8 PUZZLE PROGRAM:

import copy

```
# Importing the heap methods from the python
# library for the Priority Queue
from heapq import heappush, heappop
# This particular var can be changed to transform
# the program from 8 puzzle(n=3) into 15
# puzzle(n=4) and so on ...
n = 3
# bottom, left, top, right
rows = [1, 0, -1, 0]
cols = [0, -1, 0, 1]
# creating a class for the Priority Queue
class priorityQueue:
  # Constructor for initializing a
  # Priority Queue
  def __init__(self):
    self.heap = []
  # Inserting a new key 'key'
  def push(self, key):
    heappush(self.heap, key)
```

```
# funct to remove the element that is minimum,
  # from the Priority Queue
  def pop(self):
    return heappop(self.heap)
  # funct to check if the Queue is empty or not
  def empty(self):
    if not self.heap:
      return True
    else:
      return False
# structure of the node
class nodes:
  def __init__(self, parent, mats, empty_tile_posi,
         costs, levels):
    # This will store the parent node to the
    # current node And helps in tracing the
    # path when the solution is visible
    self.parent = parent
    # Useful for Storing the matrix
    self.mats = mats
    # useful for Storing the position where the
    # empty space tile is already existing in the matrix
    self.empty_tile_posi = empty_tile_posi
```

```
self.costs = costs
    # Store no. of moves so far
    self.levels = levels
  # This func is used in order to form the
  # priority queue based on
  # the costs var of objects
  def __lt__(self, nxt):
    return self.costs < nxt.costs
# method to calc. the no. of
# misplaced tiles, that is the no. of non-blank
# tiles not in their final posi
def calculateCosts(mats, final) -> int:
  count = 0
  for i in range(n):
    for j in range(n):
      if ((mats[i][j]) and
         (mats[i][j] != final[i][j])):
         count += 1
  return count
def newNodes(mats, empty_tile_posi, new_empty_tile_posi,
      levels, parent, final) -> nodes:
```

Store no. of misplaced tiles

```
# Copying data from the parent matrixes to the present matrixes
  new mats = copy.deepcopy(mats)
  # Moving the tile by 1 position
  x1 = empty_tile_posi[0]
  y1 = empty_tile_posi[1]
  x2 = new_empty_tile_posi[0]
  y2 = new_empty_tile_posi[1]
  new\_mats[x1][y1], new\_mats[x2][y2] = new\_mats[x2][y2], new\_mats[x1][y1]
  # Setting the no. of misplaced tiles
  costs = calculateCosts(new_mats, final)
  new_nodes = nodes(parent, new_mats, new_empty_tile_posi,
           costs, levels)
  return new_nodes
# func to print the N by N matrix
def printMatsrix(mats):
  for i in range(n):
    for j in range(n):
      print("%d " % (mats[i][j]), end = " ")
    print()
# func to know if (x, y) is a valid or invalid
# matrix coordinates
```

```
def isSafe(x, y):
  return x \ge 0 and x < n and y \ge 0 and y < n
# Printing the path from the root node to the final node
def printPath(root):
  if root == None:
    return
  printPath(root.parent)
  printMatsrix(root.mats)
  print()
# method for solving N*N - 1 puzzle algo
# by utilizing the Branch and Bound technique. empty_tile_posi is
# the blank tile position initially.
def solve(initial, empty_tile_posi, final):
  # Creating a priority queue for storing the live
  # nodes of the search tree
  pq = priorityQueue()
  # Creating the root node
  costs = calculateCosts(initial, final)
  root = nodes(None, initial,
         empty_tile_posi, costs, 0)
```

