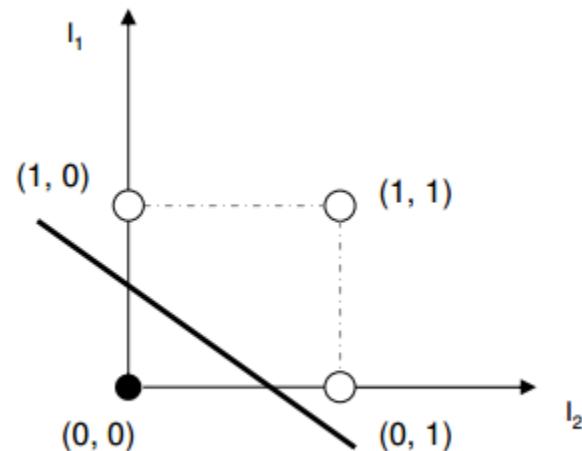
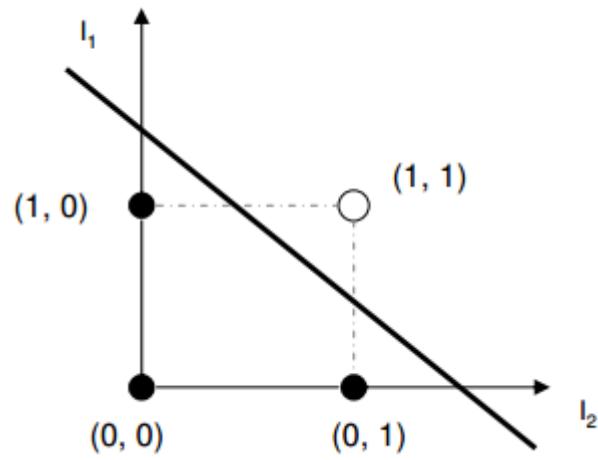
OR

	T	F
T	T	T
F	T	F

XOR

	T	F
T	F	T
F	T	F

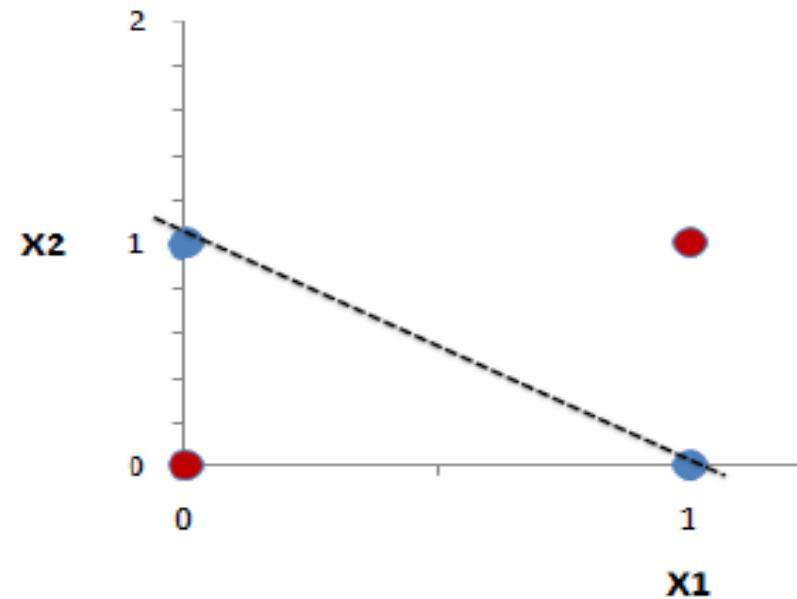
***XOR is the equivalent of OR and  
NOT AND***



