DATA ANALYTICS THEORY ASSIGNMENT 1

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ROLL NUMBER-22MCS0030

DATASET- SHUTTLE-LANDING-CONTROL.csv

About the Dataset

- 1. Title: Space Shuttle Autolanding Domain
- 2. Sources:
 - (a) Original source: unknown
 - -- NASA: Mr. Roger Burke's autolander design team
 - (b) Donor: Bojan Cestnik

Jozef Stefan Institute

Jamova 39

61000 Ljubljana

Yugoslavia (tel.: (38)(+61) 214-399 ext.287)

- (c) Date: November 1988
- 3. Past Usage: (several, it appears)

Example: Michie, D. (1988). The Fifth Generation's Unbridged Gap. In Rolf Herken (Ed.) The Universal Turing Machine: A Half-Century Survey, 466-489, Oxford University Press.

4. Relevant Information:

This is a tiny database. Michie reports that Burke's group used RULEMASTER to generate comprehendable rules for determining the conditions under which an autolanding would be preferable to manual control of the spacecraft.

- 5. Number of Instances: 15
- 6. Number of Attributes: 7 (including the class attribute)
- 7. Attribute Information:

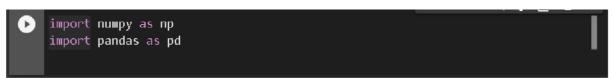
- 1. Class: noauto, auto
 - -- that is, advise using manual/automatic control
- 2. STABILITY: stab, xstab
- 3. ERROR: XL, LX, MM, SS
- 4. SIGN: pp, nn
- 5. WIND: head, tail
- 6. MAGNITUDE: Low, Medium, Strong, OutOfRange
- 7. VISIBILITY: yes, no
- 8. Missing Attribute Values:
 - -- none
 - -- but several "don't care" values: (denoted by "*")

Attribute Number: Number of Don't Care Values:

- 2: 2
- 3: 3
- 4: 8
- 5: 8
- 6: 5
- 7: 0
- 9. Class Distribution:
 - 1. Use noauto control: 6
 - 2. Use automatic control:

Implementation-

1. Importing the libraries



2.Importing the dataset

[19] df=pd.read_csv('/content/csv_result-dataset_114_shuttle-landing-control.csv')

3. Basic Data Exploration

```
#Basic Data Exploration
print("Number of rows:", len(df))
print("Number of columns:", len(df.columns))
print("Data types of each column:")
print(df.dtypes)
print("Missing values:")
print(df.isnull().sum())
```

```
Number of rows: 15
Number of columns: 8
Data types of each column:
id int64
Class int64
STABILITY object
ERROR object
SIGN object
SIGN object
WIND object
MAGNITUDE object
int64
VISIBILITY
                  int64
dtype: object
Missing values:
id
Class
STABILITY Ø
ERROR
                 0
SIGN
                 0
WIND
                 0
MAGNITUDE
                 0
VISIBILITY
                  0
dtype: int64
```

4. Handling of missing values

Here, we fill up the missing values by using the simple imputer .The numerical meathod we use is the mode or most frequent occurance is filled in the missing slots

```
[48] #Handling the missing values
    from sklearn.impute import SimpleImputer
    imputer = SimpleImputer(strategy='most_frequent')
    df_filled = pd.DataFrame(imputer.fit_transform(df), columns=df.columns)
    print(df_filled)
```

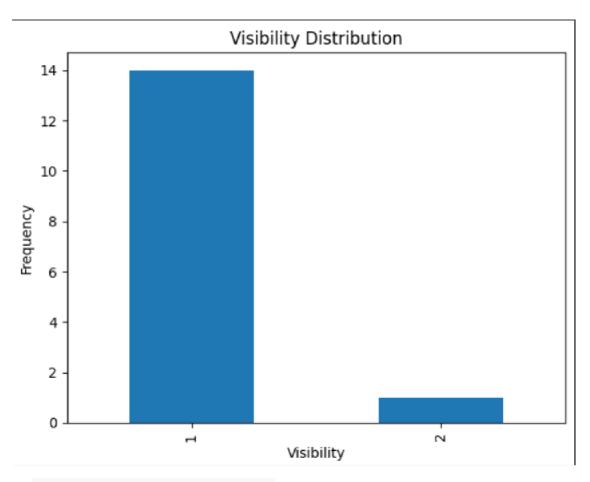
<u>.</u> >		id	Class	STABILITY	ERROR	SIGN	WIND	MAGNITUDE	VISIBILITY
	Ø	3	1	1	2	?	?	?	1
	1	4	1	1	1			3	1
	2	5	1	1	3	2	2	3	1
	3	7	2	1	4			1	1
	4	8	2	1	4			2	1
	5	9	2	1	4			3	1
	6	10	2	1	3	1	1	1	1
	7	11	2	1	3	1	1	2	1
	8	12	2	1	3	1	2	1	1
	9	13	2	1	3	1	2	2	1
	10	14	1	1	3	1	1	3	1
	11	15	2	1	3	1	2	3	1

5. Descriptive analysis

Here, we use the df.describe() to show the descriptive analysis

```
#Descriptive analysis
print("Summary statistics:")
print(df.describe())
Summary statistics:
                    Class VISIBILITY
count 15.000000 15.000000 15.000000
mean 8.000000 1.600000 1.066667
std
      4.472136 0.507093 0.258199
min
       1.000000
                1.000000
                            1.000000
                1.000000
25%
       4.500000
                             1.000000
50%
      8.000000 2.000000
                            1.000000
75%
      11.500000
                2.000000
                             1.000000
max
      15.000000
                 2.000000
                             2.000000
```

Next, we plot a frequency graph for the visibility



6. Printing the correlation matrix

```
#PRINTING THE CORRELATION MATRIX
correlation_matrix = df.corr()
print("Correlation matrix:")
print(correlation_matrix)
```

7. Performing predictive analysis using logistic regression and seeing the accuracy score

Accuracy: 0.6666666666666666

8. Drawing a KMeans Clustering Graph using K=3

```
#Drawing a Kmeans Clustering Graph with K=3
from sklearn.cluster import KMeans

target_variable = 'ERROR'  # Replace 'ERROR' with the desired column name as the target variable

# Remove rows with '?' in the target variable column

df_filled = df_filled[df_filled[target_variable] !- '?']

# Convert target variable to numeric

df_filled[target_variable] = pd.to_numeric(df_filled[target_variable])

target_variable = 'VISIBILITY'  # Replace 'ERROR' with the desired column name as the target variable

# Remove rows with '?' in the target variable column

df_filled = df_filled[df_filled[target_variable] != '?']

# Convert target variable to numeric

df_filled[target_variable] = pd.to_numeric(df_filled[target_variable])

features = df_filled[['VISIBILITY', 'ERROR']]  # Features for clustering

# Define the number of clusters
num_clusters = 3
```

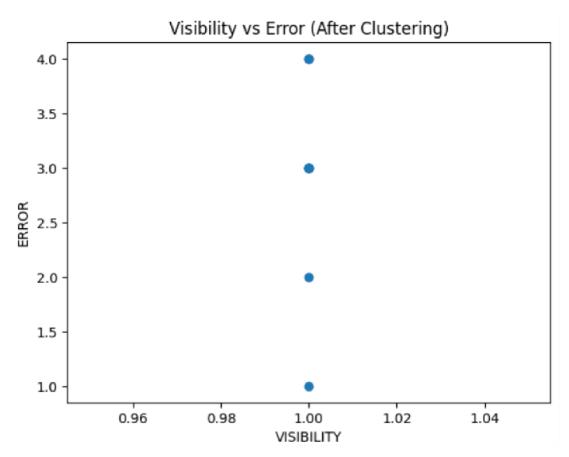
```
features = df_filled[['VISIBILITY', 'ERROR']] # Features for clustering

# Define the number of clusters
num_clusters = 3

kmeans = KMeans(n_clusters=num_clusters)
kmeans.fit(features)
cluster_labels = kmeans.labels_

# Add the cluster labels to the dataset
df['Cluster'] = cluster_labels

# step 7: Visualization of 'VISIBILITY' vs 'ERROR' after clustering
plt.scatter(df_filled['VISIBILITY'], df_filled['ERROR'])
plt.xlabel('VISIBILITY')
plt.ylabel('ERROR')
plt.title('Visibility vs Error (After Clustering)')
plt.show()
```



Inference- By analyzing the given dataset we can conclude that the error in a shuttle landing is not dependent on the visibility on that day. This is because modern shuttles are equipped with radar, GPS and other such high tech equipments.