Adding root to the list of live nodes

```
pq.push(root)
# Discovering a live node with min. costs,
# and adding its children to the list of live
# nodes and finally deleting it from
# the list.
while not pq.empty():
  # Finding a live node with min. estimatsed
  # costs and deleting it form the list of the
  # live nodes
  minimum = pq.pop()
  # If the min. is ans node
  if minimum.costs == 0:
    # Printing the path from the root to
    # destination;
    printPath(minimum)
    return
  # Generating all feasible children
  for i in range(n):
    new_tile_posi = [
       minimum.empty_tile_posi[0] + rows[i],
       minimum.empty_tile_posi[1] + cols[i], ]
    if isSafe(new_tile_posi[0], new_tile_posi[1]):
```

```
# Creating a child node
         child = newNodes(minimum.mats,
                  minimum.empty_tile_posi,
                  new_tile_posi,
                  minimum.levels + 1,
                  minimum, final,)
         # Adding the child to the list of live nodes
         pq.push(child)
# Main Code
# Initial configuration
# Value 0 is taken here as an empty space
initial = [ [ 1, 2, 3 ],
      [5,6,0],
      [7, 8, 4]]
# Final configuration that can be solved
# Value 0 is taken as an empty space
final = [[1, 2, 3],
    [5, 8, 6],
    [0,7,4]]
# Blank tile coordinates in the
# initial configuration
empty_tile_posi = [1, 2]
# Method call for solving the puzzle
```

solve(initial, empty_tile_posi, final)

```
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```

8QUEENS:

```
# Taking number of queens as input from user
print ("Enter the number of queens")
N = int(input())
# here we create a chessboard
# NxN matrix with all elements set to 0
board = [[0]*N for _ in range(N)]
def attack(i, j):
  #checking vertically and horizontally
  for k in range(0,N):
    if board[i][k]==1 or board[k][j]==1:
       return True
  #checking diagonally
  for k in range(0,N):
    for I in range(0,N):
      if (k+l==i+j) or (k-l==i-j):
         if board[k][l]==1:
           return True
  return False
def N_queens(n):
```

```
if n==0:
       return True
   for i in range(0,N):
       for j in range(0,N):
          if (not(attack(i,j))) and (board[i][j]!=1):
              board[i][j] = 1
              if N_queens(n-1)==True:
                 return True
              board[i][j] = 0
   return False
N_queens(N)
for i in board:
   print (i)
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Python 3.10.7 (tags/vs.10.7-teccbis), Sep 5 2022, 14:08:36) [MSC v.1933 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
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```

Tower of Hanoi:

```
def TowerOfHanoi(n , source, destination, auxiliary):
   if n==1:
```

print ("Move disk 1 from source", source, "to destination", destination) return

TowerOfHanoi(n-1, source, auxiliary, destination)

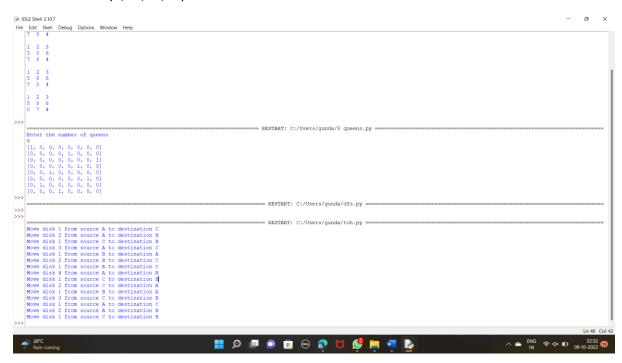
print ("Move disk",n,"from source",source,"to destination",destination)

TowerOfHanoi(n-1, auxiliary, destination, source)

Driver code

n = 4

TowerOfHanoi(n,'A','B','C')



Water jug:

This function is used to initialize the

dictionary elements with a default value.