# Xor Function

INPUT		OUTPUT
A	B	C
0	0	0
0	1	1
1	0	1
1	1	0

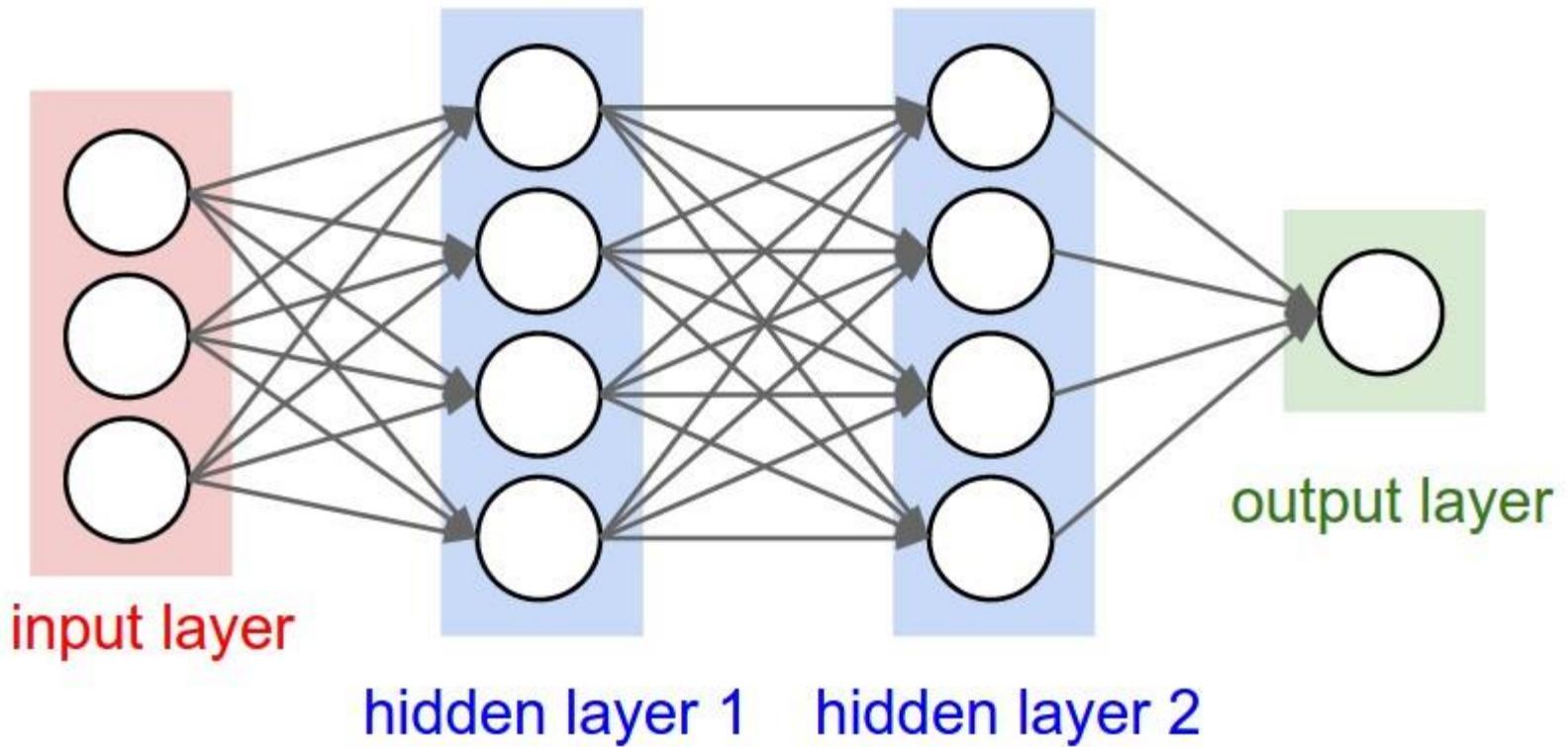
Truth Table



