

Problem 1

What is dual norm. Derive the dual norm of the L_1 , L_2 and L_∞ .

Solution Let $\|w\|$ be a generic norm of vector w .

The dual norm is defined as follows.

$$\|x\|_* = \max \langle w, x \rangle \text{ such that } \|w\| \leq 1.$$

Hence, we get the following result.

$$\langle w, z \rangle \leq \|w\| \|z\|_*$$

Dual norm of L_1 and L_∞

Let $\|z\| = \sum |z_i| = \|Z\|_1$ (l_1 norm).

maximize $\sum z_i y_i$ for $\sum |z_i| \leq 1$.

$$= \max |y_i| = \|y\|_\infty.$$

Hence, the dual norm of L_1 is L_∞ . Since we know that the dual norm of the dual norm of is the original norm. Hence, the dual norm of L_∞ is L_1 .

Dual norm of L_2

We can see from the below equation that dual norm of L_2 is the L_2 itself.

$$\max_{\|z\|_2 \leq 1} z^T y \leq \|z\|_2 \|y\|_2 \leq \|y\|_2 \quad (1)$$

The equality is obtained when,

$$z = \begin{cases} \|y\|_2^{-1} \cdot y, & y \neq 0 \\ 0, & y = 0 \end{cases}$$

Problem 2

Gram-Schmidt Let $(1, -1, 1, 1), (1, 0, 1, 0), (0, 1, 0, 1)$ be a linearly independent set in R^4 . Find an orthonormal set v_1, v_2, v_3 st $L((1, 1, 1, 1), (1, 0, 1, 0), (0, 1, 0, 1)) = L(v_1, v_2, v_3)$

Solution step-1

$$\tilde{\mathbf{u}}_1 = \tilde{\mathbf{v}}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \quad \tilde{\mathbf{e}}_1 = \frac{\tilde{\mathbf{u}}_1}{|\tilde{\mathbf{u}}_1|} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

step-2

$$\tilde{\mathbf{u}}_2 = \tilde{\mathbf{v}}_2 - \text{proj}_{\tilde{\mathbf{u}}_1}(\tilde{\mathbf{v}}_2) = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix} \quad \tilde{\mathbf{e}}_2 = \frac{\tilde{\mathbf{u}}_2}{|\tilde{\mathbf{u}}_2|} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$$

step-3

$$\tilde{\mathbf{u}}_3 = \tilde{\mathbf{v}}_3 - \text{proj}_{\tilde{\mathbf{u}}_1}(\tilde{\mathbf{v}}_3) - \text{proj}_{\tilde{\mathbf{u}}_2}(\tilde{\mathbf{v}}_3) = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} \quad \tilde{\mathbf{e}}_3 = \frac{\tilde{\mathbf{u}}_3}{|\tilde{\mathbf{u}}_3|} = \begin{bmatrix} 0 \\ \frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{bmatrix}$$

answer:

$$\left\{ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{\sqrt{2}}{2} \\ 0 \\ \frac{\sqrt{2}}{2} \end{bmatrix} \right\} \approx \left\{ \begin{bmatrix} 0.5 \\ -0.5 \\ 0.5 \\ 0.5 \end{bmatrix}, \begin{bmatrix} 0.5 \\ 0.5 \\ 0.5 \\ -0.5 \end{bmatrix}, \begin{bmatrix} 0 \\ 0.707106781186548 \\ 0 \\ 0.707106781186548 \end{bmatrix} \right\}.$$

Problem 3

Prove that every real, symmetric matrix X has the decomposition $X = Q\Lambda Q^T$. Q is an orthogonal matrix and Λ is a diagonal matrix with eigenvalues as elements.

Solution

Let n be the order of real symmetric matrix A .

And x_1, x_2, \dots, x_n be the eigenvector of A with corresponding eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$.

Let $\Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_n \end{bmatrix}$ be the eigenvalue matrix of A . And $Q = [x_1, x_2, \dots, x_n]$ be the eigenvector matrix of A .

Then, we have,

$$AQ = A[x_1, x_2, \dots, x_n]$$

$$= [Ax_1, Ax_2, \dots, Ax_n]$$

$$= [\lambda_1 x_1, \lambda_2 x_2, \dots, \lambda_n x_n]$$

$$= Q\Lambda$$

Hence, $AQ = Q\Lambda$.

Or, $A = Q\Lambda Q^{-1}$

If we can prove that Q is orthogonal then we would get our desired result of $A = Q\Lambda Q^T$ as for any orthogonal matrix, $Q^{-1} = Q^T$

We know that for any real matrix A and any vectors x and y , we have,

$$\langle Ax, y \rangle = \langle x, A^T y \rangle$$

Let x, y be the eigenvector of A corresponding to distinct eigenvalue λ_1 and λ_2 . We already know that A is a real, symmetric matrix. Then,

$$\lambda_1 \langle x, y \rangle = \langle \lambda_1 x, y \rangle = \langle Ax, y \rangle = \langle x, A^T y \rangle = \langle x, Ay \rangle = \langle x, \lambda_2 y \rangle = \lambda_2 \langle x, y \rangle$$

Therefore, $(\lambda_1 - \lambda_2)\langle x, y \rangle = 0$. Since $(\lambda_1 - \lambda_2) \neq 0$ as they are distinct eigenvalues. Therefore, x and y are orthogonal to each other.

Similarly, we can prove that any two eigenvector of A are orthogonal to each other. Hence, the matrix Q is orthogonal.

Hence, $A = Q\Lambda Q^T$

Problem 4

Can an orthogonal matrix have an entry $U_{ij} > 1$? Why?

Solution Yes. Since, all diagonal matrix are orthogonal and a diagonal matrix can have a diagonal element greater than 1. Hence, it is possible for an orthogonal matrix to have an element greater than 1.

Problem 5

When is a diagonal matrix orthogonal?

Solution Every diagonal matrix has the property that it is orthogonal. Hence, every diagonal matrix is already orthogonal.

Problem 6

When is an upper triangular matrix orthogonal ?

Solution Let A be an upper triangular matrix which is also orthogonal. Then, as per orthogonality, $A^{-1} = A^T$.

Also, note that the inverse of an upper triangular matrix is also an upper triangular matrix. Hence, A^T is both upper triangular and lower triangular matrix, i.e., a diagonal matrix. It implies that A is also a diagonal matrix.

Hence, an upper triangular matrix will be orthogonal when it is diagonal.

Problem 7

Is the inverse of an orthogonal matrix orthogonal ?

Solution We know that, $A^T = A^{-1}$

Taking inverse, $(A^{-1})^{-1} = A$

Taking transpose, $(A^T)^T = A$

Hence, $(A^{-1})^{-1} = A = (A^T)^T = (A^{-1})^T$

Problem 8

What are eigenvalues and eigenvectors of a diagonal matrix ?

Solution The eigenvalues of a diagonal matrix are present as the elements of that diagonal matrix. And its eigenvector form a canonical basis for space K^n

Problem 9

Can you find vectors that attain each of the equality cases in $\lambda_{min} \leq \frac{x^T Ax}{\|x\|^2} \leq \lambda_{max}$?

Solution The given inequality is known as Rayleigh Inequality. Here, A is any symmetric matrix of order n and x is any vector of \mathbb{R}^n .

One vector for which equality can be attain in both the cases is when $x = [1 \ 0 \ 0]$ and A is an identity matrix of order 3.

Then λ_{min} and λ_{max} both are 1 and $\|x\|^2 = 1.1 + 0.0 + 0.0 = 1$ and $x^T Ax = 1$.

There are many other vectors as well. Any column vector of an identity matrix will also satisfy this property.