

Security Analytics

Assignment 3

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Problem 1: Security Basics

- **1. Threat Model:** The security of any system is measured with respect to the adversarial goals and capabilities that it is designed to defend against the system's threat model. Therefore, a threat model is a characterization of threats, a system deals with.
- **2. Relationship between a vulnerability and a compromise:** Vulnerability is a weakness in an information system, system security procedures, internal controls, or implementation that could be exploited or triggered by a threat source. Compromise means when an attack is successful in putting the system at risk. Therefore, a system will be compromised if the vulnerabilities in the system are exploited by an attacker successfully.
- **3. Security Model:** A security model is a framework in which a security policy is developed. The development of this security policy is geared to a particular setting or instance of a policy.
- **4. CIA:**
 - **Confidentiality** ensures that computer related assets are accessed by only authorized parties.
 - **Integrity** requires that computer system assets and transmitted information be capable of modification only by authorized parties.
 - **Availability** implies the degree to which data or systems are accessible and in functioning condition.
- **5.** Attacks on Integrity is with respect to the model outputs. Attacks are performed to induce model behavior as chosen by adversary.
Attacks on confidentiality is with respect to the model and data. If adversary is an untrusted user, and tries to extract the model parameters which is confidential information or if the model owner is untrusted, then there can be chances of theft of user's private data.
- **6.**
 - (a) attacks per day = 500
 - (b) logins per day = 10000
 - (c) $P(\text{attack}) = 500/10000 = 0.05$
 - (d) $P(\text{!attack}) = 1 - p(\text{attack}) = 1 - 0.05 = 0.95$

- (e) $P(\text{flag}=\text{attack}) = 0.90$
- (f) $P(\text{flag}=\text{!attack}) = 1 - P(\text{flag}=\text{attack}) = 0.10$
- (g) $P(\text{flag}) = p(\text{flag}/\text{attack}) * p(\text{attack}) + p(\text{flag}/\text{!attack}) * p(\text{!attack}) = (0.90 * 0.05) + (0.10 * 0.95) = 0.14$
- (h) true positives = $p(\text{attack}=\text{flag}) = \frac{p(\text{flag}|\text{attack}) * p(\text{attack})}{p(\text{flag})} = 0.90*0.05/0.14 = 0.3214$
- (i) false positives = $1 - \text{true positives} = 1 - 0.3214 = 0.6786$
- (j) Why is this number of false positives acceptable or unacceptable? Yes the false positive is acceptable as only 67% of the negative samples are marked as positive that will require manual processing.

Problem 2

1. Score function F can be written as $F = (2 * a1 + a2 - a3)$. As the value of $a1$ will have twice the importance of $a2$ in calculating score. Importance of $a3$ is as of $a2$, but correlates to SPAM negatively.

2.

	a1	a2	a3	Spam?	Score
M1	2	1	1	Spam	4
M2	1	3	4	Not Spam	1
M3	4	1	0	Spam	9
M4	2	4	6	Spam	2
M5	2	5	2	Not Spam	7
M6	1	3	3	Not Spam	2
M7	4	2	2	Not Spam	8
M8	1	11	10	Spam	3
M9	1	14	9	Spam	7
M10	3	2	6	Not Spam	2

Given Table and Score Calculation.

- 3. Given threshold $(t) = 3$;
- False Positive Rate = $\frac{FP}{ActuallyNotSpam} = \frac{2}{5}$
- True Positive Rate = $\frac{TP}{ActuallySpam} = \frac{4}{5}$
- False Negative Rate = $\frac{FN}{ActuallySpam} = \frac{1}{5}$
- True Negative Rate = $\frac{TN}{ActuallyNotSpam} = \frac{3}{5}$

```

In [6]: y=[5/5,5/5,5/5,5/5,4/5,3/5,2/5,2/5,2/5,1/5,1/5,0/5] # TPR

In [7]: x=[5/5,5/5,5/5,4/5,2/5,2/5,2/5,2/5,2/5,1/5,0/5,0/5] #FPR

In [8]: z=[0,1,2,3,4,5,6,7,8,9,10] # threshold values

In [9]: import matplotlib.pyplot as plt

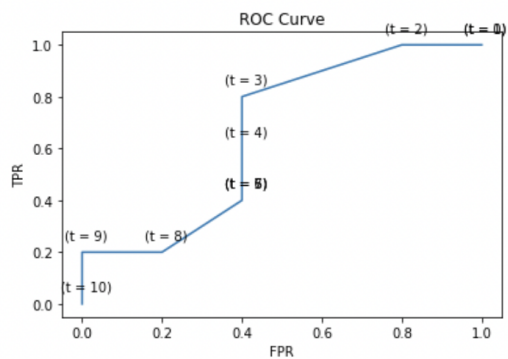
In [19]: plt.plot(x,y)
k=0;
for a,b in zip(x,y):

    label = "(t = "+str(z[k])+")"
    k+=1

    plt.annotate(label, # this is the text
                 (a,b), # these are the coordinates to position the label
                 textcoords="offset points", # how to position the text
                 xytext=(3,10), # distance from text to points (x,y)
                 ha='center') # horizontal alignment can be left, right c

plt.xlabel('FPR')
plt.ylabel('TPR')
plt.title('ROC Curve')
#plt.show()
plt.savefig('output.png', dpi=300, bbox_inches='tight')

```



4.