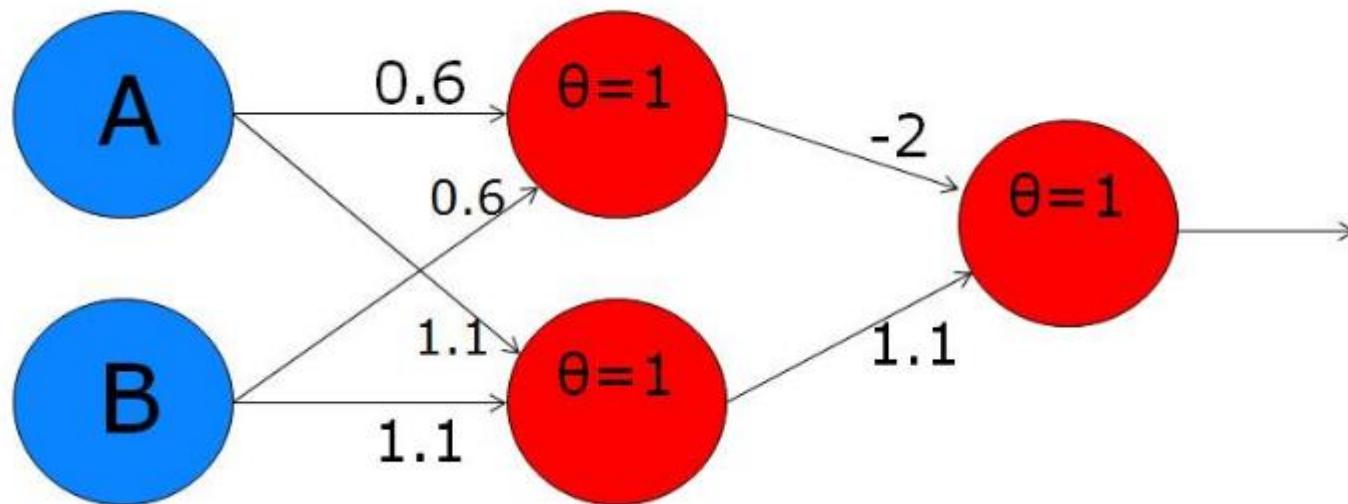
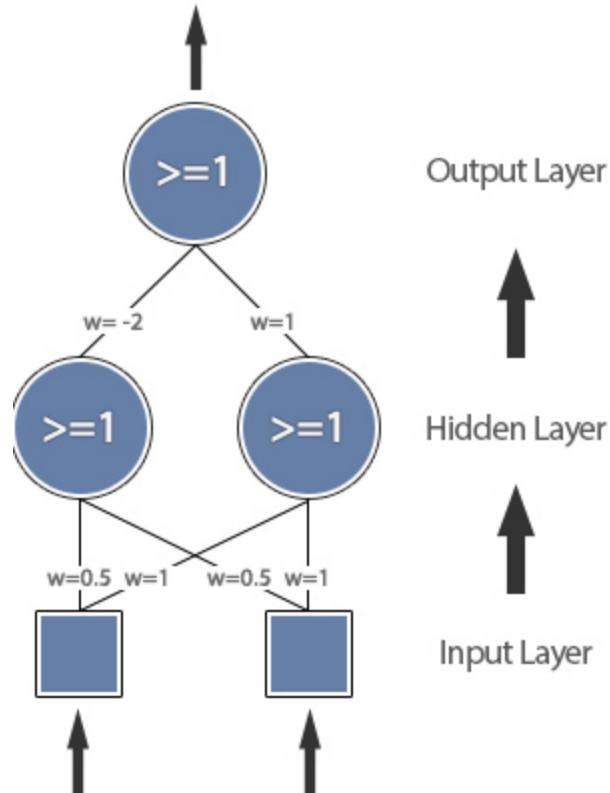
It is Not Linear separable.

It can not model using single Perceptron .

