

**Solution prepared by:**  
**Bintang A.S.W.A.M,**  
<https://github.com/baswam95>

**Analytical Approach of Tangency on Geometry Problem**

(posted by Mr.Sourabh-Bhat)

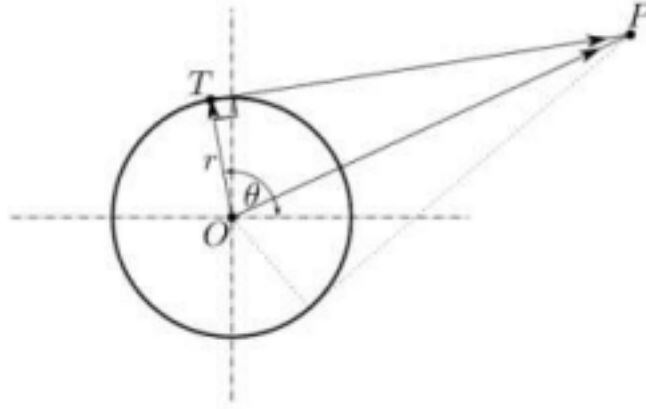


Figure 1. Schematic diagram of the problem<sup>[1]</sup>

Analytical solution:

From your final tangent line equation, it gives the following result:

$$(x_p - x_o)\cos\theta + (y_p - y_o)\sin\theta - r = 0$$

In behalf of algebraic manipulation, let define  $\Delta x$  and  $\Delta y$  as given below:

$$\Delta x \equiv x_p - x_o ; \Delta y \equiv y_p - y_o$$

then,

$\Delta x \cos\theta + \Delta y \sin\theta - r = 0$	(1)
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Let's recall trigonometry identity as given below:

$$\sin^2\theta + \cos^2\theta = 1 \leftrightarrow \cos^2\theta = 1 - \sin^2\theta$$

Next, let's rearrange the form of (1) by taking square on both of sides as follows:

$(r - \Delta y \sin\theta)^2 = (\Delta x \cos\theta)^2 \leftrightarrow r^2 - 2r\Delta y \sin\theta + \Delta y^2 \sin^2\theta = \Delta x^2 \cos^2\theta$	(1.1)
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Now, let's substitute  $\cos^2\theta$  from trigonometry identity into (1.1) and by a little bit rearrangement of (1.1), it gives

$\sin^2\theta - \frac{2r\Delta y}{\Delta x^2 + \Delta y^2} \sin\theta + \frac{r^2 - \Delta x^2}{\Delta x^2 + \Delta y^2} = 0$	(2)
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It can be viewed that (2) resembles the general quadratic equation in which  $\sin\theta$  as an unknown variable. Otherwise, I can apply “**abc formula**” as given below:

$$x_{1,2} = \frac{-b \pm \sqrt{D}}{2a} ; D = b^2 - 4ac$$

in this case,  $a = 1$ ;  $b = \frac{-2r\Delta y}{\Delta x^2 + \Delta y^2}$ ;  $c = \frac{r^2 - \Delta x^2}{\Delta x^2 + \Delta y^2}$

then,

$$\sin\theta_{1,2} = \frac{-\left(\frac{-2r\Delta y}{\Delta x^2 + \Delta y^2}\right) \pm \sqrt{\left(-\frac{2r\Delta y}{\Delta x^2 + \Delta y^2}\right)^2 - 4(1)\left(\frac{r^2 - \Delta x^2}{\Delta x^2 + \Delta y^2}\right)}}{2(1)}$$

by a little bit simplification, it can be obtained that

$\sin\theta_{1,2} = \frac{r\Delta y \pm \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}$	(3)
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From (3), It has two distinct solutions which are  $\theta_1$  and  $\theta_2$ . Therefore, both of  $\theta_1$  and  $\theta_2$  are expressed below:

$\theta_1 = \sin^{-1}\left(\frac{r\Delta y + \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)$ $\theta_2 = \sin^{-1}\left(\frac{r\Delta y - \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)$	(3.1)
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It's known that both of  $\theta_1$  and  $\theta_2$  are evaluated in radian unit (not in degree unit).

Moreover, the coordinate of tangency point ( $X_T, Y_T$ ) associated with  $\theta_1$  and  $\theta_2$  is given below:

$$\begin{aligned} X_{T,1} &= X_O + r\cos\theta_1; Y_{T,1} = Y_O + r\sin\theta_1 \\ X_{T,2} &= X_O + r\cos\theta_2; Y_{T,2} = Y_O + r\sin\theta_2 \end{aligned}$$

Hence,

The coordinate of 1<sup>st</sup> tangency point ( $X_{T,1}, Y_{T,1}$ ):

$$\begin{aligned} X_{T,1} &= X_O + r\cos\theta_1 = X_O + r\cos\left(\sin^{-1}\left(\frac{r\Delta y + \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)\right) \\ Y_{T,1} &= Y_O + r\sin\theta_1 = Y_O + r\sin\left(\sin^{-1}\left(\frac{r\Delta y + \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)\right) \end{aligned}$$

The coordinate of 2<sup>nd</sup> tangency point ( $X_{T,2}, Y_{T,2}$ ):

$$\begin{aligned} X_{T,2} &= X_O + r\cos\theta_2 = X_O + r\cos\left(\sin^{-1}\left(\frac{r\Delta y - \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)\right) \\ Y_{T,2} &= Y_O + r\sin\theta_2 = Y_O + r\sin\left(\sin^{-1}\left(\frac{r\Delta y - \Delta x\sqrt{\Delta x^2 + \Delta y^2 - r^2}}{\Delta x^2 + \Delta y^2}\right)\right) \end{aligned}$$

Reference:

- [1]. <https://spbhat.in/blogs/tangent/index.html>, accessed on Friday, July 5, 2019 at 4.14 PM