Problem 3

- 1. The size of convoluted matrix

$$= ((InputImageSize - FilterSize + 2 * Padding) / Stride) + 1$$

$$= ((28 - 7 + 2 * 0) / 1) + 1$$

$$= 22$$
- 2. The Output Matrix will be

4	6	5
6	6	8
9	8	8

Problem 4

```
In [1]: # Imports.
import random
import network.network as Network
import network.mnist_loader as mnist_loader
import pickle
import matplotlib.pyplot as plt
import numpy as np

# Set the random seed. DO NOT CHANGE THIS!
seedVal = 41
random.seed(seedVal)
np.random.seed(seedVal)

%matplotlib inline
```

Use a pre-trained network. It has been saved as a pickle file. Load the model, and continue. The network has only one hidden layer of 30 units, 784 input units (MNIST images are $28 \times 28 = 784$ pixels large), and 10 output units. All the activations are sigmoidal.

```
In [2]: # Load the pre-trained model.
with open('network/trained_network.pkl', 'rb') as f:
    u = pickle.Unpickler(f)
    u.encoding = 'latin1'
    net = u.load()

# Helpful function to load the MNIST data.
training_data, validation_data, test_data = mnist_loader.load_data_wrapper()
```

The neural network is pretrained, so it should already be set up to predict characters. Run `predict(n)` to evaluate the n^{th} digit in the test set using the network. You should see that even this relatively simple network works really well (~97% accuracy). The output of the network is a one-hot vector indicating the network's predictions:

```
In [3]: def predict(n):
# Get the data from the test set
x = test_data[n][0]

# Print the prediction of the network
print('Network output: \n' + str(np.round(net.feedforward(x), 2)) + '\n')
print('Network prediction: ' + str(np.argmax(net.feedforward(x))) + '\n')
print('Actual image: ')

# Draw the image
plt.imshow(x.reshape((28,28)), cmap='Greys')

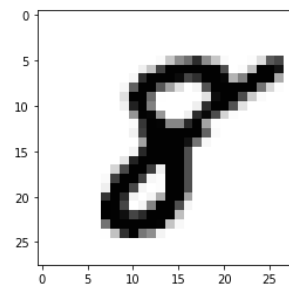
# Replace the argument with any number between 0 and 9999
predict(8384)
```

Network output:

```
[[0.]
 [0.]
 [0.]
 [0.]
 [0.]
 [0.]
 [0.]
 [0.]
 [0.]
 [1.]
 [0.]]
```

Network prediction: 8

Actual image:



To actually generate adversarial examples we solve a minimization problem. We do this by setting a "goal" label called \vec{y}_{goal} (for instance, if we wanted the network to think the adversarial image is an 8, then we would choose \vec{y}_{goal} to be a one-hot vector with the eighth entry being 1). Now we define a cost function:

$$C = \frac{1}{2} \|\vec{y}_{goal} - \hat{y}(\vec{x})\|_2^2$$

where $\|\cdot\|_2^2$ is the squared Euclidean norm and \hat{y} is the network's output. It is a function of \vec{x} , the input image to the network, so we write $\hat{y}(\vec{x})$. Our goal is to find an \vec{x} such that C is minimized. Hopefully this makes sense, because if we find an image \vec{x} that minimizes C then that means the output of the network when given \vec{x} is close to our desired output, \vec{y}_{goal} . So in full mathy language, our optimization problem is:

$$\arg \min_{\vec{x}} C(\vec{x})$$

that is, find the \vec{x} that minimizes the cost C .

To actually do this we can do gradient descent on C . Start with an initially random vector \vec{x} and take steps (changing \vec{x}) gradually in the direction opposite of the gradient $\nabla_{\vec{x}} C$. To actually get these derivatives we can perform backpropagation on the network. In contrast to training a network, where we perform gradient descent on the weights and biases, when we create adversarial examples we hold the weights and biases constant (because we don't want to change the network!), and change the inputs to our network.

Helper functions to evaluate the non-linearity and it's derivative:

```
In [4]: def sigmoid(z):
        """The sigmoid function."""
        return 1.0/(1.0+np.exp(-z))

def sigmoid_prime(z):
    """Derivative of the sigmoid function."""
    return sigmoid(z)*(1-sigmoid(z))
```

Also, a function to find the gradient derivatives of the cost function, $\nabla_{\vec{x}} C$ with respect to the input \vec{x} , with a goal label of \vec{y}_{goal} . (Don't worry too much about the implementation, just know it calculates derivatives).

```
In [5]: def input_derivative(net, x, y):
        """ Calculate derivatives wrt the inputs"""
        nabla_b = [np.zeros(b.shape) for b in net.biases]
        nabla_w = [np.zeros(w.shape) for w in net.weights]

        # feedforward
        activation = x
        activations = [x] # list to store all the activations, layer by layer
        zs = [] # list to store all the z vectors, layer by layer
        for b, w in zip(net.biases, net.weights):
            z = np.dot(w, activation)+b
            zs.append(z)
            activation = sigmoid(z)
            activations.append(activation)

        # backward pass
        delta = net.cost_derivative(activations[-1], y) * \
            sigmoid_prime(zs[-1])
        nabla_b[-1] = delta
        nabla_w[-1] = np.dot(delta, activations[-2].transpose())

        for l in range(2, net.num_layers):
            z = zs[-l]
            sp = sigmoid_prime(z)
            delta = np.dot(net.weights[-l+1].transpose(), delta) * sp
            nabla_b[-l] = delta
            nabla_w[-l] = np.dot(delta, activations[-l-1].transpose())

        # Return derivatives WRT to input
        return net.weights[0].T.dot(delta)
```

The actual function that generates adversarial examples and a wrapper function:

(a) Non Targeted Attack

```

In [6]: def nonTargetedAdversarial(net, n, steps, eta):
        """
        net : network object
              neural network instance to use
        n : integer
            our goal label (just an int, the function transforms it into a one-hot vector)
        steps : integer
            number of steps for gradient descent
        eta : float
            step size for gradient descent
        """

        ##### Enter your code below #####

        # Set the goal output
        goal = np.zeros((10,1))
        goal[n] = 1

        # Create a random image to initialize gradient descent with
        x = np.random.normal(.5, .3, (784, 1))

        # Gradient descent on the input
        for i in range(steps):
            # Calculate the derivative
            d = input_derivative(net,x,goal)

            # The GD update on x
            x -= eta*d;

        return x

# Wrapper function
def generate(n):
    """
    n : integer
        goal label (not a one hot vector)
    """

    ##### Enter your code below #####

    # Find the vector x with the above function that you just wrote.

    a=nonTargetedAdversarial(net,n,1000,0.01)

    # Pass the generated image (vector) to the neural network. Perform a forward pass, and get the prediction.
    x = net.feedforward(a)

    print('Network Output: \n' + str(np.round(x,2)) + '\n')

    print('Network Prediction: ' + str(np.argmax(x)) + '\n')

    print('Adversarial Example: ')

    plt.imshow(a.reshape(28,28), cmap='Greys')

```

Now let's generate some adversarial examples! Use the function provided to mess around with the neural network. (For some inputs gradient descent doesn't always converge; 0 and 5 seem to work pretty well though. I suspect convergence is very highly dependent on our choice of random initial \vec{x} . We'll see later in the notebook if we force the adversarial example to "look like" a handwritten digit, convergence is much more likely. In a sense we will be adding regularization to our generation process).

```

In [7]: generate(2)

```

Network Output:

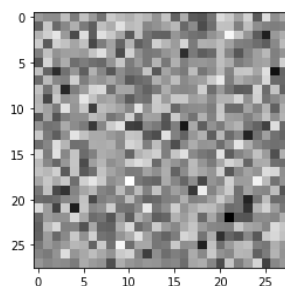
```

[[0.  ]
 [0.  ]
 [0.95]
 [0.  ]
 [0.  ]
 [0.  ]
 [0.  ]
 [0.  ]
 [0.  ]
 [0.  ]
 [0.  ]]

```

Network Prediction: 2

Adversarial Example:



(b) Targeted Attack(s)

Sweet! We've just managed to create an image that looks utterly meaningless to a human, but the neural network thinks is a '5' with very high certainty. We can actually take this a bit further. Let's

generate an image that looks like one number, but the neural network is certain is another. To do this we will modify our cost function a bit. Instead of just optimizing the input image, \vec{x} , to get a desired output label, we'll also optimize the input to look like a certain image, \vec{x}_{target} , at the same time. Our new cost function will be

$$C = \|\vec{y}_{goal} - y_{hat}(\vec{x})\|_2^2 + \lambda \|\vec{x} - \vec{x}_{target}\|_2^2$$

The added term tells us the distance from our \vec{x} and some \vec{x}_{target} (which is the image we want our adversarial example to look like). Because we want to minimize C , we also want to minimize the distance between our adversarial example and this image. The λ is hyperparameter that we can tune; it determines which is more important: optimizing for the desired output or optimizing for an image that looks like \vec{x}_{target} .

If you are familiar with ridge regularization, the above cost function might look suspiciously like the ridge regression cost function. In fact, we can view this generation method as giving our model a prior, centered on our target image.

Here is a function that implements optimizing the modified cost function, called `sneaky_adversarial` (because it is very sneaky). Note that the only difference between this function and `adversarial` is an additional term on the gradient descent update for the regularization term:

```
In [ ]: # Probably include a question on why not generate an image of 5, instead of having to find the vector x using
# gradient based optimization methods. (as in the above case)
```

```
In [8]: def targetedAdversarial(net, n, x_target, steps, eta, lam=.05):
    """
    net : network object
    neural network instance to use
    n : integer
    our goal label (just an int, the function transforms it into a one-hot vector)
    x_target : numpy vector
    our goal image for the adversarial example
    steps : integer
    number of steps for gradient descent
    eta : float
    step size for gradient descent
    lam : float
    lambda, our regularization parameter. Default is .05
    """

    # Set the goal output
    goal = np.zeros((10, 1))
    goal[n] = 1

    # Create a random image to initialize gradient descent with
    x = np.random.normal(.5, .3, (784, 1))

    # Gradient descent on the input
    for i in range(steps):

        # Calculate the derivative
        d = input_derivative(net,x,goal)

        # The GD update on x, with an added penalty to the cost function
        x -= eta*(d + lam*(x-x_target))

    return x

# Wrapper function
def generate_advSample(n, m):
    """
    n: int 0-9, the target number to match
    m: index of example image to use (from the test set)
    """

    # Find random instance of m in test set
    idx = np.random.randint(0,8000)
    while test_data[idx][1] != m:
        idx += 1

    # Hardcode the parameters for the wrapper function
    a = targetedAdversarial(net, n, test_data[idx][0], 100, 1)
    x = np.round(net.feedforward(a), 2)

    print('\nWhat we want our adversarial example to look like: ')
    plt.imshow(test_data[idx][0].reshape((28,28)), cmap='Greys')
    plt.show()

    print('\n')

    print('Adversarial Example: ')

    plt.imshow(a.reshape(28,28), cmap='Greys')
    plt.show()

    print('Network Prediction: ' + str(np.argmax(x)) + '\n')

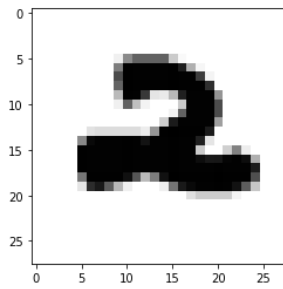
    print('Network Output: \n' + str(x) + '\n')

    return a
```