# Multi-layer Perceptron



# XOR

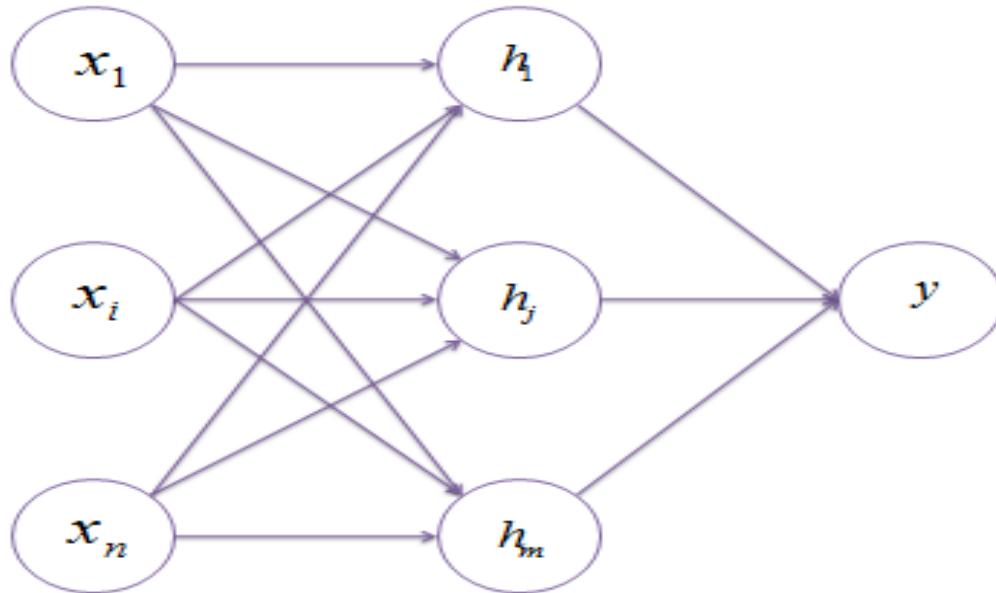


# Multi-layer Perceptron

A multi-layer perceptron (**MLP**) has the same structure of a single layer perceptron with one or more hidden layers.

The backpropagation algorithm consists of two phases:

1. The forward phase where the activations are propagated from The input to the output layer.
  
2. Backward phase, where the error between the observed actual and the requested nominal value in the output layer is propagated backwards in order to modify the weights and bias values.



1. Error in any **output** neuron

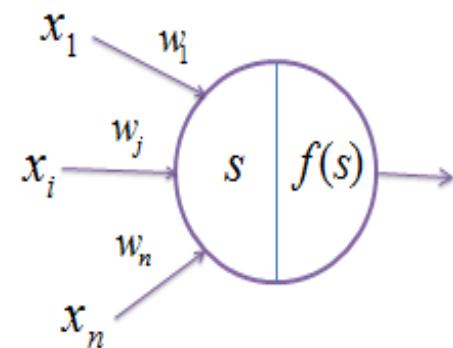
$$d_o = y \times (1 - y) \times (t - y)$$

2. Error in any **hidden** neuron

$$d_i = y_i \times (1 - y_i) \times (w_i \times d_o)$$

3. Change the **weights**

$$\Delta w = \eta \times d \times x$$



**Summation**

$$s = \sum w \cdot x$$

**Transformation**

$$f(s) = \frac{1}{1 + e^{-s}}$$

# Calculate the output of a simple neuron

1. Define neuron parameters
2. Define input vector
3. Calculate neuron output
4. Plot neuron output over the range of inputs

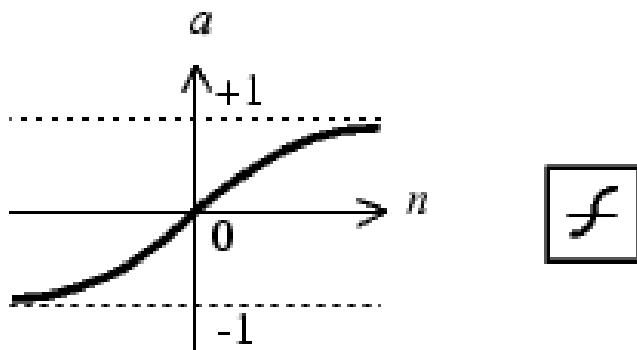
Transfer functions convert a neural network layer's net input into its net output.

**tansig** Symmetric sigmoid transfer function.

$A = \text{tansig}(N)$ .