from collections import defaultdict

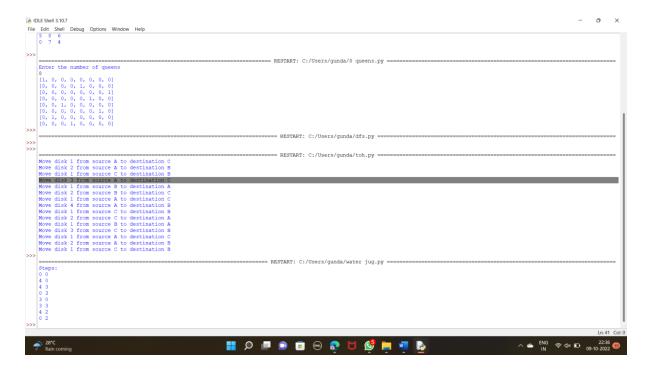
jug1 and jug2 contain the value

for max capacity in respective jugs

and aim is the amount of water to be measured.

```
jug1, jug2, aim = 4, 3, 2
# Initialize dictionary with
# default value as false.
visited = defaultdict(lambda: False)
# Recursive function which prints the
# intermediate steps to reach the final
# solution and return boolean value
# (True if solution is possible, otherwise False).
# amt1 and amt2 are the amount of water present
# in both jugs at a certain point of time.
def waterJugSolver(amt1, amt2):
       # Checks for our goal and
       # returns true if achieved.
       if (amt1 == aim and amt2 == 0) or (amt2 == aim and amt1 == 0):
               print(amt1, amt2)
               return True
       # Checks if we have already visited the
       # combination or not. If not, then it proceeds further.
       if visited[(amt1, amt2)] == False:
               print(amt1, amt2)
               # Changes the boolean value of
               # the combination as it is visited.
               visited[(amt1, amt2)] = True
```

```
# Check for all the 6 possibilities and
              # see if a solution is found in any one of them.
              return (waterJugSolver(0, amt2) or
                             waterJugSolver(amt1, 0) or
                             waterJugSolver(jug1, amt2) or
                             waterJugSolver(amt1, jug2) or
                             waterJugSolver(amt1 + min(amt2, (jug1-amt1)),
                             amt2 - min(amt2, (jug1-amt1))) or
                             waterJugSolver(amt1 - min(amt1, (jug2-amt2)),
                             amt2 + min(amt1, (jug2-amt2))))
       # Return False if the combination is
       # already visited to avoid repetition otherwise
       # recursion will enter an infinite loop.
       else:
              return False
print("Steps: ")
# Call the function and pass the
# initial amount of water present in both jugs.
waterJugSolver(0, 0)
```



Greedy first search:

```
from queue import PriorityQueue
```

```
v = 14
graph = [[] for i in range(v)]
# Function For Implementing Best First Search
# Gives output path having lowest cost
```

```
def best_first_search(actual_Src, target, n):
    visited = [False] * n
    pq = PriorityQueue()
    pq.put((0, actual_Src))
    visited[actual_Src] = True

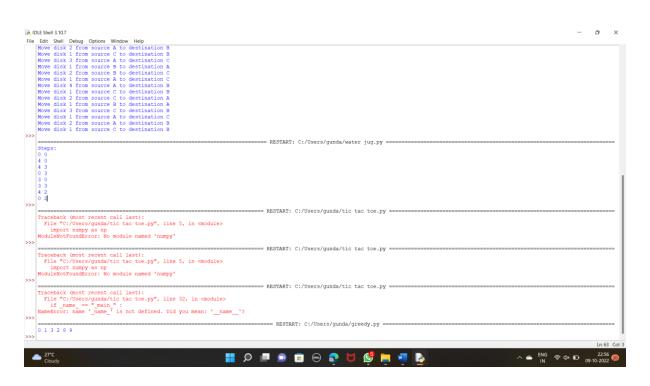
    while pq.empty() == False:
        u = pq.get()[1]
```

```
# Displaying the path having lowest cost
              print(u, end=" ")
              if u == target:
                      break
              for v, c in graph[u]:
                      if visited[v] == False:
                             visited[v] = True
                             pq.put((c, v))
       print()
# Function for adding edges to graph
def addedge(x, y, cost):
       graph[x].append((y, cost))
       graph[y].append((x, cost))
# The nodes shown in above example(by alphabets) are
# implemented using integers addedge(x,y,cost);
addedge(0, 1, 3)
addedge(0, 2, 6)
addedge(0, 3, 5)
addedge(1, 4, 9)
addedge(1, 5, 8)
addedge(2, 6, 12)
addedge(2, 7, 14)
addedge(3, 8, 7)
```

```
addedge(8, 9, 5)
addedge(8, 10, 6)
addedge(9, 11, 1)
addedge(9, 12, 10)
addedge(9, 13, 2)

source = 0
target = 9
best_first_search(source, target, v)
```