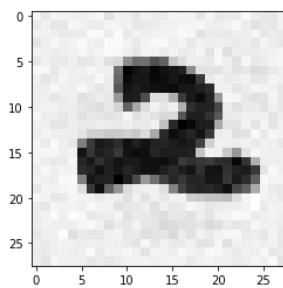
Play around with this function to make "sneaky" adversarial examples! (Again, some numbers converge better than others... try 0, 2, 3, 5, 6, or 8 as a target label. 1, 4, 7, and 9 still don't work as well... no idea why... We get more numbers that converge because we've added regularization term to our cost function. Perhaps changing λ will get more to converge?)

```
In [9]: # generate_advSample(target_label, target digit)
adv_ex = generate_advSample(8, 2)
```

What we want our adversarial example to look like:



Adversarial Example:



Network Prediction: 8

Network Output:

```
[[0. ]
 [0. ]
 [0.01]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [1. ]
 [0. ]]
```

(c) Protection against adversarial attacks

Awesome! We've just created images that trick neural networks. The next question we could ask is whether or not we could protect against these kinds of attacks. If you look closely at the original images and the adversarial examples you'll see that the adversarial examples have some sort of grey tinged background.

So how could we protect against these adversarial attacks? One very simple way would be to use binary thresholding. Set a pixel as completely black or completely white depending on a threshold. This should remove the "noise" that's always present in the adversarial images. Let's see if it works:


```
In [10]: def simple_defense(n, m):
        """
        n: int 0-9, the target number to match
        m: index of example image to use (from the test set)
        """

        # Generate an adversarial sample.
        x = generate_advSample(n, m)

        # Perform binary thresholding on the generated sample. You can choose the threshold as 0.5.

        x = (x > .5).astype(float)
        print("With binary thresholding: ")

        # Plot a grayscale image of the binarized generated sample.
        plt.imshow(x.reshape(28,28), cmap="Greys")
        plt.show()

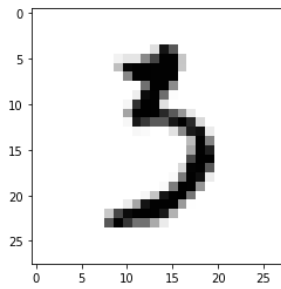
        binary_activations = net.feedforward(x)
        binary_prediction = np.argmax(net.feedforward(x))

        # Print the network's predictions.
        print("Prediction with binary thresholding: " + str(binary_prediction) + '\n')

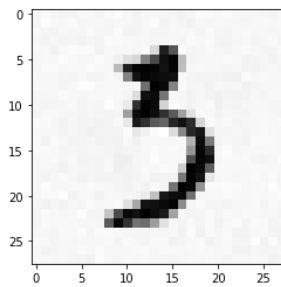
        # The output of the network.
        print("Network output: ")
        print( str(np.round(binary_activations,2)) )
```

```
In [16]: # binary_thresholding(target digit, actual digit)
simple_defense(0, 3)
```

What we want our adversarial example to look like:



Adversarial Example:

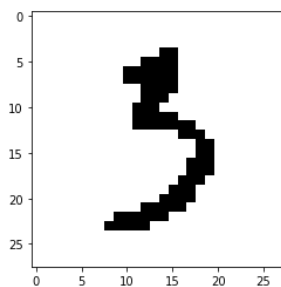


Network Prediction: 0

Network Output:

```
[[0.98]
 [0. ]
 [0. ]
 [0.02]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]]
```

With binary thresholding:



Prediction with binary thresholding: 3

Network output:

```
[[0. ]
 [0. ]
 [0. ]
 [0.18]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]
 [0. ]]
```

In []:

Looks like it works pretty well! However, note that most adversarial attacks, especially on convolutional neural networks trained on massive full color image sets such as imagenet, can't be defended against by a simple binary threshold.

Problem 5

```
In [2]: # Imports
import warnings
warnings.filterwarnings("ignore", category=DeprecationWarning)
import keras
import random
import numpy as np
import matplotlib.pyplot as plt

from keras.datasets import mnist
from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten, InputLayer
from keras.layers import Conv2D, MaxPooling2D
from keras import backend as K
from tensorflow.keras import layers

from art.attacks.evasion import FastGradientMethod, BasicIterativeMethod, UniversalPerturbation, SaliencyMapMethod
#from art.attacks import FastGradientMethod, BasicIterativeMethod, UniversalPerturbation, SaliencyMapMethod
#from art.classifiers import KerasClassifier
from art.estimators.classification import KerasClassifier

# Set the random seeds. DO NOT CHANGE THIS!
seedVal = 41
random.seed(seedVal)
np.random.seed(seedVal)

# Defining some constants
NUM_CLASSES = 10
BATCH_SIZE = 64
```

Please use only IBM's ART library for this assignment, and not any other libraries.

Setting up things

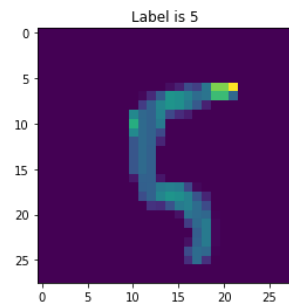
```
In [3]: # Load the MNIST dataset
(x_train, y_train), (x_test, y_test) = mnist.load_data()

# Normalization
x_train = keras.utils.normalize(x_train, axis=1)
x_test = keras.utils.normalize(x_test, axis=1)

# Plot an example image (after normalization) from the train set
plt.title('Label is {}'.format(y_train[100]))
plt.imshow(x_train[100])
plt.show()

# convert class vectors to binary class matrices
y_train = keras.utils.to_categorical(y_train, NUM_CLASSES)
y_test = keras.utils.to_categorical(y_test, NUM_CLASSES)

K.set_image_data_format('channels_first')
x_train = x_train.reshape(x_train.shape[0], 1, 28, 28)
x_test = x_test.reshape(x_test.shape[0], 1, 28, 28)
```



Train CNN based model

You need to complete the following.

```
In [4]: # Define the CNN network architecture.
cnn_based_model = Sequential()
cnn_based_model.add(Conv2D(32, (3, 3), activation='relu', input_shape=(1,28,28), data_format='channels_first'))

# Define the intermediate layers.

cnn_based_model.add(MaxPooling2D((2, 2)))
cnn_based_model.add(Flatten())
cnn_based_model.add(Dense(BATCH_SIZE, activation='relu'))
cnn_based_model.add(Dense(NUM_CLASSES, activation='softmax'))
```

WARNING:tensorflow:From /Users/chandrikamukherjee/opt/anaconda3/envs/cs529/lib/python3.7/site-packages/keras/backend/tensorflow_backend.py:4070: The name tf.nn.max_pool is deprecated. Please use tf.nn.max_pool2d instead.

```
In [5]: # Compile the CNN model.
# compile model
cnn_based_model.compile(loss=keras.losses.categorical_crossentropy,
                        optimizer=keras.optimizers.Adadelta(),
                        metrics=['accuracy'])

cnn_based_classifier = KerasClassifier(model=cnn_based_model, clip_values=(0,1))
cnn_based_classifier.fit(x_train, y_train, nb_epochs=5, batch_size=BATCH_SIZE)

# Get the predictions on the test set.
predictions = cnn_based_model.predict(x_test, batch_size=BATCH_SIZE, verbose=0)

score = cnn_based_model.evaluate(x_test, y_test, verbose=0)

# Compute the accuracy on the test set.
cnn_score = score[1]

print('Test accuracy:', cnn_score)
```

WARNING:tensorflow:From /Users/chandrikamukherjee/opt/anaconda3/envs/cs529/lib/python3.7/site-packages/keras/backend/tensorflow_backend.py:422: The name tf.global_variables is deprecated. Please use tf.compat.v1.global_variables instead.

```
Epoch 1/5
60000/60000 [=====] - 58s 973us/step - loss: 0.2752 - accuracy: 0.9169
Epoch 2/5
60000/60000 [=====] - 60s 997us/step - loss: 0.0957 - accuracy: 0.9718
Epoch 3/5
60000/60000 [=====] - 58s 967us/step - loss: 0.0662 - accuracy: 0.9803
Epoch 4/5
60000/60000 [=====] - 58s 969us/step - loss: 0.0514 - accuracy: 0.9851
Epoch 5/5
60000/60000 [=====] - 58s 966us/step - loss: 0.0417 - accuracy: 0.9872
Test accuracy: 0.9822999835014343
```

Train ANN based model (dense layers only)

You need to complete the following.

```
In [6]: # Define the ANN network architecture.
ann_based_model = Sequential()
ann_based_model.add(InputLayer(input_shape=(1,28,28)))

# Define the intermediate layers.

ann_based_model.add(Flatten())
ann_based_model.add(Dense(512, activation="relu"))
ann_based_model.add(Dense(256, activation="relu"))
ann_based_model.add(Dense(128, activation="relu"))
ann_based_model.add(Dense(64, activation="relu"))
ann_based_model.add(Dense(NUM_CLASSES, activation="softmax"))
```

```
In [7]: # Compile the ANN model.
ann_based_model.compile(loss='categorical_crossentropy',
                        optimizer='adam',
                        metrics=['acc'])
```

```
In [8]: ann_based_classifier = KerasClassifier(model=ann_based_model, clip_values=(0,1))
ann_based_classifier.fit(x_train, y_train, nb_epochs=10, batch_size=BATCH_SIZE)

# Get the predictions on the test set.
predictions = ann_based_model.predict(x_test)

# Compute the accuracy on the test set.
score2 = ann_based_model.evaluate(x_test, y_test, verbose=0)
ann_score = score2[1]

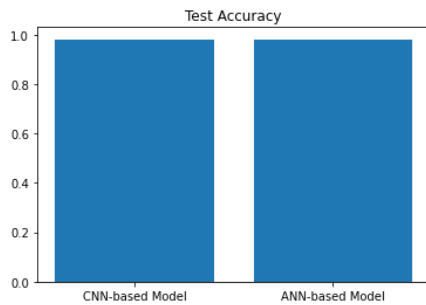
print('Test accuracy:', ann_score)
```

```
Epoch 1/10
60000/60000 [=====] - 10s 167us/step - loss: 0.2417 - acc: 0.9276
Epoch 2/10
60000/60000 [=====] - 10s 158us/step - loss: 0.0935 - acc: 0.9711
Epoch 3/10
60000/60000 [=====] - 10s 163us/step - loss: 0.0642 - acc: 0.9804
Epoch 4/10
60000/60000 [=====] - 10s 168us/step - loss: 0.0467 - acc: 0.9852
Epoch 5/10
60000/60000 [=====] - 10s 172us/step - loss: 0.0353 - acc: 0.9886
Epoch 6/10
60000/60000 [=====] - 10s 174us/step - loss: 0.0309 - acc: 0.9900
Epoch 7/10
60000/60000 [=====] - 11s 176us/step - loss: 0.0242 - acc: 0.9924
Epoch 8/10
60000/60000 [=====] - 11s 179us/step - loss: 0.0201 - acc: 0.9934
Epoch 9/10
60000/60000 [=====] - 11s 179us/step - loss: 0.0198 - acc: 0.9937
Epoch 10/10
60000/60000 [=====] - 11s 179us/step - loss: 0.0180 - acc: 0.9940
Test accuracy: 0.9790999889373779
```

Compare the classification accuracy on the test data graphically

You need to complete the following.

```
In [9]: X = ['CNN-based Model', 'ANN-based Model']
Y = [cnn_score, ann_score]
plt.bar(X,Y)
plt.title('Test Accuracy')
plt.show()
plt.close()
```



Part 2: Generate adversarial examples using four methods

You need to complete the following.

In this question, we will use the following four attack methods:

- (1) FGSM,
- (2) Basic Iterative Method,
- (3) Saliency Map Method,
- (4) Universal Perturbation.

```
In [10]: def generate_adv_examples_FGSM(classifier, x):
# This attack is known as the "Fast Gradient Sign Method".
attacker = FastGradientMethod(estimator=classifier )
attack = attacker.generate(x=x)
return attack

def generate_adv_examples_BasicIterativeMethod(classifier, x):
# The Basic Iterative Method is the iterative version of FGM and FGSM.
attacker = BasicIterativeMethod(estimator=classifier)
attack = attacker.generate(x=x)
return attack

def generate_adv_examples_SaliencyMapMethod(classifier, x):
# attack from the Jacobian-based Saliency Map Attack (Papernot et al. 2016).
# Paper link: https://arxiv.org/abs/1511.07528
attacker = SaliencyMapMethod(classifier=classifier)
attack = attacker.generate(x=x)
return attack

def generate_adv_examples_UniversalPerturbation(classifier, x):
attacker = UniversalPerturbation(classifier=classifier)
attack = attacker.generate(x=x)
return attack
```

```
In [11]: # Generate examples for CNN-based model
cnn_adv_examples_FGSM = generate_adv_examples_FGSM(cnn_based_classifier, x_test[1:9])
cnn_adv_examples_BasicIterativeMethod = generate_adv_examples_BasicIterativeMethod(cnn_based_classifier, x_test[1:9])
cnn_adv_examples_SaliencyMapMethod = generate_adv_examples_SaliencyMapMethod(cnn_based_classifier, x_test[1:9])
cnn_adv_examples_UniversalPerturbation = generate_adv_examples_UniversalPerturbation(cnn_based_classifier, x_test[1:9])

# Generate plot
fig, ax = plt.subplots(8, 4, sharex='col', sharey='row', figsize=(15,15))
fig.suptitle('Adversarial examples generated for the CNN-based model')
cnn_adv_examples = []
cnn_adv_examples.append(cnn_adv_examples_FGSM)
cnn_adv_examples.append(cnn_adv_examples_BasicIterativeMethod)
cnn_adv_examples.append(cnn_adv_examples_SaliencyMapMethod)
cnn_adv_examples.append(cnn_adv_examples_UniversalPerturbation)

for i in range(8):
    for j in range(4):
        ax[i, j].imshow(cnn_adv_examples[j][i].squeeze())
        predictions = cnn_based_classifier.predict(np.expand_dims(cnn_adv_examples[j][i], 0))
        ax[i, j].set_title('Network Prediction: {}'.format(np.argmax(predictions)))
```

PGD - Random Initializations: 100% 1/1 [00:01<00:00, 1.30s/it]

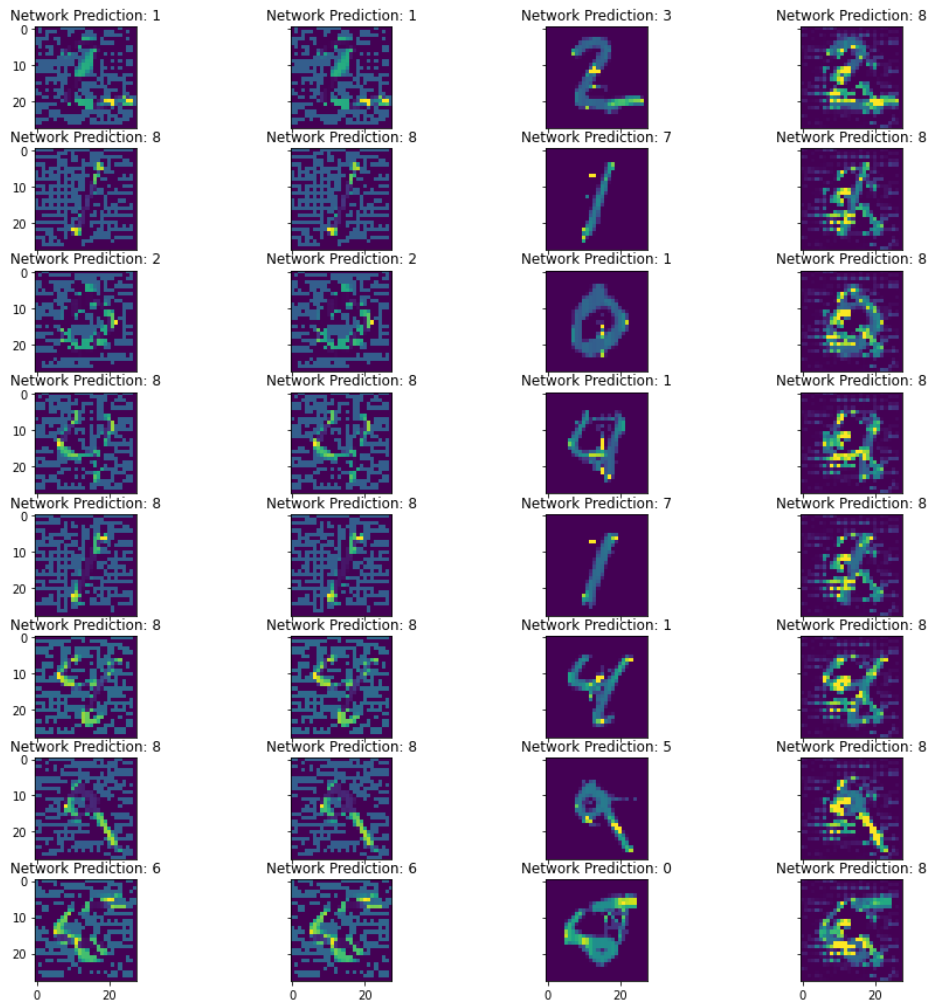
JSMA: 100% 8/8 [00:02<00:00, 3.54it/s]

Universal perturbation: 5% 1/20 [00:00<00:16, 1.16it/s]

DeepFool: 100% 1/1 [00:00<00:00, 1.27it/s]

DeepFool: 100% 1/1 [00:00<00:00, 37.96it/s]

Adversarial examples generated for the CNN-based model




```
In [12]: # Generate examples for ANN-based model
ann_adv_examples_FGSM = generate_adv_examples_FGSM(ann_based_classifier, x_test[1:9])
ann_adv_examples_BasicIterativeMethod = generate_adv_examples_BasicIterativeMethod(ann_based_classifier, x_test[1:9])
ann_adv_examples_SaliencyMapMethod = generate_adv_examples_SaliencyMapMethod(ann_based_classifier, x_test[1:9])
ann_adv_examples_UniversalPerturbation = generate_adv_examples_UniversalPerturbation(ann_based_classifier, x_test[1:9])

# Generate plots
fig, ax = plt.subplots(8, 4, sharex='col', sharey='row', figsize=(15,15))
fig.suptitle('Adversarial examples generated for the ANN-based model')
ann_adv_examples = []
ann_adv_examples.append(ann_adv_examples_FGSM)
ann_adv_examples.append(ann_adv_examples_BasicIterativeMethod)
ann_adv_examples.append(ann_adv_examples_SaliencyMapMethod)
ann_adv_examples.append(ann_adv_examples_UniversalPerturbation)

for i in range(8):
    for j in range(4):
        ax[i, j].imshow(ann_adv_examples[j][i].squeeze())
        predictions = ann_based_classifier.predict(np.expand_dims(ann_adv_examples[j][i], 0))
        ax[i, j].set_title('Network Prediction: {}'.format(np.argmax(predictions)))
```

PGD - Random Initializations: 100% 1/1 [00:00<00:00, 4.48it/s]

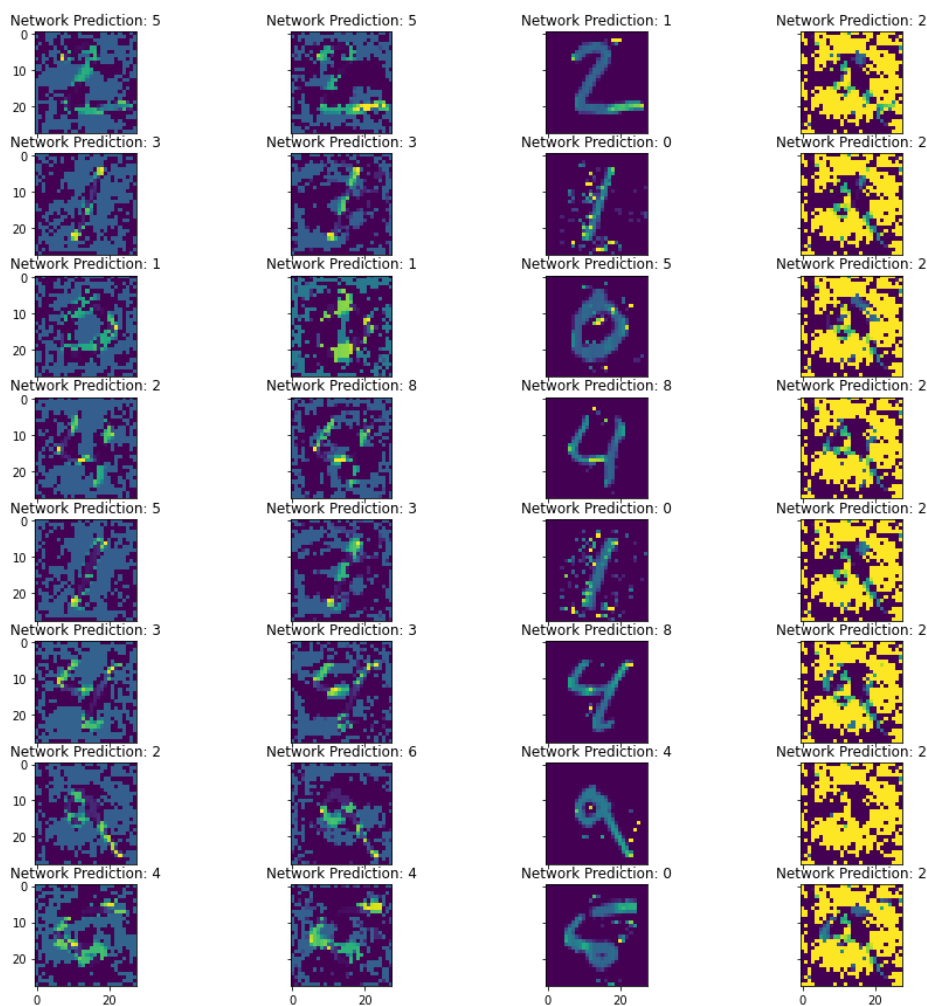
JSMA: 100% 8/8 [00:01<00:00, 4.68it/s]