$N$ :S-by-Q matrix of net input (column) vectors

returns  $A$ , the S-by-Q matrix of  $N$ 's elements squashed into [-1 1].



$$a = \text{tansig}(n)$$

```
n = -5:0.1:5;  
a = tansig(n);  
plot(n,a)
```

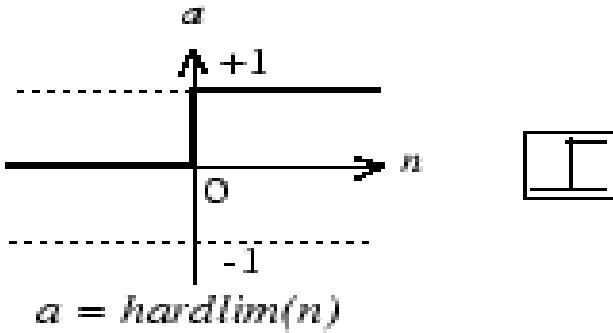
Tan-Sigmoid Transfer Function

**hardlim**:Hard-limit transfer function

**A = hardlim(N)**

N S-by-Q matrix of net input (column) vectors.

returns A, the S-by-Q Boolean matrix with 1s where  $N \geq 0$ .



```
n = -5:0.1:5;  
a = hardlim(n);  
plot(n,a)
```

Hard-Limit Transfer Function

Meshgrid: Rectangular grid in 2-D and 3-D space

[X,Y] = meshgrid(1:3,10:14).

surf:3-D shaded surface plot

[X,Y] = meshgrid(-2:.2:2, -2:.2:2);

[X,Y] = meshgrid(-2:.2:2, -2:.2:2);

Z = X .\* exp(-X.^2 - Y.^2);

surf(X,Y,Z)

Define neuron parameters

close all, clear all, clc, format compact

w = [4 -2]

b = -3

func = 'tansig'

p=[2 3]

activation\_potential = p\*w'+b

neuron\_output = feval(func, activation\_potential)

### Plot neuron output over the range of inputs

```
[p1,p2] = meshgrid(-10:.25:10);  
z = feval(func, [p1(:) p2(:)]*w'+b );  
z = reshape(z,length(p1),length(p2));  
plot3(p1,p2,z)  
grid on  
xlabel('Input 1')  
ylabel('Input 2')  
zlabel('Neuron output')
```

# Create custom neural network

```
net = network
```

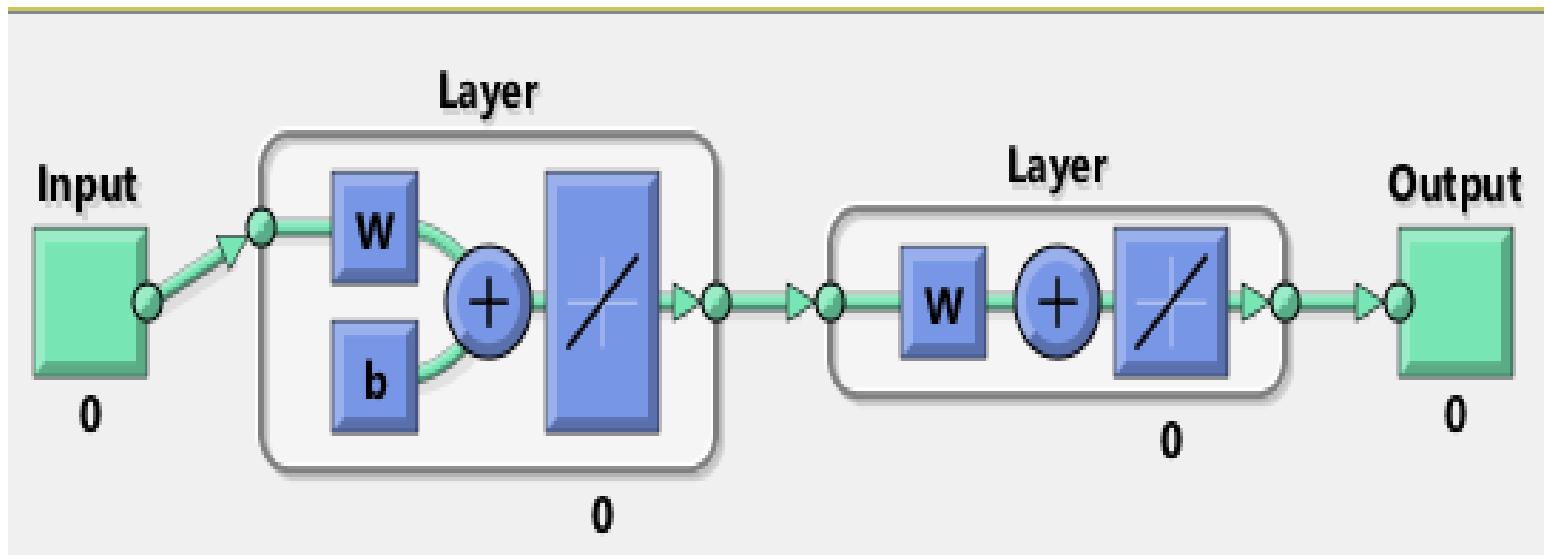
```
net =
```

```
network(numInputs,numLayers,biasConnect,inputConn  
ect,layerConnect,outputConnect)
```