This code is contributed by Jyotheeswar Ganne



Dfs:

Python program to print DFS traversal for complete graph from collections import defaultdict

```
# This class represents a directed graph using adjacency
# list representation
class Graph:
       # Constructor
       def __init__(self):
               # default dictionary to store graph
               self.graph = defaultdict(list)
       # function to add an edge to graph
       def addEdge(self,u,v):
               self.graph[u].append(v)
       # A function used by DFS
       def DFSUtil(self, v, visited):
               # Mark the current node as visited and print it
               visited[v]= True
               print v,
               # Recur for all the vertices adjacent to
               # this vertex
               for i in self.graph[v]:
                       if visited[i] == False:
                              self.DFSUtil(i, visited)
```

```
# The function to do DFS traversal. It uses
       # recursive DFSUtil()
       def DFS(self):
               V = len(self.graph) #total vertices
               # Mark all the vertices as not visited
               visited =[False]*(V)
               # Call the recursive helper function to print
               # DFS traversal starting from all vertices one
               # by one
               for i in range(V):
                       if visited[i] == False:
                              self.DFSUtil(i, visited)
# Driver code
# Create a graph given in the above diagram
g = Graph()
g.addEdge(0, 1)
g.addEdge(0, 2)
g.addEdge(1, 2)
g.addEdge(2, 0)
g.addEdge(2, 3)
g.addEdge(3, 3)
print "Following is Depth First Traversal"
g.DFS()
```

```
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```

Map colouring:

```
# Python3 program for the above approach

# Number of vertices in the graph

# define 4 4

# check if the colored

# graph is safe or not

def isSafe(graph, color):

# check for every edge
for i in range(4):
    for j in range(i + 1, 4):
        if (graph[i][j] and color[j] == color[i]):
```

return False

return True

```
#/* This function solves the m Coloring
# problem using recursion. It returns
# false if the m colours cannot be assigned,
# otherwise, return true and prints
# assignments of colours to all vertices.
# Please note that there may be more than
# one solutions, this function prints one
# of the feasible solutions.*/
def graphColoring(graph, m, i, color):
       # if current index reached end
       if (i == 4):
               # if coloring is safe
               if (isSafe(graph, color)):
                      # Print the solution
                       printSolution(color)
                       return True
               return False
       # Assign each color from 1 to m
       for j in range(1, m + 1):
               color[i] = j
```

```
# Recur of the rest vertices
               if (graphColoring(graph, m, i + 1, color)):
                       return True
               color[i] = 0
        return False
# /* A utility function to print solution */
def printSolution(color):
       print("Solution Exists:" "Following are the assigned colors ")
       for i in range(4):
               print(color[i], end=" ")
# Driver code
if __name__ == '__main__':
       #/* Create following graph and
       # test whether it is 3 colorable
       # (3)---(2)
       # | / |
       # | / |
       # | / |
       # (0)---(1)
       # */
       graph = [
               [0, 1, 1, 1],
```

```
[1, 0, 1, 0],
        [1, 1, 0, 1],
        [1, 0, 1, 0],
]

m = 3 # Number of colors

# Initialize all color values as 0.
# This initialization is needed
# correct functioning of isSafe()
color = [0 for i in range(4)]