Universal perturbation: 5% 1/20 [00:01<00:20, 1.07s/it]

DeepFool: 100% 1/1 [00:00<00:00, 1.44it/s]

DeepFool: 100% 1/1 [00:00<00:00, 2.87it/s]

Adversarial examples generated for the ANN-based model



Part 3: Create a new test set, based entirely on the adversarial images generated previously. Test your classifiers performance on this test set.

You need to complete the following.


```
In [13]: # We will be using the FGSM method in this part
ann_adv_examples_FGSM = generate_adv_examples_FGSM(ann_based_classifier, x_test)
cnn_adv_examples_FGSM = generate_adv_examples_FGSM(cnn_based_classifier, x_test)
```

```
In [14]: # Evaluate ANN-based-classifier on the newly generated adversarial test set
predictions = ann_based_model.predict(ann_adv_examples_FGSM)
ann_based_score = ann_based_model.evaluate(ann_adv_examples_FGSM, y_test, verbose=0)[1]
print('ANN-based Model Score: {}'.format(ann_based_score))

ANN-based Model Score: 0.020999999716877937
```

```
In [15]: # Evaluate CNN-based-classifier on the newly generated adversarial test set
predictions = cnn_based_model.predict(cnn_adv_examples_FGSM)
cnn_based_score = cnn_based_model.evaluate(cnn_adv_examples_FGSM, y_test, verbose=0)[1]
print('CNN-based Model Score: {}'.format(cnn_based_score))

CNN-based Model Score: 0.021199999377131462
```

Create a new augmented test set (original test images + adversarial images)

You need to complete the following.

```
In [18]: # ANN-based-classifier
ann_augmented_examples = []
for i in range(10000):

    # Select adversarial samples.
    if random.randint(0, 1) == 0:
        ann_augmented_examples.append(ann_adv_examples_FGSM[i])
    # Select actual samples.
    else:
        ann_augmented_examples.append(x_test[i])

#ann_augmented_examples = np.concatenate(ann_augmented_examples, axis=0)
ann_augmented_examples = np.array(ann_augmented_examples)

predictions = ann_based_model.predict(ann_augmented_examples)
ann_based_score_aug = ann_based_model.evaluate(ann_augmented_examples, y_test, verbose=0)[1]
print('ANN-based Model Score: {}'.format(ann_based_score_aug))

ANN-based Model Score: 0.49810001254081726
```

```
In [17]: # CNN-based-classifier
cnn_augmented_examples = []
for i in range(10000):

    # Select adversarial samples.
    if random.randint(0, 1) == 0:
        cnn_augmented_examples.append(cnn_adv_examples_FGSM[i])
    # Select actual samples.
    else:
        cnn_augmented_examples.append(x_test[i])

#cnn_augmented_examples = np.concatenate(cnn_augmented_examples, axis=0)
cnn_augmented_examples = np.array(cnn_augmented_examples)

predictions = cnn_based_model.predict(cnn_augmented_examples)
cnn_based_score_aug = cnn_based_model.evaluate(cnn_augmented_examples, y_test, verbose=0)[1]
print('CNN-based Model Score: {}'.format(cnn_based_score_aug))

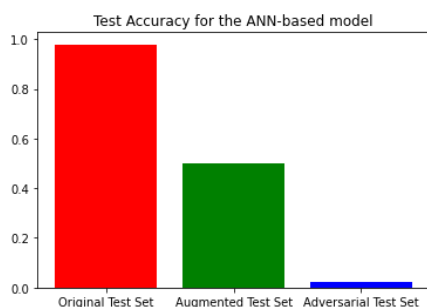
CNN-based Model Score: 0.5019999742507935
```

Make a single plot, wherein you compare the test accuracies of all the models, on the three types of test sets that you have

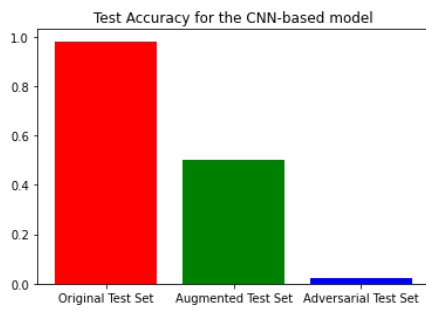
You need to complete the following.

```
In [19]: ann_models_score = [ann_score, ann_based_score_aug, ann_based_score]
cnn_models_score = [cnn_score, cnn_based_score_aug, cnn_based_score]
```

```
In [20]: # Plot for the ANN based model.
X = ['Original Test Set', 'Augmented Test Set', 'Adversarial Test Set']
plt.bar(X, ann_models_score, color=['r', 'g', 'b'])
plt.title('Test Accuracy for the ANN-based model')
plt.show()
plt.close()
```



```
In [21]: # Plot for the CNN based model.  
X = ['Original Test Set', 'Augmented Test Set', 'Adversarial Test Set']  
plt.bar(X, cnn_models_score, color=['r', 'g', 'b'])  
plt.title('Test Accuracy for the CNN-based model')  
plt.show()  
plt.close()
```



```
In [ ]: #6.
```