View

For displaying the network

```
inputs = [1:6]' % input vector (6-dimensional pattern)
outputs = [1 2]' % corresponding target output vector
net = network( ...
    1,      ... % numInputs,   number of inputs,
    2,      ... % numLayers,   number of layers
    [1; 0], ... % biasConnect, numLayers-by-1 Boolean vector,
    [1; 0], ... % inputConnect, numLayers-by-numInputs Boolean
                 matrix,
    [0 0; 1 0], ... % layerConnect, numLayers-by-numLayers Boolean
                    matrix
    [0 1]      ... % outputConnect, 1-by-numLayers Boolean vector
);
view(net)
```

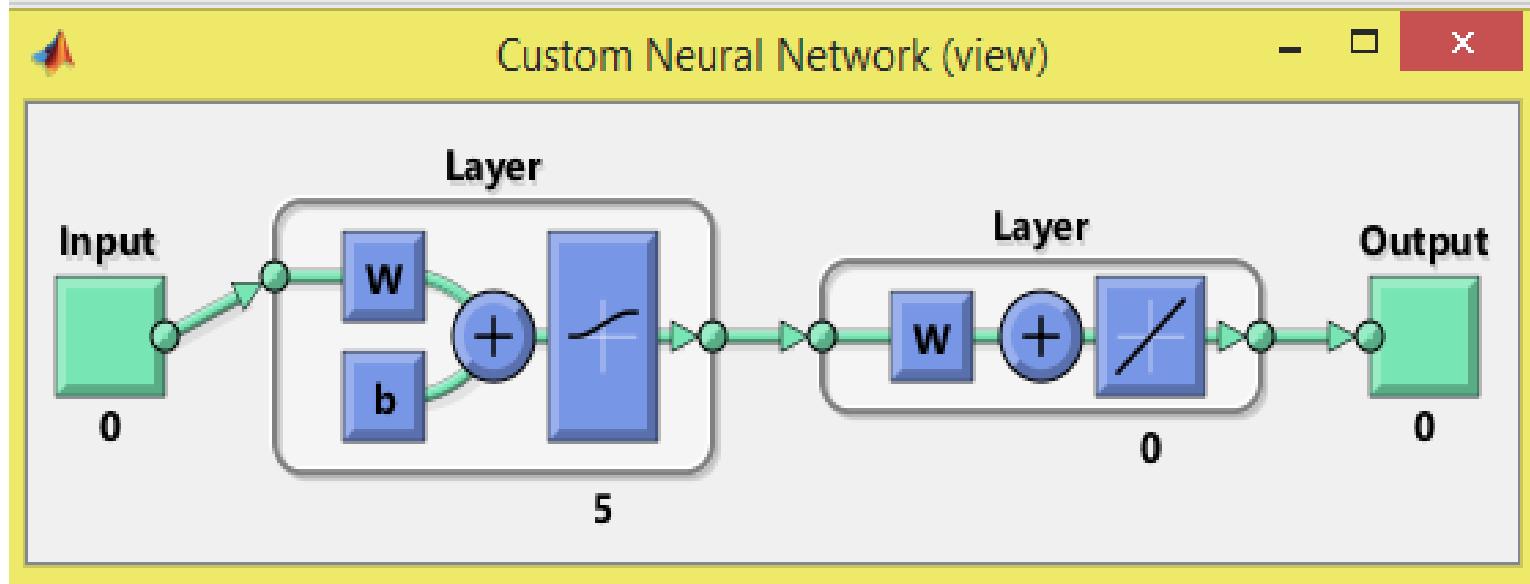
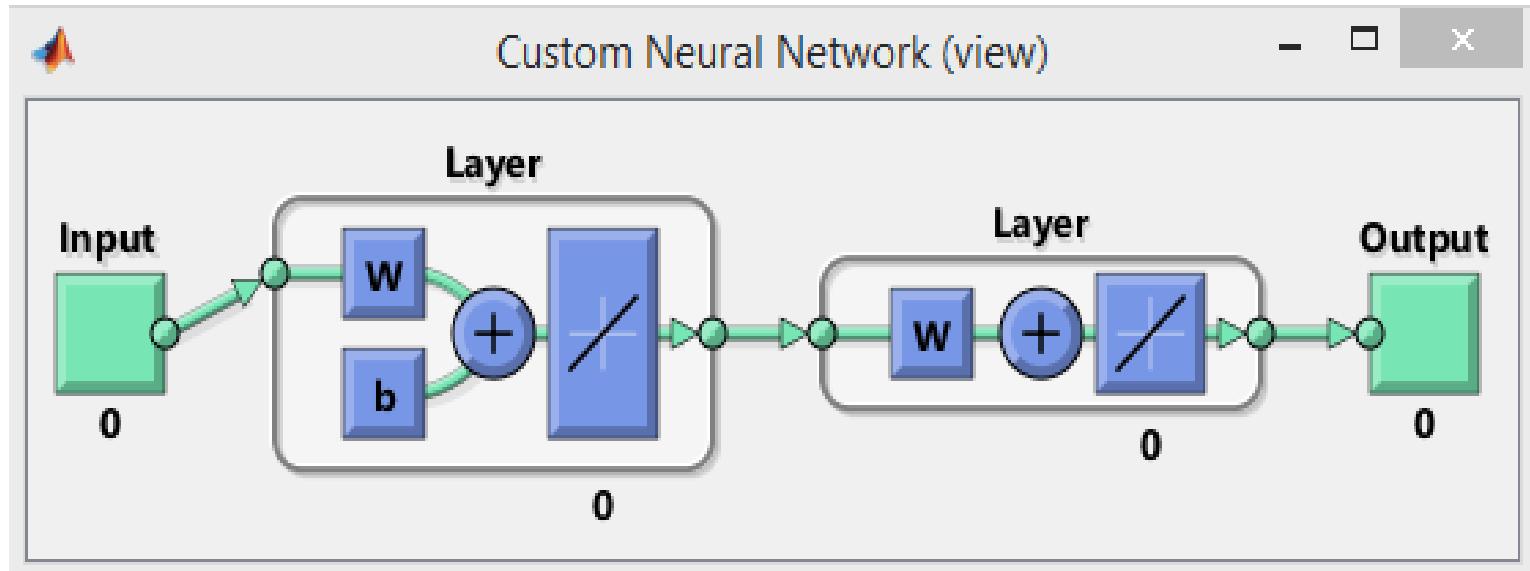


```
net.adaptFcn  
net.initFcn  
net.performFcn
```

```
net.inputs{1}  
net.layers{1},  
net.layers{2}  
net.biases{1}  
net.IW{1,1}, net.IW{2,1},  
net.b{1}
```

```
net.layers{1}.transferFcn = 'tansig';  
net.layers{2}.transferFcn = 'logsig';
```

```
net.layers{1}.size = 5;  
% hidden layer transfer function  
net.layers{1}.transferFcn = 'logsig';  
view(net)
```



# Train net and calculate neuron output

```
% initial network response without training  
initial_output = net(inputs)  
  
% network training  
net.trainFcn = 'trainlm';  
net.performFcn = 'mse';  
net = train(net,inputs,outputs);  
  
% network response after training  
final_output = net(inputs)
```