# Function call
if (not graphColoring(graph, m, 0, color)):
        print("Solution does not exist")
```

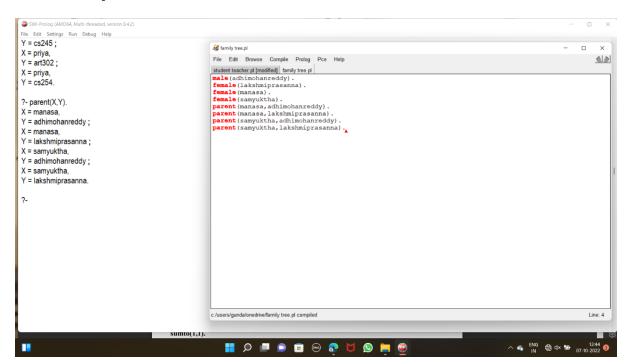


Prolog programms:

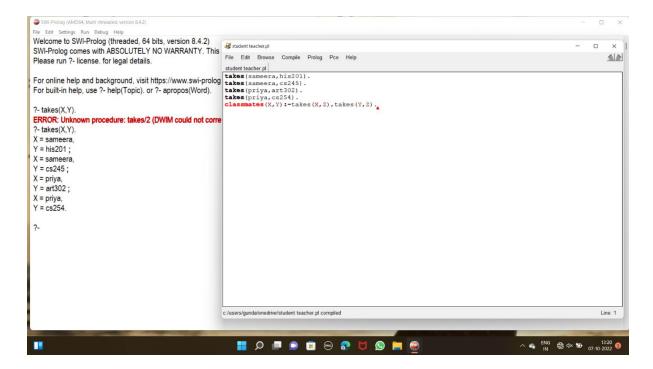
Planet db:

```
File Edit Settings Run Debug Help
% c:/users/gunda/onedrive/planet db compiled 0.00 sec, 0 c
?- orbits(A,B).
                                                                                                                                                                                                                                                                                                                                  File Edit Browse Compile Prolog Pce Help
A = mercury,
                                                                                                           File Edit Browse Comple Prolog Pce Help student teacher pl [modified] family tree pl planet db pl orbits (mercury, sun). orbits (venus, sun). orbits (mars, sun). orbits (mars, sun). orbits (moon, earth). orbits (phobos, mars). orbits (deimos, mars). orbits (deimos, mars). orbits (deimos, mars). orbits (deimos, to be supplement (P) : orbits (P, sun). satellite(S) : orbits (P, P), planet (P).
B = sun;
A = venus
B = sun ;
A = earth,
B = sun;
A = mars,
B = sun;
A = moon
B = earth;
A = phobos
B = mars;
 A = deimos,
B = mars.
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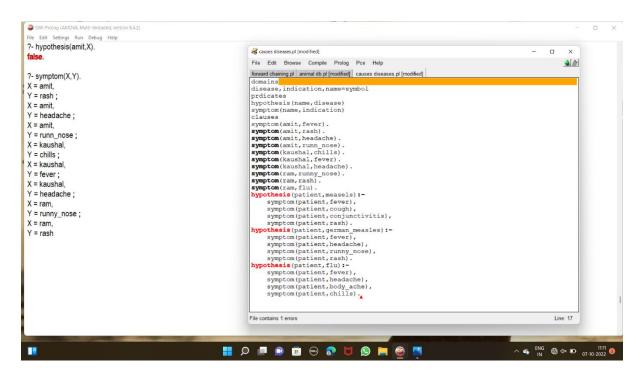
Family tree:



Student teacher:



Causes diseases:



Animal db:

```
SWI-Prolog (AMD64, Multi-threaded, version 8.4.2)
File Edit Settings Run Debug Help ?- animal(A,B,C,D).
                                                                                                                                animal db.pl
 A = mammal,
                                                                                                                                File Edit Browse Compile Prolog Pce Help
                                                                                                                                                                                                                                                                                                                 44
B = tiger.
                                                                                                                               Fine tot browse Compne Protog Pce Help

Toward chaining pil animat db pl

animal (mammal, tiger, carnivore, ustripes).

animal (mammal, tiger, carnivore, ustripes).

animal (mammal, rebra, herbivore, stripes).

animal (tiger, septra, herbivore, stripes).

animal (reptile, snake, carnivore, long).

animal (reptile, slake, carnivore, long).
C = carnivore,
D = stripes;
A = mammal,
B = lion,
C = carnivore,
D = ugly;
A = mammal
B = hyena,
C = carnivore,
D = mane;
A = mammal,
B = zebra,
C = herbivore,
D = stripes;
A = bird,
B = eagle
C = carnivore,
D = large;
A = bird,
B = sparrow,
C = scavenger,
D = small;
A = reptile
B = snake
C = carnivore,
                                                                                                                              c:/users/gunda/onedrive/animal db.pl compiled
                                                                                                                                                                                                                                                                                                             Line: 1
D = long
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```

Forward chain:

