







Dr.-Ing Chandramouli Gnanasambandham

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71263 Weil der Stadt

-  6th August 1990
-  Married, no children
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Profile

I am a passionately curious engineer with excellent intercultural communication skills. I have been spearheading the development of robust multi-fidelity vehicle models for highly-scalable simulations with over 300 active users in my current organization. Moreover, I have been first author of 6 peer-reviewed journal articles in the field of particle dynamics during my time at the academia. All this was possible, thanks to my exceptional adaptability to rapidly changing environments and my extraordinary analytical and team skills. I am now seeking new opportunities as a Senior Engineer, where I can leverage my expertise in simulation and analytical problem-solving to contribute to cutting-edge innovations in mobility.

Languages

■ ■ ■ ■ ■	Proficient German
■ ■ ■ ■ ■	Proficient English
■ ■ ■ ■ ■	Mother tongue Tamil
■ ■ ■ ■ □	Advanced Hindi

Web

LinkedIn
[linkedin.com/in/gnanasambandhamc](https://www.linkedin.com/in/gnanasambandhamc)

Medium
chandramouli.medium.com

Matlab
MatlabCentral Profile

Educational Qualification

May 2016 - April 2021

Ph.D. in Mechanical Engineering

University of Stuttgart

- Dissertation Titel: Particle Dampers- Enhancing Energy Dissipation using Fluid/Solid Interactions and Rigid Obstacle-Grids

October 2012 - April 2016

Master of Science in Commercial Vehicle Technology

Technical University of Kaiserslautern, Grade: 1.9

June 2008 - April 2012

Bachelor of Engineering in Production Engineering

Anna University, Chennai, India, Grade CGPA: 8.3/10

Professional Career

April 2023 - present

Torc Europe GmbH, Stuttgart

Staff software engineer

- Spearheaded a team develop a highly-scalable vehicle model in C++ following Test-Driven Development (TDD) and Object-Oriented Programming (OOP)
- Integrated vehicle models into a Robotic Operating System (ROS) based simulator to enable virtual validation of Level 4 autonomous vehicles
- Collaborated with external stakeholders to develop a scalable validation strategy for vehicle models as per ISO-26262.

August 2021 - March 2023

Daimler Truck AG, Stuttgart

Vehicle model engineer

- Develop multi-fidelity vehicle models for scalable simulations in the context of virtual validation in MATLAB/Simulink
- Developed a co-simulation interface in C++ to couple a high-fidelity multibody truck model and the virtual driver using TCP/IP communication interface.

Awards

Best Presentation Award 2014

Optimization of Vehicle Parameters based on Lap-Time Simulations using Multiobjective Evolutionary Algorithm

Best Presentation Award 2015

An Adaptive Approach to Real-Time Estimation of Vehicle Dynamics Parameters using Kalman Filtering

Both awards were offered by ALTEN GmbH, complemented with a cash-prize of **500€** respectively.

Other Fun Projects

July 2020 - present

Raspberry Pi Powered Smart-Home

As part of a on-going hobby project, I have built a versatile Raspberry-Pi smart home network with remote-ssh-access, custom file storage server with automatic backups using `rsync`, Zigbee2Mqtt server for controlling IOT devices using siri/google-nest and custom automations.

Juni 2015

Machine Learning Suite

Implementation of a deep convolution neural network for optical character recognition as part of a freelance software project in MATLAB. To increase performance the MEX API was used.

Juni 2014

Driver-in-the-Loop Simulator

As part of my work for a formula student racing team, I developed a driver-in-the-loop simulator based on a communication interface between IPG CarMaker and MATLAB/Simulink.

Professional Career (continued)

May 2016 - April 2021

University of Stuttgart

Scientific staff at the institute for engineering and computational mechanics (ITM) October 2015 - April 2016

Fraunhofer Institute (ITWM), Kaiserslautern

Intern in the department of mathematics for vehicle engineering

Technical Skills

Programming Languages:

■ ■ ■ ■ ■ 12 years | C/C++

■ ■ ■ ■ ■ 12 years | MATLAB

■ ■ ■ ■ □ 9 years | BASH

■ ■ ■ □ □ 6 years | Python

Operating System:

■ ■ ■ ■ ■ Linux (Debian, Ubuntu)

■ ■ ■ ■ □ Microsoft Windows

Simulation and Data Skills:

- **MATLAB/Simulink:** Modelling, simulation, numerical optimization, SiL/DiL simulations, MATLAB GUI, FMI
- **C/C++:** MEX API, SilverBypass, FMI, ROS, TCP/IP and UDP
- **Multibody-Simulation:** LMS Virtual.Lab Motion, Neweul-M², MSC Adams, Project Chrono
- **ADAS/AD-Simulation Tools:** Applied Object-Sim, IPG CarMaker, IPG TruckMaker
- **Multibody-Simulation:** LMS Virtual.Lab Motion, Neweul-M²
- **Other Software Tools:** Silver Virtual-ECU, COMSOL Multiphysics, OptiSlang, Oracle VM VirtualBox

Software Development Tools:


- **CI Tools:** Git, Github CLI, Jenkins, Docker
- **Technologies:** PETSc, EIGEN, OpenGL
- **Debuggers/Profilers:** gdb, valgrind, calgrind, Intel VTune

Selected Publications

Gnanasambandham, C.; Fleissner, F.; Eberhard, P.: Enhancing the Dissipative Properties of PDs using Rigid Obstacle-Grids. *Journal of Sound and Vibration*, Vol. 484, p. 115522, 2020.

Gnanasambandham, C.; Stender, M.; Hoffmann, N.; Eberhard, P.: Multi-Scale Dynamics of PDs using Wavelets: Extracting Particle Activity Metrics from Ring Down Experiments. *Journal of Sound Vibration*, Vol. 454, pp. 1-13, 2019.

Stuttgart, Monday 25th November, 2024


Dr.-Ing Chandramouli Gnanasambandham