# Classification of linearly separable data with a perceptron

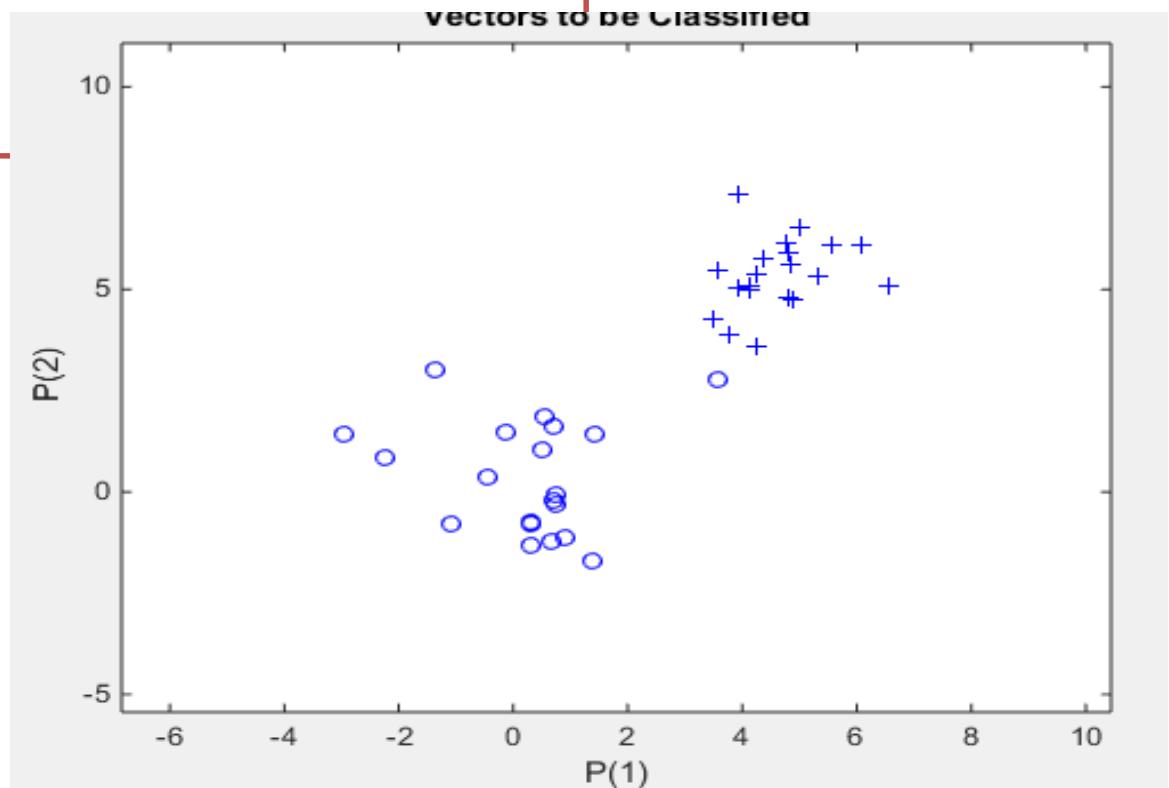
Two clusters of data, belonging to two classes, are defined in a 2-dimensional input space. Classes are linearly separable. The task is to construct a Perceptron for the classification of data

1. Define input and output data
2. Create and train perceptron
3. Plot decision boundary

plotpv

Plot perceptron input/target vectors

```
close all, clear all, clc, format compact  
% number of samples of each class  
N = 20;  
offset = 5; % offset for second class  
x = [randn(2,N) randn(2,N)+offset]; % inputs  
y = [zeros(1,N) ones(1,N)]; % outputs  
figure(1)  
plotpv(x,y);
```



Create and train perceptron

**perceptron(hardlimitTF,perceptronLF)**

```
net = perceptron;
```

```
net = train(net,x,y);
```

```
view(net);
```

Plot decision boundary

```
figure(1)
```

```
plotpc(net.IW{1},net.b{1});
```

### Vectors to be Classified

